

Scalable Visual Comparison of Biological Trees and Sequences

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Imager

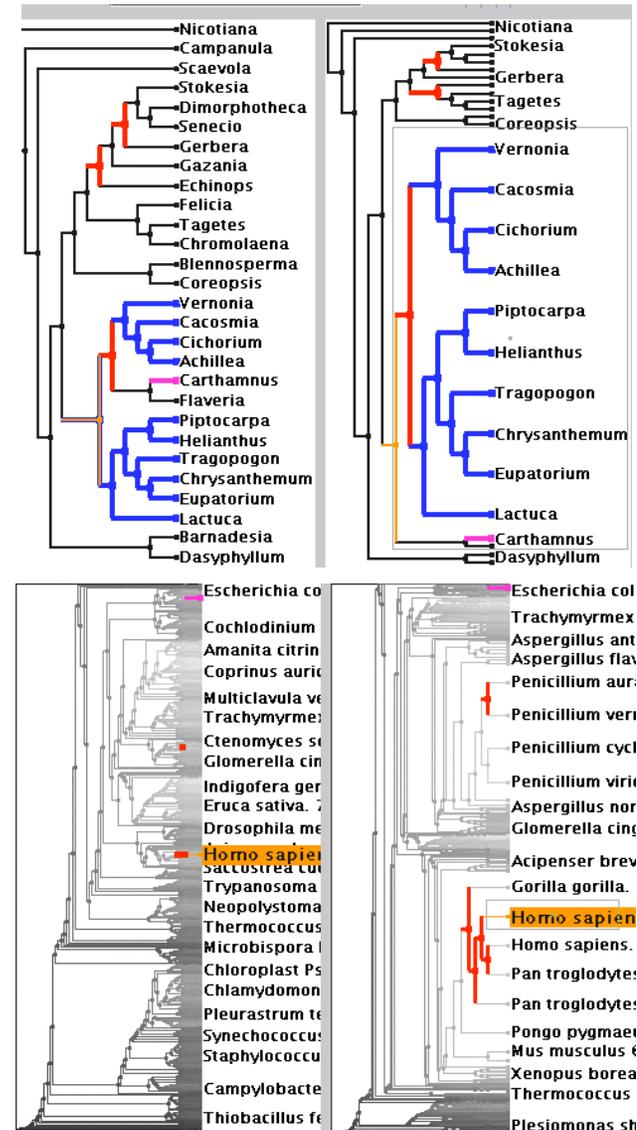


Outline

- **Accordion Drawing**
 - information visualization technique
- **TreeJuxtaposer**
 - tree comparison
- **SequenceJuxtaposer**
 - sequence comparison
- **PRISAD**
 - generic accordion drawing framework

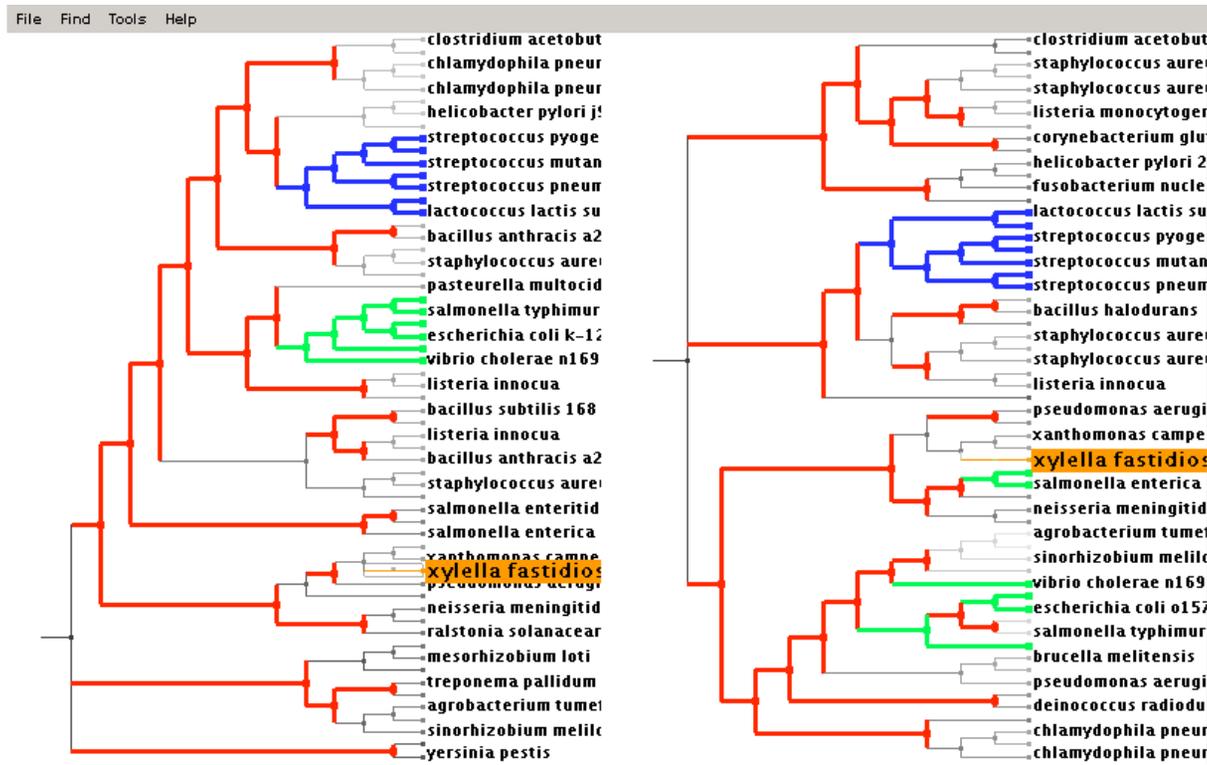
Accordion Drawing

- rubber-sheet navigation
 - stretch out part of surface, the rest squishes
 - borders nailed down
 - Focus+Context technique
 - integrated overview, details
 - old idea
 - [Sarkar et al 93], [Robertson et al 91]
- guaranteed visibility
 - marks always visible
 - important for scalability
 - new idea
 - [Munzner et al 03]



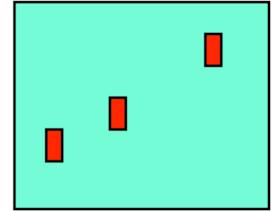
Guaranteed Visibility

- marks are always visible
- easy with small datasets



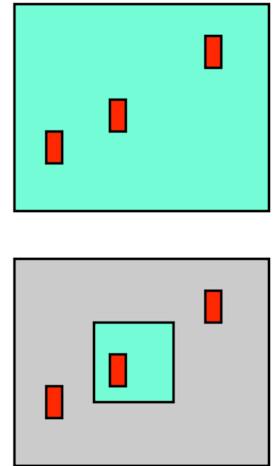
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible



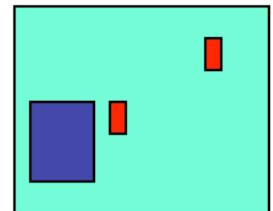
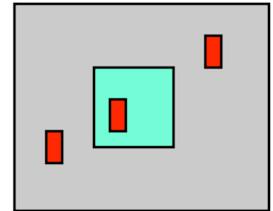
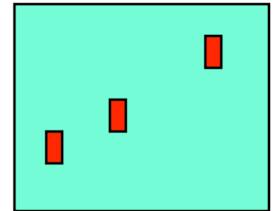
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation



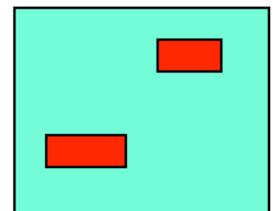
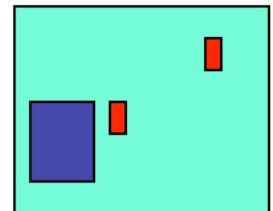
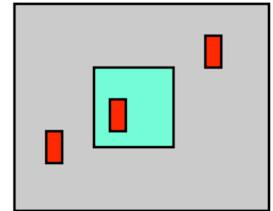
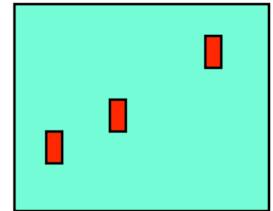
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation
 - underneath other marks
 - AD solution: avoid 3D



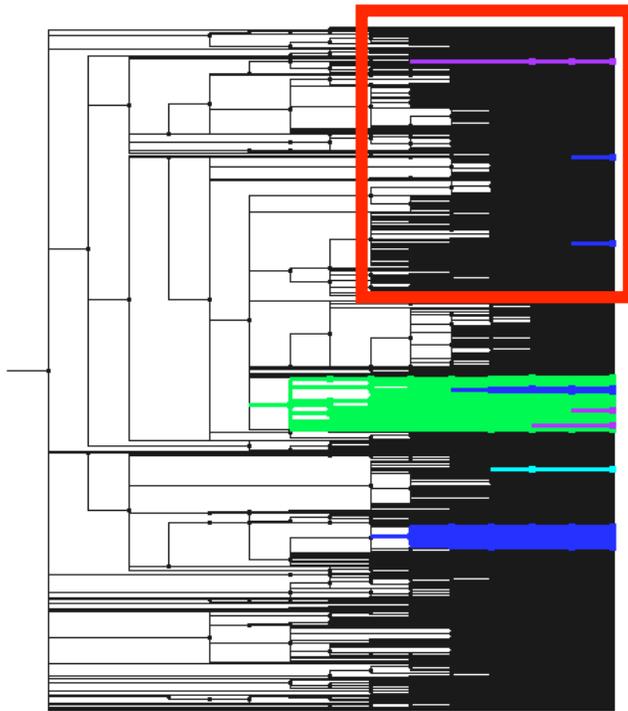
Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation
 - underneath other marks
 - AD solution: avoid 3D
 - smaller than a pixel
 - AD solution: smart culling

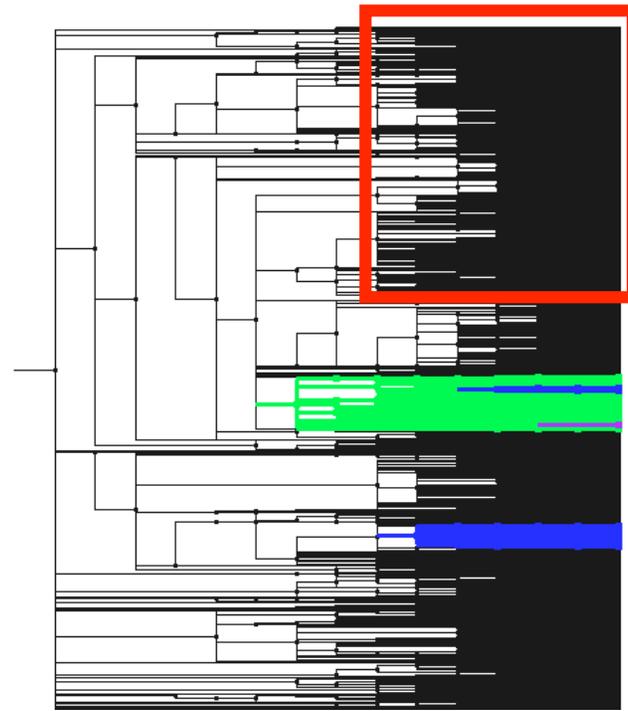


Guaranteed Visibility: Small Items

- Naïve culling may not draw all marked items



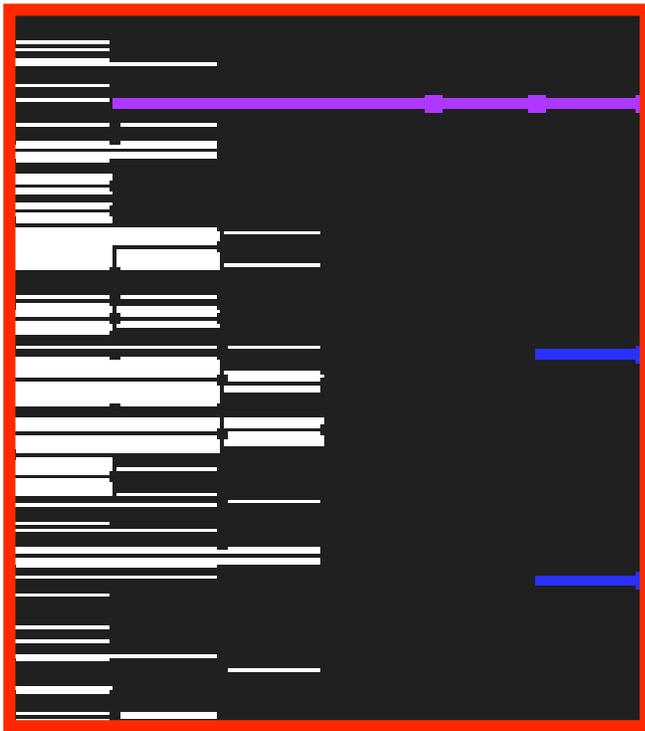
**Guaranteed visibility
of marks**



No guaranteed visibility

Guaranteed Visibility: Small Items

- Naïve culling may not draw all marked items



**Guaranteed visibility
of marks**

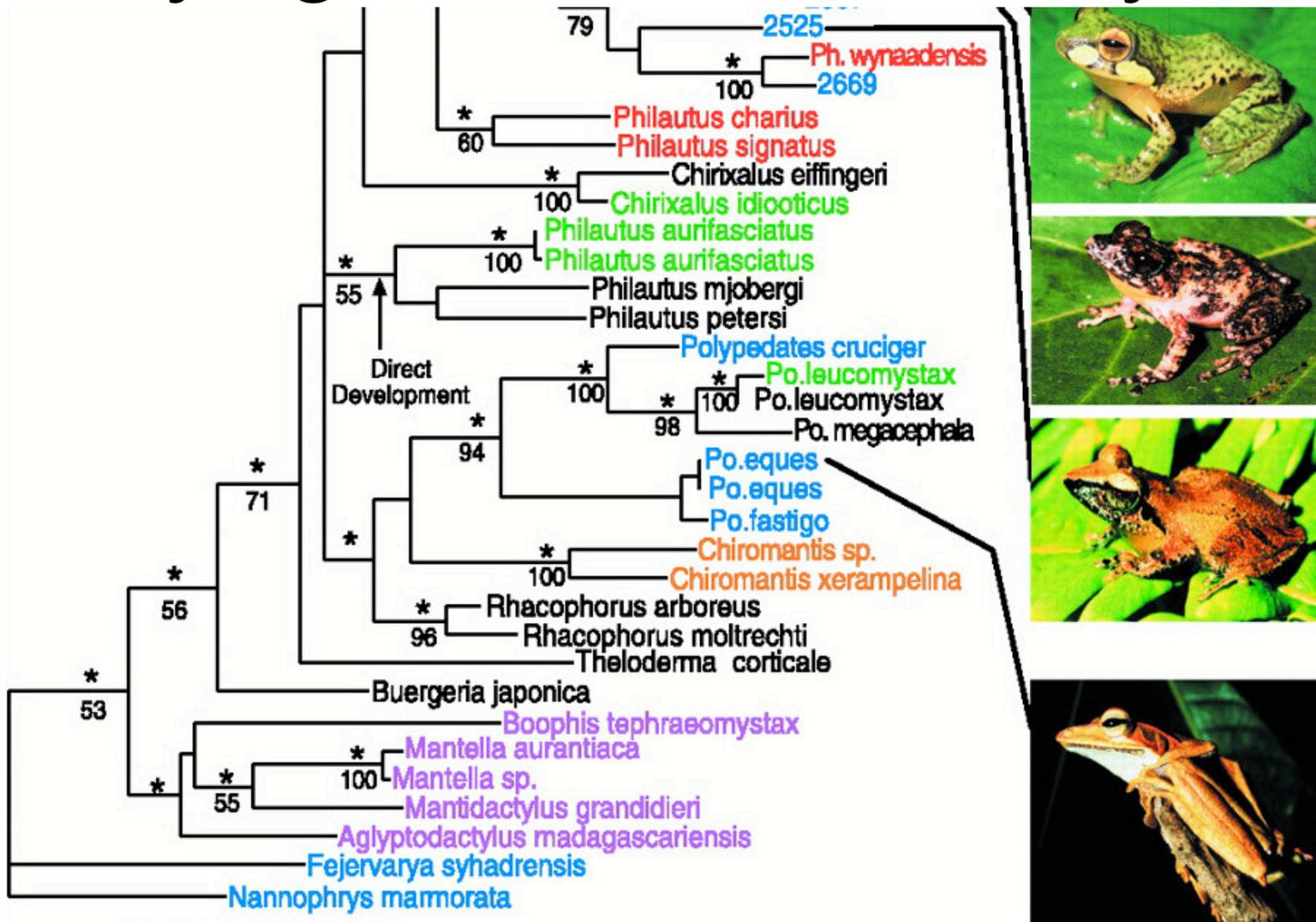


No guaranteed visibility

Outline

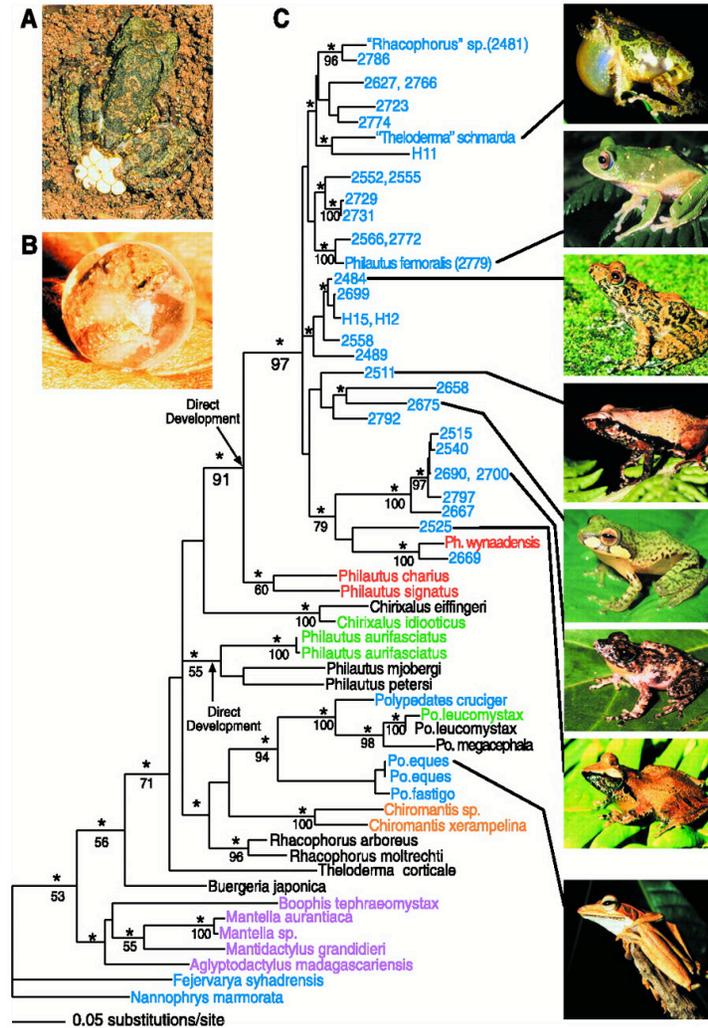
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Phylogenetic/Evolutionary Tree

