

Stat 521A

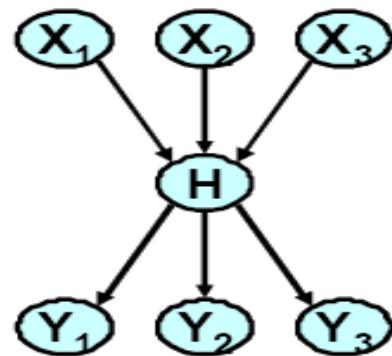
Lecture 20

Outline

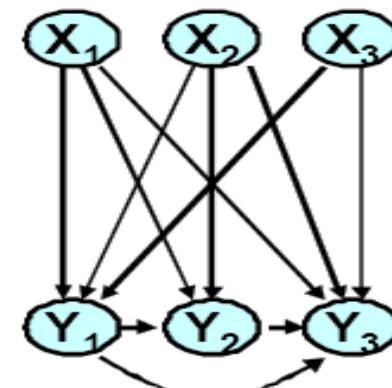
- Overview of learning (ch 16)
- MLE for DGMs (17.2)
- Bayesian parameter estimation for DGMs (17.4)
- Parameter tying (17.5)
- Hierarchical Bayes (17.5.4)
- PAC analysis (17.6)

Overview of learning

- Learn parameters or structure
- Observe all variables, or have missing values, or have known hidden variables, or have unknown hidden variables
- Hidden variables can simplify the model (fewer params)



17 parameters



59 parameters

Overview of learning

[t]

Learning Bayesian networks

	Complete data	Missing data	Hidden variables
Known structure	Closed form solution	<ul style="list-style-type: none"> Iterated optimization to local maximum, Inference on network multiple times 	<ul style="list-style-type: none"> Symmetrical solutions Infinite # of solutions
Unknown structure, known variables	<ul style="list-style-type: none"> Combinatorial optimization over structures score has closed form 	<ul style="list-style-type: none"> Inference over multiple different network structures no closed form for score 	
Unknown vars	N/A	N/A	<ul style="list-style-type: none"> Infinite number of possible solutions

Learning Markov networks

	Complete data	Missing data	Hidden variables
Known structure	<ul style="list-style-type: none"> Convex optimization problem solved optimally via numerical optimization Inference on network multiple times 	<ul style="list-style-type: none"> Non-convex problem iterated optimization to local maximum Inference on network multiple times 	<ul style="list-style-type: none"> Symmetrical solutions Infinite # of solutions
Unknown structure, known variables	<ul style="list-style-type: none"> Combinatorial and numerical formulations Can be solved via convex optimization Inference over multiple different network structures 		
Unknown vars	N/A	N/A	<ul style="list-style-type: none"> Infinite number of possible solutions

Rest of ch 16

- Overfitting
- Cross validation
- Empirical risk minimization
- PAC bounds (see later)
- Generative vs discriminative
- Bias/variance tradeoff
- Prediction vs density estimation vs knowledge discovery

MLE for DGMs

- Assume DAG is known and variables are fully observed
- The likelihood factorizes into a product of local likelihoods, so we can optimize each CPD independently

$$\begin{aligned} p(\mathcal{D}|\boldsymbol{\theta}) &= \prod_{n=1}^N p(\mathbf{x}_n|\boldsymbol{\theta}) \\ &= \prod_{n=1}^N \prod_{i=1}^D p(x_{in}|\mathbf{x}_{\pi_i,n}, \boldsymbol{\theta}_i) \\ &= \prod_{i=1}^D \left[\prod_{n=1}^N p(x_{in}|\mathbf{x}_{\pi_i,n}, \boldsymbol{\theta}_i) \right] \\ &= \prod_{i=1}^D p(\mathcal{D}_i|\boldsymbol{\theta}_i) \end{aligned}$$

