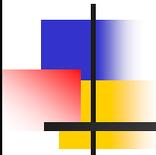


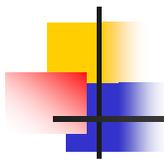


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Chapter 8



Scan Conversion (part 2)– Drawing Polygons on Raster Display



Rasterizing Polygons/Triangles

- Basic surface representation in rendering
- Why?
 - Lowest common denominator
 - Can approximate any surface with arbitrary accuracy
 - All polygons can be broken up into triangles
 - Guaranteed to be:
 - Planar
 - Triangles - Convex
 - Simple to render
 - Can implement in hardware

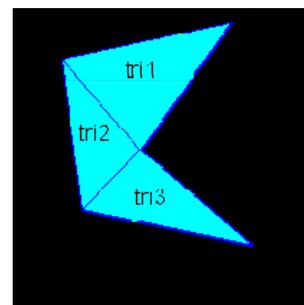
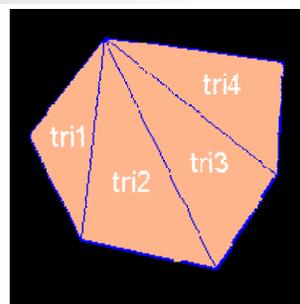
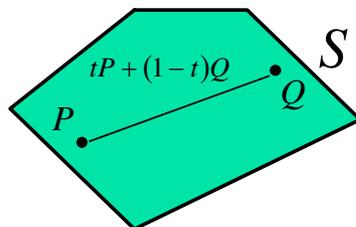


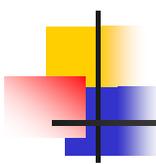
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Triangulation

- Convex polygons easily triangulated
- Concave polygons present a challenge
- Convexity - formal definition:

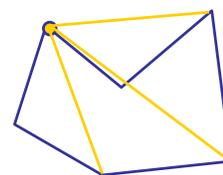
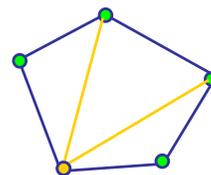
Object S is **convex** iff for any two points $P, Q \in S$, $tP + (1-t)Q \subseteq S$, $t \in [0,1]$.



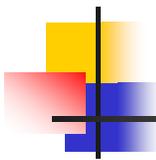


OpenGL Triangulation

- Simple convex polygons
 - break into triangles, trivial
 - glBegin(GL_POLYGON) ... glEnd()
- Concave or non-simple polygons
 - break into triangles, more effort
 - gluNewTess(), gluTessCallback(), ...

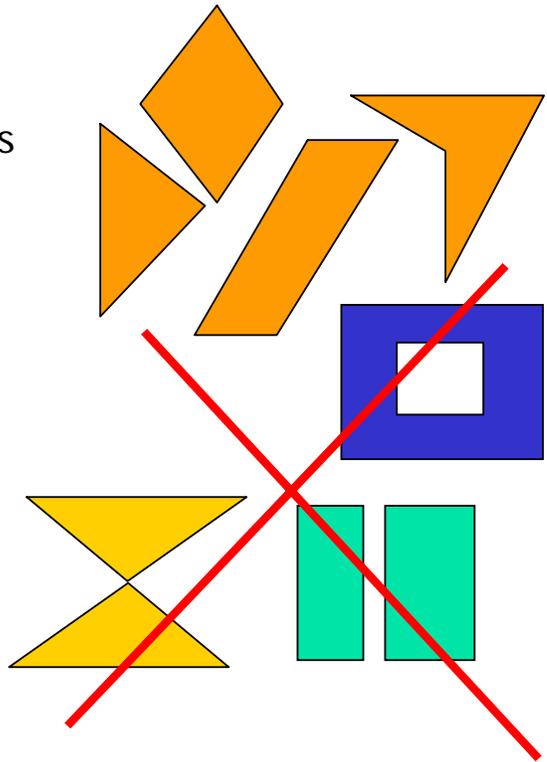


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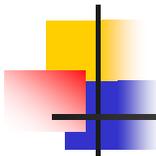


Polygon Rasterization

- Assumptions – well behaved
 - simple - no self intersections
 - simply connected
 - (no holes)
- Solutions
 - Flood fill
 - Scan line
 - Implicit test

