

CS340

Bayesian concept learning cont'd

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Prior $p(h)$

- $X = \{60, 80, 10, 30\}$
- Why prefer “multiples of 10” over “even numbers”?
 - Size principle (likelihood)
- Why prefer “multiples of 10” over “multiples of 10 except 50 and 20”?
 - Prior
- Cannot learn efficiently if we have a uniform prior over all 2^{100} logically possible hypotheses

Need for prior (inductive bias)

- Consider all $2^{2^2} = 16$ possible binary functions on 2 binary inputs

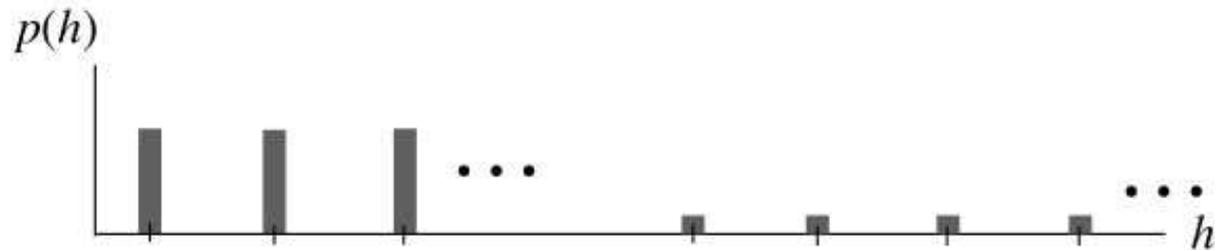
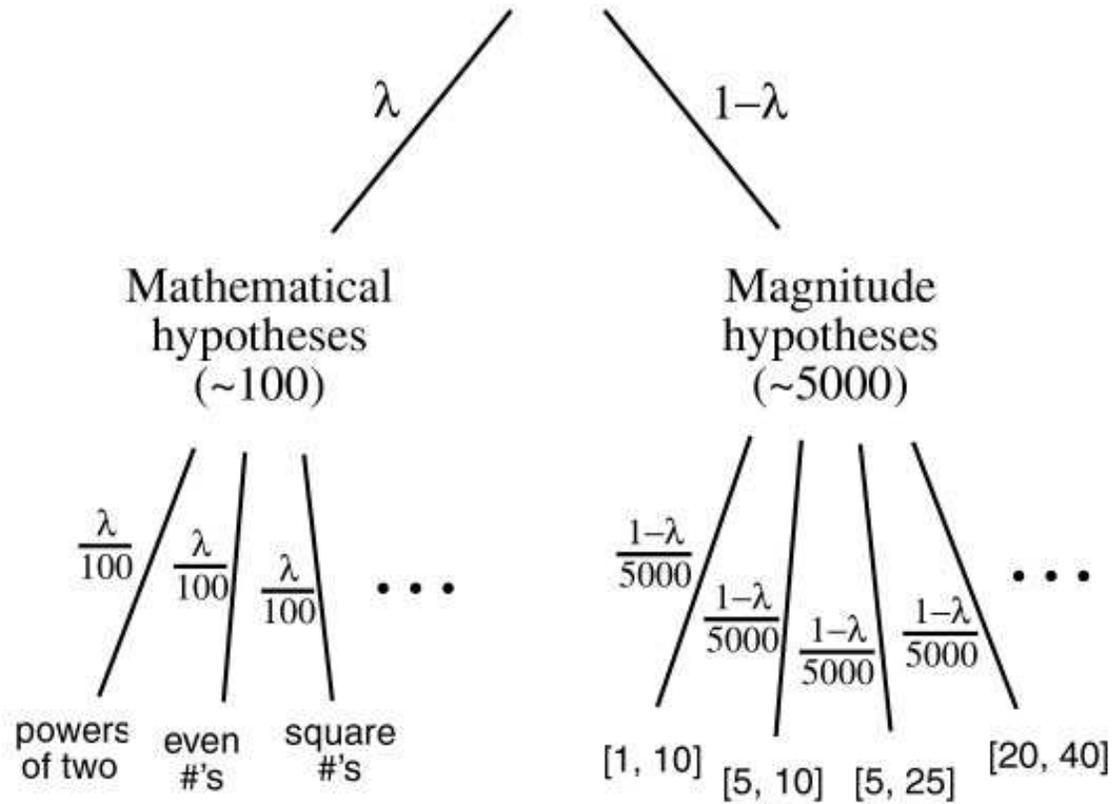
Boolean functions.

x_1	x_2	h_1	h_2	h_3	h_4	h_5	h_6	h_7	h_8	h_9	h_{10}	h_{11}	h_{12}	h_{13}	h_{14}	h_{15}	h_{16}
0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1
0	1	0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
1	0	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1
1	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1

