

CPSC 340: Machine Learning and Data Mining

Sparse Matrix Factorization

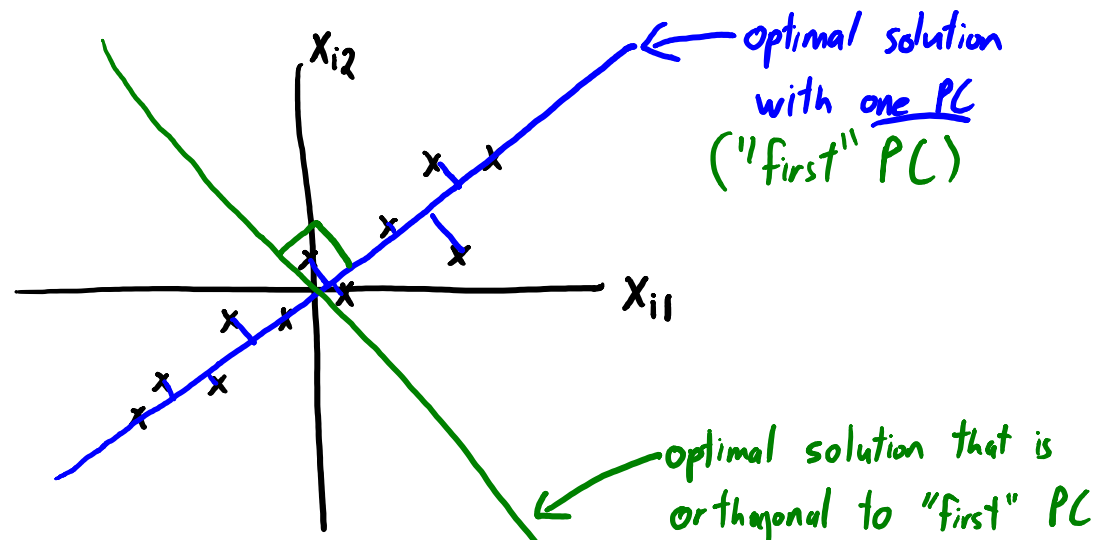
Fall 2017

Admin

- **Assignment 4:**
 - Due Friday.
- **Assignment 5:**
 - Posted, due Monday of last week of classes

Last Time: PCA with Orthogonal/Sequential Basis

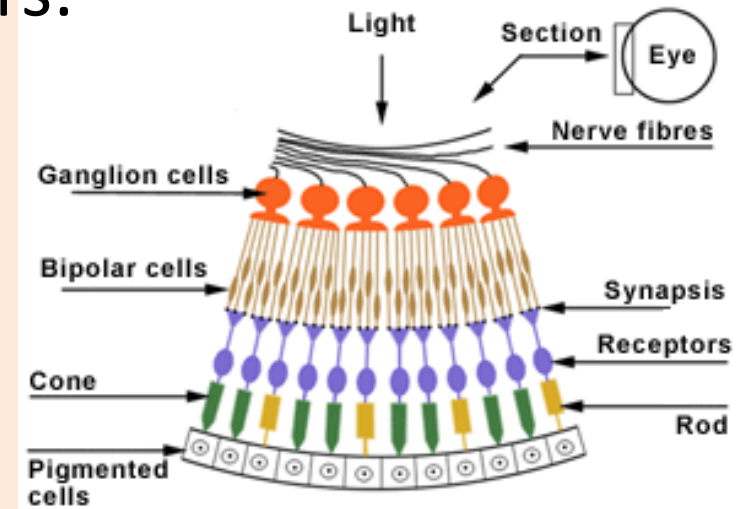
- When $k = 1$, PCA has a **scaling problem**.
- When $k > 1$, have **scaling, rotation, and label switching**.
 - Standard fix: use **normalized orthogonal rows** W_c of 'W'.
$$\|w_c\| = 1 \quad \text{and} \quad w_c^T w_{c'} = 0 \quad \text{for } c' \neq c$$
 - And **fit the rows in order**:
 - First row "explains the most variance" or "reduces error the most".



Colour Opponency in the Human Eye

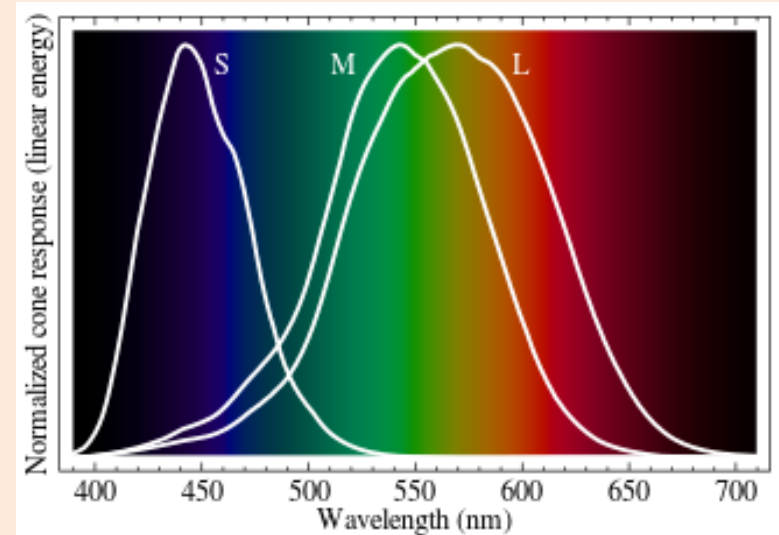
- Classic model of the eye is with 4 photoreceptors:

- Rods (more sensitive to brightness).
- L-Cones (most sensitive to red).
- M-Cones (most sensitive to green).
- S-Cones (most sensitive to blue).



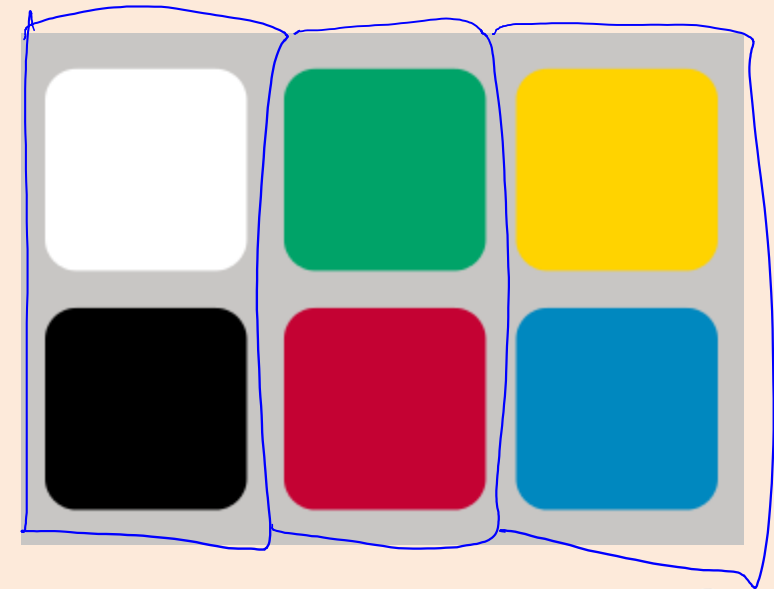
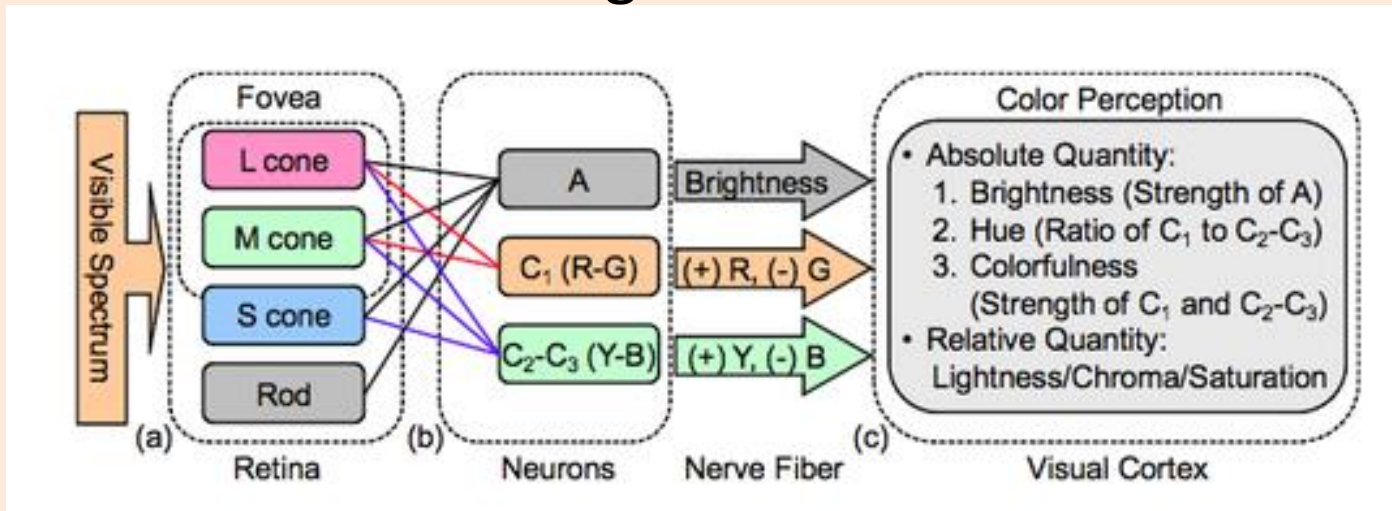
- Two problems with this system:

- Not orthogonal.
 - High correlation in particular between red/green.
- We have 4 receptors for 3 colours.

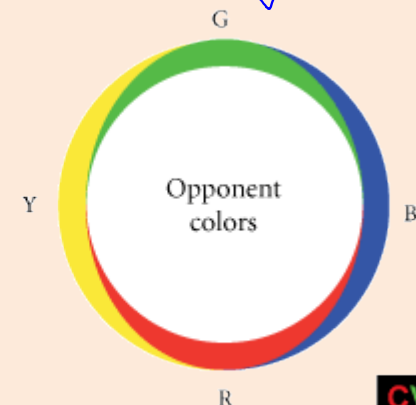


Colour Opponency in the Human Eye

- Bipolar and ganglion cells seem to code using “opponent colors”:
 - 3-variable orthogonal basis:



- This is similar to PCA ($d = 4, k = 3$).



Colour Opponency Representation

For this pixel, eye gets 4 signals

Can represent 4 original values with these 3 z_i values and matrix 'W'



$= W_1$



First row of W

(First PC)



Analogous to means in k-means.



brightness

$+W_2$



Second row (4x1)



red/green

$+W_3$



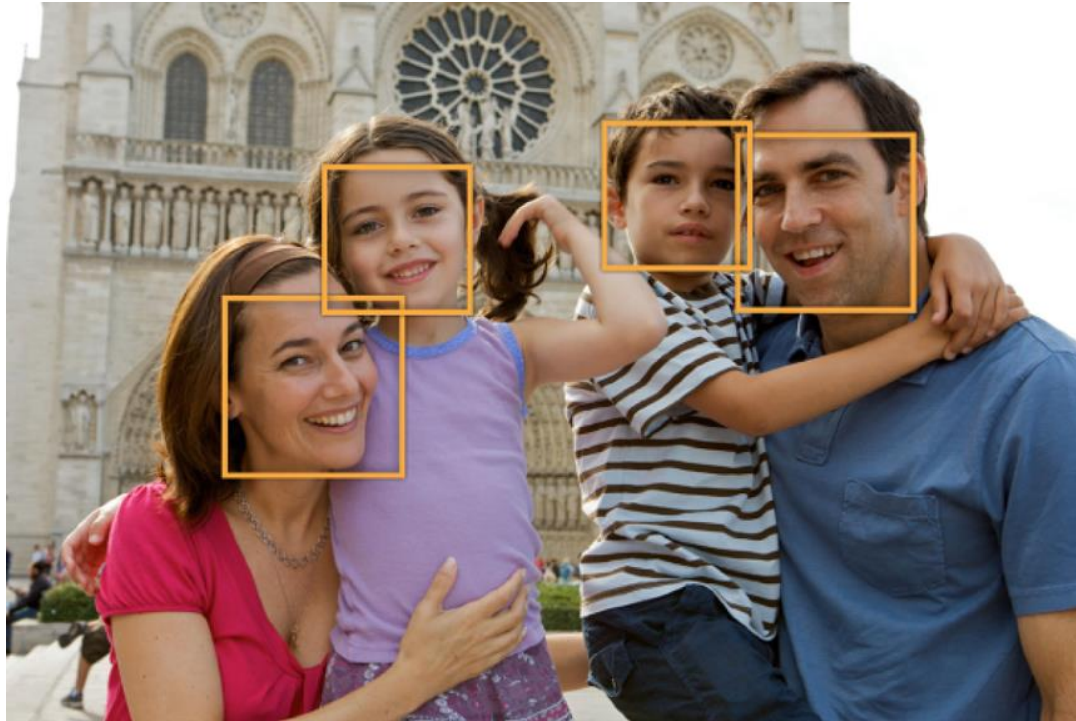
Third row (4x1)



