

Tamara Munzner

Viewing/Projections IV

Week 4, Fri Feb 1

<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2008>

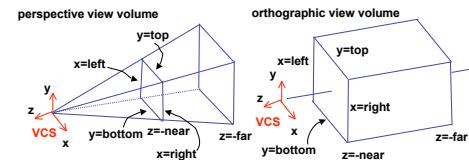
News

- extra TA office hours in lab next week to answer questions
 - Mon 1-3
 - Tue 2-4
 - Wed 1-3
- reminder
 - Wed 2/6: Homework 1 due 1pm sharp
 - Wed 2/6: Project 1 due 6pm.

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Review: View Volumes

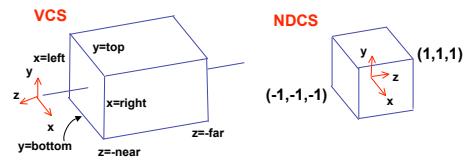
- specifies field-of-view, used for clipping
- restricts domain of z stored for visibility test



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Review: Understanding Z

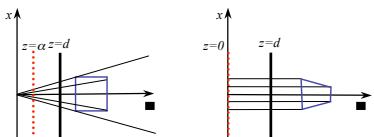
- z axis flip changes coord system handedness
 - RHS before projection (eye/view coords)
 - LHS after projection (clip, norm device coords)



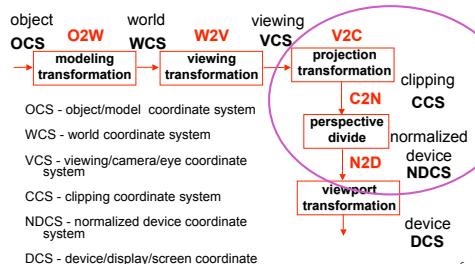
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Review: Projection Normalization

- warp perspective view volume to orthogonal view volume
 - render all scenes with orthographic projection!
 - aka perspective warp

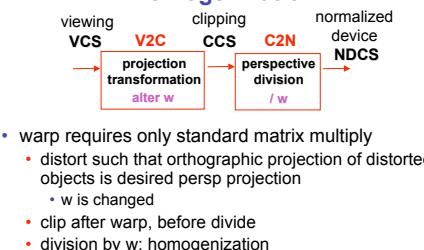


Review: Projective Rendering Pipeline



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Review: Separate Warp From Homogenization



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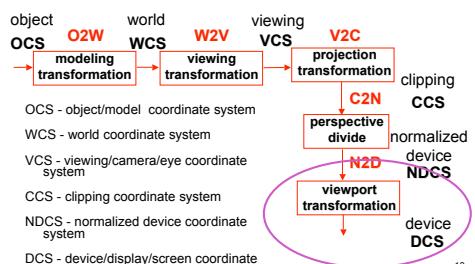
Reading for Viewing

- FCG Chapter 7 Viewing
- FCG Section 6.3.1 Windowing Transforms
- RB rest of Chap Viewing
- RB rest of App Homogeneous Coords

Reading for Next Time

- RB Chap Color
- FCG Sections 3.2-3.3
- FCG Chap 20 Color
- FCG Chap 21.2.2 Visual Perception (Color)

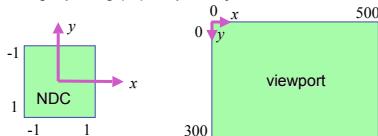
Projective Rendering Pipeline



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NDC to Device Transformation

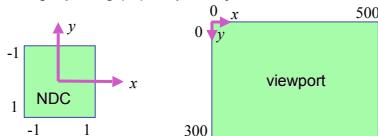
- map from NDC to pixel coordinates on display
 - NDC range is $x = -1\dots1$, $y = -1\dots1$, $z = -1\dots1$
 - typical display range: $x = 0\dots500$, $y = 0\dots300$
 - maximum is size of actual screen
 - z range max and default is $(0, 1)$, use later for visibility



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Origin Location

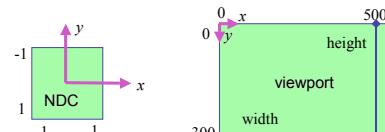
- yet more (possibly confusing) conventions
 - OpenGL origin: lower left
 - most window systems origin: upper left
- then must reflect in y
- when interpreting mouse position, have to flip your y coordinates



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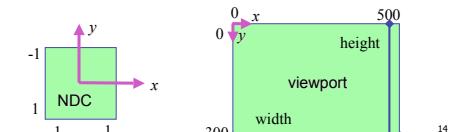
N2D Transformation

