

Notes

- ◆ Extra class next week (Oct 12, not this Friday)
- ◆ To submit your assignment: email me the URL of a page containing (links to) the answers and code
- ◆ Compiling example assignment code on Solaris apparently doesn't work: try Linux cs-grad machines instead
 - Also: there is an installation of ATLAS (for an AMD architecture) at `/ubc/cs/research/scl/sclpublic/public/atlas-3.6.0`

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High Dimensional Data

- ◆ So far we've considered scalar data values f_i (or interpolated/approximated each component of vector values individually)
- ◆ In many applications, data is itself in high dimensional space
 - Or there's no real distinction between dependent (f) and independent (x) -- we just have data points
- ◆ Assumption: data is actually organized along a smaller dimension manifold
 - generated from smaller set of parameters than number of output variables
- ◆ Huge topic: machine learning
- ◆ Simplest: Principal Components Analysis (PCA)

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PCA

- ◆ We have n data points from m dimensions: store as columns of an $m \times n$ matrix A
- ◆ We're looking for linear correlations between dimensions
 - Roughly speaking, fitting lines or planes or hyperplanes through the origin to the data
 - May want to subtract off the mean value along each dimension for this to make sense

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Reduction to 1D

- ◆ Assume data points on a line through the origin (1D subspace)
- ◆ In this case, say line is along unit vector u . (m -dimensional vector)
- ◆ Each data point should be a multiple of u (call the scalar multiples w_i):
$$A_{*:i} = u w_i$$
- ◆ That is, A would be rank-1: $A = u w^T$
- ◆ Problem in general: find rank-1 matrix that best approximates A

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The rank-1 problem

- ◆ Use Least-Squares formulation again:

$$\min_{\substack{u \in \mathbf{R}^m, \|u\|=1 \\ w \in \mathbf{R}^n}} \|A - u w^T\|_F^2$$

- ◆ Clean it up: take $w = \sigma v$ with $\sigma \geq 0$ and $\|v\|=1$

$$\min_{\substack{u \in \mathbf{R}^m, \|u\|=1 \\ v \in \mathbf{R}^n, \|v\|=1 \\ \sigma \geq 0}} \|A - u \sigma v^T\|_F^2$$

- ◆ u and v are the first principal components of A

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Solving the rank-1 problem

- ◆ Remember trace version of Frobenius norm:

$$\begin{aligned} \|A - u w^T\|_F^2 &= \text{tr}(A - u w^T)^T (A - u w^T) \\ &= \text{tr}(A^T A) - \text{tr}(A^T u w^T) - \text{tr}(w u^T A) + \text{tr}(w u^T u w^T) \\ &= \text{tr}(A^T A) - 2u^T A w + \|w\|^2 \end{aligned}$$

- ◆ Minimize with respect to w :

$$\begin{aligned} \frac{\partial}{\partial w} \|A - u w^T\|_F^2 &= 0 \\ -2u^T A + 2w^T &= 0 \\ w &= A^T u \end{aligned}$$

- ◆ Then plug in to get a problem for u :

$$\min (u^T A A^T u)^2 \Leftrightarrow \max (u^T A A^T u)$$

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Finding u

- ◆ AA^T is symmetric, thus has a complete set of orthonormal eigenvectors X , eigenvalues μ
- ◆ Write u in this basis:

$$u = \sum_{i=1}^m \hat{u}_i X_i$$

- ◆ Then see:

$$u^T AA^T u = \left(\sum_{i=1}^m \hat{u}_i X_i \right)^T \left(\sum_{i=1}^m \mu_i \hat{u}_i X_i \right) = \sum_{i=1}^m \mu_i \hat{u}_i^2$$

- ◆ Obviously pick u to be the eigenvector with largest eigenvalue

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Finding v and sigma

- ◆ Similar argument gives v the eigenvector corresponding to max eigenvalue of $A^T A$
- ◆ Finally, knowing u and v , can find σ that minimizes

$$\|A - u\sigma v^T\|_F^2$$

with the same approach: $\sigma = u^T A v$

- ◆ We also know that

$$\sigma^2 = \max \lambda(AA^T) = \max \lambda(A^T A) = \|A\|_2^2$$

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Generalizing

- ◆ In general, if we expect problem to have subspace dimension k , we want the closest rank- k matrix to A
 - That is, express the data points as linear combinations of a set of k basis vectors (plus error)
 - We want the optimal set of basis vectors and the optimal linear combinations:

$$\min_{\substack{U \in \mathbf{R}^{m \times k}, U^T U = I \\ W \in \mathbf{R}^{n \times k}}} \|A - UW^T\|_F^2$$

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Finding W

- ◆ Take the same approach as before:

$$\begin{aligned} \|A - UW^T\|_F^2 &= \text{tr}(A - UW^T)^T (A - UW^T) \\ &= \text{tr} A^T A - 2 \text{tr} WU^T A + \text{tr} WU^T U W^T \\ &= \|A\|_F^2 - 2 \text{tr} WU^T A + \|W\|_F^2 \end{aligned}$$

