Sequential Minimal Optimization

## OVERVIEW: Convergence Analysis of Sequential Minimal Optimization

## Motivation:

- Support vector machines (SVMs) are widely used in many applictions.
- Sequential minimal optimization (SMO) has been a popular dual 2-coordinate ascent method for training SVMs for around 20 years.
SMO can train SVMs with an unregularized bias, which is preferred when there are imbalanced class labels.

(a) regularized bias

(b) unregularized bias
- This unregularized bias leads to a linear equality constraint across the dual variables,

$$
\sum_{i=1}^{n} \alpha_{i} x_{i}=0 \quad \text { where } \alpha_{i} \in\{-1,1\}
$$

in addition to the constraints

$$
0 \leq x_{i} \leq c \quad \text { for all } i \in\{1,2, \ldots, n\}
$$

which complicates analysis of modern stochastic dual coordinate ascent (SDCA) methods.

## This Work:

* New convergence analysis of SMO with uniformly random coordinate selection (rSMO).
$\rightarrow$ Show linear convergence of rSMO by generalizing convergence result of block coordinate descent (BCD) with linearly coupled constraints.
$\rightarrow$ Previous works give sublinear rates.
$\rightarrow$ Show that rSMO identifies the final set of support vectors in a finite number of iterations under mild conditions.


## Problem of Interest

- We consider the SVM dual as an instance of the general problem

$$
\begin{equation*}
\underset{x \in \mathcal{X}}{\operatorname{minimize}} \quad f(x), \tag{1}
\end{equation*}
$$

where $\mathcal{X}$ is a set of the form $\{x \mid l \leq x \leq u, A x=b\}$.
$\rightarrow l$ and $u$ are upper and lower bounds on the variables.
$\rightarrow A$ is an $m \times n$ matrix where $m \leq n$ and $b$ is a $m \times 1$ vector defining linear constraints.

- The gradient $\nabla f$ is $L$-Lipschitz continuous,

$$
\begin{equation*}
\|\nabla f(y)-\nabla f(x)\| \leq L\|y-x\|, \quad \text { for all } x, y \in \mathcal{X} \tag{2}
\end{equation*}
$$

and the problem satisfies proximal-PL inequality (prox-PL), written in this case as

$$
\begin{equation*}
\frac{1}{2} \mathcal{D}_{g}(x, L) \geq \mu\left(f(x)-f^{*}\right), \quad \text { for all } x, y \in \mathcal{X}, \text { some } \mu>0 \tag{3}
\end{equation*}
$$

where

$$
\left.\mathcal{D}_{g}(x, \mu) \equiv-2 \mu \operatorname{argmin}_{y \in \mathcal{X}}\left\{\langle\nabla f(x), y-x\rangle+\frac{L}{2}\|y-x\|^{2}\right\}\right] .
$$

$\rightarrow$ Prox-PL is weaker than strong convexity and always holds for SVMs by convexity of $f$ and quadratic growth (QG) property.


Figure: convex + QG but not strongly convex

## Sequential Minimal Optimization

* On each iteration, SMO chooses a block from the candidate block set

$$
B=\{\{i, j\} \mid i, j \in\{1,2, \ldots, n\}, i \neq j\}
$$

* The iteration update corresponds to

$$
\begin{aligned}
& x_{i}^{k+1}=\left\{x_{i}-\frac{1}{H_{i i}^{k}+H_{j j}^{k} \pm 2 H_{i j}^{k}}\left[\nabla_{i} f(x) \pm \nabla_{j} f(x)\right]\right\}_{\text {clipped }} \\
& x_{j}^{k+1}=\left\{x_{j}-\frac{1}{H_{j j}^{k}+H_{i i}^{k} \pm 2 H_{i j}^{k}}\left[\nabla_{j} f(x) \pm \nabla_{i} f(x)\right]\right\}_{\text {clipped }}
\end{aligned}
$$