blue/yellow

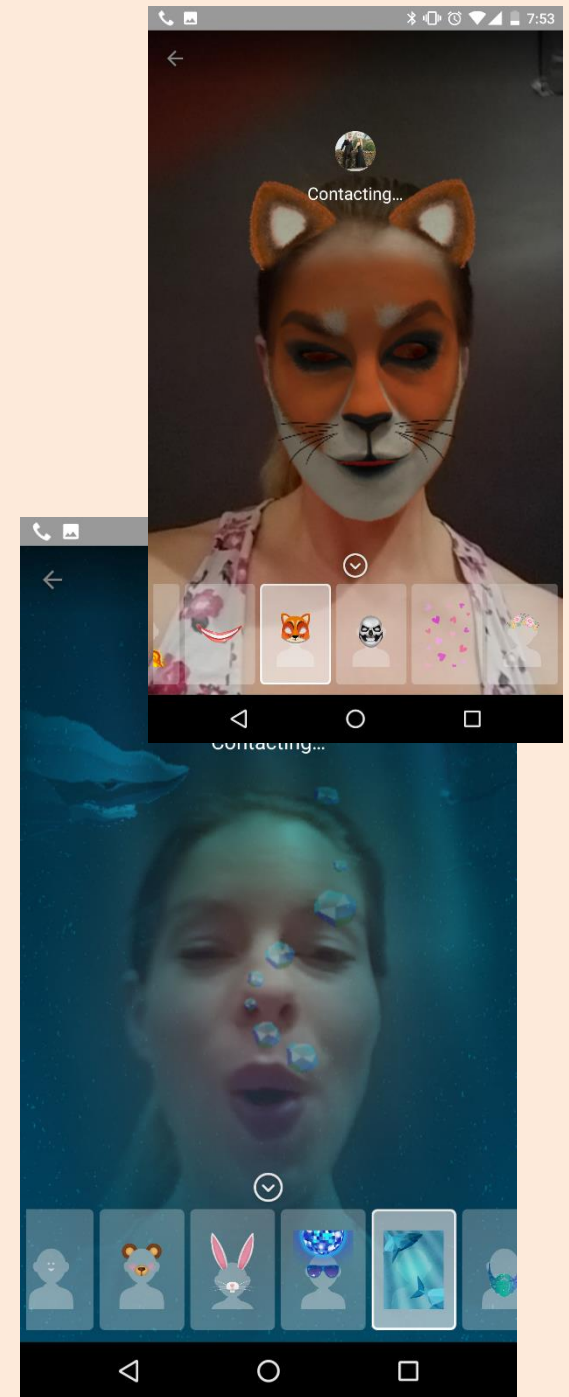
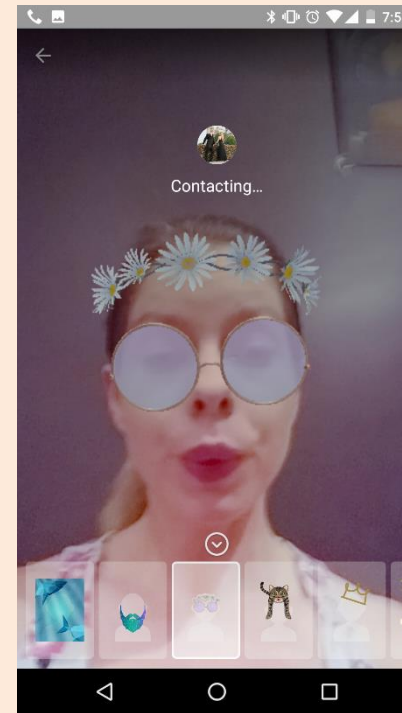
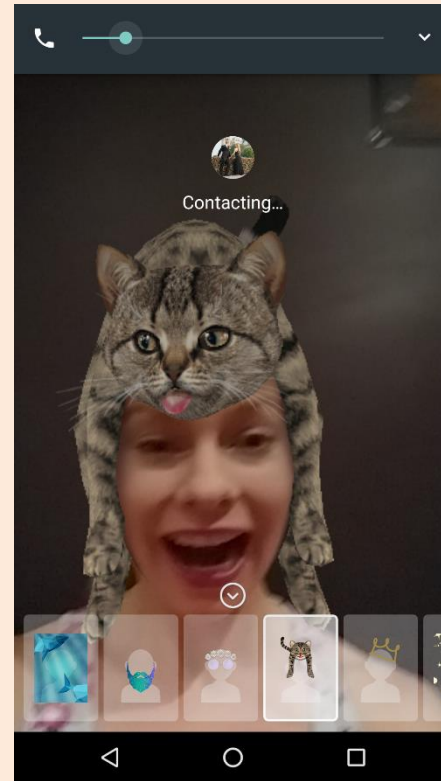
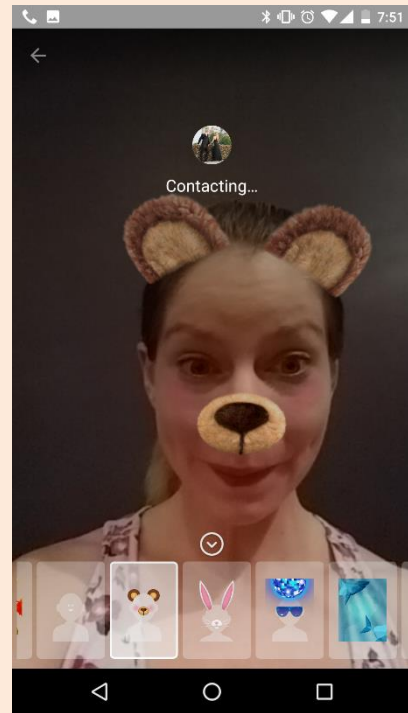
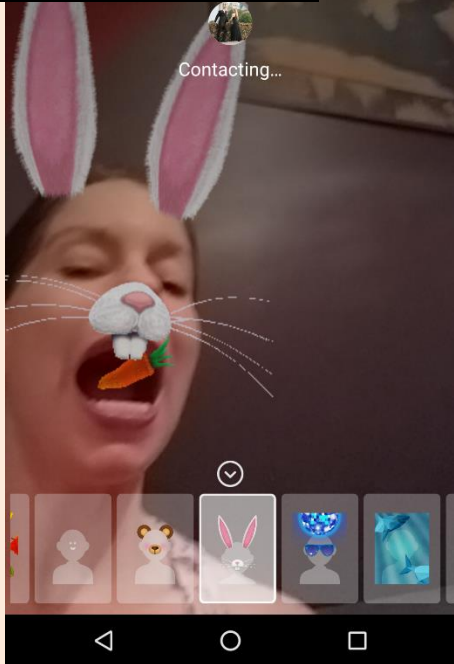
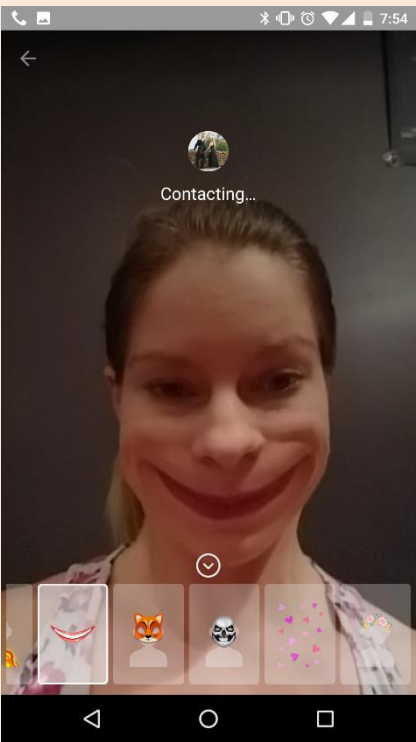
Application: Face Detection

- Consider problem of face detection:



- Classic methods use “eigenfaces” as basis:
 - PCA applied to images of faces.

Application: Face Detection



Eigenfaces

- Collect a bunch of images of faces under different conditions:



Each row of X will be pixels in one image:

$X =$

If have ' n ' images that are ' m ' by ' m ' then X is ' n ' by m^2 .

Eigenfaces

Compute mean μ_j of each column,



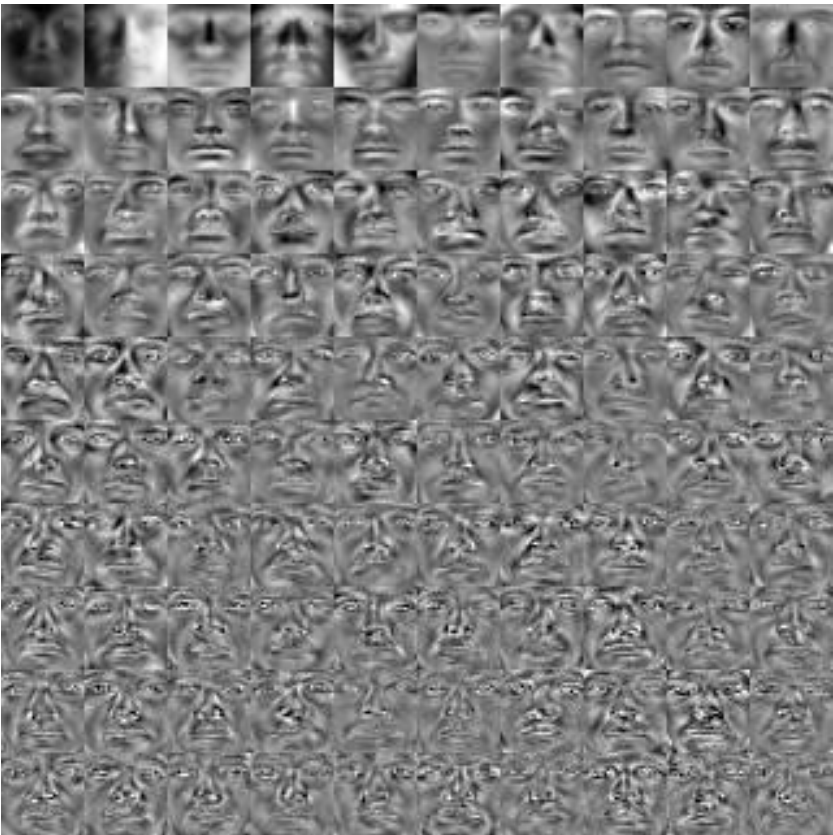
Replace each x_{ij} by $x_{ij} - \mu_j$

Each row of X will be pixels in one image:

$$X = \begin{bmatrix} \text{---} x_1 - \mu \text{---} \\ \text{---} x_2 - \mu \text{---} \\ \vdots \\ \text{---} x_n - \mu \text{---} \end{bmatrix}$$

Eigenfaces

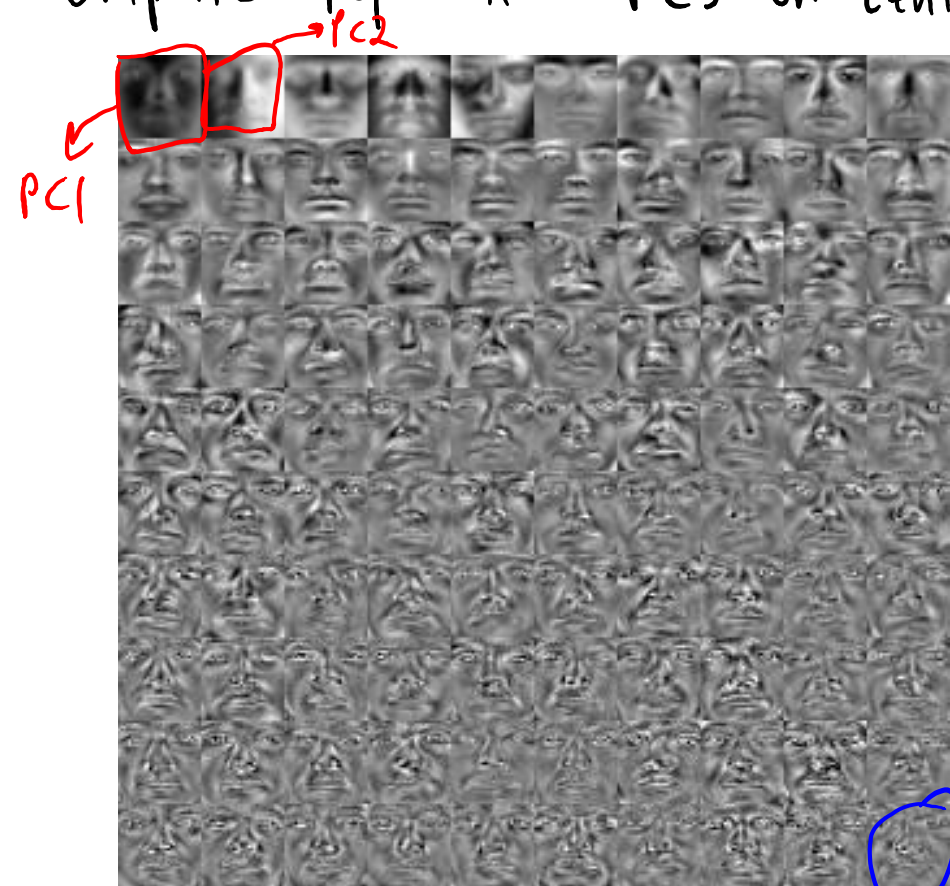
Compute top 'k' PCs on centered data: Each row of X will be pixels in one image:



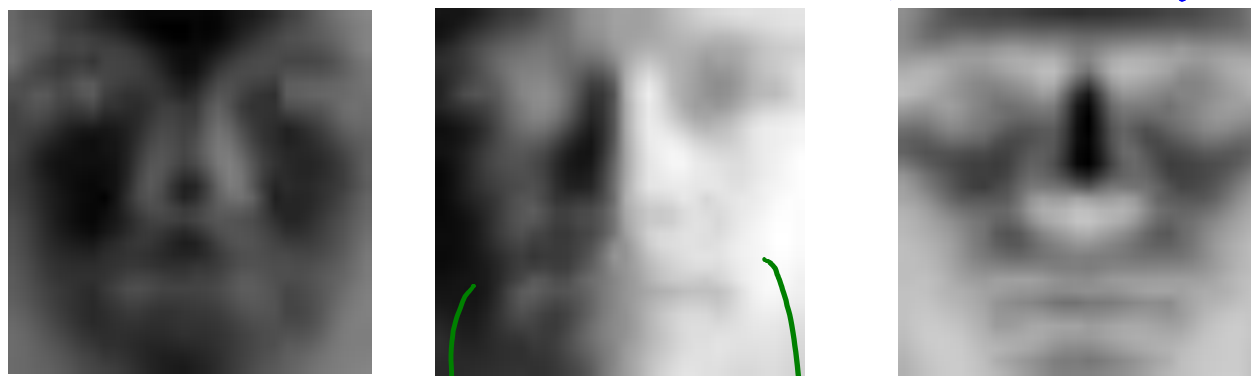
$$X = \begin{bmatrix} \text{---} x_1 - \mu \text{---} \\ \text{---} x_2 - \mu \text{---} \\ \vdots \\ \text{---} x_n - \mu \text{---} \end{bmatrix}$$

Eigenfaces

Compute top 'k' PCs on centered data:



Note that these are "signed" images.



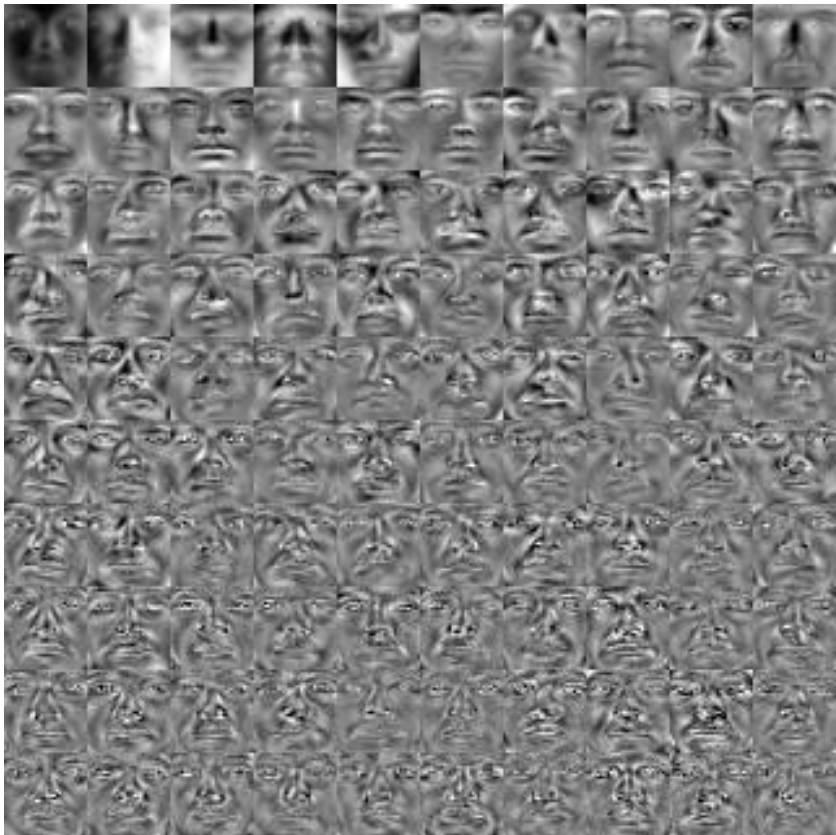
"gray" represents values close to 0.

