

# Chap 13: Reduce Items and Attributes

## Paper: Glimmer

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<http://www.cs.ubc.ca/~tmm/course/547-14/#chap13>

# Idiom design choices: Part 2

## Manipulate

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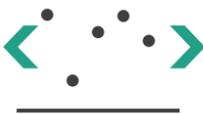
### → Change



### → Select



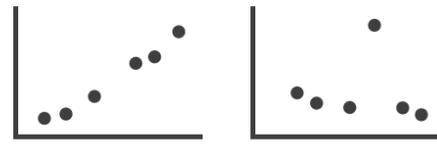
### → Navigate



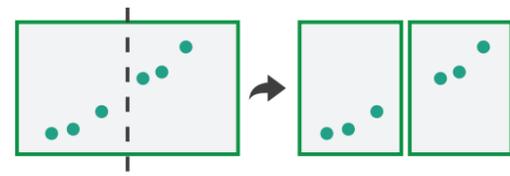
## Facet

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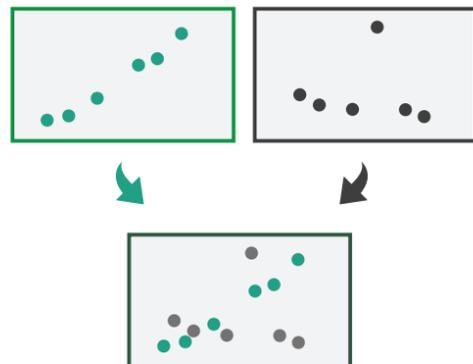
### → Juxtapose



### → Partition



### → Superimpose



## Reduce

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### → Filter



### → Aggregate



### → Embed



# Reduce items and attributes

- reduce/increase: inverses
- filter
  - pro: straightforward and intuitive
    - to understand and compute
  - con: out of sight, out of mind
- aggregation
  - pro: inform about whole set
  - con: difficult to avoid losing signal
- not mutually exclusive
  - combine filter, aggregate
  - combine reduce, change, facet

## Reducing Items and Attributes

### ① Filter

→ Items

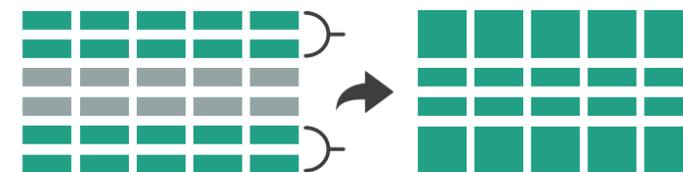


→ Attributes

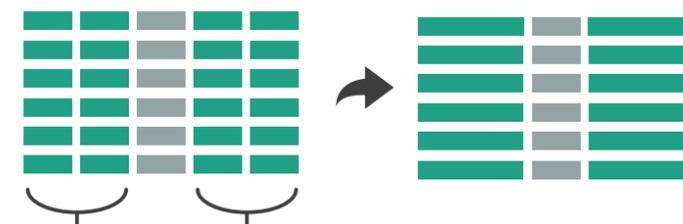


### ② Aggregate

→ Items



→ Attributes



## Reduce

### ① Filter



### ② Aggregate



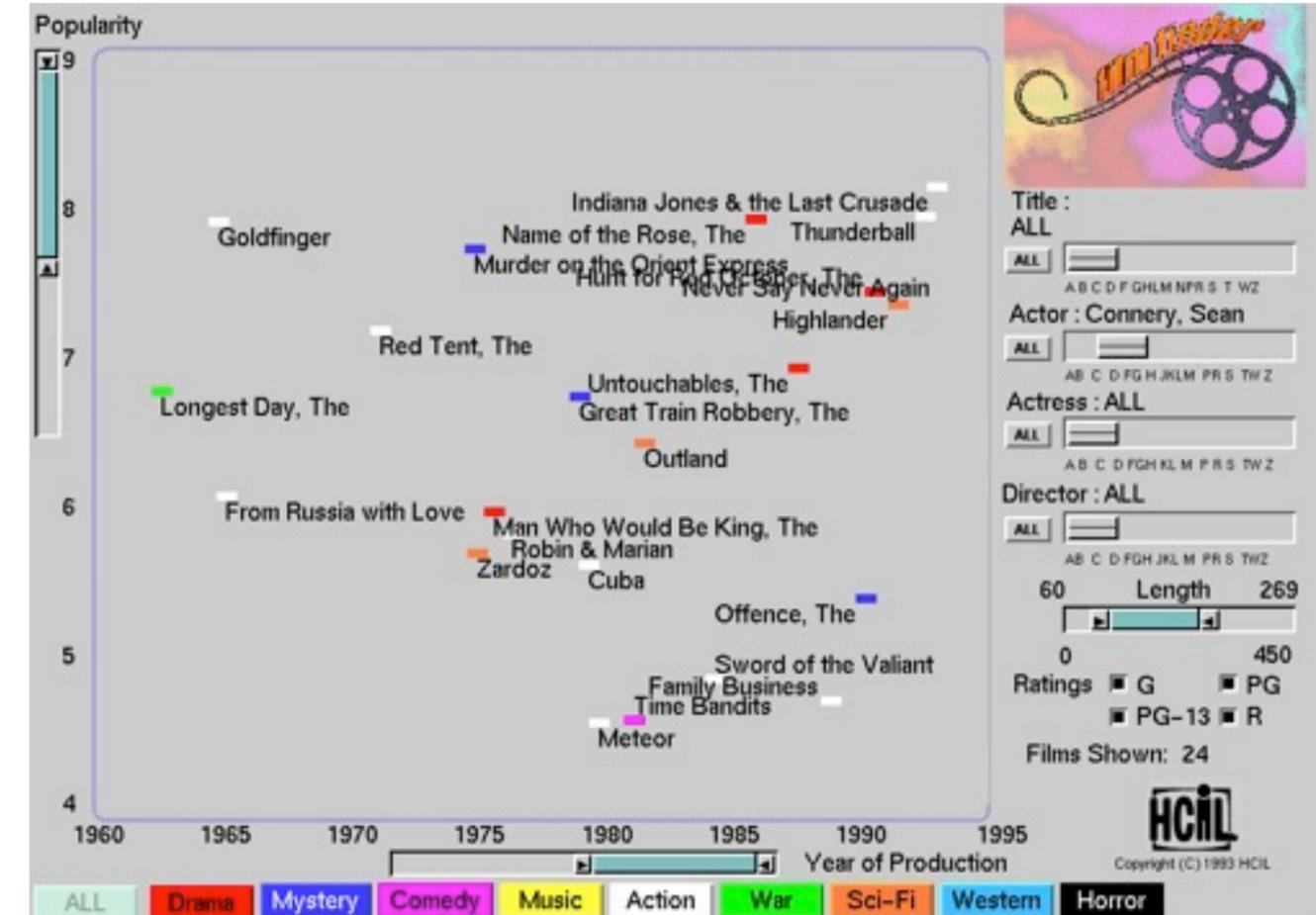
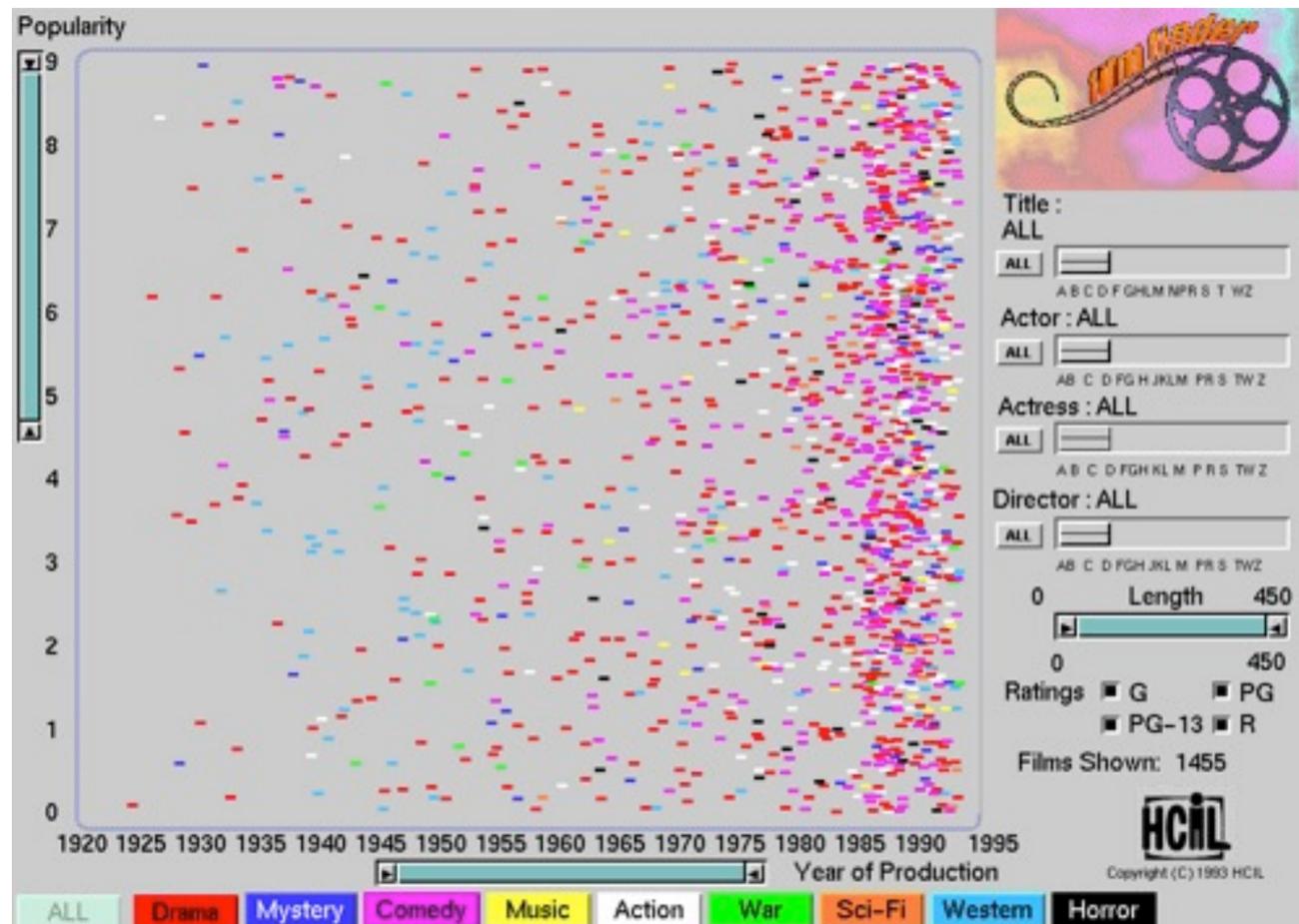
### ③ Embed



