Visual Al

Deep learning models for Computer Graphics and

Computer Vision

CPSC 533R - 2020/2021 Term 1

Helge Rhodin



Visual Al

CPSC 533R - 2020/2021

Lecture 1. Overview and programming environment

Helge Rhodin



Helge Rhodin





Organization



Instructor: Helge Rhodin rhodin@cs.ubc.ca

Office hours: TBD Room: Zoom (via Canvas)



Teaching assistant: Yuchi Zhang yuchi45@cs.ubc.ca

Office hours:



TBD: <u>https://doodle.com/poll/qynygb3daznvqtgy</u> Room: Zoom (via Canvas)

Course Website

Curriculum	https://www.cs.ubc.ca/~rhodin/2020_2021_CPSC_533R/
Forum	https://piazza.com/ubc.ca/winterterm12020/cpsc533R
Canvas	https://canvas.ubc.ca/courses/53581

Official Disclaimer



Keep in mind that some UBC courses might cover topics that are censored or considered illegal by non-Canadian governments. This may include, but is not limited to, human rights, representative government, defamation, obscenity, gender or sexuality, and historical or current geopolitical controversies. If you are a student living abroad, you will be subject to the laws of your local jurisdiction, and your local authorities might limit your access to course material or take punitive action against you. UBC is strongly committed to academic freedom, but has no control over foreign authorities (please visit http://www.calendar.ubc.ca/vancouver/index.cfm?tree=3,33,86,0 for an articulation of the values of the University conveyed in the Senate Statement on Academic Freedom). Thus, we recognize that students will have legitimate reason to exercise caution in studying certain subjects. If you have concerns regarding your personal situation, consider postponing taking a course with manifest risks, until you are back on campus or reach out to your academic advisor to find substitute courses. For further information and support, please visit: http://academic.ubc.ca/support-resources/freedom-expression

Computer graphics, computer vision and machine learning





Overview

- 9 Lectures (~ once a week)
 - Introduction
 - Deep learning basics and best practices
 - Network architectures for image processing
 - Representing images and sparse 2D keypoints
 - Representing dense and 3D keypoints
 - Representing geometry and shape
 - Representation learning
 - Unpaired image translation
 - Attention models
- 3x Assignments
 - Playing with pytorch (5% of points)
 - Pose estimation (10% of points)
 - Shape generation (10% of points)



- 1x Paper presentation (Weeks 3 12)
 - Presentation, once per student (25% of points) (15 min + 15 min discussion)
 - Read and review one out of the two papers presented per session (10% of points)
- 1x Project (40 % of points)
 - Project pitch (3 min, week 6&7)
 - Project presentation (10 min, week 13&14)
 - Project report (6 pages, Dec 14)

Computer Vision Topics



A few examples

Object detection





[Redmon et al., YOLO: Real-Time Object Detection, CVPR 2016] detection + offset regression

CPSC 532R/533R - Visual AI - Helge Rhodin

Instance segmentation





[He et al., Mask R-CNN, ICCV 2017] detection & pixel classification

CPSC 532R/533R - Visual AI - Helge Rhodin

3D Human pose estimation





[VNect: Real-time 3D Human Pose Estimation with a Single RGB Camera, SIGGRAPH 2017] Regression + 2D&3D skeleton fitting

Surface reconstruction





[MonoPerfCap: Human Performance Capture from Monocular Video, TOG 2018]

Computer Graphics Topics



A few examples

Computer Graphics



Classic CG Illumination & reflectance Texture mapping

Learning-based CG



[Facebook AI Research]

[Utah teapot, www.reallusion.com, www.turbosquid.com]

CPSC 532R/533R - Visual AI - Helge Rhodin

Facial reenactment





Live capture using a commodity webcam



Input Target

Tracking Target

Expr. Transfer

[Face2Face: Real-time Face Capture and Reenactment of RGB Videos, CVPR 2016]

Geometry based, no machine learning!

CPSC 532R/533R - Visual AI - Helge Rhodin

Novel view synthesis



Overview



Learning a geometry-aware representation from multiple-views

[Unsupervised Geometry-Aware Representation Learning for 3D Human Pose Estimation, ECCV 2018]

Disentangled appearance and pose







Latent space interpolation



Image interpolation

Appearance swap

GAN Paint – conditional image generation

Online demo: <u>http://ganpaint.io/demo/?project=church</u>







[Semantic Photo Manipulation with a Generative Image Prior, SIGGRAPH 2019] CPSC 532R/533R - Visual AI - Helge Rhodin







NVIDIA GauGAN Segmentation Input

Jama Jurabaev, Concept Designer and Art Director Star Wars: The Mandalorian, Jurassic World 2, Ready Player One, Avengers

[Semantic Image Synthesis with Spatially-Adaptive Normalization, CVPR 2019]

