

STAT 406: ALGORITHMS FOR CLASSIFICATION
AND PREDICTION

MIDTERM REVIEW

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OUTLINE

- Some useful probability distributions
- Maximum likelihood estimation
- Bayesian estimation
- Empirical Bayes
- Bayesian classifiers

PROBABILITY DISTRIBUTIONS

Type	1D	MultiD
D	Binomial $Bin(x n, \theta)$	Multinomial $Mu(x n, \theta)$
D	Bernoulli $Ber(x \theta)$	Multinomial $Mu(x 1, \theta)$
C	Gaussian $\mathcal{N}(x \mu, \sigma^2)$	Gaussian $\mathcal{N}(x \mu, \Sigma)$
C	Beta $Beta(x \alpha_1, \alpha_0)$	Dirichlet $Dir(x \alpha_1, \dots, \alpha_K)$

DISCRETE PROBABILITY DISTRIBUTIONS

Binomial $X \in \{0, 1, \dots, N\}$, $\theta \in [0, 1]$

$$Bi(X|n, \theta) = \binom{n}{X} \theta^X (1 - \theta)^{n-X} \quad (1)$$

Bernoulli $X \in \{0, 1\}$, $\theta \in [0, 1]$

$$Be(X|\theta) = \theta^X (1 - \theta)^{1-X} = \theta^{I(X=1)} (1 - \theta)^{I(X=0)} \quad (2)$$

Multinomial $X_k \in \{0, 1, \dots, N\}$, $\theta_k \in [0, 1]$, $\sum_{k=1}^K \theta_k = 1$

$$Mu(X|n, \theta) = \binom{n}{x_1 \dots x_K} \prod_{j=1}^K \theta_j^{x_j} \quad (3)$$

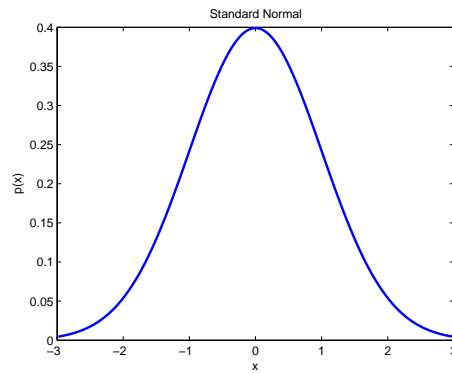
Multinomial $X \in \{1, \dots, K\}$, $\theta_k \in [0, 1]$, $\sum_{k=1}^K \theta_k = 1$

$$Mu(X|1, \theta) = \prod_{j=1}^K \theta_j^{I(X=j)} \quad (4)$$

1D GAUSSIANS

Univariate $x \in \mathbb{R}$, $\mu \in \mathbb{R}$, $\sigma \in \mathbb{R}^+$

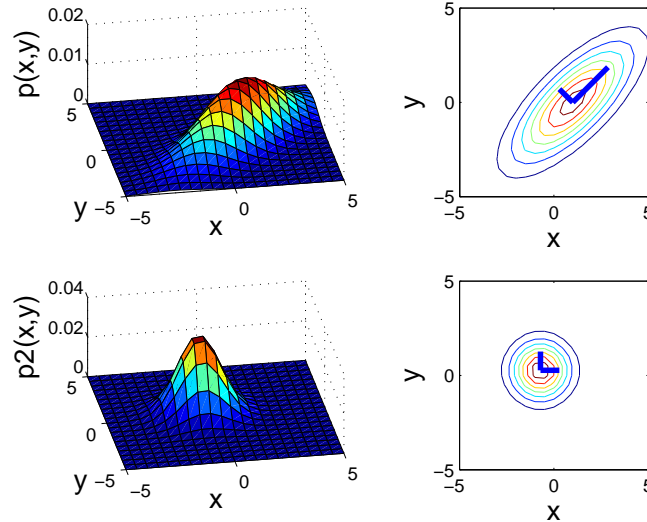
$$\mathcal{N}(x|\mu, \sigma) \stackrel{\text{def}}{=} \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} \quad (5)$$