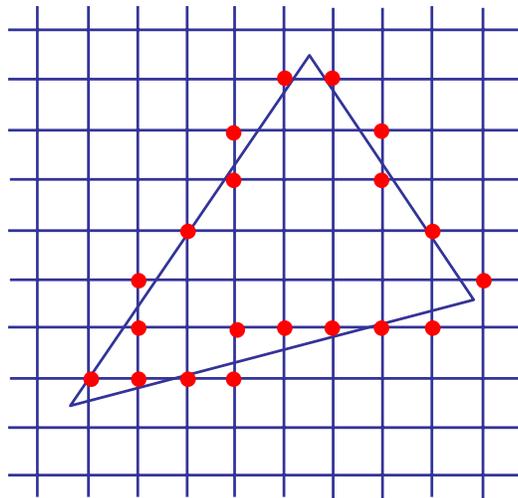


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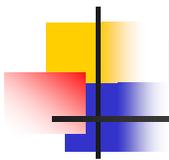


Formulation

- Input
 - polygon P with rasterized edges
- Problem: Fill its interior with specified color on graphics display

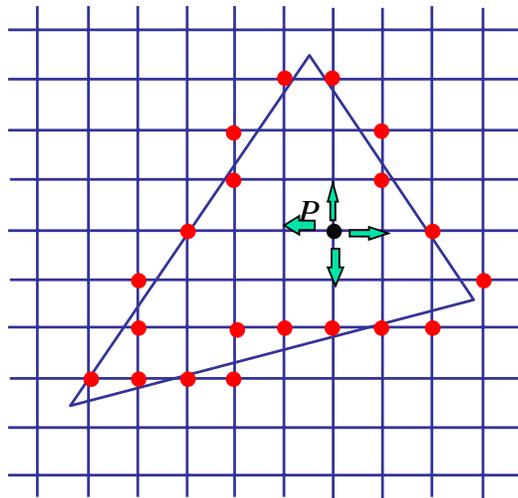


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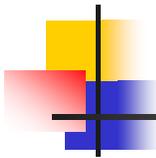


Flood Fill Algorithm

- Input
 - polygon P with rasterized edges
 - $P = (x,y) \in P$ point inside P



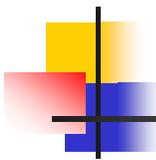
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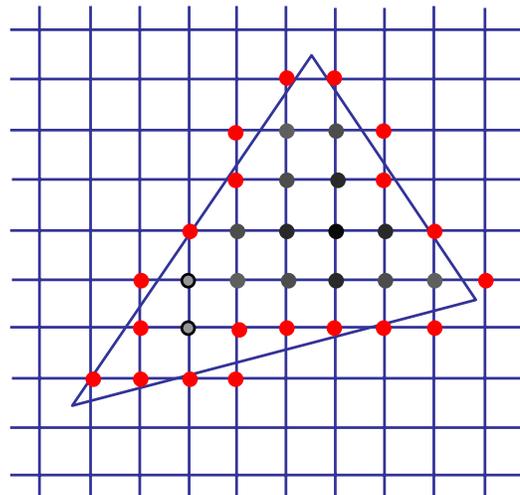
Flood Fill

```
FloodFill (Polygon P, int x, int y, Color C)
if not (OnBoundary (x, y, P) or Colored (x, y, C))
begin
PlotPixel (x, y, C);
FloodFill (P, x + 1, y, C);
FloodFill (P, x, y + 1, C);
FloodFill (P, x, y - 1, C);
FloodFill (P, x - 1, y, C);
end ;
```





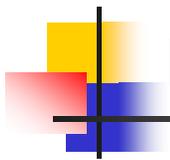
Flood Fill



- Drawbacks?



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Flood Fill - Drawbacks

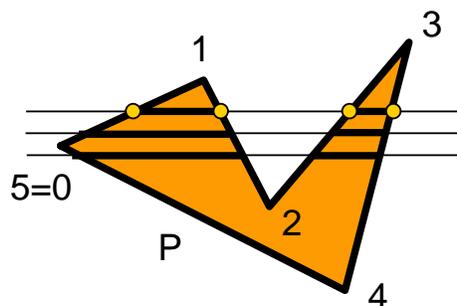
- How do we find a point inside?
- Pixels visited up to 4 times to check if already set
- Need per-pixel flag indicating if set already
 - clear for every polygon!