# Idiom: **dynamic filtering**

# System: **FilmFinder**

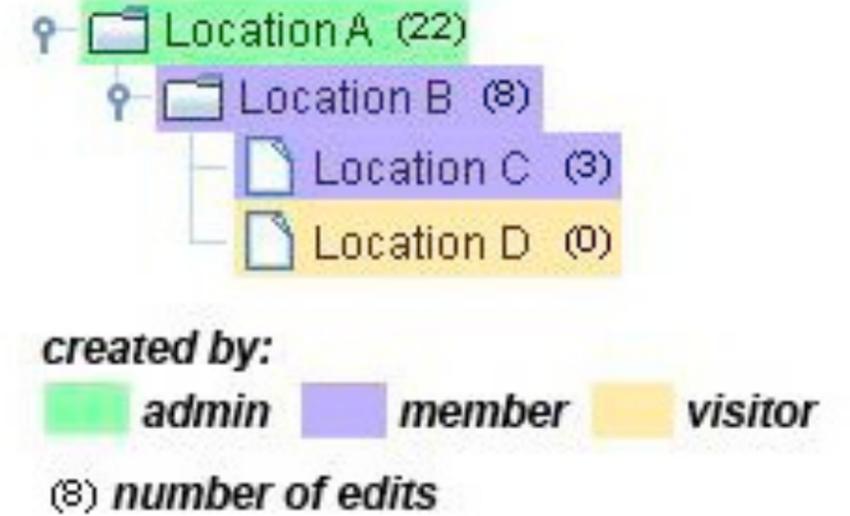
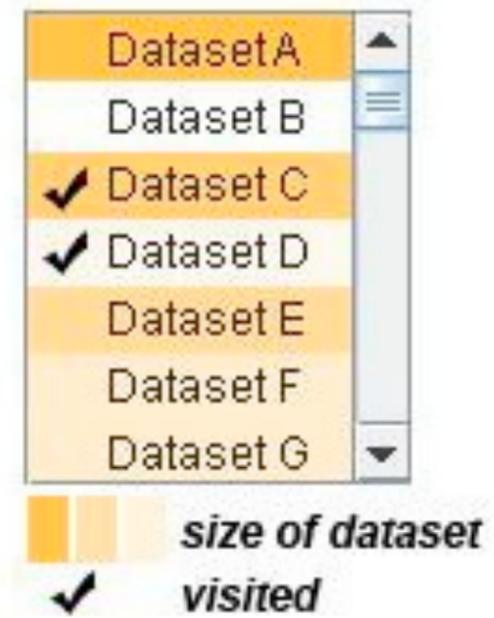
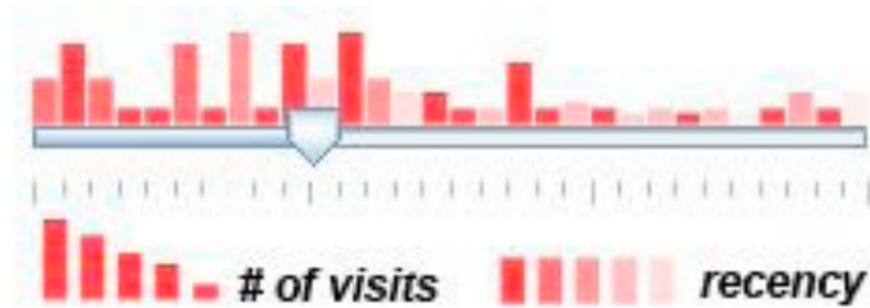
- item filtering
- browse through tightly coupled interaction
  - alternative to queries that might return far too many or too few



[Visual information seeking: Tight coupling of dynamic query filters with starfield displays. Ahlberg and Shneiderman. Proc. ACM Conf. on Human Factors in Computing Systems (CHI), pp. 313–317, 1994.]

# Idiom: scented widgets

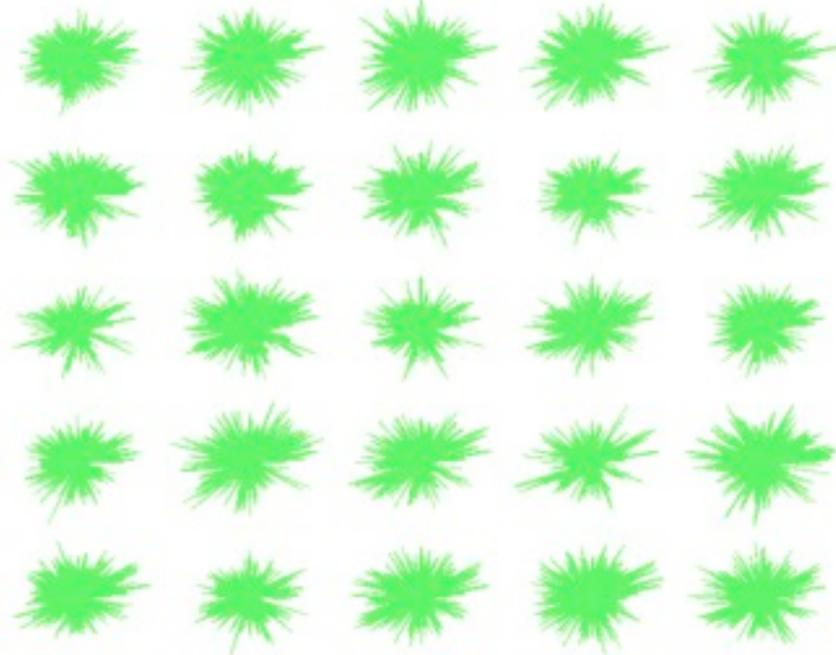
- augment widgets for filtering to show **information scent**
  - cues to show whether value in drilling down further vs looking elsewhere
- concise, in part of screen normally considered control panel



[Scented Widgets: Improving Navigation Cues with Embedded Visualizations. Willett, Heer, and Agrawala. *IEEE Trans. Visualization and Computer Graphics (Proc. InfoVis 2007)* 13:6 (2007), 1129–1136.]

# Idiom: **DOSFA**

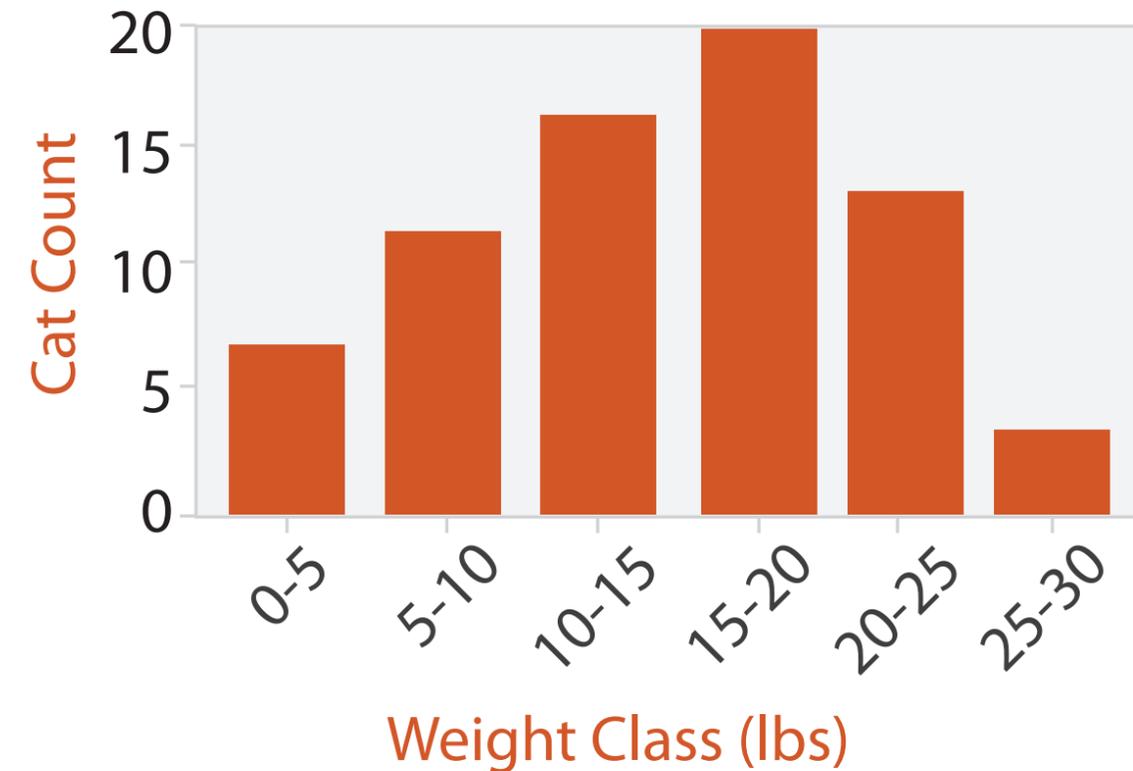
- attribute filtering
- encoding: star glyphs



*[Interactive Hierarchical Dimension Ordering, Spacing and Filtering for Exploration Of High Dimensional Datasets. Yang, Peng, Ward, and. Rundensteiner. Proc. IEEE Symp. Information Visualization (InfoVis), pp. 105–112, 2003.]*

