

## Hierarchical modelling

- **recap: composing transforms**
- **finish: rendering pipeline**
- **matrix hierarchies and stacks**
- **display lists**

## News

### Project 0:

- depth test
  - `glEnable(GL_DEPTH_TEST); // before loop`
  - `glClear(GL_COLOR_BUFFER_BIT | GL_DEPTH_BUFFER_BIT); // in display`
- avoid blob effect: try changing color for each face
- glutDodecahedron **not** the intended solution
  - *good for checking your approach*

## Composing transforms recap

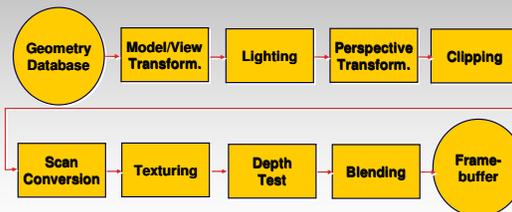
### Order matters

- 4x4 matrix multiplication not commutative!

### Moving to origin

- Transformation of geometry into coordinate system where operation becomes simpler
- Perform operation
- Transform geometry back to original coordinate system

## The Rendering Pipeline



## Discussion

### Advantages of a pipeline structure

- Logical separation of the different components, modularity
- Easy to parallelize:
  - *Earlier stages can already work on new data while later stages still work with previous data*
  - *Similar to pipelining in modern CPUs*
  - *But much more aggressive parallelization possible (special purpose hardware!)*
  - *Important for hardware implementations!*
- Only local knowledge of the scene is necessary

## Discussion

### Disadvantages:

- Limited flexibility
- Some algorithms would require different ordering of pipeline stages
  - *Hard to achieve while still preserving compatibility*
- Only local knowledge of scene is available
  - *Shadows*
  - *Global illumination*

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## Matrix hierarchies and stacks

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## Matrix Operations in OpenGL

**Direct matrix specification:**

- load
  - `glLoadMatrix`
  - `glLoadIdentity`
- multiply
  - `glMultMatrix`

**Transformations:**

- `glRotate*`
- `glTranslate*`
- `glScale*`

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## Matrix Operations in OpenGL

`glRotate*( $\theta$ , x, y, z)`

$\theta$  : ccw rotation angle, looking along vector towards origin

x, y, z : vector along which rotation occurs

equivalent to `glMultMatrix(A)`,  $A =$

$$\begin{bmatrix} x^2(1-\cos\theta)+\cos\theta & xy(1-\cos\theta)-z\sin\theta & xz(1-\cos\theta)+y\sin\theta & 0 \\ yx(1-\cos\theta)+z\sin\theta & y^2(1-\cos\theta)+\cos\theta & yz(1-\cos\theta)-x\sin\theta & 0 \\ xz(1-\cos\theta)-y\sin\theta & yz(1-\cos\theta)+x\sin\theta & z^2(1-\cos\theta)+\cos\theta & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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## Matrix Operations in OpenGL

**2 Matrices:**

- Model/view matrix M
- Projective matrix P

**Example:**

```
glMatrixMode( GL_MODELVIEW );
glLoadIdentity(); // M=Id
glRotatef( angle, x, y, z ); // M=Id*R( $\alpha$ )
glTranslatef( x, y, z ); // M= Id*R ( $\alpha$ )*T(x,y,z)
glMatrixMode( GL_PROJECTION );
glRotatef( ... ); // P= ...
```

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## Matrix Operations in OpenGL

**Semantics:**

- `MatrixMode` sets the matrix that is to be affected by all following transformations
- Whenever primitives are rendered with `glBegin()`, the vertices are transformed with whatever the current model/view and perspective matrix is
  - *OpenGL as state machine*
- Multiplication order:
  - *post: right to left, top to bottom*

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## Transformation Hierarchies

**scene graph**

```

graph TD
  road((road)) --- stripe1((stripe1))
  road --- stripe2((stripe2))
  road --- car1((car1))
  road --- car2((car2))
  car1 --- w1((w1))
  car1 --- w2((w2))
  car1 --- w3((w3))
  car1 --- w4((w4))
  
