

# Graphical Models

Clique trees & Belief Propagation

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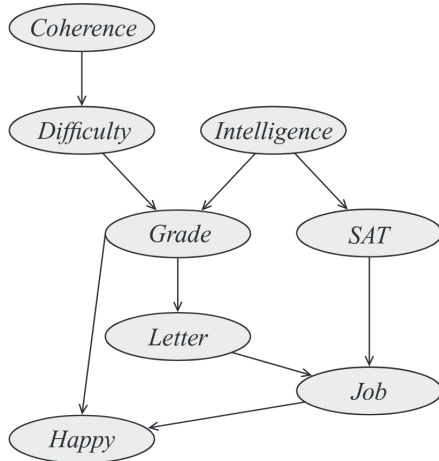
# Learning objectives

- message passing on clique trees
- its relation to variable elimination
- two different forms of belief propagation

# Recap: variable elimination (VE)

- marginalize over a subset - e.g.,  $P(J)$
- expensive to calculate (why?)  $\sum_{C,D,I,G,S,L,H} P(C, D, I, G, S, L, J, H)$
- use the **factorized form** of P

$$\sum_{C,D,I,G,S,L} P(D|C)P(G|D,I)P(S|I)P(L|G)P(J|L,S)P(H|G,J)$$

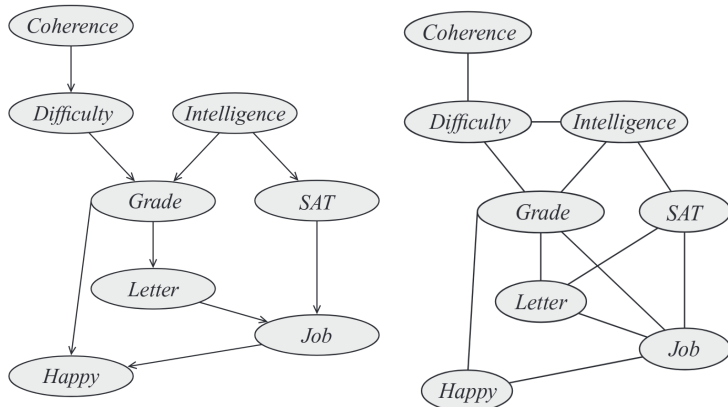


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$$\downarrow$$
$$\phi_2(H, G, J)$$



note that they do not encode the same CIs

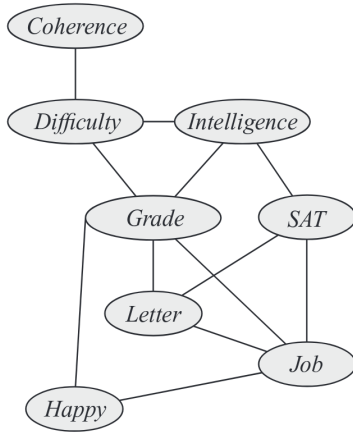
think of this as a factor/potential  
**same treatment of**

- Bayes-nets
  - Markov nets
- for inference**

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- use the **factorized form** of P

$$\sum_{C,D,I,G,S,L} \phi_1(D, C)\phi_2(G, D, I)\phi_3(S, I)\phi_4(L, G)\phi_5(J, L, S)\phi_6(H, G, J)$$



