

# Scalable Visual Comparison of Biological Trees and Sequences

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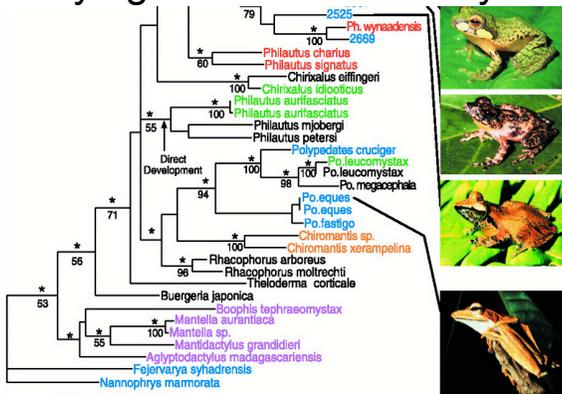
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# Outline

- TreeJuxtaposer
  - tree comparison
- Accordion Drawing
  - information visualization technique
- SequenceJuxtaposer
  - sequence comparison
- PRISAD
  - generic accordion drawing framework
- Evaluation
  - comparing AD to pan/zoom, with/without overview

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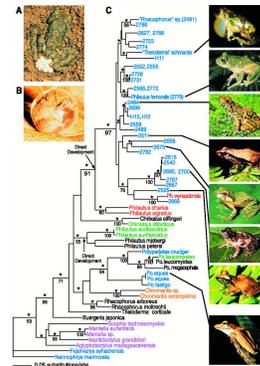
## Phylogenetic/Evolutionary Tree



M Meegaskumbura et al., Science 298:379 (2002)

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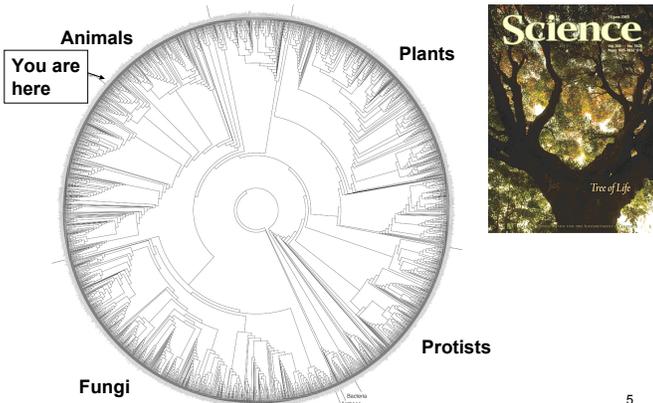
## Common Dataset Size Today



M Meegaskumbura et al., Science 298:379 (2002)

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## Future Goal: 10M Node Tree of Life



David Hillis, Science 300:1687 (2003)

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## Paper Comparison: Multiple Trees

focus



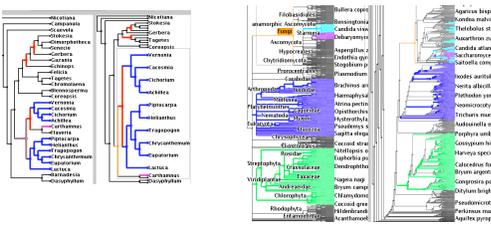
context



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## TreeJuxtaposer

- side by side comparison of evolutionary trees
  - [video]
  - software downloadable from <http://olduvai.sf.net/tj>



[TreeJuxtaposer: Scalable Tree Comparison using Focus+Context with Guaranteed Visibility. Tamara Munzner, François Guimbertière, Serdar Tasiran, Li Zhang, Yunhong Zhou. Proc SIGGRAPH 2003]

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## Related Work: Tree Browsing

- general
  - Cone Trees [Robertson et al 91]
  - Hyperbolic Trees [Lamping 94]
  - H3 [Munzner 97]
  - Hierarchical Clustering Explorer [Seo & Shneiderman 02]
  - SpaceTree [Plaisant et al 02]
  - DOI Tree [Card and Nation 02]
- phylogenetic trees
  - TreeWiz [Rost and Bornberg-Bauer 02]
  - TaxonTree [Lee et al 04]

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## Related Work: Comparison

- tree comparison
  - RF distance [Robinson and Foulds 81]
  - perfect node matching [Day 85]
- visual tree comparison
  - creation/deletion only [Chi and Card 99]
  - leaves only [Graham and Kennedy 01]
- subsequent work
  - DoubleTree [Parr et al 04]