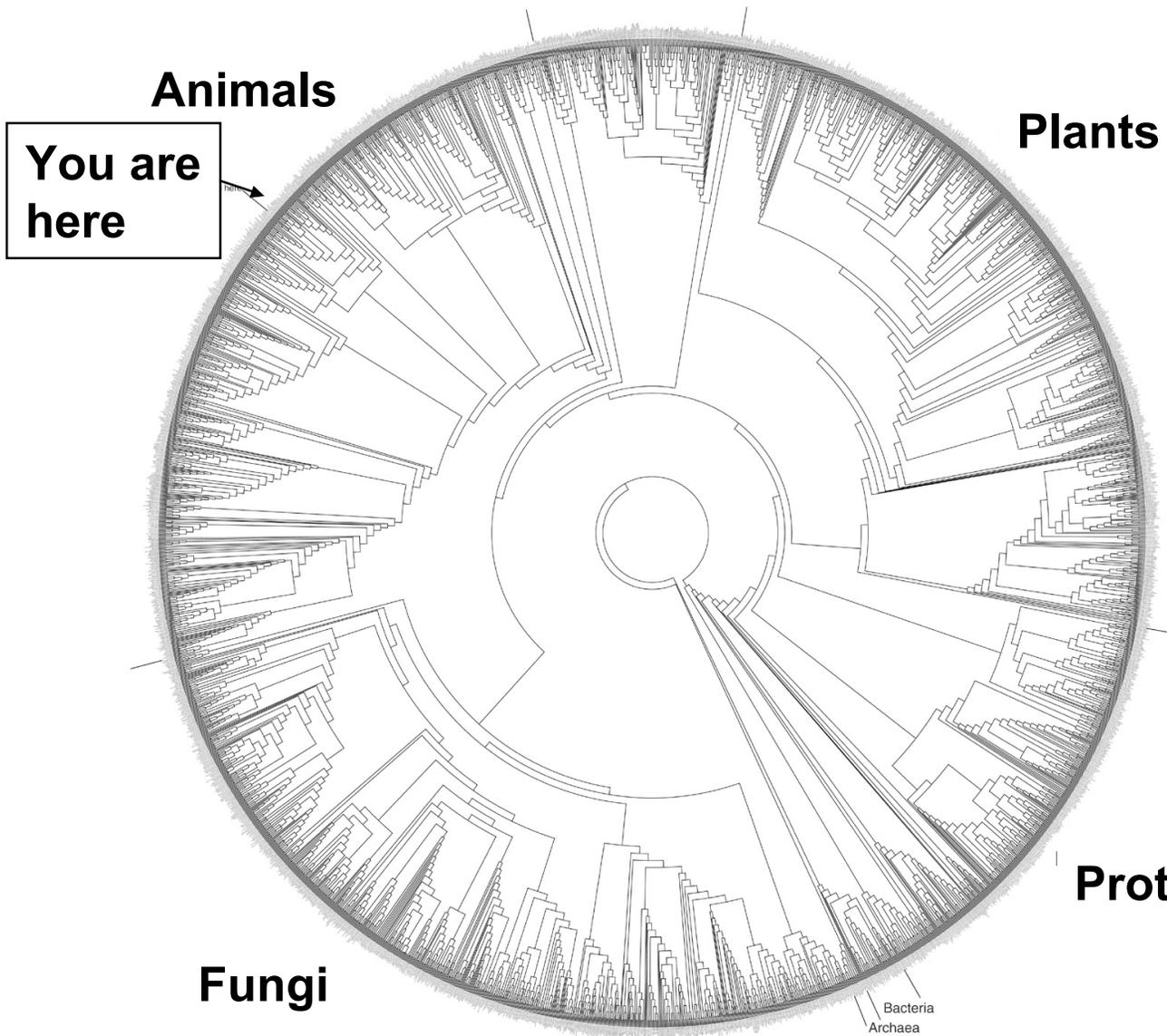


M Meegaskumbura et al., Science 298:379 (2002)

Common Dataset Size Today

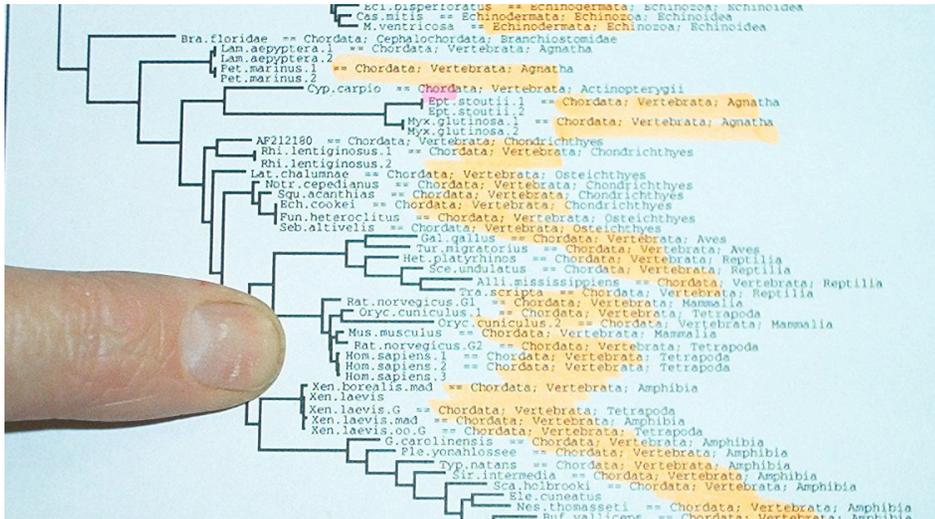


Future Goal: 10M node Tree of Life

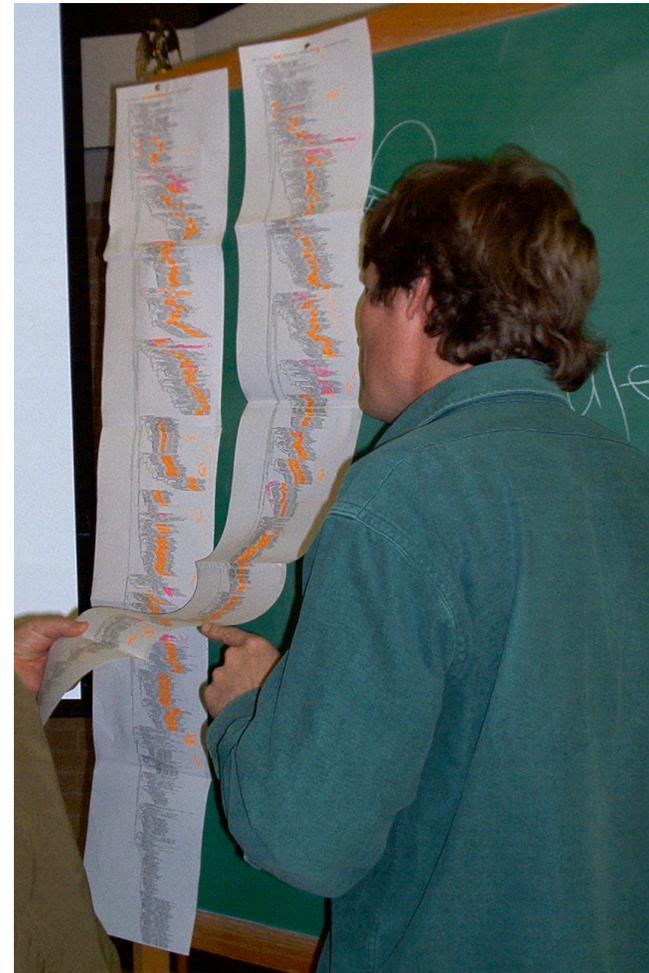


Paper Comparison: Multiple Trees

focus

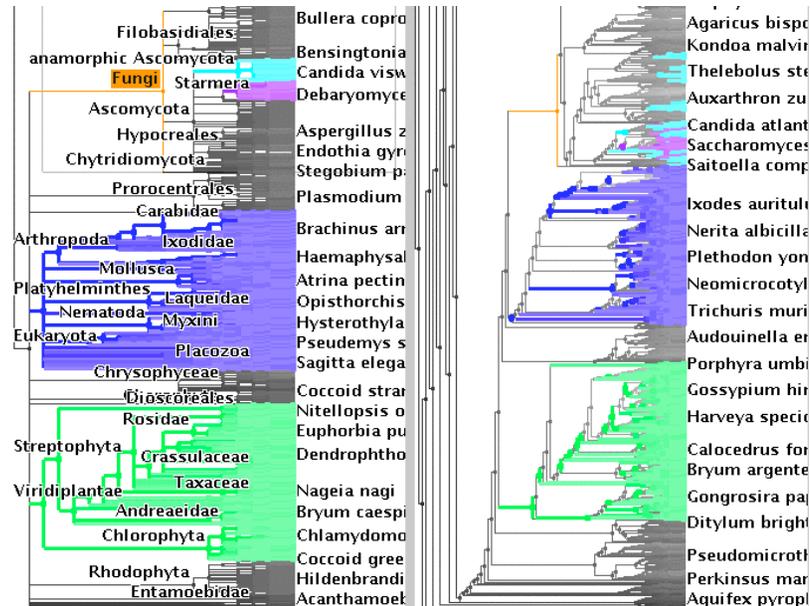
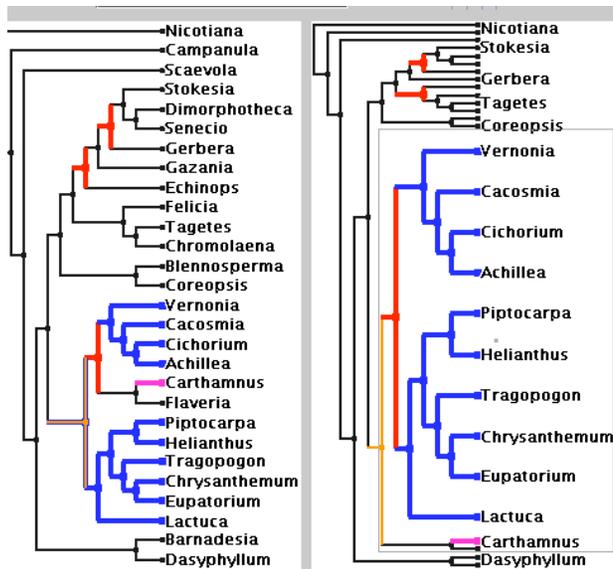


context



TreeJuxtaposer

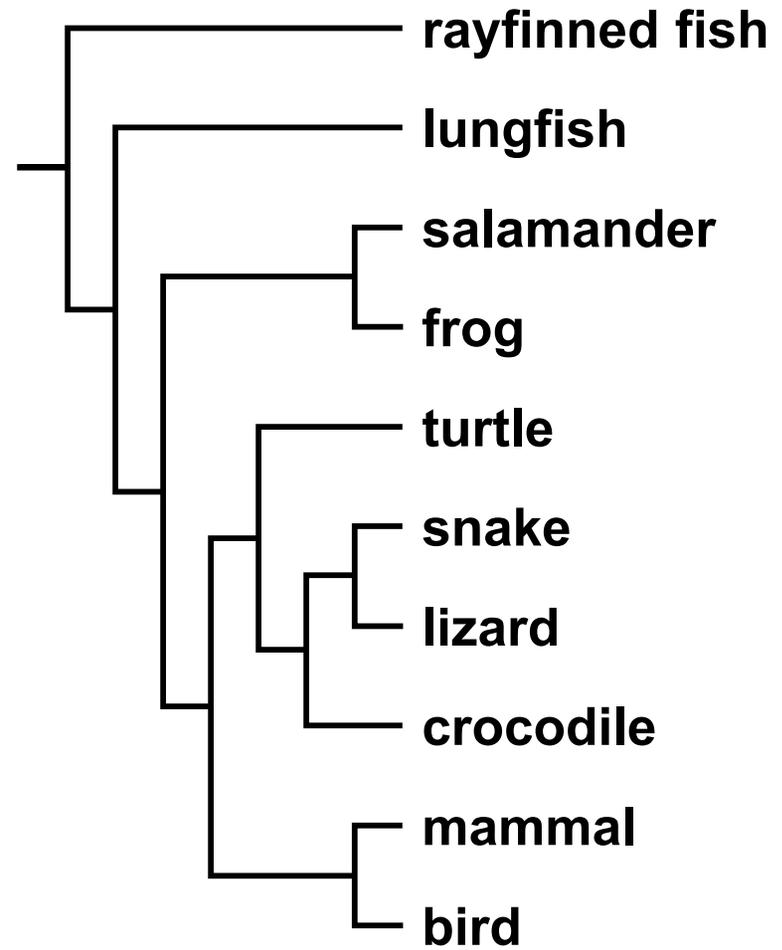
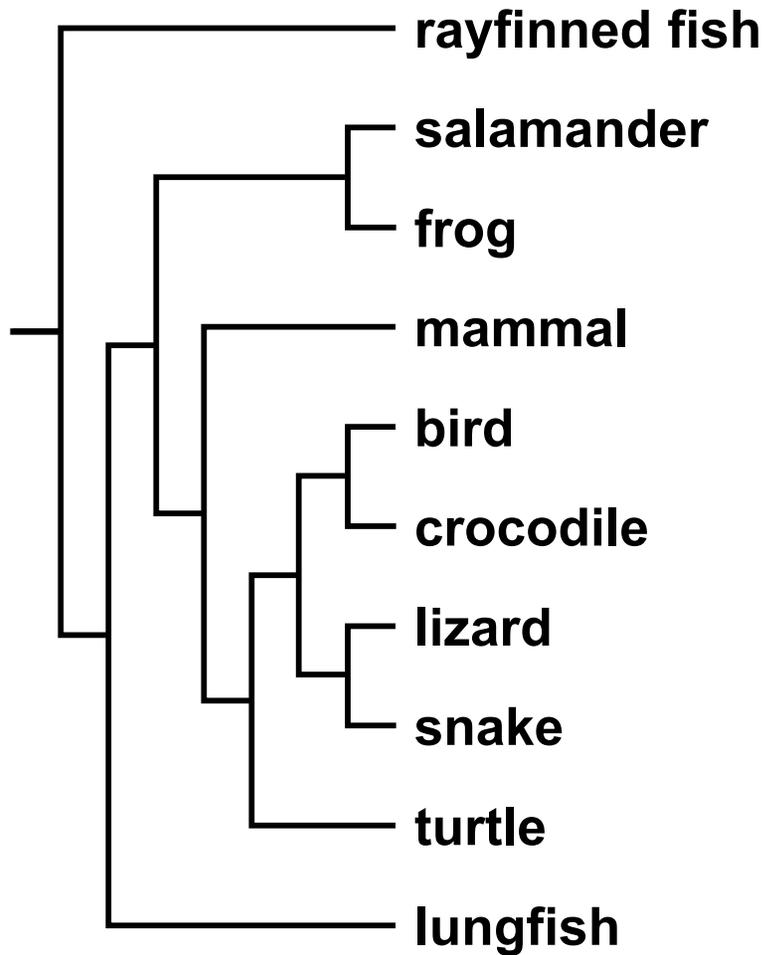
- side by side comparison of evolutionary trees
- [video]
 - video/software downloadable from <http://olduvai.sf.net/tj>



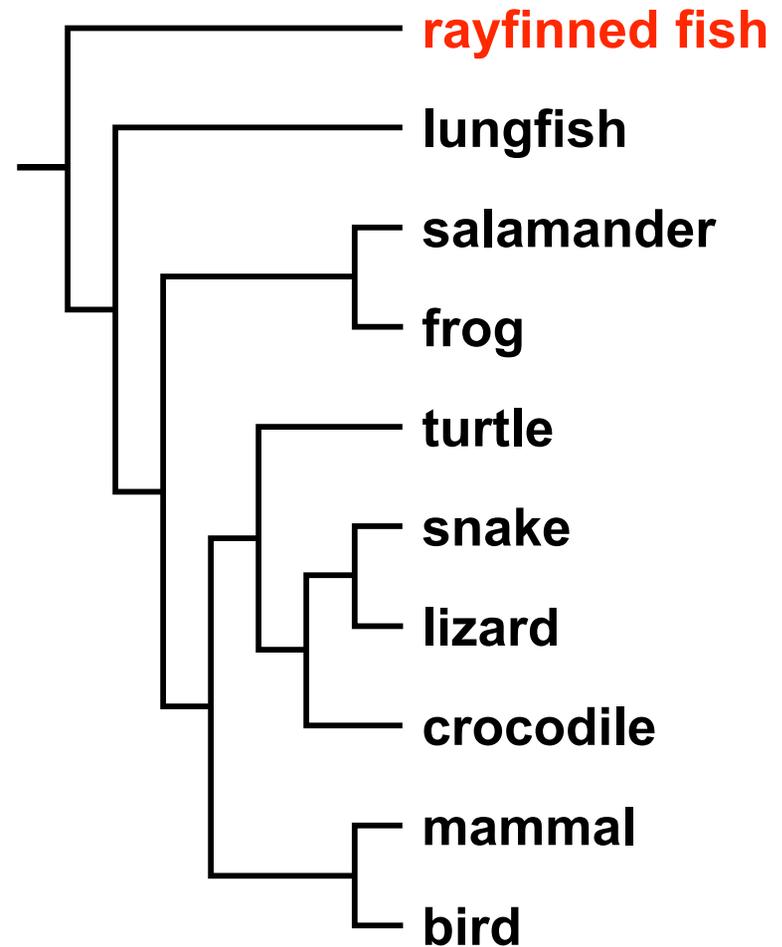
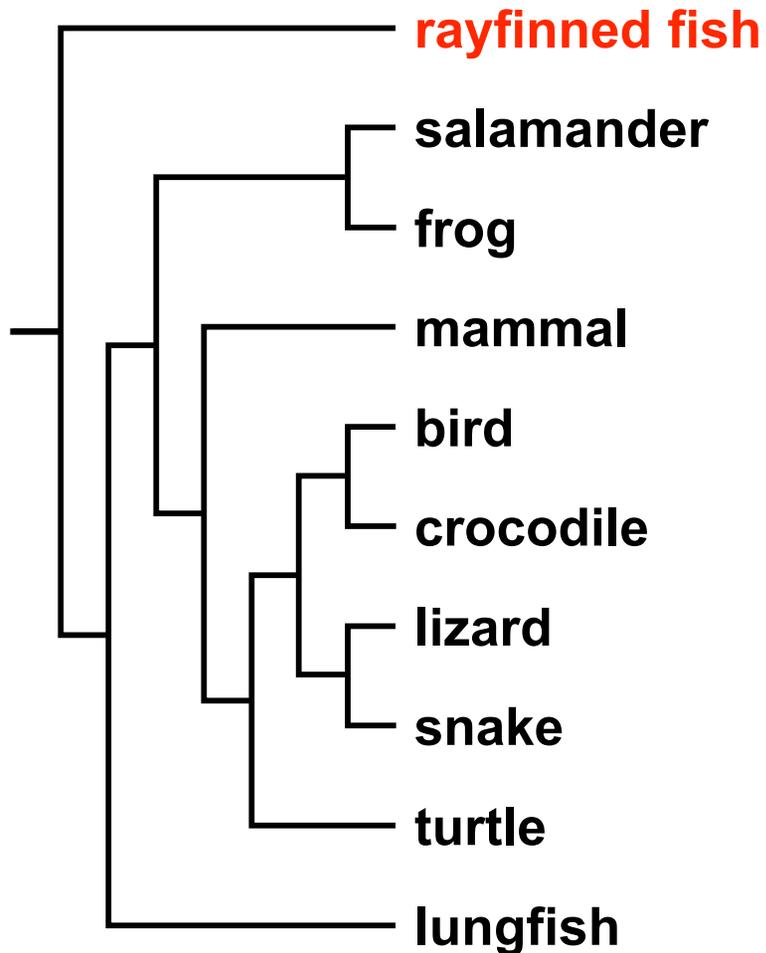
TJ Contributions