"dark" represents negative values

"bright" represents positive values

Eigenfaces

Compute top 'k' PCs on centered data:



"Eigenface" representation:

$$\hat{x}_i = \mu + z_{i1} \text{PC1} + z_{i2} \text{PC2} + z_{i3} \text{PC3} + \dots$$

(first row of W)

Eigenfaces

106 of the original faces:



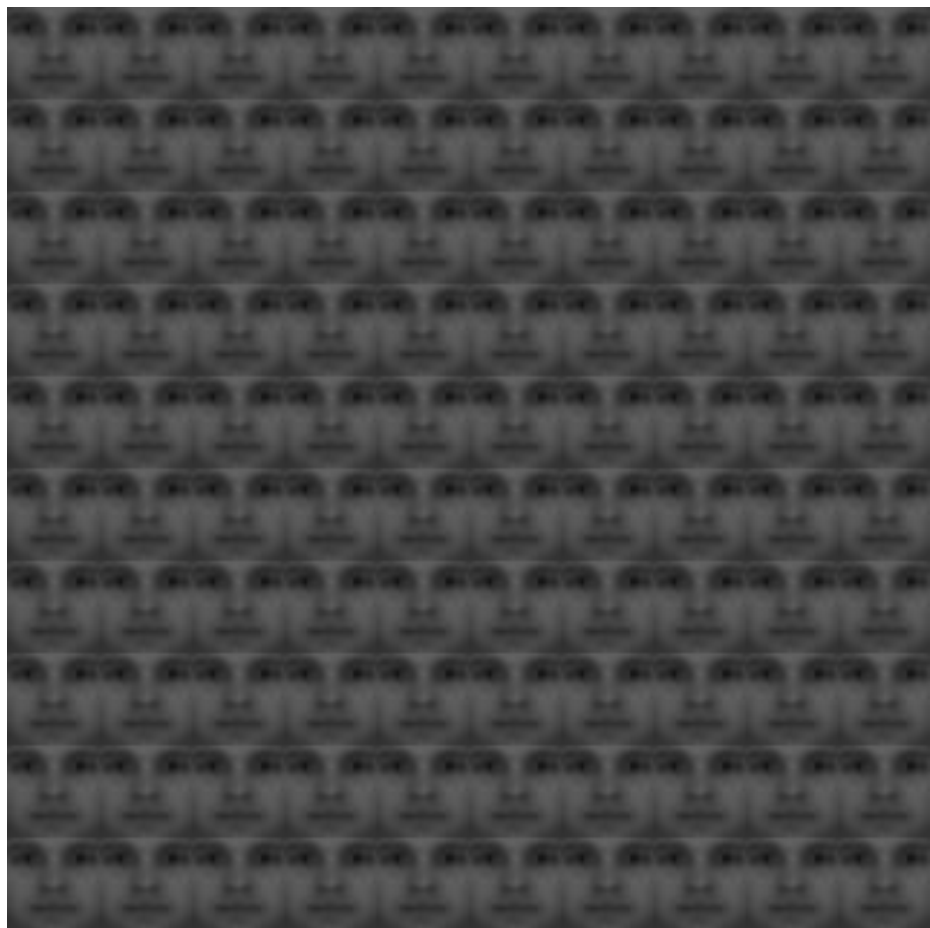
"Eigenface" representation:

$$\hat{x}_i = \mu + z_{i1} \text{PC1} + z_{i2} \text{PC2} + z_{i3} \text{PC3} + \dots$$

(first row of W)

Eigenfaces

Reconstruction with $k=0$



Variance explained: 0%

"Eigenface" representation:

$$\hat{x}_i = \mu + z_{i1} \text{PC1} + z_{i2} \text{PC2} + z_{i3} \text{PC3} + \dots$$

PC1
(first row of W)

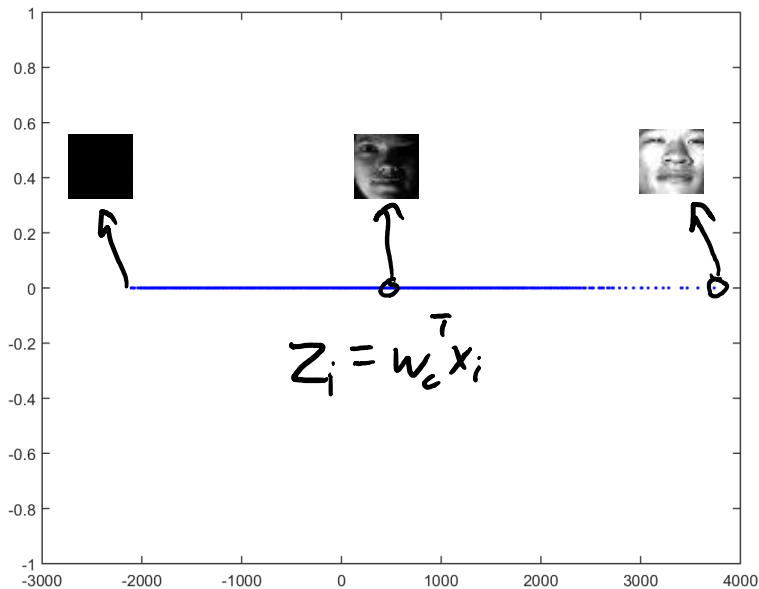
Eigenfaces

Reconstruction with $k=1$



Variance explained: 34%

PCA Visualization:



"Eigenface" representation:

$$\hat{x}_i = \mu + z_{i1} \text{PC1} + z_{i2} \text{PC2} + z_{i3} \text{PC3} + \dots$$

(first row of w)

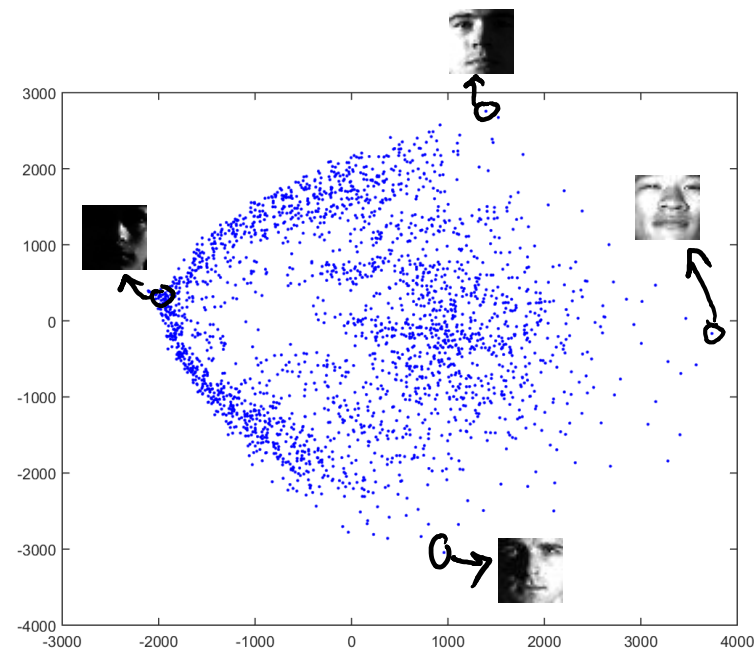
Eigenfaces

Reconstruction with $k=2$



Variance explained: 71%

PCA Visualization:



"Eigenface" representation:

$$\hat{x}_i = \mu + z_{i1} \text{PC1} + z_{i2} \text{PC2} + z_{i3} \text{PC3} + \dots$$

(first row of W)

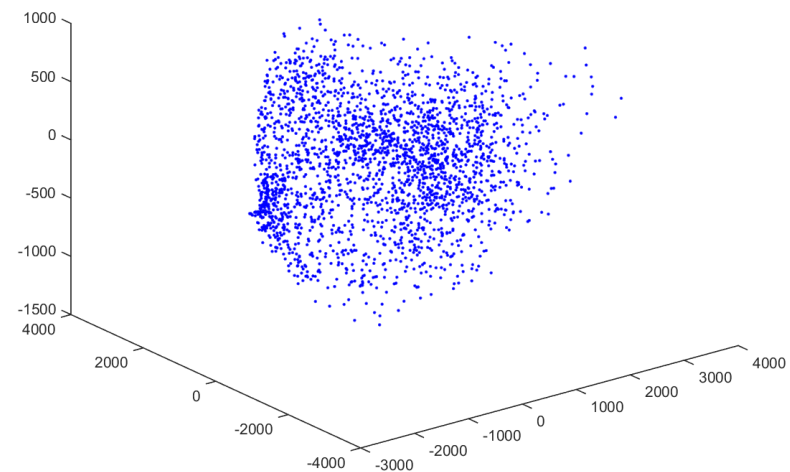
Eigenfaces

Reconstruction with $k=3$



Variance explained: 76%

PCA Visualization:



"Eigenface" representation:

$$\hat{x}_i = \mu + z_{i1} \text{PC1} + z_{i2} \text{PC2} + z_{i3} \text{PC3} + \dots$$

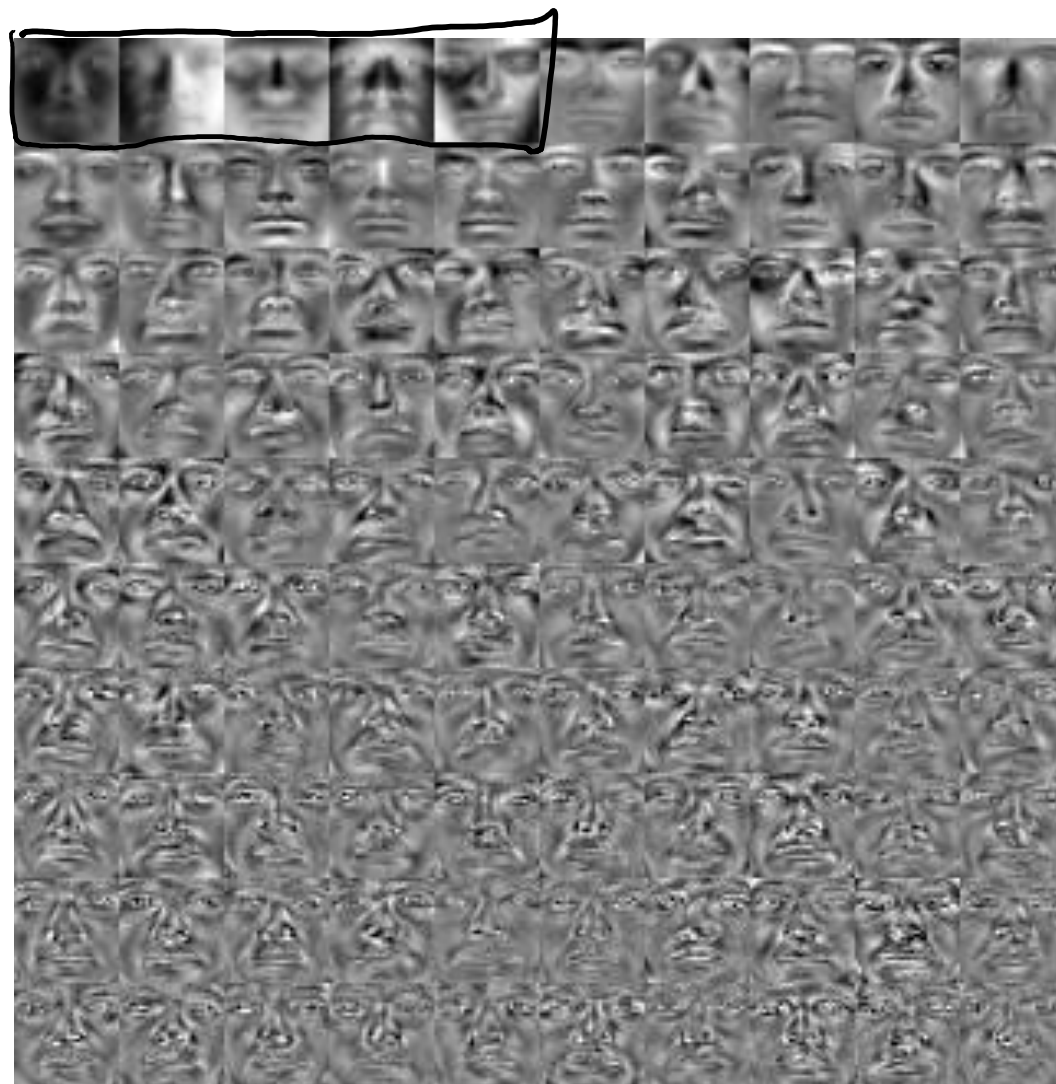
(first row of W)