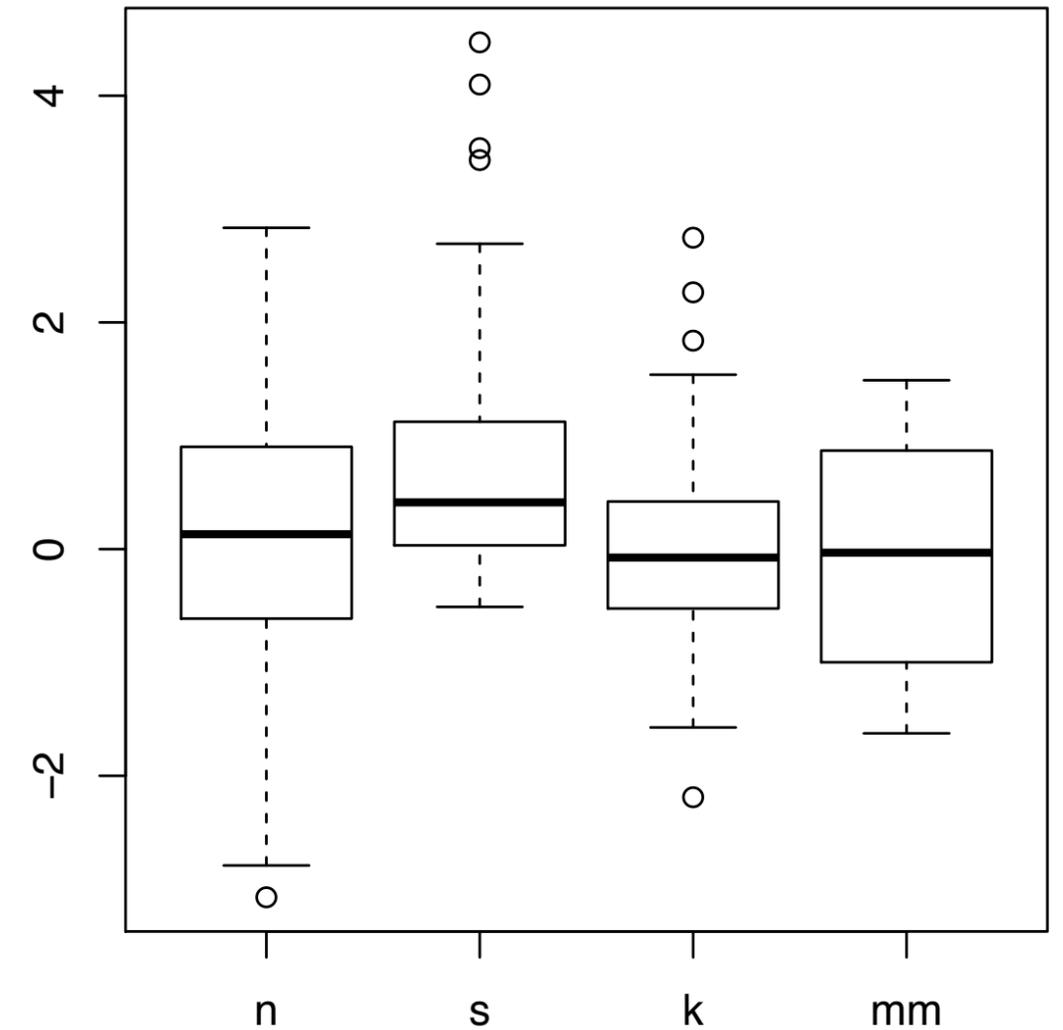
# Idiom: **histogram**

- static item aggregation
- task: find distribution
- data: table
- derived data
  - new table: keys are bins, values are counts
- bin size crucial
  - pattern can change dramatically depending on discretization
  - opportunity for interaction: control bin size on the fly



# Idiom: **boxplot**

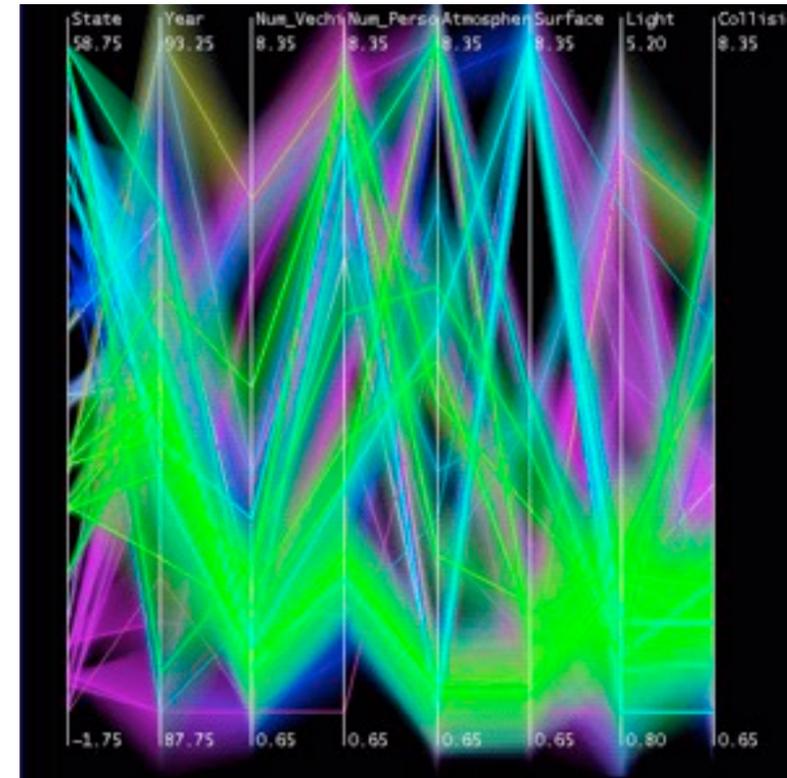
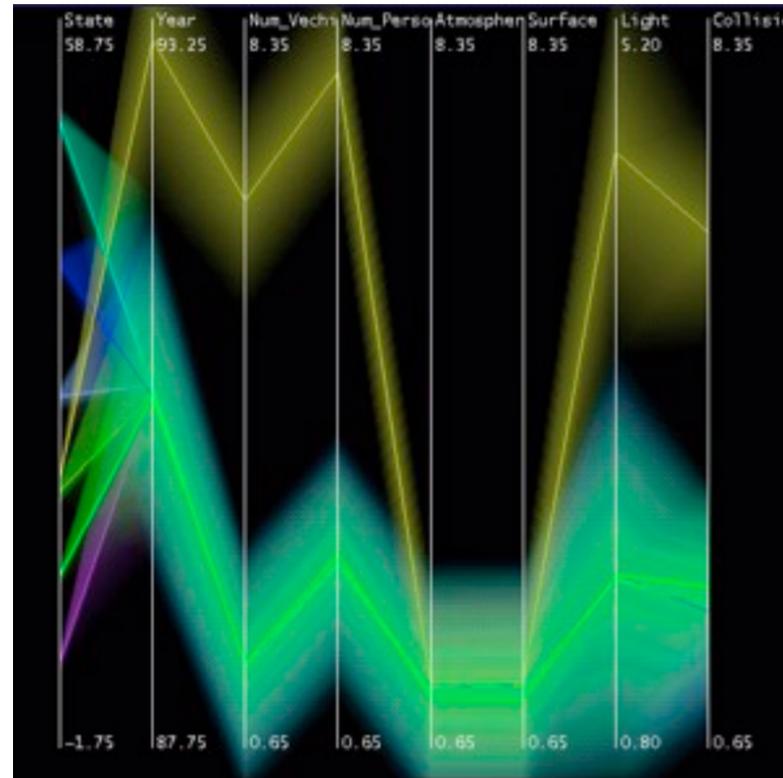
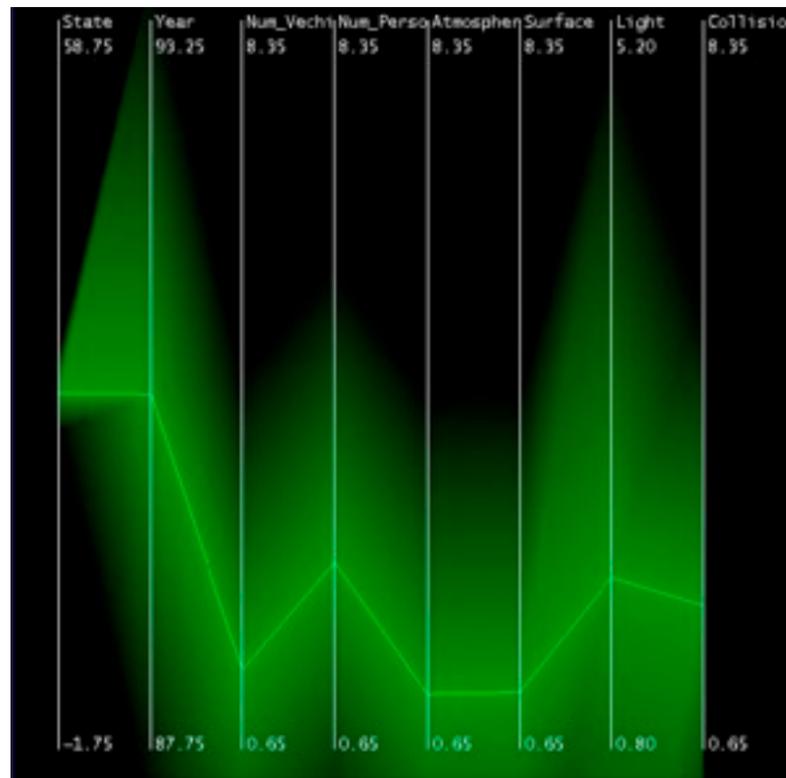
- static item aggregation
- task: find distribution
- data: table
- derived data
  - 5 quant attribs
    - median: central line
    - lower and upper quartile: boxes
    - lower upper fences: whiskers
      - values beyond which items are outliers
  - outliers beyond fence cutoffs explicitly shown



*[40 years of boxplots. Wickham and Stryjewski. 2012. had.co.nz]*

# Idiom: Hierarchical parallel coordinates

- dynamic item aggregation
- derived data: **hierarchical clustering**
- encoding:
  - cluster band with variable transparency, line at mean, width by min/max values
  - color by proximity in hierarchy



[Hierarchical Parallel Coordinates for Exploration of Large Datasets. Fua, Ward, and Rundensteiner. Proc. IEEE Visualization Conference (Vis '99), pp. 43– 50, 1999.]