$$= \dots \sum_I \phi_3(S|I) \sum_D \phi_2(G, D, I) \sum_C \phi_1(D, C)$$

- repeat this

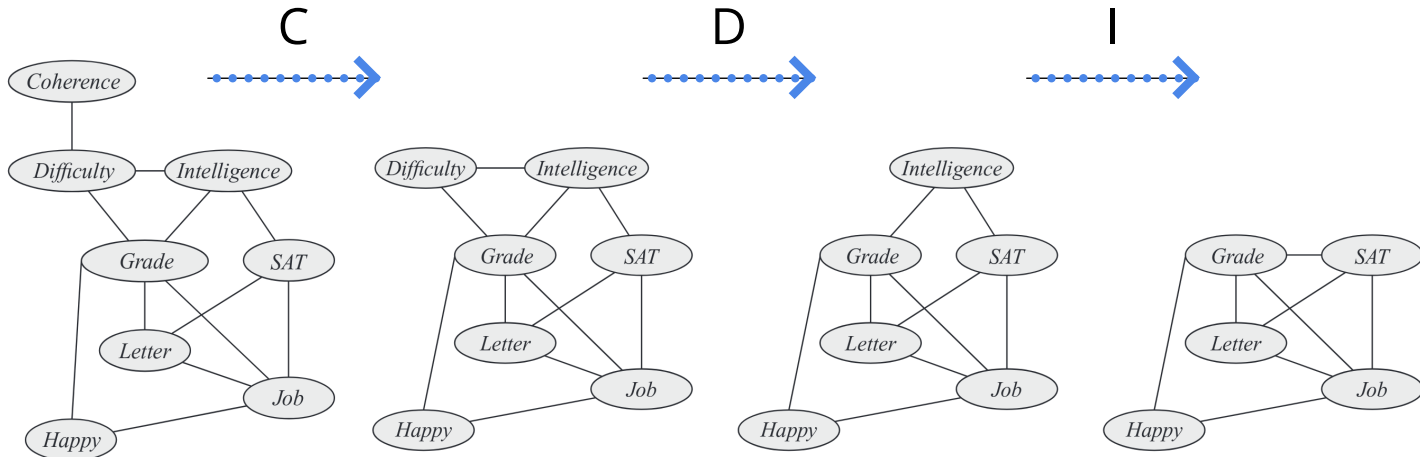
$$\begin{array}{c} \psi'_1(D) \quad \psi_1(D, C) \\ \downarrow \quad \downarrow \end{array}$$

$$= \dots \sum_I \phi_3(S, I) \sum_D \phi_2(G, D, I) \psi'_1(D)$$

$$\begin{array}{c} \psi'_2(G, I) \quad \psi_2(G, I, D) \\ \downarrow \quad \downarrow \end{array}$$

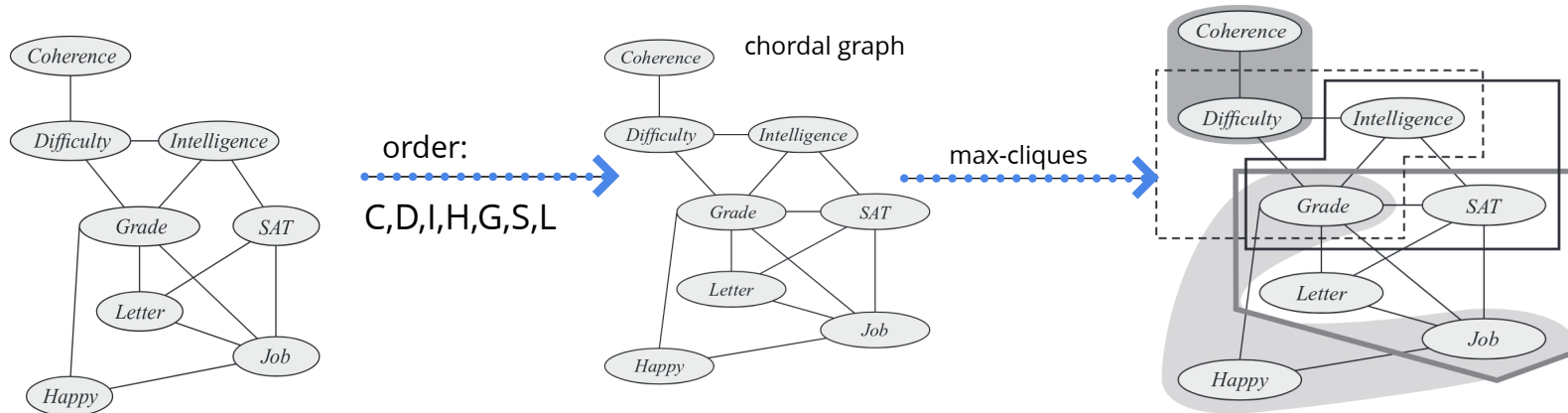
# Recap: variable elimination (VE)

- marginalize over a subset - e.g.,  $P(J)$
- expensive to calculate (why?)  $\sum_{C,D,I,G,S,L,H} P(C, D, I, G, S, L, J, H)$
- **eliminate variables** in some order