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## TJ Contributions

- first interactive tree comparison system
  - automatic structural difference computation
- scalable to large datasets
  - 250,000 to 500,000 total nodes
  - all preprocessing subquadratic
  - all realtime rendering sublinear
    - items to render >> number of available pixels
- scalable to large displays (4000 x 2000)
- introduced accordion drawing

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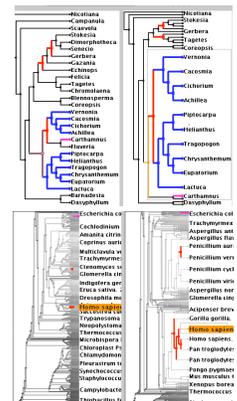
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## Accordion Drawing

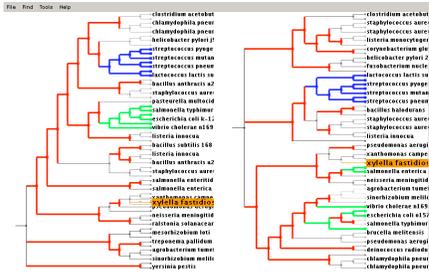
- rubber-sheet navigation
  - stretch out part of surface, the rest squishes
  - borders nailed down
  - Focus+Context technique
    - integrated overview, details
  - old idea
    - [Sarkar et al 93], [Robertson et al 91]
- guaranteed visibility
  - marks always visible
  - important for scalability
  - new idea
    - [Munzner et al 03]



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## Guaranteed Visibility

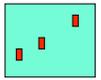
- marks are always visible
  - regions of interest shown with color highlights
  - search results, structural differences, user specified
- easy with small datasets



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## Guaranteed Visibility Challenges

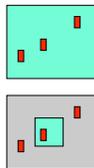
- hard with larger datasets
- reasons a mark could be invisible



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## Guaranteed Visibility Challenges

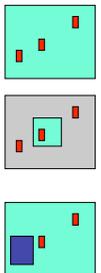
- hard with larger datasets
- reasons a mark could be invisible
  - outside the window
    - AD solution: constrained navigation



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## Guaranteed Visibility Challenges

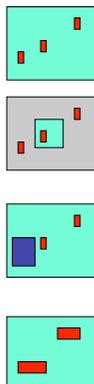
- hard with larger datasets
- reasons a mark could be invisible
  - outside the window
    - AD solution: constrained navigation
  - underneath other marks
    - AD solution: avoid 3D



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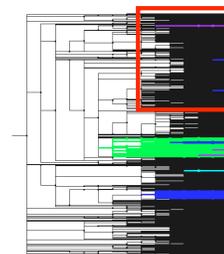
## Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
  - outside the window
    - AD solution: constrained navigation
  - underneath other marks
    - AD solution: avoid 3D
  - smaller than a pixel
    - AD solution: smart culling

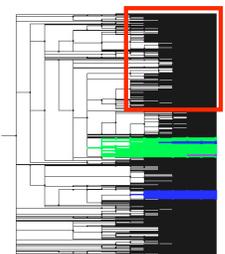


## Guaranteed Visibility: Small Items

- Naïve culling may not draw all marked items



Guaranteed visibility of marks

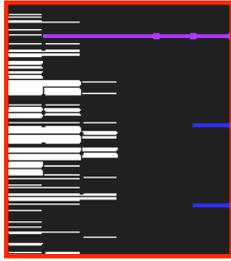


No guaranteed visibility

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## Guaranteed Visibility: Small Items

- Naïve culling may not draw all marked items



Guaranteed visibility  
of marks



No guaranteed visibility

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## Guaranteed Visibility Rationale

- relief from exhaustive exploration
  - missed marks lead to false conclusions
  - hard to determine completion
  - tedious, error-prone
- compelling reason for Focus+Context
  - controversy: does distortion help or hurt?
  - strong rationale for comparison
- infrastructure needed for efficient computation

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## Related Work

- multiscale zooming
  - Pad++ [Bederson and Hollan 94]
- multiscale visibility
  - space-scale diagrams [Furnas & Bederson 95]
  - effective view navigation [Furnas 97]
  - critical zones [Jul and Furnas 98]