# Dimensionality reduction

- attribute aggregation
  - derive low-dimensional target space from high-dimensional measured space
  - use when you can't directly measure what you care about
    - true dimensionality of dataset conjectured to be smaller than dimensionality of measurements
    - latent factors, hidden variables

Tumor  
Measurement Data

data: 9D measured space

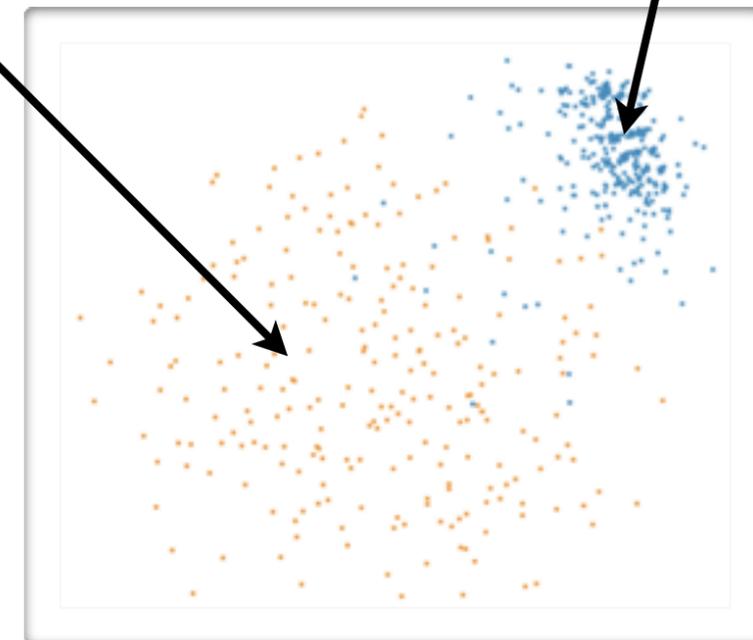


**DR**



Malignant

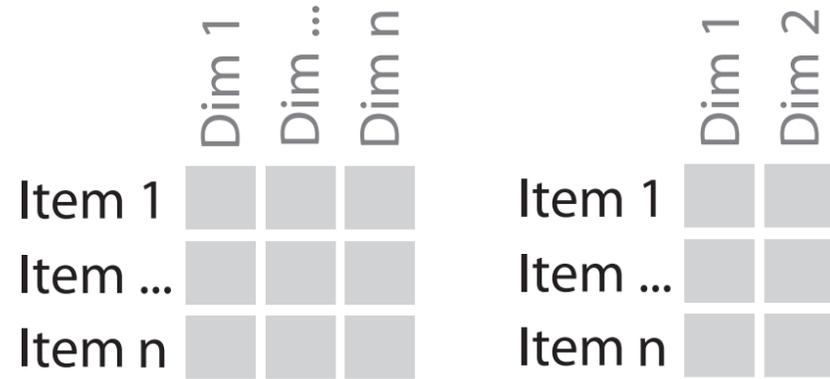
Benign



derived data: 2D target space

# Dimensionality reduction for documents

## Task 1



**In** HD data → **Out** 2D data

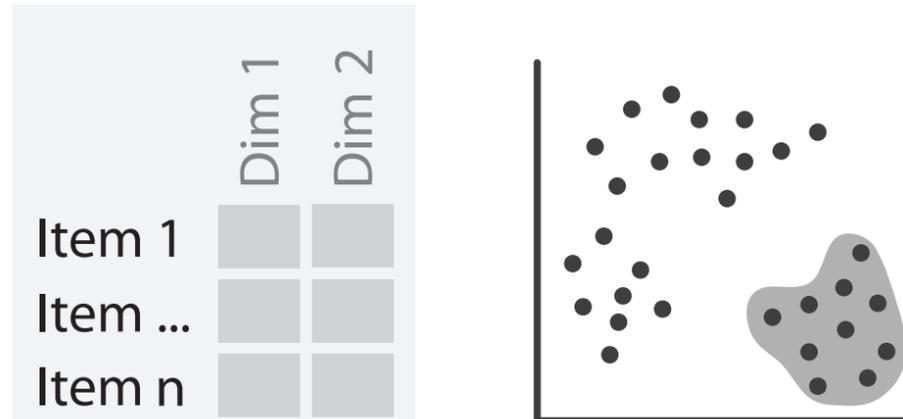
### What?

### Why?

- **In** High-dimensional data
- **Out** 2D data

- Produce
- Derive

## Task 2



**In** 2D data → **Out** Scatterplot  
Clusters & points

### What?

### Why?

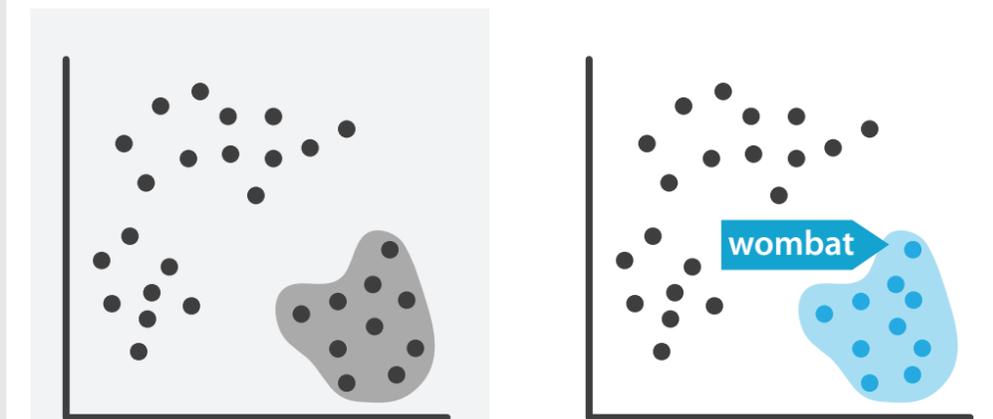
### How?

- **In** 2D data
- **Out** Scatterplot
- **Out** Clusters & points

- Discover
- Explore
- Identify

- Encode
- Navigate
- Select

## Task 3



**In** Scatterplot  
Clusters & points → **Out** Labels for  
clusters

### What?

### Why?

- **In** Scatterplot
- **In** Clusters & points
- **Out** Labels for clusters

- Produce
- Annotate

# Dimensionality vs attribute reduction

- vocab use in field not consistent
  - dimension/attribute
- attribute reduction: reduce set with filtering
  - includes orthographic projection
- dimensionality reduction: create smaller set of new dims/attribs
  - typically implies dimensional aggregation, not just filtering
  - vocab: projection/mapping

# Estimating true dimensionality

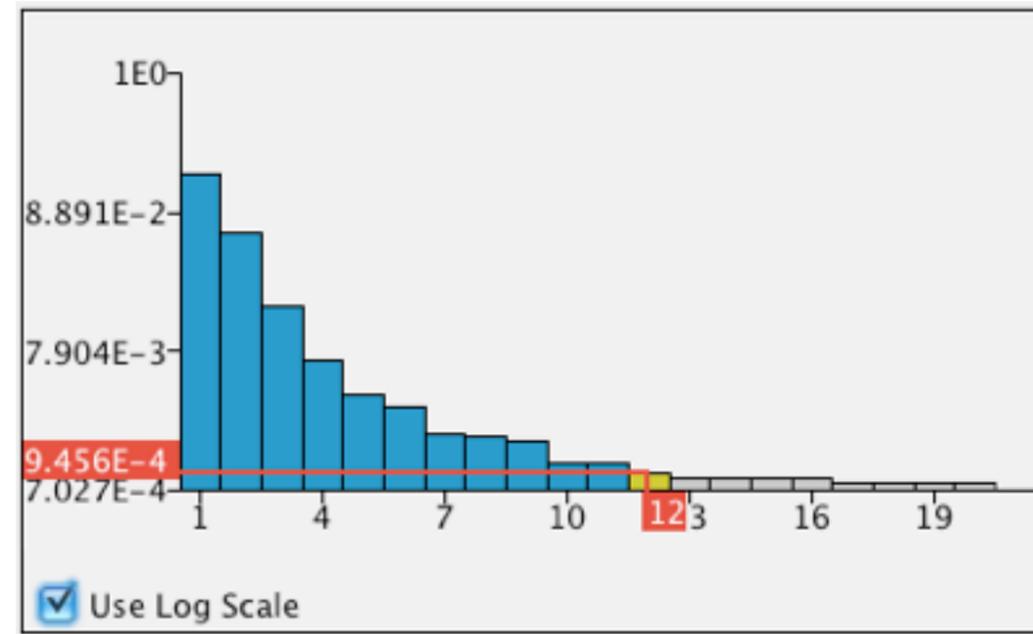
- how do you know when you would benefit from DR?
  - consider error for low-dim projection vs high-dim projection
- no single correct answer; many metrics proposed
  - cumulative variance that is not accounted for
  - strain: match variations in distance (vs actual distance values)
  - stress: difference between interpoint distances in high and low dims

$$\text{stress}(D, \Delta) = \sqrt{\frac{\sum_{ij} (d_{ij} - \delta_{ij})^2}{\sum_{ij} \delta_{ij}^2}}$$

- $D$ : matrix of lowD distances
- $\Delta$ : matrix of hiD distances  $\delta_{ij}$

# Estimating true dimensionality

- scree plots as simple way: error against # attribs



- original dataset: 294 dims
- estimate: almost all variance preserved with  $< 20$  dims

[Fig 2. DimStiller: Workflows for dimensional analysis and reduction. Ingram et al. Proc. VAST 2010, p 3-10]