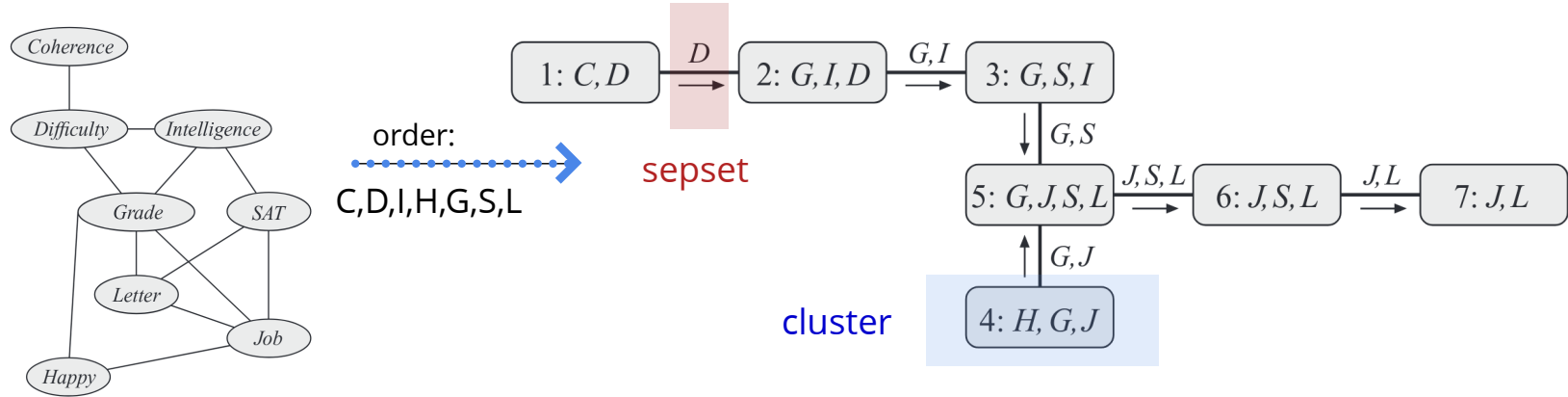
# Recap: variable elimination (VE)

- eliminate variables in some order
- creates a **chordal graph**
- **maximal cliques** are the factors created during VE ( $\psi_t$ )



# Clique-tree

- summarize the *VE* computation using a **clique-tree**



- clusters** are maximal cliques (factors that are marginalized)

$$C_i = \text{Scope}[\psi_i]$$

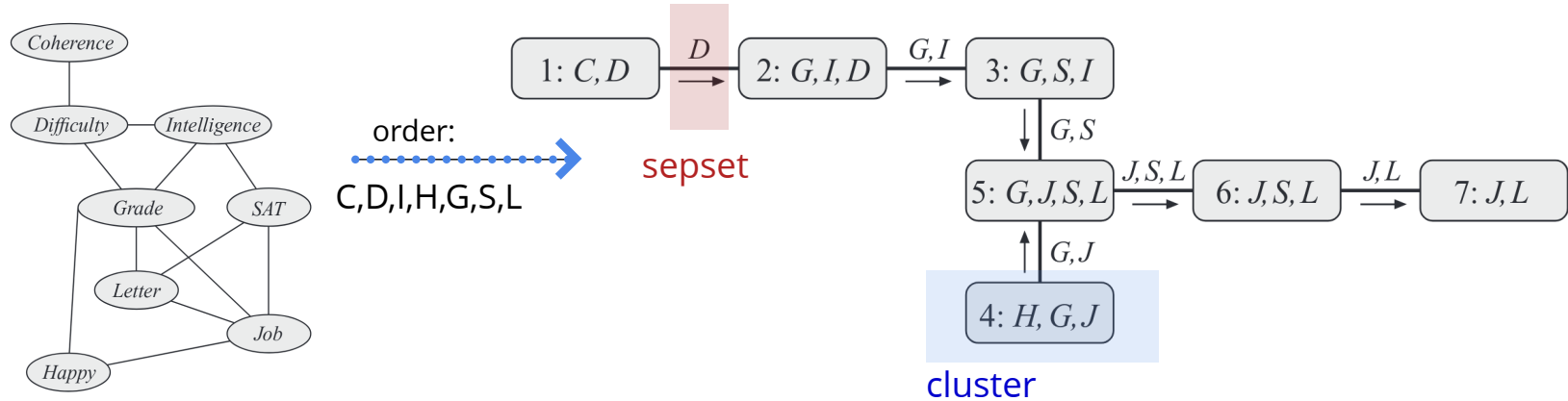
$$P(J) = \dots \sum_I P(S|I) \sum_D P(G|D, I) \sum_C P(D|C)$$