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Scanline Algorithm

- Observation: Each intersection of straight line with boundary moves it from/into polygon
- Detect (& set) pixels inside polygon boundary (simple closed curve) with set of horizontal lines (pixel apart)



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ScanConvert (Polygon P , Color C)

For $y := 0$ to ScreenYMax do

$I \leftarrow$ Points of intersections of edges of P with line $Y = y$;

Sort I in increasing X order and

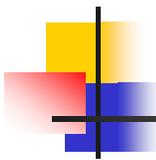
Fill with color C alternating segments ;

end ;

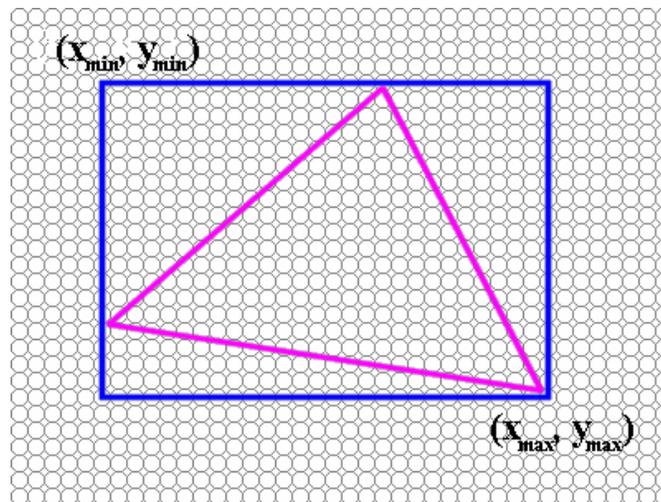
- Limit to *bounding box* to speed up
- Other enhancements....



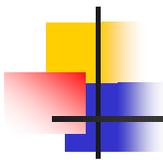
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Bounding Box



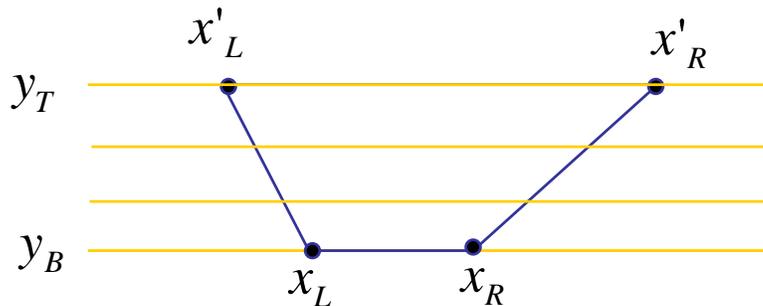
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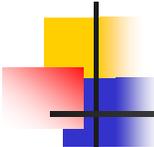
Edge Walking

- Scanline is more efficient for specific polygons
– trapezoids (triangles)

scanTrapezoid($x_L, x_R, y_B, y_T, x'_L, x'_R$)

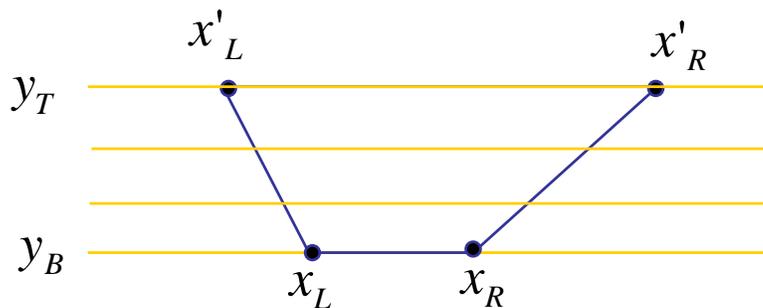


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Edge Walking

```
for (y=yB; y<=yT; y++) {  
    xl = intersect(Y=y, (xL,x'L));  
    xr = intersect(Y=y, (xR,x'R));  
    for (x=xl; x<=xr; x++)  
        setPixel(x,y);  
}
```

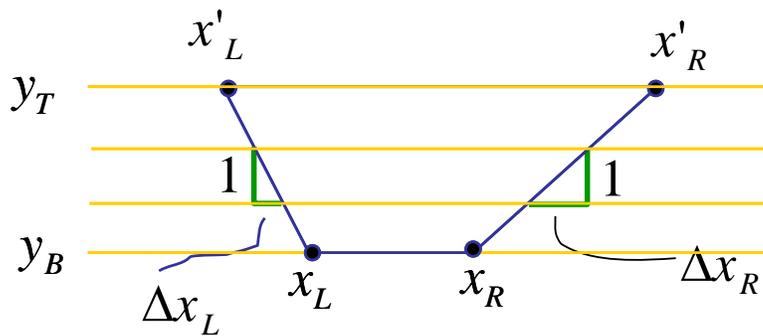


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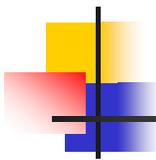
Edge Walking

- Exploit continuous L and R edges

scanTrapezoid($x_L, x_R, y_B, y_T, \Delta x_L, \Delta x_R$)

