

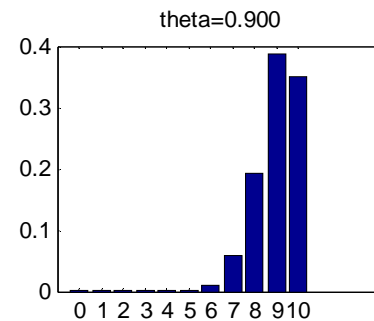
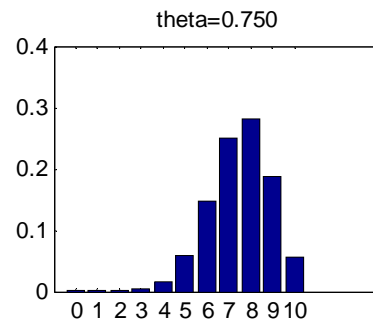
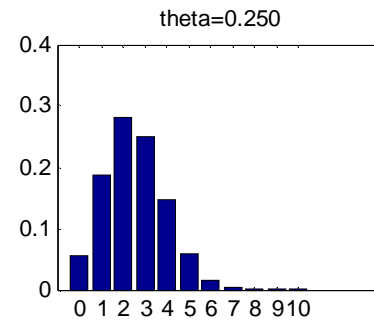
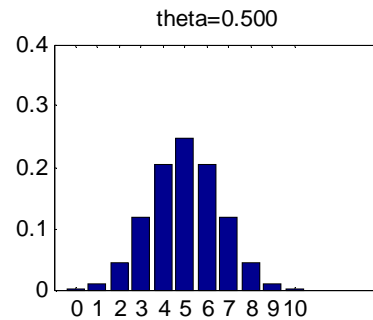
CS340 Machine learning

Bayesian statistics 2

Binomial distribution (count data)

- $X \sim \text{Binom}(\theta, N)$, $X \in \{0, 1, \dots, N\}$

$$P(X = x | \theta, N) = \binom{N}{x} \theta^x (1 - \theta)^{N-x}$$



Bernoulli distribution (binary data)

- Binomial distribution when $N=1$ is called the Bernoulli distribution.
- We write $X \sim \text{Ber}(\theta)$, $X \in \{0,1\}$

$$p(X) = \theta^X (1 - \theta)^{1-X}$$

- So $p(X=1) = \theta$, $p(X=0) = 1-\theta$



Bernoulli likelihood function

- The likelihood is

$$\begin{aligned} L(\theta) &= p(D|\theta) = \prod_{n=1}^N p(x_n|\theta) \\ &= \prod_n \theta^{I(x_n=1)} (1 - \theta)^{I(x_n=0)} \\ &= \theta^{\sum_n I(x_n=1)} (1 - \theta)^{\sum_n I(x_n=0)} \\ &= \theta^{N_1} (1 - \theta)^{N_0} \end{aligned}$$

We say that N_0 and N_1 are sufficient statistics of D for θ

This is the same as the Binomial likelihood function, up to constant factors.

Summary of beta-Bernoulli model

- **Prior** $p(\theta) = \text{Beta}(\theta|\alpha_1, \alpha_0) = \frac{1}{B(\alpha_1, \alpha_0)} \theta^{\alpha_1-1} (1-\theta)^{\alpha_0-1}$
- **Likelihood** $p(D|\theta) = \theta^{N_1} (1-\theta)^{N_0}$
- **Posterior** $p(\theta|D) = \text{Beta}(\theta|\alpha_1 + N_1, \alpha_0 + N_0)$
- **Posterior predictive** $p(X = 1|D) = \frac{\alpha_1 + N_1}{\alpha_1 + \alpha_0 + N}$

