

University of British Columbia **CPSC 314 Computer Graphics** Jan-Apr 2007

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Textures I

Week 9, Wed Mar 14

http://www.ugrad.cs.ubc.ca/~cs314/Vjan2007

Reading for Today and Next Time

- FCG Chap 11 Texture Mapping
- except 11.8
- RB Chap Texture Mapping
- FCG Sect 16.6 Procedural Techniques
- FCG Sect 16.7 Groups of Objects

News

- Q3 specular color should be (1,1,0)
- · P3: bug in sample implementation fixed
- · new reference images and sample binaries
- · no change to template

posted

Correction: HSV and RGB

- HSV/HSI conversion from RGB
- · not expressible in matrix

$$I = \frac{R + G + B}{3} \qquad S = 1 - \frac{\min(R, G, B)}{I}$$

$$H = \cos^{-1} \left[\frac{\frac{1}{2} [(R-G) + (R-B)]}{\sqrt{(R-G)^2 + (R-B)(G-B)}} \right]$$

Review: Z-Buffer Algorithm

- augment color framebuffer with Z-buffer or depth buffer which stores Z value at each pixel
- · at frame beginning, initialize all pixel depths to ∞
- when rasterizing, interpolate depth (Z) across polygon
- check Z-buffer before storing pixel color in framebuffer and storing depth in Z-buffer
- don't write pixel if its Z value is more distant than the Z value already stored there

Clarification/Review: Depth Test Precision

 reminder: projective transformation maps eye-space z to generic z-range (NDC)

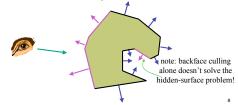
$$\begin{bmatrix} x_N \\ y_N \\ z_N \\ w_N \end{bmatrix} = \begin{bmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{-(f+n)}{f-n} & \frac{-2fn}{f-n} \\ 0 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} x_E \\ y_E \\ z_E \\ w_E \end{bmatrix}$$
• thus $z_N \sim = 1/z_E$

$$z_N = \frac{-(f+n)}{f-n} z_E + \frac{-2fn}{f-n} w_E, w_N = -z_E \qquad \frac{z_N}{w_N} = \frac{f+n}{f-n} + \frac{2fn}{f-n} \frac{w_E}{z_E}$$

Backface Culling

Back-Face Culling

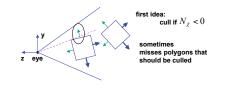
· on the surface of a "solid" object, polygons whose normals point away from the camera are always occluded:



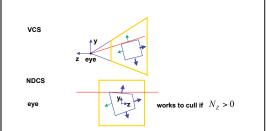
Back-Face Culling

- not rendering backfacing polygons improves performance
- by how much?
 - reduces by about half the number of polygons to be considered for each pixel
- · optimization when appropriate

Back-face Culling: VCS



Back-face Culling: NDCS



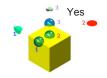
Back-Face Culling: Manifolds

- · most objects in scene are typically "solid"
- · specifically: orientable closed manifolds
- · orientable: must have two distinct sides
 - · cannot self-intersect
 - · a sphere is orientable since has two sides, 'inside' and 'outside'.
 - · a Mobius strip or a Klein bottle is
- not orientable closed: cannot "walk" from one side to the other
- · sphere is closed manifold
- · plane is not



Back-Face Culling: Manifolds

- · most objects in scene are typically "solid"
- · specifically: orientable closed manifolds
 - · manifold: local neighborhood of all points isomorphic to disc
 - · boundary partitions space into interior & exterior





Backface Culling: Manifolds

- examples of manifold objects:
 - sphere
 - torus
 - · well-formed CAD part
- examples of non-manifold objects
 - · a single polygon
 - · a terrain or height field
 - · polyhedron w/ missing face
 - · anything with cracks or holes in boundary

 - · one-polygon thick lampshade

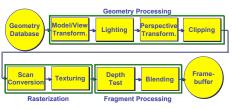


Invisible Primitives

- why might a polygon be invisible?
- polygon outside the field of view / frustum
 - solved by clipping
- · polygon is backfacing
- · solved by backface culling
- · polygon is occluded by object(s) nearer the viewpoint
 - · solved by hidden surface removal

Texturing





Texture Mapping

- real life objects have nonuniform colors, normals
- to generate realistic objects, reproduce coloring & normal variations = texture
- can often replace complex geometric details

glTexCoord2d(1, 1);

glVertex3d (x, y, z);

glTexCoord2d(4, 4);

glVertex3d (x, y, z);





8

Texture Mapping

- · introduced to increase realism
- · lighting/shading models not enough
- hide geometric simplicity
- images convey illusion of geometry
- map a brick wall texture on a flat polygon
- · create bumpy effect on surface
- · associate 2D information with 3D surface
 - point on surface corresponds to a point in texture
 - · "paint" image onto polygon