↓  $\psi'_1(D)$       ↓  $\psi_1(D, C)$



# Clique-tree

- summarize the *VE computation* using a **clique-tree**



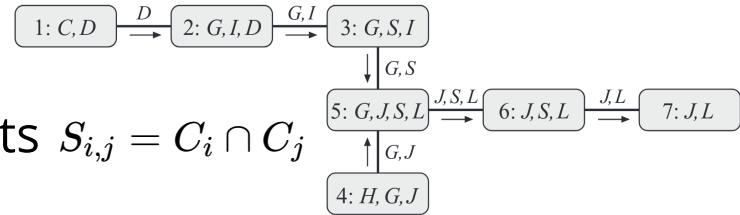
- clusters** are maximal cliques (factors that are marginalized)
- sepsets** are the result of marginalization over cliques

$$C_i = \text{Scope}[\psi_i]$$

$$S_{i,j} = \text{Scope}[\psi'_i]$$

$$S_{i,j} = C_i \cap C_j$$

# Clique-tree: **properties**

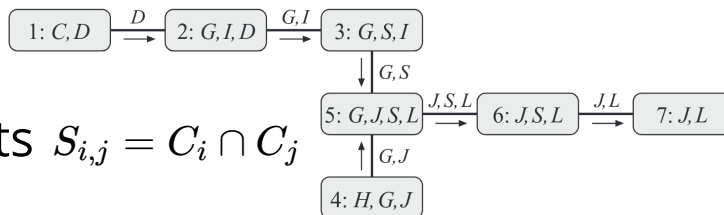


- a tree  $\mathcal{T}$  from clusters  $C_i$  and sepsets  $S_{i,j} = C_i \cap C_j$

- **family-preserving property:**  $\alpha(\phi) = j$

- each factor  $\phi$  is associated with a cluster  $C_j$  s.t.  $Scope[\phi] \subseteq C_j$

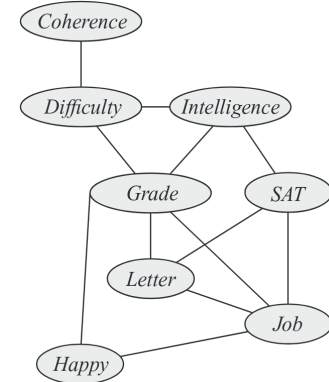
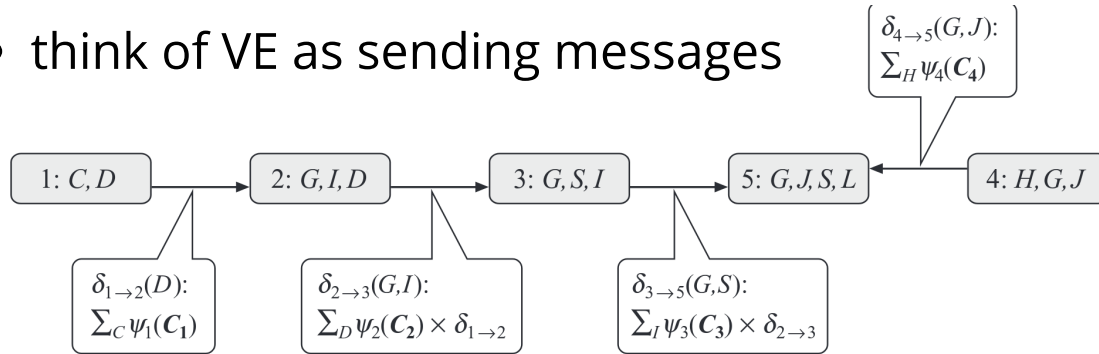
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- a tree  $\mathcal{T}$  from clusters  $C_i$  and sepsets  $S_{i,j} = C_i \cap C_j$
- **family-preserving property:**  $\alpha(\phi) = j$ 
  - each factor  $\phi$  is associated with a cluster  $C_j$  s.t.  $Scope[\phi] \subseteq C_j$
- **running intersection property:**
  - if  $X \in C_i, C_j$  then  $X \in C_k$  for  $C_k$  in the path  $C_i \rightarrow \dots \rightarrow C_j$