- general formulation
 - reflect in y for upper vs. lower left origin
 - scale by width, height, depth
 - translate by width/2, height/2, depth/2
 - FCG includes additional translation for pixel centers at $(.5, .5)$ instead of $(0,0)$



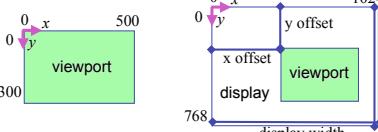
N2D Transformation

$$\begin{bmatrix} x_d \\ y_d \\ z_d \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & \frac{width}{2} - \frac{1}{2} \\ 0 & 1 & 0 & \frac{height}{2} - \frac{1}{2} \\ 0 & 0 & 1 & \frac{depth}{2} \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} \frac{width(x_d + 1) - 1}{2} \\ \frac{height(y_d + 1) - 1}{2} \\ \frac{depth(z_d + 1)}{2} \\ 1 \end{bmatrix}$$



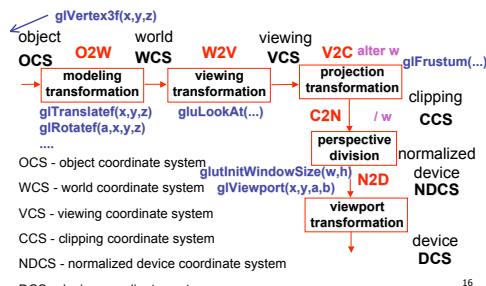
Device vs. Screen Coordinates

- viewport/window location wrt actual display not available within OpenGL
 - usually don't care
 - use relative information when handling mouse events, not absolute coordinates
 - could get actual display height/width, window offsets from OS
 - loose use of terms: device, display, window, screen...



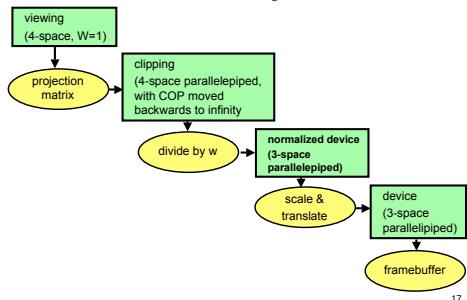
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Projective Rendering Pipeline

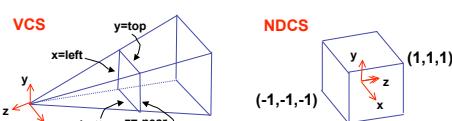


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Coordinate Systems



Perspective To NDCS Derivation



Perspective Derivation

$$\text{simple example earlier: } \begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

complete: shear, scale, projection-normalization

$$\begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} E & 0 & A & 0 \\ F & 1 & B & 0 \\ 0 & 0 & C & D \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

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Perspective Derivation

$$\text{earlier: } \begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

complete: shear, scale, projection-normalization

$$\begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} E & 0 & A & 0 \\ F & 1 & B & 0 \\ 0 & 0 & C & D \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

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Perspective Derivation

$$\text{earlier: } \begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

complete: shear, scale, projection-normalization

$$\begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} E & 0 & A & 0 \\ F & 1 & B & 0 \\ 0 & 0 & C & D \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

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Perspective Derivation

$$\begin{bmatrix} x' \\ y' \\ z' \\ w' \end{bmatrix} = \begin{bmatrix} E & 0 & A & 0 \\ 0 & F & B & 0 \\ 0 & 0 & C & D \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

$$\begin{aligned} x' &= Ex + Az & x = left \rightarrow x'/w' = 1 \\ y' &= Fy + Bz & x = right \rightarrow x'/w' = -1 \\ z' &= Cz + D & y = top \rightarrow y'/w' = 1 \\ w' &= -z & y = bottom \rightarrow y'/w' = -1 \\ && z = near \rightarrow z'/w' = 1 \\ && z = far \rightarrow z'/w' = -1 \end{aligned}$$

$$y' = Fy + Bz, \quad \frac{y'}{w'} = \frac{Fy + Bz}{w'}, \quad 1 = \frac{Fy + Bz}{w'}, \quad 1 = \frac{Fy + Bz}{-z},$$

$$1 = F \frac{y}{-z} + B \frac{z}{-z}, \quad 1 = F \frac{y}{-z} - B, \quad 1 = F \frac{top}{-(near)} - B,$$

$$1 = F \frac{top}{near} - B$$

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Perspective Derivation

- similarly for other 5 planes
- 6 planes, 6 unknowns

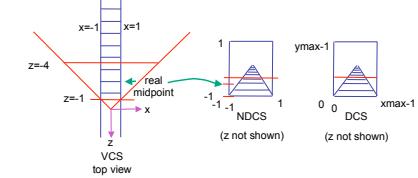
$$\begin{bmatrix} 2n \\ r-l \\ 0 \\ t-b \\ 0 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2n \\ t-b \\ -(f+n) \\ -2fn \\ 0 \end{bmatrix} \begin{bmatrix} r+l \\ r-l \\ t+b \\ -(f+n) \\ -2fn \\ -1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