- first interactive tree comparison system
 - automatic structural difference computation
 - guaranteed visibility of marked areas
- scalable to large datasets
 - 250,000 to 500,000 total nodes
 - all preprocessing subquadratic
 - all realtime rendering sublinear
- scalable to large displays (4000 x 2000)
- introduced
 - guaranteed visibility, accordion drawing

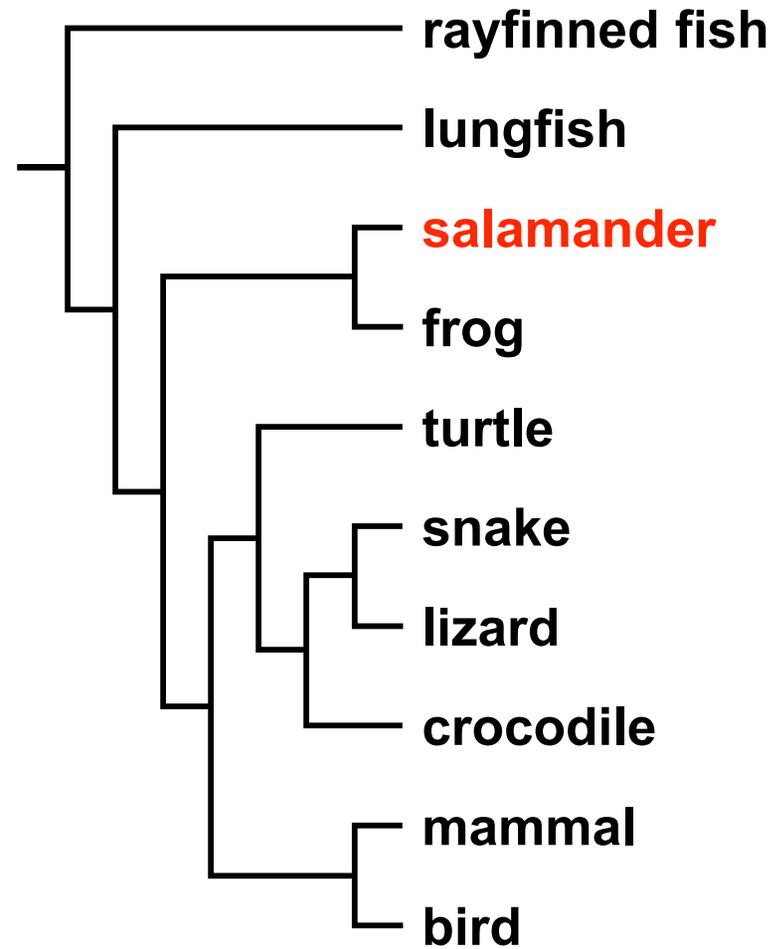
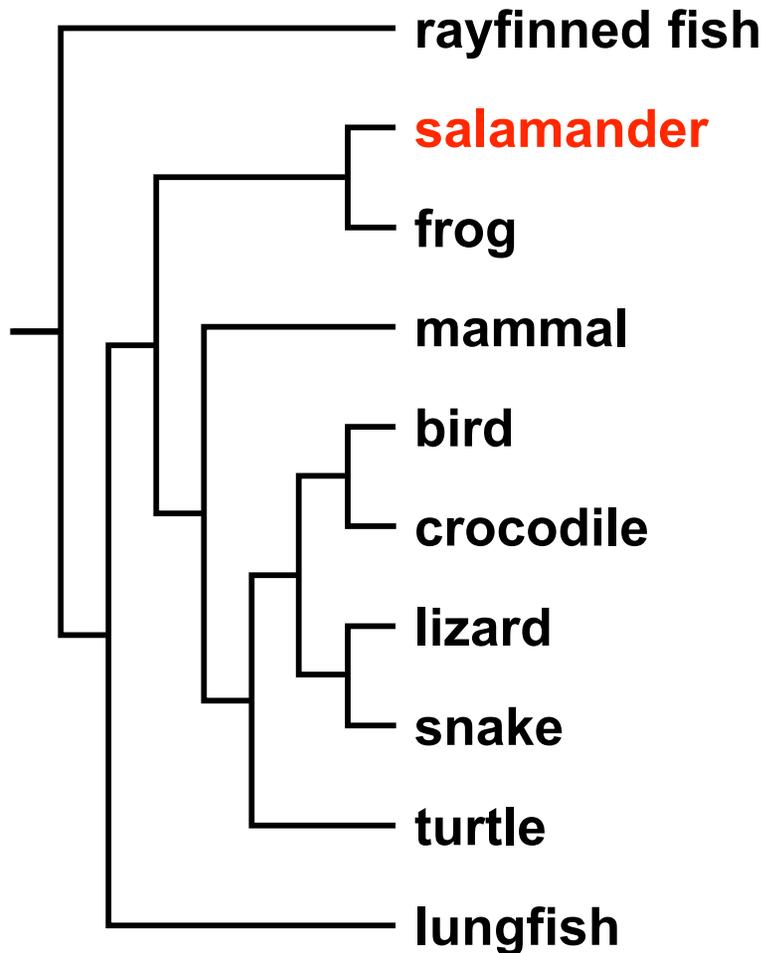
Structural Comparison



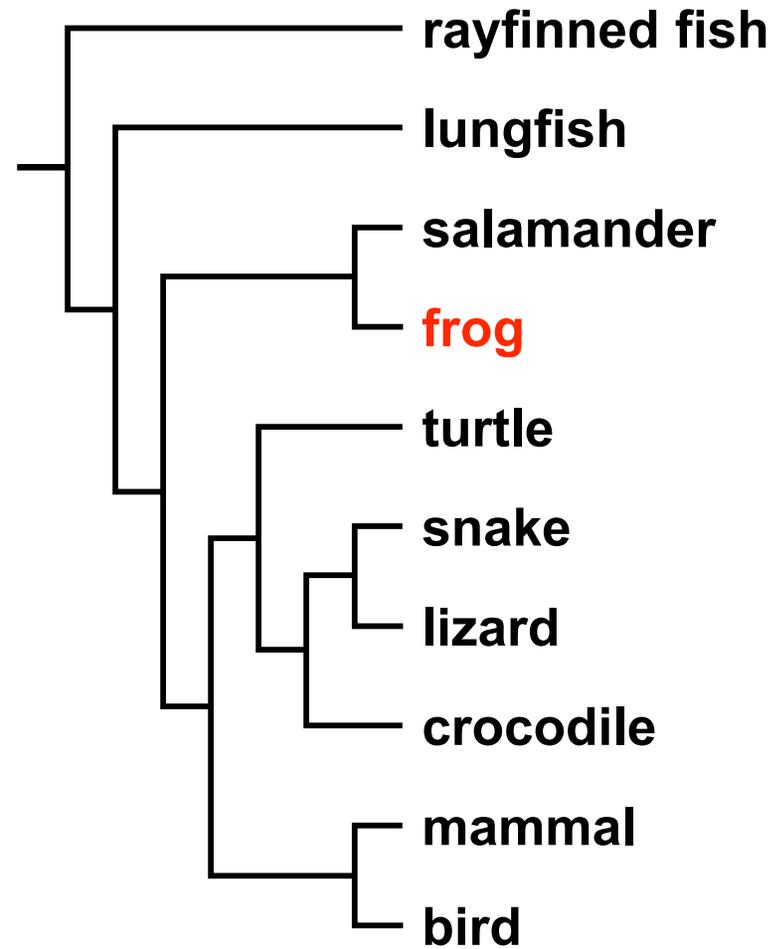
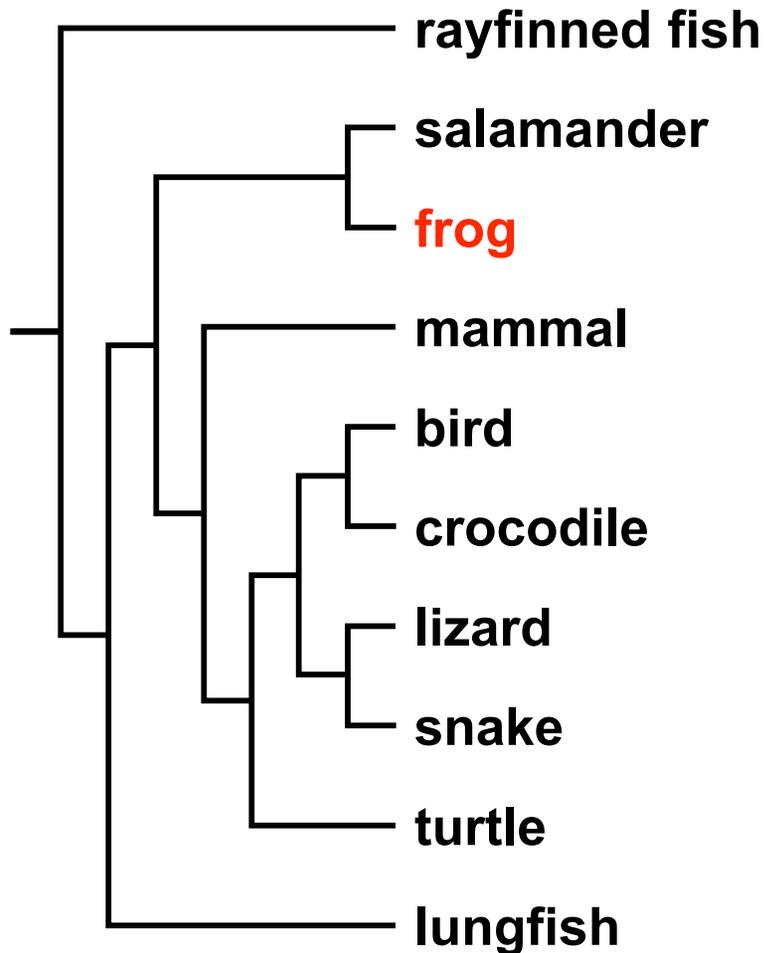
Matching Leaf Nodes



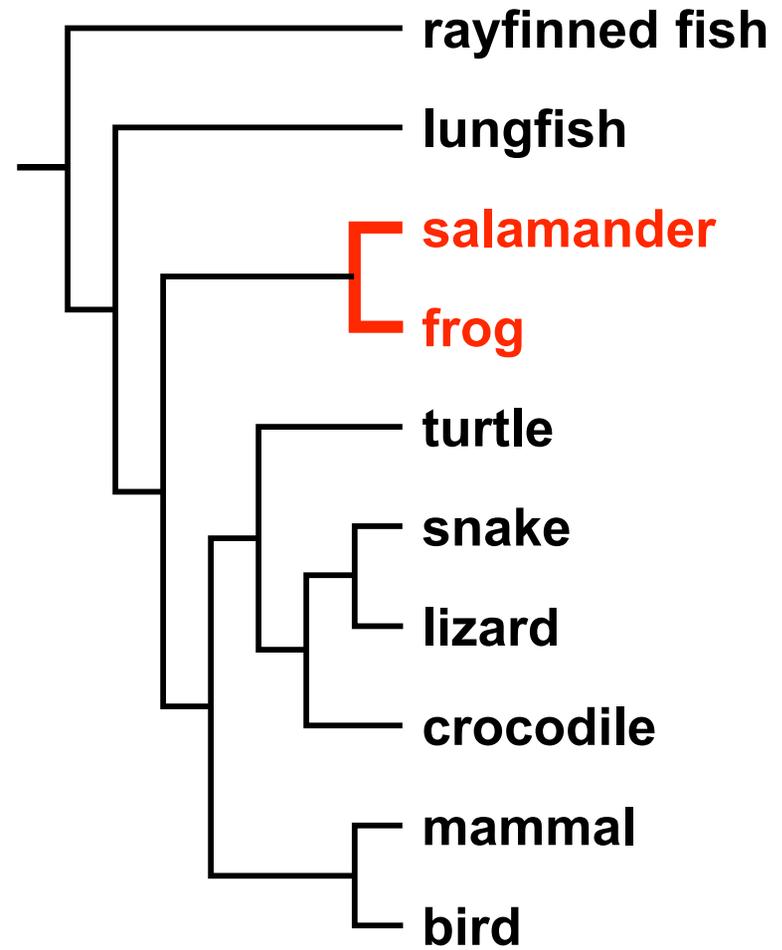
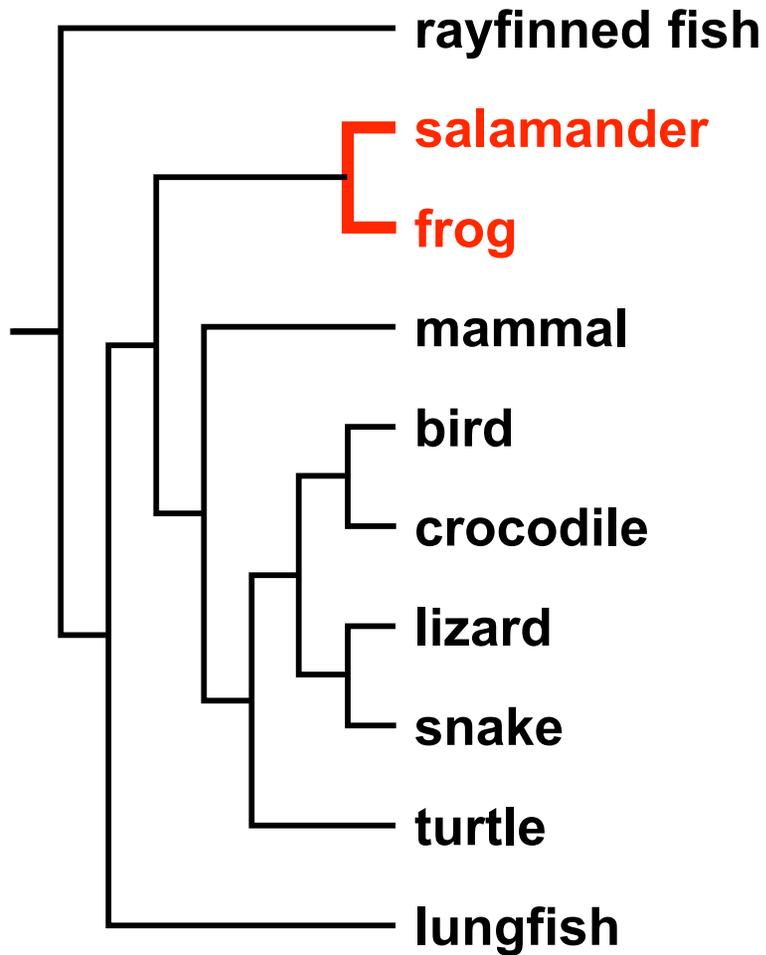
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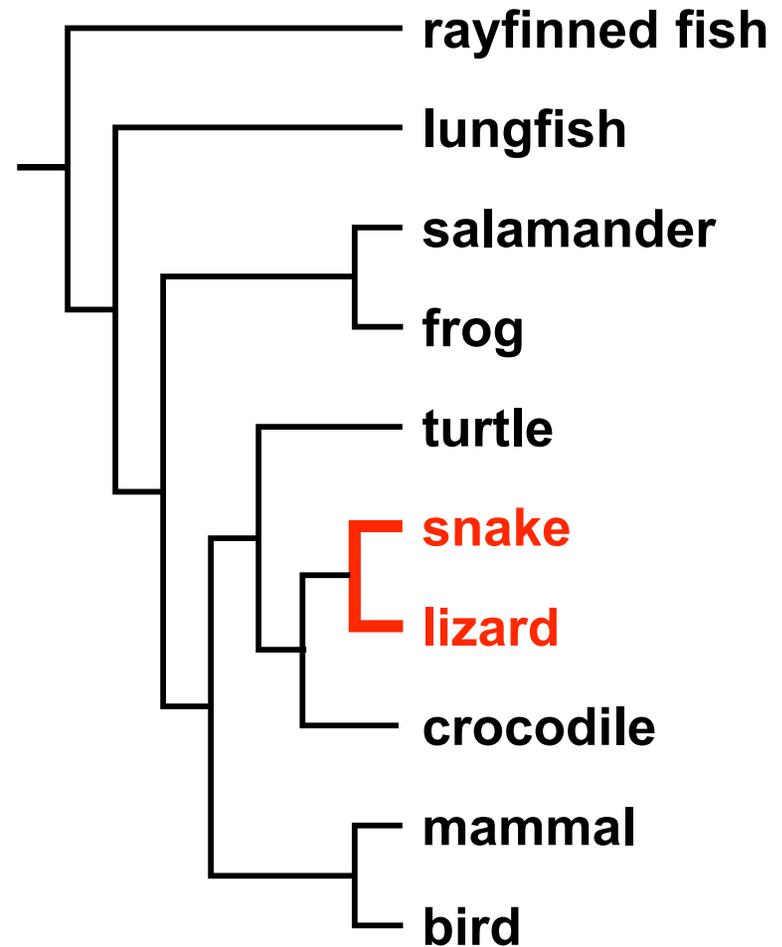
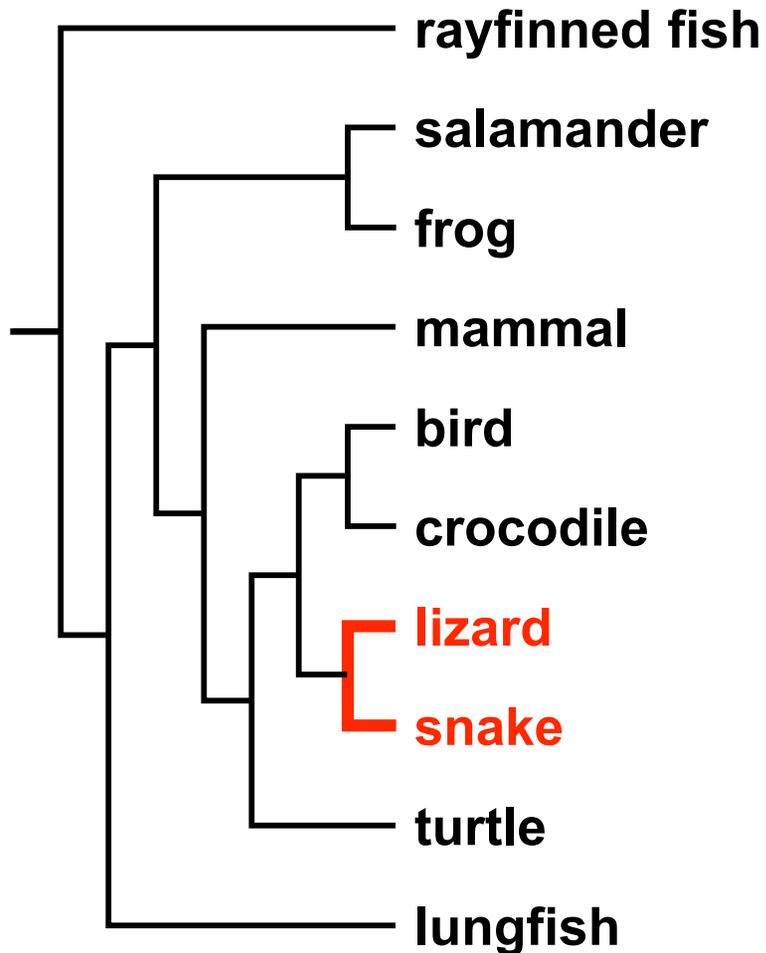
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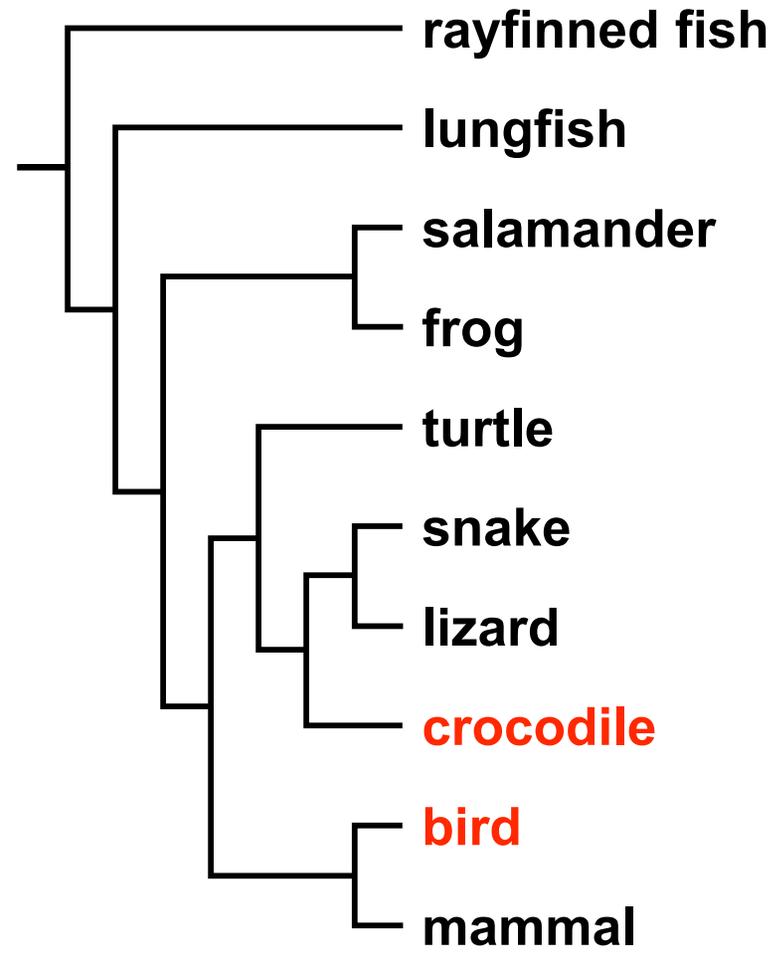
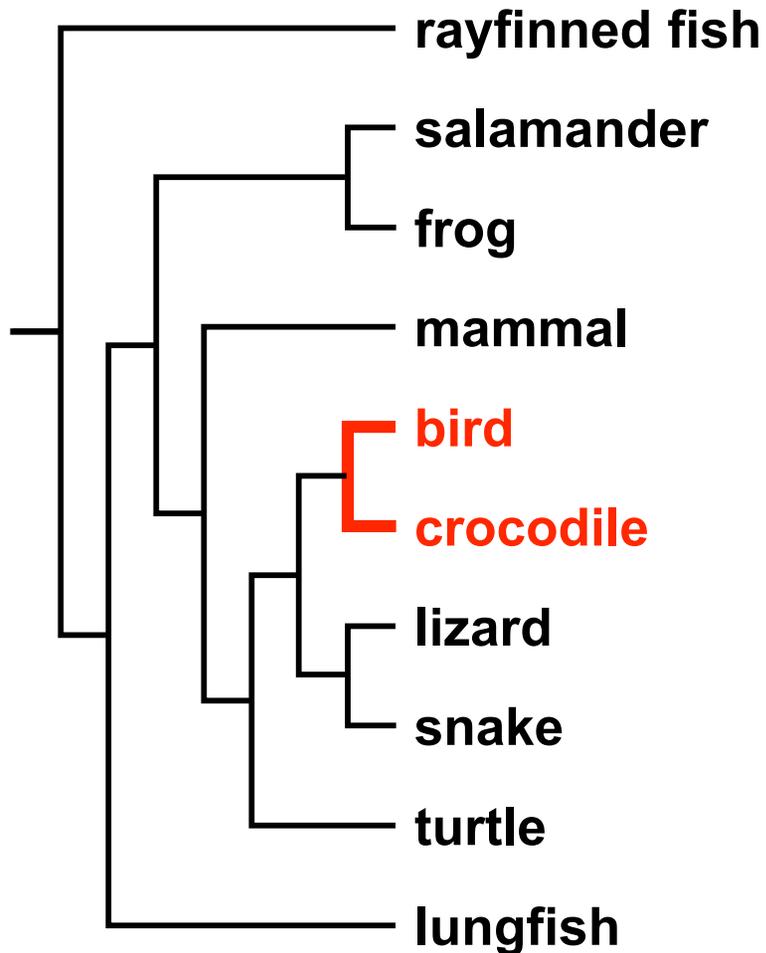
Matching Interior Nodes



