



Tamara Munzner

## Clipping

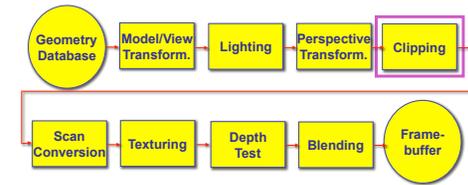
<http://www.ugrad.cs.ubc.ca/~cs314/Vjan2013>

## Reading for Clipping

- FCG Sec 8.1.3-8.1.6 Clipping
- FCG Sec 8.4 Culling
  - (12.1-12.4 2nd ed)

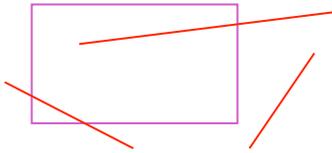
## Clipping

## Rendering Pipeline



## Next Topic: Clipping

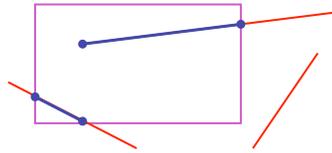
- we've been assuming that all primitives (lines, triangles, polygons) lie entirely within the *viewport*
  - in general, this assumption will not hold:



5

## Clipping

- analytically calculating the portions of primitives within the viewport



6

## Why Clip?

- bad idea to rasterize outside of framebuffer bounds
- also, don't waste time scan converting pixels outside window
  - could be billions of pixels for very close objects!

7

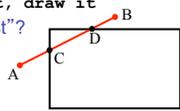
## Line Clipping

- 2D
  - determine portion of line inside an axis-aligned rectangle (screen or window)
- 3D
  - determine portion of line inside axis-aligned parallelepiped (viewing frustum in NDC)
  - simple extension to 2D algorithms

8

## Clipping

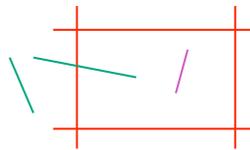
- naïve approach to clipping lines:
  - for each line segment
  - for each edge of viewport
  - find intersection point
  - pick "nearest" point
  - if anything is left, draw it
- what do we mean by "nearest"?
- how can we optimize this?



9

## Trivial Accepts

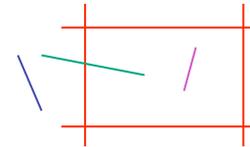
- big optimization: trivial accept/rejects
  - Q: how can we quickly determine whether a line segment is entirely inside the viewport?
  - A: test both endpoints



10

## Trivial Rejects

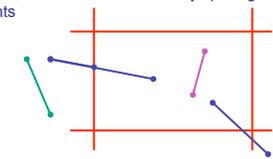
- Q: how can we know a line is outside viewport?
- A: if both endpoints on wrong side of **same** edge, can trivially reject line



11

## Clipping Lines To Viewport

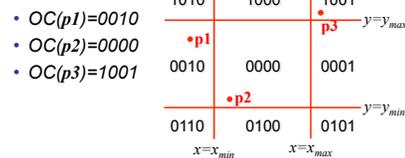
- combining trivial accepts/rejects
  - trivially **accept** lines with both endpoints **inside all edges of the viewport**
  - trivially **reject** lines with both endpoints **outside the same edge of the viewport**
  - otherwise, reduce to trivial cases by **splitting into two segments**



12

## Cohen-Sutherland Line Clipping

- outcodes
- 4 flags encoding position of a point relative to top, bottom, left, and right boundary



13

## Cohen-Sutherland Line Clipping

- assign outcode to each vertex of line to test
  - line segment: (p1,p2)
- trivial cases
  - $OC(p1) == 0 \ \&\& \ OC(p2) == 0$ 
    - both points inside window, thus line segment completely visible (trivial accept)
  - $(OC(p1) \ \& \ OC(p2)) \neq 0$ 
    - there is (at least) one boundary for which both points are outside (same flag set in both outcodes)
    - thus line segment completely outside window (trivial reject)

