

Tutorial 4

CPSC 340

Overview

Vector Quantization with K-means

Vector Quantization

Example

DBSCAN

DBSCAN Algorithm

DBSCAN Algorithm

Linear Algebra Review

Exercises

Vector Quantization with K-means

- ▶ Two motivations for clustering
 - Discovering object groups
 - Vector quantization
- ▶ Vector quantization:
 - Find a prototype for each cluster
 - Replace points in the cluster by their prototype
- ▶ Vector quantization with K-means:
 - Apply K-means
 - ▶ Define groups by means
 - ▶ Assign objects to nearest mean
 - Replace objects with the mean of their group

Example - Image Color Space Compression

- ▶ RGB representation
 - 24 bits per pixel (three 8-bit numbers)
- ▶ Compress color space: reduce the bits required per pixel
 - Find prototype colors, replace pixels by prototypes
 - b bits per pixel, $k = 2^b$ clusters



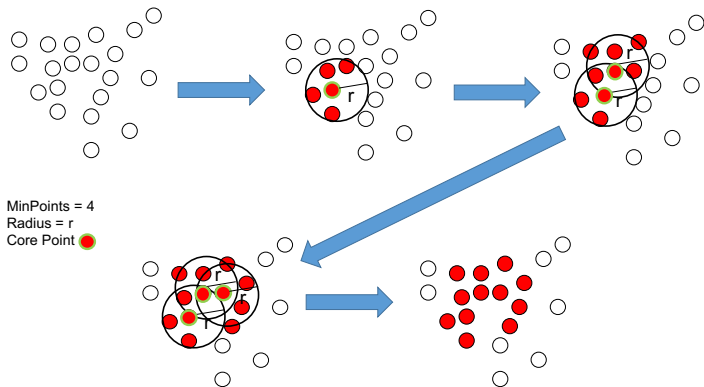
Figure: Taken from <http://opencvpython.blogspot.ca/2012/12/k-means-clustering-2-working-with-scipy.html>

DBSCAN

- ▶ A density-based clustering algorithm
 - Clusters are defined by all the objects in dense regions
 - Objects in non-dense regions don't get clustered.
 - Non-parametric (no fixed k)
- ▶ DBSCAN Parameters
 - **Radius**: maximum distance between points to be considered close
 - ▶ Points within this radius called **reachable**
 - **MinPoints**: number of reachable points needed to define a cluster
 - ▶ A point that has minPoints reachable points is called a **core point**
- ▶ DBSCAN Algorithm
 - Each core point defines a cluster
 - Merge clusters if core points are reachable from each other.

DBSCAN Algorithm

- ▶ Each core point defines a cluster
- ▶ Merge clusters if core points are reachable from each other.



Exercise 1

Let $\alpha = 2$, $x = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$, $y = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$, $z = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$, $A = \begin{bmatrix} 3 & 5 & 1 \\ 2 & 3 & 4 \end{bmatrix}$

1. x^T
2. $\alpha(x + y)$ (vector addition and scalar multiplication)
3. $x^T y + \|x\|^2$ (inner product and norm $\|x\|_2^2 = x^T x$)
4. A^T
5. Ax (matrix-vector multiplication)
6. $A^T A$ (matrix-matrix multiplication)

Exercise 2

$\{x, y, z\}$ are real-valued column vectors (of the same length) and $\{A, B, C\}$ are real-valued matrices such that the additions/multiplications below have the right dimensions, which two of the following are not true in general?

1. $x^T y = y^T x$

2. $x^T A y = y^T A^T x$

3. $x^T (y + z) = x^T y + x^T z$

4. $x^T (y^T z) = (x^T y)^T z$

5. $A + (B + C) = C + (A + B)$

6. $A(BC) = (AB)C$

7. $A(B + C) = AB + AC$

8. $AB = BA$

9. $(AB)^T = B^T A^T$

Vector notation and inner product

- ▶ Column Vector (m by 1): $w = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \end{bmatrix}$
- ▶ Row Vector (1 by n): $w^T = [w_1 \quad w_2 \quad w_3 \quad w_4]$
- ▶ The **inner product** between vectors of the same length is:

$$x^T w = \sum_{i=1}^n x_i w_i = x_1 w_1 + x_2 w_2 + \cdots + x_n w_n = \gamma$$

Sum notation to vector notation

Let $X = \begin{bmatrix} x_{11} & x_{12} & x_{13} & x_{14} \\ x_{21} & x_{22} & x_{23} & x_{24} \\ x_{31} & x_{32} & x_{33} & x_{34} \end{bmatrix}$ and $w = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \end{bmatrix}$. Compute x_1, x_1^T ,
and $y = Xw$.

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$$y = Xw = \begin{bmatrix} x_{11} & x_{12} & x_{13} & x_{14} \\ x_{21} & x_{22} & x_{23} & x_{24} \\ x_{31} & x_{32} & x_{33} & x_{34} \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^4 x_{1j}w_j \\ \sum_{j=1}^4 x_{2j}w_j \\ \sum_{j=1}^4 x_{3j}w_j \end{bmatrix} = \begin{bmatrix} x_1^T w \\ x_2^T w \\ x_3^T w \end{bmatrix}$$

$$y_i = x_i^T w$$

Vector and matrix notation

- ▶ Let $f(x_1, x_2, x_3) = 2x_1 + 4x_2 + 8x_3$

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$$- f(x) = w^T x \text{ with } x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, w = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}.$$

- ▶ Let

$$\begin{aligned} 4x_1 - 5x_2 &= -13 \\ -2x_1 + 3x_2 &= 9. \end{aligned}$$

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$$- Ax = b \text{ with } A = \begin{bmatrix} 4 & -5 \\ -2 & 3 \end{bmatrix}, b = \begin{bmatrix} -13 \\ 9 \end{bmatrix}$$

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► In matrix notation?

– $f(x) = x^T Ax$ with $x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$, $A = \begin{bmatrix} 4 & 3 \\ 3 & 6 \end{bmatrix}$.