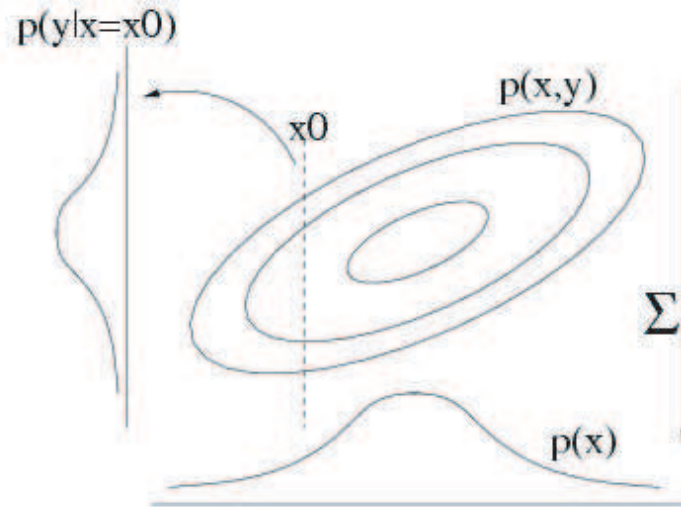
MULTIVARIATE NORMAL

MVN $x \in \mathbb{R}^d$, $\mu \in \mathbb{R}^d$, Σ psd

$$\mathcal{N}(\vec{x}|\vec{\mu}, \Sigma) \stackrel{\text{def}}{=} \frac{1}{(2\pi)^{p/2} |\Sigma|^{1/2}} \exp\left[-\frac{1}{2}(\vec{x} - \vec{\mu})^T \Sigma^{-1} (\vec{x} - \vec{\mu})\right] \quad (6)$$



MVN: MARGINALS AND CONDITIONALS



$$p(x_1, x_2) = p(x_2)p(x_1|x_2) \quad (7)$$

$$= \mathcal{N}(x_2|\mu_2, \Sigma_{22})\mathcal{N}(x_1|\mu_{1|2}, \Sigma_{1|2}) \quad (8)$$

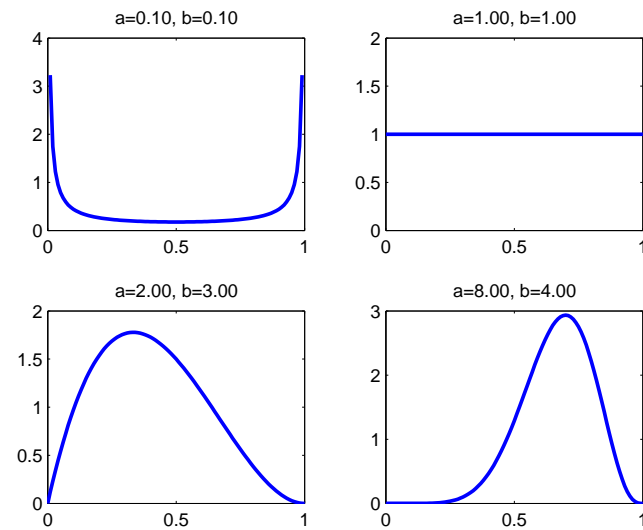
$$\mu_{1|2} = \mu_1 + \Sigma_{12}\Sigma_{22}^{-1}(x_2 - \mu_2) \quad (9)$$

$$\Sigma_{1|2} = \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21} \quad (10)$$

BETA DISTRIBUTION

Beta $x \in [0, 1]$, $\alpha_0, \alpha_1 \in \mathbb{R}^+$

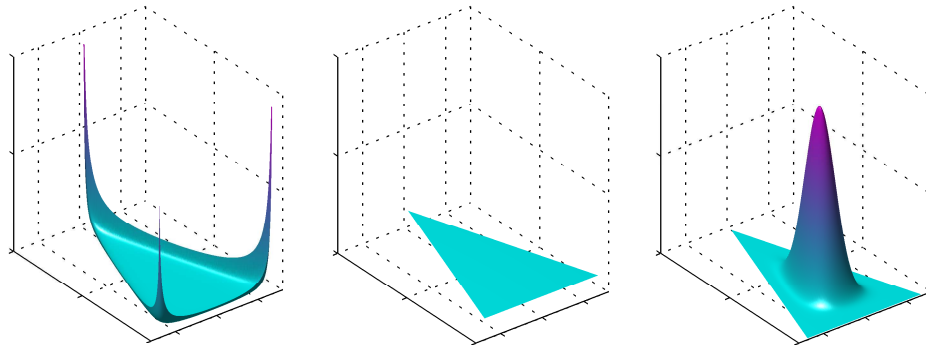
$$\text{Beta}(x|\alpha_1, \alpha_0) = \frac{1}{B(\alpha_1, \alpha_0)} x^{\alpha_1-1} (1-x)^{\alpha_0-1} \quad (11)$$