Tabular CPDs

$$\theta_{ijk} \stackrel{\text{def}}{=} p(X_i = k | \mathbf{X}_{\pi_i} = j)$$

$$\begin{aligned} \prod_{n=1}^N p(x_{in} | \mathbf{x}_{\pi_i, n}, \boldsymbol{\theta}_i) &= \prod_{n=1}^N \prod_{j=1}^{r_i} \prod_{k=1}^{q_i} \theta_{ijk}^{I(x_{i,n}=k, \mathbf{x}_{\pi_i,n}=j)} \\ &= \prod_j \prod_k \theta_{ijk}^{N_{ijk}} \end{aligned}$$

$$N_{ijk} \stackrel{\text{def}}{=} \sum_{n=1}^N I(x_{i,n} = k, \mathbf{x}_{\pi_i,n} = j)$$

$$\hat{\theta}_{ijk} = \frac{N_{ijk}}{\sum_{j'=1}^{r_i} N_{ij'k}}$$

$$\hat{\theta}_{x|u} = \frac{M[u, x]}{M[u]},$$

MLE for linear Gaussian CPDs

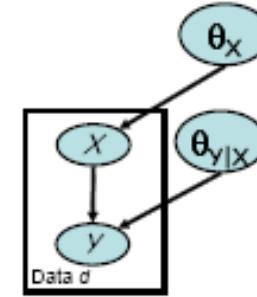
- Use usual linear regression equations

$$p(x_i | \mathbf{x}_{\pi_i}, \boldsymbol{\theta}_i) = \mathcal{N}(x_i | \mathbf{w}_i^T \mathbf{x}_{\pi_i}, \sigma_i^2)$$

Bayesian parameter estimation

- Global parameter independence

$$p(\boldsymbol{\theta}) = \prod_{i=1}^D p(\boldsymbol{\theta}_i)$$



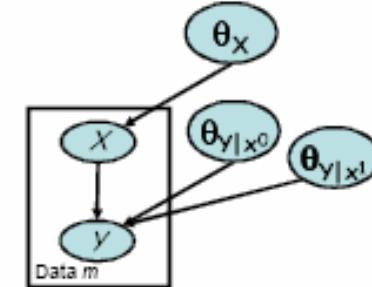
- Implies factorized posterior

$$p(\boldsymbol{\theta}|\mathcal{D}) \propto \prod p(\boldsymbol{\theta}_i) p(\mathcal{D}_i|\boldsymbol{\theta}_i)$$

- For multinomials, let us assume local param indep

$$p(\boldsymbol{\theta}) = \prod_{i=1}^n \prod_{j=1}^{r_i} p(\boldsymbol{\theta}_{ij})$$