- If we observe $(x_1=0, x_2=1, y=0)$, this removes $h_5, h_6, h_7, h_8, h_{13}, h_{14}, h_{15}, h_{16}$
- Still leaves exponentially many hypotheses!
- Cannot learn efficiently without assumptions (no free lunch theorem)

Hierarchical prior

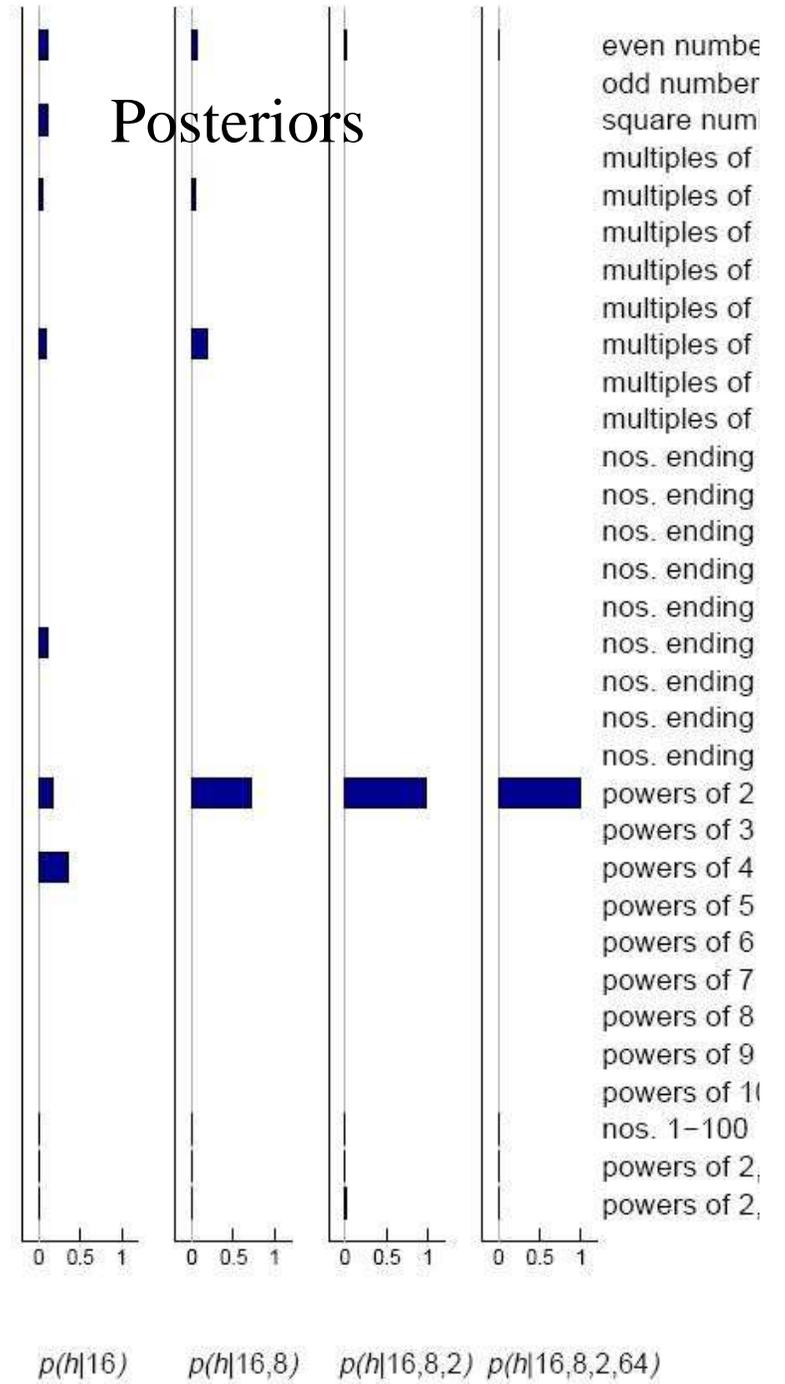
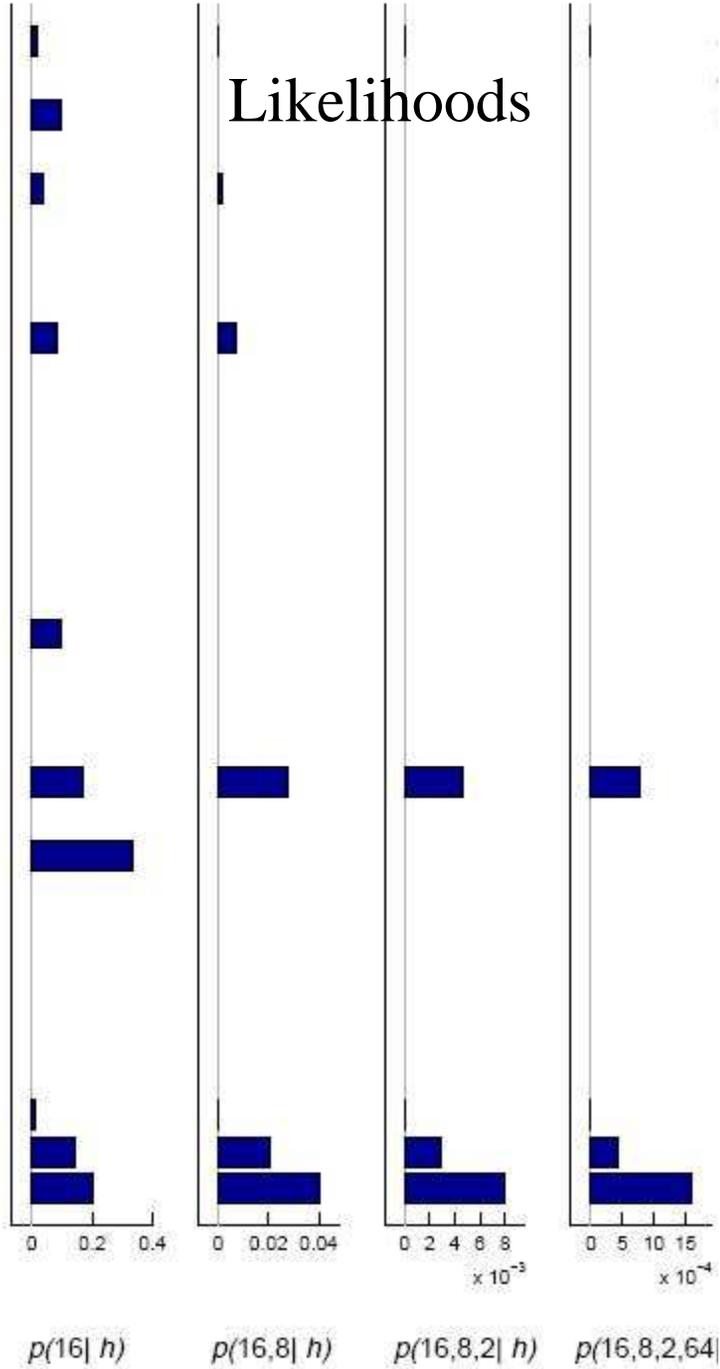
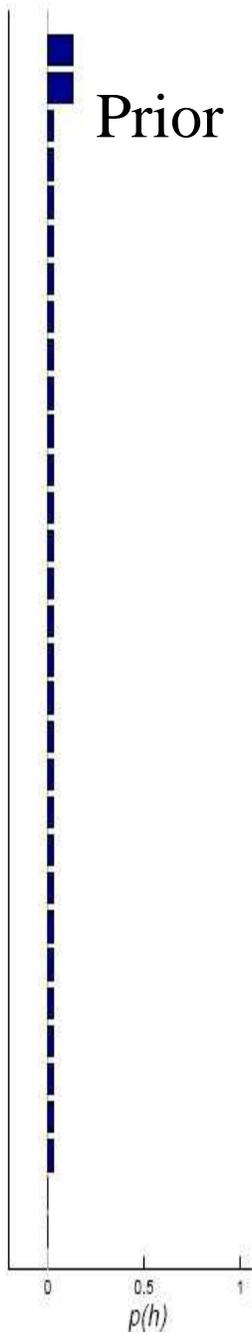
$$\text{Total probability mass} = \sum_h p(h) = 1$$