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## Genomic Sequences

- multiple aligned sequences of DNA
- investigate benefits of accordion drawing
  - showing multiple focus areas in context
  - smooth transitions between states
  - guaranteed visibility for globally visible landmarks
- now commonly browsed with web apps
  - zoom and pan with abrupt jumps

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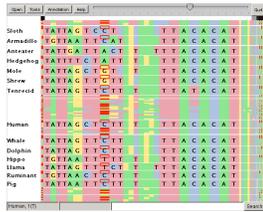
## Related Work

- web based, database driven, multiple tracks
  - Ensembl [Hubbard 02]
  - UCSC Genome Browser [Kent 02]
  - NCBI [Wheeler 02]
- client side approaches
  - Artemis [Rutherford et al 00]
  - BARD [Spell et al 03]
  - PhyloVISTA [Shah et al 03]

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## SequenceJuxtaposer

- side by side comparison of multiple aligned gene sequences
- [video], software downloadable from <http://olduvai.sf.net/sj>

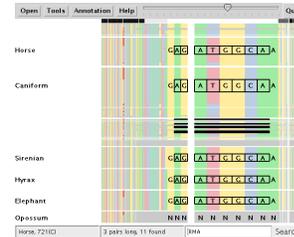


[SequenceJuxtaposer: Fluid Navigation For Large-Scale Sequence Comparison In Context. James Slack, Kristian Hildebrand, Tamara Munzner, and Katherine St. John. Proc. German Conference on Bioinformatics 2004]

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## Searching

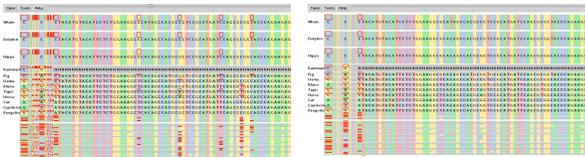
- search for motifs
  - protein/codon search
  - regular expressions supported
- results marked with guaranteed visibility



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## Differences

- explore differences between aligned pairs
  - slider controls difference threshold in realtime
  - standard difference algorithm, not novel
- results marked with guaranteed visibility



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## SJ Contributions

- fluid tree comparison system
  - showing multiple focus areas in context
  - guaranteed visibility of marked areas
    - thresholded differences, search results
- scalable to large datasets
  - 2M nucleotides
  - all realtime rendering sublinear

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## Scaling Up: TJC/TJC-Q

- TJC: 15M nodes
  - no quadtree
  - picking with new hardware feature
    - requires HW multiple render target support
- TJC-Q: 5M nodes
  - lightweight quadtree for picking support
- both support tree browsing only
  - no comparison data structures

[Scalable, Robust Visualization of Large Trees  
Dale Beermann, Tamara Munzner, Greg Humphreys.  
Proc. EuroVis 2005]

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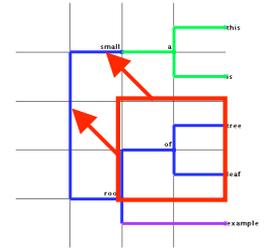
# Generic Infrastructure: PRISAD

- generic AD infrastructure
  - PRITree is TreeJuxtaposer using PRISAD
  - PRISeq is SequenceJuxtaposer using PRISAD
- efficiency
  - faster rendering: minimize overdrawing
  - smaller memory footprint
- correctness
  - rendering with no gaps: eliminate overculling

[Partitioned Rendering Infrastructure for Scalable Accordion Drawing. James Slack, Kristian Hildebrand, and Tamara Munzner. Proc. InfoVis 2005 extended version: Information Visualization, to appear]

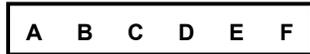
# Navigation

- generic navigation infrastructure
  - application independent
  - uses deformable grid
  - split lines
    - grid lines define object boundaries
  - horizontal and vertical separate
    - independently movable

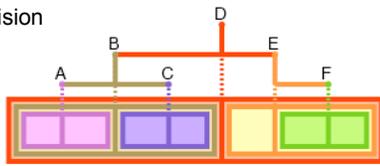


# Split Line Hierarchy

- data structure supports navigation, picking, drawing
- two interpretations
  - linear ordering