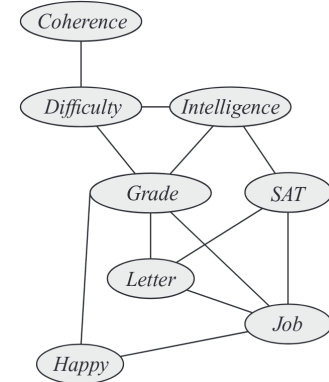
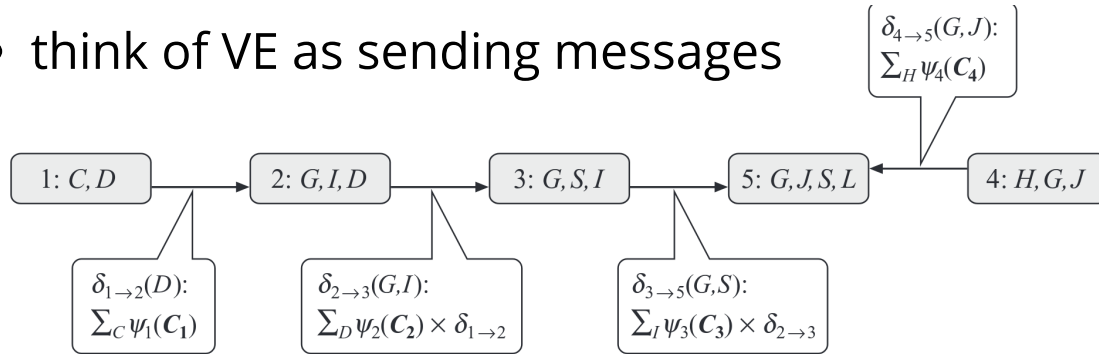
# VE as message passing

- think of VE as sending messages



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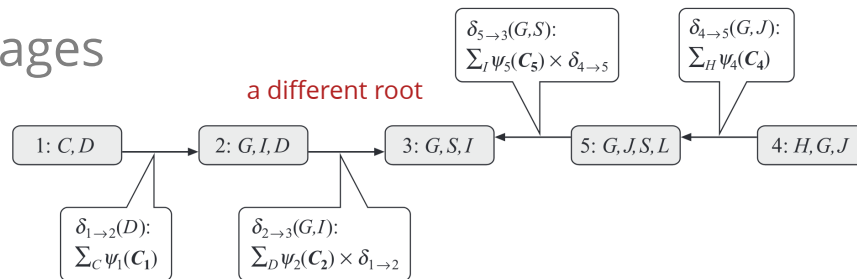
calculate the product of factors in each clique  $\psi_i(C_i) \triangleq \prod_{\phi: \alpha(\phi)=i} \phi$

send messages from the leaves towards a root:

$$\delta_{i \rightarrow j}(S_{i,j}) = \sum_{C_i - S_{i,j}} \psi_i(C_i) \prod_{k \in Nb_i - j} \delta_{k \rightarrow i}(S_{i,k})$$

# message passing

- think of VE as sending messages



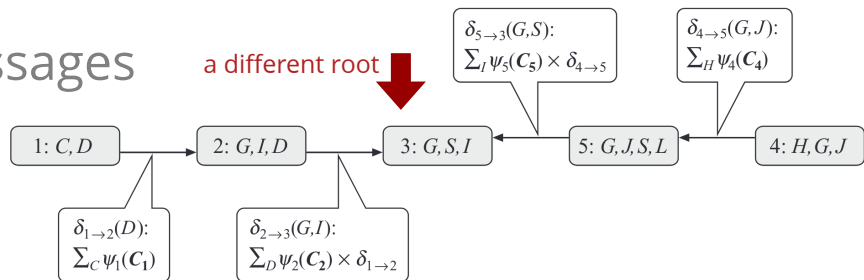
- send messages from the leaves towards a root:

$$\begin{aligned} \delta_{i \rightarrow j}(S_{i,j}) &= \sum_{C_{i-S_{i,j}}} \psi_i(C_i) \prod_{k \in Nb_{i-j}} \delta_{k \rightarrow i}(S_{i,k}) \\ &= \sum_{\mathcal{V} \prec (i \rightarrow j)} \prod_{\phi \in \mathcal{F} \prec (i \rightarrow j)} \phi \end{aligned}$$