DIRICHLET DISTRIBUTION

Dirichlet $x \in [0, 1]^K$, $\sum_j x_j = 1$, $\alpha_j \in \mathbb{R}^+$

$$\mathcal{D}(x|\alpha) = \frac{1}{Z(\alpha)} \cdot x_1^{\alpha_1-1} \cdot x_2^{\alpha_2-1} \cdots x_K^{\alpha_K-1} \quad (12)$$



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- Some useful probability distributions ✓
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MAXIMUM LIKELIHOOD ESTIMATION

$$\hat{\theta}^{mle} = \arg \max_{\theta} \log \prod_{i=1}^n p(x_i|\theta) = \arg \max_{\theta} \sum_{i=1}^n \log p(x_i|\theta) \quad (13)$$

- Most widely used point estimate (enjoys various theoretical properties, often gives intuitive answer)
- When maximizing likelihood with constraints, use Lagrange multipliers eg., for multinomial, we maximize

$$\tilde{\ell}(\theta) = \log \prod_k \theta_k^{N_k} + \lambda(1 - \sum_k \theta_k) \quad (14)$$

- Frequentist (classical) statistics represents uncertainty in estimates by deriving the sampling distribution $\hat{\theta}(X_{1:n})$ from the underlying distributions of the X_i ; often this is asymptotically Gaussian. From this, we can derive confidence intervals.

SOME MLES

Bernoulli

$$\theta = \frac{\sum_i x_i}{n} \quad (15)$$

Multinomial

$$\theta_j = \frac{\sum_i I(x_i = j)}{n} \quad (16)$$

Gaussian

$$\mu = \frac{\sum_i x_i}{n} = \bar{x} \quad (17)$$

$$\sigma^2 = \frac{1}{n} \sum_i (x_i - \bar{x})^2 \quad (18)$$

$$\Sigma = \frac{1}{n} \sum_i (x_i - \bar{x})(x_i - \bar{x})^T = \frac{1}{n} X X^T - \bar{x} \bar{x}^T \quad (19)$$

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BAYESIAN PARAMETER ESTIMATION

In Bayesian statistics, all forms of uncertainty are represented with probability distributions. We estimate parameters using Bayes rule

$$p(\theta|D) = \frac{p(D|\theta)p(\theta)}{p(D)} = \frac{p(D|\theta)p(\theta)}{\int p(D|\theta)p(\theta)d\theta} \quad (20)$$

A natural conjugate prior $p(\theta)$ is a distribution of the same functional form as the likelihood $p(D|\theta)$. In this case, the posterior $p(\theta|D)$ is also the same form, and can be used as a prior for the next round of learning.

BETA-BERNOULLI MODEL

- Prior

$$p(\theta) = Be(\theta|\alpha_1, \alpha_0) = \frac{1}{B(\alpha_1, \alpha_0)} \theta^{\alpha_1-1} (1-\theta)^{\alpha_0-1} \quad (21)$$

$$B(\alpha_1, \alpha_0) = \frac{\Gamma(\alpha_1)\Gamma(\alpha_0)}{\Gamma(\alpha_1 + \alpha_0)} \quad (22)$$

- Likelihood

$$p(D|\theta) = \prod_{i=1}^N \theta^{N_1} (1-\theta)^{N_0} \quad (23)$$

- Posterior

$$p(\theta|D) = Be(\alpha_1 + N_1, \alpha_0 + N_0) = Be(\alpha'_1, \alpha'_0) \quad (24)$$

- Marginal likelihood:

$$p(D) = \frac{B(\alpha'_0, \alpha'_1)}{B(\alpha_1, \alpha_0)} \quad (25)$$

- Posterior predictive.

$$p(X = 1|D) = \frac{\alpha'_1}{\alpha'_1 + \alpha'_0} \quad (26)$$

DIRICHLET-MULTINOMIAL ($M_i = 1$) MODEL

- Prior

$$p(\theta|\vec{\alpha}) = Dir(\theta|\vec{\alpha}) = \frac{1}{Z(\alpha)} \cdot \theta_1^{\alpha_1-1} \cdot \theta_2^{\alpha_2-1} \dots \theta_K^{\alpha_K-1} \quad (27)$$

$$Z_{Dir}(\vec{\alpha}) = \frac{\prod_{i=1}^K \Gamma(\alpha_i)}{\Gamma(\sum_{i=1}^K \alpha_i)} \quad (28)$$