Computing the posterior

- In this talk, we will not worry about computational issues (we will perform brute force enumeration or derive analytical expressions).

$$p(h | X) = \frac{p(X | h) p(h)}{\sum_{h' \in H} p(X | h') p(h')}$$



Generalizing to new objects

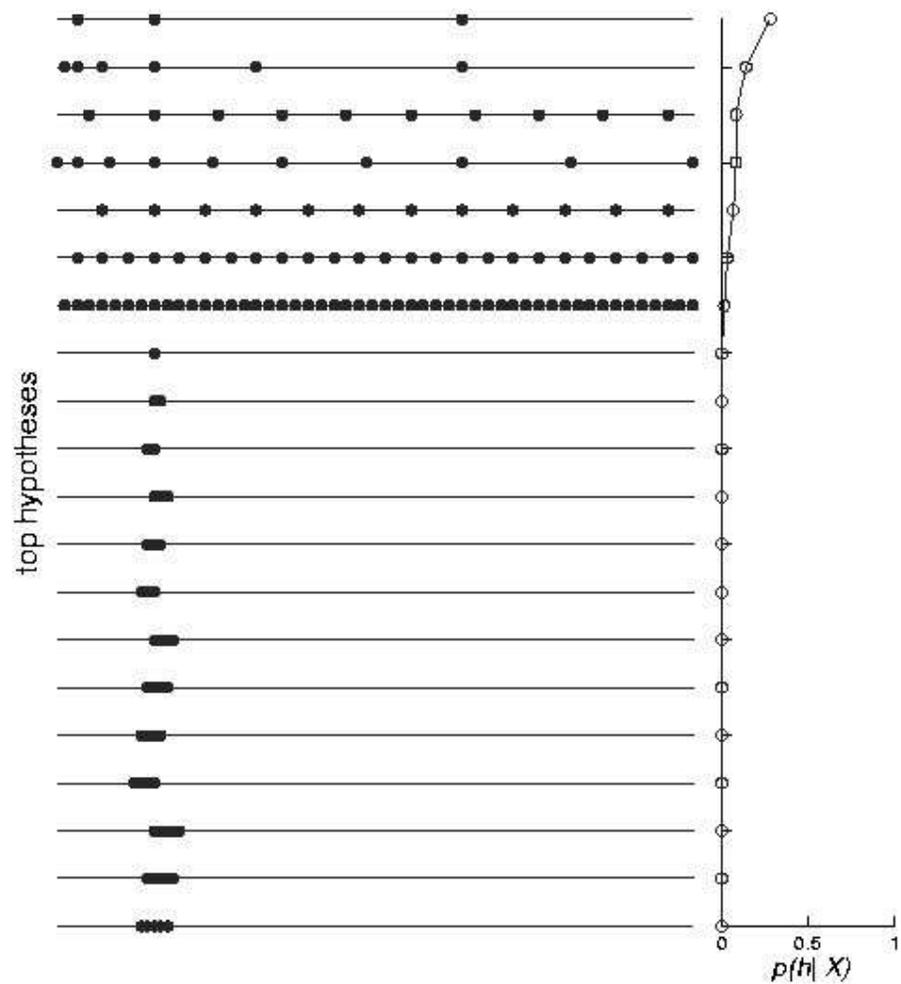
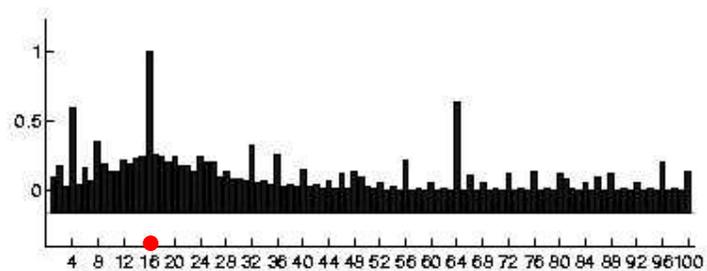
Given $p(h|X)$, how do we compute $p(y \in C | X)$, the probability that C applies to some new stimulus y ?

Posterior predictive distribution

Compute the probability that C applies to some new object y by averaging the predictions of all hypotheses h , weighted by $p(h|X)$
(Bayesian model averaging):

$$\begin{aligned} p(y \in C | X) &= \sum_{h \in H} \underbrace{p(y \in C | h)}_{\begin{cases} 1 & \text{if } y \in h \\ 0 & \text{if } y \notin h \end{cases}} p(h | X) \\ &= \sum_{h \supset \{y, X\}} p(h | X) \end{aligned}$$

