

Announcements

- Solution to assignment 6 in web page
- Assignment 7 due next Monday
- Midterm next Thursday. Format like last midterm.

It is remarkable that a science which began with the consideration of games of chance should become the most important object of human knowledge . . . The most important questions of life are, for the most part, really only problems of probability . . .

The theory of probabilities is at bottom nothing but common sense reduced to calculus.

– Pierre Simon de Laplace, Théorie Analytique de Probabilités [1812]

Main approaches to determine posterior distributions in graphical models:

- Variable Elimination, recursive conditioning: exploit the structure of the network to eliminate (sum out) the non-observed, non-query variables one at a time.
- Stochastic simulation: random cases are generated according to the probability distributions.
- Variational methods: find the closest tractable distribution to the (posterior) distribution we are interested in.
- Bounding approaches: bound the conditional probabilities above and below and iteratively reduce the bounds.
- ...

- A **factor** is a representation of a function from a tuple of random variables into a number.
- We write factor f on variables X_1, \dots, X_j as $f(X_1, \dots, X_j)$.
- We can assign some or all of the variables of a factor:
 - ▶ $f(X_1=v_1, X_2, \dots, X_j)$, where $v_1 \in \text{domain}(X_1)$, is a factor on X_2, \dots, X_j .
 - ▶ $f(X_1=v_1, X_2=v_2, \dots, X_j=v_j)$ is a number that is the value of f when each X_i has value v_i .

The former is also written as $f(X_1, X_2, \dots, X_j)_{X_1=v_1}$, etc.

Example factors

$r(X, Y, Z):$

X	Y	Z	val
t	t	t	0.1
t	t	f	0.9
t	f	t	0.2
t	f	f	0.8
f	t	t	0.4
f	t	f	0.6
f	f	t	0.3
f	f	f	0.7

$r(X=t, Y, Z):$

Y	Z	val
t	t	0.1
t	f	0.9
f	t	0.2
f	f	0.8

$r(X=t, Y, Z=f):$

Y	val
t	0.9
f	0.8

$r(X=t, Y=f, Z=f) = 0.8$

Clicker Question

If $f(W, X, Y, Z)$ is a factor on variables $\{W, X, Y, Z\}$, then $f(W, X = 3, Y = \text{true}, Z)$ is a factor on

- A $\{W, X, Y, Z\}$
- B $\{X, Y\}$
- C $\{W, Z\}$
- D $\{\}$
- E none of the above

Clicker Question

If $f(W, X, Y, Z)$ is a factor on variables $\{W, X, Y, Z\}$, then $f(W = 17, X = 3, Y = \text{true}, Z = \text{false})$ is a factor on

- A $\{W, X, Y, Z\}$
- B $\{X, Y\}$
- C $\{W, Z\}$
- D $\{\}$
- E none of the above

The **product** of factor $f_1(\bar{X}, \bar{Y})$ and $f_2(\bar{Y}, \bar{Z})$, where \bar{Y} are the variables in common, is the factor $(f_1 * f_2)(\bar{X}, \bar{Y}, \bar{Z})$ defined by:

$$(f_1 * f_2)(\bar{X}, \bar{Y}, \bar{Z}) = f_1(\bar{X}, \bar{Y})f_2(\bar{Y}, \bar{Z}).$$

Multiplying factors example

f_1 :

A	B	val
t	t	0.1
t	f	0.9
f	t	0.2
f	f	0.8

f_2 :

B	C	val
t	t	0.3
t	f	0.7
f	t	0.6
f	f	0.4

$f_1 * f_2$:

A	B	C	val
t	t	t	0.03
t	t	f	0.07
t	f	t	0.54
t	f	f	0.36
f	t	t	0.06
f	t	f	0.14
f	f	t	0.48
f	f	f	0.32

Clicker Question

If f is a factor on $\{W, X, Y\}$ and

g is a factor on $\{W, U\}$

$(f * g)$ is a factor on

A $\{W, X, Y, U\}$

B $\{X, Y, U\}$

C $\{W\}$

D $\{f, g, W, X, Y, U\}$

E there is not enough information to tell

Clicker Question

If $f(W=3, X=4, Y=5) = 10$ and
 $g(W=3, U=12) = 15$
 $(f * g)(W=3, X=4, Y=5, U=12) =$

- A a factor on $\{W, X, Y, U\}$
- B 25
- C 150
- D none of the above
- E there is not enough information to tell

Summing out variables

We can **sum out** a variable, say X_1 with domain $\{v_1, \dots, v_k\}$, from factor $f(X_1, \dots, X_j)$, resulting in a factor on X_2, \dots, X_j defined by:

$$\begin{aligned} & \left(\sum_{X_1} f \right) (X_2, \dots, X_j) \\ &= f(X_1=v_1, \dots, X_j) + \dots + f(X_1=v_k, \dots, X_j) \end{aligned}$$

Summing out a variable example

f_3 :

A	B	C	val
t	t	t	0.03
t	t	f	0.07
t	f	t	0.54
t	f	f	0.36
f	t	t	0.06
f	t	f	0.14
f	f	t	0.48
f	f	f	0.32

$\sum_B f_3$:

A	C	val
t	t	0.57
t	f	0.43
f	t	0.54
f	f	0.46

Exercise

Given factors:

s:

A	val
t	0.75
f	0.25

t:

A	B	val
t	t	0.6
t	f	0.4
f	t	0.2
f	f	0.8

o:

A	val
t	0.3
f	0.1

What are the following a function of?

