

# CPSC 213

## Introduction to Computer Systems

*Unit 2e*

### *The Operating System*

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## Readings for Next Two Lectures

### ▶ Text

- Exceptional Control Flow: Processes, System Call Error Handling
- VM as a Tool for Memory Protection
- 2nd edition: 8.2, 8.3, 9.5
- 1st edition: 8.2, 8.3, 10.5

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## Implementing the System Abstractions

### ▶ We've got some cool abstractions

- virtual processors (threads)
- virtual memory
- processes
- authenticated users
- file systems
- inter-process and network communication

### ▶ What properties do we want from their implementation

- encapsulation of implementation by an interface
- failure and security isolation
- programming-language heterogeneity

### ▶ We've got a problem ...

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## Hardware Enforced Encapsulation

### ▶ Goal

- define a set of interfaces (APIs) whose implementations are protected
- implementation code and data can only be accessed through interface

### ▶ Obstacle

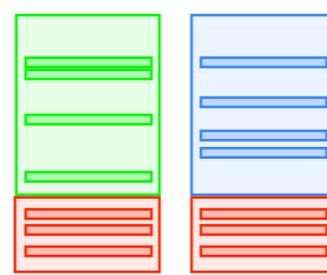
- can not use language protection without excluding languages like C

### ▶ Use Hardware for Protection

- virtual memory already provides a way to protect memory
- data in one address space can not even be named by thread in another
- so, we've got the protected implementation part
- we'll need to add the interface part

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# The Operating System



- ▶ The operating system is
  - a C/assembly program
  - implements a set of abstractions for applications
  - it encapsulates the implementation of these abstractions, including hardware
- ▶ The Operating System's Address Space
  - a part of every application's page table is reserved for the OS
  - all code and data of OS is part of every page table (exact copies)
  - and so the operating system is part of every application's address space
- ▶ Dual Protection Domains
  - each address space splits into application and system **protection domain**
  - CPU can run in one of two modes: user and kernel
  - when in user mode, the OS part of virtual memory is inaccessible
  - when in kernel mode, all of virtual memory is accessible

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# Implementing Hardware Encapsulation

- ▶ Hardware
  - mode register (user or kernel) `boolean isKernelMode;`
  - certain instructions only legal in kernel mode
  - page table entries have protection flag (user or kernel)
  - attempting to access a kernel page while in user mode causes fault
  - special instructions for switching between user and kernel modes

## ▶ Translation

```
int translate (int va) {
    int vpn    = va >>> 12;
    int offset = va & 0xfff;
    if (pte[vpn].isValid && (isKernelMode || !pte[vpn].isKernel))
        return pte[vpn].pfn << 12 | offset;
    else
        throw new IllegalAddressException (va);
}
```

```
class PageTableEntry {
    boolean isValid;
    boolean isKernel;
    int    pfn;
}
```

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# Protected Procedure Call

- ▶ Switching from User Mode to Kernel Mode must be protected
  - OS has a fixed set of "entry points", its public API
  - an application can call any of these entry points, but no others
  - when in kernel mode the application can access anything
  - so, application can only switch to kernel mode after calling entry point
  - but, even entry points are in inaccessible memory
- ▶ Implementing Protected Calls
  - OS boot sets up entry-point jump table in kernel memory
  - jump table is indexed by system call number and stores procedure address
  - system call instruction changes mode and jumps through jump table
  - in IA32 this instruction is called "int 80" (i.e., interrupt number 0x80)
  - this works like an IO-Controller interrupt, it transfers control to interrupt-handler
  - but this also switches the processor into kernel mode (all interrupts do this)

```
movl $1, %eax # system call number (exit)
int  $0x80   # interrupt 80 is a system call
```

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## ▶ Implementing Protected Call Instruction

Two special hardware registers

```
boolean isKernelMode
void    (**systemCallTable());
```

Initialized at OS boot time

```
isKernelMode = true;
*systemCallTable = malloc (sizeof (void*) * MAX_SYS_CALL_NUM);
systemCallTable[0] = syscall;
systemCallTable[1] = exit;
systemCallTable[2] = fork;
systemCallTable[3] = read;
...
```

Protected call instruction, assuming syscall number is in r0

```
syscallNum = r[0];
if (syscallNum >= 0 && syscallNum <= MAX_SYSCALL_NUM) {
    isKernelMode = true;
    pc           = systemCallTable [syscallNum];
} else
    throw new IllegalSystemCall ();
```

IO-Controller interrupts revisited ...

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# Setting Up Other Protection Domains

- ▶ Any application can be a protection domain
  - we often call them “servers” or “daemons”
- ▶ Encapsulation
  - the application’s address space is private
- ▶ Public interface
  - implemented manually in application using message-passing
  - OS provides Inter-process Communication (IPC) interface (send/receive)
  - server sets up “communication endpoint” and waits to receive messages
  - callers send messages to request the server to perform a protected function
  - send/receive are system calls
- ▶ Calling a server
  - server calls receive, traps to the OS and blocks there
  - caller calls send, traps to OS
  - OS context switches to server, and unblocks server

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# Summary

- ▶ Single System Image
  - hardware implements a set of instructions needed by compilers
  - compilers translate programs into these instructions
  - translation assumes private memory and processor
- ▶ Threads
  - an abstraction implemented by software to manage asynchrony and concurrency
  - provides the illusion of single processor to applications
  - differs from processor in that it can be stopped and restarted
- ▶ Virtual Memory
  - an abstraction implemented by software and hardware
  - provides the illusion of a single, private memory to application
  - not all data need be in memory, paged in on demand
- ▶ Hardware Enforced Encapsulation
  - kernel mode register and VM mapping restriction
  - allows OS to export a public interface and to encapsulate (hide) the implementation

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