- ◆ Set gradient w.r.t. W equal to zero:

$$\begin{aligned} -2A^T U + 2W &= 0 \\ W &= A^T U \end{aligned}$$

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Finding U

- ◆ Plugging in $W=A^T U$ we get

$$\begin{aligned} \min \|A - UW^T\|_F^2 \\ \Leftrightarrow \min -2 \text{tr} A^T U U^T A + \text{tr} A^T U U^T A \\ \Leftrightarrow \max \text{tr} U^T A A^T U \end{aligned}$$

- ◆ AA^T is symmetric, hence has a complete set of orthonormal eigenvectors, say columns of X , and eigenvalues along the diagonal of M (sorted in decreasing order):

$$AA^T = XMX^T$$

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Finding U cont'd

- ◆ Our problem is now: $\max \text{tr} U^T XMX^T U$
- ◆ Note X and U are both orthogonal, so is $X^T U$, which we can call Z : $\max_{Z^T Z = I} \text{tr} Z^T M Z$

$$\Leftrightarrow \max_{Z^T Z = I} \sum_{i=1}^k \sum_{j=1}^m \mu_j Z_{ji}^2$$

- ◆ Simplest solution: set $Z=(I \ 0)^T$ which means that U is the first k columns of X (first k eigenvectors of AA^T)

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Back to W

- ◆ We can write $W=V\Sigma^T$ for an orthogonal V , and square $k \times k$ Σ
- ◆ Same argument as for U gives that V should be the first k eigenvectors of $A^T A$
- ◆ What is Σ ?
- ◆ Can derive that it is diagonal, containing the square-roots of the eigenvalues of AA^T or $A^T A$ (they're identical)

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The Singular Value Decomposition

- ◆ Going all the way to $k=m$ (or n) we get the Singular Value Decomposition (SVD) of A
- ◆ $A=U\Sigma V^T$
- ◆ The diagonal entries of Σ are called the **singular values**
- ◆ The columns of U (eigenvectors of AA^T) are the left singular vectors
- ◆ The columns of V (eigenvectors of $A^T A$) are the right singular vectors
- ◆ Gives a formula for A as a sum of rank-1 matrices:

$$A = \sum_i \sigma_i u_i v_i^T$$

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Cool things about the SVD

- ◆ 2-norm: $\|A\|_2 = \sigma_1$
- ◆ Frobenius norm: $\|A\|_F^2 = \sigma_1^2 + \dots + \sigma_n^2$
- ◆ Rank(A)= # nonzero singular values
 - Can make a sensible numerical estimate
- ◆ Null(A) spanned by columns of U for zero singular values
- ◆ Range(A) spanned by columns of V for nonzero singular values
- ◆ For invertible A : $A^{-1} = V\Sigma^{-1}U^T$

$$= \sum_{i=1}^n \frac{v_i u_i^T}{\sigma_i}$$

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Least Squares with SVD

- ◆ Define pseudo-inverse for a general A :

$$A^+ = V\Sigma^+U^T = \sum_{\substack{i=1 \\ \sigma_i > 0}}^n \frac{v_i u_i^T}{\sigma_i}$$

- ◆ Note if $A^T A$ is invertible, $A^+ = (A^T A)^{-1} A^T$
 - I.e. solves the least squares problem]
- ◆ If $A^T A$ is singular, pseudo-inverse defined: $A^+ b$ is the x that minimizes $\|b - Ax\|_2$ and of all those that do so, has smallest $\|x\|_2$

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Solving Eigenproblems

- ◆ Computing the SVD is another matter!
- ◆ We can get U and V by solving the **symmetric eigenproblem** for AA^T or $A^T A$, but more specialized methods are more accurate
- ◆ The **unsymmetric eigenproblem** is another related computation, with complications:
 - May involve complex numbers even if A is real
 - If A is not normal ($AA^T \neq A^T A$), it doesn't have a full basis of eigenvectors
 - Eigenvectors may not be orthogonal... Schur decomposition
- ◆ Generalized problem: $Ax = \lambda Bx$
- ◆ LAPACK provides routines for all these
- ◆ We'll examine symmetric problem in more detail

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The Symmetric Eigenproblem

- ◆ Assume A is symmetric and real
- ◆ Find orthogonal matrix V and diagonal matrix D s.t. $AV = VD$
 - Diagonal entries of D are the eigenvalues, corresponding columns of V are the eigenvectors
- ◆ Also put: $A = VD V^T$ or $V^T A V = D$
- ◆ There are a few strategies
 - More if you only care about a few eigenpairs, not the complete set...
- ◆ Also: finding eigenvalues of an $n \times n$ matrix is equivalent to solving a degree n polynomial
 - No "analytic" solution with radicals in general for $n \geq 5$
 - Thus general algorithms are **iterative**

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