- i) $s * t$ A {A}
- ii) $\sum_B (s * t)$ B {B}
- iii) $s * o$ C {A, B}
- iv) $\sum_A s * t * o$ D {}
- v) $\sum_B (\sum_A s * t * o)$ E none of the above

- To compute the posterior probability of Z given evidence $E=e$:

$$\begin{aligned} P(Z \mid E=e) &= \frac{P(Z, E=e)}{P(E=e)} \\ &= \frac{P(Z, E=e)}{\sum_Z P(Z, E=e)}. \end{aligned}$$

- So the computation reduces to the probability of $P(Z, E=e)$
- then normalize at the end.

Probability of a conjunction

- The variables of the belief network are X_1, \dots, X_n .
- The evidence is $Y_1=v_1, \dots, Y_j=v_j$
- To compute $P(Z, Y_1=v_1, \dots, Y_j=v_j)$:
we add the other variables,
 $Z_1, \dots, Z_k = \{X_1, \dots, X_n\} - \{Z\} - \{Y_1, \dots, Y_j\}$.
and sum them out.
- We order the Z_i into an **elimination ordering**.

$$\begin{aligned} & P(Z, Y_1=v_1, \dots, Y_j=v_j) \\ &= \sum_{Z_k} \cdots \sum_{Z_1} P(X_1, \dots, X_n)_{Y_1=v_1, \dots, Y_j=v_j} \\ &= \sum_{Z_k} \cdots \sum_{Z_1} \prod_{i=1}^n P(X_i \mid \text{parents}(X_i))_{Y_1=v_1, \dots, Y_j=v_j} \end{aligned}$$

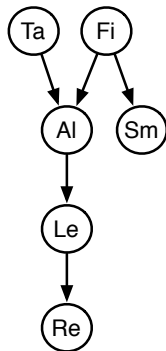
Computation in belief networks reduces to computing the sums of products.

- How can we compute $ab + ac$ efficiently?
- Distribute out a giving $a(b + c)$
- How can we compute $\sum_{Z_1} \prod_{i=1}^n P(X_i \mid \text{parents}(X_i))$ efficiently?
- Distribute out those factors that don't involve Z_1 .

Inference as factorization example

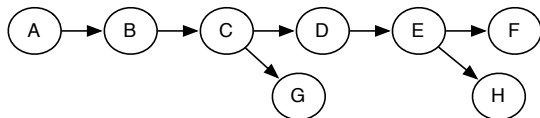
Query: $P(Re \mid SM=true)$

write $SM=true$ as sm



$$\begin{aligned} & P(Re, sm) \\ &= \sum_{Le} \sum_{Al} \sum_{Fi} \sum_{Ta} P(Ta, Fi, Al, sm, Le, Re) \\ &= \sum_{Le} \sum_{Al} \sum_{Fi} \sum_{Ta} P(Ta)P(Fi)P(Al \mid Ta, Fi) \\ &\quad P(sm \mid Fi)P(Le \mid Al)P(Re \mid Le) \\ &= \sum_{Le} \sum_{Al} \sum_{Fi} P(Fi)P(sm \mid Fi)P(Le \mid Al) \\ &\quad P(Re \mid Le) \sum_{Ta} P(Ta)P(Al \mid Ta, Fi) \\ &= \sum_{Le} P(Re \mid Le) \sum_{Al} P(Le \mid Al) \\ &\quad \sum_{Fi} P(Fi)P(sm \mid Fi) \sum_{Ta} P(Ta)P(Al \mid Ta, Fi) \end{aligned}$$

Inference as factorization example



Query: $P(G | f)$; elimination ordering: A, H, E, D, B, C

$$P(G | f) \propto \sum_C \sum_B \sum_D \sum_E \sum_H \sum_A P(A)P(B | A)P(C | B) \\ P(D | C)P(E | D)P(f | E)P(G | C)P(H | E)$$

$$= \sum_C \left(\sum_B \left(\sum_A P(A)P(B | A) \right) P(C | B) \right) P(G | C) \\ \left(\sum_D P(D | C) \left(\sum_E P(E | D)P(f | E) \sum_H P(H | E) \right) \right)$$

Variable elimination algorithm

To compute $P(Z \mid Y_1=v_1 \wedge \dots \wedge Y_j=v_j)$:

- Construct a factor for each conditional probability.
- Set the observed variables to their observed values.
- Sum out each of the non-observed non-query variables (the $\{Z_1, \dots, Z_k\}$) according to some elimination ordering.
- Multiply the remaining factors.
- Normalize by dividing the resulting factor $f(Z)$ by $\sum_Z f(Z)$.

Summing out a variable

To sum out a variable Z_j from a product f_1, \dots, f_k of factors:

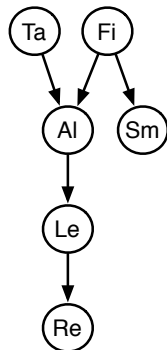
- Partition the factors into
 - ▶ those that don't contain Z_j , say f_1, \dots, f_i ,
 - ▶ those that contain Z_j , say f_{i+1}, \dots, f_k

Then:

$$\sum_{Z_j} f_1 * \dots * f_k = f_1 * \dots * f_i * \left(\sum_{Z_j} f_{i+1} * \dots * f_k \right).$$

- Explicitly construct a representation of the rightmost factor. Replace the factors f_{i+1}, \dots, f_k by the new factor.

Inference as factorization example



Query: $P(Re \mid SM=true)$.

See Alspace.org → Belief and decision network tool
→ File → Load Sample Problem → Fire Alarm Belief Network → Load → Solve → Make Observation Smoke → Query Report → Verbose