14

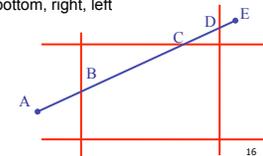
## Cohen-Sutherland Line Clipping

- if line cannot be trivially accepted or rejected, subdivide so that one or both segments can be discarded
- pick an edge that the line crosses (*how?*)
- intersect line with edge (*how?*)
- discard portion on wrong side of edge and assign outcode to new vertex
- apply trivial accept/reject tests; repeat if necessary

15

## Cohen-Sutherland Line Clipping

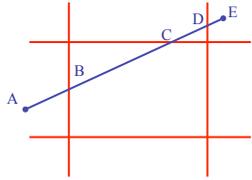
- if line cannot be trivially accepted or rejected, subdivide so that one or both segments can be discarded
- pick an edge that the line crosses
  - check against edges in same order each time
    - for example: top, bottom, right, left



16

## Cohen-Sutherland Line Clipping

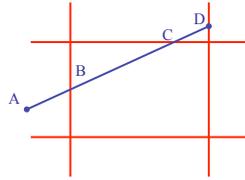
- intersect line with edge



17

## Cohen-Sutherland Line Clipping

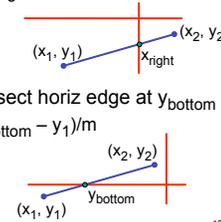
- discard portion on wrong side of edge and assign outcode to new vertex
- apply trivial accept/reject tests and repeat if necessary



18

## Viewport Intersection Code

- $(x_1, y_1), (x_2, y_2)$  intersect vertical edge at  $x_{right}$ 
  - $y_{intersect} = y_1 + m(x_{right} - x_1)$
  - $m = (y_2 - y_1) / (x_2 - x_1)$
- $(x_1, y_1), (x_2, y_2)$  intersect horiz edge at  $y_{bottom}$ 
  - $x_{intersect} = x_1 + (y_{bottom} - y_1) / m$
  - $m = (y_2 - y_1) / (x_2 - x_1)$



19

## Cohen-Sutherland Discussion

- key concepts
  - use opcodes to quickly eliminate/include lines
    - best algorithm when trivial accepts/rejects are common
  - must compute viewport clipping of remaining lines
    - non-trivial clipping cost
    - redundant clipping of some lines
- basic idea, more efficient algorithms exist

20

## Line Clipping in 3D

- approach
  - clip against parallelepiped in NDC
    - after perspective transform
  - means that clipping volume always the same
    - $x_{min}=y_{min}=-1, x_{max}=y_{max}=1$  in OpenGL
- boundary lines become boundary planes
  - but outcodes still work the same way
  - additional front and back clipping plane
    - $z_{min} = -1, z_{max} = 1$  in OpenGL

21

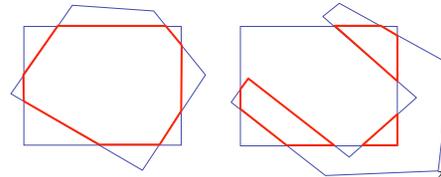
## Polygon Clipping

- objective
  - 2D: clip polygon against rectangular window
    - or general convex polygons
    - extensions for non-convex or general polygons
  - 3D: clip polygon against parallelepiped

22

## Polygon Clipping

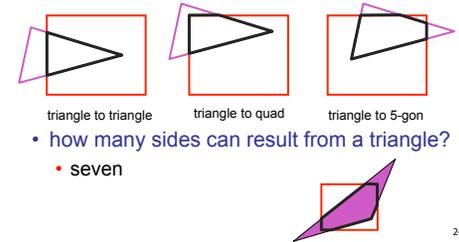
- not just clipping all boundary lines
- may have to introduce new line segments



23

## Why Is Clipping Hard?

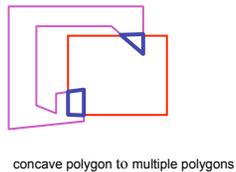
- what happens to a triangle during clipping?
  - some possible outcomes:
    - triangle to triangle
    - triangle to quad
    - triangle to 5-gon
- how many sides can result from a triangle?
  - seven