- Geiger & Heckerman showed this implies θ_{ij} must have a Dirichlet prior

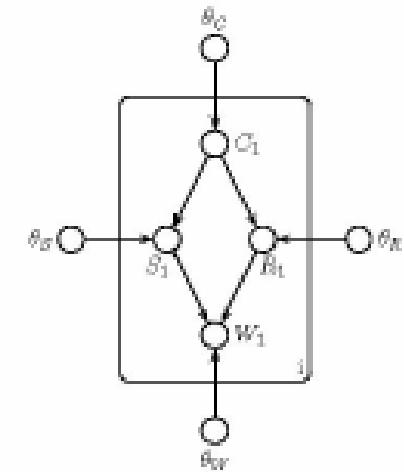


Tabular CPDs

- We have

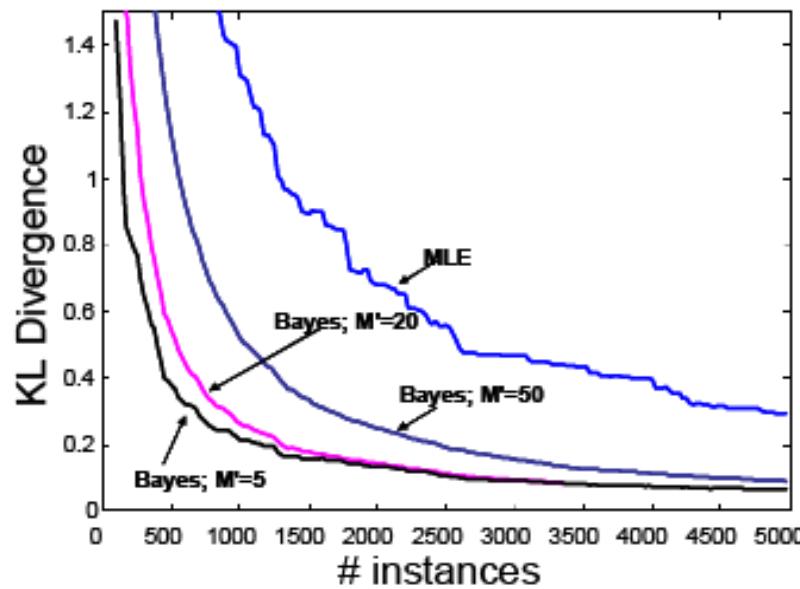
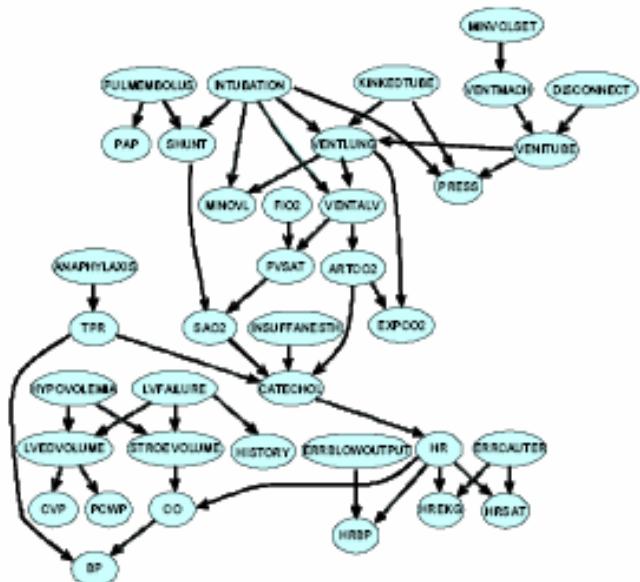
$$p(\boldsymbol{\theta} | \mathcal{D}) \propto \prod_{i=1}^D \prod_{j=1}^{r_i} \text{Dir}(\boldsymbol{\theta}_{ij} | \boldsymbol{\alpha}_{ij} + \mathbf{N}_{ij})$$

		$p(\theta_C)$	$p(\theta_R C=0)$	$p(\theta_R C=1)$
i	C S R W	1 1	1 1	1 1
1	0 0 0 0	2 1	2 1	1 1
2	0 0 1 1	3 1	2 2	1 1
3	1 1 1 1	3 2	2 2	1 2



Example

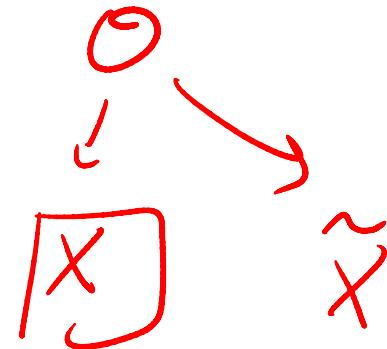
- ICU alarm network, 37 nodes, 504 params
- Compute theta-hat using MLE or posterior mean.
Then compute $\text{KL}(p(X|\theta^*), p(X|\hat{\theta}))$ as a function of sample size.



Posterior predictive density

- We can predict future variables by integrating out the params

$$p(\tilde{X}|\mathcal{D}) = \int p(\tilde{X}|\boldsymbol{\theta})p(\boldsymbol{\theta}|\mathcal{D})d\boldsymbol{\theta}$$



- In the case of Dirichlet-multinomial model, this is equivalent to plugging in the posterior mean