- Likelihood

$$p(D|\vec{\theta}) = \prod_{j=1}^K \theta_j^{N_j} \quad (29)$$

- Posterior

$$p(\theta|D, \vec{\alpha}) = Dir(\alpha_1 + N_1, \dots, \alpha_K + N_K) = Dir(\alpha'_1, \dots, \alpha'_K) \quad (30)$$

- Marginal likelihood:

$$p(D) = \frac{Z_{Dir}(\vec{N} + \vec{\alpha})}{Z_{Dir}(\vec{\alpha})} \quad (31)$$

$$(32)$$

- Posterior predictive

$$p(X = j|D) = \frac{\alpha_j + N_j}{N + \sum_k \alpha_k} \quad (33)$$

NORMAL-NORMAL MODEL

- Prior

$$p(\mu) = \mathcal{N}(\mu|\mu_0, \sigma_0) = \frac{1}{\sigma_0\sqrt{2\pi}} \exp\left(-\frac{1}{2\sigma_0^2}(\mu - \mu_0)^2\right) \quad (34)$$

- Likelihood

$$P(D|\mu, \sigma^2) = \prod_{i=1}^N \mathcal{N}(x_i|\mu, \sigma^2) \propto \mathcal{N}(\bar{x}|\mu, \sigma^2/N) \quad (35)$$

- Posterior

$$p(\mu|D, \sigma^2) = \mathcal{N}(\mu|\mu_N, \sigma_N^2) \quad (36)$$

$$\mu_N = \frac{\sigma^2}{N\sigma_0^2 + \sigma^2}\mu_0 + \frac{N\sigma_0^2}{N\sigma_0^2 + \sigma^2}\mu_{ML} \quad (37)$$

$$\sigma_N^2 = \frac{\sigma^2\sigma_0^2}{N\sigma_0^2 + \sigma^2} \quad (38)$$

- Marginal likelihood

$$p(D) = \mathcal{N}(\bar{x}|\mu_0, \sigma_0^2 + \sigma^2/N) \quad (39)$$

- Posterior predictive

$$p(X|D, \sigma^2) = \mathcal{N}(X|\mu_N, \sigma_N^2 + \sigma^2) \quad (40)$$

POSTERIOR MEAN

Posterior mean $E[\theta|D]$ is a common point estimate derived from the posterior. It is convex combination of prior mean and MLE. For Beta-Binomial:

$$E[\theta|D] = w \frac{\alpha_1}{\alpha_1 + \alpha_0} + (1 - w) \frac{N_1}{N_1 + N_0} \quad (41)$$

where $w = (\alpha_1 + \alpha_0) / (N_1 + N_0 + \alpha_1 + \alpha_0)$.

For Normal-Normal:

$$E(\mu|D) = w\mu_0 + (1 - w)\bar{x} \quad (42)$$

where $w = \frac{\lambda_0}{\lambda_0 + N\lambda}$.

POSTERIOR MODE (MAP ESTIMATION)

Posterior mode is another common point estimate

$$\hat{\theta}^{MAP} = \arg \max p(\theta|D) = \arg \max \log p(D|\theta) + \log p(\theta) \quad (43)$$

This is equivalent to penalized (regularized) maximum likelihood.

For a Gaussian, posterior mode = posterior mean.

For a Beta,

$$\hat{\theta}^{MAP} = \frac{N_1 + \alpha_1 - 1}{N_0 + N_1 + \alpha_1 + \alpha_0 - 2} \quad (44)$$

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EMPIRICAL BAYES FOR A GAUSSIAN MEAN