```

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## Transformation Hierarchies

world  
torso  
LUleg RUleg LUarm RUarm head  
LLleg RLleg LLarm RLarm  
Lfoot Rfoot Lhand Rhand

$\text{trans}(0.30,0,0) \text{rot}(z,\theta)$

## Matrix Stacks

**Challenge:**

- Avoid extra computation
  - using inverse to return to origin
  - computing incremental  $T_1 \rightarrow T_2$

World coordinates

Object coordinates

## Transformation Hierarchies

**Matrix Stack**

```
glPushMatrix()
glPopMatrix()
D = C scale(2,2,2) trans(1,0,0)
```

```
DrawSquare()
glPushMatrix()
glScale3f(2,2,2)
glTranslate3f(1,0,0)
DrawSquare()
glPopMatrix()
```

## Composing Transformations

**OpenGL example**

```
glLoadIdentity();
glTranslatef(4,1,0);
glPushMatrix();
glRotatef(45,0,0,1);
glTranslatef(0,2,0);
glScalef(2,1,1);
glTranslate(1,0,0);
glPopMatrix();
```

## Transformation Hierarchies

**Example**

```
glTranslate3f(x,y,0);
glRotatef(theta,0,0,1);
DrawBody();
glPushMatrix();
glTranslate3f(0,7,0);
DrawHead();
glPopMatrix();
glPushMatrix();
glTranslate(2.5,5.5,0);
glRotatef(theta,0,0,1);
DrawUArm();
glTranslate(0,-3.5,0);
glRotatef(theta_3,0,0,1);
DrawLArm();
glPopMatrix();
... (draw other arm)
```

## Hierarchical Modeling: Matrix Stacks

**Advantages:**

- Matrix stacks make it feasible to have multiple copies of one object
- No need to compute inverse matrices all the time
- Avoids incremental changes to coordinate systems
  - Accumulation of numerical errors

**Practical issues:**

- In graphics hardware, depth of matrix stacks is limited
  - typically 16 for model/view and about 4 for projective matrix

## Example: modularization

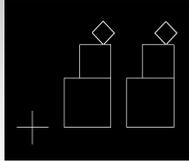


### Drawing a scaled square

```
void drawBlock(float k) {
    glPushMatrix();

    glScalef(k, k, k);
    glBegin(GL_LINE_LOOP);
    glVertex3f(0, 0, 0);
    glVertex3f(1, 0, 0);
    glVertex3f(1, 1, 0);
    glVertex3f(0, 1, 0);
    glEnd();

    glPopMatrix();
}
```



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## Example: applets



<http://www.cs.brown.edu/exploratories/freeSoftware/catalogs/scenegraphs.html>



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## Display lists



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## Display Lists



### Concept:

- If multiple copies of an object are required, it can be compiled into a display list:

```
glNewList( listId, GL_COMPILE );
```

```
glBegin( ... );
```

```
... // geometry goes here
```

```
glEndList();
```

```
// render two copies of geometry offset by 1 in z-direction:
```

```
glCallList( listId );
```

```
glTranslatef( 0.0, 0.0, 1.0 );
```

```
glCallList( listId );
```

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## Display Lists



### Advantages:

- More efficient than individual function calls for every vertex/attribute
- Can be cached on the graphics board (bandwidth!)
- Display lists exist across multiple frames
  - Represent static objects in an interactive application

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## Display Lists



### Example: 36 Snowmen

<http://www.lighthouse3d.com/opengl/displaylists/>

efficiency issues

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## Snowmen: no lists



```
// Draw 36 Snowmen
for(int i = -3; i < 3; i++)
    for(int j=-3; j < 3; j++) {
        glPushMatrix();
        glTranslatef(i*10.0,j * 10.0);
        // Call the function to draw a snowman
        drawSnowMan();
        glPopMatrix();
    }
```