19

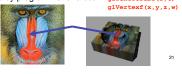
Color Texture Mapping

- define color (RGB) for each point on object surface
- two approaches
 - · surface texture map
- volumetric texture

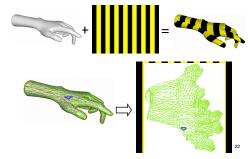


Texture Coordinates

- texture image: 2D array of color values (texels)
- assigning texture coordinates (s,t) at vertex with object coordinates (x,y,z,w)
 - use interpolated (s,t) for texel lookup at each pixel
 - use value to modify a polygon's color
 - or other surface property
 - specified by programmer or artist glTexCoord2f(s,t)
 glVertexf(x,y,z,w



Texture Mapping Example



Tiled Texture Map

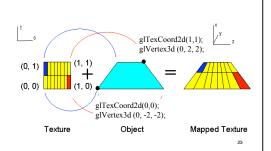
(1.0)

(0,0)

(0.1)

(0,4)

Example Texture Map



Fractional Texture Coordinates



Texture Lookup: Tiling and Clamping

- what if s or t is outside the interval [0...1]?
- multiple choices
- use fractional part of texture coordinates
 - cyclic repetition of texture to tile whole surface gITexParameteri(..., GL_TEXTURE_WRAP_S, GL_REPEAT, GL_TEXTURE_WRAP_T, GL_REPEAT,...)
- clamp every component to range [0...1]
 - re-use color values from texture image border glTexParameteri(..., GL_TEXTURE_WRAP_S, GL_CLAMP, GL_TEXTURE_WRAP_T, GL_CLAMP, ...)

25

17

Demo

- Nate Robbins tutors
 - texture

Texture Coordinate Transformation

- motivation
- change scale, orientation of texture on an object
- approach
 - texture matrix stack
 - transforms specified (or generated) tex coords glMatrixMode(GL_TEXTURE); glLoadIdentity(); glRotate();
 - · more flexible than changing (s,t) coordinates
- [demo]

10]

Texture Functions

- once have value from the texture map, can:
 directly use as surface color: GL REPLACE
 - · throw away old color, lose lighting effects
 - modulate surface color: GL MODULATE
 - · multiply old color by new value, keep lighting info
 - texturing happens after lighting, not relit
 - use as surface color, modulate alpha: GL_DECAL
 like replace, but supports texture transparency
 - blend surface color with another: GL BLEND
 - new value controls which of 2 colors to use
 indirection, new value not used directly for coloring
- specify with gltexEnvi(GL_TEXTURE_ENV, GL_TEXTURE_ENV_MODE, <mode>)
- [demo]

Texture Pipeline

(x, y, z)Object position $(\cdot 2.3, 7.1, 17.7)$ (s, t) (s, t)

Texture Objects and Binding

- · texture object
 - an OpenGL data type that keeps textures resident in memory and provides identifiers to easily access them
 - provides efficiency gains over having to repeatedly load and reload a texture
 - · you can prioritize textures to keep in memory
 - OpenGL uses least recently used (LRU) if no priority is assigned
- texture binding
- which texture to use right now
- · switch between preloaded textures

Basic OpenGL Texturing

- create a texture object and fill it with texture data:
- glGenTextures (num, &indices) to get identifiers for the objects
- glBindTexture(GL_TEXTURE_2D, identifier) to bind
- following texture commands refer to the bound texture
 glTexParameteri (GL TEXTURE 2D, ..., ...) to specify
- parameters for use when applying the texture
- glTexImage2D(GL_TEXTURE_2D,) to specify the texture data (the image itself)
- enable texturing: glEnable (GL_TEXTURE_2D)
- state how the texture will be used:
- glTexEnvf(...)
- specify texture coordinates for the polygon:
- use glTexCoord2f(s,t) before each vertex:
- glTexCoord2f(0,0); glVertex3f(x,y,z);

30

Low-Level Details

- · large range of functions for controlling layout of texture data
- · state how the data in your image is arranged
- e.g.: glPixelStorei(GL UNPACK ALIGNMENT, 1) tells OpenGL not to skip bytes at the end of a row
- you must state how you want the texture to be put in memory: how many bits per "pixel", which channels,...
- textures must be square and size a power of 2
- common sizes are 32x32, 64x64, 256x256
- smaller uses less memory, and there is a finite amount of texture memory on graphics cards
- ok to use texture template sample code for project 4
- http://nehe.gamedev.net/data/lessons/lesson.asp?lesson=09

Texture Mapping

- · texture coordinates
 - · specified at vertices glTexCoord2f(s,t);

glVertexf(x,y,z);

- interpolated across triangle (like R,G,B,Z)
 - · ...well not quite!