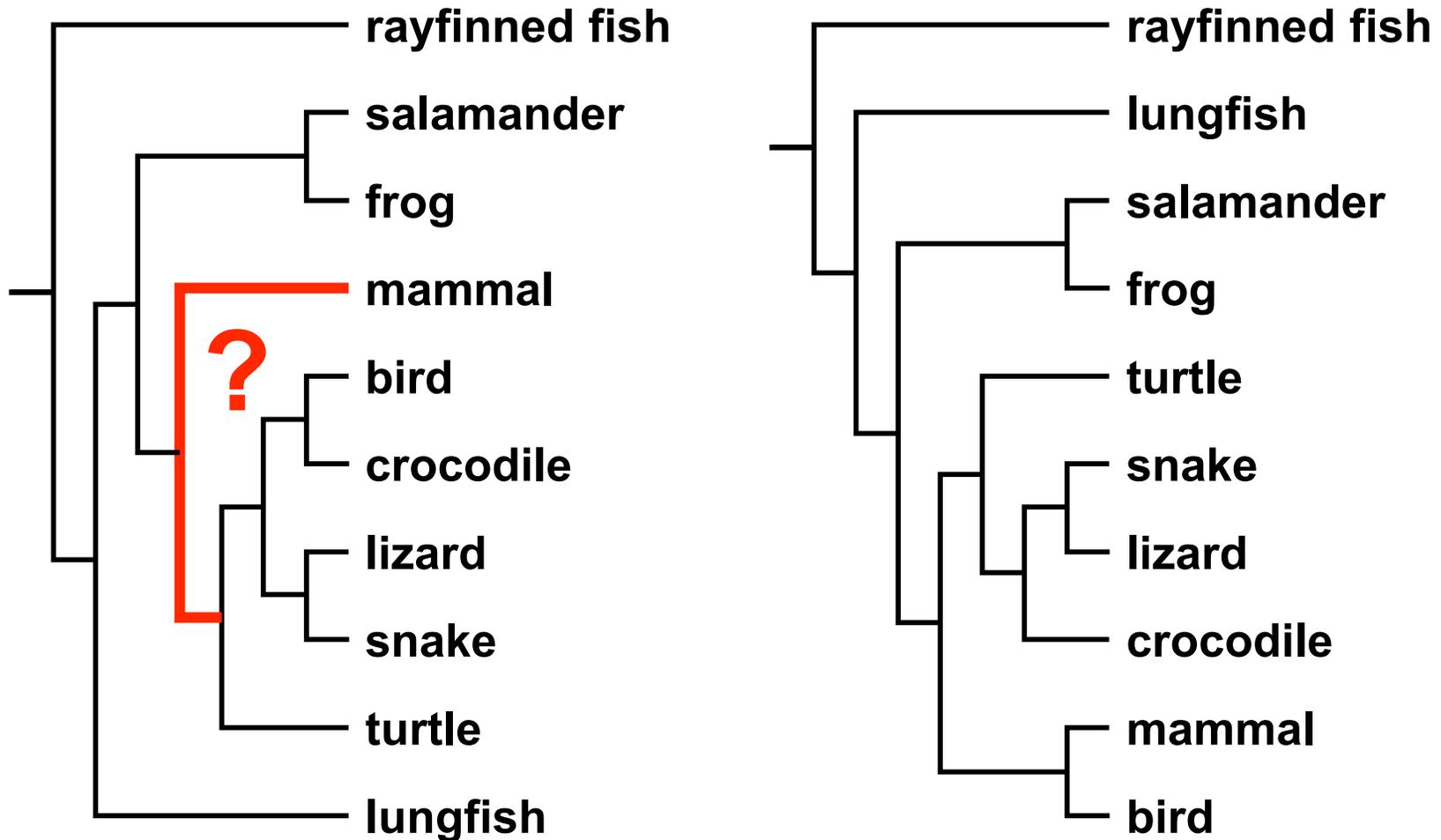
Matching Interior Nodes



Matching Interior Nodes



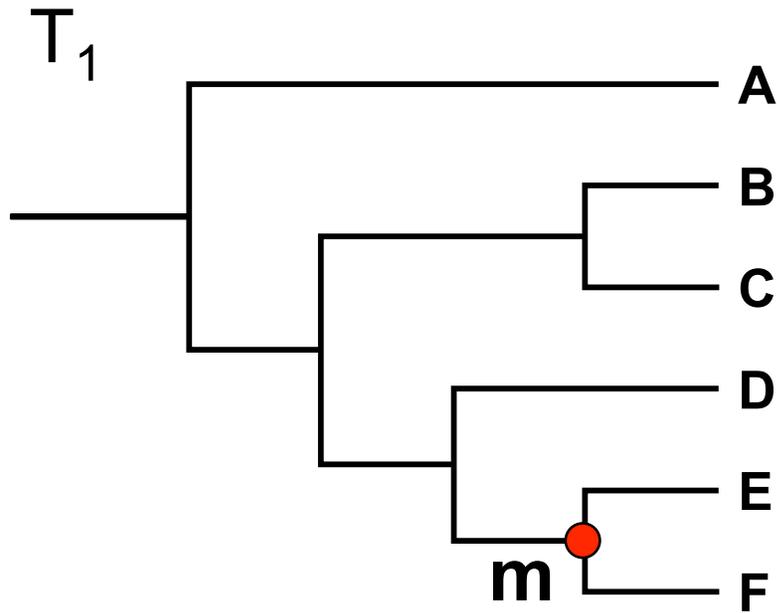
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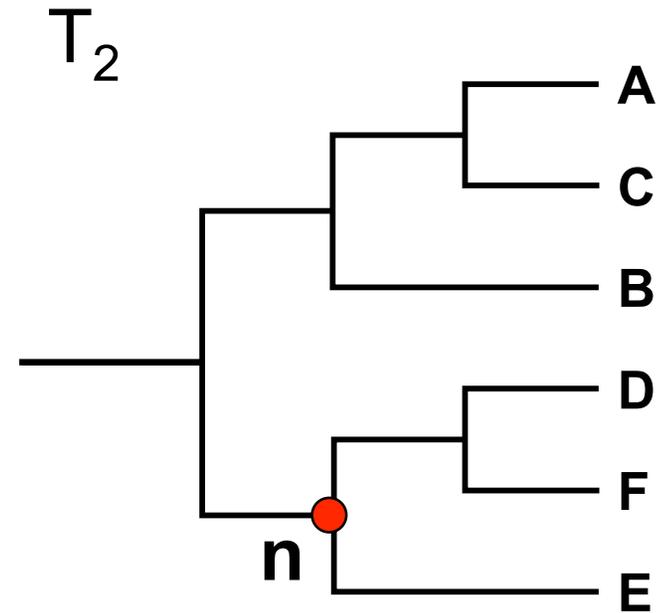
Previous Work

- tree comparison
 - RF distance [Robinson and Foulds 81]
 - perfect node matching [Day 85]
 - creation/deletion [Chi and Card 99]
 - leaves only [Graham and Kennedy 01]

Similarity Score: $S(m,n)$



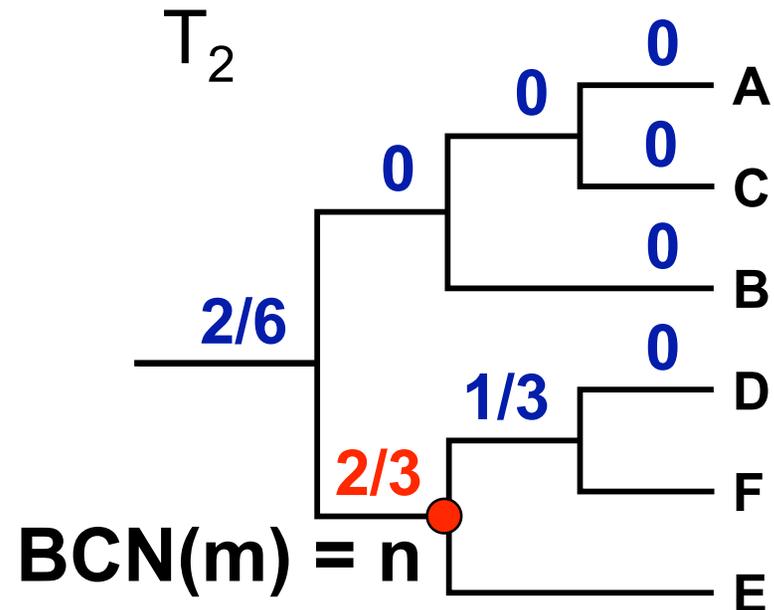
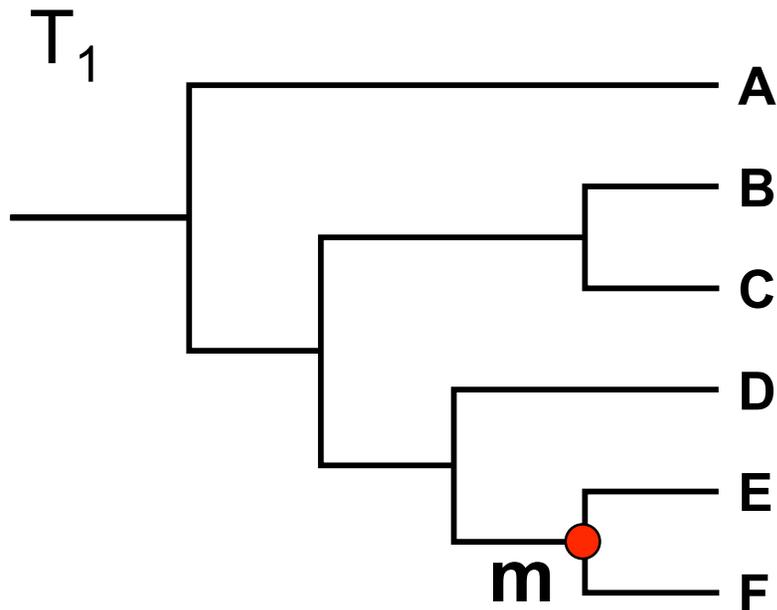
$$L(m) = \{E, F\}$$



$$L(n) = \{D, E, F\}$$

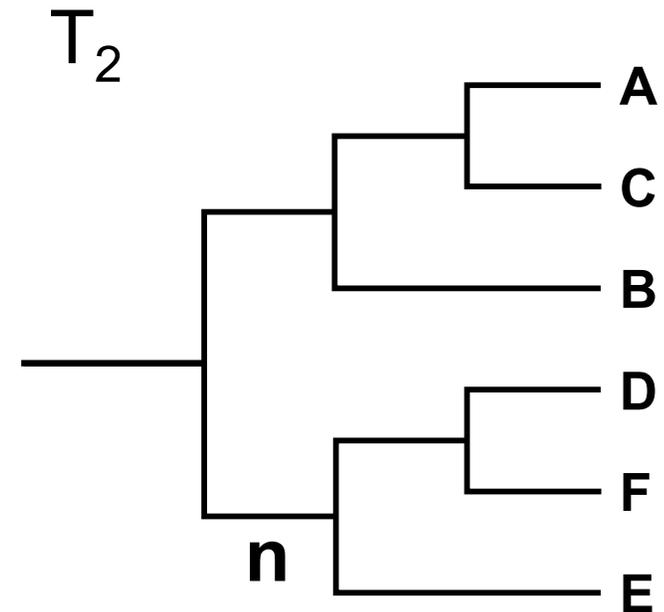
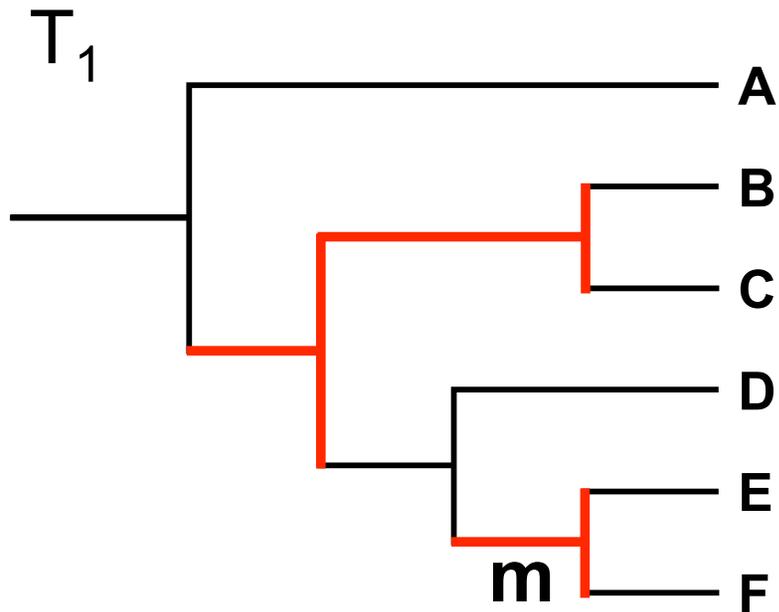
$$S(m,n) = \frac{|L(m) \cap L(n)|}{|L(m) \cup L(n)|} = \frac{|\{E, F\}|}{|\{D, E, F\}|} = \frac{2}{3}$$

Best Corresponding Node



- $BCN(m) = \operatorname{argmax}_{v \in T_2} (S(m, v))$
 - computable in $O(n \log^2 n)$
 - linked highlighting

Marking Structural Differences



- Nodes for which $S(v, \text{BCN}(v)) \neq 1$
 - Matches intuition

Outline

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Genomic Sequences

- multiple aligned sequences of DNA
- now commonly browsed with web apps
 - zoom and pan with abrupt jumps
 - previous work
 - Ensembl [Hubbard 02], UCSC Genome Browser [Kent 02], NCBI [Wheeler 02]
- investigate benefits of accordion drawing
 - showing focus areas in context
 - smooth transitions between states
 - guaranteed visibility for globally visible landmarks

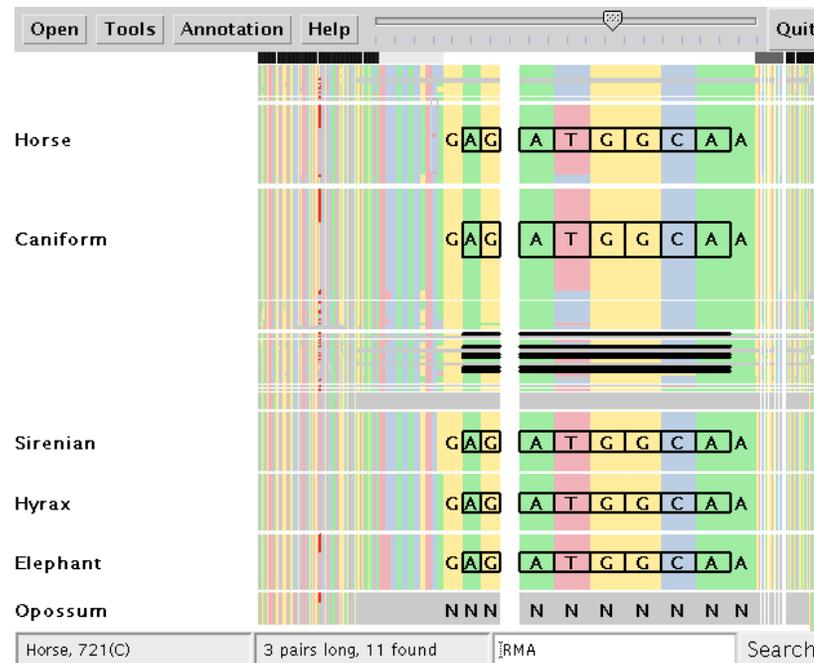
SequenceJuxtaposer

- comparing multiple aligned gene sequences
- provides searching, difference calculation
- [video]
 - video/software downloadable from <http://olduvai.sf.net/tj>