Marginal likelihood

- When performing Bayesian model selection and empirical Bayes estimation, we will need

$$p(D) = \int p(D|\theta)p(\theta)d\theta$$

- This is given by a ratio of the posterior and prior normalizing constants

$$\begin{aligned} p(\theta|D) &= \frac{p(\theta)p(D|\theta)}{p(D)} \\ &= \frac{1}{p(D)} \left[\frac{1}{B(\alpha_1, \alpha_0)} \theta^{\alpha_1-1} (1-\theta)^{\alpha_0-1} \right] [\theta^{N_1} (1-\theta)^{N_0}] \\ &= \frac{\theta^{\alpha'_1-1} (1-\theta)^{\alpha'_0-1}}{B(\alpha'_1, \alpha'_0)} \\ p(D) &= \frac{B(\alpha'_1, \alpha'_0)}{B(\alpha_1, \alpha_0)} \quad \alpha'_1 = \alpha_1 + N_1, \quad \alpha'_0 = \alpha_0 + N_0 \end{aligned}$$

Summary of beta-Bernoulli model

- **Prior** $p(\theta) = \text{Beta}(\theta|\alpha_1, \alpha_0) = \frac{1}{B(\alpha_1, \alpha_0)} \theta^{\alpha_1-1} (1-\theta)^{\alpha_0-1}$
- **Likelihood** $p(D|\theta) = \theta^{N_1} (1-\theta)^{N_0}$
- **Posterior** $p(\theta|D) = \text{Beta}(\theta|\alpha_1 + N_1, \alpha_0 + N_0)$
- **Posterior predictive** $p(X = 1|D) = \frac{\alpha_1 + N_1}{\alpha_1 + \alpha_0 + N}$
- **Marginal likelihood**

$$p(D) = \frac{B(\alpha_1 + N_1, \alpha_0 + N_0)}{B(\alpha_1, \alpha_0)} = \frac{\Gamma(\alpha_1 + N_1)\Gamma(\alpha_0 + N_0)}{\Gamma(\alpha_1 + N_1 + \alpha_0 + N_0)} \frac{\Gamma(\alpha_1 + \alpha_0)}{\Gamma(\alpha_1)\Gamma(\alpha_0)}$$

From coins to dice

- Let $(X_1, \dots, X_d) \mid N \sim \text{Multinomial}(\theta, N)$

$$P(x_1, \dots, x_d \mid \theta, N) = \binom{N}{x_1 \dots x_d} \prod_{i=1}^d \theta_i^{x_i}$$

X_i 's no longer conditionally independent since $\sum_i x_i = N$

$$= \frac{N!}{x_1! x_2! \dots x_d!} \prod_{i=1}^d \theta_i^{x_i}$$

We also require $\sum_i \theta_i = 1$.

$$= \left(\sum_i x_i \right)! \prod_i \frac{\theta_i^{x_i}}{x_i!}$$

$X_i \in \{0, \dots, N\}$ = number of times face i occurs

Multinomial($\theta, 1$)

- Let $(X_1, \dots, X_d) \sim \text{Multinomial}(\theta, 1)$

$$P(x_1, \dots, x_d | \theta) = \prod_{i=1}^d \theta_i^{x_i}$$

- Since $\sum_i X_i = 1$, only one “bit” can be on, eg $(0, 1, 0)$ means face 2 occurred.
- Let $X \in \{1, \dots, d\}$ represent the event that occurred.

$$P(X = k | \theta) = \prod_{i=1}^d \theta_i^{I(X=k)} = \theta_k$$

Likelihood function for the multinomial

- Let $D = (X_1, \dots, X_N)$, where $X_i \in \{1, \dots, K\}$

$$P(D|\theta) \propto \prod_{n=1}^N \prod_{k=1}^K \theta_k^{x_{nk}} = \prod_k \theta_k^{\sum_n x_{nk}} = \prod_k \theta_k^{N_k}$$