Reconstruction with $k=5$



Variance explained: 86%

Eigenfaces

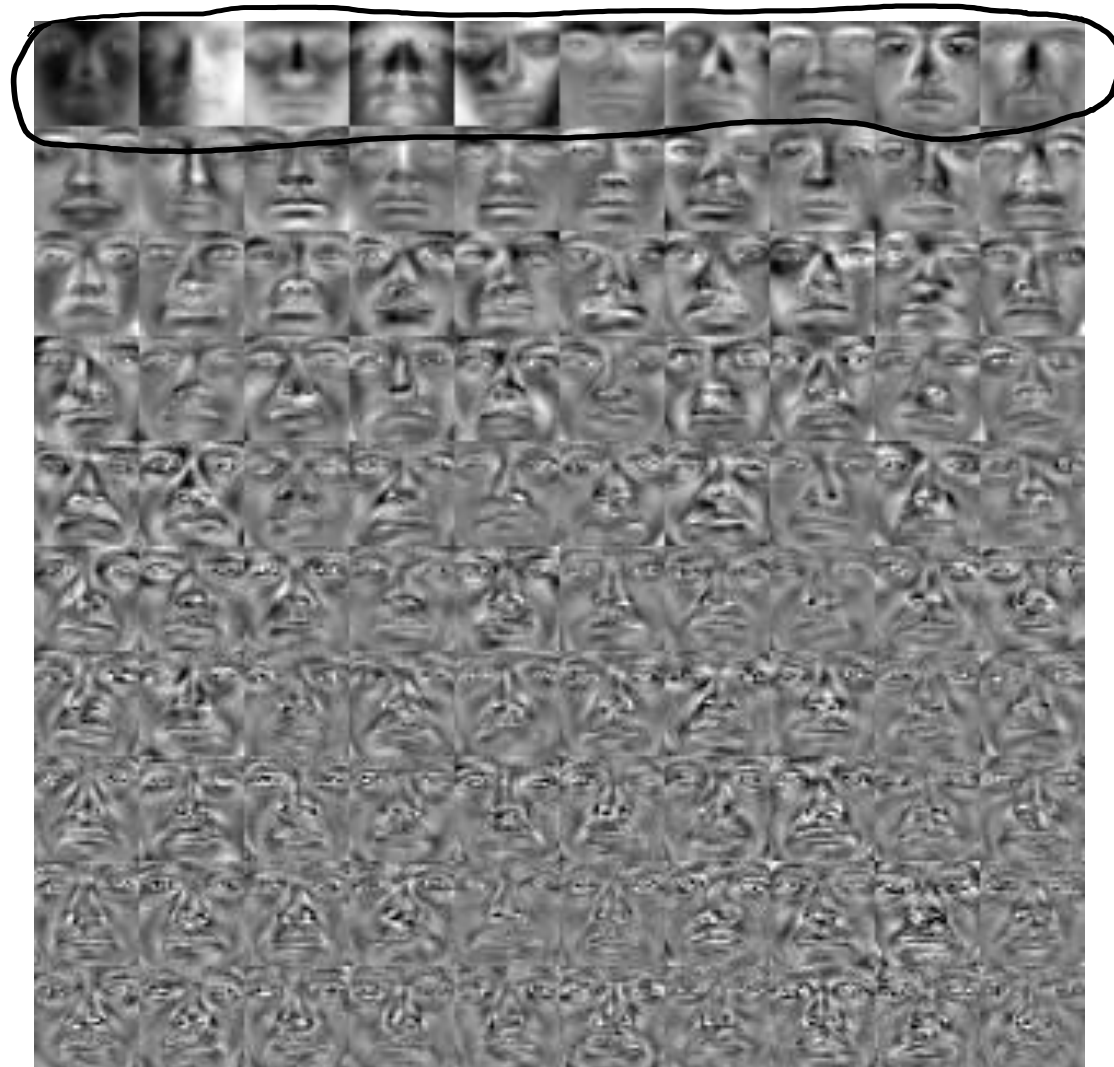


Reconstruction with $k=10$



Variance explained: 85%

Eigenfaces

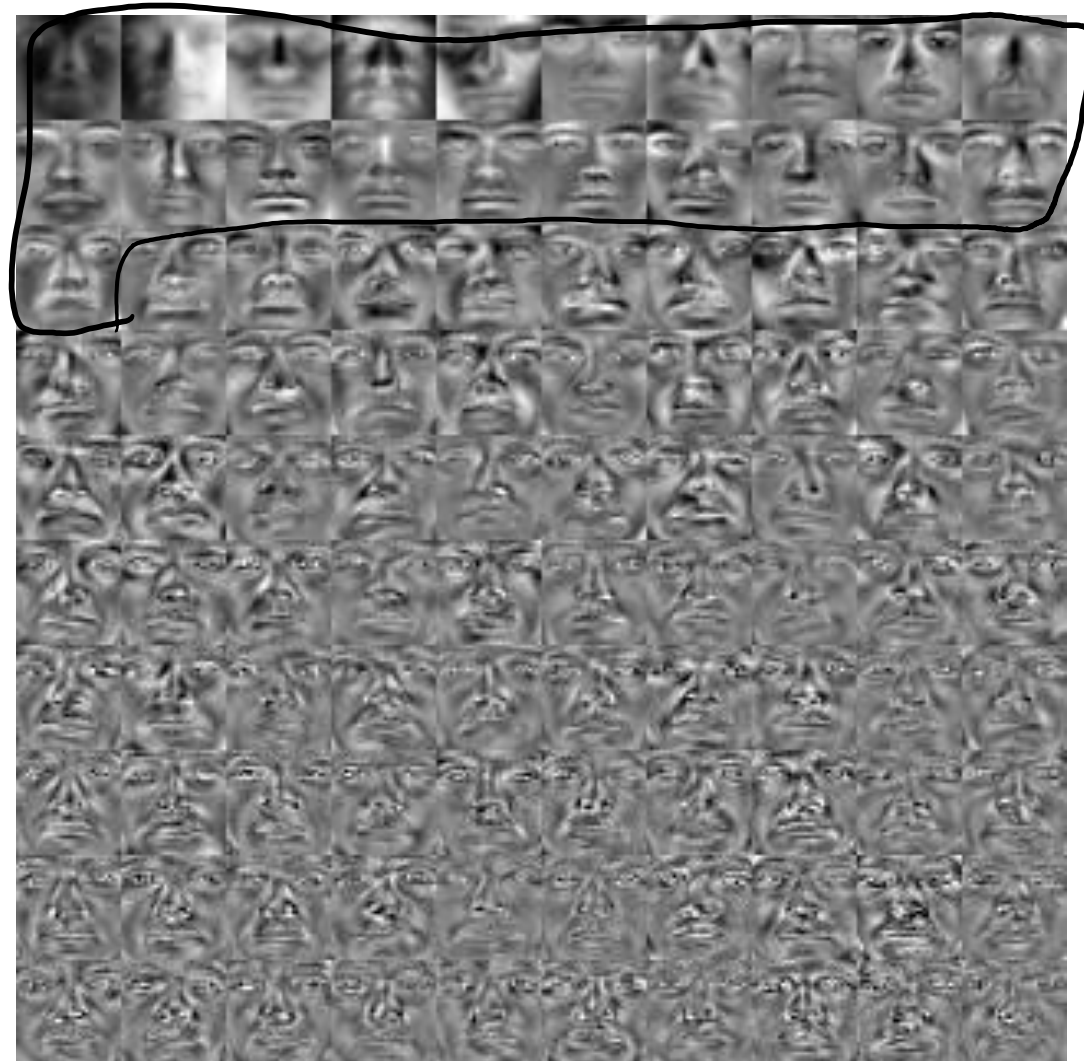


Eigenfaces

Reconstruction with $k=21$



Variance explained: 90%

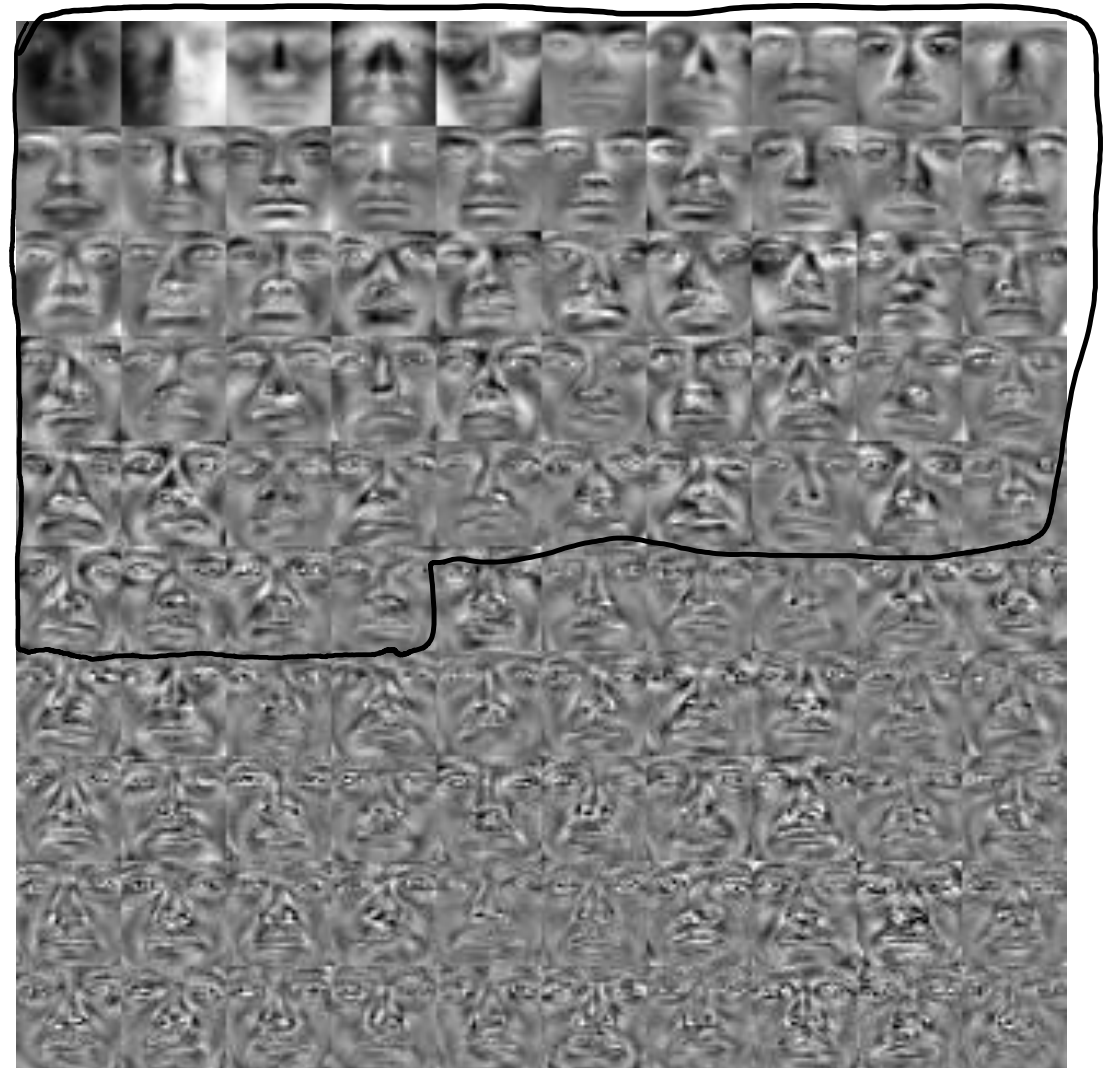


Eigenfaces

Reconstruction with $k=54$



Variance explained: 95%

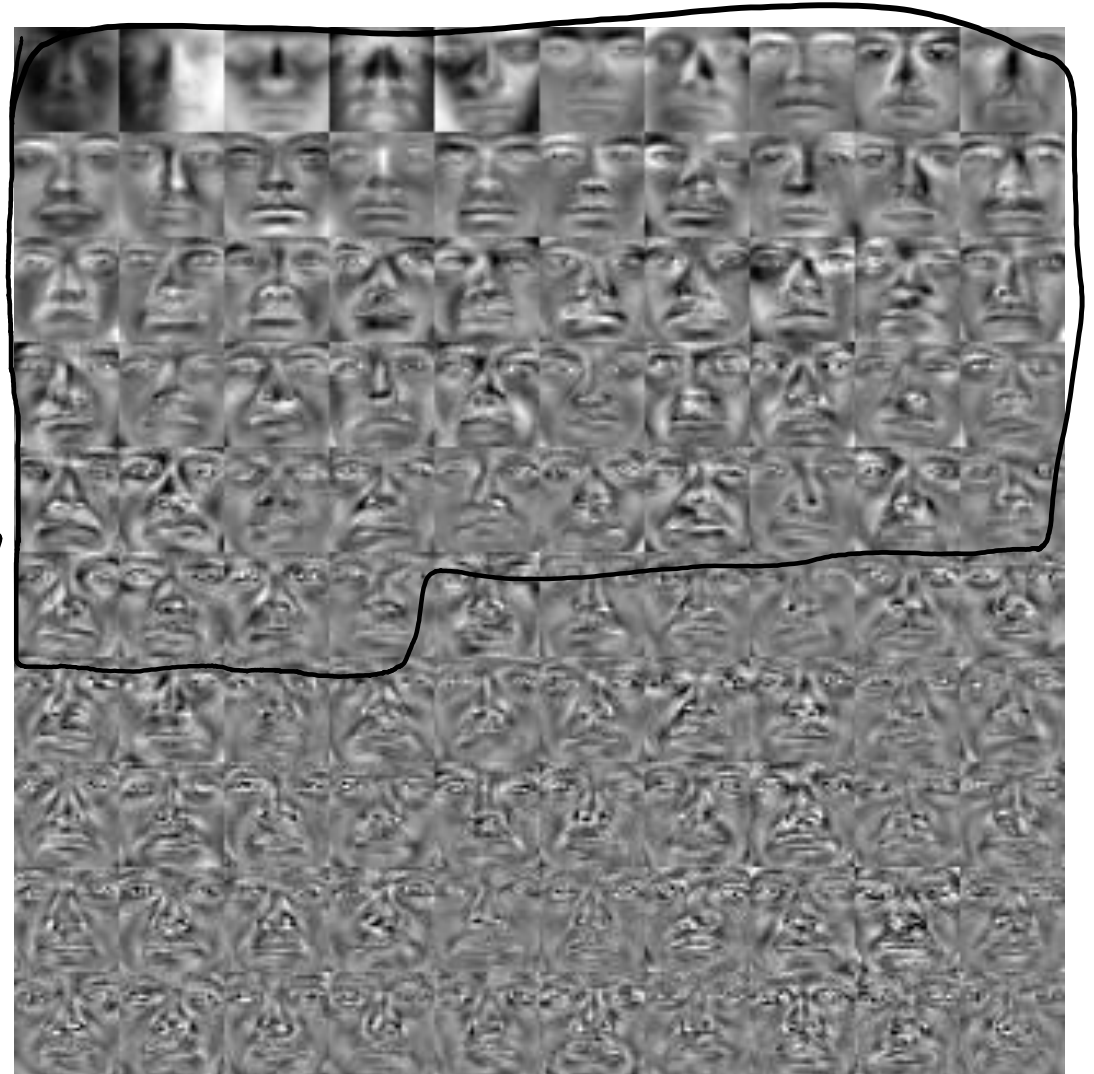


Eigenfaces

Original Images again:



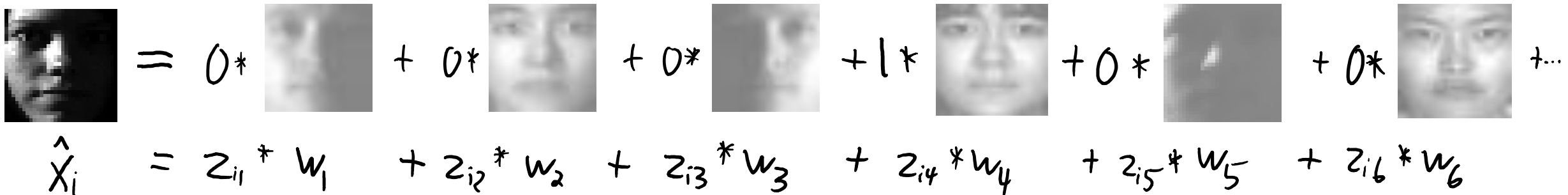
Plus these
"eigenfaces"
and
the
mean.