Searching

- search for motifs
 - protein/codon search
 - regular expressions supported
- results marked with guaranteed visibility



SJ Contributions

- fluid tree comparison system
 - showing multiple focus areas in context
 - guaranteed visibility of marked areas
 - thresholded differences, search results
- scalable to large datasets
 - 2M nucleotides
 - all realtime rendering sublinear

Outline

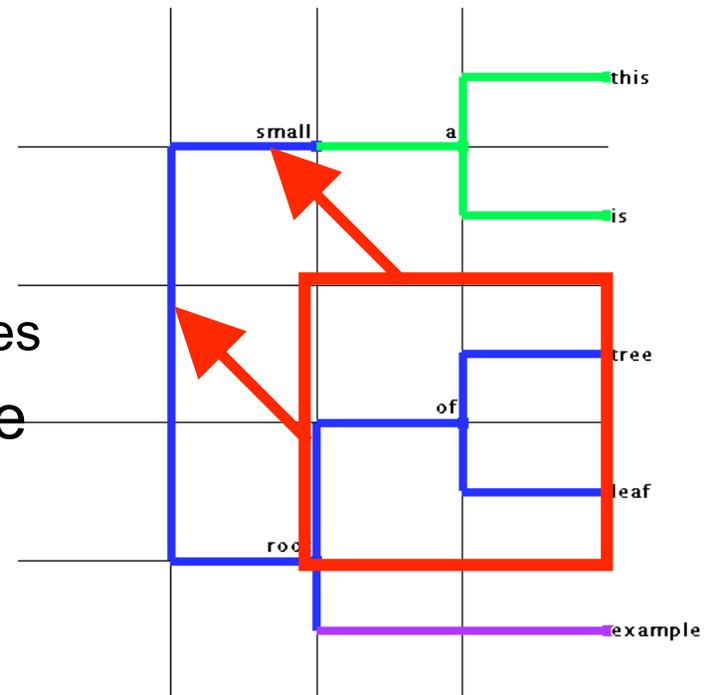
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Goals of PRISAD

- generic AD infrastructure
 - tree and sequence applications
 - PRITree is TreeJuxtaposer using PRISAD
 - PRISeq is SequenceJuxtaposer using PRISAD
- efficiency
 - faster rendering: minimize overdrawing
 - smaller memory footprint
- correctness
 - rendering with no gaps: eliminate overculling

PRISAD Navigation

- generic navigation infrastructure
 - application independent
 - uses deformable grid
 - split lines
 - Grid lines define object boundaries
 - horizontal and vertical separate
 - Independently movable



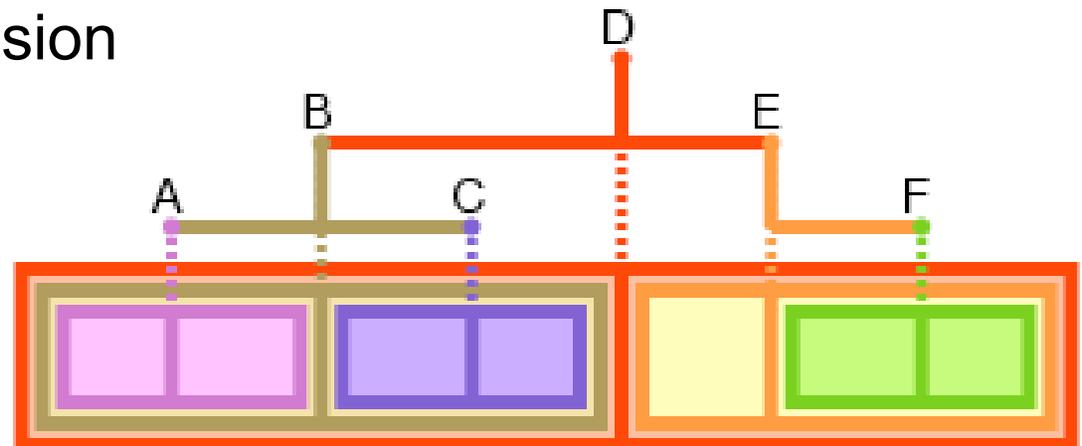
Split line hierarchy

- data structure supports navigation, picking, drawing
- two interpretations

– linear ordering



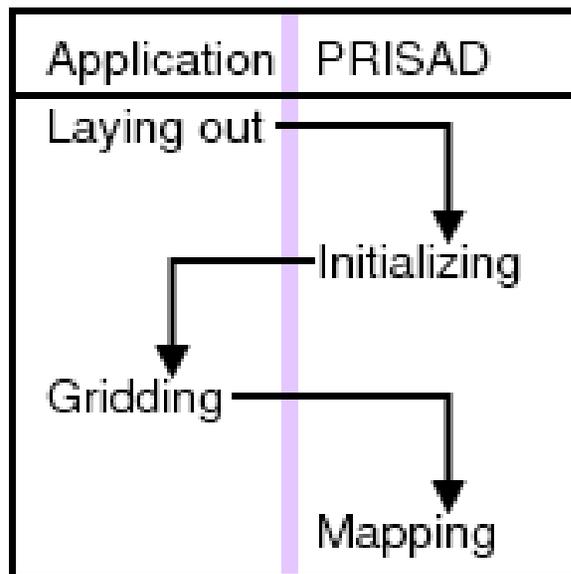
– hierarchical subdivision



PRISAD Architecture

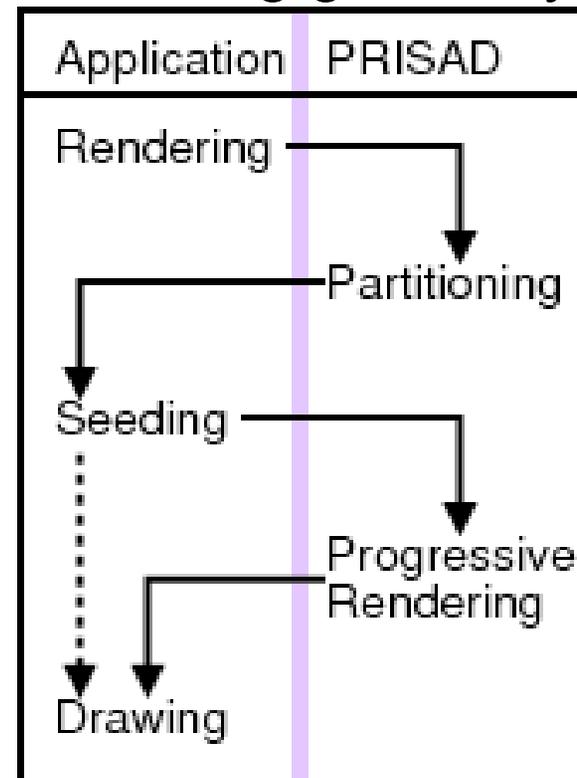
world-space discretization

- preprocessing
 - initializing data structures
 - placing geometry



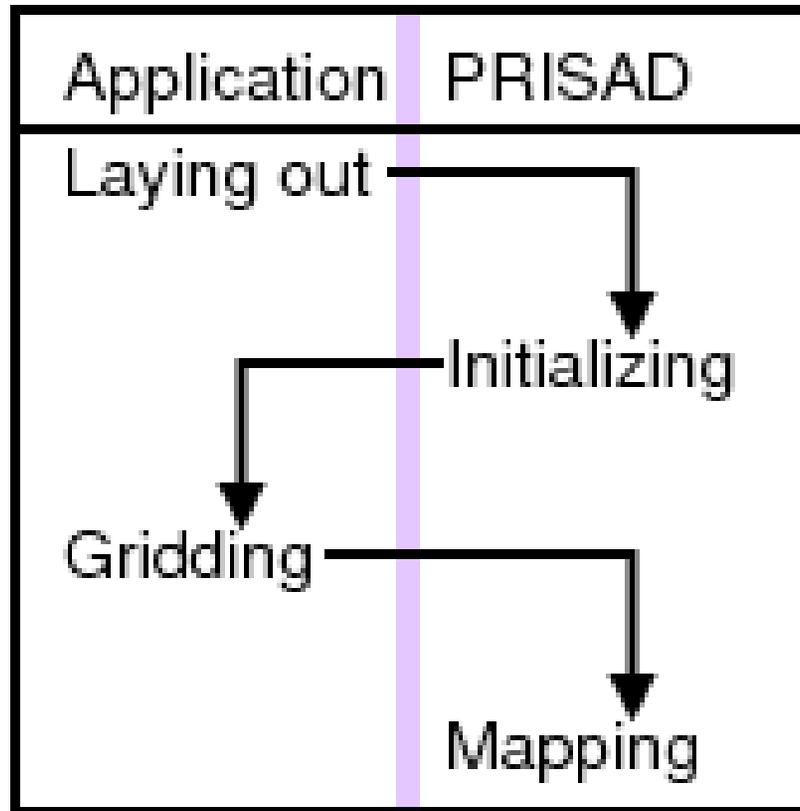
screen-space rendering

- frame updating
 - analyzing navigation state
 - drawing geometry



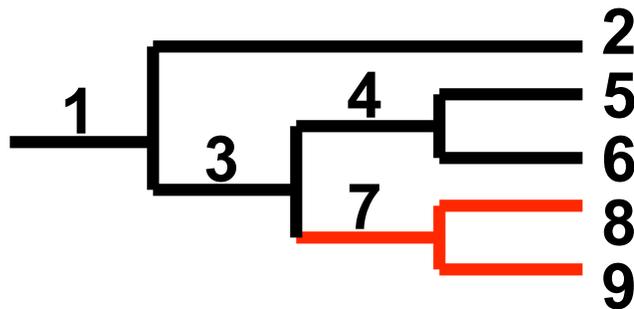
World-space Discretization

interplay between infrastructure and application



Laying Out & Initializing

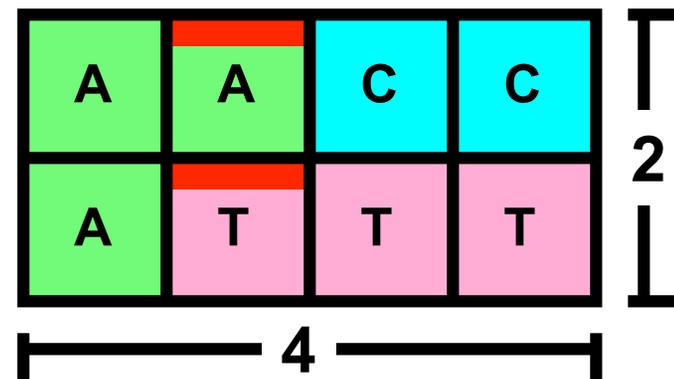
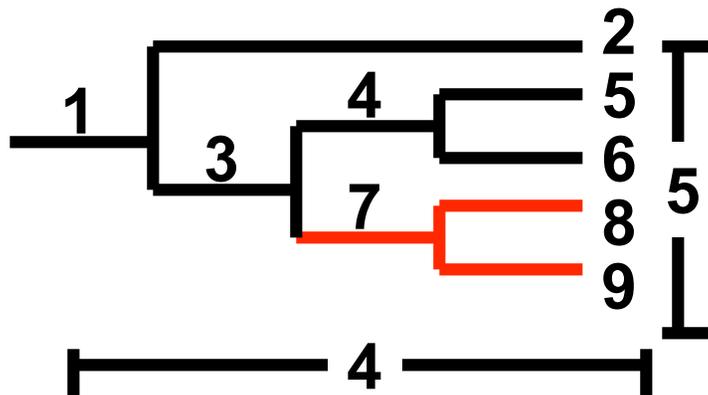
- application-specific layout of dataset
 - non-overlapping objects
- initialize PRISAD split line hierarchies
 - objects aligned by split lines



A	A	C	C
A	T	T	T

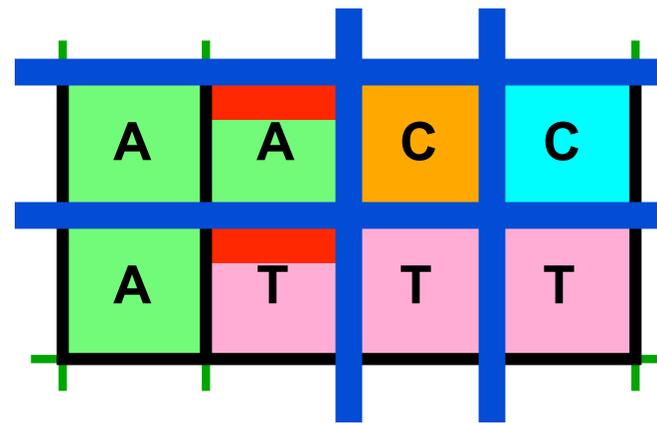
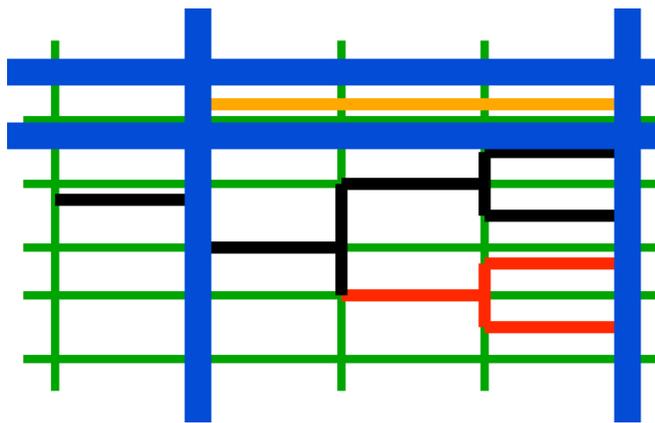
Laying Out & Initializing

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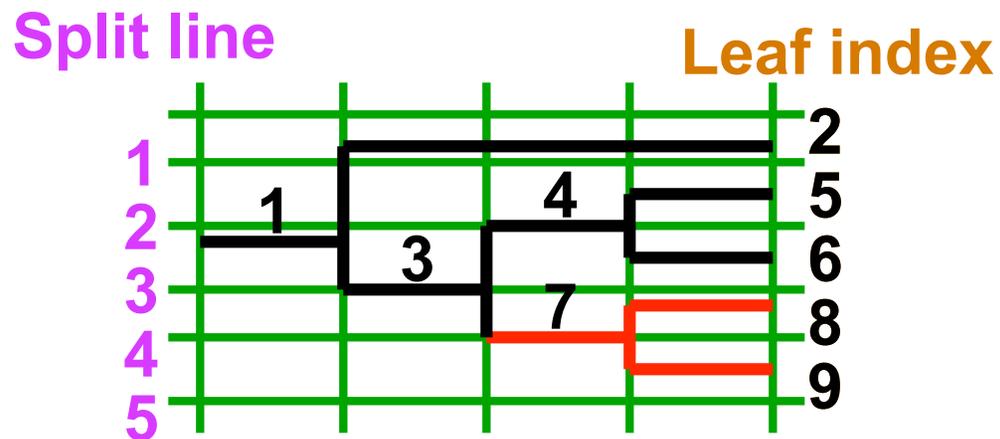
Gridding

- each geometric object assigned its four encompassing split line boundaries



Mapping

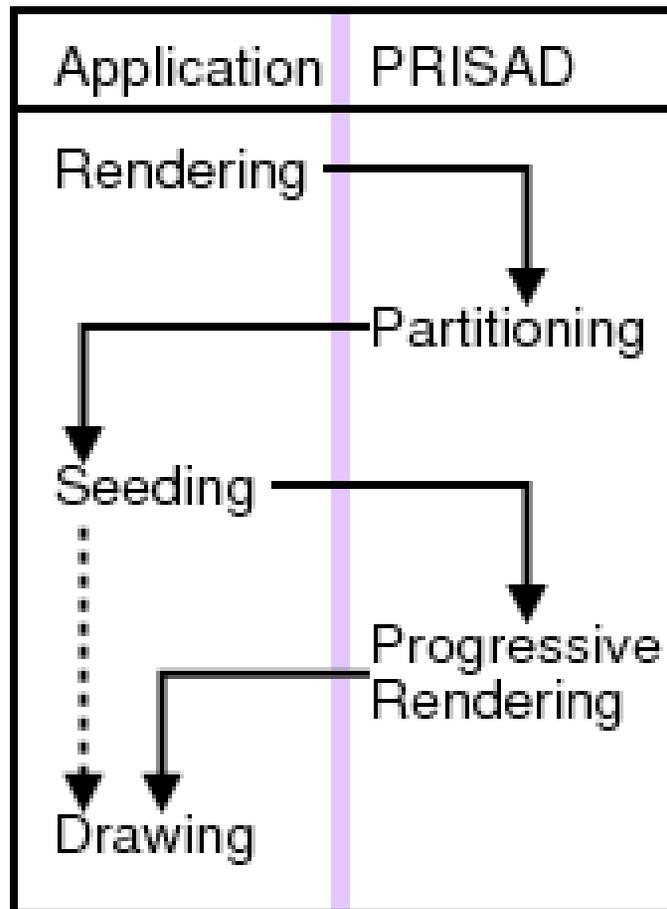
- PRITree mapping initializes leaf references
 - bidirectional $O(1)$ reference between leaves and split lines



