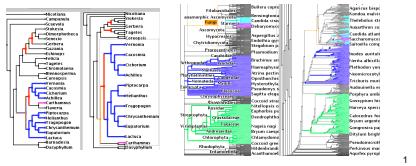


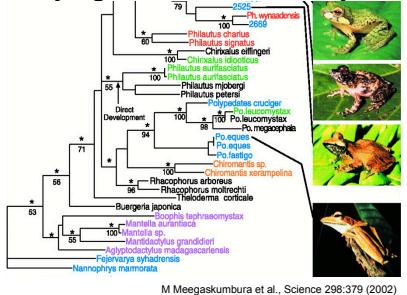
TreeJuxtaposer

- side by side comparison of evolutionary trees



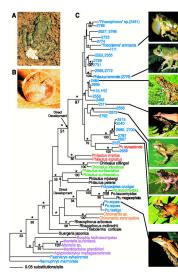
1

Phylogenetic/Evolutionary Tree



2

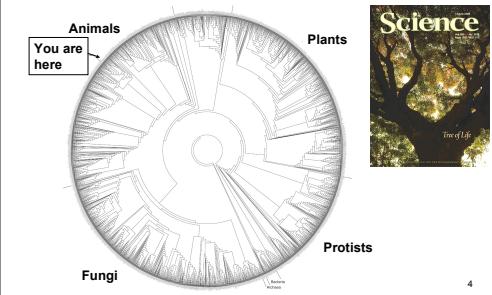
Common Dataset Size Today



M Meegaskumbura et al., Science 298:379 (2002)

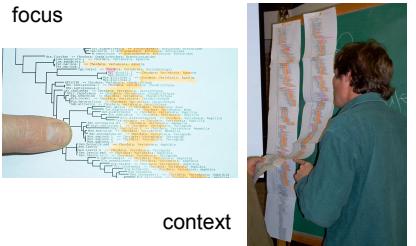
3

Future Goal: 10M node Tree of Life



4

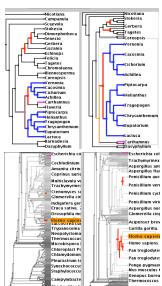
Paper Comparison: Multiple Trees



5

Accordion Drawing

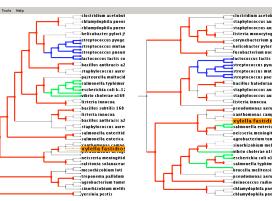
- rubber-sheet navigation
 - stretch out part of surface, the rest squishes
 - borders nailed down
 - Focus+Context technique
 - integrated overview, details
 - old idea
 - [Sarkar et al 93], [Robertson et al 91]
- guaranteed visibility
 - marks always visible
 - important for scalability
 - new idea
 - [Munzner et al 03]



6

Guaranteed Visibility

- marks are always visible
- easy with small datasets



7

Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible



8

Guaranteed Visibility Challenges

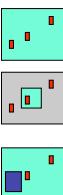
- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation



9

Guaranteed Visibility Challenges

- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation
 - underneath other marks
 - AD solution: avoid 3D



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Guaranteed Visibility Challenges

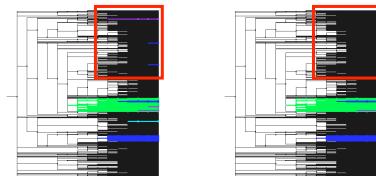
- hard with larger datasets
- reasons a mark could be invisible
 - outside the window
 - AD solution: constrained navigation
 - underneath other marks
 - AD solution: avoid 3D
 - smaller than a pixel
 - AD solution: smart culling



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Guaranteed Visibility: Small Items

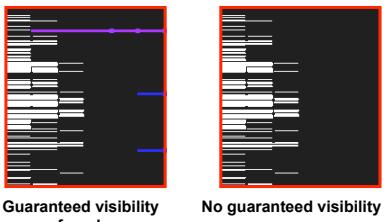
- Naïve culling may not draw all marked items