Suppose $X_i \sim \mathcal{N}(\theta_i, \sigma^2)$ and $\theta_i \sim \mathcal{N}(\mu, \tau^2)$. We will estimate the hyper parameters using ML-II:

$$(\mu, \tau^2) = \arg \max \prod_i p(X_i | \mu, \tau^2) \quad (45)$$

$$= \arg \max \prod_i \int p(X_i | \theta_i) p(\theta_i | \mu, \tau^2) d\theta_i \quad (46)$$

$$= \arg \max \prod_i \mathcal{N}(x_i | \mu, \tau^2 + \sigma^2) \quad (47)$$

We find

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i = \bar{x} \quad (48)$$

$$\hat{\tau}^2 = s^2 - \sigma^2 \quad (49)$$

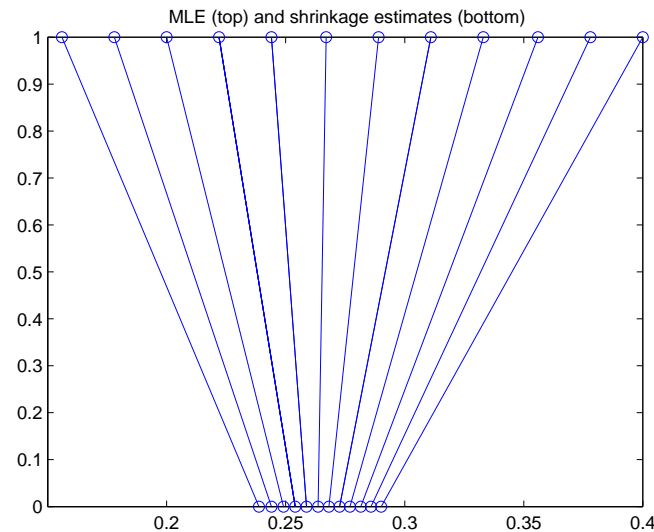
SHRINKAGE

Plugging in the estimated hyperparameters yields the following posterior mean:

$$\hat{\theta}_i = B\bar{x} + (1 - B)x_i = \bar{x} + (1 - B)(x_i - \bar{x}) \quad (50)$$

where the shrinkage factor is

$$\hat{B} = \frac{\sigma^2}{s^2} \quad (51)$$



EMPIRICAL BAYES FOR THE BETA-BINOMIAL MODEL

Suppose $X_i \sim \text{Bin}(n_i, \theta_i)$ and $\theta_i \sim \text{Beta}(\alpha, \beta)$. We can estimate the hyper parameters using ML-II:

$$(\alpha, \beta) = \arg \max \prod_i \int p(X_i | \theta_i) p(\theta_i | \alpha, \beta) d\theta_i \quad (52)$$

$$= \arg \max \prod_i \frac{B(I(X_i = 1) + \alpha, I(X_i = 0) + \beta)}{B(\alpha, \beta)} \quad (53)$$

or we can use method of moments to get

$$\hat{\alpha} = \frac{m_1(m_2 - tm_1)}{m_1((t-1)m_1 + t) - tm_2} \quad (54)$$

$$\hat{\beta} = \frac{(t - m_1)(m_2 - tm_1)}{m_1(4m_1 + t) - tm_2} \quad (55)$$

where $m_1 = \frac{1}{n} \sum_{i=1}^n X_i$ and $m_2 = \frac{1}{n} \sum_{i=1}^n X_i^2$ and $t = n_i$.

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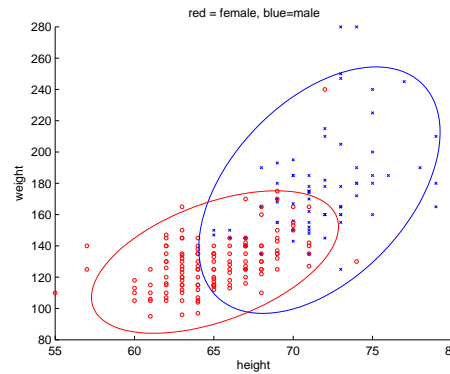
BAYESIAN (GENERATIVE) CLASSIFIERS

$$p(y|x) = \frac{p(x, y)}{p(x)} = \frac{p(x|y)p(y)}{\sum_{y'=1}^C p(x|y')p(y')} \quad (56)$$

$p(y)$ is Multinomial.

Class conditional densities $p(x|y)$ can be Gaussian or multinomial or other.