1	2	Map
2	5	
3	6	
4	8	
5	9	

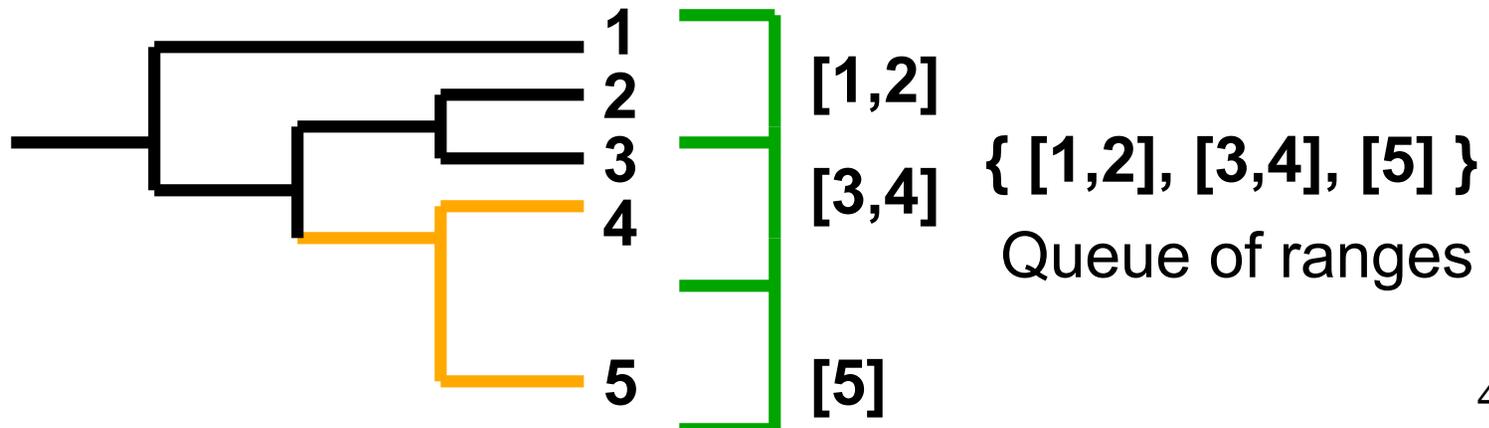
Screen-space Rendering

control flow to draw each frame



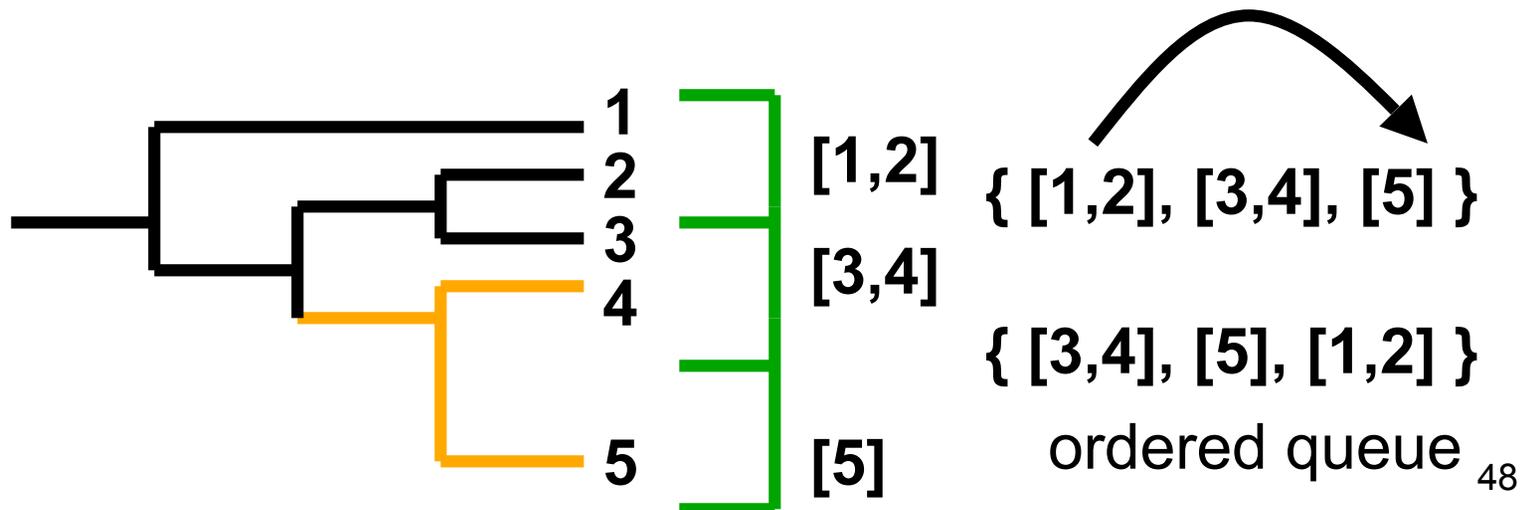
Partitioning

- partition object set into bite-sized ranges
 - using current split line screen-space positions
 - required for every frame
 - subdivision stops if region smaller than 1 pixel
 - or if range contains only 1 object



Seeding

- reordering range queue result from partition
 - marked regions get priority in queue
 - drawn first to provide landmarks

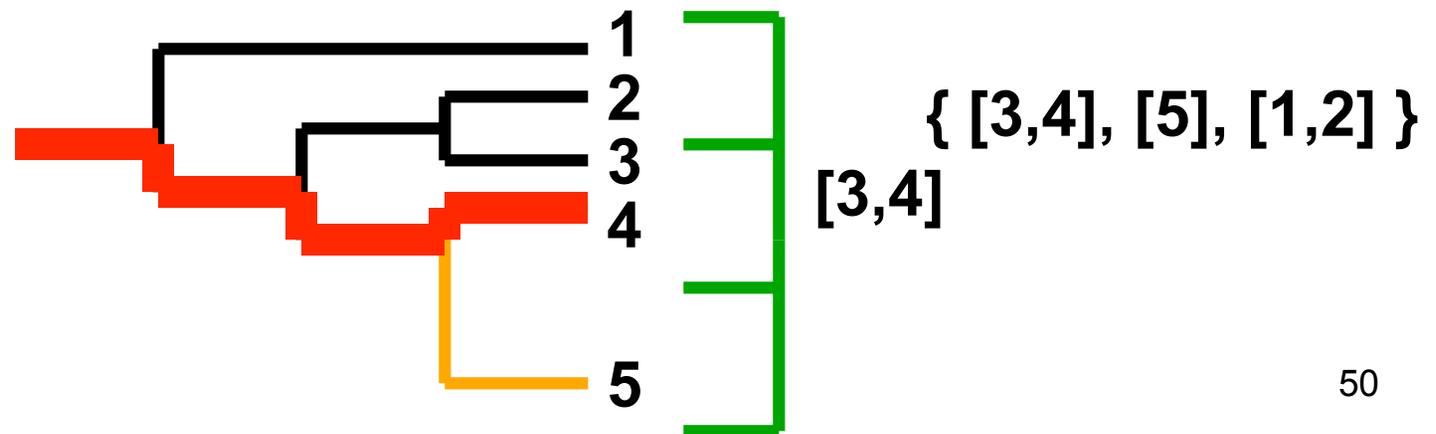


Drawing Single Range

- each enqueued object range drawn according to application geometry
 - selection for trees
 - aggregation for sequences

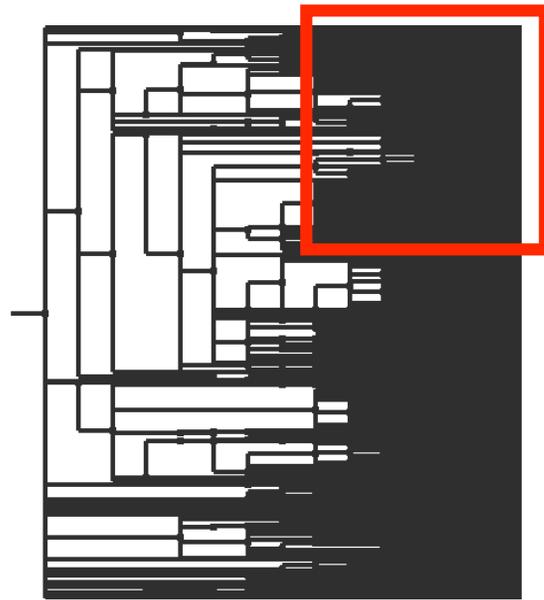
PRITree Range Drawing

- select suitable leaf in each range
- draw path from leaf to the root
 - ascent-based tree drawing
 - efficiency: minimize overdrawing
 - only draw one path per range

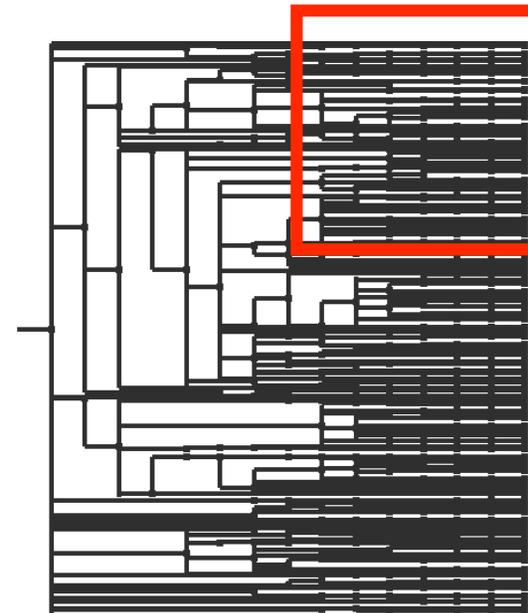


Rendering Dense Regions

- correctness: eliminate overculling
 - bad leaf choices would result in misleading gaps
- efficiency: maximize partition size to reduce rendering
 - too much reduction would result in gaps



Intended rendering



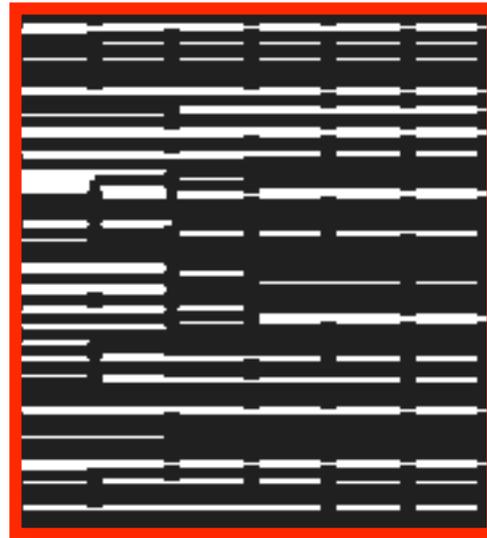
Partition size too big

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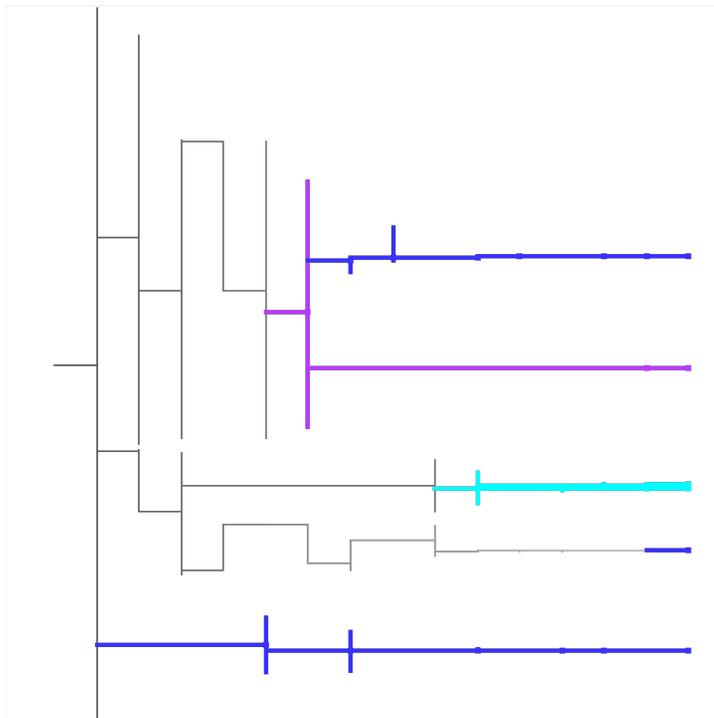


Partition size too big

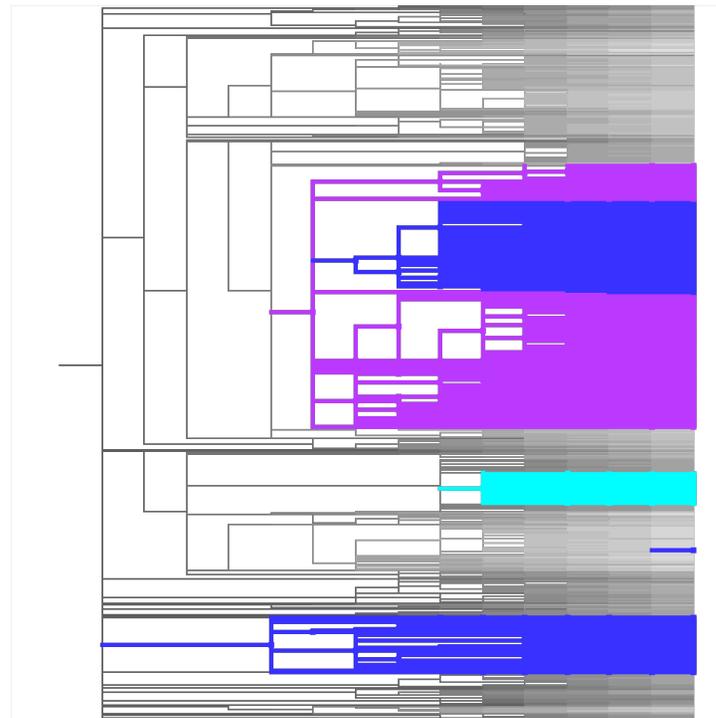
PRITree Skeleton

- guaranteed visibility of marked subtrees during progressive rendering

first frame: one path
per marked group

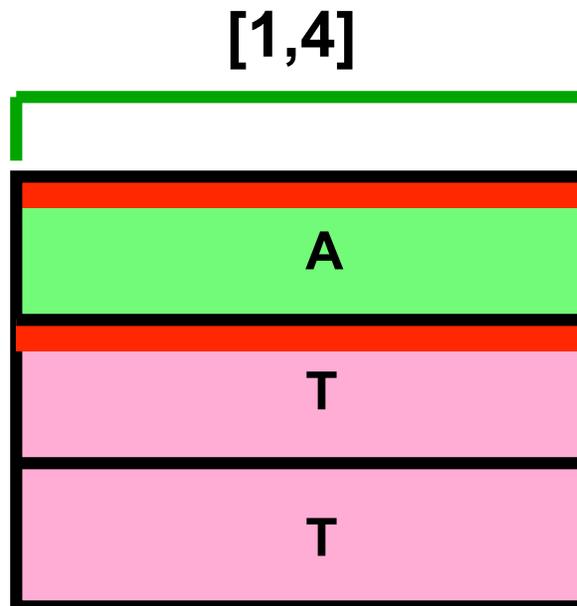
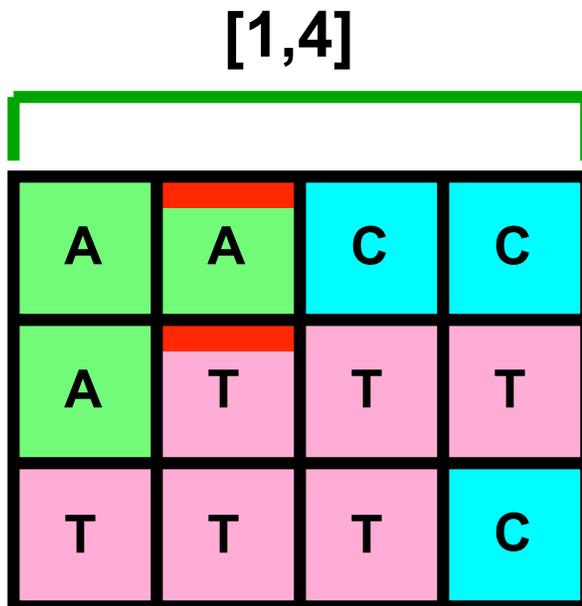


full scene:
entire marked subtrees



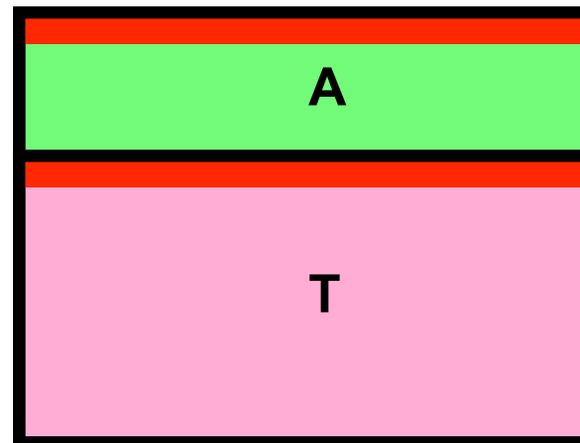
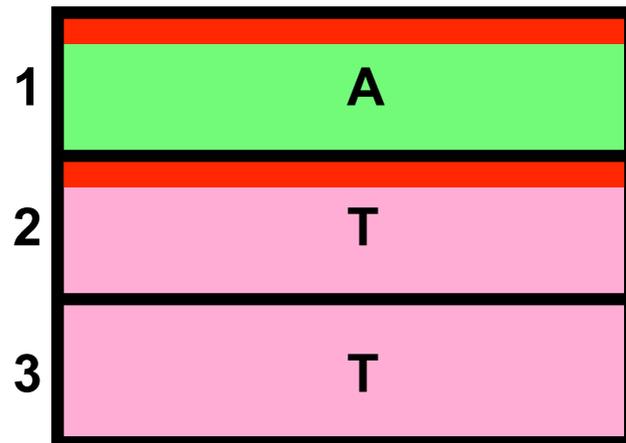
PRISeq Range Drawing: Aggregation

- aggregate range to select box color for each sequence
 - random select to break ties



PRISeq Range Drawing

- collect identical nucleotides in column
 - form single box to represent identical objects
 - attach to split line hierarchy cache
 - lazy evaluation
- draw vertical column