- the message is the marginal from one side of the tree

# message passing

- think of VE as sending messages



- send messages from the leaves towards a root:

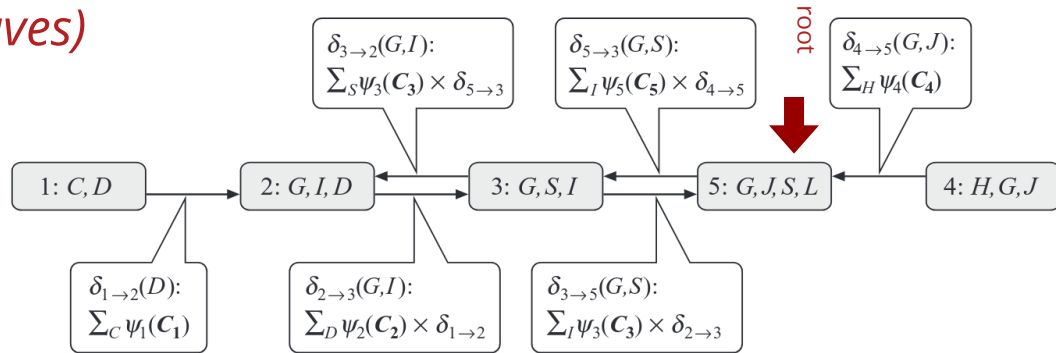
$$\delta_{i \rightarrow j}(S_{i,j}) \triangleq \sum_{C_i - S_{i,j}} \psi_i(C_i) \prod_{k \in Nb_{i-j}} \delta_{k \rightarrow i}(S_{i,k}) = \sum_{\mathcal{V} \prec (i \rightarrow j)} \prod_{\phi \in \mathcal{F}_{\prec (i \rightarrow j)}} \phi$$

- the **belief** at the root clique is  $\beta_r(C_r) \triangleq \psi_r(C_r) \prod_{k \in Nb_r} \delta_{k \rightarrow r}(S_{r,k})$   
proportional to the marginal  $\beta_r(C_r) \propto \sum_{\mathbf{X} - C_i} P(\mathbf{X})$

# message passing: downward pass

- what if we continue sending messages?

*(from the root to leaves)*

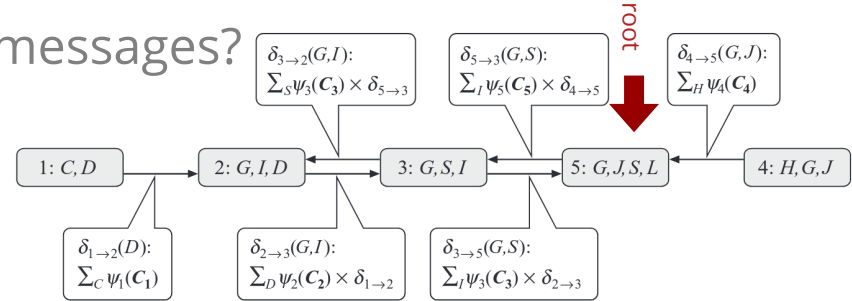


- clique **i** sends a message to clique **j** when received messages from all the **other** neighbors **k**



# message passing: downward pass

- what if we continue sending messages?  
(from the root to leaves)



- sum-product **belief propagation (BP)**

$$\delta_{i \rightarrow j}(S_{i,j}) = \sum_{C_i - S_{i,j}} \psi_i(C_i) \prod_{k \in Nb_i - j} \delta_{k \rightarrow i}(S_{i,k})$$

async. message update

$$\mu_{i,j}(S_{i,j}) \triangleq \delta_{i \rightarrow j}(S_{i,j}) \delta_{j \rightarrow i}(S_{i,j})$$

$$\beta_i(C_i) \triangleq \psi_i(C_i) \prod_{k \in Nb_i} \delta_{k \rightarrow i}(S_{i,k})$$

marginals

for any clique (not only root)

# Clique-tree & queries

What **type of queries** can we answer?