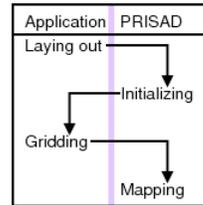
- hierarchical subdivision



# PRISAD Architecture

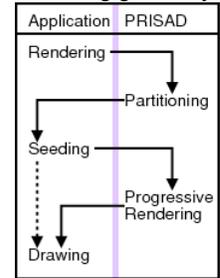
## world-space discretization

- preprocessing
  - initializing data structures
  - placing geometry



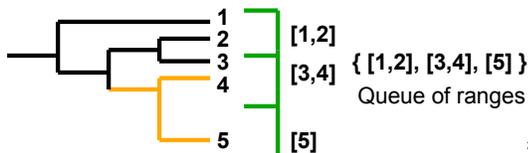
## screen-space rendering

- frame updating
  - analyzing navigation state
  - drawing geometry



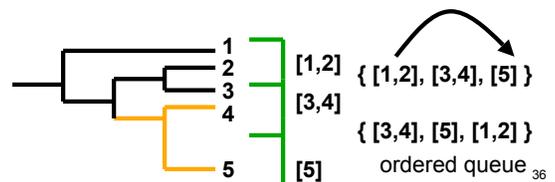
# Partitioning

- partition object set into bite-sized ranges
  - using current split line screen-space positions
    - required for every frame
  - subdivision stops if region smaller than 1 pixel
    - or if range contains only 1 object



# Seeding

- reordering range queue result from partition
  - marked regions get priority in queue
    - drawn first to provide landmarks



## Drawing Single Range

- each enqueued object range drawn according to application geometry
  - selection for trees
  - aggregation for sequences

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## PRITree Range Drawing

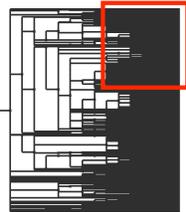
- select suitable leaf in each range
- draw path from leaf to the root
  - ascent-based tree drawing
  - efficiency: minimize overdrawing
    - only draw one path per range



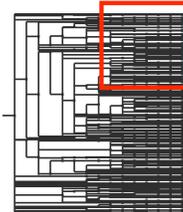
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## Rendering Dense Regions

- correctness: eliminate overculling
  - bad leaf choices would result in misleading gaps
- efficiency: maximize partition size to reduce rendering
  - too much reduction would result in gaps



Intended rendering



Partition size too big 39

## Rendering Dense Regions

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Intended rendering



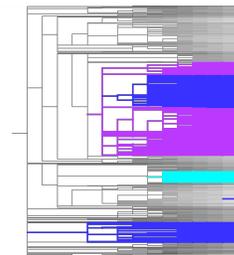
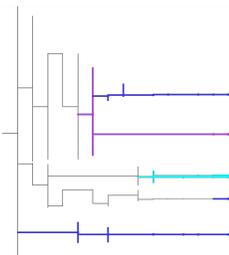
Partition size too big 40

## PRITree Skeleton

- guaranteed visibility of marked subtrees during progressive rendering

first frame: one path per marked group

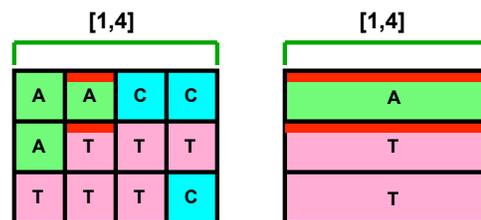
full scene: entire marked subtrees



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## PRISeq Range Drawing: Aggregation

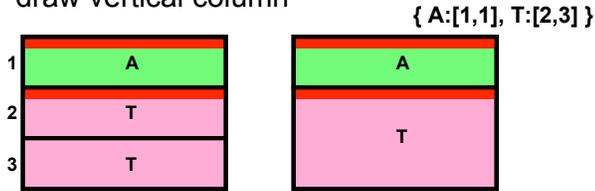
- aggregate range to select box color for each sequence
  - random select to break ties



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## PRISeq Range Drawing

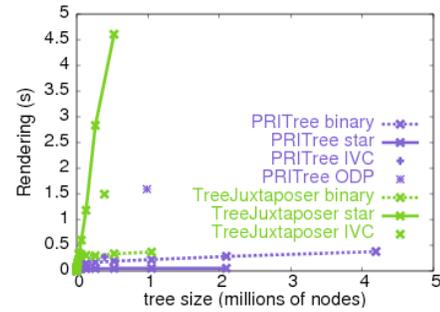
- collect identical nucleotides in column
  - form single box to represent identical objects
    - attach to split line hierarchy cache
    - lazy evaluation
- draw vertical column



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## PRITree Rendering Time Performance