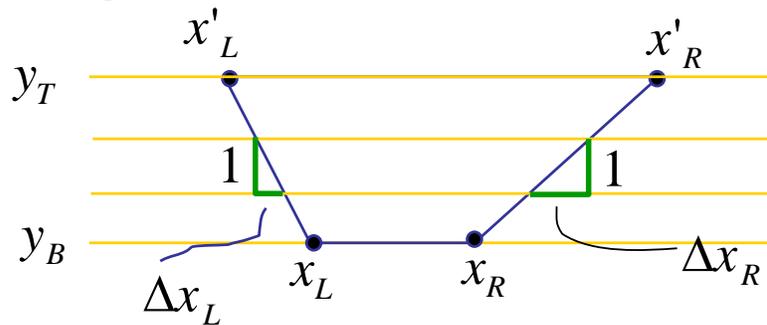


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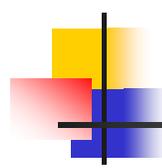


Edge Walking

```
for (y=yB; y<=yT; y++) {  
  for (x=xL; x<=xR; x++)  
    setPixel(x,y);  
  xL += DxL;  
  xR += DxR;  
}
```



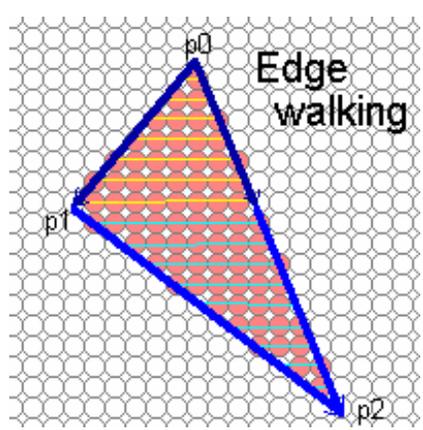
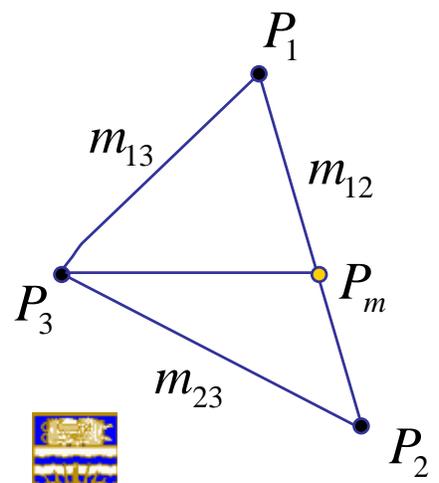
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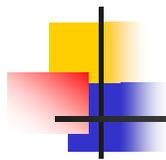


Edge Walking Triangles

- Split triangles into two regions with continuous left and right edges

$\text{scanTrapezoid}(x_3, x_m, y_3, y_1, \frac{1}{m_{13}}, \frac{1}{m_{12}})$
 $\text{scanTrapezoid}(x_2, x_m, y_2, y_3, \frac{1}{m_{23}}, \frac{1}{m_{12}})$



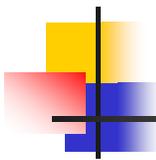


Edge Walking Triangles

- Issues
 - Many small triangles
 - setup cost is non-trivial
 - Clipping triangles produces non-triangles

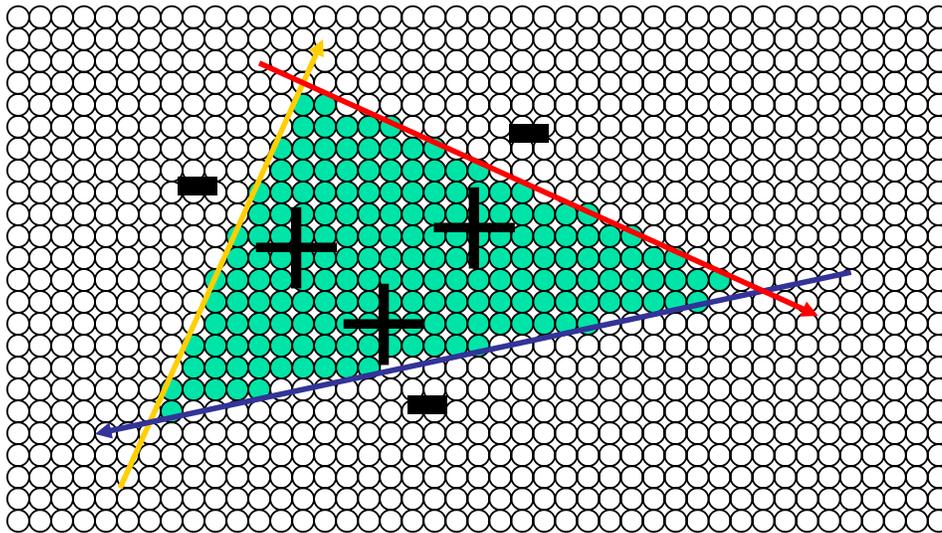


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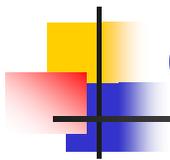