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## Snowmen: no lists



```
void drawSnowMan() {
    glColor3f(1.0f, 1.0f, 1.0f);
    // Draw Body
    glTranslatef(0.0f, 0.75f, 0.0f);
    glutSolidSphere(0.75f,20,20);
    // Draw Head
    glTranslatef(0.0f, 1.0f, 0.0f);
    glutSolidSphere(0.25f,20,20);
    // Draw Eyes
    glPushMatrix();
    glColor3f(0.0f,0.0f,0.0f);
    glTranslatef(0.05f, 0.10f, 0.18f);
    glutSolidSphere(0.05f,10,10);
    glTranslatef(-0.1f, 0.0f, 0.0f);
    glutSolidSphere(0.05f,10,10);
    glPopMatrix();
    // Draw Nose
    glColor3f(1.0f, 0.5f , 0.5f);
    glRotatef(0.0f,1.0f, 0.0f, 0.0f);
    glutSolidCone(0.08f,0.5f,10,2);
}
```

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## Snowmen: no lists



```
// Draw 36 Snowmen
for(int i = -3; i < 3; i++)
    for(int j=-3; j < 3; j++) {
        glPushMatrix();
        glTranslatef(i*10.0,j * 10.0);
        // Call the function to draw a snowman
        drawSnowMan();
        glPopMatrix();
    }
```

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## Display Lists



### Example: 36 Snowmen

<http://www.lighthouse3d.com/opengl/displaylists/>

benchmarks of 36K polygons

- 55 FPS: no display list

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## Snowmen: display lists



```
GLuint createDL() {
    GLuint snowManDL;
    // Create the id for the list
    snowManDL = glGenLists(1);
    // start list
    glNewList(snowManDL, GL_COMPILE);
    // call the function that contains the rendering commands
    drawSnowMan();
    // endList
    glEndList();
    return(snowManDL); }
```

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## Snowmen: no lists



```
// Draw 36 Snowmen
for(int i = -3; i < 3; i++)
    for(int j=-3; j < 3; j++) {
        glPushMatrix();
        glTranslatef(i*10.0,j * 10.0);
        // Call the function to draw a snowman
        glCallList(DLid);
        glPopMatrix();
    }
```

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## Display Lists



### Example: 36 Snowmen

<http://www.lighthouse3d.com/opengl/displaylists/>

benchmarks of 36K polygons

- 55 FPS: no display list
- 153 FPS: 1 snowman display list, called 36 times

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## Snowmen: one big list



```
GLuint createDL() {
    GLuint snowManDL;
    snowManDL = glGenLists(1);
    glNewList(snowManDL, GL_COMPILE);
    for(int i = -3; i < 3; i++)
        for(int j = -3; j < 3; j++) {
            glPushMatrix();
            glTranslatef(i*10.0, 0, j * 10.0);
            drawSnowMan();
            glPopMatrix();
        }
    glEndList();
    return(snowManDL);
}
```

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## Display Lists



### Example: 36 Snowmen

<http://www.lighthouse3d.com/opengl/displaylists/>

benchmarks of 36K polygons

- 55 FPS: no display list
- 153 FPS: 1 snowman display list, called 36 times
- 108 FPS: single 36 snowman display list

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## Snowmen: nested lists



```
GLuint createDL() {
    GLuint snowManDL, loopDL;
    snowManDL = glGenLists(1);
    loopDL = glGenLists(1);
    glNewList(snowManDL, GL_COMPILE);
    drawSnowMan();
    glEndList();
    glNewList(loopDL, GL_COMPILE);
    for(int i = -3; i < 3; i++)
        for(int j = -3; j < 3; j++) {
            glPushMatrix();
            glTranslatef(i*10.0, 0, j * 10.0);
            glCallList(snowManDL);
            glPopMatrix();
        }
    glEndList();
    return(loopDL);
}
```

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## Display Lists



### Example: 36 Snowmen

<http://www.lighthouse3d.com/opengl/displaylists/>

benchmarks of 36K polygons

- 55 FPS: no display list
- 153 FPS: 1 snowman display list, called 36 times
- 108 FPS: single 36 snowman display list
- 153 FPS: nested display lists

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