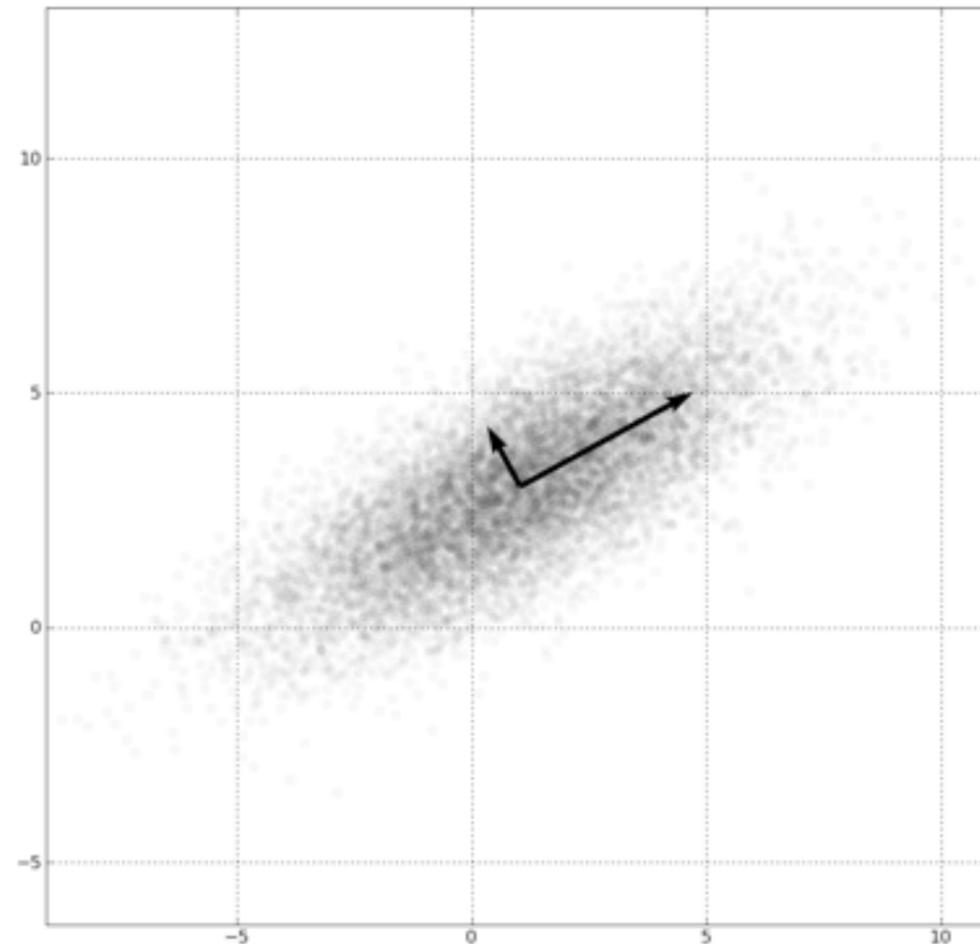
# Dimensionality Reduction

- why do people do DR?
  - improve performance of downstream algorithm
    - avoid curse of dimensionality
  - data analysis
    - if look at the output: visual data analysis!
- DR tasks
  - dimension-oriented task sequences
    - name synthetic dimensions, map synthetic dims to original ones
  - cluster-oriented task sequences
    - verify clusters, name clusters, match clusters and classes

*[Visualizing Dimensionally-Reduced Data: Interviews with Analysts and a Characterization of Task Sequences. Brehmer, Sedlmair, Ingram, and Munzner. Proc BELIV 2014.]*

# Linear dimensionality reduction

- principal components analysis (PCA)
  - describe location of each point as linear combination of weights for each axis
  - finding axes: first with most variance, second with next most, ...



[<http://en.wikipedia.org/wiki/File:GaussianScatterPCA.png>]

# Nonlinear dimensionality reduction

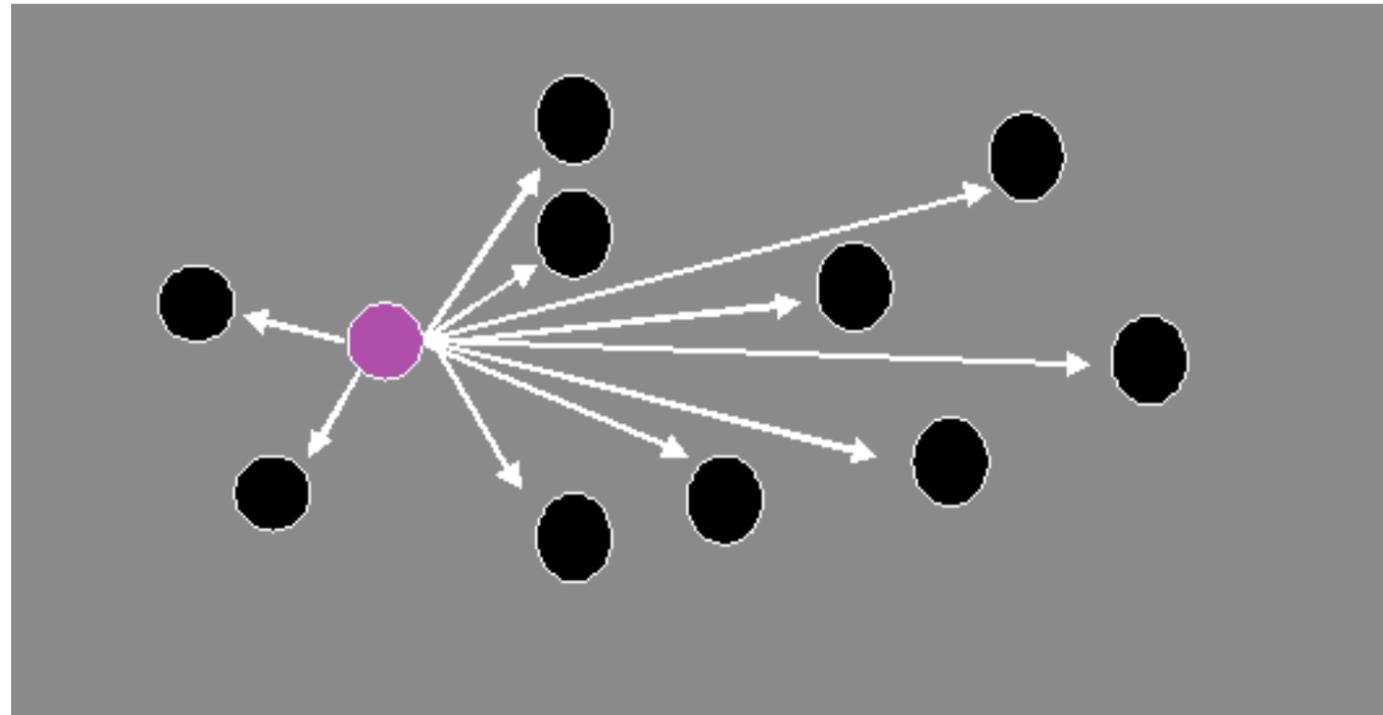
- many techniques proposed
  - MDS, charting, isomap, LLE, T-SNE
  - many literatures: visualization, machine learning, optimization, psychology, ...
- pro: can handle curved rather than linear structure
- cons: lose all ties to original dims/attribs
  - new dimensions cannot be easily related to originals

# MDS: Multidimensional Scaling

- confusingly: entire family of methods, linear and nonlinear!
- classical scaling: minimize strain
  - early formulation equivalent to PCA (linear)
  - Nystrom/spectral methods approximate eigenvectors:  $O(N)$ 
    - Landmark MDS [de Silva 2004], PivotMDS [Brandes & Pich 2006]
  - limitations: quality for very high dimensional sparse data
- distance scaling: minimize stress
  - nonlinear optimization:  $O(N^2)$ 
    - SMACOF [de Leeuw 1977]
  - force-directed placement:  $O(N^2)$ 
    - Stochastic Force [Chalmers 1996]
    - limitations: quality problems from local minima
- Glimmer goal:  $O(N)$  speed and high quality