Modern Rasterization

- Define a triangle from implicit edge equations:



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Computing Edge Equations

- Computing A, B, C from $(x_1, y_1), (x_2, y_2)$

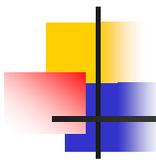
$$Ax_1 + By_1 + C = 0$$

$$Ax_2 + By_2 + C = 0$$

- Two equations, three unknowns
- Express A, B in terms of C



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Computing Edge Equations

$$\begin{bmatrix} x_1 & y_1 \\ x_2 & y_2 \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = -C \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

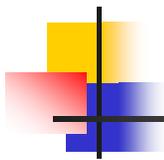
$$A = \frac{-C - By_1}{x_1}$$

$$B(x_1y_2 - x_2y_1) = C(x_2 - x_1)$$

(special case if $x_1 = 0$)

- Choose $C = x_2y_1 - x_1y_2$ for convenience
- Then $A = y_2 - y_1$ and $B = x_1 - x_2$
 - Our original implicit formula
- Note – in literature you can find same equation multiplied by -1
 - Changes sides



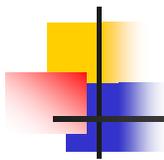


Edge Equations

- Given P_0, P_1, P_2 , what are our three edges?
- *Half-spaces defined by the edge equations must share the same sign on the interior of the triangle*
 - Consistency (Ex: $[P_0 P_1], [P_1 P_2], [P_2 P_0]$)
- *How do we make sure that sign is positive?*
 - Test & flip if needed ($A = -A, B = -B, C = -C$)



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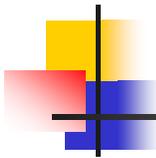


Edge Equations: Code

- Basic structure of code:
 - Setup: compute edge equations, bounding box
 - (Outer loop) For each scanline in bounding box...
 - (Inner loop) ...check each pixel on scanline:
 - evaluate edge equations
 - draw pixel if all three are positive



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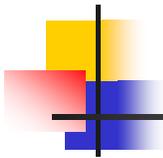
Edge Equations: Code

```
findBoundingBox(&xmin, &xmax, &ymin, &ymax);
setupEdges (&a0,&b0,&c0,&a1,&b1,&c1,&a2,&b2,&c2);

for (int y = yMin; y <= yMax; y++) {
    for (int x = xMin; x <= xMax; x++) {
        float e0 = a0*x + b0*y + c0;
        float e1 = a1*x + b1*y + c1;
        float e2 = a2*x + b2*y + c2;
        if (e0 > 0 && e1 > 0 && e2 > 0)
            Image[x][y] = TriangleColor;
    }
}
```



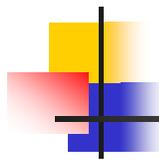
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Edge Equations: Code

```
// more efficient inner loop
for (int y = yMin; y <= yMax; y++) {
    float e0 = a0*xMin + b0*y + c0;
    float e1 = a1*xMin + b1*y + c1;
    float e2 = a2*xMin + b2*y + c2;
    for (int x = xMin; x <= xMax; x++) {
        if (e0 > 0 && e1 > 0 && e2 > 0)
            Image[x][y] = TriangleColor;
        e0 += a0;    e1+= a1;    e2 += a2;
    }
}
```



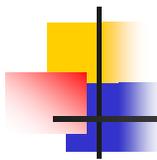


Triangle Rasterization Issues

- *Exactly which pixels should be lit?*
 - Pixels inside triangle edges
- *What about pixels exactly on the edge?*
 - Draw - BUT order of triangles matters (it shouldn't)
 - Don't draw - BUT gaps possible between triangles
- Need consistent (if arbitrary) rule
 - Example: draw pixels on left or top edge, but not on right or bottom edge