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Perspective Example

tracks in VCS:
left x=-1, y=-1
right x=1, y=-1

view volume
left = -1, right = 1
bot = -1, top = 1
near = 1, far = 4



Perspective Example

view volume
• left = -1, right = 1
• bot = -1, top = 1
• near = 1, far = 4

$$\begin{bmatrix} 2n \\ r-l \\ 0 \\ 0 \\ t-b \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2n \\ t-b \\ -(f+n) \\ -2fn \\ 0 \end{bmatrix} \begin{bmatrix} r+l \\ r-l \\ t+b \\ -(f+n) \\ -2fn \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

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Perspective Example

$$\begin{bmatrix} 1 \\ -1 \\ -5z_{VCS}/3 - 8/3 \\ -z_{VCS} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & -5/3 & -8/3 \\ -1 & z_{VCS} & 1 \end{bmatrix}$$

/ w

$$x_{NDCS} = -1/z_{VCS}$$

$$y_{NDCS} = 1/z_{VCS}$$

$$z_{NDCS} = \frac{5}{3} + \frac{8}{3z_{VCS}}$$

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OpenGL Example



```

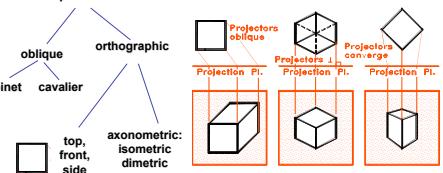
CCS: glMatrixMode( GL_PROJECTION );
glLoadIdentity();
gluPerspective( 45, 1.0, 0.1, 200.0 );
VCS: glMatrixMode( GL_MODELVIEW );
glLoadIdentity();
glTranslate( 0.0, 0.0, -5.0 );
WCS: glPushMatrix();
glTranslate( 4, 4, 0 ); W2O
OCS1: glutSolidTeapot(1);
glPopMatrix(); W2O
OCS2: glutSolidTeapot(1);

```

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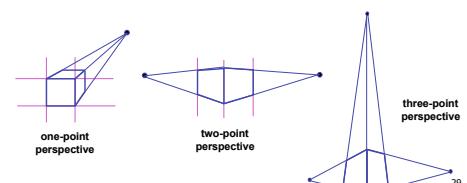
Projection Taxonomy

- perspective: projectors converge
 - orthographic, axonometric: projectors parallel and perpendicular to projection plane
 - oblique: projectors parallel, but not perpendicular to projection plane



Perspective Projections

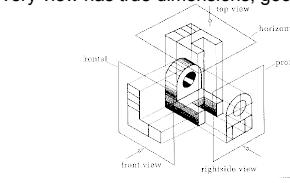
- projectors converge on image plane
- select how many vanishing points
 - one-point: projection plane parallel to two axes
 - two-point: projection plane parallel to one axis
 - three-point: projection plane not parallel to any axis



Tuebingen demo: vanishingpoints

Orthographic Projections

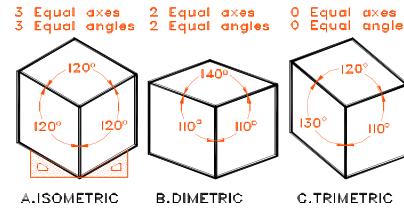
- projectors parallel, perpendicular to image plane
- image plane normal parallel to one of principal axes
- select view: top, front, side
- every view has true dimensions, good for measuring



http://www.cs.fit.edu/~wds/classes/cse5255/thesis/images/proj/orthoProj.gif

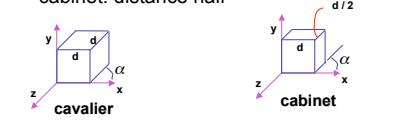
Axonometric Projections

- projectors parallel, perpendicular to image plane
- image plane normal not parallel to axes
- select axis lengths
- can see many sides at once



Oblique Projections

- projectors parallel, oblique to image plane
- select angle between front and z axis
 - lengths remain constant
- both have true front view
 - cavalier: distance true
 - cabinet: distance half



Tuebingen demo: oblique projections