CPSC 532R/533R - Visual AI - Helge Rhodin

Puppeteering





[Interactive Motion Mapping for Real-time Character Control, Eurographics 2014]

CPSC 532R/533R - Visual AI - Helge Rhodin

Character animation



User Control



CPSC 532R/533R - Visual AI - Helge Rhodin

[Phase-Functioned Neural Networks for Character Control, SIGGRAPH 2017]

Computer Graphics & Computer Vision Topics



Example topics





StyleGAN – generating images from noise





Result of combining A and B

everything else

CPSC 532R/533R - Visual AI - Helge Rhodin

HoloGAN – providing viewpoint control







Azimuth

[HoloGAN: Unsupervised learning of 3D representations from natural images, ICCV 2019]

CPSC 532R/533R - Visual AI - Helge Rhodin

Discussion



• What other topics do you know?

• Which ones are interesting?

• Which ones are hard to solve with machine learning, which ones are easy?

• Black lives matter!

Break



Register on Piazza, get to know your neighbor, discuss

Prime conferences



Graphics

- SIGGRAPH
- SIGGRAPH Asia
- Eurographics (EG)
- Journals: TOG and CFG
- Computer vision
- Conference on Computer Vision and Pattern Recognition (CVPR)
- International Conference on Computer Vision (ICCV)
- European Conference on Computer Vision (ECCV) every second year, alternates with ICCV
- Journals: IJCV and TPAMI
- Machine learning
- Conference on Neural Information Processing (NeurIPS)
- International Conference on Machine Learning (ICML)
- International Conference on Learning Representations (ICLR)

Underlying ML Methods



Deep learning models = architecture?





[Alex Net]

Deep learning models for computer graphics and computer vision





Logistics



Visual AI - Goals



Get to know and advance the state-of-the-art in Visual Computing

- Computer Graphics
- Computer Vision
- towards Visual AI
- Practice machine learning (ML)
 - From design through implementation to evaluation
 - Become a PyTorch and ML expert (PyTorch = deep learning framework)
 - tricks, hacks, gems, best practices, ...
- Prepare you for academia (my group?!) and industry
 - independently complete a mini research project
 - become a researcher





Syllabus



Talks will be assigned once all students are enrolled

- Until then: open for paper suggestions
- Choose a project topic before the project pitch (~mid term)

Topics in Computer Graphics / AI (CPSC 533R)

Winter Term 1, 2020/2021 - Preliminary Schedule

Date	Content	Reading
Sept 8 (week 1)	UBC Welcome day, no class	
Sept 10	Introduction The first lecture will be on zoom, access via Canvas or mail me for the link. - Challenges in using deep learning for creative tasks - Course expectations and grading - First steps in PyTorch Homework 1 release	SIGGRAPH p <u>rogram</u> / trailer Pytorch intro
Sep 15 (week 2)	Deep learning basics and best practices - regression/classification, objective functions - stochastic gradient descent vanishing and exploding gradients. Extra: How to read a paper efficiently?	<u>Deep Learning Book -</u> <u>Chapter 8</u> <u>Adam Optimizer</u>
Sep 17	Network architectures for image processing - Which neural network architectures work, why and how? - ResNet, DenseNet, UNet, FlowNet, MaskRCNN Extra: How to give a good presentation?	<u>Deep Learning Book -</u> <u>Chapter 9 ResNet, Unet</u>
Sep 22 (week 3)	Advanced architectures and representing sparse 2D keypoints - heat maps, part-affinity fields - regression vs. classification Homework 1 due. Homework 2 release	Heat Maps Part Affinity Fields
Sep 24	Presentations: Objective functions and log-likelihood Christopher Bishop, Mixture Density Networks <u>paper</u> Jonathan T. Barron, A General and Adaptive Robust Loss Function <u>paper</u> Submit review on the day before every presentation day.	
Sep 29 (week 4)	Representing 3D skeletons and point clouds - PointNet, articulated skeletons - Chamfer distance and other metrics (MPJPE, PCK) - Affine and perspective transformations	PointNet
Oct 1	Presentations: TBD	Read one of the two papers listed for each presentation session.
Oct 6 (week 5)	Representing and learning shapes - voxels, implicit functions, location maps - uv-coordinates, graph CNN, spiral convolution	Dense Pose Location Maps Spiral convolution
Oct 8	Presentations: TBD	