- The N_k are the sufficient statistics

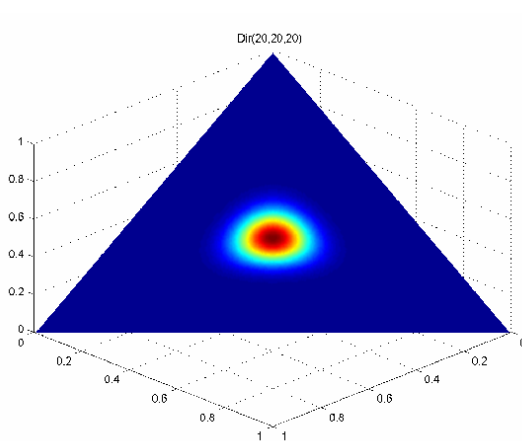
Dirichlet distribution

- Generalization of Beta to K dimensions $E[x_k] = \alpha_k / (\sum_j \alpha_j)$

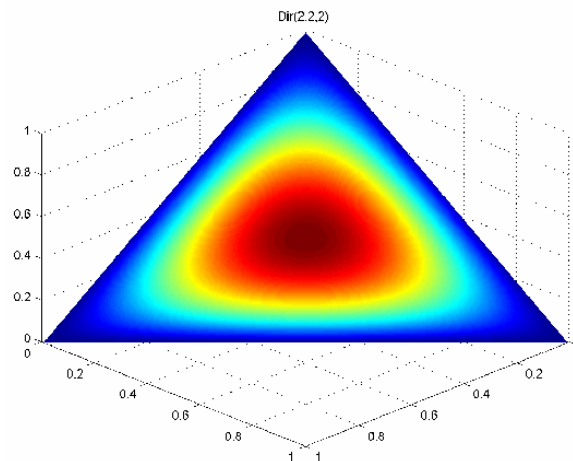
$$p(x|\alpha) = \mathcal{D}(x|\alpha) = \frac{1}{Z(\alpha)} \cdot x_1^{\alpha_1-1} \cdot x_2^{\alpha_2-1} \cdot \dots \cdot x_K^{\alpha_K-1} I\left(\sum_{k=1}^K x_k - 1\right)$$

- Normalization constant

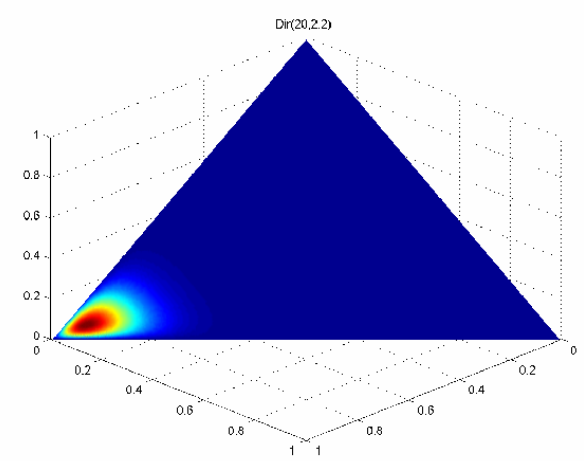
$$Z(\alpha) = \int \dots \int x_1^{\alpha_1-1} \dots x_K^{\alpha_K-1} dx_1 \dots dx_K = \frac{\prod_{j=1}^K \Gamma(\alpha_j)}{\Gamma(\sum_{j=1}^K \alpha_j)}$$



(20,20,20)



(2,2,2)



(20,2,2)

Summary of Dirichlet-multinomial model

- $X_n \sim \text{Mult}(\theta, 1)$, $p(X_n=k) = \theta_k$
- **Prior** $p(\theta) = \text{Dir}(\theta|\alpha_1, \dots, \alpha_K) = \frac{1}{Z(\alpha_1, \dots, \alpha_K)} \prod_{k=1}^K \theta_k^{\alpha_k - 1}$
- **Likelihood** $p(D|\theta) = \prod_{k=1}^K \theta_k^{N_k}$
- **Posterior** $p(\theta|D) = \text{Dir}(\theta|\alpha_1 + N_1, \dots, \alpha_K + N_K)$
- **Posterior predictive** $p(X = k|D) = \frac{\alpha_k + N_k}{\sum_{k'} \alpha_{k'} + N_{k'}}$
- **Marginal likelihood**

$$p(D) = \frac{Z(\vec{N} + \vec{\alpha})}{Z(\vec{\alpha})} = \frac{\Gamma(\sum_k \alpha_k)}{\Gamma(N + \sum_k \alpha_k)} \prod_k \frac{\Gamma(N_k + \alpha_k)}{\Gamma(\alpha_k)}$$

Normal-Normal model

- Consider estimating the mean of a Gaussian whose variance is known.
- The natural conjugate prior is Gaussian.
- So the posterior is also Gaussian (“Gaussian times Gaussian gives Gaussian”).
- The algebra is rather messy (see handout), so we will just state and interpret the results.