GAUSSIAN CLASS CONDITIONAL DENSITIES



We usually use the plug-in rule

$$p(x|y = c) = \mathcal{N}(x|\hat{\mu}_c, \hat{\Sigma}_c) \quad (57)$$

where the MLEs are

$$\hat{\vec{\mu}}_c = \frac{1}{N_c} \sum_{i:y_i=c} \vec{x}_i \quad (58)$$

$$\hat{\Sigma}_c = \frac{1}{N_c} \sum_{i:y_i=c} (\vec{x}_i - \hat{\vec{\mu}}_c)(\vec{x}_i - \hat{\vec{\mu}}_c)' \quad (59)$$

But we could be more Bayesian and use

$$p(x|y = c) = \int \int \mathcal{N}(x|\mu_c, \Sigma_c)p(\mu_c)p(\Sigma_c)d\mu_cd\Sigma_c \quad (60)$$

This results in a multivariate T-distribution which has fatter tails.

MULTINOMIAL CONDITIONAL DENSITIES

We make the naive Bayes assumption

$$p(x|y = c) = \prod_{j=1}^d p(x_j|y = c) \quad (61)$$

We usually use the plug-in rule

$$p(x_j|y = c) = p(x_j|y = c, \hat{\theta}_{jc}) = \prod_{k=1}^K \hat{\theta}_{jck}^{I(x_j=k)} \quad (62)$$

where the MLEs are

$$\hat{\theta}_{jck} = \frac{\sum_{i:y_i=c} I(x_{ij} = k)}{N_c} \quad (63)$$

But we could be more Bayesian and use

$$p(x_j|y = c) = \int Mu(x_j|\theta_{jc}) Dir(\theta_{jc}|\alpha_{jc}) d\theta_{jc} = \prod_{k=1}^K \bar{\theta}_{jck}^{I(x_j=k)} \quad (64)$$

where we plug in the posterior mean parameters

$$\bar{\theta}_{jck} = \frac{\sum_{i:y_i=c} I(x_{ij} = k) + \alpha_{jck}}{N_c + \sum_{k'} \alpha_{jck'}} \quad (65)$$

CLASS POSTERIOR FOR GAUSSIANS

If the class-conditional densities are Gaussian, then the posterior becomes

$$p(Y = j | \vec{x}) = \frac{p(\vec{x} | Y = j)p(Y = j)}{\sum_{k=1}^C p(\vec{x} | Y = k)p(Y = k)} \quad (66)$$

$$= \frac{\pi_j \exp \left[-\frac{1}{2}(\vec{x} - \mu_j)^T \Sigma_j^{-1} (\vec{x} - \mu_j) \right]}{\sum_k \pi_k \exp \left[-\frac{1}{2}(\vec{x} - \mu_k)^T \Sigma_k^{-1} (\vec{x} - \mu_k) \right]} \quad (67)$$

2 CLASS CASE GIVES RISE TO LOGISTIC REGRESSION

$$p(Y = 1|\vec{x}) = \sigma(\beta^T \vec{x} + \gamma) \quad (68)$$

where

$$\beta \stackrel{\text{def}}{=} \Sigma^{-1}(\mu_1 - \mu_0) \quad (69)$$

$$\gamma \stackrel{\text{def}}{=} -\frac{1}{2}(\mu_1 - \mu_0)^T \Sigma^{-1}(\mu_1 + \mu_0) + \log \frac{\pi_1}{\pi_0} \quad (70)$$

$$\sigma(z) \stackrel{\text{def}}{=} \frac{1}{1 + e^{-z}} = \frac{e^z}{e^z + 1} \quad (71)$$

K CLASS CASE GIVES RISE TO SOFTMAX REGRESSION

$$p(Y = j | \vec{x}) = \frac{\pi_j \exp \left[-\frac{1}{2}(\vec{x} - \mu_j)^T \Sigma_j^{-1} (\vec{x} - \mu_j) \right]}{\sum_k \pi_k \exp \left[-\frac{1}{2}(\vec{x} - \mu_k)^T \Sigma_k^{-1} (\vec{x} - \mu_k) \right]} \quad (72)$$

$$= \frac{\exp \left[\mu_j^T \Sigma^{-1} \vec{x} - \frac{1}{2} \mu_j^T \Sigma^{-1} \mu_j + \log \pi_j \right]}{\sum_k \exp \left[\mu_k^T \Sigma^{-1} \vec{x} - \frac{1}{2} \mu_k^T \Sigma^{-1} \mu_k + \log \pi_k \right]} \quad (73)$$