Oct 13 (week 6)	Representation learning - auto-encoder (AE) - variational auto-encoder (VAE) Homework 3 due.	PCA face model Deep Learning Book - Chapter 14
Oct 15	Presentations: TBD Submit project pitch slides (PDF, three slides incl. title)	
Oct 20 (week 7)	Project Pitches(3 min pitch)	
Oct 22	Presentations: TBD	
Oct 27 (week 8)	Attentian models - spatial transformers, Rol pooling, attention maps - camera models and multi-view Extra: How to write a paper for the right audience? Report Abstract due.	<u>Rol pooling, Spatial</u> <u>Transformer</u> <u>Multi-view Geometry</u>
Oct 29	Presentations: TBD	
Nov 3 (week 9)	GANs and unpaired image translation - cycle consistency - style transfer Report Related Work section due.	Cycle Gan Style transfer
Nov 5	Presentations: TBD	
Nov 10 (week 10)	Presentations: TBD Report Method section (up to problem def.) due.	
Nov 12	Presentations: TBD	
Nov 17 (week 11)	Presentations: TBD Report Evaluation section (up to datasets and metrics) due.	
Nov 19	Presentations: TBD	
Nov 24 (week 12)	Presentations: TBD Report Introduction section due.	
Nov 26	Presentations: TBD	
Dec 1 (week 13)	Project Presentations. (10 min talk per group, first half of groups)	
Dec 3	Project Presentations. (10 min talk per group, second half of groups)	
Dec 14 (no class)	Final Project Report submission. (6 page PDF document, 11:59 pm)	

Assignments



Assignment 1 Playing with PyTorch (supervised learning) Assignment 2: Egocentric human pose estimation (2D human pose regression) Assignment 3: Shape generation (unsupervised learning)







Assignments - rules



Academic Integrity. Assignments must be solved in teams of two using the available course material and other online sources. You are neither allowed to copy nor look at parts of any of the assignments from anyone outside of your team. Accordingly, it is not allowed to post solutions online or distribute them in (private) forums. The university policies on academic integrity are rigorously applied.

Submission. Solutions must be handed in through the Canvas system and be kept private.

Deadline and grading. Assignments will be due on the dates specified in the schedule, always at 11:59 pm PST. A late submission by one day will still be accepted but reduces the score by -25%. The grading is based on correctness and completeness, as detailed in each exercise description.

Deep Learning with PyTorch, first steps



Deep learning – a new way of programming



- Classical programming
- Write down computational rules
 c = a + b
- Requires human programmer (domain expert + CS skills)

Data driven approach

- Give lots of input-output examples
 [(3,4) -> 7, (2,3) -> 5, (100,2) -> 102, (2,2) -> 4, (4,3) -> 7, ...]
- Requires human annotator (domain expert)
- or Artificial Intelligence (AI) ?
 - Weak supervision, Self-supervision
 - Reinforcement learning ...



https://futurism.com/2-whats-the-next-blue-collar-job-coding



CPSC 532R/533R - Visual AI - Helge Rhodin

Deep learning – its curve fitting

Parametric curves

Polynomial

 $f(x) = \theta_0 + \theta_1 x + \theta_2 x^2$

- Spline $f(x) = \begin{cases} f_1(x), & \text{if } x_1 < x \le x_2 \\ f_2(x), & \text{if } x_2 < x \le x_3 \\ \vdots & \vdots \\ f_n(x), & \text{if } x_n < x \le x_{n+1} \end{cases}$
- Neural network

 $f(x) = h(\operatorname{linear}(h(\operatorname{linear}(x, W^{(1)})), W^{(2)}))$

Goal: Find θ that minimizes the objective function on the dataset D $\arg\min_{\theta} E(D,\theta)$

Low-dimensional poly.





Multilayer perceptron (fully connected network) interactive: playground.tensorflow.org





Programming environment - 🔁 python





Advantages

- high productivity / quick prototyping
- extensive support libraries
- high performance (with libraries linked to programs compiled from FORTRAN, C++, Cuda, ...)
- we will use python 3!

Questions per year in Stack Overflow



Machine learning framework - **PYT**⁶**RCH**

UBC

Features

- efficient matrix and tensor operations (like NumPy)
- automatic differentiation (dynamic)
- large number of tutorials
- many open source repositories

Resources

- PyTorch tutorials <u>https://pytorch.org/tutorials/</u>
- PyTorch introduction <u>https://pytorch.org/tutorials/beginner/</u> <u>deep_learning_60min_blitz.html</u>



https://thegradient.pub/state-of-ml-frameworks-2019-pytorch-dominates-research-tensorflow-dominates-industry/

CPSC 532R/533R - Visual AI - Helge Rhodin

Google colab

Cloud computing

- <u>http://colab.research.google.com</u>
- Provides a Jupyter notebook
- Incredible easy to setup
- Provides GPU access (for some time)
- Free of charge
- Interfaces with google drive





Assignment I

"Playing with PyTorch"

- Network architecture
- Dataloaders
- Evaluation
- Visualization
- Posted on course website
- Submit solution on Canvas
- Work in randomly assigned teams