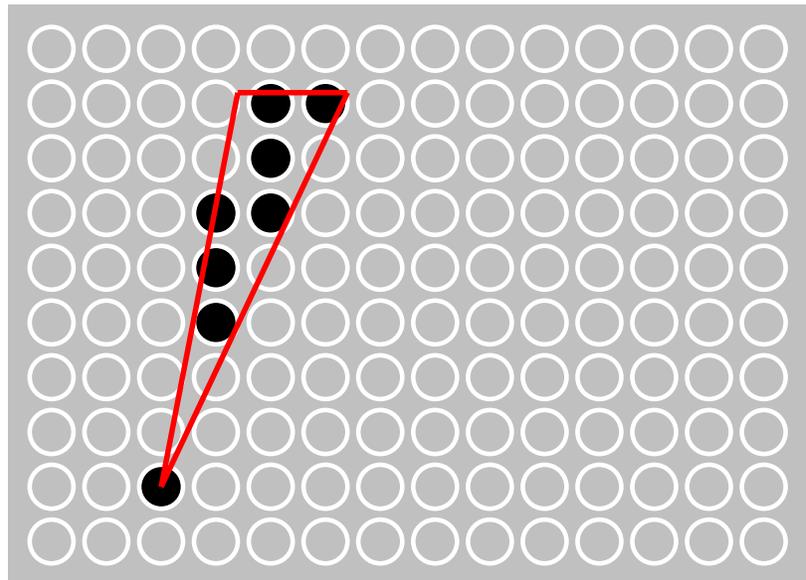


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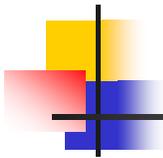


Triangle Rasterization Issues

- Sliver

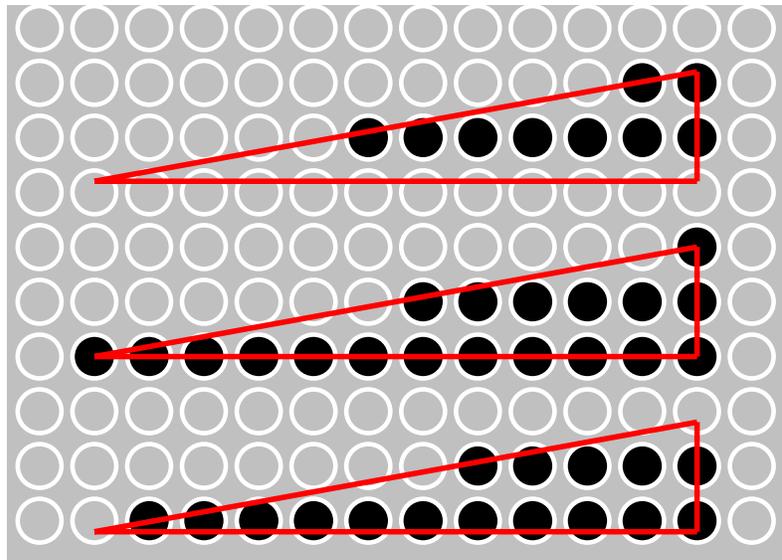


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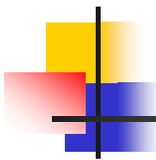


Triangle Rasterization Issues

- Moving Slivers

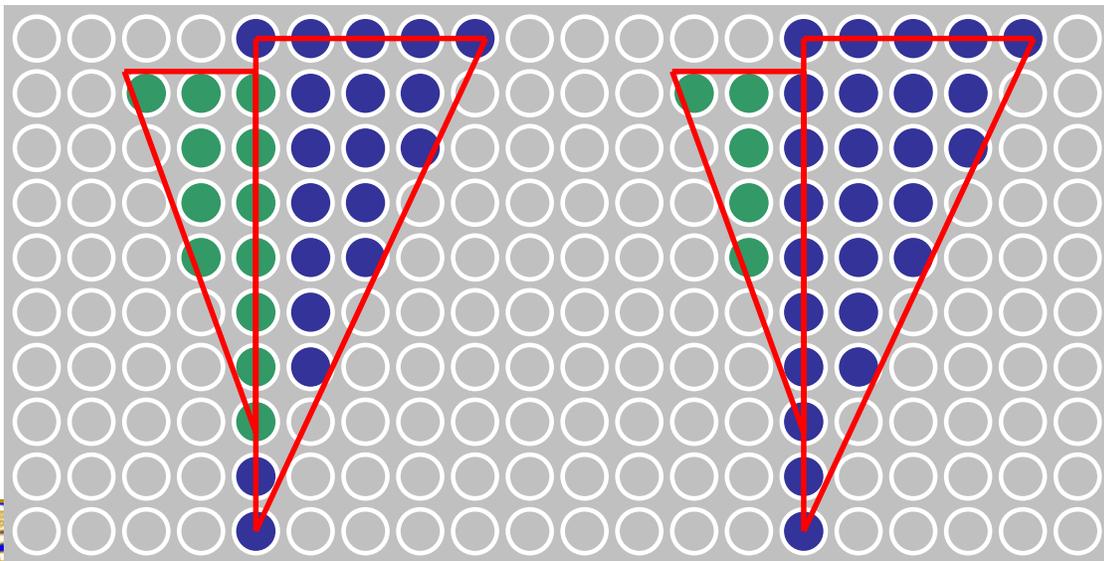


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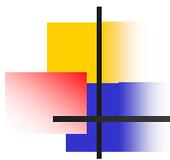