Texture Mapping

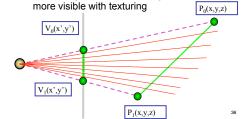
- · texture coordinate interpolation
- · perspective foreshortening problem





Interpolation: Screen vs. World Space

- screen space interpolation incorrect
 - · problem ignored with shading, but artifacts



MIPmapping

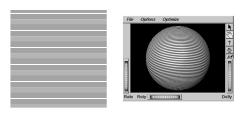
Texture Coordinate Interpolation

- · perspective correct interpolation
 - α, β, γ:
 - · barycentric coordinates of a point P in a triangle
 - s0, s1, s2:
 - · texture coordinates of vertices
 - w0, w1,w2:
- · homogeneous coordinates of vertices



 $\alpha \cdot s_0 / w_0 + \beta \cdot s_1 / w_1 + \gamma \cdot s_2 / w_2$ $\alpha/w_0 + \beta/w_1 + \gamma/w_2$

Reconstruction



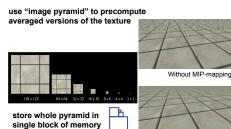
(image courtesy of Kiriakos Kutulakos, U Rochester)

Reconstruction

- how to deal with:
 - pixels that are much larger than texels?
 - · apply filtering, "averaging"

· pixels that are much smaller than texels?

interpolate

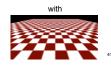


With MIP-mappin

MIPmaps

- · multum in parvo -- many things in a small place
 - prespecify a series of prefiltered texture maps of decreasing resolutions
- · requires more texture storage
- · avoid shimmering and flashing as objects move
- gluBuild2DMipmaps
- automatically constructs a family of textures from original texture size down to 1x1





MIPmap storage

· only 1/3 more space required



Texture Parameters

- · in addition to color can control other material/object properties
- surface normal (bump mapping)
- · reflected color (environment mapping)

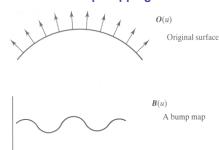


Bump Mapping: Normals As Texture

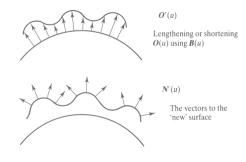
- object surface often not smooth to recreate correctly need complex geometry model
- can control shape "effect" by locally perturbing surface
- random perturbation
- · directional change over region



Bump Mapping

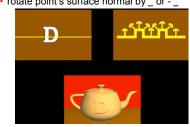


Bump Mapping



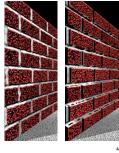
Embossing

- at transitions
 - · rotate point's surface normal by _ or _



Displacement Mapping

- bump mapping gets silhouettes wrong
- · shadows wrong too
- change surface geometry instead
 - · only recently available with realtime graphics
 - · need to subdivide surface



Environment Mapping

- · cheap way to achieve reflective effect
 - · generate image of surrounding
- · map to object as texture



Environment Mapping

- · used to model object that reflects surrounding textures to the eye
- movie example: cyborg in Terminator 2
- different approaches
- · sphere, cube most popular
 - OpenGL support GL_SPHERE_MAP, GL_CUBE_MAP
- · others possible too

Sphere Mapping

- · texture is distorted fish-eye view
- point camera at mirrored sphere
- · spherical texture mapping creates texture coordinates that correctly index into this texture map





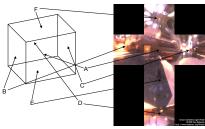
Cube Mapping

- · 6 planar textures, sides of cube
 - · point camera in 6 different directions, facing out from origin





Cube Mapping



Volumetric Bump Mapping

Marble

Bump

53

Cube Mapping

- direction of reflection vector r selects the face of the cube to be indexed
- · co-ordinate with largest magnitude
 - e.g., the vector (-0.2, 0.5, -0.84) selects the -Z face
- remaining two coordinates (normalized by the 3rd coordinate) selects the pixel from the face.
 - e.g., (-0.2, 0.5) gets mapped to (0.38, 0.80).
- difficulty in interpolating across faces

54

Review: Texture Objects and Binding

- texture objects
- · texture management: switch with bind, not reloading
- · can prioritize textures to keep in memory
- Q: what happens to textures kicked out of memory?
 - · A: resident memory (on graphics card) vs. nonresident (on CPU)
 - · details hidden from developers by OpenGL

Volumetric Texture

- · define texture pattern over 3D domain - 3D space containing the object
- · texture function can be digitized or procedural
- for each point on object compute texture from point location in space
- · common for natural material/irregular textures (stone, wood,etc...)



Volumetric Texture Principles

• 3D function ρ

 $\forall \rho = \rho(x, y, z)$

- texture space 3D space that holds the texture (discrete or continuous)
- rendering: for each rendered point P(x,y,z) compute $\rho(x,y,z)$
- · volumetric texture mapping function/space transformed with objects