Normal-normal model

- Likelihood

$$p(D|\mu) = \prod_{n=1}^N \mathcal{N}(x_n|\mu, \sigma^2)$$
$$\propto \exp\left(-\frac{N}{2\sigma^2}(\bar{x} - \mu)^2\right) \propto \mathcal{N}(\bar{x}|\mu, \frac{\sigma^2}{N})$$

- Natural conjugate prior

$$p(\mu) \propto \exp\left(-\frac{1}{2\sigma_0^2}(\mu - \mu_0)^2\right) \propto \mathcal{N}(\mu|\mu_0, \sigma_0^2)$$

- Posterior

$$p(\mu|D) = \mathcal{N}(\mu|\mu_N, \sigma_N^2)$$

$$\mu_N = \frac{\sigma^2}{N\sigma_0^2 + \sigma^2}\mu_0 + \frac{N\sigma_0^2}{N\sigma_0^2 + \sigma^2}\bar{x} = \sigma_N^2 \left(\frac{\mu_0}{\sigma_0^2} + \frac{N\bar{x}}{\sigma^2} \right)$$

$$\sigma_N^2 = \frac{\sigma^2\sigma_0^2}{N\sigma_0^2 + \sigma^2} = \frac{1}{\frac{N}{\sigma_0^2} + \frac{1}{\sigma^2}}$$

$$\frac{1}{\sigma_N^2} = \frac{N}{\sigma_0^2} + \frac{1}{\sigma^2}$$

$$\lambda_N = N\lambda + \lambda_0$$

Posterior mean

- Consider $N=1$.

$$\mu_1 = \frac{\sigma^2}{\sigma^2 + \sigma_0^2} \mu_0 + \frac{\sigma_0^2}{\sigma^2 + \sigma_0^2} x$$

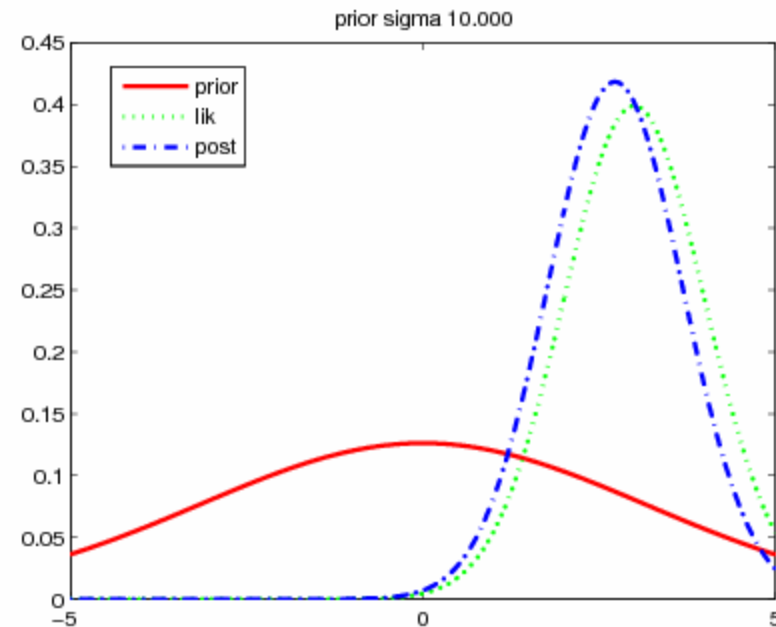
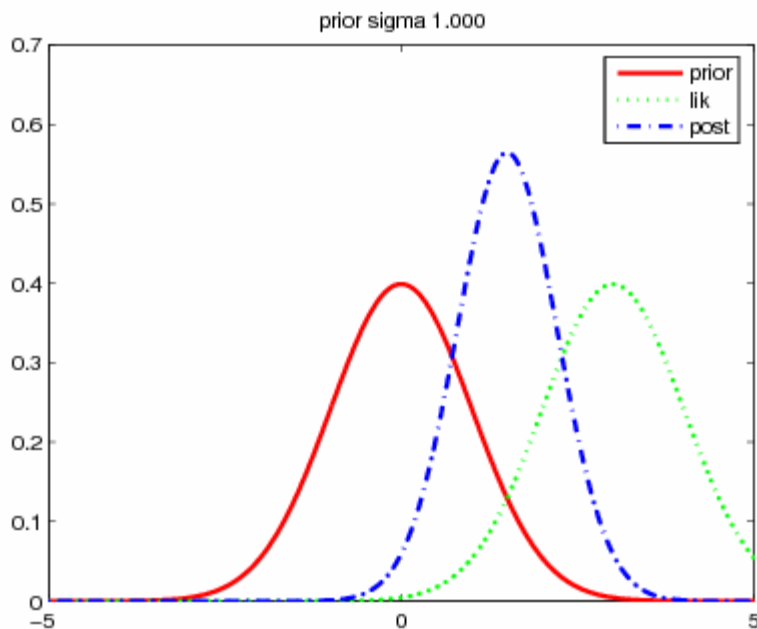
Convex comb of prior and MLE

