Tutorial 3

CPSC 340: Machine Learning and Data Mining

Fall 2017

Overview

- Naive Bayes Classifier
- 2 Non-Parametric Models
 - Definitions
 - KNN

3 Training, Testing, and Validation Set

- Naive Bayes is a probabilistic classifier.
 - Based on Bayes' theorem.
 - Strong independence assumption between features.

- Naive Bayes is a probabilistic classifier.
 - Based on Bayes' theorem.
 - Strong independence assumption between features.
- In the rest of this tutorial,
 - We use y_i for the label of object i (element i of y).
 - We use x_i for the features of object i (row i of X).
 - We use x_{ij} for feature j of object i.
 - We use d for the number of features in object i.

• Bayes' rule

Posterior probability Likelihood Prior probability

$$p(y_i|x_i) = \frac{p(x_i|y_i)p(y_i)}{p(x_i)}$$
Evidence

we want to compare P(y=clx_i) for different values of c and choose the maximum value

• Bayes' rule

Posterior probability Likelihood Prior probability $p(y_i|x_i) = \frac{p(x_i|y_i)p(y_i)}{p(x_i)}$ Evidence

• Since the denominator does not depend on y_i , we are only interested in the numerator:

$$p(y_i|x_i) \propto p(x_i|y_i)p(y_i)$$

• The numerator is equal to the joint probability:

$$p(x_i|y_i)p(y_i) = p(x_i, y_i) = p(x_{i1}, ..., x_{id}, y_i)$$

$$\mathsf{P}(\mathsf{xi1}, \mathsf{xi2}, \ldots, \mathsf{yi}) = \mathsf{P}(\mathsf{xi1}|\mathsf{xi2}, \mathsf{xi3}, \ldots, \mathsf{yi}) \; \mathsf{P}(\mathsf{xi2}, \mathsf{xi3}, \ldots, \mathsf{yi})$$

• The numerator is equal to the joint probability:

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• Chain rule:

$$\begin{split} p(x_{i1},...,x_{id},y_i) &= p(x_{i1}|x_{i2},...,x_{id},y_i) p(x_{i2},...,x_{id},y_i) \\ &= ... \\ &= p(x_{i1}|x_{i2},...,x_{id},y_i) p(x_{i2}|x_{i3},...,x_{id},y_i) \ ... \ p(x_{id}|y_i) p(y_i) \\ &\qquad \qquad \text{P(xi1lyi)} \qquad \qquad \text{P(xi2lyi)} \qquad \qquad \text{P(xidlyi)} \qquad \text{P(yi)} \end{split}$$

These are our parameters

• The numerator is equal to the joint probability:

$$p(x_i|y_i)p(y_i) = p(x_i, y_i) = p(x_{i1}, ..., x_{id}, y_i)$$

• Chain rule:

$$p(x_{i1},...,x_{id},y_i) = p(x_{i1}|x_{i2},...,x_{id},y_i)p(x_{i2},...,x_{id},y_i)$$

$$= ...$$

$$= p(x_{i1}|x_{i2},...,x_{id},y_i)p(x_{i2}|x_{i3},...,x_{id},y_i) ... p(x_{id}|y_i)p(y_i)$$

• Each feature in x_i is independent of the others given y_i :

$$p(x_{ij}|x_{ij+1},...,x_{id},y_i) = p(x_{ij}|y_i)$$

• The numerator is equal to the joint probability:

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$$= ...$$

$$= p(x_{i1}|x_{i2}, ..., x_{id}, y_i)p(x_{i2}|x_{i3}, ..., x_{id}, y_i) ... p(x_{id}|y_i)p(y_i)$$

• Each feature in x_i is independent of the others given y_i :

$$p(x_{ij}|x_{ij+1},...,x_{id},y_i) = p(x_{ij}|y_i)$$

• Therefore:

our score for a given yi

$$p(y_i, x_i) \propto p(y_i) \prod_{j=1}^{a} p(x_{ij}|y_i)$$

Problem: Naive Bayes Classifier



headache	runny nose	fever	flu
N	Υ	Y	N
Y	N	N	N
N	N	N	N
Y	Y	Y	Y
Y	Υ	N	Y
N	N	Y	Y

Problem: Naive Bayes Classifier



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N	Υ	Y	N
Y	N	N	N
N	N	N	N
Y	Υ	Y	Y
Y	Y	N	Υ
N	N	Y	Υ

headache	runny nose	fever	flu
Y	N	Y	?

p(headache=Y flu=N)	1/3
p(headache=Y <mark>flu=Y</mark>)	2/3
p(runny nose=N flu=N)	2/3
p(runny nose=N flu=Y)	1/3
p(fever=Y flu=N)	1/3
p(fever=Y <mark>flu=Y</mark>)	2/3
p(flu=N)	1/2
p(flu=Y)	1/2

p(headache=Y flu=N)	1/3
p(headache=Y flu=Y)	2/3
p(runny nose=N flu=N)	2/3
p(runny nose=N flu=Y)	1/3
p(fever=Y flu=N)	1/3
p(fever=Y <mark>flu=Y</mark>)	2/3
p(flu=N)	1/2
p(flu=Y)	1/2