- **marginals** over subset of cliques  $P(A) \quad A \subseteq C_i$
- updating the beliefs after **new evidence**  $P(A \mid E^{(t)} = e^{(t)}) \quad A \subseteq C_i, E \subseteq C_j$ 
  - multiply the (*previously calibrated*) beliefs  $\beta(C_i)\mathbb{I}(E^{(t)} = e^{(t)})$
  - propagate to recalibrate

# Clique-tree & queries

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- **marginals** over subset of cliques  $P(A) \quad A \subseteq C_i$
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  - multiply the (*previously calibrated*) beliefs  $\beta(C_i)\mathbb{I}(E^{(t)} = e^{(t)})$
  - propagate to recalibrate
- **marginals outside cliques:**  $P(A, B) \quad A \subseteq C_i, B \subseteq C_j$ 
  - define a super-clique that has both A,B
  - a more efficient alternative?
- **partition function**  $Z$

# Chordal graph and clique-tree

any chordal graph gives a clique-tree

how to get a chordal graph? **triangulation**

- use the chordal graph from VE
  - min-neighbor, min-fill ...
- or find the optimal chordal graph
  - smallest tree-width
  - also smallest max-clique

**NP-hard**

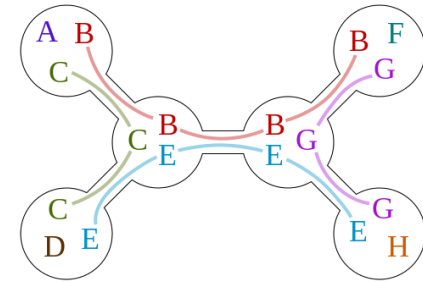
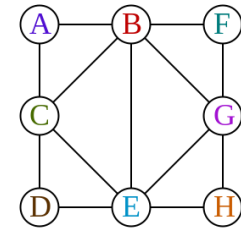


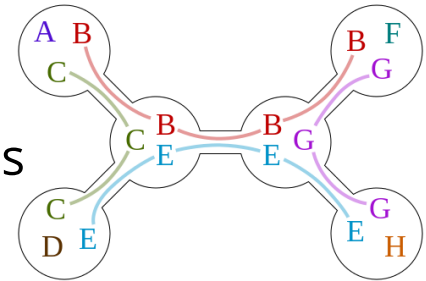
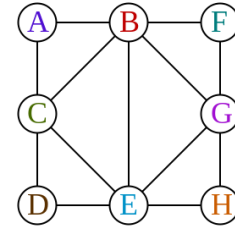
image: wikipedia

# Chordal graph and clique-tree

Chordal graph = Markov  $\cap$  Bayesian networks

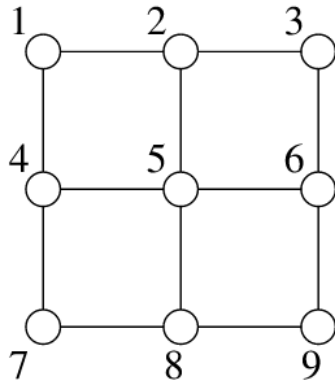
from MRF to Bayes-net:

- triangulate
- build a clique-tree
- **within cliques:** fully connected directed edges
- **between cliques:** from a root to leaves

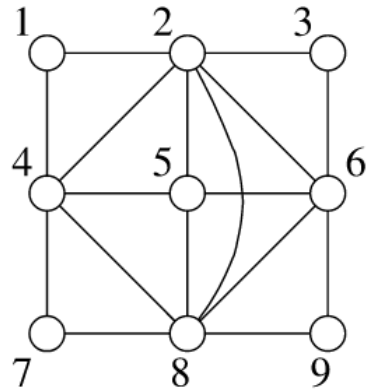


# Building a clique-tree: **example**

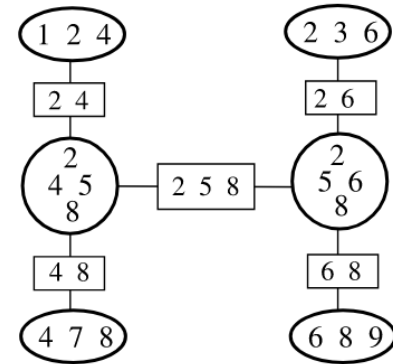
input



triangulated



clique-tree



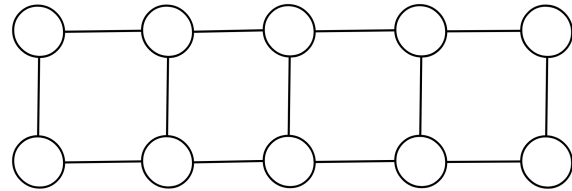
from: wainwright & jordan

# clique-tree quiz

what clique-tree to use here?

what are the sepsets?

cost of exact inference?