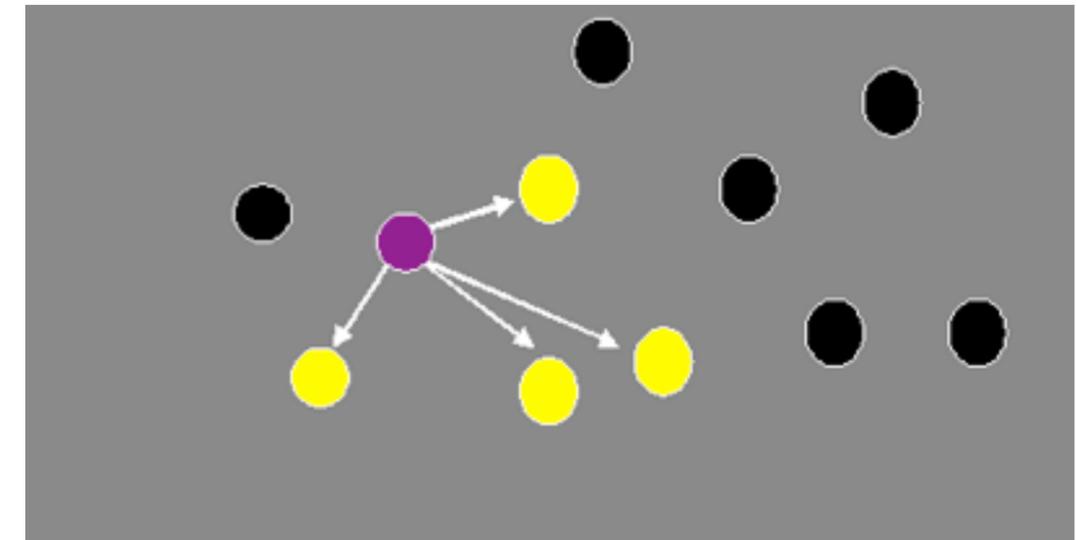
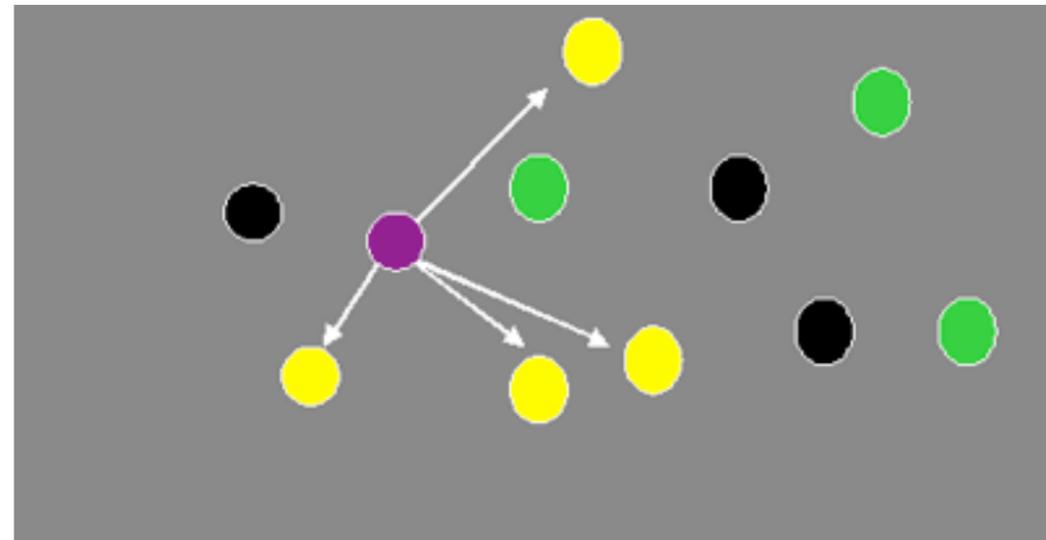
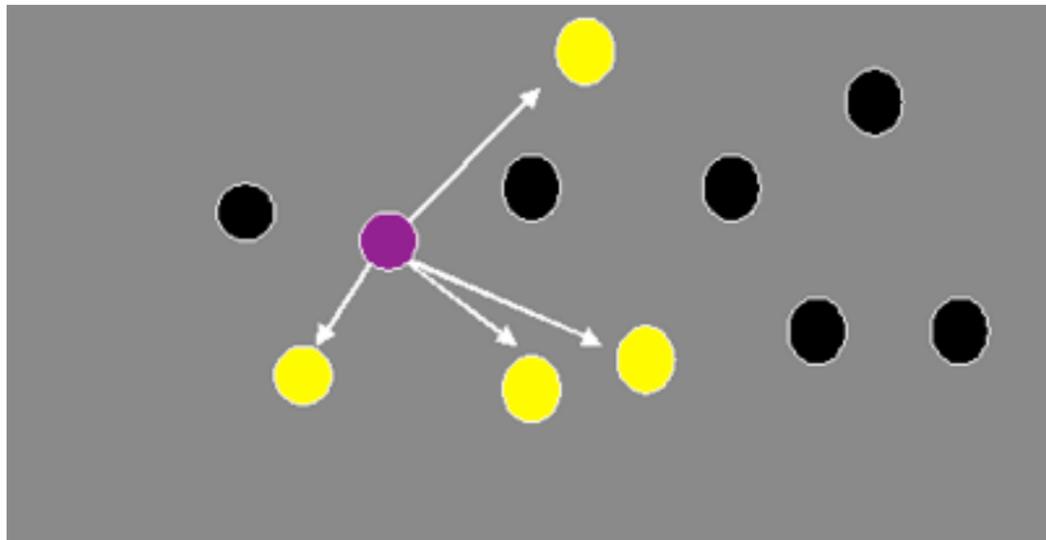
# Spring-based MDS: naive

- repeat for all points
  - compute spring force to all other points
  - difference between high dim, low dim distance
  - move to better location using computed forces
- compute distances between all points
  - $O(N^2)$  iteration,  $O(N^3)$  algorithm



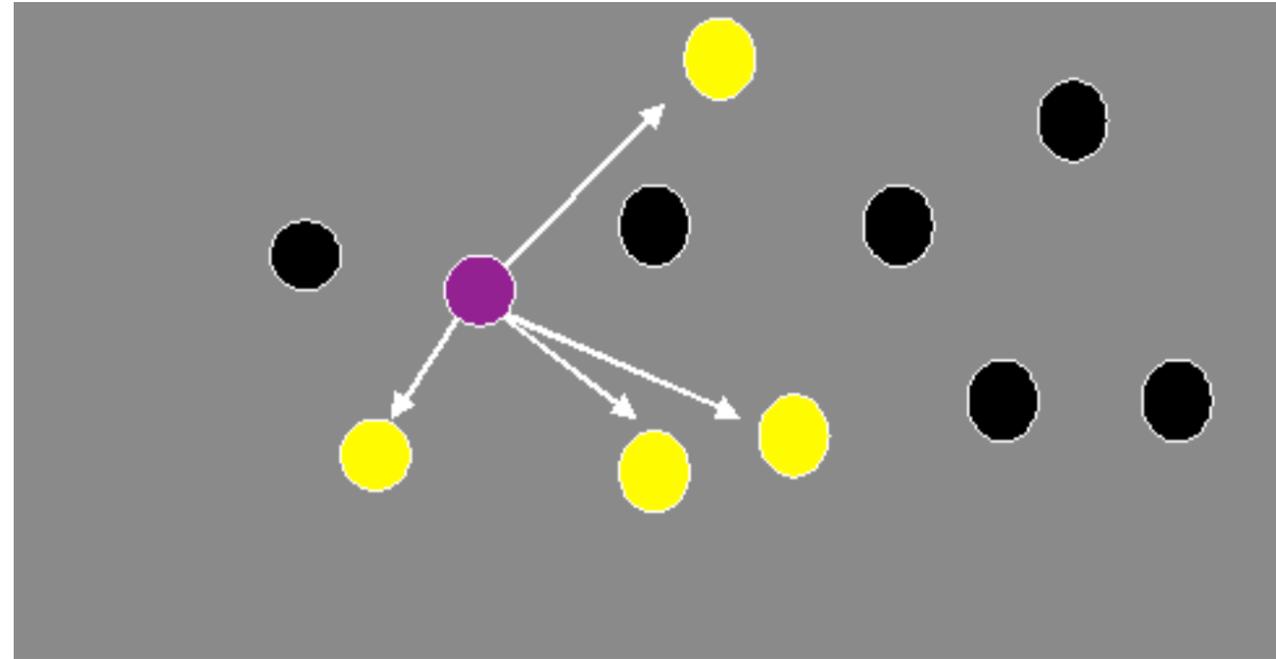
# Faster spring model: Stochastic

- compare distances only with a few points
  - maintain small local neighborhood set
  - each time pick some randoms, swap in if closer
- small constant: 6 locals, 3 randoms (typically)
  - $O(N)$  iteration,  $O(N^2)$  algorithm



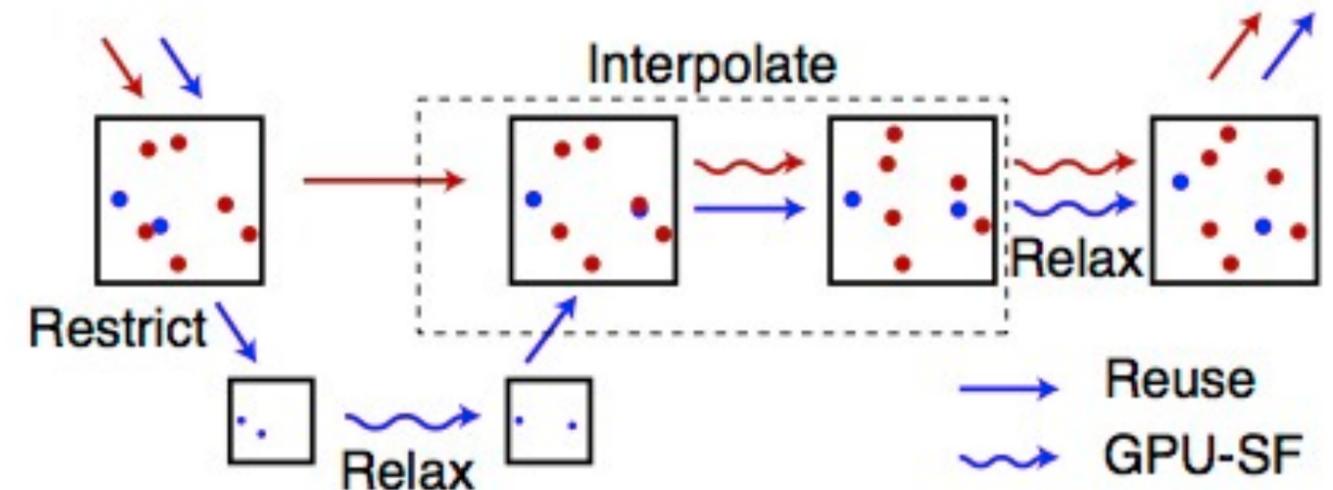
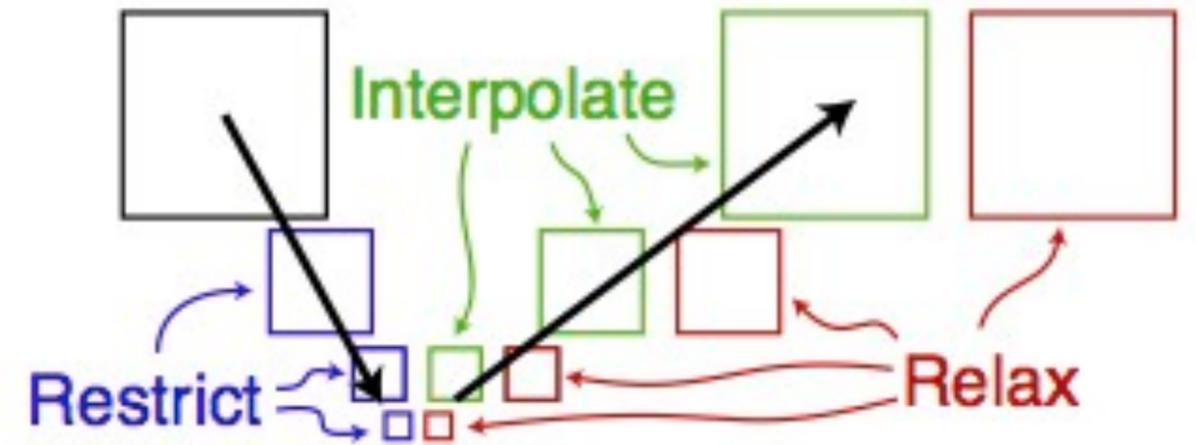
# Faster spring model: Stochastic