Examples: 16



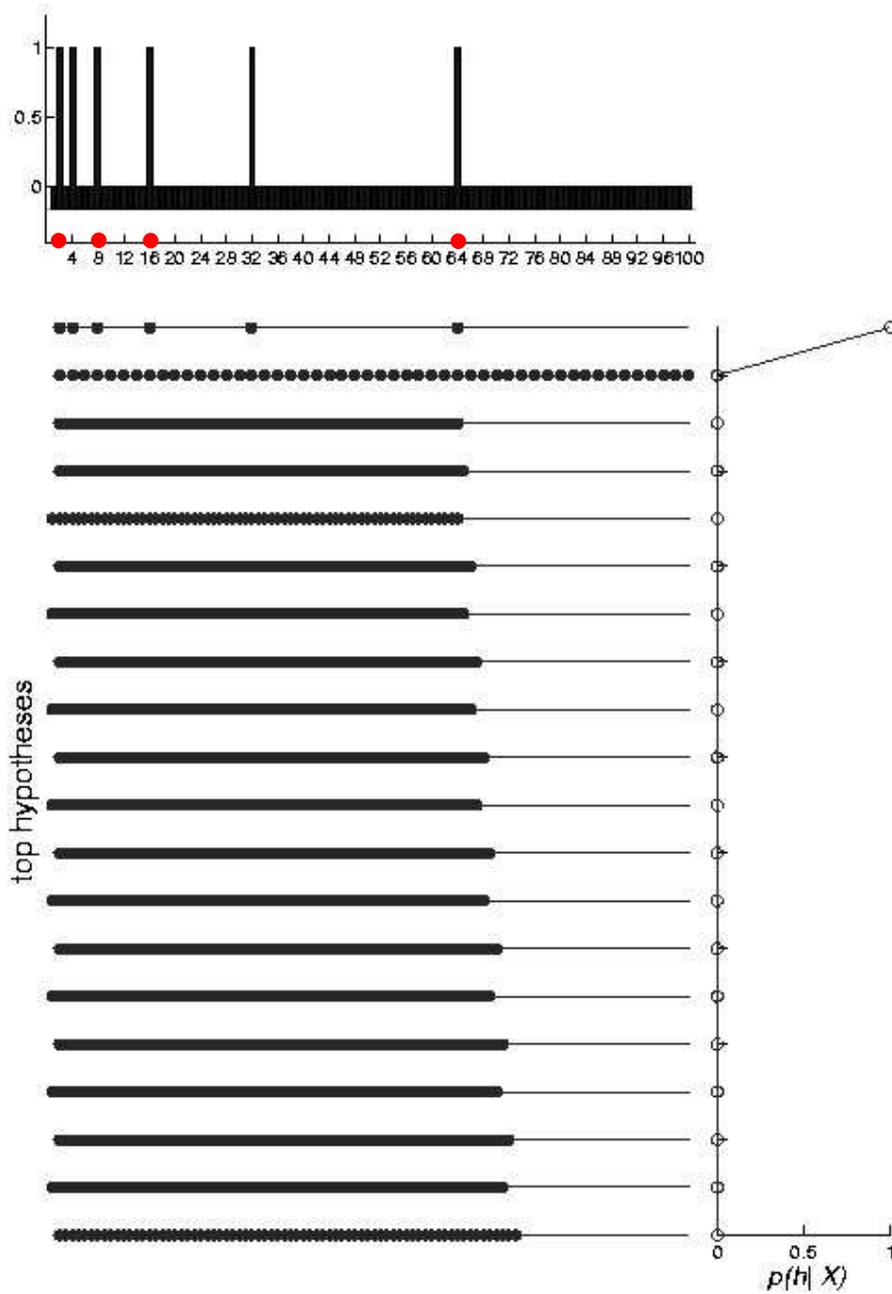
Examples:

16

8

2

64



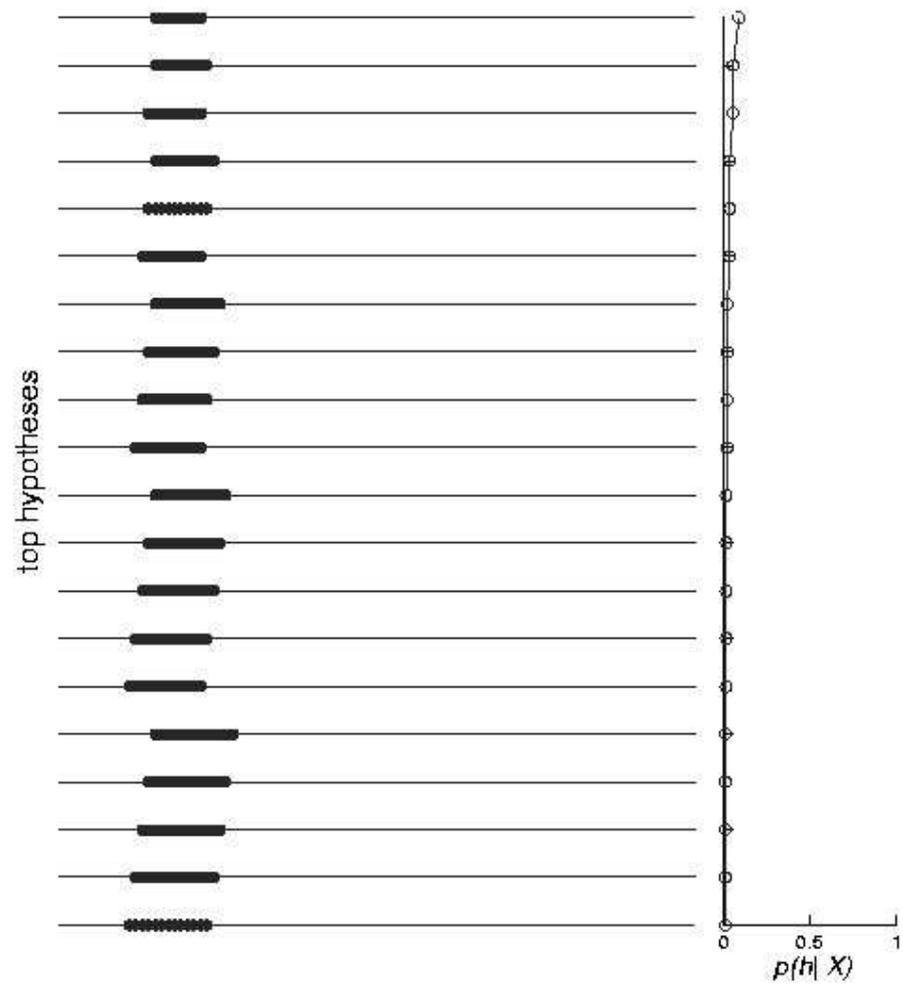
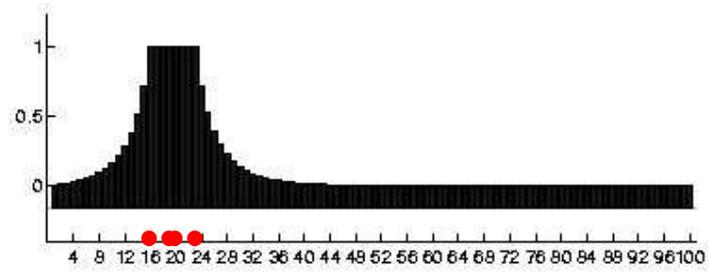
Examples:

16

23

19

20

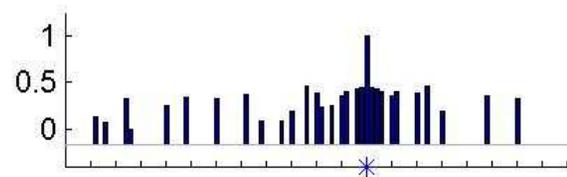
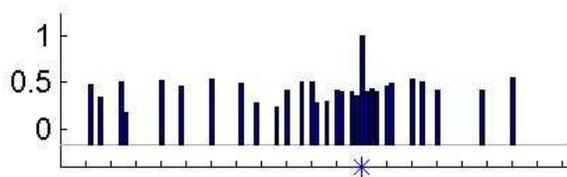


+ Examples

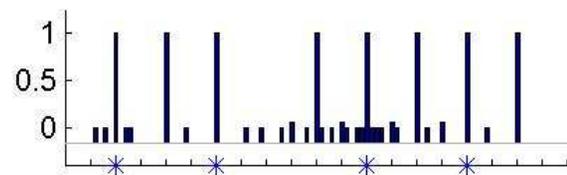
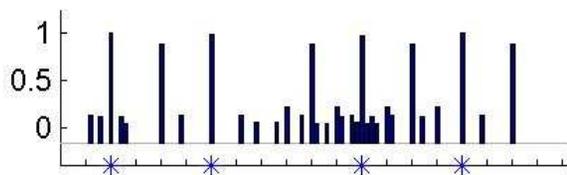
Human generalization

Bayesian Model

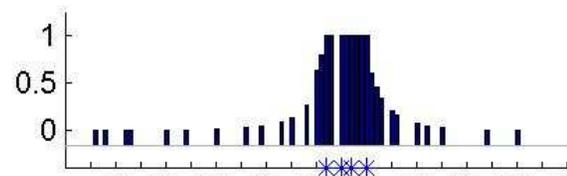
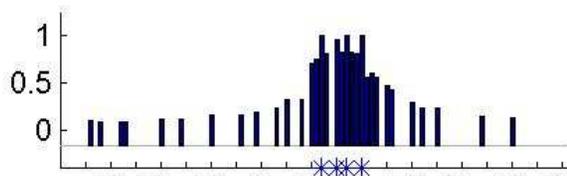
60



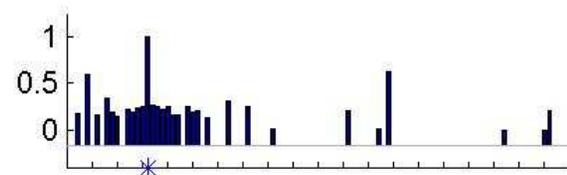
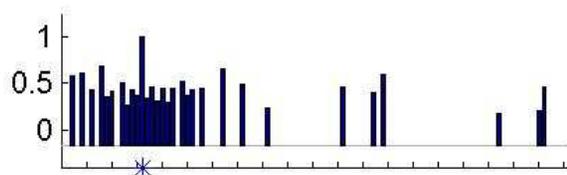
60 80 10 30



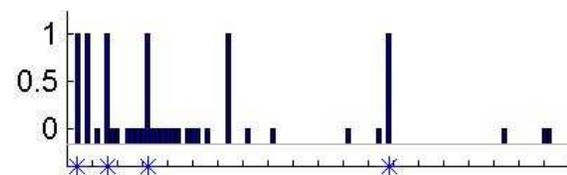
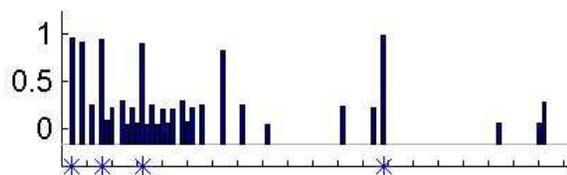
60 52 57 55