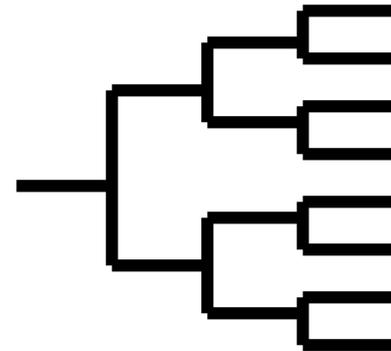
{ A:[1,1], T:[2,3] }

PRISAD Performance

- PRITree vs. TreeJuxtaposer (TJ)
- synthetic and real datasets

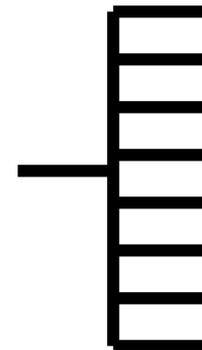
– complete binary trees

- lowest branching factor
- regular structure



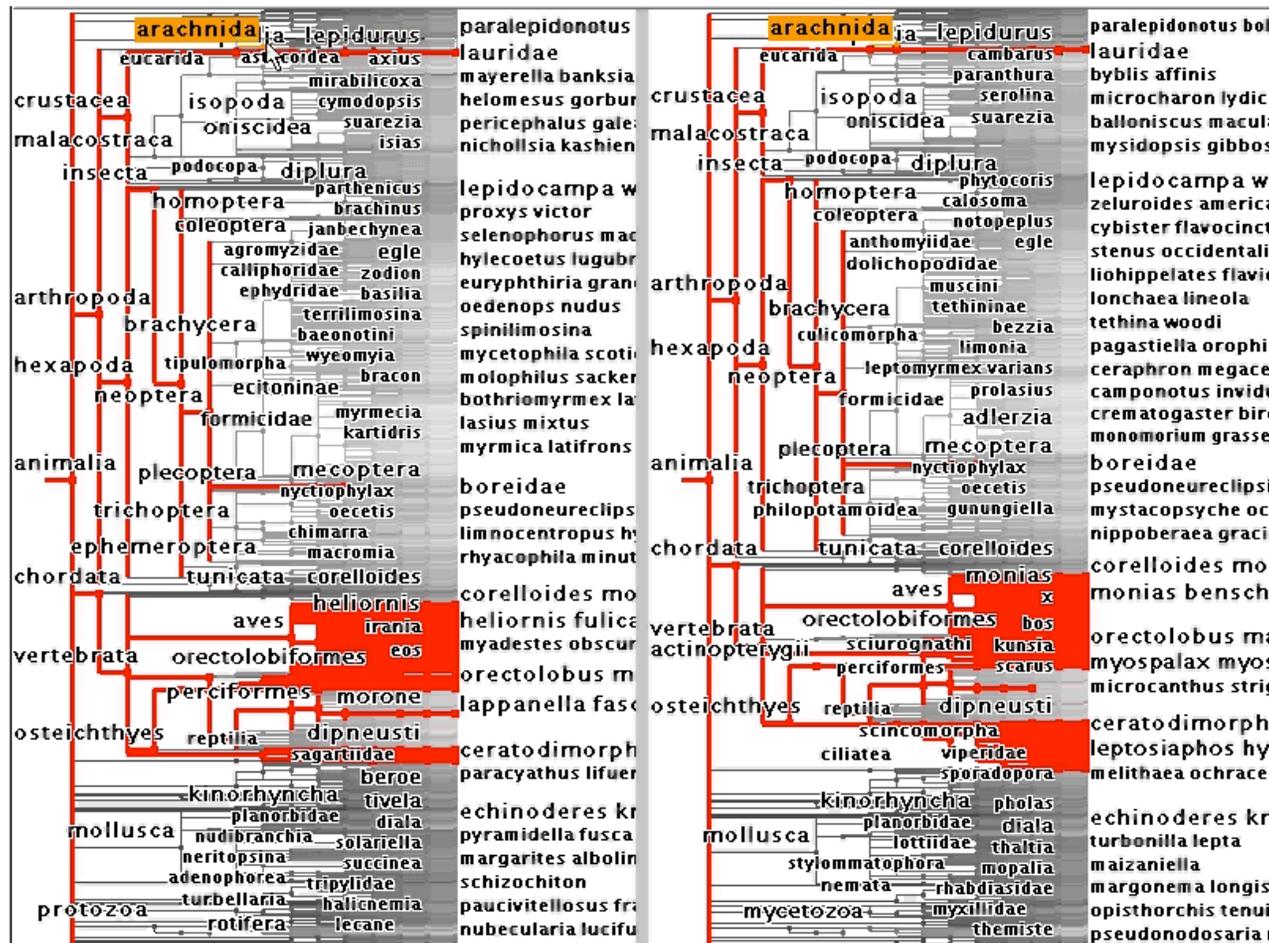
– star trees

- highest possible branching factor



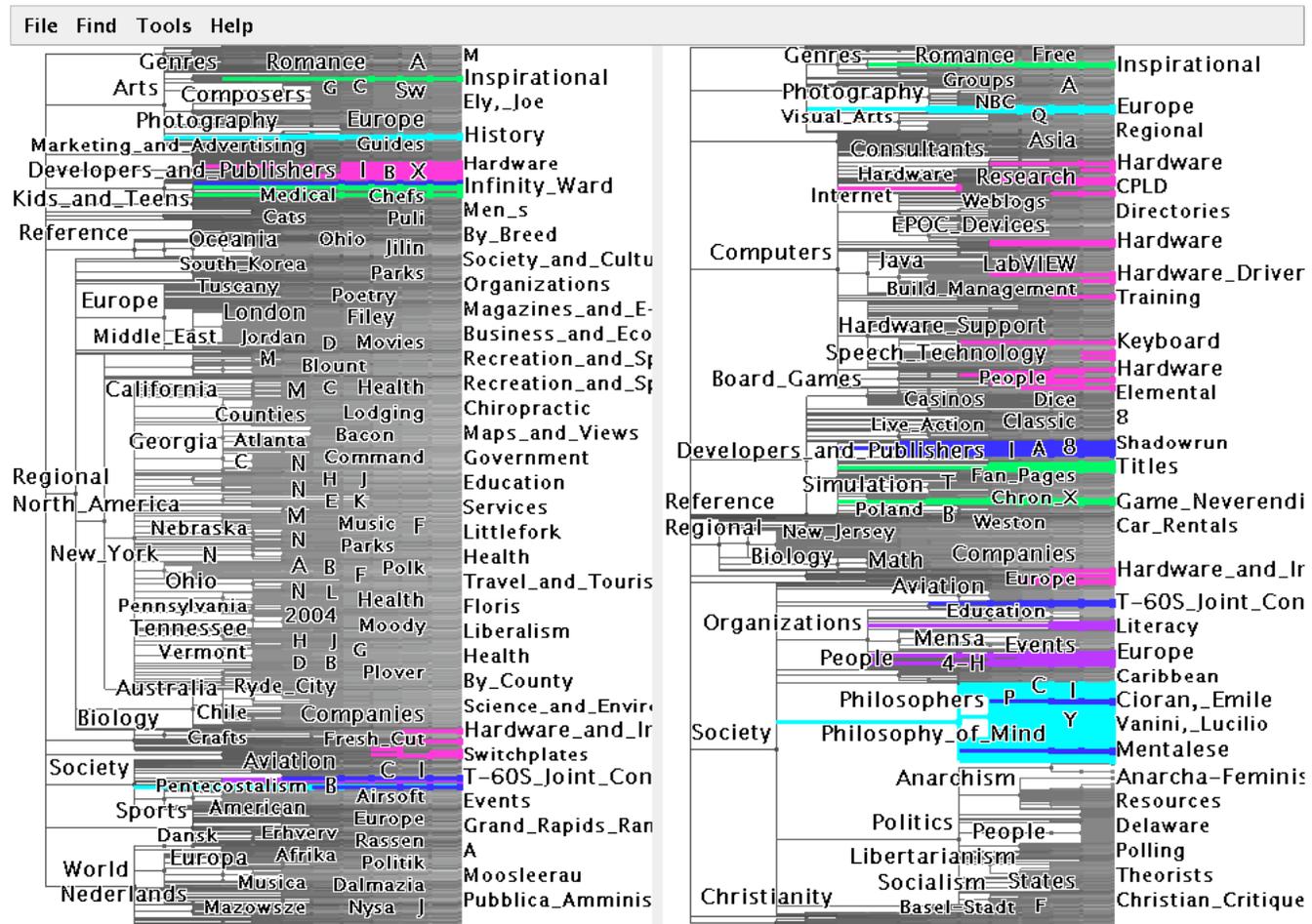
InfoVis Contest Benchmarks

- two 190K node trees
- directly compare TJ and PT



OpenDirectory benchmarks

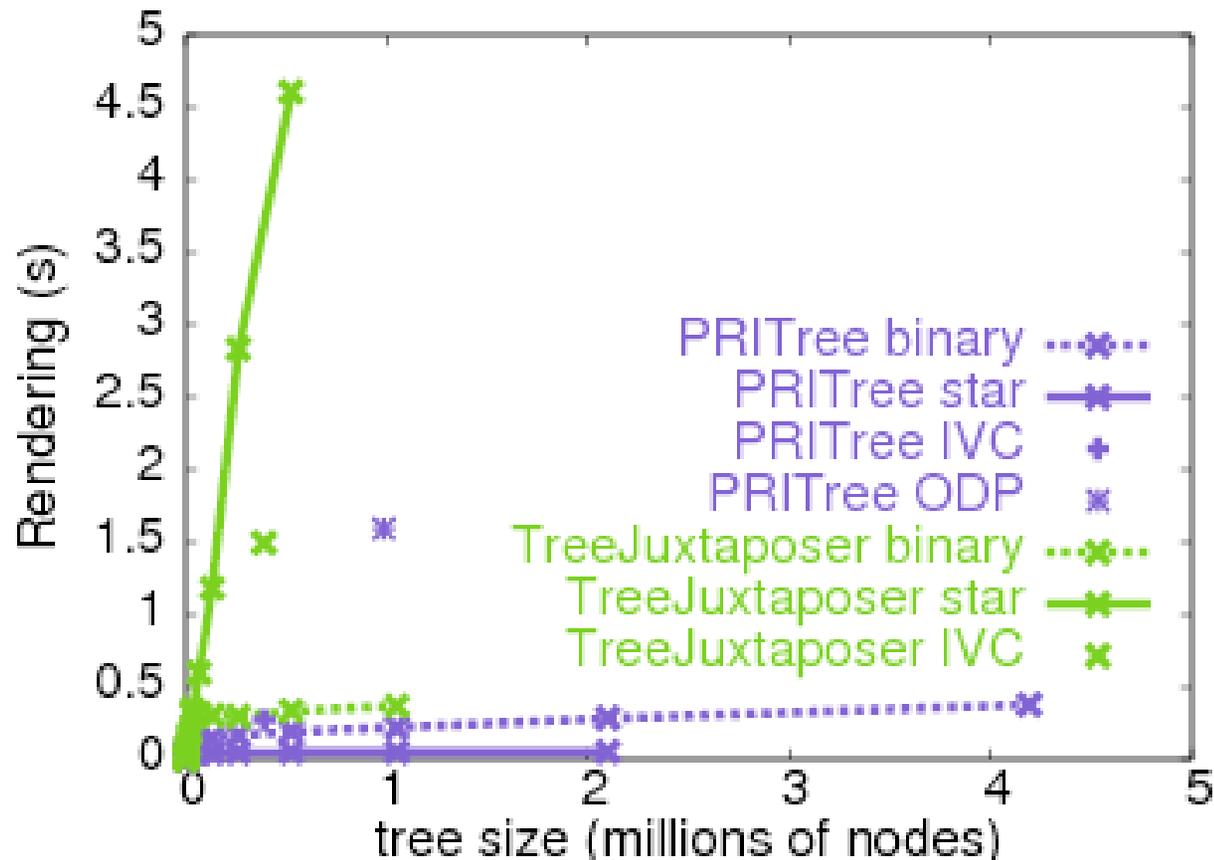
- two 480K node trees
- too large for TJ, PT results only



PRITree Rendering Time Performance

TreeJuxtaposer renders **all** nodes for star trees

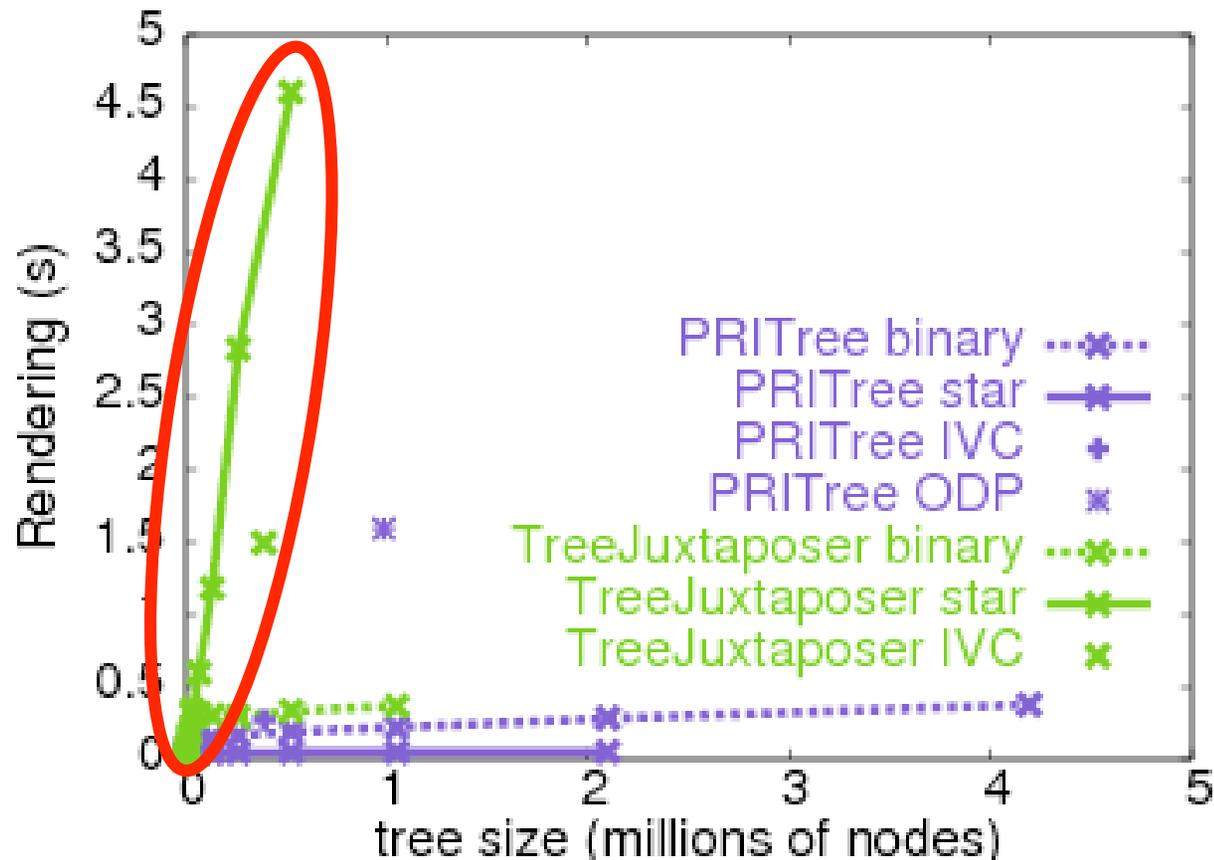
- branching factor k leads to $O(k)$ performance



PRITree Rendering Time Performance

TreeJuxtaposer renders **all** nodes for star trees

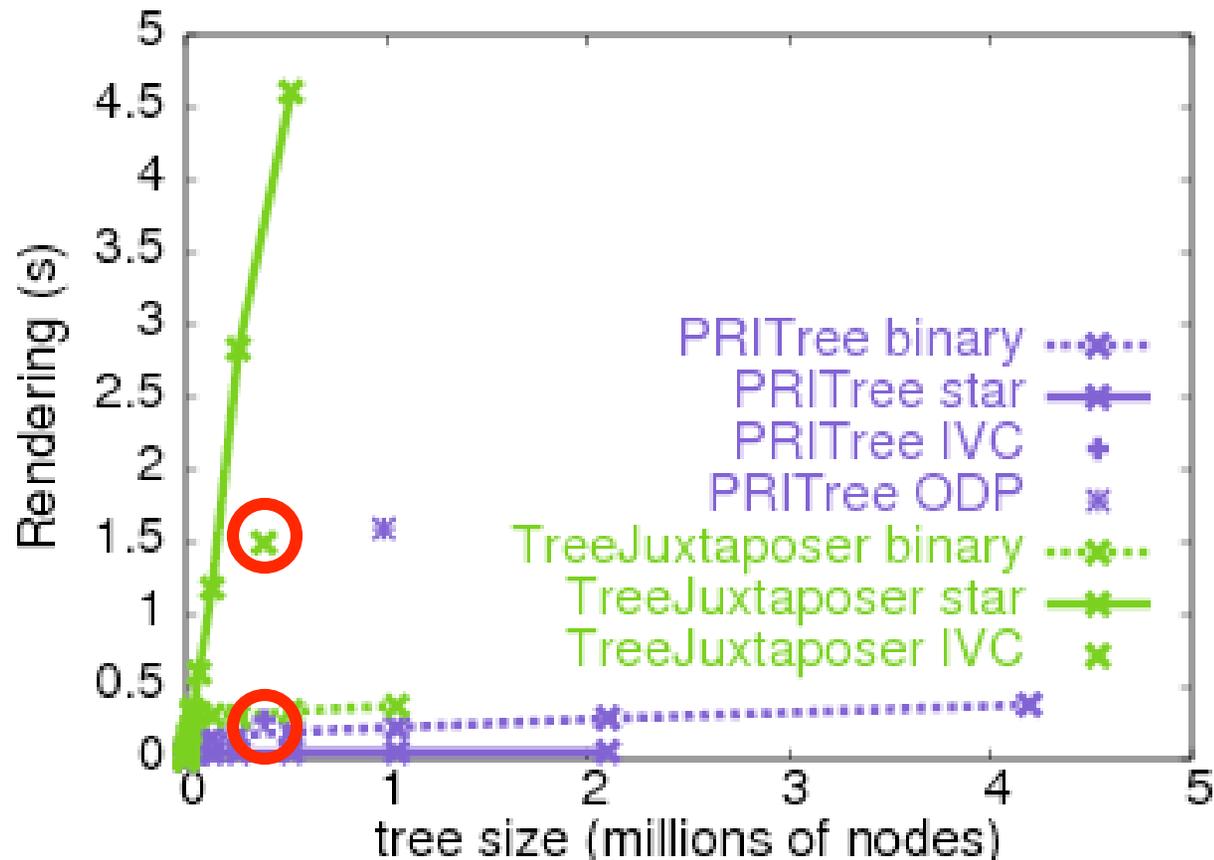
- branching factor k leads to $O(k)$ performance



