

## Notes

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## Meshing goals

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- ◆ Robust: doesn't fail on reasonable geometry
- ◆ Efficient: as few triangles as possible
  - Easy to refine later if needed
- ◆ High quality: triangles should be "well-shaped"
  - Extreme triangles make for poor performance of FEM - particularly large obtuse angles

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## A few approaches

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- ◆ **Multiblock methods:**
  - If you can mesh simple parts (conformal mapping), decompose region into block to mesh...
  - Hard to handle general geometry!
- ◆ **Advancing front:**  
start at boundary, work inwards
  - Can give very high quality near boundary, fast
  - Can run into problems when fronts meet...
- ◆ **Tile-based approach:**  
tile space regularly, cut out geometry
  - Can give optimal quality in the interior, fast
  - But can run into problems at the boundary...
- ◆ **Delaunay**

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## Delaunay triangulation

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- ◆ Given  $n$  points  $\{x_i\}$  mesh **convex hull** with triangles
- ◆ Triangles localized in the following sense: the **circumcircle** of each triangle is empty
- ◆ Dual of Voronoi diagram
  - Voronoi region for point  $x_i$ : set of all points closer to  $x_i$  than any other point
  - Dual: "rotate" edges, faces become points, points become faces
  - Circumcentres are points where three or more Voronoi regions meet

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## Nice things about Delaunay

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- ◆ Always exists
  - Unique up to choice of chords in a polygon inscribed in a circle (degenerate Voronoi Diagram)
- ◆ Easiest triangulation (in some sense) to construct:  $O(n \log n)$  or better algorithms
- ◆ Maximizes minimum angle
  - Not the best guarantee of quality, but useful

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## Algorithms

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- ◆ Incremental insertion:
  - Begin with one big triangle containing all points (deleted at the end)
  - Add points one by one, maintaining Delaunay property
  - Each new point may modify nearby triangles: use a tree to accelerate point location
- ◆ Divide-and-conquer
  - Split point set in half
  - Triangulate each half recursively
  - Sew two halves together

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## Lawson's edge-flipping algorithm

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- ◆ One particular incremental algorithm
- ◆ To insert a new point  $p$ :
  - Find triangle containing  $p$
  - Add  $p$  by dividing triangle in three
  - "Flip" edges that violate Delaunay property: is  $p$  in the circumcircle of adjacent triangles?  
If so: flip edge, check newly adjacent triangles

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## Predicates

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- ◆ Major problem: degenerate triangles
  - E.g. if boundary contains straight edges
- ◆ Floating-point rounding can kill the algorithm
- ◆ Handle by reducing to simplest predicates possible
  - And then either compute exactly, or in a consistent way
  - See Shewchuk's Triangle code

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## Delaunay refinement

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- ◆ Typically we're only given points on the boundary (and maybe not even that many)
- ◆ Need to add new points
- ◆ Chew showed one particularly good strategy is to add circumcentres of badly shaped triangles
  - Maintain priority queue of worst triangles
  - Adding circumcentre destroys the triangle, replaces it with better shaped versions
  - On boundary: split edges
- ◆ Additionally drive insertion by required "size"
  - E.g. coming from error control of PDE

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## Mesh improvement

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- ◆ Additionally can postprocess mesh:
  - Move nodes to more optimal locations (if just centroid, called "mesh smoothing")
  - Flip edges to get more balanced valences

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