We can replace 1024 x_i values by 54 z_i values

VQ vs. PCA vs. NMF

- But how *should* we represent faces?
 - **Vector quantization** (k-means).
 - Replace face by the **average face in a cluster**.
 - ‘Grandmother cell’: one neuron = one face.
 - **Can’t distinguish between people** in the same cluster (only ‘k’ possible faces).
 - Almost certainly not true: too few neurons.


$$\hat{X}_i = z_{i1} * w_1 + z_{i2} * w_2 + z_{i3} * w_3 + z_{i4} * w_4 + z_{i5} * w_5 + z_{i6} * w_6 + \dots$$

VQ vs. PCA vs. NMF

- But how *should* we represent faces?
 - Vector quantization (k-means).
 - PCA (orthogonal basis).
 - Global average plus linear combination of “eigenfaces”.
 - “Distributed representation”.
 - Coded by pattern of group of neurons: can represent infinite number of faces by changing z_i .
 - But “eigenfaces” are not intuitive ingredients for faces.
 - PCA tends to use positive/negative cancelling bases.


$$\hat{X}_i = \mu + z_{i1} * w_1 + z_{i2} * w_2 + z_{i3} * w_3 + z_{i4} * w_4 + z_{i5} * w_5 + \dots$$

VQ vs. PCA vs. NMF

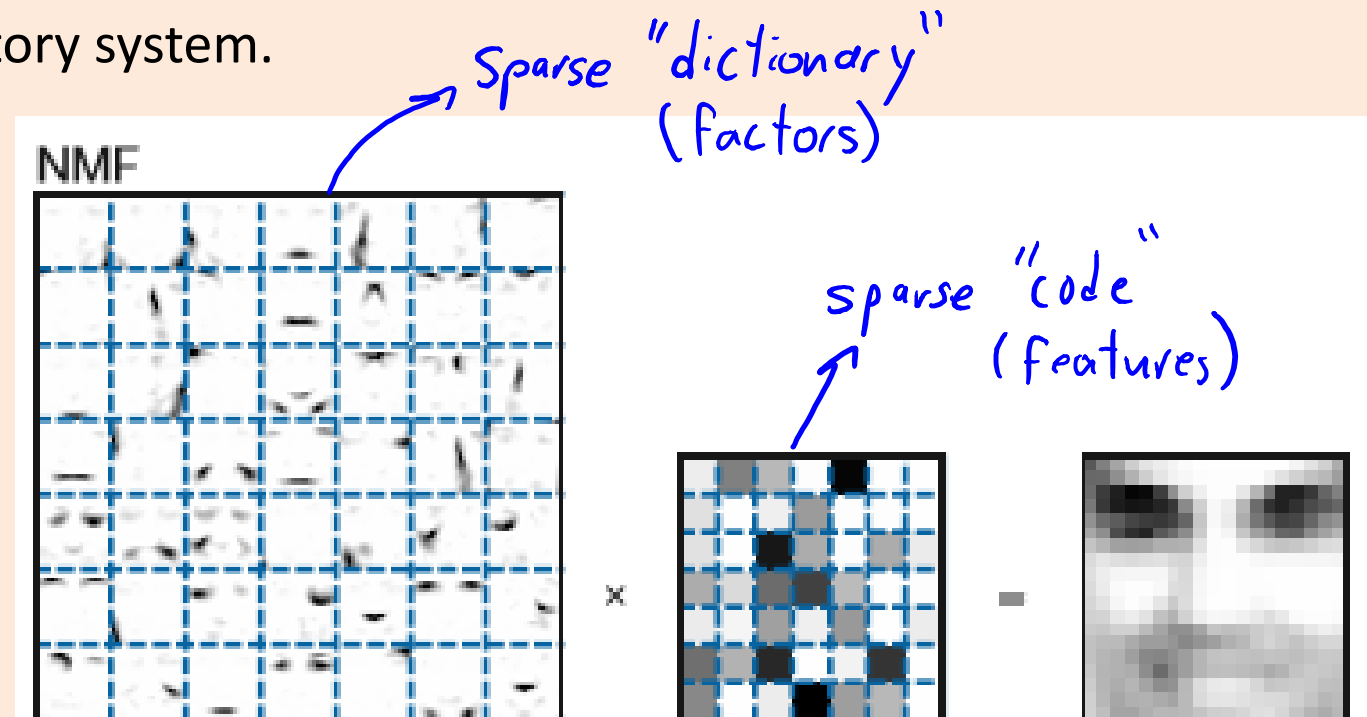
- But how *should* we represent faces?
 - Vector quantization (k-means).
 - PCA (orthogonal basis).
 - NMF (non-negative matrix factorization):
 - Instead of orthogonality/ordering in W , require W and Z to be **non-negativity**.
 - Example of “**sparse coding**”:
 - The z_i are **sparse** so each face is coded by a **small number of neurons**.
 - The w_c are **sparse** so neurons tend to be “**parts**” of the object.

$$\hat{X}_i = 4.2 * w_1 + 0 * w_2 + 0 * w_3 + 3.3 * w_4 + 0 * w_5 + \dots$$

$z_{i1} * w_1 + z_{i2} * w_2 + z_{i3} * w_3 + z_{i4} * w_4 + z_{i5} * w_5 + \dots$

Representing Faces

- Why sparse coding?
 - “Parts” are intuitive, and brains seem to use sparse representation.
 - Energy efficiency if using sparse code.
 - Increase number of concepts you can memorize?
 - Some evidence in fruit fly olfactory system.



Warm-up to NMF: Non-Negative Least Squares

- Consider our usual **least squares** problem:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w^T x_i - y_i)^2$$

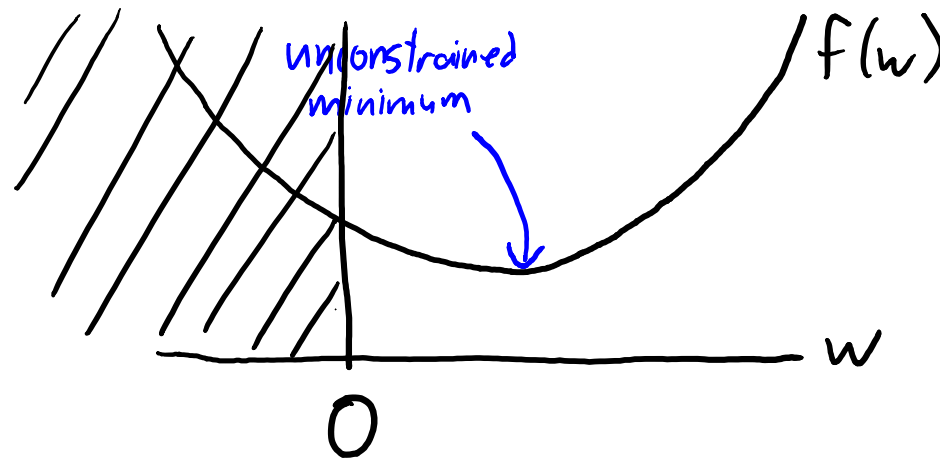
- But assume **y_i and elements of x_i are non-negative**:
 - Could be sizes ('height', 'milk', 'km') or counts ('vicodin', 'likes', 'retweets').
- Assume we want elements of ' **w** ' to be **non-negative**, too:
 - **No physical interpretation to negative weights.**
 - If x_{ij} is amount of product you produce, what does $w_j < 0$ mean?
- **Non-negativity leads to sparsity...**

Sparsity and Non-Negative Least Squares

- Consider 1D non-negative least squares objective:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w x_i - y_i)^2 \quad \text{with } w > 0$$

- Plotting the (constrained) objective function:



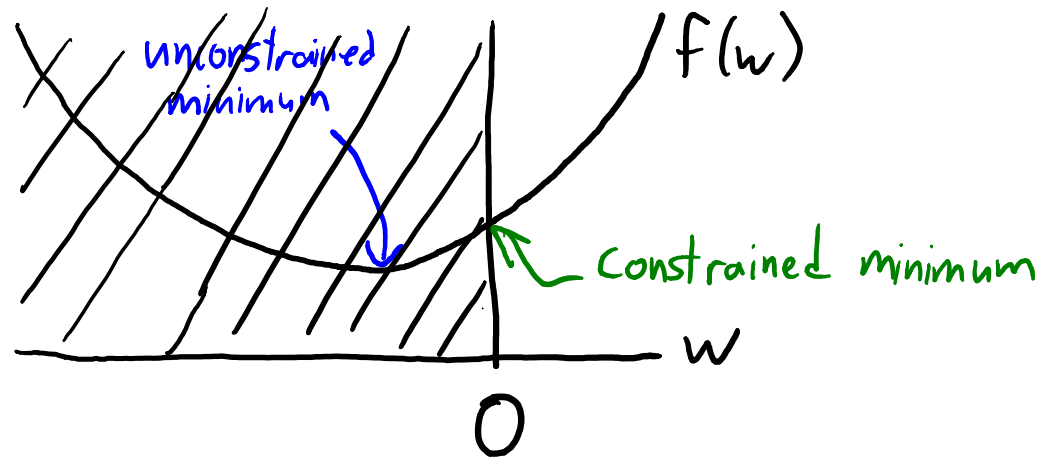
- In this case, non-negative solution is least squares solution.

Sparsity and Non-Negative Least Squares

- Consider 1D non-negative least squares objective:

$$f(w) = \frac{1}{2} \sum_{i=1}^n (w x_i - y_i)^2 \quad \text{with } w > 0$$

- Plotting the (constrained) objective function:



- In this case, **non-negative solution is $w = 0$.**

Sparsity and Non-Negativity

- Similar to L1-regularization, **non-negativity leads to sparsity**.
 - Also **regularizes**: w_j are smaller since can't "cancel" out negative values.
- How can we minimize $f(w)$ with **non-negative constraints**?
 - **Naive approach**: solve least squares problem, set negative w_j to 0.

$$\text{Compute } w = (X^T X)^{-1} (X^T y)$$

$$\text{Set } w_j = \max\{0, w_j\}$$

- This is correct when $d = 1$.
- **Can be worse than setting $w = 0$** when $d \geq 2$.

Sparsity and Non-Negativity

- Similar to L1-regularization, **non-negativity leads to sparsity**.
 - Also **regularizes**: w_j are smaller since can't “cancel” out negative values.
- How can we minimize $f(w)$ with **non-negative constraints**?
 - A correct approach is **projected gradient** algorithm:
 - Run a **gradient descent** iteration:

$$w^{t+1/2} = w^t - \alpha^t \nabla f(w^t)$$

- **After each step, set negative values to 0.**

$$w_j^{t+1} = \max\{0, w_j^{t+1/2}\}$$

- Repeat.

Sparsity and Non-Negativity

- Similar to L1-regularization, **non-negativity leads to sparsity**.
 - Also **regularizes**: w_j are smaller since can't "cancel" out negative values.
- How can we minimize $f(w)$ with **non-negative constraints**?
 - A correct approach is **projected gradient** algorithm:

$$w^{t+1/2} = w^t - \alpha^t \nabla f(w^t)$$

$$w_j^{t+1} = \max\{0, w_j^{t+1/2}\}$$

– Similar properties to gradient descent:

- Guaranteed decrease of 'f' if α_t is small enough.
- Reaches local minimum under weak assumptions (global minimum for convex 'f').
 - Least squares objective is still convex when restricted to non-negative variables.
- Generalizations allow things like **L1-regularization** instead of non-negativity.

(findMinL1.m)

Projected-Gradient for NMF

- Back to the **non-negative matrix factorization (NMF)** objective:

$$f(W, Z) = \sum_{i=1}^n \sum_{j=1}^d ((w^{(j)})^T z_i - x_{ij})^2 \quad \text{with } w_{cj} \geq 0 \text{ and } z_{ij} \geq 0$$

– Different ways to use **projected gradient**:

- Alternate between projected gradient steps on 'W' and on 'Z'.
- Or run projected gradient on both at once.
- Or sample a random 'i' and 'j' and do **stochastic projected gradient**.

Set $z_i^{t+1} = z_i^t - \alpha^t \nabla_{z_i} f(W, Z)$ and $(w^{(j)})^{t+1} = (w^{(j)})^t - \alpha^t \nabla_{w^{(j)}} f(W, Z)$ for selected i and j

– **Non-convex** and (unlike PCA) is sensitive to initialization.

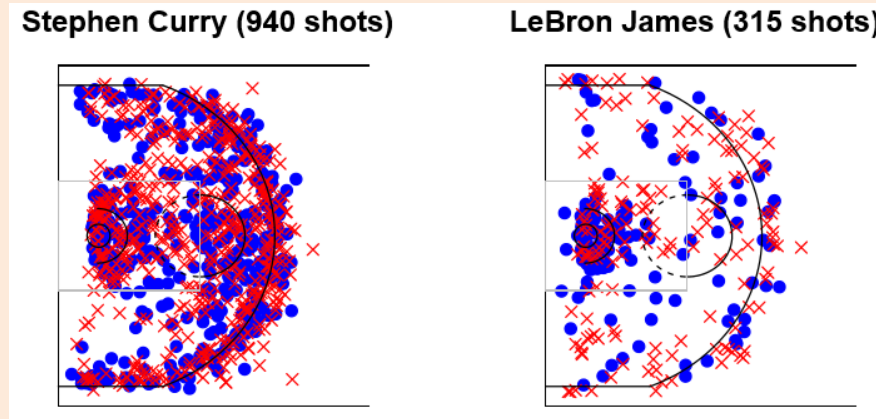
- Hard to find the global optimum.
- Typically use **random initialization**.

(keep other values of W and Z fixed)

Then set negative values to 0.