PRITree Rendering Time Performance

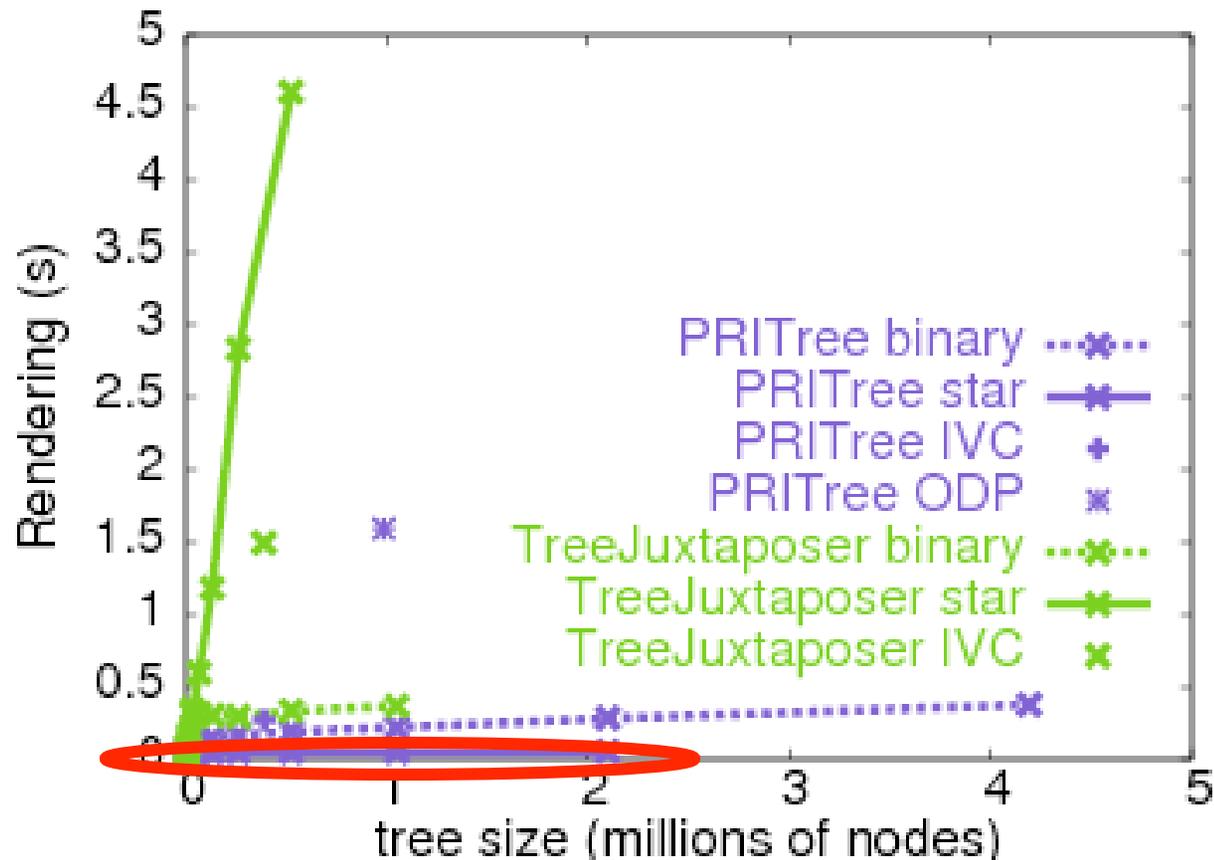
InfoVis 2003 Contest dataset

- 5x rendering speedup

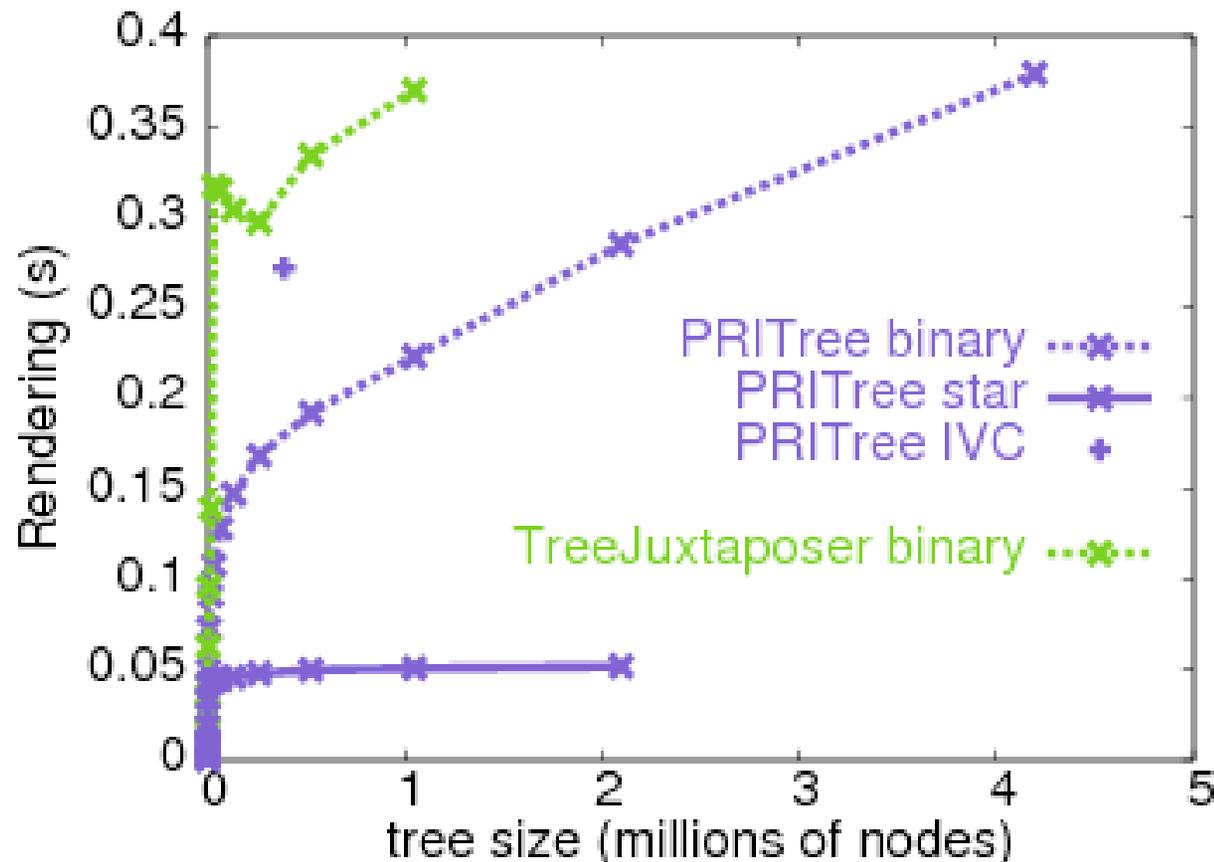


PRITree Rendering Time Performance

a closer look at the fastest rendering times



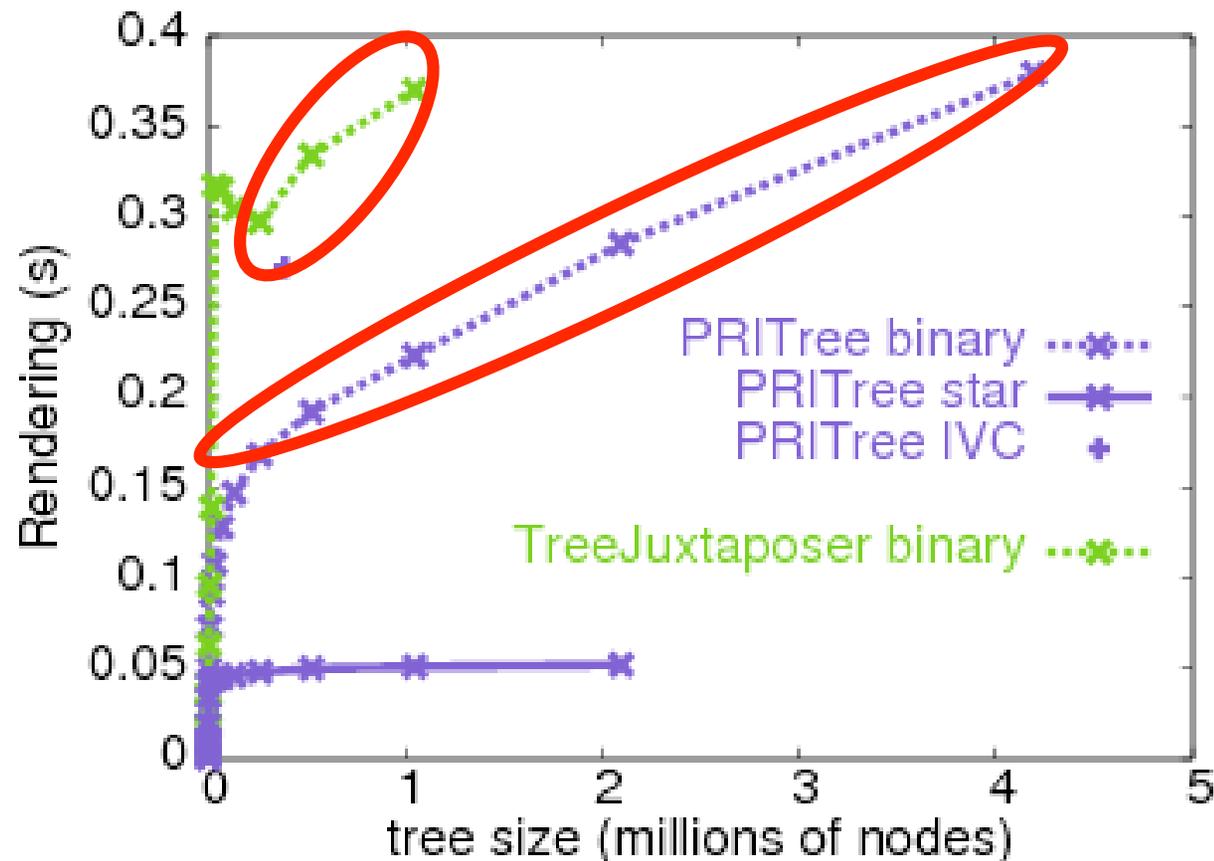
PRITree Rendering Time Performance



Detailed Rendering Time Performance

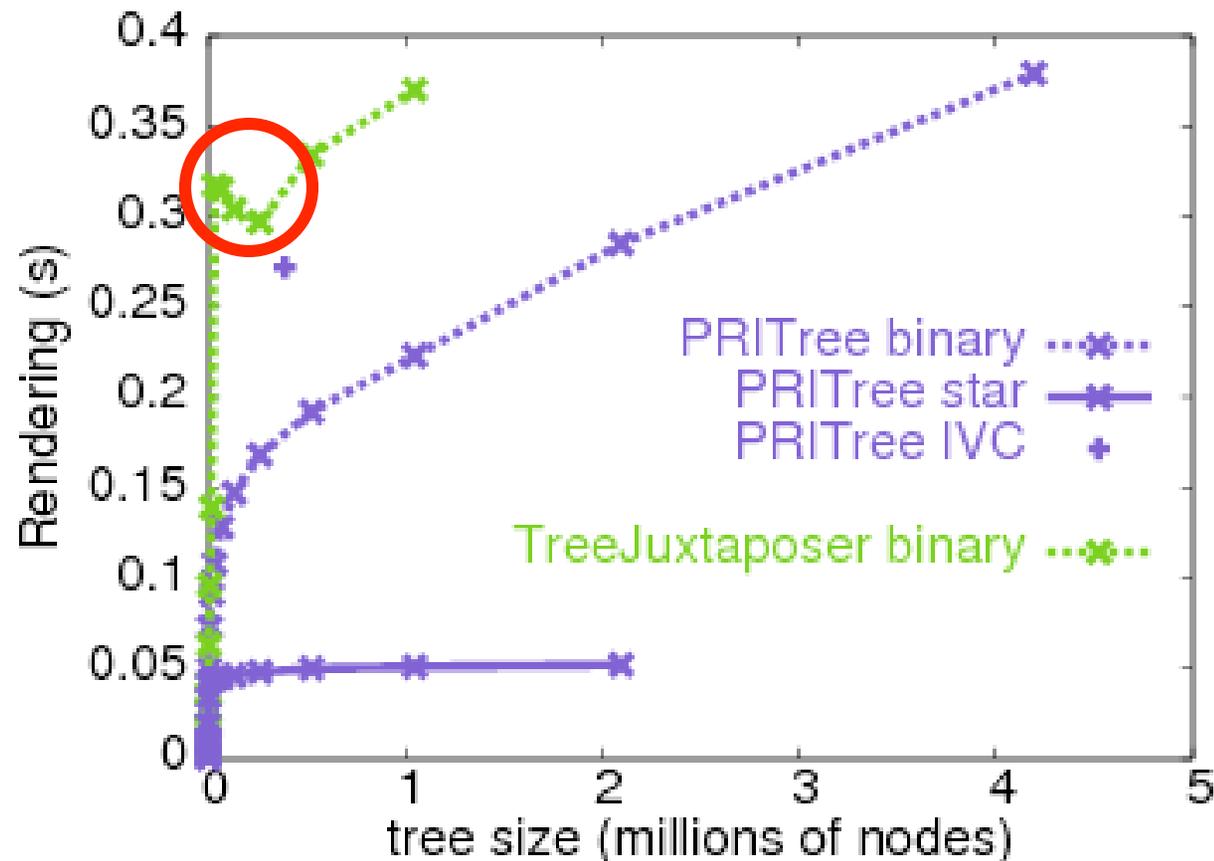
PRITree handles 4 million nodes in under 0.4 seconds

- TreeJuxtaposer takes twice as long to render 1 million nodes



Detailed Rendering Time Performance

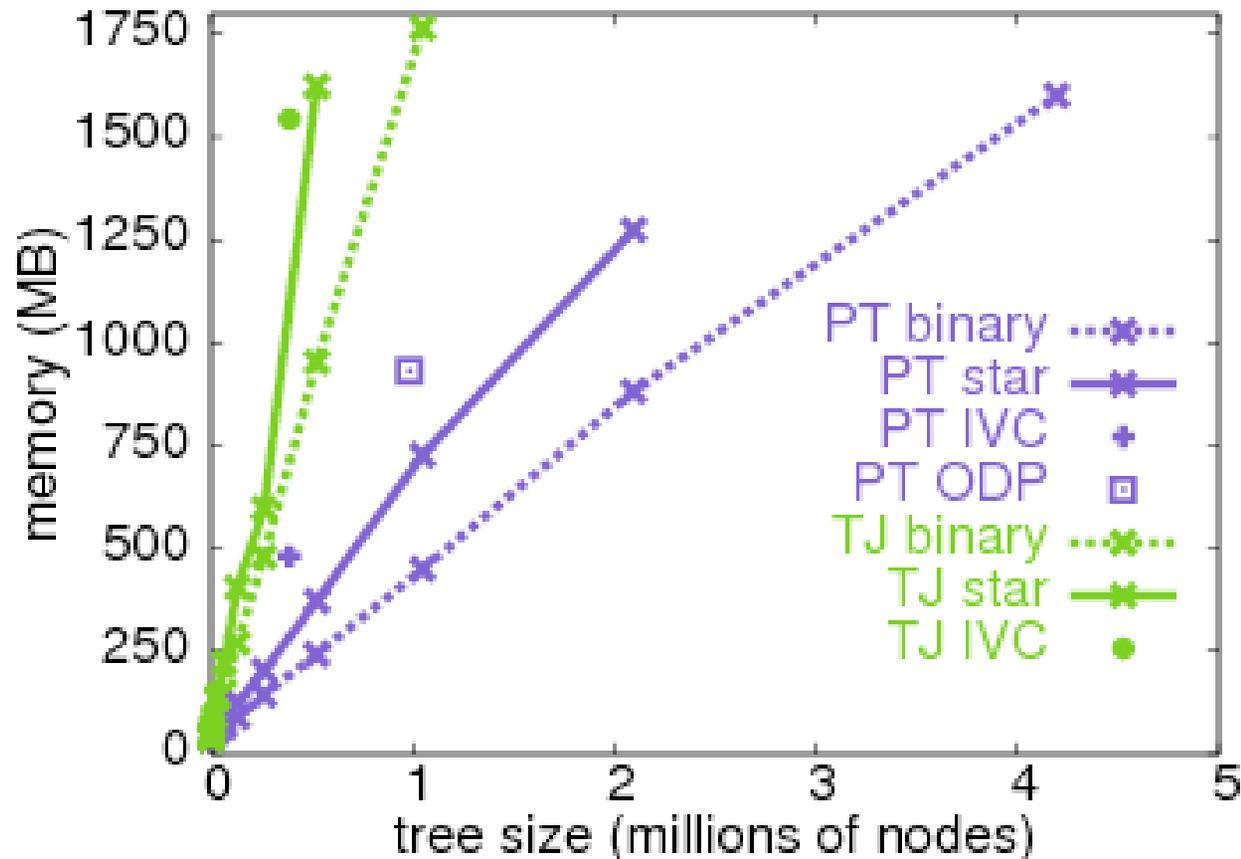
TreeJuxtaposer valley from overculling



Memory Performance

linear memory usage for both applications

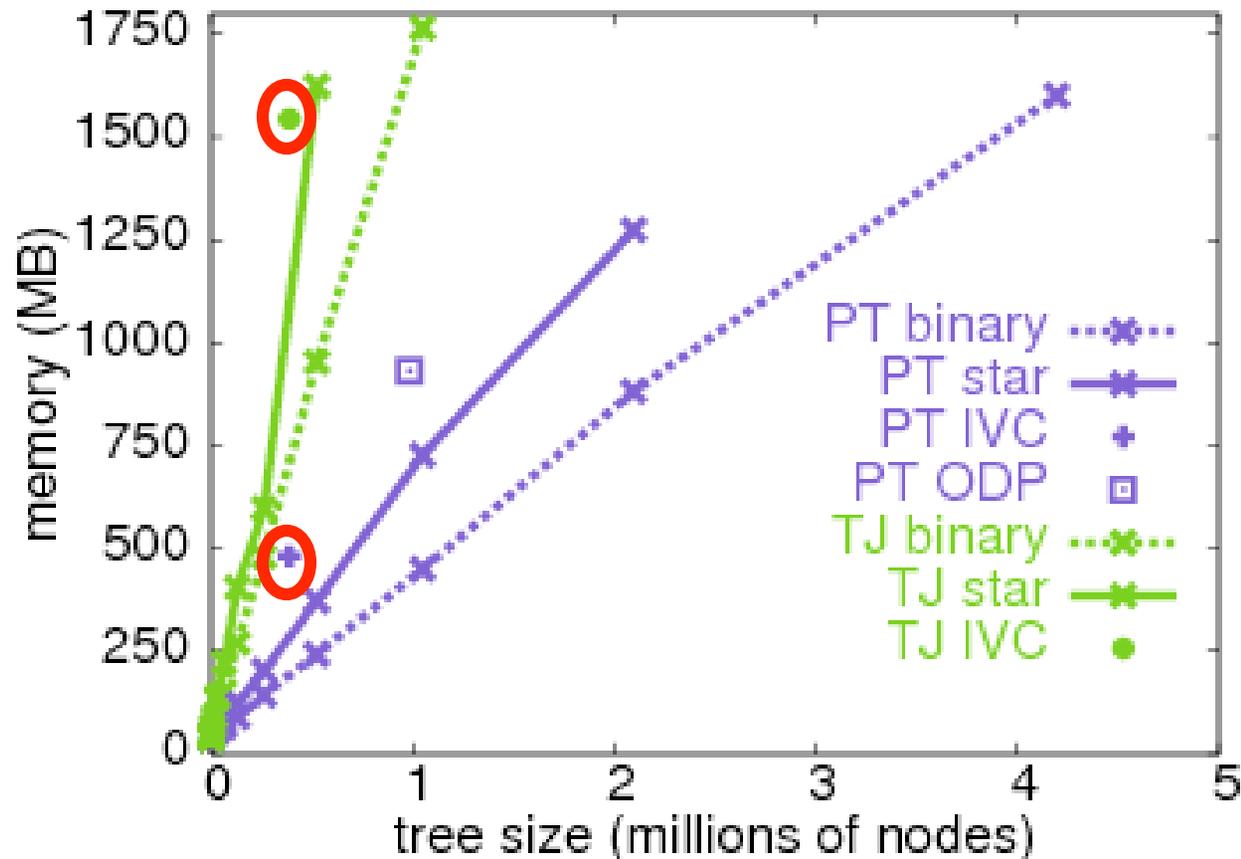
- 4-5x more efficient for synthetic datasets



Memory Performance

1GB difference for InfoVis contest comparison

- marked range storage changes improve scalability



Performance Comparison

- PRITree vs. TreeJuxtaposer
 - detailed benchmarks against identical TJ functionality
 - 5x faster, 8x smaller footprint
 - handles over 4M node trees
- PRISeq vs. SequenceJuxtaposer
 - 15x faster rendering, 20x smaller memory size
 - 44 species * 17K nucleotides = 770K items
 - 6400 species * 6400 nucleotides = 40M items

Future Work

- future work
 - editing and annotating datasets
 - PRISAD support for application specific actions
 - logging, replay, undo, other user actions
 - develop process or template for building applications

PRISAD Contributions

- infrastructure for efficient, correct, and generic accordion drawing
- efficient and correct rendering
 - screen-space partitioning tightly bounds overdrawing and eliminates overculling
- first generic AD infrastructure
 - PRITree renders 5x faster than TJ
 - PRISeq renders 20x larger datasets than SJ

Joint Work

- TreeJuxtaposer
 - François Guimbretière, Serdar Ta_iran, Li Zhang, Yunhong Zhou
 - SIGGRAPH 2003
- SequenceJuxtaposer
 - James Slack, Kristian Hildebrand, Katherine St.John
 - German Conference on Bioinformatics 2004
- TJC/TJC-Q
 - Dale Beermann, Greg Humphreys
 - EuroVis 2005
- PRISAD
 - James Slack, Kristian Hildebrand
 - IEEE InfoVis Symposium 2005
 - Information Visualization journal, to appear

Open Source

- software freely available from <http://olduvai.sourceforge.net>
 - SequenceJuxtaposer
olduvai.sf.net/sj
 - TreeJuxtaposer
olduvai.sf.net/tj
 - requires Java and OpenGL
 - JOGL bindings for TJ, GL4Java for SJ (JOGL coming soon)
- papers, talks, videos also from <http://www.cs.ubc.ca/~tmm>

Other Projects

- Focus+Context evaluation
 - high-level user studies of systems
 - low-level visual search and memory
- graph drawing
- dimensionality reduction