# Summary

- VE as message passing in a clique-tree
- clique-tree: running intersection & family preserving
- belief propagation updates:
  - message update
  - belief update
- types of queries
- how to build a clique-tree for exact inference



**bonus slides**

# Clique-tree: calibration

represent  $P$  using marginals:  $\frac{\prod_i \beta_i}{\prod_{i,j \in \mathcal{E}} \mu_{i,j}} = \frac{\prod_i \psi_i \prod_{k \rightarrow i} \delta_{k \rightarrow i}}{\prod_{i,j \in \mathcal{E}} \delta_{i \rightarrow j} \delta_{j \rightarrow i}} = \prod_i \psi_i = \tilde{P}$

how about about **arbitrary** assignments?  $\beta_i, \mu_{i,j} \quad \forall i, j \in \mathcal{E}$   
*can they represent  $P$  as above?*

an assignment is **calibrated** iff

*BP produces calibrated beliefs*

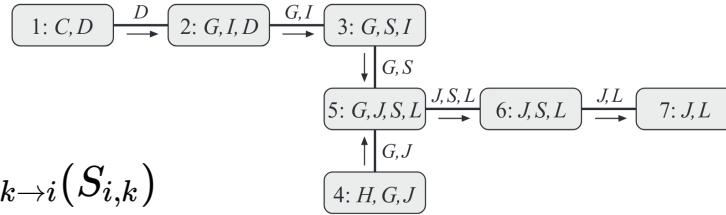
$$\mu_{i,j}(S_{i,j}) = \sum_{C_i - S_{i,j}} \beta_i(C_i) = \sum_{C_j - S_{i,j}} \beta_j(C_j)$$

for calibrated beliefs these "arbitrary assignments" have to be marginals

$$\tilde{P}(\mathbf{X}) \propto \frac{\prod \beta_i(C_i)}{\prod_{i,j \in \mathcal{E}} \mu_{i,j}(S_{i,j})} \iff \beta_i(C_i) \propto P(C_i)$$

# BP: an alternative update

## message update



$$\delta_{i \rightarrow j}(S_{i,j}) = \sum_{C_i - S_{i,j}} \psi_i(C_i) \prod_{k \in Nb_{i-j}} \delta_{k \rightarrow i}(S_{i,k})$$

calculate the beliefs **in the end**  $\beta_i(C_i) = \psi_i(C_i) \prod_{k \in Nb_i} \delta_{k \rightarrow i}(S_{i,k})$

## belief update

since  $\delta_{i \rightarrow j}(S_{i,j}) = \frac{\sum_{C_i - S_{i,j}} \beta_i(C_i)}{\delta_{j \rightarrow i}(S_{i,j})}$  we can **update the beliefs**  
*instead of messages*

# BP: an alternative update

## belief update

initialize  $\beta_i \leftarrow \psi_i = \prod_{\phi: \alpha(\phi)=i} \phi, \quad \mu_{i,j} \leftarrow 1$

until convergence:

pick some  $(i, j) \in \mathcal{E}$

$$\hat{\mu}_{i,j} \leftarrow \sum_{C_i - S_{i,j}} \beta_i \quad // \quad \hat{\mu}_{i,j} = \delta_{i \rightarrow j}^{new} \delta_{j \rightarrow i}$$

$$\beta_j \leftarrow \beta_j \frac{\hat{\mu}_{i,j}}{\mu_{i,j}} \quad // \quad \frac{\hat{\mu}_{i,j}}{\mu_{i,j}} = \frac{\delta_{i \rightarrow j}^{new} \delta_{j \rightarrow i}}{\delta_{i \rightarrow j}^{old} \delta_{j \rightarrow i}} = \frac{\delta_{i \rightarrow j}^{new}}{\delta_{i \rightarrow j}^{old}}$$

$$\mu_{i,j} \leftarrow \hat{\mu}_{i,j}$$

at convergence, beliefs are calibrated

$$\sum_{C_i - S_{i,j}} \beta_i(C_i) = \sum_{C_j - S_{i,j}} \beta_j(C_j)$$

and so they are  $\propto$  marginals