where $\pm$ is $-\alpha_{i} \cdot \alpha_{j}$, and the updates are clipped to stay within the bounds $\left[\mathcal{L}_{i}^{k}, \mathcal{U}_{i}^{k}\right]$ :

$$
\mathcal{L}_{i}^{k}=\left\{\begin{array}{ll}
\max \left\{0, x_{i}^{k}-\left(c-x_{j}^{k}\right)\right\} & \alpha_{i}=\alpha_{j} \\
\max \left\{0, x_{i}^{k}-x_{j}^{k}\right\} & \alpha_{i} \neq \alpha_{j}
\end{array} \quad \mathcal{U}_{i}^{k}= \begin{cases}\min \left\{c, x_{i}^{k}+x_{j}^{k}\right\} & \alpha_{i}=\alpha_{j} \\
\min \left\{c, x_{i}^{k}+\left(c-x_{j}^{k}\right)\right\} & \alpha_{i} \neq \alpha_{j}\end{cases}\right.
$$

and $\left[\mathcal{L}_{j}^{k}, \mathcal{U}_{j}^{k}\right]$ (with the indices swapped) respectively.
$H^{k}=\nabla^{2} f\left(x^{k}\right)$
$\rightarrow$ Avoid $H_{i i}^{k}+H_{j j}^{k} \pm 2 H_{i j}^{k}=0$ without strong convexity by using $H^{k}=L \mathbb{I}$ instead.

## Block Coordinate Descent

- SMO is an instance of general BCD with an iteration update given by

$$
\begin{equation*}
x^{k+1}=\underset{\left\{y_{b}|>| y \in \mathcal{X}\right\}}{\operatorname{argmin}}\left\{f\left(x^{k}\right)+\left\langle\nabla f\left(x^{k}\right), y-x^{k}\right\rangle+\frac{L}{2}\left\|y-x^{k}\right\|_{H^{k}}^{2}\right\} . \tag{4}
\end{equation*}
$$

The candidate block set $B$ contains the supports of the elementary vectors of null $(A)$ :

## Definition

$\rightarrow$ For $A \in \mathbb{R}^{m \times n}$ and $m \leq n$, an elementary vector of $\operatorname{null}(A)$, is a vector $d \in \operatorname{null}(A)$ such that
$\forall d^{\prime} \in \operatorname{null}(A)$ that are conformal to $d, \operatorname{supp}\left(d^{\prime}\right)=\operatorname{supp}(d)$.
$\rightarrow$ Let $d, d^{\prime} \in \mathbb{R}^{n}$. Then $d^{\prime}$ is conformal to $d$ if
$\operatorname{supp}\left(d^{\prime}\right) \subseteq \operatorname{supp}(d)$ and $d_{j}^{\prime} d_{j} \geq 0, \forall j=1, \ldots, n$.

$$
\text { Let } d=\left(\begin{array}{c}
d_{1} \\
0 \\
d_{3} \\
d_{4} \\
0
\end{array}\right), \quad \text { then } \underset{\text { conformal }}{\left(\begin{array}{c}
d_{1} \\
0 \\
0 \\
5 \cdot d_{4} \\
0
\end{array}\right)} \underset{\text { not conformal }}{\left(\begin{array}{c}
d_{1} \\
0 \\
0 \\
-5 \cdot d_{4} \\
d_{5}
\end{array}\right) .}
$$

- The matrix $H^{k}$ satisfies the generalized inequality,

$$
\begin{equation*}
\nabla^{2} f\left(x^{k}\right) \preceq H^{k} \preceq L \mathbb{I} . \tag{5}
\end{equation*}
$$

## Linear Convergence

## Lemma

BCD with uniformly random block selection with updates (4) for problem (1) achieves

$$
\begin{equation*}
\mathbb{E}\left[f\left(x^{k}\right)\right]-f^{*} \leq\left(1-\frac{\mu}{|B| L}\right)^{k}\left(f\left(x^{0}\right)-f^{*}\right) \tag{6}
\end{equation*}
$$