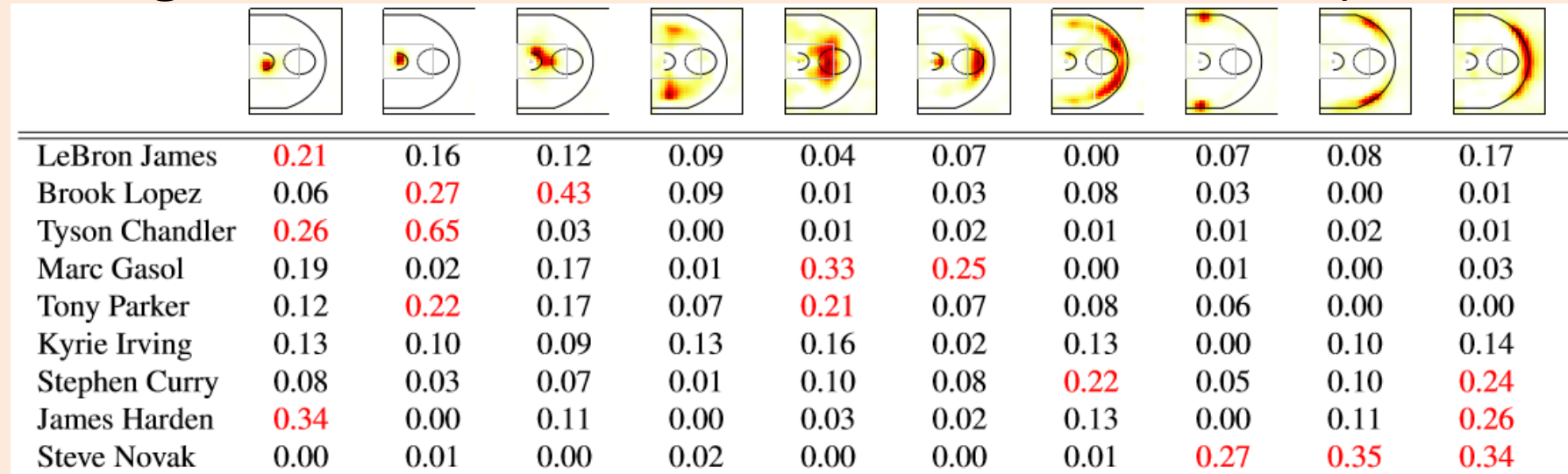
Application: Sports Analytics

- NBA shot charts:



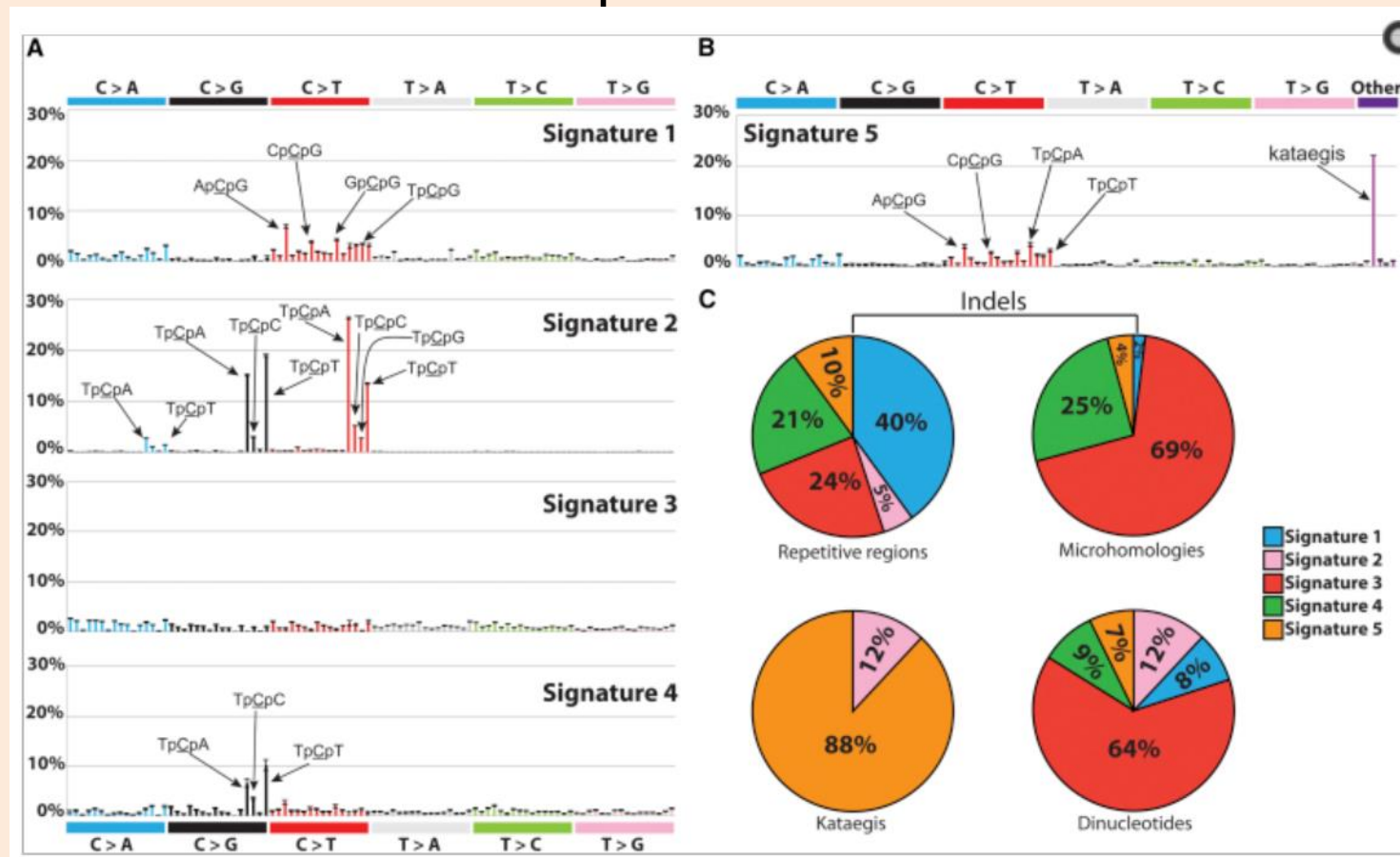
- NMF (using “KL divergence” loss with $k=10$ and smoothed data).

– Negative values would not make sense here.



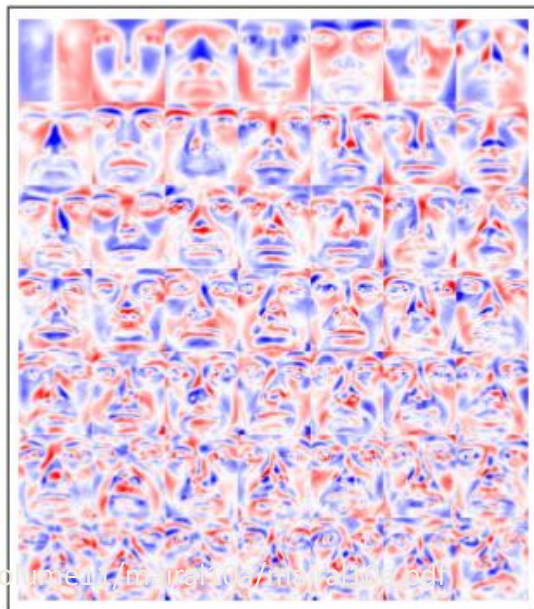
Application: Cancer “Signatures”

- What are common sets of mutations in different cancers?
 - May lead to new treatment options.

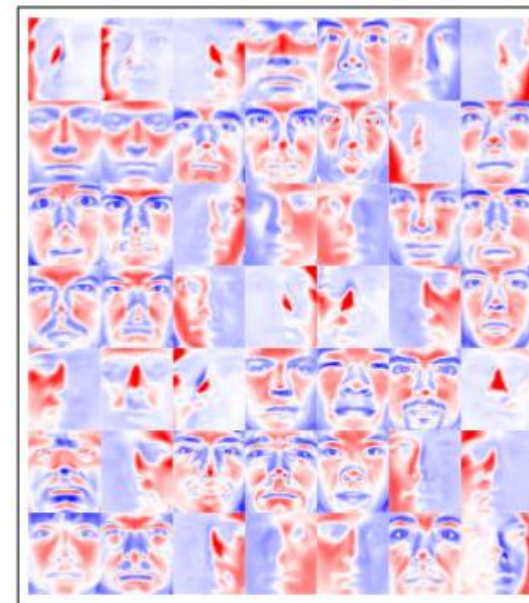


Regularized Matrix Factorization

- For many PCA applications, ordering orthogonal PCs makes sense.
 - Latent factors are independent of each other.
 - We definitely want this for visualization.
- In other cases, ordering orthogonal PCs doesn't make sense.
 - We might not expect a natural "ordering".



Usual
orthogonal
eigen faces



PCA with
non-orthogonal
basis.

Regularized Matrix Factorization

- More recently people have considered **L2-regularized PCA**:

$$f(W, Z) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda_1}{2} \|W\|_F^2 + \frac{\lambda_2}{2} \|Z\|_F^2$$

- **Replaces normalization/orthogonality/sequential-fitting.**
 - But requires **regularization parameters** λ_1 and λ_2 .
- **Need to regularize W and Z** because of scaling problem:
 - **If you only regularize 'W' it doesn't do anything:**
 - I could take unregularized solution, replace W by αW for a tiny α to shrink $\|W\|_F$ as much as I want, then multiply Z by $(1/\alpha)$ to get same solution.
 - Similarly, if you only regularize 'Z' it doesn't do anything.

Sparse Matrix Factorization

- Instead of non-negativity, we could use L1-regularization:

$$f(W, Z) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda_1}{2} \sum_{i=1}^n \|z_i\|_1 + \frac{\lambda_2}{2} \sum_{j=1}^d \|w_j\|_1$$

- Called **sparse coding** (L1 on 'Z') or **sparse dictionary learning** (L1 on 'W').
- **Disadvantage of using L1-regularization** over non-negativity:
 - Sparsity controlled by λ_1 and λ_2 so you need to set these.
- **Advantage of using L1-regularization:**
 - Negative coefficients usually make sense.
 - Sparsity controlled by λ_1 and λ_2 , so you can **control amount of sparsity**.

Sparse Matrix Factorization

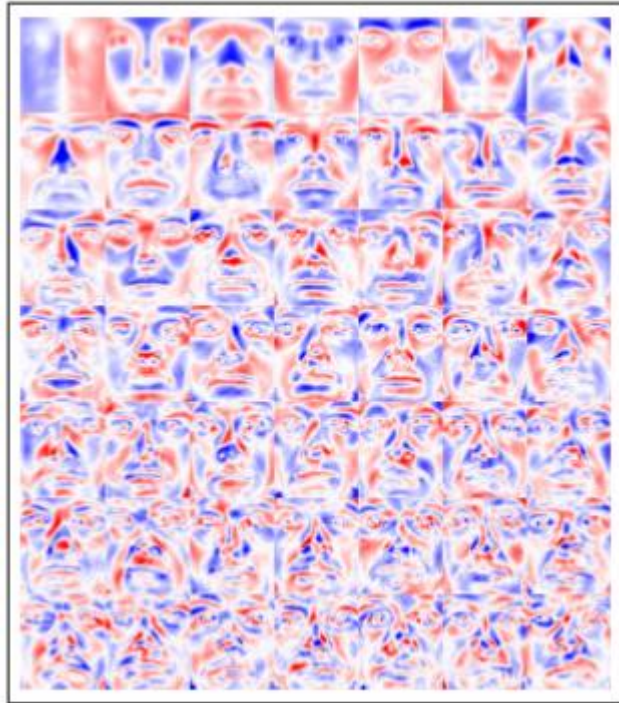
- Instead of non-negativity, we could use L1-regularization:

$$f(W, Z) = \frac{1}{2} \|ZW - X\|_F^2 + \frac{\lambda_1}{2} \sum_{i=1}^n \|z_i\|_1 + \frac{\lambda_2}{2} \sum_{j=1}^d \|w_j\|_1$$

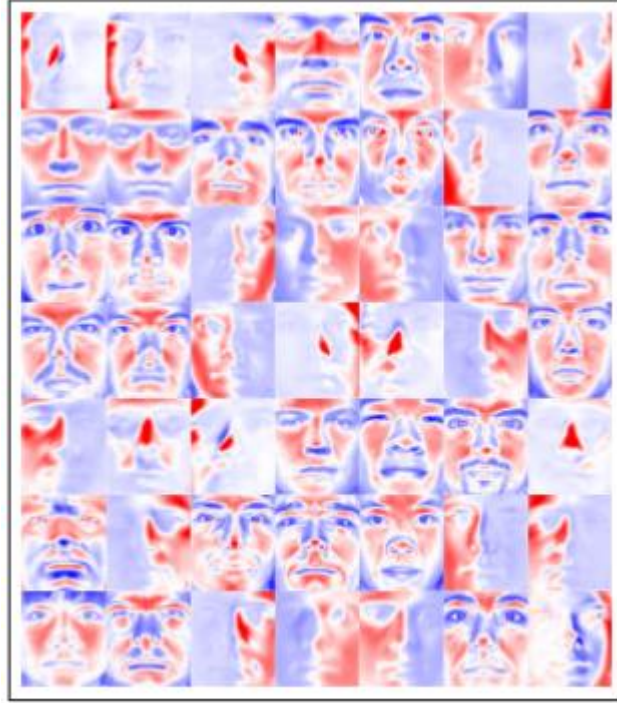
- Called **sparse coding** (L1 on 'Z') or **sparse dictionary learning** (L1 on 'W').
- Many variations exist:
 - Mixing L2-regularization and L1-regularization.
 - Or normalizing 'W' (in L2-norm or L1-norm) and regularizing 'Z'.
 - **K-SVD** constrains each z_i to have at most 'k' non-zeroes:
 - K-means is special case where $k = 1$.
 - PCA is special case where $k = d$.