12

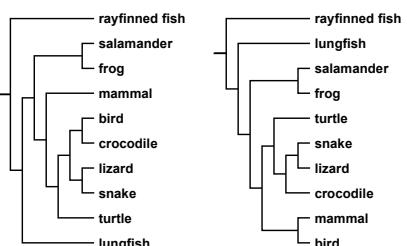
Guaranteed Visibility: Small Items

- Naïve culling may not draw all marked items



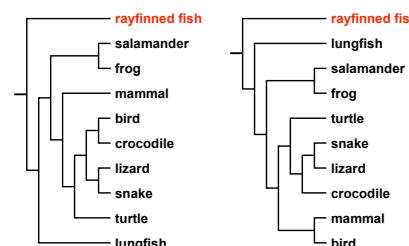
13

Structural Comparison



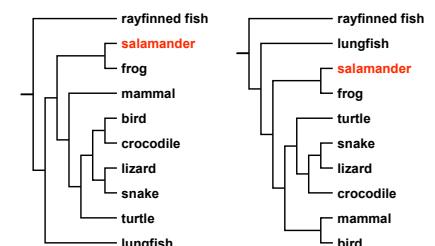
14

Matching Leaf Nodes



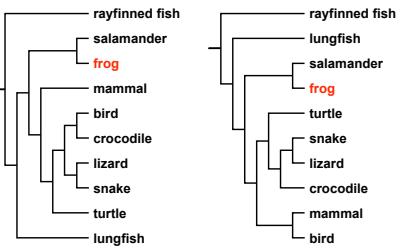
15

Matching Leaf Nodes

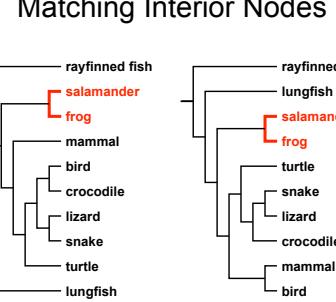


16

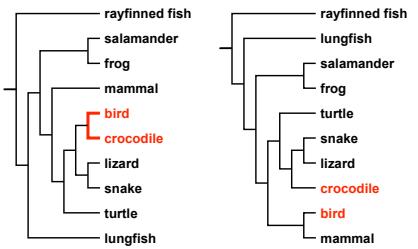
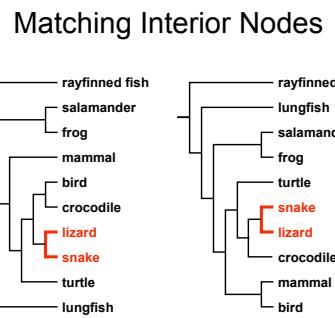
Matching Leaf Nodes



7

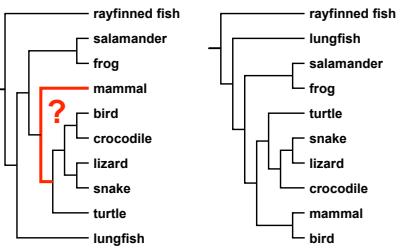


1



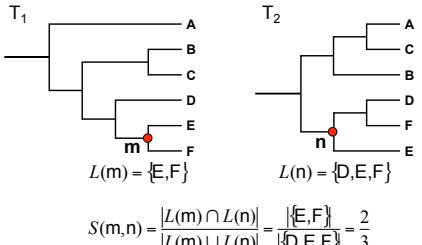
20

Matching Interior Nodes



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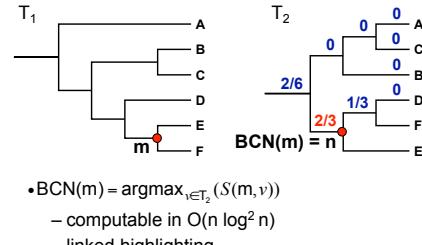
Similarity Score: $S(m,n)$



$$S(m,n) = \frac{|L(m) \cap L(n)|}{|L(m) \cup L(n)|} = \frac{|\{\text{E,F}\}|}{|\{\text{D,E,F}\}|} = \frac{2}{3}$$

2

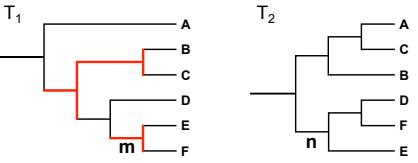
Best Corresponding Node



- BCN(m) = $\text{argmax}_{v \in T_2}(S(m, v))$
 - computable in $O(n \log^2 n)$
 - linked highlighting

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Marking Structural Differences

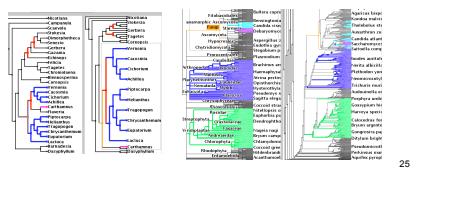


- Nodes for which $S(v, \text{BCN}(v)) \neq 1$
 - Matches intuition

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TreeJuxtaposer

- video, software from olduvai.sourceforge.net/tj



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