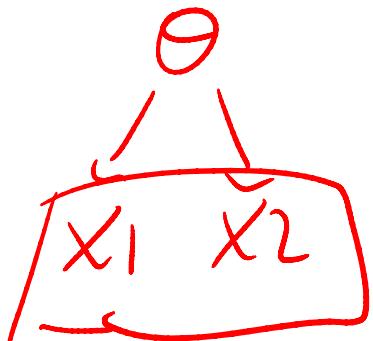
$$\begin{aligned} p(\tilde{X} = k|\mathcal{D}) &= \int \theta_k p(\boldsymbol{\theta}|\mathcal{D})d\boldsymbol{\theta} \\ &= \int \theta_k p(\boldsymbol{\theta}_k|\mathcal{D})d\boldsymbol{\theta} \\ &= \bar{\theta}_k = \frac{\alpha_k + N_k}{\sum_{k'} \alpha_{k'} + N_{k'}} \end{aligned}$$

MAP estimation

- Since in general computing the posterior is difficult, a compromise is to compute a MAP estimate
- However, the result is not invariant to parameterization – change of variables formula changes the prior density (Box 17.D)
- Reparameterizing the likelihood does not change the MLE, since the lik is not a density function
- Reparameterizing the posterior does not change anything, since we integrate over params

Parameter tying

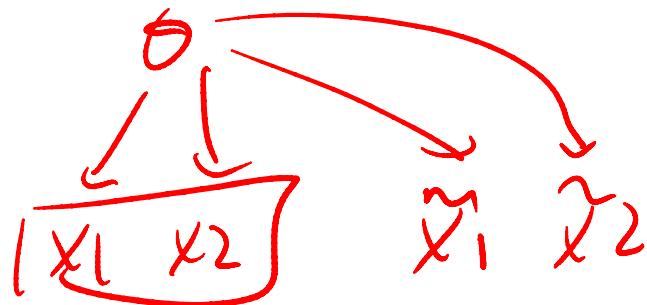
- We just pool the sufficient statistics from the nodes that share the same params



$$p(\boldsymbol{\theta}|\mathcal{D}) = \text{Dir}(\alpha_k + \sum_n I(X_{1n} = j) + \sum_n I(X_{2n} = j))$$

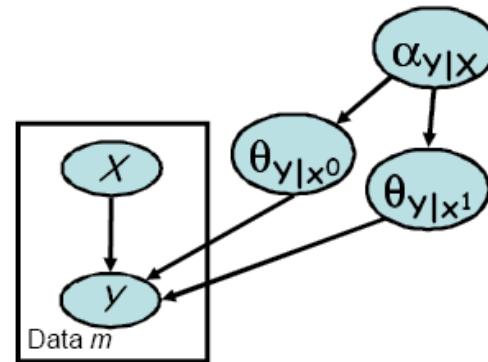
Prediction with tied params

- A subtlety arises when computing the posterior predictive density with tied params
- When we observe \tilde{X}_1 , we learn something about theta that helps us predict \tilde{X}_2 . So we cannot just multiply the postpred for each node separately, but need to use the formula for a batch of data

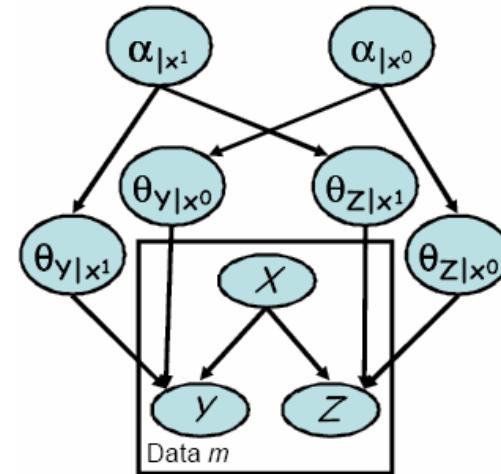


Hierarchical priors

- Encourage params to be similar across conditioning contexts (rows) within 1 CPD