Triangle Rasterization Issues

- Shared Edge Ordering



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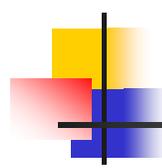


Interpolation – access triangle interior

- Interpolate between vertices:
 - z
 - r, g, b - colour components
 - u, v - texture coordinates
 - N_x, N_y, N_z - surface normals
- Equivalent
 - Bilinear interpolation
 - Barycentric coordinates



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Barycentric Coordinates

- Area

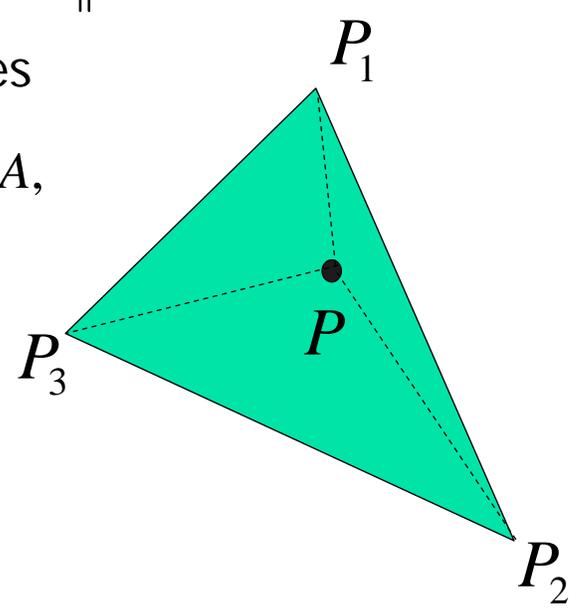
$$A = \frac{1}{2} \left\| \overrightarrow{P_1P_2} \times \overrightarrow{P_1P_3} \right\|$$

- Barycentric coordinates

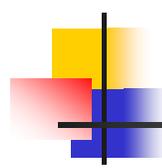
$$a_1 = A_{P_2P_3P} / A, a_2 = A_{P_3P_1P} / A,$$

$$a_3 = A_{P_1P_2P} / A,$$

$$P = a_1P_1 + a_2P_2 + a_3P_3$$



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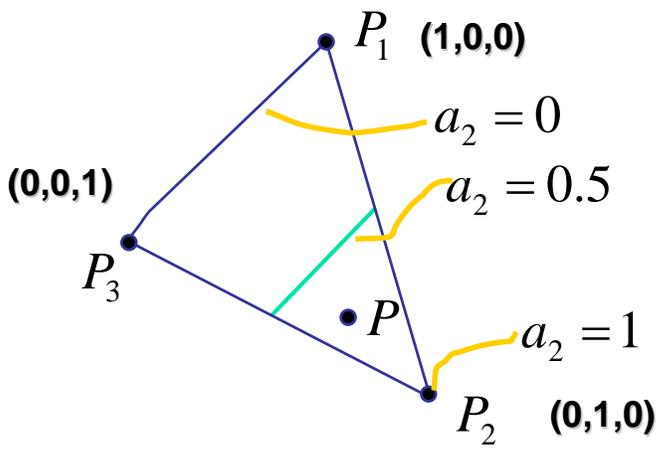
Barycentric Coordinates

- weighted combination of vertices

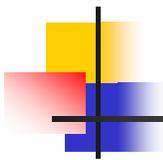
$$P = a_1 \cdot P_1 + a_2 \cdot P_2 + a_3 \cdot P_3$$

$$a_1 + a_2 + a_3 = 1$$

$$0 \leq a_1, a_2, a_3 \leq 1$$

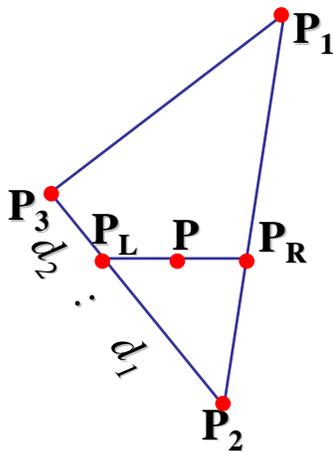


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Barycentric Coords: Alternative formula

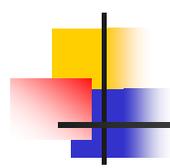
- For point P on scanline:



$$\begin{aligned}
 P_L &= P_2 + \frac{d_1}{d_1 + d_2} (P_3 - P_2) \\
 &= \left(1 - \frac{d_1}{d_1 + d_2}\right) P_2 + \frac{d_1}{d_1 + d_2} P_3 = \\
 &= \frac{d_2}{d_1 + d_2} P_2 + \frac{d_1}{d_1 + d_2} P_3
 \end{aligned}$$