24

## Why Is Clipping Hard?

- a really tough case:



concave polygon to multiple polygons

25

## Polygon Clipping

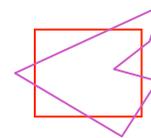
- classes of polygons
  - triangles
  - convex
  - concave
  - holes and self-intersection



26

## Sutherland-Hodgeman Clipping

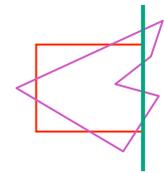
- basic idea:
  - consider each edge of the viewport individually
  - clip the polygon against the edge equation
  - after doing all edges, the polygon is fully clipped



27

## Sutherland-Hodgeman Clipping

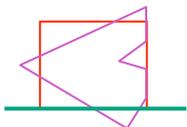
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28

## Sutherland-Hodgeman Clipping

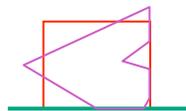
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29

## Sutherland-Hodgeman Clipping

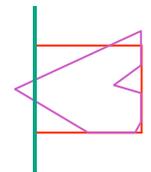
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30

## Sutherland-Hodgeman Clipping

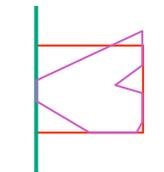
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31

## Sutherland-Hodgeman Clipping

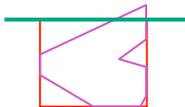
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32

## Sutherland-Hodgeman Clipping

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33

## Sutherland-Hodgeman Clipping

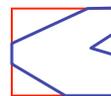
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34

## Sutherland-Hodgeman Clipping

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35

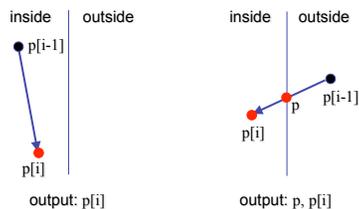
## Sutherland-Hodgeman Algorithm

- input/output for whole algorithm
  - input: list of polygon vertices in order
  - output: list of clipped polygon vertices consisting of old vertices (maybe) and new vertices (maybe)
- input/output for each step
  - input: list of vertices
  - output: list of vertices, possibly with changes
- basic routine
  - go around polygon one vertex at a time
  - decide what to do based on 4 possibilities
    - is vertex inside or outside?
    - is previous vertex inside or outside?

36

## Clipping Against One Edge

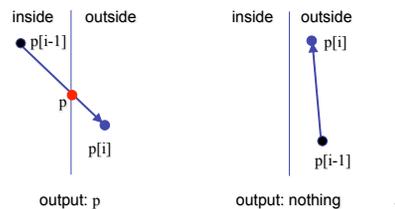
- $p[i]$  inside: 2 cases



37

## Clipping Against One Edge

- $p[i]$  outside: 2 cases



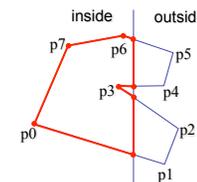
38

## Clipping Against One Edge

```
clipPolygonToEdge( p[n], edge ) {
  for( i= 0 ; i < n ; i++ ) {
    if( p[i] inside edge ) {
      if( p[i-1] inside edge ) output p[i]; // p[-1]= p[n-1]
      else {
        p= intersect( p[i-1], p[i], edge ); output p, p[i];
      }
    } else { // p[i] is outside edge
      if( p[i-1] inside edge ) {
        p= intersect( p[i-1], p[i], edge ); output p;
      }
    }
  }
}
```

39

## Sutherland-Hodgeman Example



40

## Sutherland-Hodgeman Discussion

- similar to Cohen/Sutherland line clipping
  - inside/outside tests: outcodes
  - intersection of line segment with edge: window-edge coordinates
- clipping against individual edges independent
  - great for hardware (pipelining)
  - all vertices required in memory at same time
    - not so good, but unavoidable
    - another reason for using triangles only in hardware rendering

41