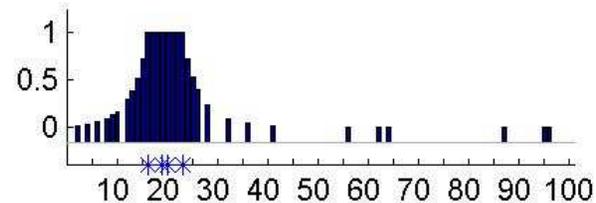
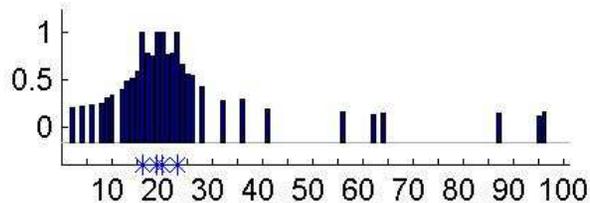
16



16 8 2 64



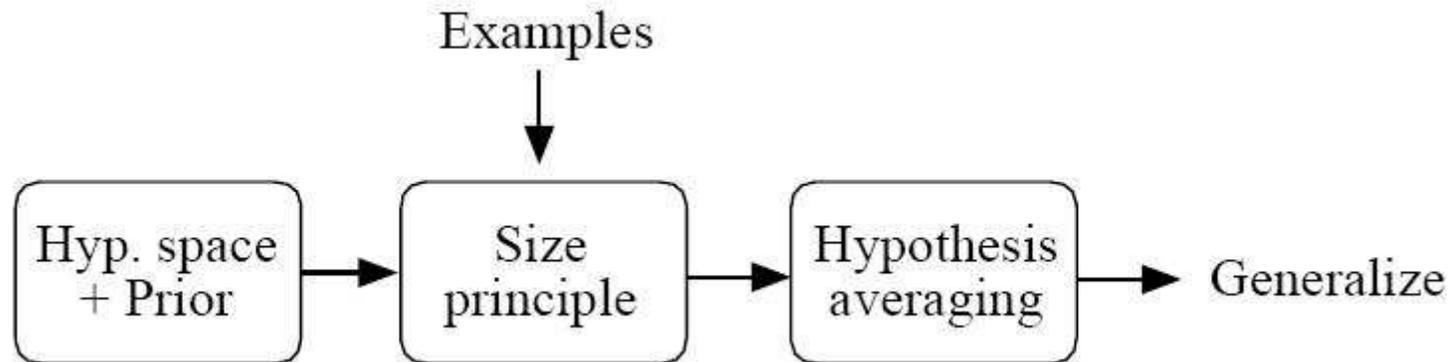
16 23 19 20



Rules and exemplars in the number game

- Hyp. space is a mixture of sparse (mathematical concepts) and dense (intervals) hypotheses.
- If data supports mathematical rule (eg $X=\{16,8,2,64\}$), we rapidly learn a rule (“aha!” moment), otherwise (eg $X=\{6,23,19,20\}$) we learn by similarity, and need many examples to get sharp boundary.

Summary of the Bayesian approach



1. Constrained hypothesis space H
2. Prior $p(h)$
3. Likelihood $p(X|h)$
4. Hypothesis (model) averaging:

$$p(y \in C | X) = \sum_h p(y \in C | h) p(h | X)$$

MAP (maximum a posterior) learning

- Instead of Bayes model averaging, we can find the mode of the posterior, and use it as a plug-in.

$$\hat{h} = \arg \max_h p(h|X) = \arg \max_h p(X|h)p(h)$$

$$p(y \in C|X) = p(y \in C|\hat{h})$$

- As $N \rightarrow \infty$, the posterior peaks around the mode, so MAP and BMA converge



$$p(y \in C|X) = \sum_h p(y \in C|h)p(h|X) \rightarrow \sum_h p(y \in C|h)\delta(h, \hat{h}) = p(y \in C|\hat{h})$$

- Cannot explain transition from similarity-based (broad posterior) to rule-based (narrow posterior)

Relation between MAP and MDL

- MAP (penalized likelihood) estimation:

$$P(h | X) \propto P(X | h) P(h)$$

- Minimum description length (MDL):