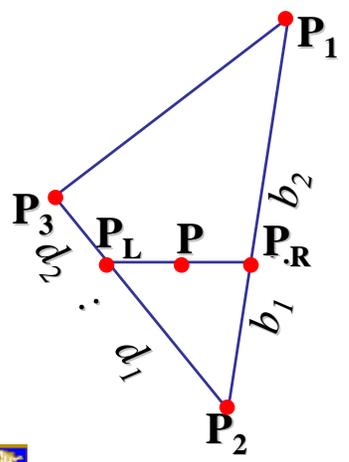


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Computing Barycentric Coords

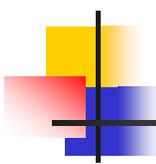
■ similarly:



$$\begin{aligned}
 P_R &= P_2 + \frac{b_1}{b_1 + b_2} (P_1 - P_2) \\
 &= \left(1 - \frac{b_1}{b_1 + b_2}\right) P_2 + \frac{b_1}{b_1 + b_2} P_1 = \\
 &= \frac{b_2}{b_1 + b_2} P_2 + \frac{b_1}{b_1 + b_2} P_1
 \end{aligned}$$



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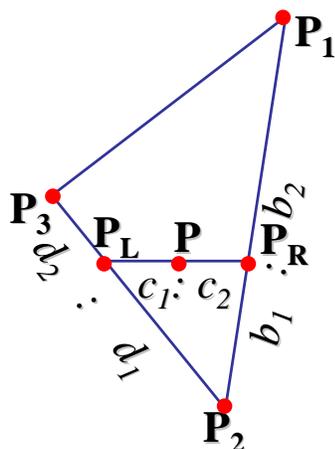
Computing Barycentric Coords

■ combining

$$P = \frac{c_2}{c_1 + c_2} \cdot P_L + \frac{c_1}{c_1 + c_2} \cdot P_R$$

$$P_L = \frac{d_2}{d_1 + d_2} P_2 + \frac{d_1}{d_1 + d_2} P_3$$

$$P_R = \frac{b_2}{b_1 + b_2} P_2 + \frac{b_1}{b_1 + b_2} P_1$$

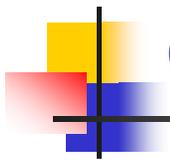


■ gives

$$P = \frac{c_2}{c_1 + c_2} \left(\frac{d_2}{d_1 + d_2} P_2 + \frac{d_1}{d_1 + d_2} P_3 \right) + \frac{c_1}{c_1 + c_2} \left(\frac{b_2}{b_1 + b_2} P_2 + \frac{b_1}{b_1 + b_2} P_1 \right)$$



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- thus

$$P = a_1 \cdot P_1 + a_2 \cdot P_2 + a_3 \cdot P_3$$

with

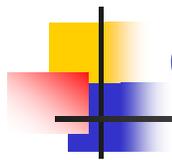
$$a_1 = \frac{c_1}{c_1 + c_2} \frac{b_1}{b_1 + b_2}$$

$$a_2 = \frac{c_2}{c_1 + c_2} \frac{d_2}{d_1 + d_2} + \frac{c_1}{c_1 + c_2} \frac{b_2}{b_1 + b_2}$$

$$a_3 = \frac{c_2}{c_1 + c_2} \frac{d_1}{d_1 + d_2}$$



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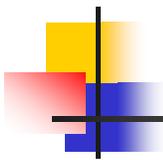
- Can verify barycentric properties

$$a_1 + a_2 + a_3 = 1$$

$$0 \leq a_1, a_2, a_3 \leq 1$$

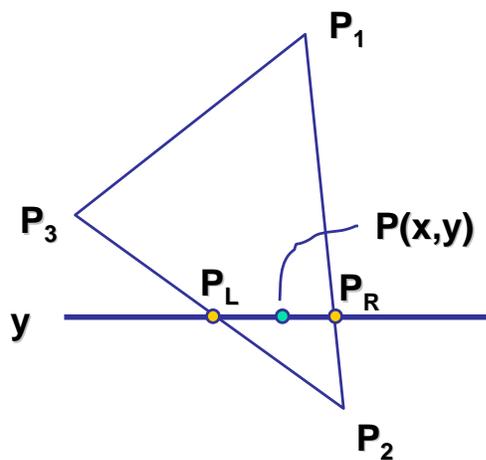


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Bilinear Interpolation

- Interpolate quantity along L and R edges, as a function of y
 - then interpolate quantity as a function of x



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