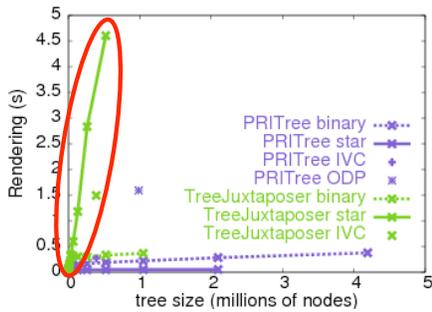
- TreeJuxtaposer renders **all** nodes for star trees
- branching factor  $k$  leads to  $O(k)$  performance



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## PRITree Rendering Time Performance

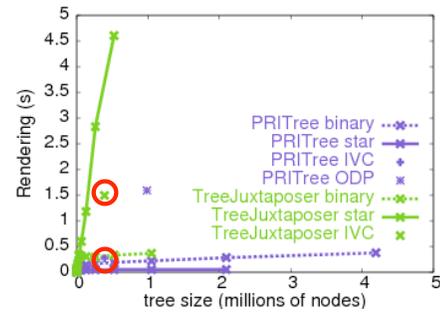
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## PRITree Rendering Time Performance

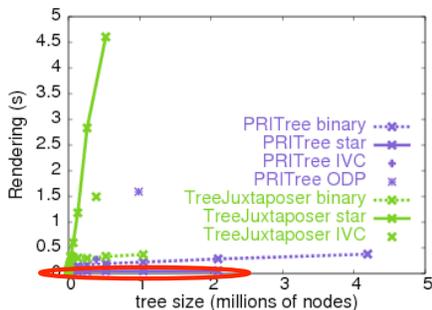
- InfoVis 2003 Contest dataset
- 5x rendering speedup



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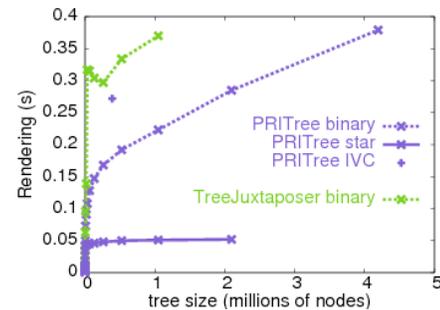
## PRITree Rendering Time Performance

a closer look at the fastest rendering times



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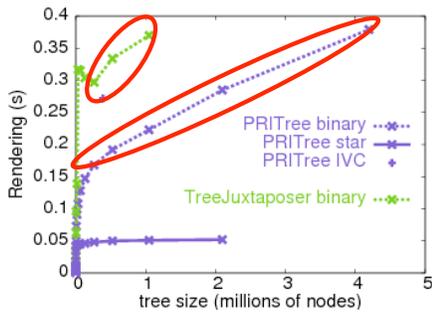
## PRITree Rendering Time Performance



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## Detailed Rendering Time Performance

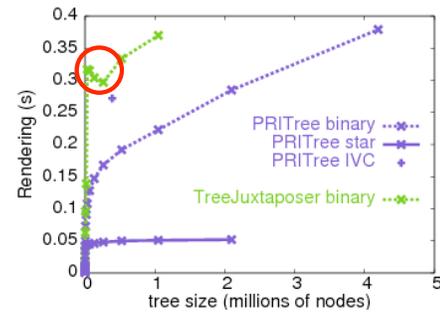
- PRITree handles 4 million nodes in under 0.4 seconds
- TreeJuxtaposer takes twice as long to render 1 million nodes



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## Detailed Rendering Time Performance

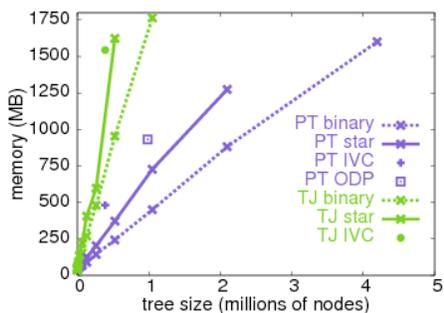
TreeJuxtaposer valley from overculling



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## Memory Performance

- linear memory usage for both applications
- 4-5x more efficient for synthetic datasets