- compare distances only with a few points
  - maintain small local neighborhood set



# Glimmer algorithm

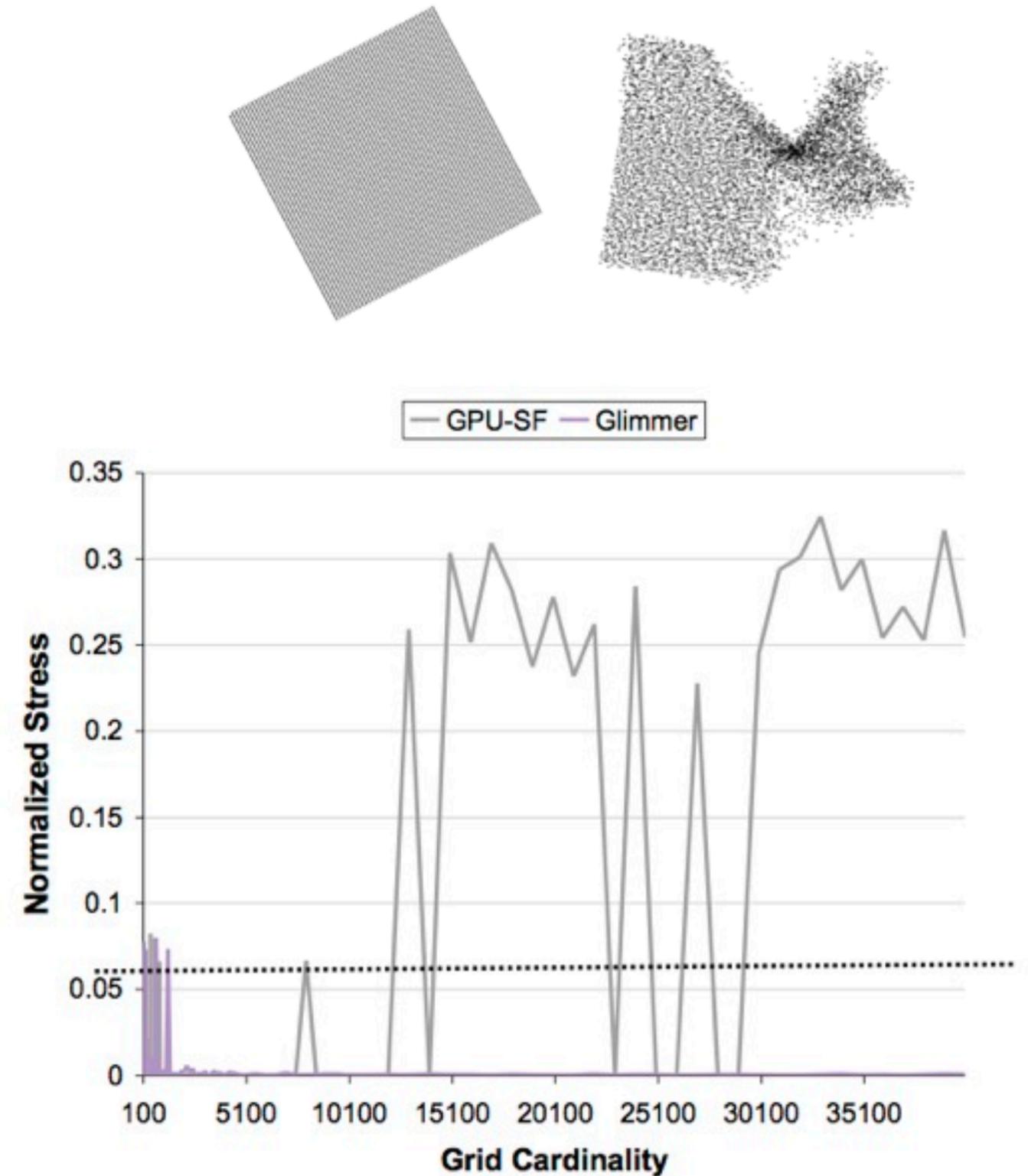
- multilevel to avoid local minima, designed to exploit GPU
- restriction to decimate
- relaxation as core computation
- relaxation to interpolate up to next level



[Glimmer: Multilevel MDS on the GPU. Ingram, Munzner, Olano. *IEEE TVCG* 15(2):249-261, 2009.]

# Glimmer Strategy

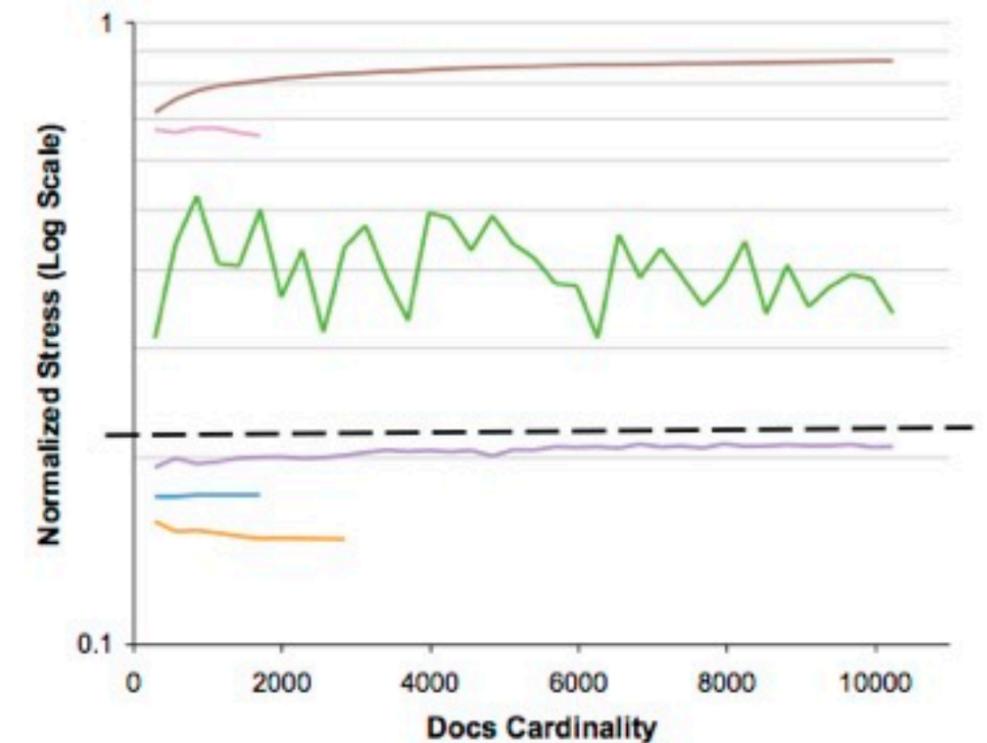
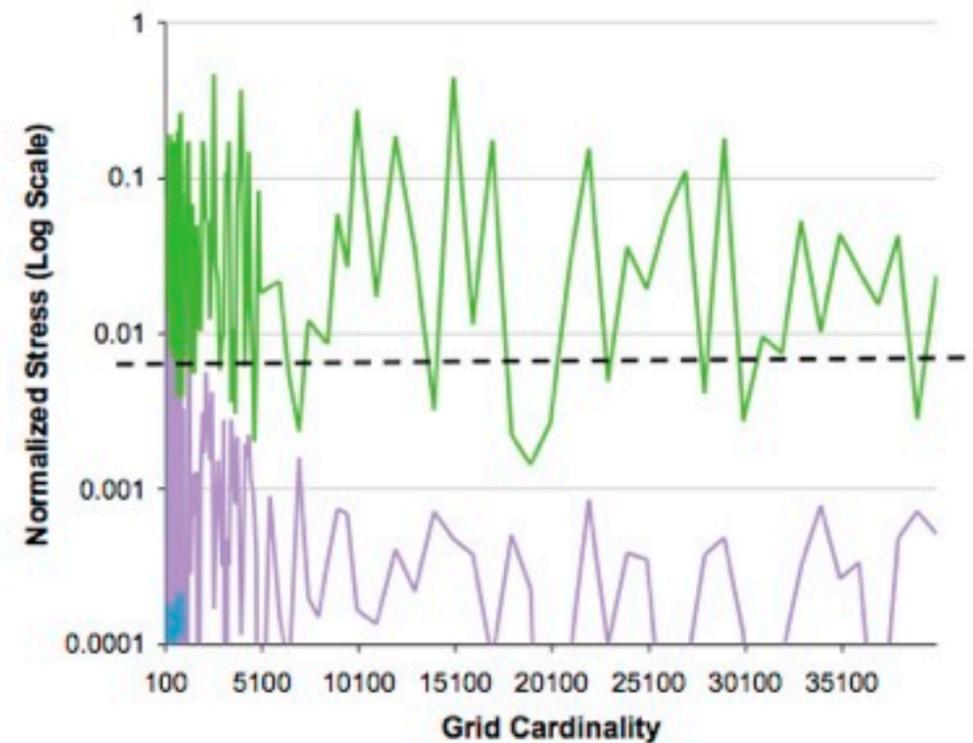
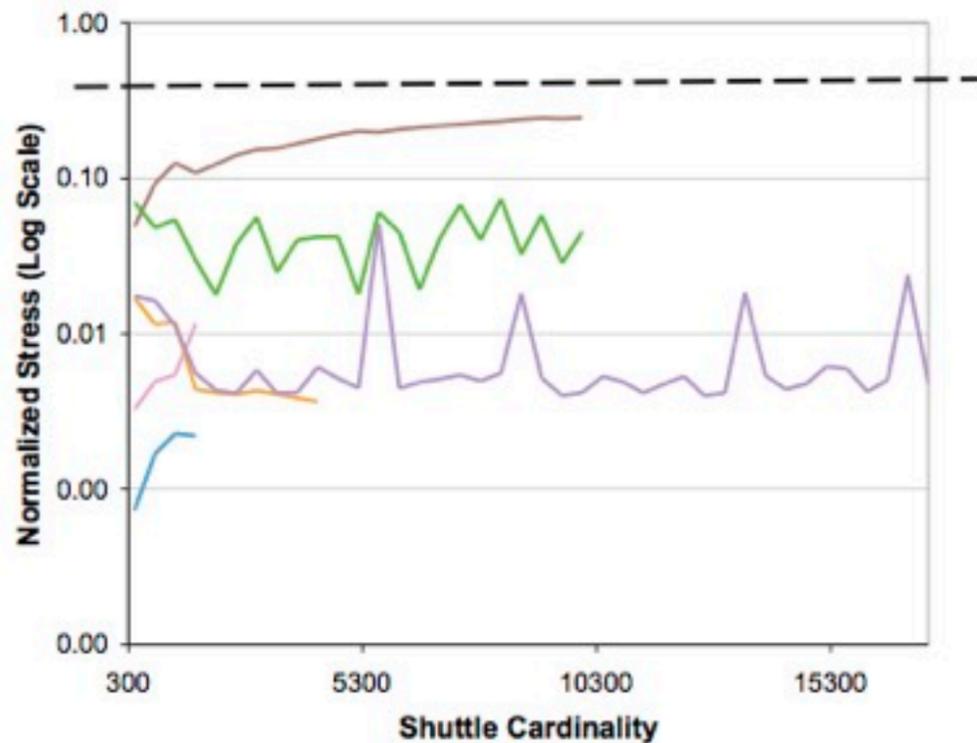
- stochastic force alg suitable for fast GPU port
  - but systematic testing shows it often terminates too soon
- use as subsystem within new multilevel GPU alg with much better convergence properties