•
$$p(\text{flu} = N | \text{headache} = Y, \text{runny nose} = N, \text{fever} = Y) \propto$$

$$p(\text{headache} = Y | \text{flu} = N) p(\text{runny nose} = N | \text{flu} = N) p(\text{fever} = Y | \text{flu} = N) p(\text{flu} = N) = \frac{1}{3} * \frac{2}{3} * \frac{1}{3} * \frac{1}{2} = 0.0370$$

p(headache=Y flu=N)	1/3
p(headache=Y <mark>flu=Y</mark>)	2/3
p(runny nose=N flu=N)	2/3
p(runny nose=N flu=Y)	1/3
p(fever=Y flu=N)	1/3
p(fever=Y <mark>flu=Y</mark>)	2/3
p(flu=N)	1/2
p(flu=Y)	1/2

- $p(\text{flu} = N | \text{headache} = Y, \text{runny nose} = N, \text{fever} = Y) \propto p(\text{headache} = Y | \text{flu} = N) p(\text{runny nose} = N | \text{flu} = N) p(\text{fever} = Y | \text{flu} = N) p(\text{flu} = N) = \frac{1}{3} * \frac{2}{3} * \frac{1}{3} * \frac{1}{2} = 0.0370$
- $p(\text{flu} = Y | \text{headache} = Y, \text{runny nose} = N, \text{fever} = Y) \propto$ $p(\text{headache} = Y | \text{flu} = Y) p(\text{runny nose} = N | \text{flu} = Y) p(\text{fever} = Y | \text{flu} = Y) p(\text{flu} = Y) = \frac{2}{3} * \frac{1}{3} * \frac{2}{3} * \frac{1}{2} = 0.0741$

p(headache=Y flu=N)	1/3
p(headache=Y <mark>flu=Y</mark>)	2/3
p(runny nose=N flu=N)	2/3
p(runny nose=N flu=Y)	1/3
p(fever=Y flu=N)	1/3
p(fever=Y <mark>flu=Y</mark>)	2/3
p(flu=N)	1/2
p(<mark>flu=Y</mark>)	1/2

- $p(\text{flu} = N | \text{headache} = Y, \text{runny nose} = N, \text{fever} = Y) \propto$ • $p(\text{headache} = Y | \text{flu} = N) p(\text{runny nose} = N | \text{flu} = N) p(\text{fever} = Y | \text{flu} = N) p(\text{flu} = N) = \frac{1}{3} * \frac{2}{3} * \frac{1}{3} * \frac{1}{2} = 0.0370$
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headache	runny nose	fever	flu
Y	N	γ	Y

Bayes' Theorem



• Bayes' Theorem enables us to reverse probabilities:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Problem: Prosecutor's fallacy



- A crime has been committed in a large city and footprints are found at the scene of the crime. The guilty person matches the footprints, p(F|G) = 1. Out of the innocent people, 1% match the footprints by chance, $p(F| \sim G) = 0.01$. A person is interviewed at random and his/her footprints are found to match those at the crime scene. Determine the probability that the person is guilty, or explain why this is not possible, p(G|F) = ?
 - \bullet Let F be the event that the footprints match.
 - Let G be the event that the person is guilty
 - $\sim G$ be the event that the person is innocent.

Solution: Prosecutor's fallacy



$$p(G|F) = \frac{p(F|G)p(G)}{p(F)} = \frac{p(F|G)p(G)}{p(F|G)p(G) + p(F| \sim G)p(\sim G)}$$

Solution: Prosecutor's fallacy



$$p(G|F) = \frac{p(F|G)p(G)}{p(F)} = \frac{p(F|G)p(G)}{p(F|G)p(G) + p(F| \sim G)p(\sim G)}$$

• $p(G) = ? \rightarrow Impossible!$



Definitions

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 - Fixed number of parameters learned (estimated) from data
 - \bullet More data \Rightarrow More accurate models.

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- Parametric Models
 - Fixed number of parameters learned (estimated) from data
 - More data ⇒ More accurate models.
- Non-parametric Models
 - Number of parameters grows with the amount of data
 - More data More complex models.
- Parametric or Non-parametric? What are the parameters?
 - Decision Trees P (if depth is given)
 - Naive Bayes P (if features are discrete)
 - KNN Non-p
 - Random Forests (the number of trees are fixed,
 - but the depth usually varies with data) Non-p
 - K-Means Clustering_P (k is given)

k-Nearest Neighbour

• How does it work?

k-Nearest Neighbour

- How does it work?
- What is the effect of k with respect to the fundamental tradeoff in machine learning?

k-Nearest Neighbour

- How does it work?
- What is the effect of k with respect to the fundamental tradeoff in machine learning?
- What is the runtime?

Training, Testing, and Validation Set

- Given training data, we would like to learn a model to minimize error on the testing data
- How do we decide decision tree depth?
- We care about test error.
- But we can't look at test data.
- So what do we do?????
- One answer: Use part of your train data to approximate test error.
- Split training objects into training set and validation set:
 - Train model on the training data.
 - Test model on the validation data.

Cross-Validation

- Isn't it wasteful to only use part of your data?
- k-fold cross-validation:
 - Train on k-1 folds of the data, validate on the other fold.
 - ullet Repeat this k times with different splits, and average the score.

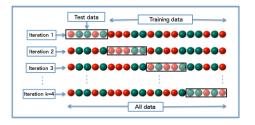


Figure 1: Adapted from Wikipedia.

• Note: if examples are ordered, split should be random.