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## Performance Comparison

- PRITree vs. TreeJuxtaposer
  - detailed benchmarks against identical TJ functionality
    - 5x faster, 8x smaller footprint
    - handles over 4M node trees
- PRISeq vs. SequenceJuxtaposer
  - 15x faster rendering, 20x smaller memory size
  - 44 species \* 17K nucleotides = 770K items
  - 6400 species \* 6400 nucleotides = 40M items

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## PRISAD Contributions

- infrastructure for efficient, correct, and generic accordion drawing
- efficient and correct rendering
  - screen-space partitioning tightly bounds overdrawing and eliminates overculling
- first generic AD infrastructure
  - PRITree renders 5x faster than TJ
  - PRISeq renders 20x larger datasets than SJ
- future work
  - editing support

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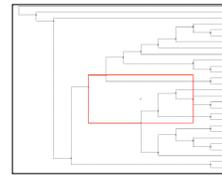
## Evaluation

- evaluate RSN navigation technique
  - compare to conventional pan/zoom
- clarify utility of overviews for navigation
  - why add overview to F+C?
    - Need evidence to support or refute common InfoVis assumption regarding usefulness of overviews

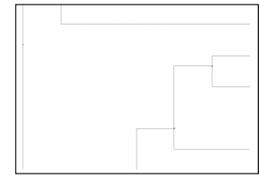
[An Evaluation of Pan & Zoom and Rubber Sheet Navigation with and without an Overview. Dmitry Nekrasovski, Adam Bodnar, Joanna McGrenere, François Guimbretière, and Tamara Munzner. Proc. SIGCHI 06. 55

## Conventional Pan & Zoom (PZN)

- navigation via panning (translation) and zooming (uniform scale changes)
- easy to lose context and become lost



Selecting region to zoom

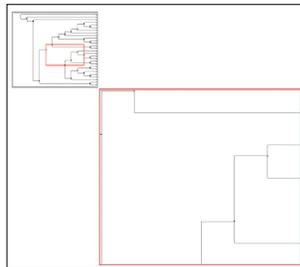


Zooming result

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## Overviews

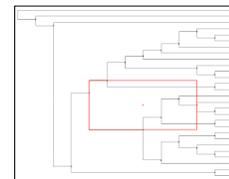
- separate global view of the dataset
- maintain contextual awareness
- force attention split between views



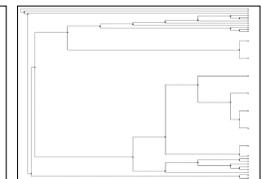
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## Rubber Sheet Navigation (RSN)

- Focus + Context technique
- stretching and squishing rubber sheet metaphor
- maintain contextual awareness in single view



Selecting region to zoom



Zooming result

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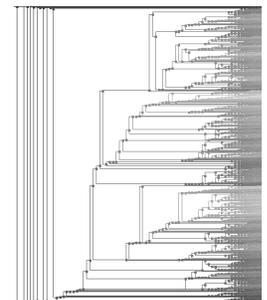
## Previous Findings Mixed

- mixed results for navigation and overviews
- speed: F+C faster than PZN  
[Schaffer et al., 1996; Gutwin and Skopik, 2003]
- accuracy: PZN more accurate than F+C  
[Hornbaek and Frokjaer, 2001; Gutwin and Fedak, 2004]
- preference: Overviews generally preferred  
[Beard and Walker, 1990; Plaisant et al., 2002]

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## Dataset

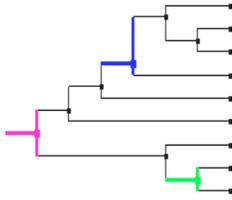
- Motivating domain: evolutionary biology
  - large datasets, clear tasks
  - require understanding topological structure at different places and scales
- 5,918 node binary tree
  - Leaves are species, internal nodes are ancestors



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## Task

- Generalized version requiring no specialized knowledge of evolutionary trees (no labels)
- Compare topological distance between marked nodes
- Requires multiple navigation actions to complete
- Several instances isomorphic in difficulty



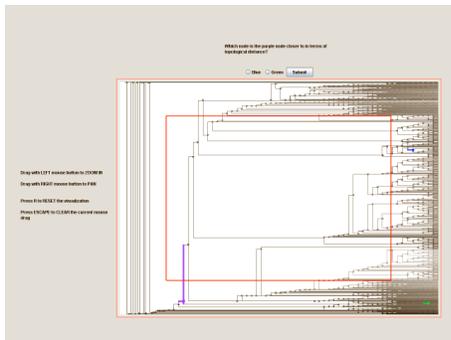
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## Experiment Interfaces