[Fig 2,4. Glimmer: Multilevel MDS on the GPU. Ingram, Munzner, Olano. *IEEE TVCG* 15(2):249-261, 2009.]

# Stochastic termination

- how do you know when it's done?
  - no absolute threshold, depends on the dataset
  - interactive click to stop does not work for subsystem



- sparse normalized stress approximation
  - minimal overhead to compute (vs full stress)
  - low pass filter

[Fig 9. Glimmer: Multilevel MDS on the GPU. Ingram, Munzner, Olano. *IEEE TVCG* 15(2):249-261, 2009.]

# GPUs

- characteristics
  - small set of localized texture accesses
  - output at predetermined locations
  - no variable length looping
  - avoid conditionals: all floating point units execute same instr at same time
- mapping problems to GPU
  - arrays become textures
  - inner loops become fragment shader code
  - program execution becomes rendering

# Finding and verifying clusters

- sparse docs dataset
  - 28K dims, 28K points
    - speed equivalent to classical
    - quality major improvement

**Glimmer**

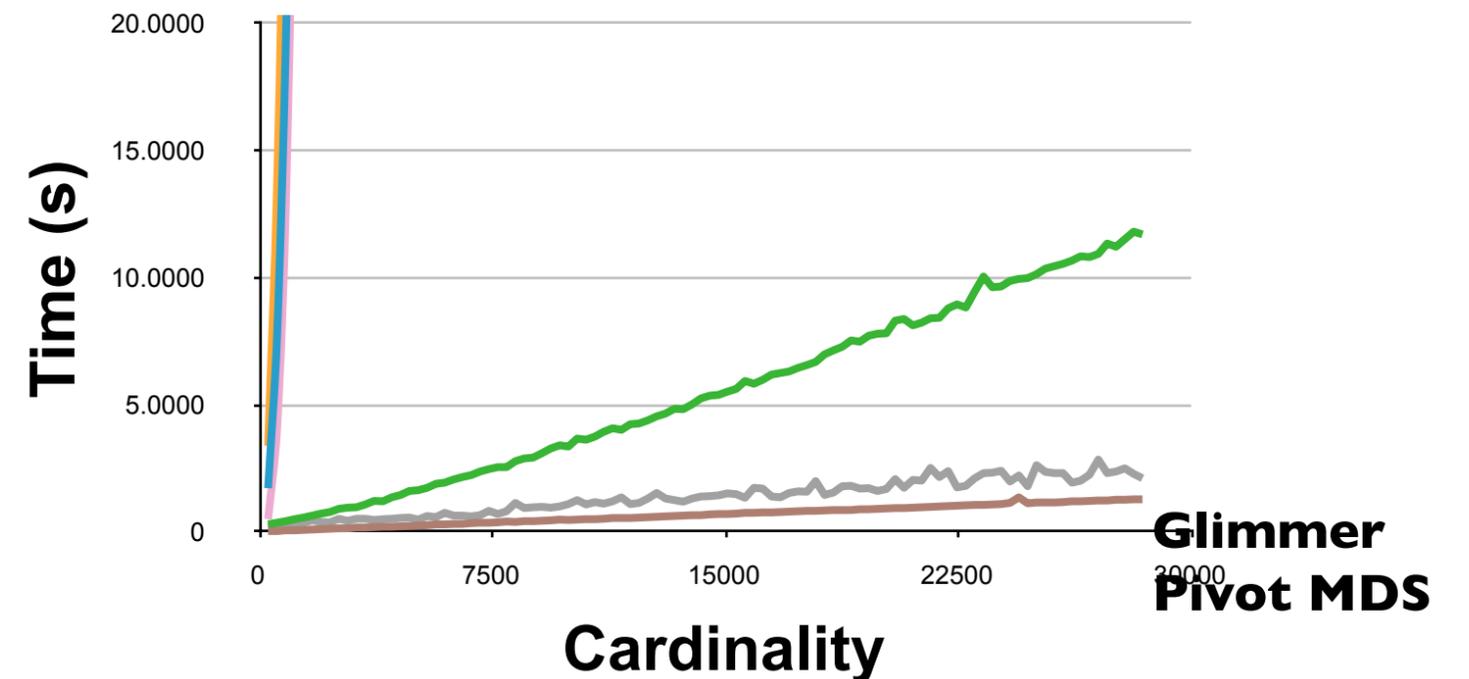
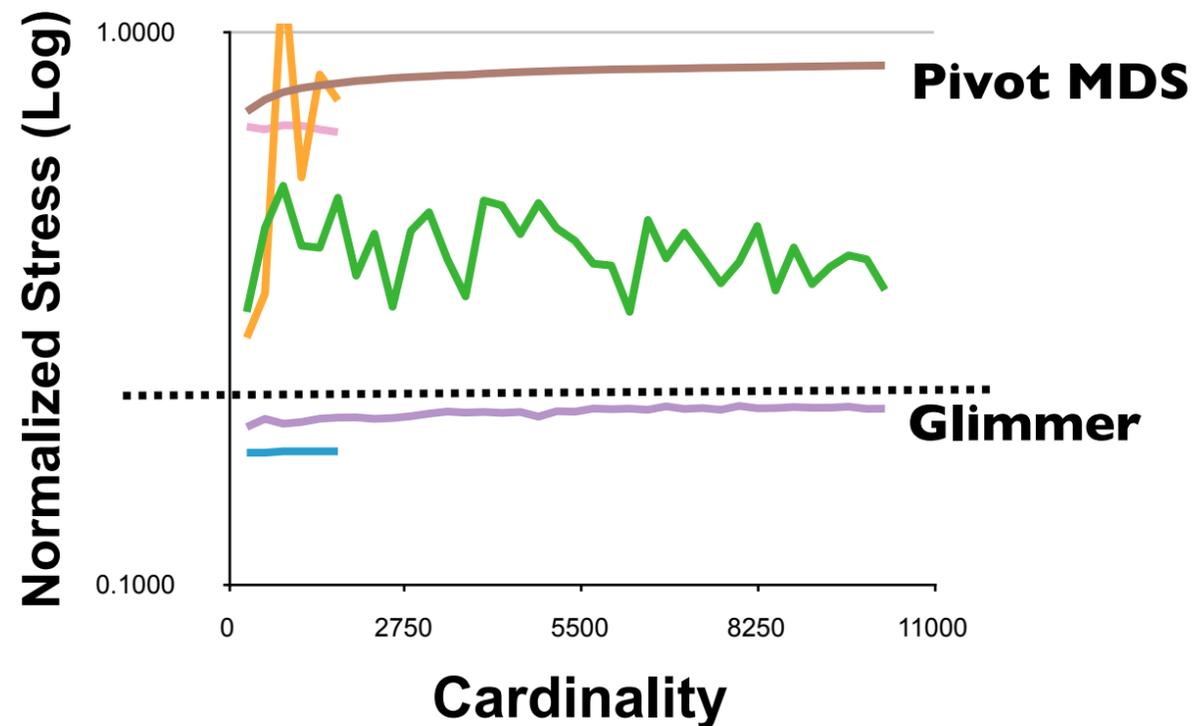


16.64 s stress=0.157

**Pivot MDS**



2.17 s stress=0.928



[Fig 8, 9. Glimmer: Multilevel MDS on the GPU. Ingram, Munzner, Olano. IEEE TVCG 15(2):249-261, 2009.]

# Methods and outcomes

- methods

- quantitative algorithm benchmarks: speed, quality
  - systematic comparison across 1K-10K instances vs a few spot checks
- qualitative judgements of layout quality

- outcomes

- characterized kinds of datasets where technique yields quality improvements
  - sparse documents

- followup work

- Q-SNE: millions of documents

*[Dimensionality Reduction for Documents with Nearest Neighbor Queries. Ingram, Munzner. Neurocomputing. Special Issue Visual Analytics using Multidimensional Projections, to appear 2014.]*