

Notes

- ◆ Even if you're not registered (not handing in assignment 1) send me an email to be added to a class list

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Time Integration

- ◆ Recall Taylor series
- ◆ Linearization in higher dimensions
- ◆ Reduction to first order systems

- ◆ Well-posed problems: problem stability
- ◆ Linear analysis

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Forward Euler

- ◆ Accuracy: truncation error vs. global error
- ◆ Algorithm stability
- ◆ Test Equation
- ◆ Stability region

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More accurate explicit methods

- ◆ Leapfrog
- ◆ Multistep/multivalued methods
- ◆ Runge-Kutta methods
 - Heun's method (RK2)
 - Standard RK4

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Error control

- ◆ Adaptive time stepping
- ◆ Integrator pairs

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Stiffness

- ◆ A problem is stiff when an explicit integrator needs to take small steps for stability, not accuracy
 - Solution space includes very rapidly vanishing transients
- ◆ Note: not stiff just because you want to take large time steps
 - If the real solution has variations on a small timescale, there's no avoiding small time steps
- ◆ Usually handled with implicit integrators
- ◆ Backwards Euler

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