Proof Outline:
Our argument closely follows the analysis of Necoara \& Patrascu.
$\rightarrow$ By Lipschitz-continuity of $\nabla f(2)$ and the property $H^{k} \preceq L \mathbb{I}(5)$,

$$
\begin{equation*}
\mathbb{E}\left[f\left(x^{k+1}\right)\right] \leq f\left(x^{k}\right)+\frac{1}{|B|} \sum_{i=1}^{|B|} \min _{\left\{d_{b_{i}} \mid x_{b_{i}}^{k}+d_{b_{i}} \in \mathcal{X}\right\}}\left\{\left\langle\nabla f_{b_{i}}\left(x^{k}\right), d_{b_{i}}\right\rangle+\frac{L}{2}\left\|d_{b_{i}}\right\|^{2}\right\} . \tag{7}
\end{equation*}
$$

$\rightarrow$ By $B$ containing the supports of the elementary vectors and properties of comformality,

$$
\begin{align*}
(7) & \leq f\left(x^{k}\right)+\frac{1}{|B|} \min _{\{d \mid}\left\{\left\langle x^{k}+d \in \mathcal{X}\right\}\right. \\
& \left.\left.=f\left(x^{k}\right)+\frac{1}{|B|} \min _{y \in \mathcal{X}}\left\{\left\langle\nabla f\left(x^{k}\right), d\right\rangle+\frac{L}{2}\|d\|^{2}\right\}, y-x^{k}\right\rangle+\frac{L}{2}\left\|y-x^{k}\right\|^{2}\right\} . \tag{8}
\end{align*}
$$

$\rightarrow$ By prox-PL inequality (3),

$$
\text { (8) } \leq f\left(x^{k}\right)-\frac{1}{|B|} \frac{\mu}{L}\left(f\left(x^{k}\right)-f^{*}\right)
$$

We can subtract $f^{*}$ from both sides and rearrange the terms, and apply this recursively to get the linear convergence result (6).

## Support Vector Identification

We additionally require that the active set of the solution set $X^{*}$ is unique,

## Definition

The active set for SVMs is the set $\mathcal{Z}=\left\{i: x_{i}^{*}=0\right.$ or $c$ for all $\left.x^{*} \in X^{*}\right\}$.
and the non-degeneracy conditions:
$\rightarrow \nabla_{i} f\left(x^{*}\right) \neq 0$ for all $i \in Z$ and $x^{*} \in X^{*}$,
$\rightarrow\left|\nabla_{i} f\left(x^{*}\right)\right| \neq\left|\nabla_{j} f\left(x^{*}\right)\right|$ for all $i \in Z, j=1, \ldots, n, i \neq j$ and $x^{*} \in X^{*}$.

## Lemma

rSMO for problems satisfying the additional requirements above detects the final set of support vectors after some finite iterate $\mathcal{K}$.

## Intuition:

$\rightarrow$ Use induction on decreasing order of $\left|\nabla_{i} f\left(x^{*}\right)\right|$, for $i \in Z$ to show that rSMO detects the active set after some finite iterate $\mathcal{K}$.

$$
x^{0}=\left(\begin{array}{c}
x_{1}^{0} \\
x_{2}^{0} \\
x_{3}^{0} \\
x_{4}^{0} \\
x_{5}^{0}
\end{array}\right) \quad \text { after finite } \mathcal{K} \text { iterations } \quad x^{\mathcal{K}}=\left(\begin{array}{c}
x_{1}^{\mathcal{K}} \\
0 \\
c \\
x_{4}^{\mathcal{K}} \\
0
\end{array}\right), \quad \text { where } \quad x^{*}=\left(\begin{array}{c}
x_{1}^{*} \\
0 \\
c \\
x_{4}^{*} \\
0
\end{array}\right)
$$

$\rightarrow$ Follow the argument used in Nutini et. al.'s work.
$\rightarrow$ Pick out the indices $i$ that are not on the active set.