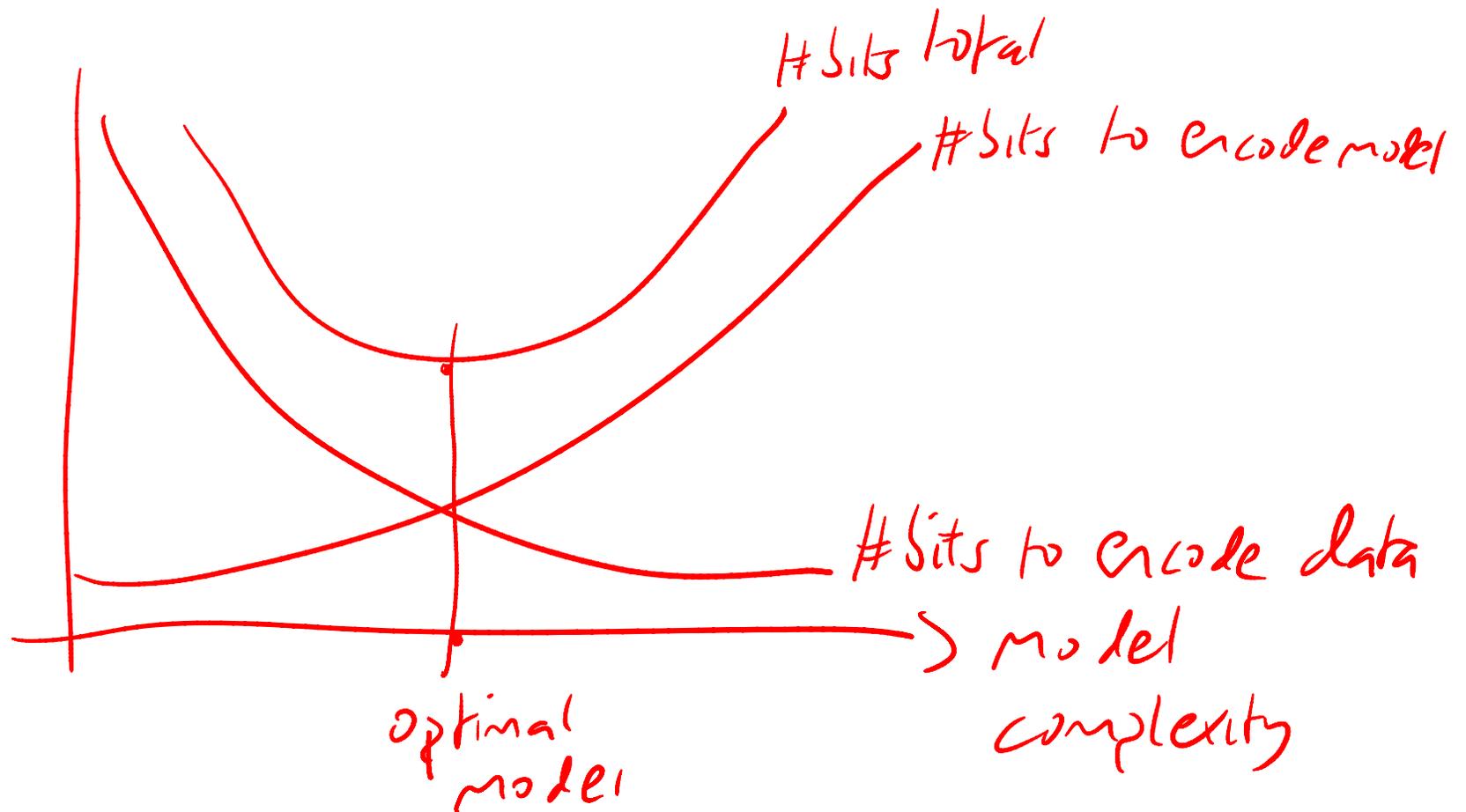
$$-\log P(h | X) = -\log P(X | h) + -\log P(h) + \text{Const}$$

↑
Total encoding
cost

↑
Cost to encode
the data given
the hypothesis

↑
Cost to encode
the hypothesis

Model selection using MDL



Bayesian Occam's Razor

- Which hypothesis is better supported by the examples {54, 6, 22}?
 - “even numbers”
 - “numbers between 6 and 54”
- Intuition: simpler hypotheses come from smaller (more constrained) hypothesis spaces.
 - “Entities should not be multiplied without necessity”
 - Prefer models with fewer free parameters.
- Both prior and likelihood contribute to this, since $p(h|X) \propto p(h) p(X|h)$

Maximum likelihood

- ML = no prior, no averaging.
- Plugs-in the MLE for prediction:

$$\hat{h} = \arg \max_h p(X|h)$$

$$p(y \in C|X) = p(y \in C|\hat{h})$$

- $X=\{16\} \rightarrow h=$ "powers of 4"
 $X=\{16,8,2,64\} \rightarrow h=$ "powers of 2".
- So predictive distribution gets broader as we get more data, in contrast to Bayes.
- ML is initially very conservative.

Large sample size behavior

- As the amount of data goes to ∞ , ML, MAP and BMA all converge to the same solution, since the likelihood overwhelms the prior, since $p(X|h)$ grows with N , but $p(h)$ is constant.
- If truth is in the hypothesis class, all methods will find it; thus they are consistent estimators.