$$= \mu_0 + (x - \mu_0) \frac{\sigma_0^2}{\sigma^2 + \sigma_0^2}$$

Prior plus data correction term

$$= x - (x - \mu_0) \frac{\sigma^2}{\sigma^2 + \sigma_0^2}$$

Data shrunk towards prior



Posterior precision

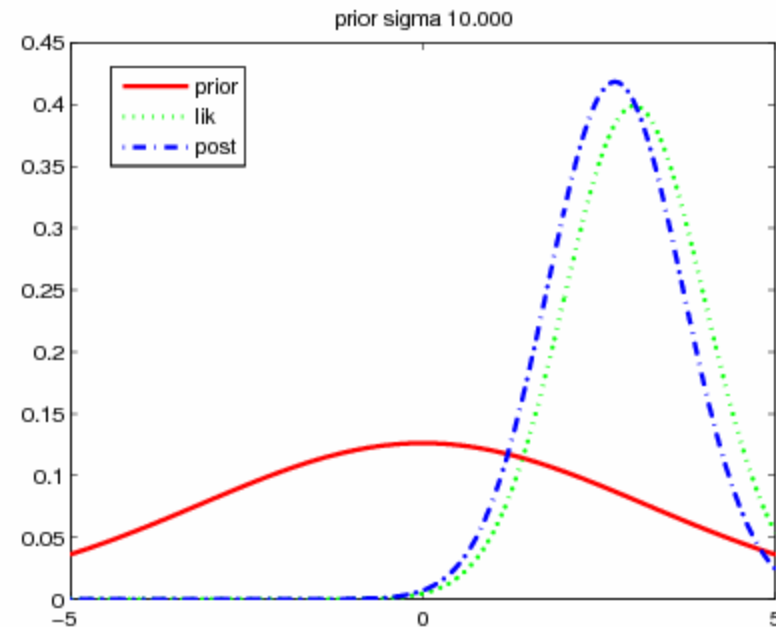
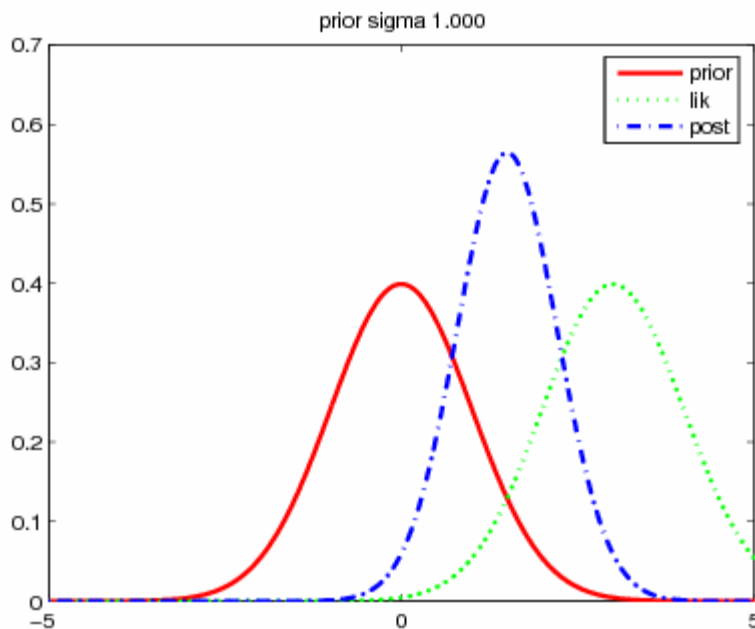
- Precision = 1/variance, $\lambda = 1/\sigma^2$.
- Precisions add, means are averaged.

