

# CPSC 213

## Introduction to Computer Systems

*Unit 2e*

***The Operating System***

# Readings for Next Two Lectures

## ▶ Text

- Exceptional Control Flow: Processes, System Call Error Handling
- VM as a Tool for Memory Protection
- 2nd edition: 8.2, 8.3, 9.5
- 1st edition: 8.2, 8.3, 10.5

# Implementing the System Abstractions

- ▶ **We've got some cool abstractions**
  - virtual processors (threads)
  - virtual memory
  - processes
  - authenticated users
  - file systems
  - inter-process and network communication
- ▶ **What properties do we want from their implementation**
  - encapsulation of implementation by an interface
  - failure and security isolation
  - programming-language heterogeneity
- ▶ **We've got a problem ...**

# Hardware Enforced Encapsulation

## ▶ Goal

- define a set of interfaces (APIs) whose implementations are protected
- implementation code and data can only be accessed through interface

## ▶ Obstacle

- can not use language protection without excluding languages like C

## ▶ Use Hardware for Protection

- virtual memory already provides a way to protect memory
- data in one address space can not even be named by thread in another
- so, we've got the protected implementation part
- we'll need to add the interface part

# The Operating System

## ▶ The operating system is

- a C/assembly program
- implements a set of abstractions for applications
- it encapsulates the implementation of these abstractions, including hardware



## ▶ The Operating System's Address Space

- a part of every application's page table is reserved for the OS
- all code and data of OS is part of every page table (exact copies)
- and so the operating system is part of every application's address space

## ▶ Dual Protection Domains

- each address space splits into application and system ***protection domain***
- CPU can run in one of two modes: user and kernel
- when in user mode, the OS part of virtual memory is inaccessible
- when in kernel mode, all of virtual memory is accessible

# Implementing Hardware Encapsulation

## ▶ Hardware

- mode register (user or kernel) `boolean isKernelMode;`
- certain instructions only legal in kernel mode
- page table entries have protection flag (user or kernel)
- attempting to access a kernel page while in user mode causes fault
- special instructions for switching between user and kernel modes

## ▶ Translation

```
int translate (int va) {  
    int vpn    = va >>> 12;  
    int offset = va & 0xfff;  
    if (pte[vpn].isValid && (isKernelMode || !pte[vpn].isKernel))  
        return pte[vpn].pfn << 12 | offset;  
    else  
        throw new IllegalArgumentException (va);  
}
```

```
class PageTableEntry {  
    boolean isValid;  
    boolean isKernel;  
    int    pfn;  
}
```

# Protected Procedure Call

- ▶ Switching from User Mode to Kernel Mode must be protected
  - OS has a fixed set of “entry points”, its public API
  - an application can call any of these entry points, but no others
  - when in kernel mode the application can access anything
  - so, application can only switch to kernel mode after calling entry point
  - but, even entry points are in inaccessible memory
- ▶ Implementing Protected Calls
  - OS boot sets up entry-point jump table in kernel memory
  - jump table is indexed by system call number and stores procedure address
  - system call instruction changes mode and jumps through jump table
  - in IA32 this instruction is called “int 80” (i.e., interrupt number 0x80)
  - this works like an IO-Controller interrupt, it transfers control to interrupt-handler
  - but this also switches the processor into kernel mode (all interrupts do this)

```
movl $1, %eax    # system call number (exit)
int  $0x80       # interrupt 80 is a system call
```

## ▶ Implementing Protected Call Instruction

Two special hardware registers

```
boolean isKernelMode  
void (**systemCallTable)();
```

Initialized at OS boot time

```
isKernelMode = true;  
*systemCallTable = malloc (sizeof (void*) * MAX_SYS_CALL_NUM);  
systemCallTable[0] = syscall;  
systemCallTable[1] = exit;  
systemCallTable[2] = fork;  
systemCallTable[3] = read;  
...
```

Protected call instruction, assuming syscall number is in r0

```
sysCallNum = r[0];  
if (sysCallNum >= 0 && sysCallNum <= MAX_SYSCALL_NUM) {  
    isKernelMode = true;  
    pc = systemCallTable [sysCallNum];  
} else  
    throw new IllegalSystemCall ();
```

IO-Controller interrupts revisited ...

# Setting Up Other Protection Domains

- ▶ Any application can be a protection domain
  - we often call them “servers” or “daemons”
- ▶ Encapsulation
  - the application’s address space is private
- ▶ Public interface
  - implemented manually in application using message-passing
  - OS provides Inter-process Communication (IPC) interface (send/receive)
  - server sets up “communication endpoint” and waits to receive messages
  - callers send messages to request the server to perform a protected function
  - send/receive are system calls
- ▶ Calling a server
  - server calls receive, traps to the OS and blocks there
  - caller calls send, traps to OS
  - OS context switches to server, and unblocks server

# Summary

## ▶ Single System Image

- hardware implements a set of instructions needed by compilers
- compilers translate programs into these instructions
- translation assumes private memory and processor

## ▶ Threads

- an abstraction implemented by software to manage asynchrony and concurrency
- provides the illusion of single processor to applications
- differs from processor in that it can be stopped and restarted

## ▶ Virtual Memory

- an abstraction implemented by software and hardware
- provides the illusion of a single, private memory to application
- not all data need be in memory, paged in on demand

## ▶ Hardware Enforced Encapsulation

- kernel mode register and VM mapping restriction
- allows OS to export a public interface and to encapsulate (hide) the implementation