Matrix Factorization with L1-Regularization

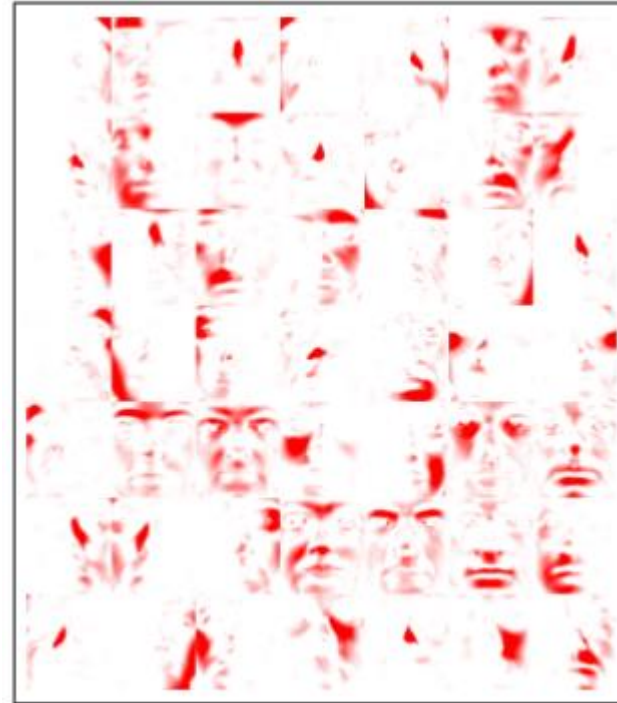
blue: negative
red: positive



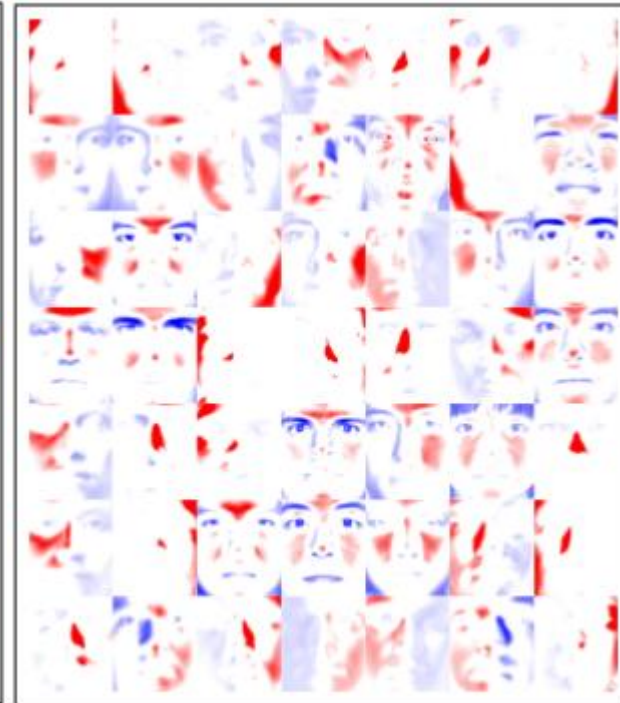
(a) PCA



(e) Dictionary Learning



(c) NMF



(d) SPCA, $\tau = 30\%$

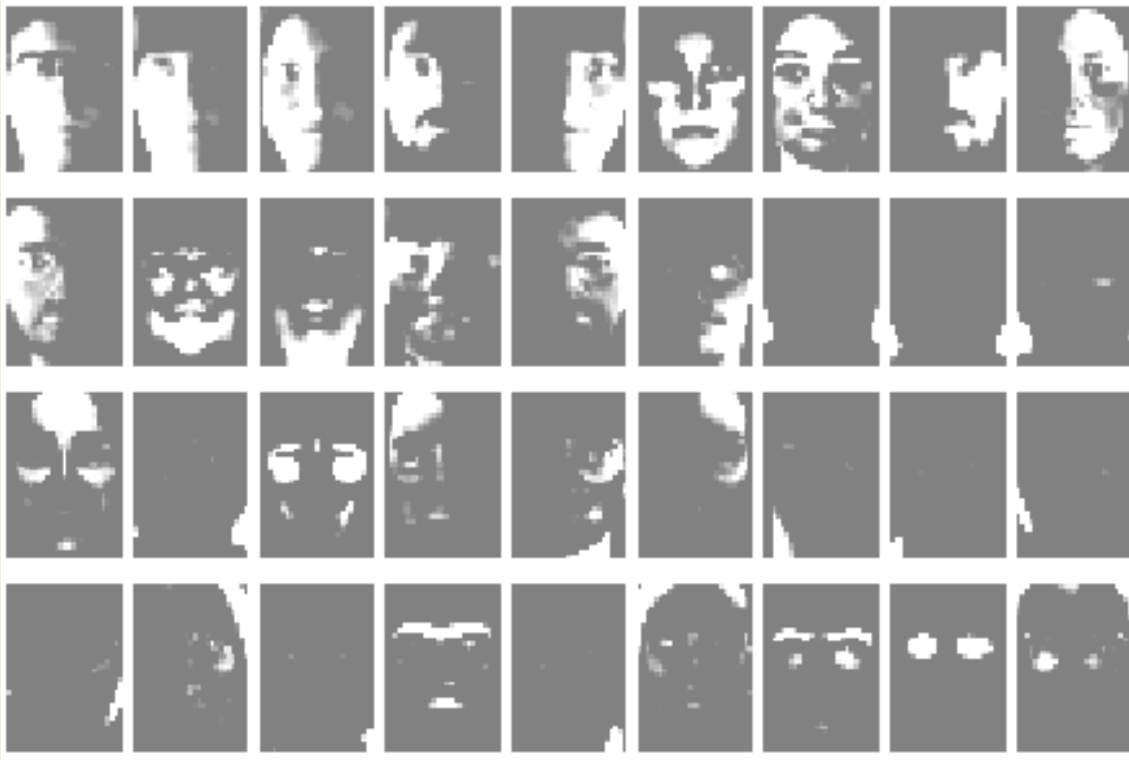
PCA without orthogonality

sparsity due to non-negativity

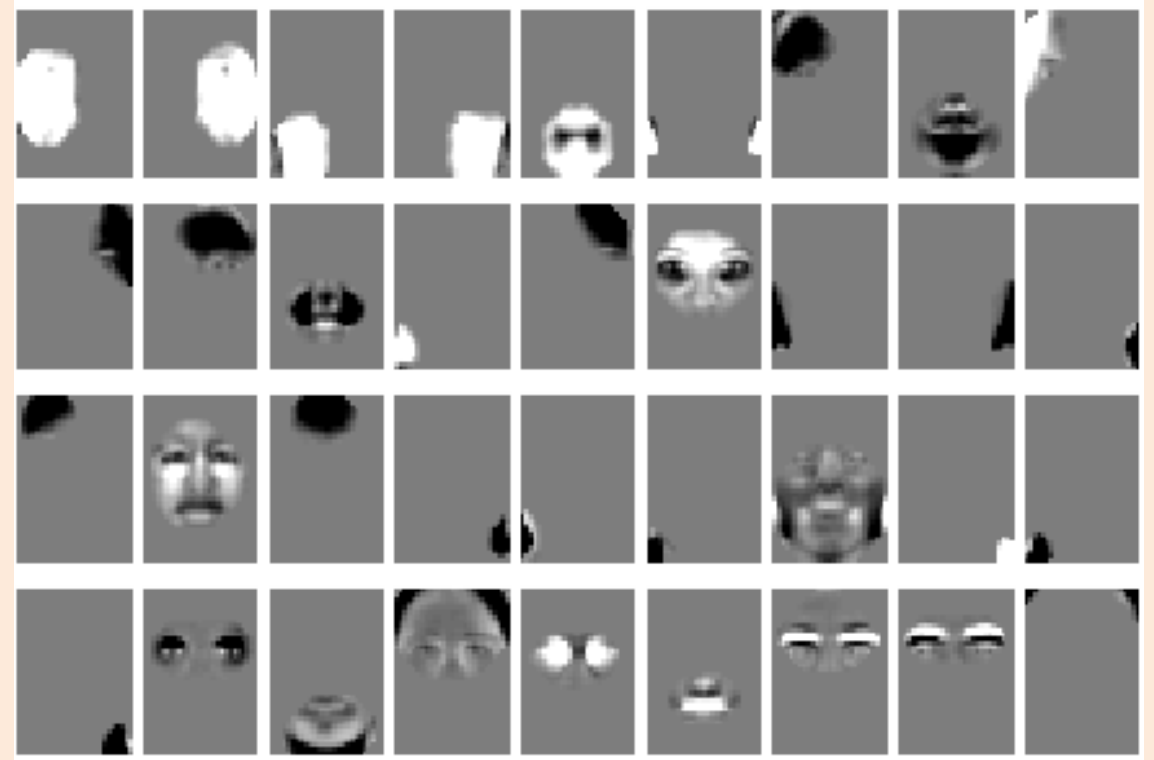
sparsity due to L_1 -regularization

Recent Work: Structured Sparsity

- “**Structured sparsity**” considers dependencies in sparsity patterns.
 - Can enforce that “parts” are convex regions.



NMF



Sparse PCA with “structured” sparsity

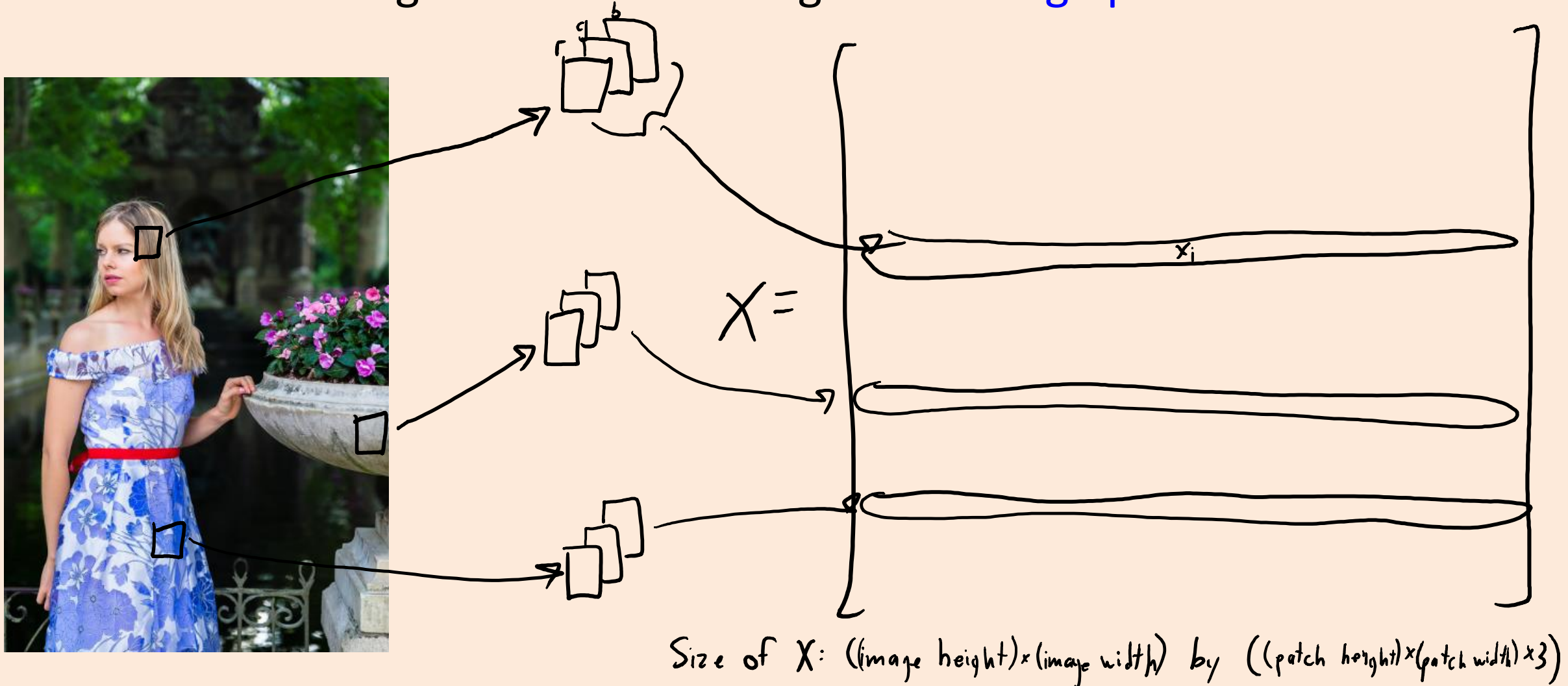
Summary

- **Biological motivation** for orthogonal and/or sparse latent factors.
- **Non-negative matrix factorization** leads to sparse LFM.
- **Non-negativity** constraints lead to sparse solution.
 - **Projected gradient** adds constraints to gradient descent.
 - **Non-orthogonal LFMs** make sense in many applications.
- **L1-regularization** leads to other sparse LFMs.

- Next time: the NetFlix challenge.

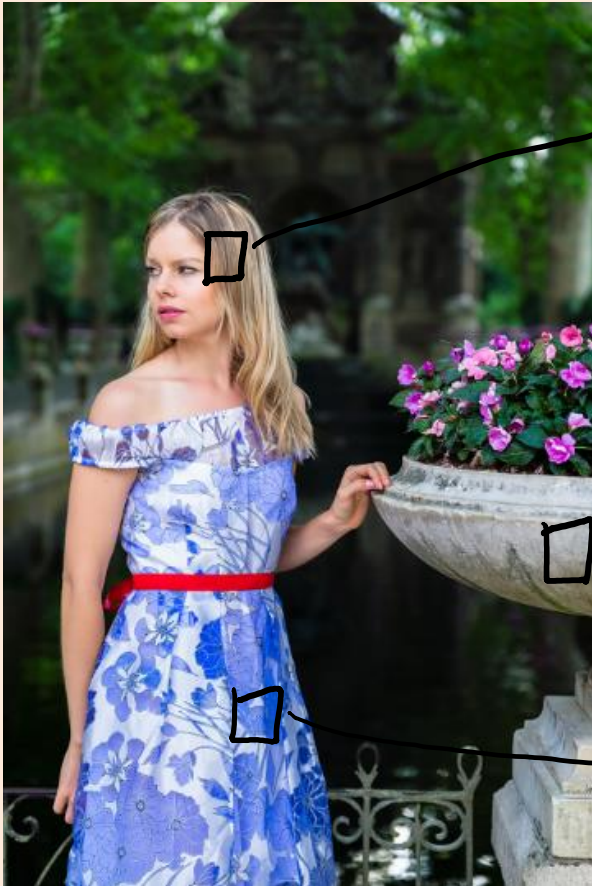
Latent-Factor Models for Image Patches

- Consider building latent-factors for general **image patches**:



Latent-Factor Models for Image Patches

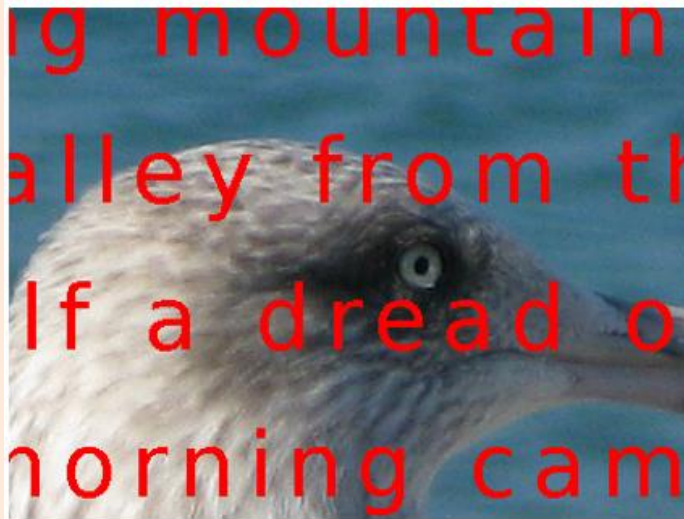
- Consider building latent-factors for general **image patches**:



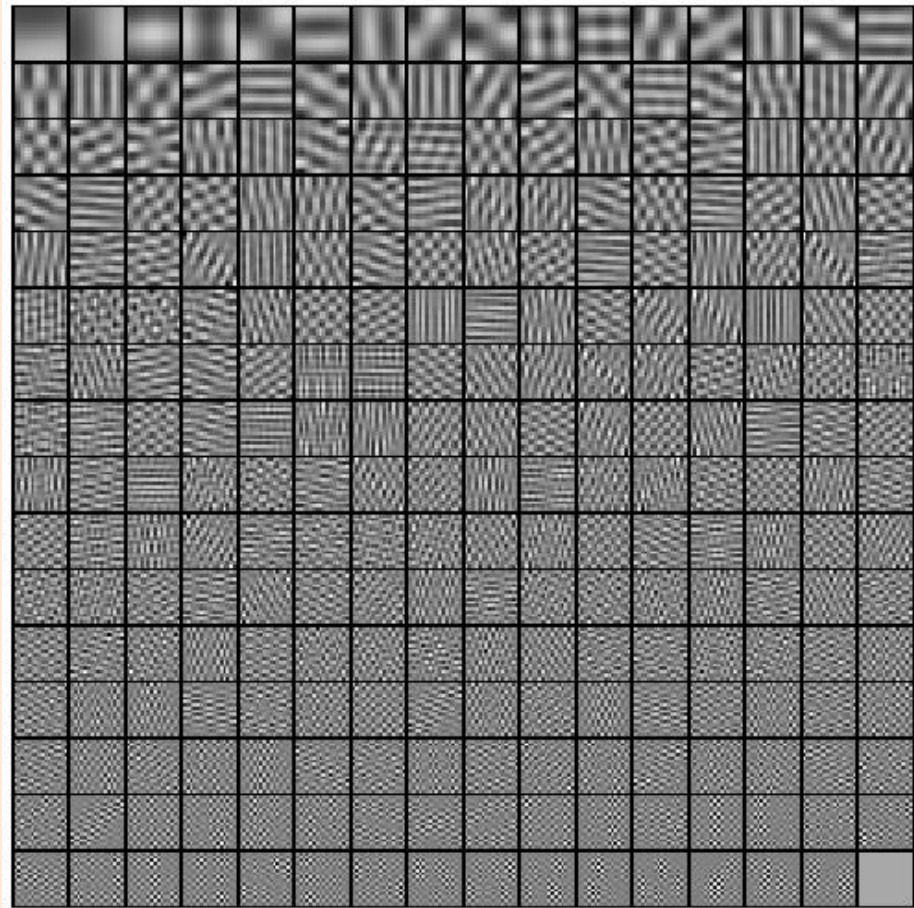
Typical pre-processing:

1. Usual variable centering
2. “Whiten” patches.
(remove correlations)

Application: Image Restoration



Latent-Factor Models for Image Patches

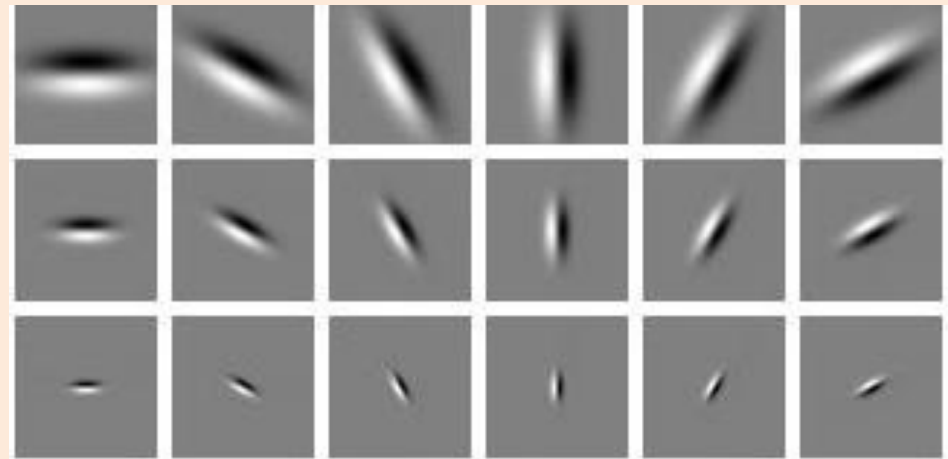


(b) Principal components.

Orthogonal bases don't seem right:

- Few PCs do almost everything.
- Most PCs do almost nothing.

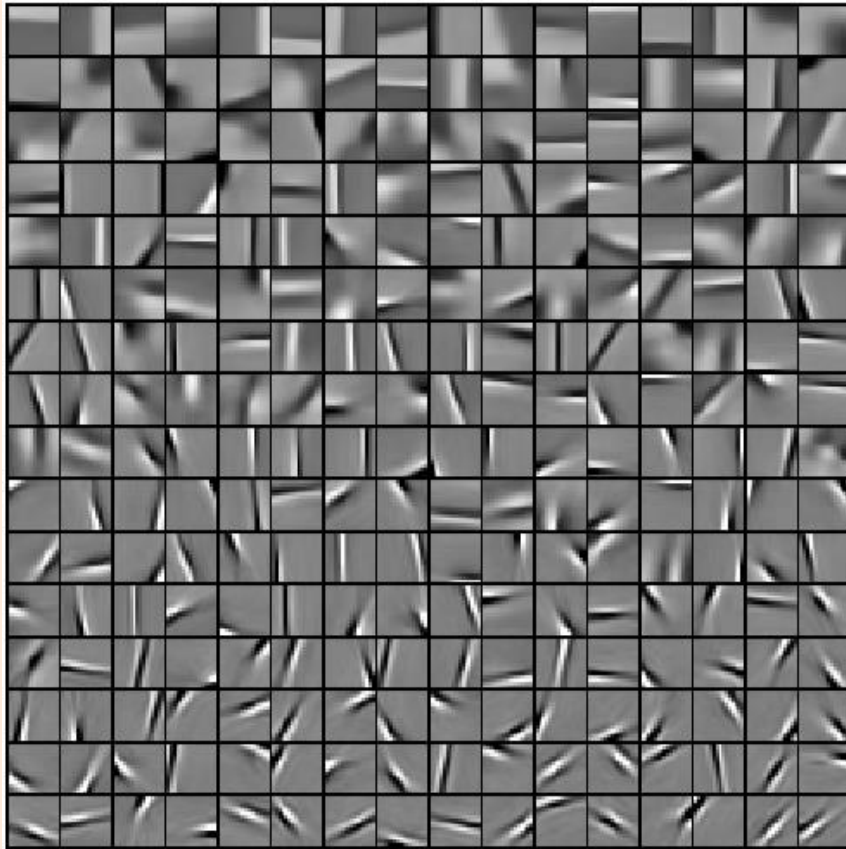
We believe “simple cells” in visual cortex use:



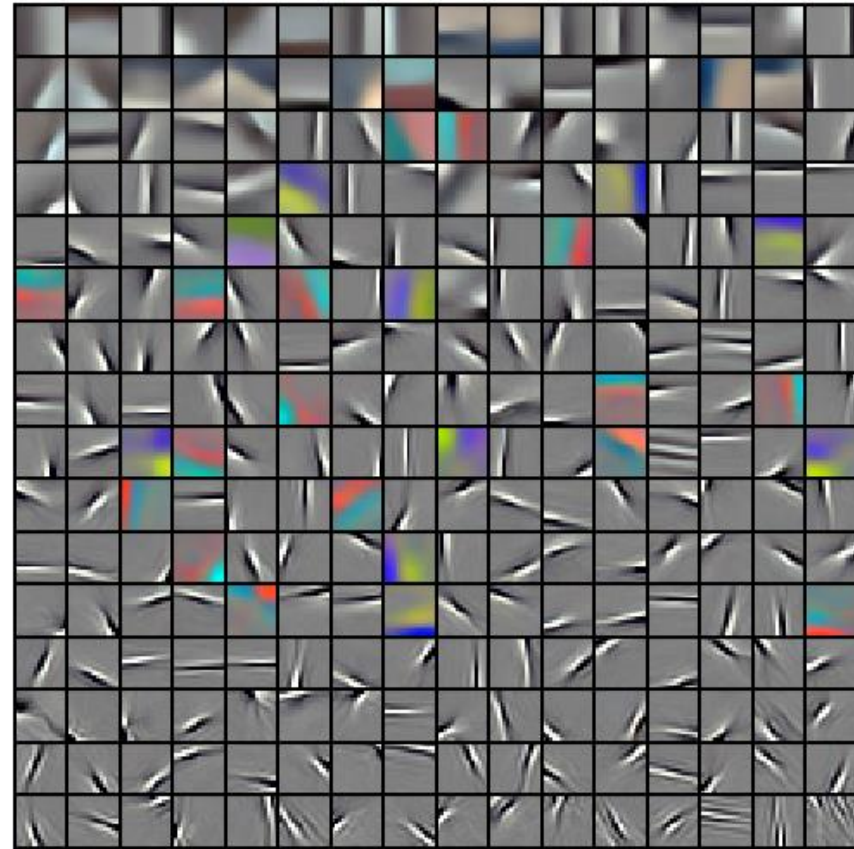
'Gabor' filters

Latent-Factor Models for Image Patches

- Results from a sparse (non-orthogonal) latent factor model:



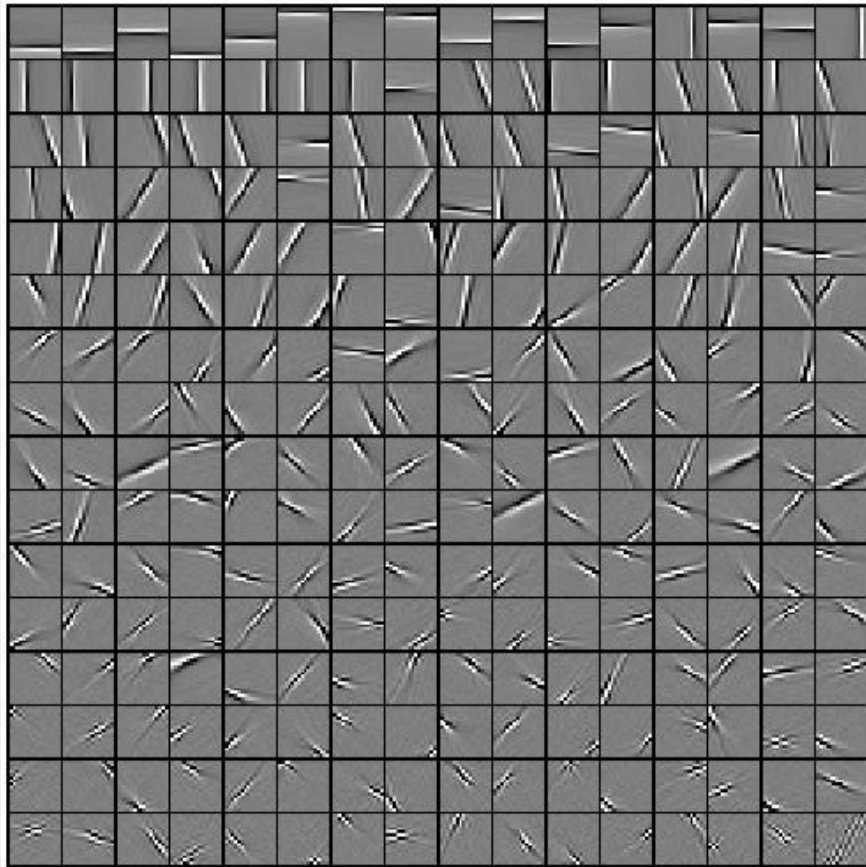
(a) With centering - gray.



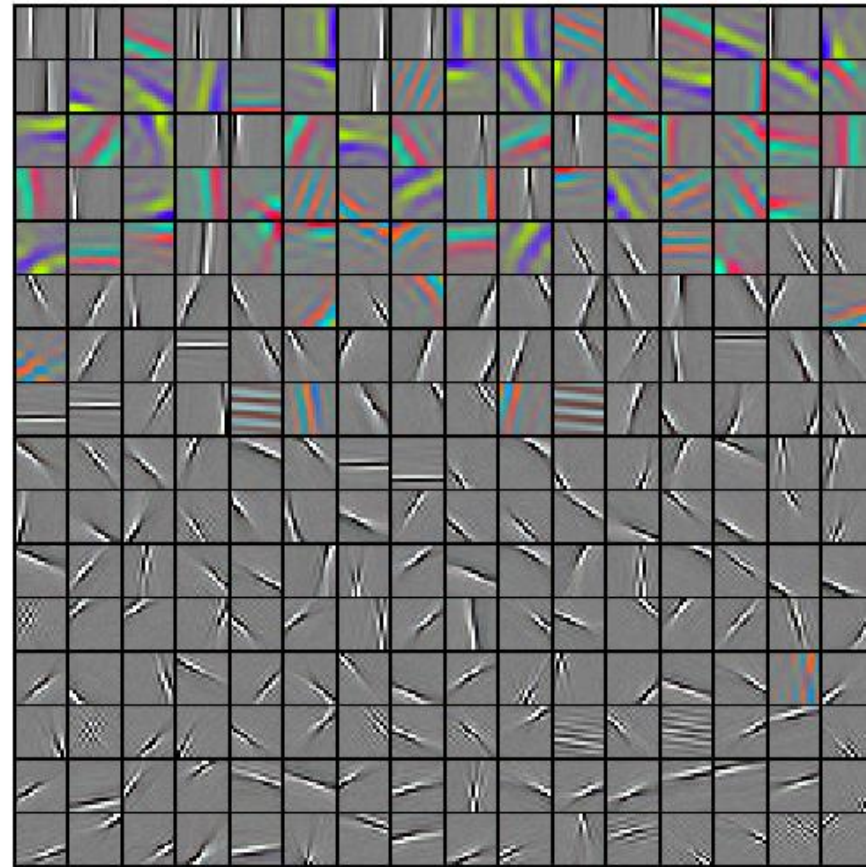
(b) With centering - RGB.

Latent-Factor Models for Image Patches

- Results from a “sparse” (non-orthogonal) latent-factor model:



(c) With whitening - gray.

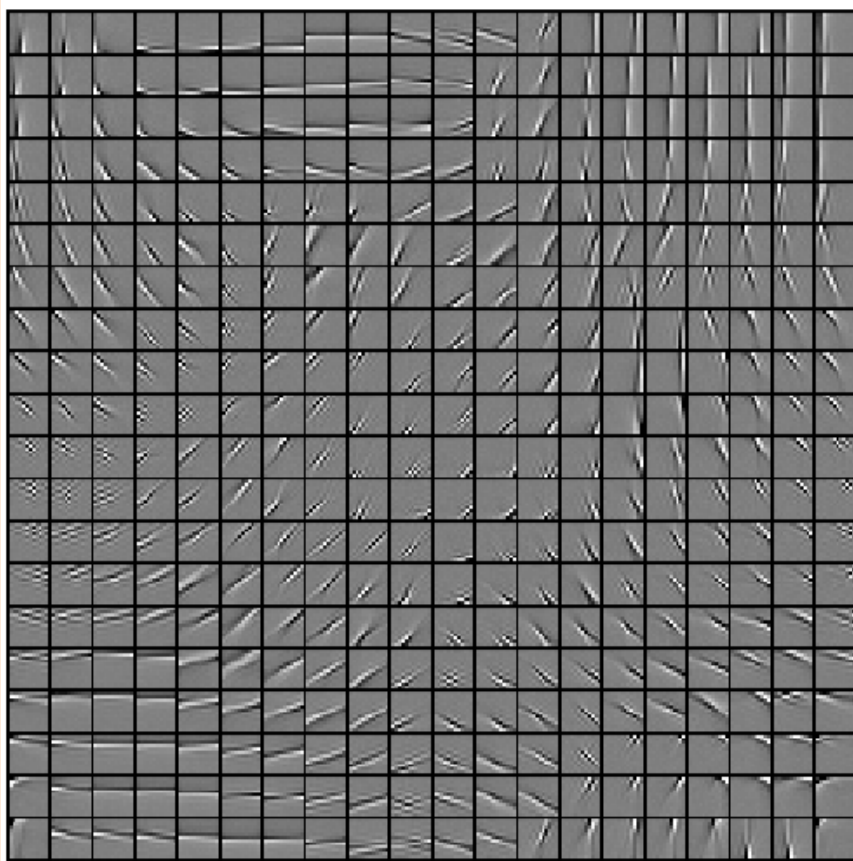


(d) With whitening - RGB.

“colour opponency”

Recent Work: Structured Sparsity

- Basis learned with a variant of “structured sparsity”:



(b) With 4×4 neighborhood.

Similar to “cortical columns”
theory in visual cortex.