$$p(\mu|D, \lambda) = \mathcal{N}(\mu|\mu_N, \lambda_N^{-1})$$

$$\lambda_N = \lambda_0 + N\lambda$$

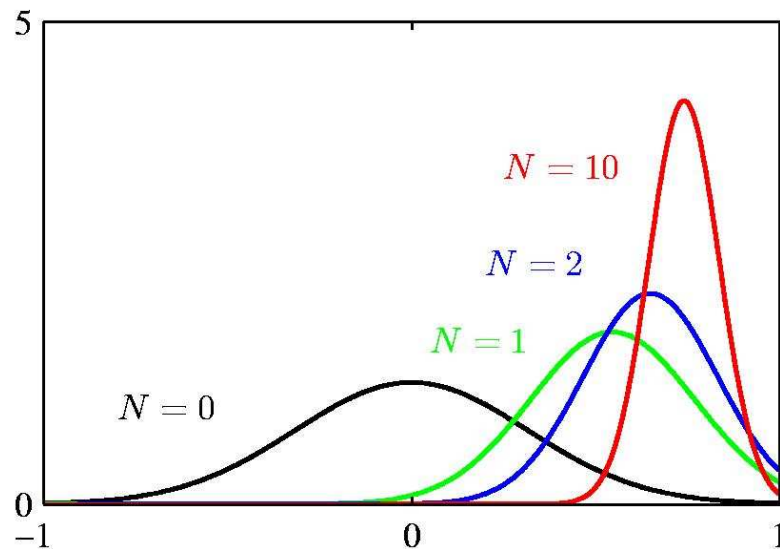
$$\mu_N = \frac{\bar{x}N\lambda + \mu_0\lambda_0}{\lambda_N} = w\bar{x} + (1-w)\mu_0$$

$$w = \frac{N\lambda}{\lambda_N}$$



Sequential updating

- Suppose true mean=0.8, true variance=0.1.
- $p(\mu|D)$ rapidly approaches a delta function centered on the true mean.



Posterior predictive distribution

- The predictive variance is the observation noise σ^2 plus the uncertainty about μ , σ_N^2

$$\begin{aligned} p(x|D) &= \int p(x|\mu)p(\mu|D)d\mu \\ &= \int \mathcal{N}(x|\mu, \sigma^2)\mathcal{N}(\mu|\mu_N, \sigma_N^2)d\mu \\ &= \mathcal{N}(x|\mu_N, \sigma_N^2 + \sigma^2) \end{aligned}$$

- Or, future $X =$ prior mean $\mu +$ noise ϵ

$$\begin{aligned} X &= \mu + \epsilon \\ \mu &\sim \mathcal{N}(\mu_n, \sigma_n^2) \\ \epsilon &\sim \mathcal{N}(0, \sigma^2) \\ E[X] &= E[\mu] + E[\epsilon] = \mu_n + 0 \\ \text{Var}[X] &= \text{Var}[\mu] + \text{Var}[\epsilon] = \sigma_n^2 + \sigma^2 \end{aligned}$$

Summary of Normal-Normal model

- Prior $p(\mu) = \mathcal{N}(\mu|\mu_0, (\lambda_0)^{-1})$
- Likelihood $p(D|\mu) = \prod_{n=1}^N \mathcal{N}(x_n|\mu, \lambda^{-1})$
- Posterior
$$p(\mu|D) = \mathcal{N}(\mu|\mu_N, (\lambda_N)^{-1})$$
$$\lambda_N = \lambda_0 + N\lambda$$
$$\mu_N = \frac{\bar{x}N\lambda + \mu_0\lambda_0}{\lambda_N}$$

- Posterior predictive

$$p(x|D) = \mathcal{N}(x|\mu_N, \sigma_N^2 + \sigma^2)$$

- Marginal likelihood

Too messy to print here (see handout)