- Common visual representation and interaction model
  - Lacking in majority of previous evaluations
- Common set of navigation actions
- Guarantee visibility of areas of interest

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## RSN



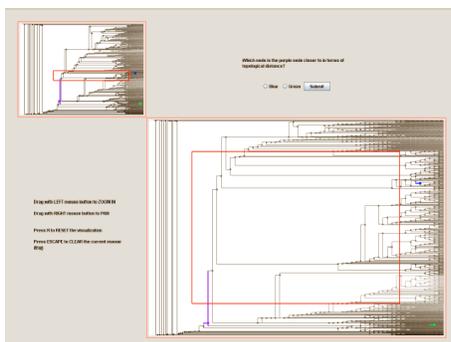
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## PZN



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## RSN + Overview



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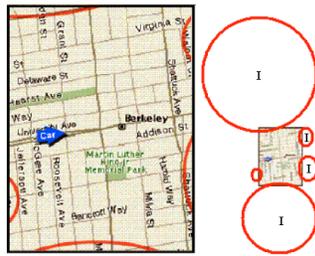
## PZN + Overview



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## Guaranteed Visibility

- PZN
  - Implemented in PZN similarly to Halo [Baudisch et al., 2003]
- RSN
  - Implicit as areas of interest compressed along bounds of display
- Sub-pixel marked regions always drawn using PRISAD framework [Slack et al., 2005]



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## Hypotheses

- H1 - RSN performs better than PZN independent of overview presence
- H2 - For RSN, presence of overview does not result in better performance
- H3 - For PZN, presence of overview results in better performance

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## Design

- 2 (navigation, between) x 2 (presence of overview, between) x 7 (blocks, within)
- Each block contained 5 randomized trials
- 40 subjects, each randomly assigned to each interface

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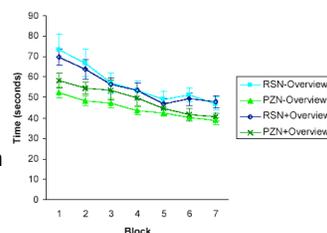
## Procedure and Measures

- Training protocols used to train subjects in effective strategies to solve task
- Subjects completed 35 trials (7 blocks x 5 trials), each isomorphic in difficulty
- Completion time, navigation actions, resets, errors, and subjective NASA-TLX workload

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## Results - Navigation

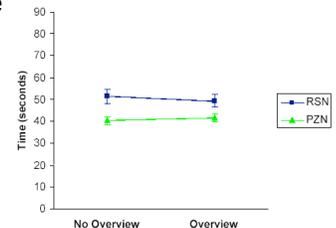
- PZN outperformed RSN ( $p < 0.001$ )
- Learning effect shows performance plateau
- Subjects using PZN performed fewer navigation actions and fewer resets
- Subjects using PZN reported less mental demand ( $p < 0.05$ )



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## Results – Presence of Overview

- No effect on any performance measure
- Subjects using overviews reported less physical demand and more enjoyment ( $p < 0.05$ )



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## Summary of Results

- H 1 - RSN performs better than PZN independent of overview presence
  - No – PZN outperformed RSN
- H 2 - For RSN, presence of overview does not result in better performance
  - Yes – No effect of overview on performance
- H 3 - For PZN, presence of overview results in better performance
  - No – No effect of overview on performance

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## Discussion – Navigation

- Performance differences cannot be ascribed to unfamiliarity with the techniques
- Design guidelines for PZN extensively studied, but not so for F+C or RSN

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## Discussion – Overviews

- Overviews for PZN and RSN:
  - No performance benefits
  - Preference for overview
- Overview may act as *cognitive cushion*
  - Provide subjective but not performance benefits
- Guaranteed visibility may provide same benefits as overviews

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## Evaluation Conclusions

- First evaluation comparing PZN and RSN techniques with and without an overview
- Performance:
  - PZN faster and more accurate than RSN
- Preference:
  - Overviews preferred, but no performance benefits

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## Other Projects

- Focus+Context evaluation
  - low-level visual search and visual memory
- graph drawing
  - TopoLayout: multi-level decomposition and layout using topological features
- dimensionality reduction
  - MDSteer: progressive and steerable MDS
- papers, talks, videos available from <http://www.cs.ubc.ca/~tmm>

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