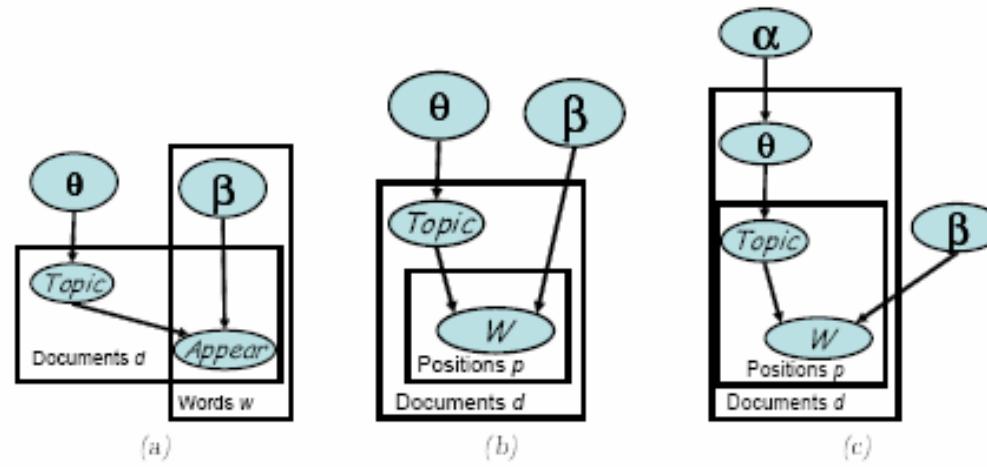


- Encourage params to be similar across response for each conditionign context



Text classification

- Let $T(d) = t$ be topic of document d , $\sim \text{Mun}(\theta)$
- Product of Bernoullis, $A(w,d)$ in $\{0,1\} \sim \text{Ber}(\beta_{w,t})$, $w = 1:K$
- Product of multinoullis, $W(p,d)$ in $\{1,\dots,K\} \sim \text{Mun}(\beta_t)$, $p=1:\text{len}(d)$
- Latent Dirichlet Allocation: $\theta(d)$ = distribution over topics, $\sim \text{Dir}(\alpha)$, $T(p,d) = t$, $W(p,d) \sim \text{Mun}(\beta_t)$



PAC analysis

- Probably approximately correct
- Let P^*M be distribution over datasets of size M drawn from P^*
- $P_{ML(D)}$ be distribution over X given by model M learned using algo L on data D
- We want to prove that

Let $\epsilon > 0$ be our approximation parameter and $\delta > 0$ our confidence parameter. Then, for M “large enough”, we have that

$$P_M^*(\{\mathcal{D} : D(P^* \| P_{ML(\mathcal{D})}) \leq \epsilon\}) \geq 1 - \delta.$$

- Frequentist analysis of estimator; bounds on deviation from ‘truth’

Excess risk

- Minimizing $\text{KL}(P^*, P)$ may be hard if P^* is not in the model class of P
- Define best achievable param in class as

$$\theta^{\text{opt}} = \arg \min_{\theta \in \Theta[\mathcal{G}]} D(P^* \| P_\theta).$$

- Define excess risk as

$$D(P^* \| P_\theta) - D(P^* \| P_{\theta^{\text{opt}}}) :$$

DGM param learning: PAC bounds

Theorem 17.6.8: Let \mathcal{G} be a network structure, and P^* a distribution consistent with some network \mathcal{G}^* such that $P^*(x_i \mid \text{pa}_i^{\mathcal{G}^*}) \geq \lambda$ for all i , x_i , and $\text{pa}_i^{\mathcal{G}^*}$. If P is the distribution learned by maximum likelihood estimate for \mathcal{G} , then

$$P(D(P^* \| P) - D(P^* \| P_{\theta^{\text{opt}}}) > n\epsilon) \leq nK^{d+1}e^{-2M\lambda^{2(d+1)}\epsilon^2 \frac{1}{(1+\epsilon)^2}}$$

where K is the maximal variable cardinality and d is the maximum number of parents in \mathcal{G} .

Corollary 17.6.9: Under the conditions of Theorem 17.6.8, if

$$M \geq \frac{1}{2} \frac{1}{\lambda^{2(d+1)}} \frac{(1+\epsilon)^2}{\epsilon^2} \log \frac{nK^{d+1}}{\delta},$$

then

$$P(D(P^* \| P) - D(P^* \| P_{\theta^{\text{opt}}}) < n\epsilon) > 1 - \delta.$$