If we define

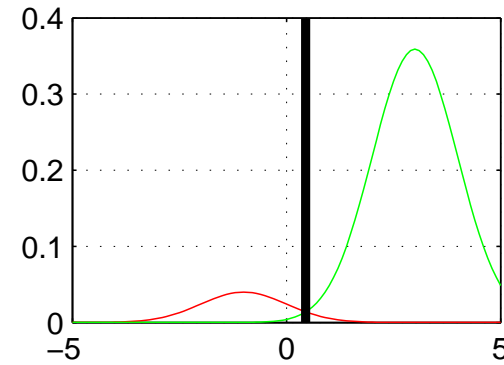
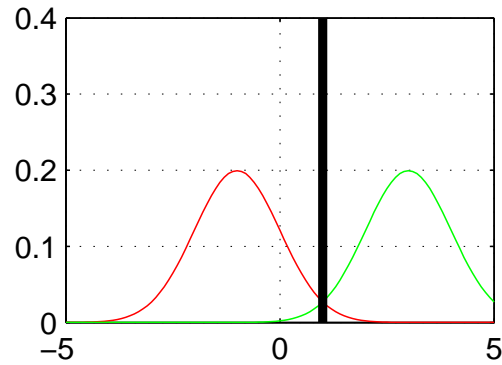
$$\theta_j \stackrel{\text{def}}{=} \begin{pmatrix} -\mu_j^T \Sigma^{-1} \mu_j + \log \pi_j \\ \Sigma^{-1} \mu_j \end{pmatrix} = \begin{pmatrix} \gamma_j \\ \beta_j \end{pmatrix} \quad (74)$$

then we find

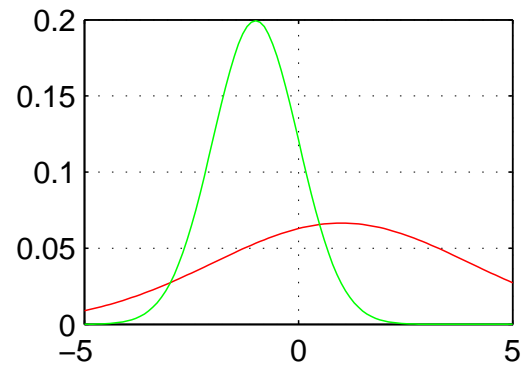
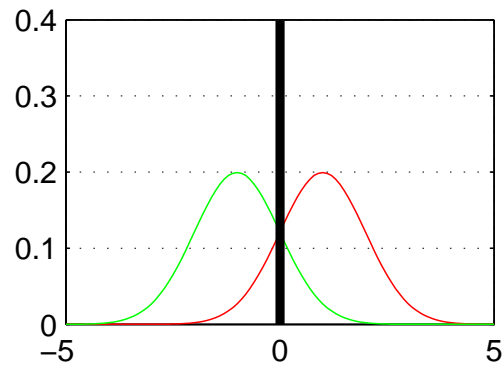
$$p(Y = j | \vec{x}) = \frac{e^{\theta_j^T \vec{x}}}{\sum_k e^{\theta_k^T \vec{x}}} = \frac{e^{\beta_j^T \vec{x} + \gamma_j}}{\sum_k e^{\beta_k^T \vec{x} + \gamma_k}} \quad (75)$$

DECISION BOUNDARY IN 1D

$\mu_1=-1.0, \mu_2=3.0, \pi_1=0.5, \sigma_1=1.0, \sigma_2=1.0$ $\mu_1=-1.0, \mu_2=3.0, \pi_1=0.1, \sigma_1=1.0, \sigma_2=1.0$



$\mu_1=1.0, \mu_2=-1.0, \pi_1=0.5, \sigma_1=1.0, \sigma_2=1.0$ $\mu_1=1.0, \mu_2=-1.0, \pi_1=0.5, \sigma_1=3.0, \sigma_2=1.0$



DECISION BOUNDARIES IN 2D

The discriminant becomes

$$g_j(\vec{x}) = \log p(\vec{x}|Y = j) + \log P(Y = j) \quad (76)$$

$$= -\frac{1}{2}(\vec{x} - \mu_j)^T \Sigma_j^{-1} (\vec{x} - \mu_j) - \frac{p}{2} \log(2\pi) - \frac{1}{2} \log |\Sigma_j| + \log p(Y = j) \quad (77)$$

If $\Sigma_c = \Sigma$ is shared, decision boundaries are linear, otherwise quadratic.

