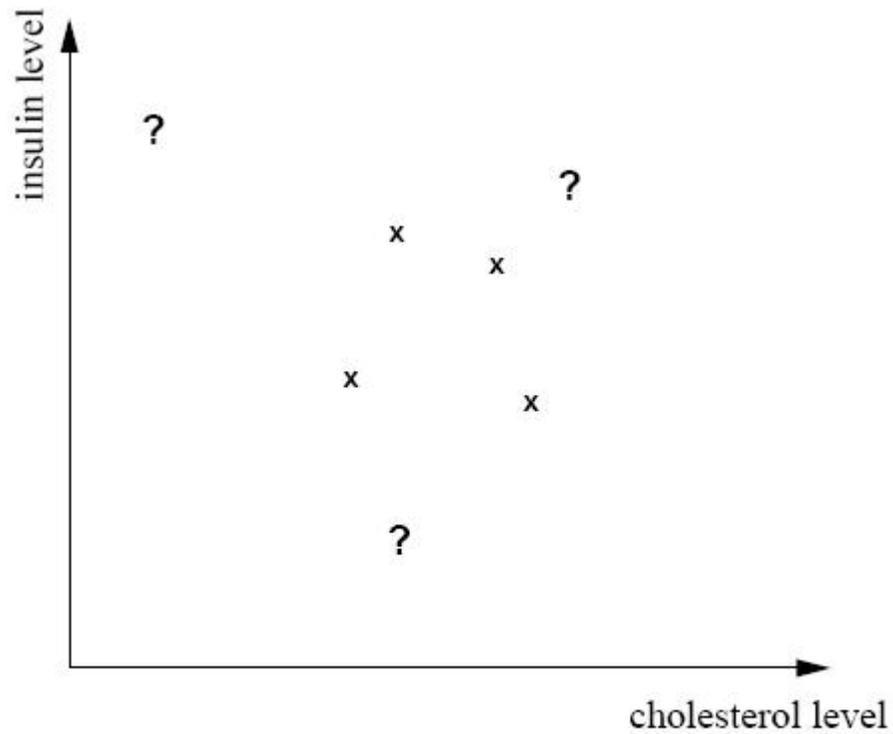


CS340

Bayesian concept learning cont'd

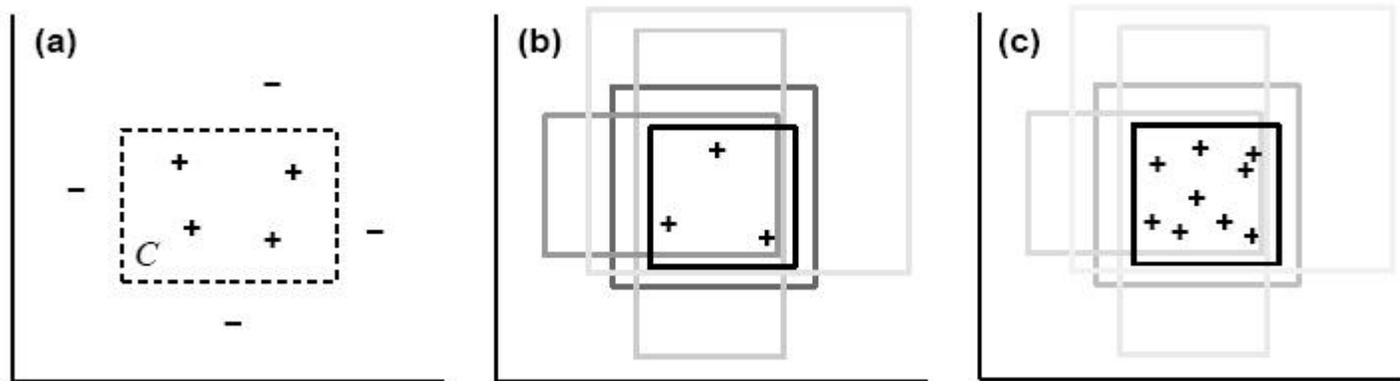
Kevin Murphy

# Healthy levels game



"healthy levels"

# Hypothesis space



$$h = (\ell_1, \ell_2, s_1, s_2)$$

Healthy levels of insulin/ cholesterol must lie between a minimum and maximum. Healthy levels of a chemical presumably lie between zero and a maximum.

# Likelihood (strong sampling)

- $p(X|h) = 1/|h|^n$  if all  $x_i \in h$ ,  
where  $|h| = s_1 \times s_2$
- $p(X|h) = 0$  if any  $x_i$  outside  $h$

# Prior $p(h)$

- Use uninformative, but location and scale-invariant, prior (Jeffrey's principle)

$$p(h) \propto \frac{1}{s_1 s_2}$$

This also happens to be conjugate to  $p(X|h)$ .

- We will explain this later...

# Posterior predictive

$$p(y \in C|X) = \int_{h \in H} p(y \in C|h)p(h|X)dh$$

Since the hypothesis space is continuous, we must use an integral instead of a sum...

# Insert hairy math

$l - s \leq -r$ , where  $s$  is size of the rectangle. Hence

$$p(X) = \int_{h \in \mathcal{H}_X} \frac{p(h)}{|h|^n} dh \quad (1.34)$$

$$= \int_{s=r}^{\infty} \int_{l=0}^{l-r} \frac{p(s)}{s^n} dl ds \quad (1.35)$$

$$= \int_{s=r}^{\infty} \left[ \int_{l=0}^{s-r} \frac{1}{s^{n+1}} dl \right] ds \quad (1.36)$$

$$= \int_{s=r}^{\infty} \frac{1}{s^{n+1}} [l]_0^{s-r} ds \quad (1.37)$$

$$= \int_{s=r}^{\infty} \frac{s-r}{s^{n+1}} ds \quad (1.38)$$

Now, using integration by parts

$$I = \int_a^b f(x)g'(x)dx = [f(x)g(x)]_a^b - \int_a^b f'(x)g(x)dx \quad (1.39)$$

with the substitutions

$$f(s) = s - r \quad (1.40)$$

$$f'(s) = 1 \quad (1.41)$$

$$f'(s) = s^{-n-1} \quad (1.42)$$

$$g(s) = \frac{s^{-n}}{-n} \quad (1.43)$$

we have

$$p(X) = \left[ \frac{(s-r)s^{-n}}{-n} \right]_r^{\infty} - \int_r^{\infty} \frac{s^{-n}}{-n} ds \quad (1.44)$$

$$= \left[ \frac{s^{-n+1}}{-n} + \frac{rs^{-n}}{n} - \frac{-1}{n} \frac{s^{-n+1}}{-n+1} \right]_r^{\infty} \quad (1.45)$$

$$= \frac{r^{-n+1}}{n} - \frac{rs^{-n}}{n} + \frac{r^{-n+1}}{n(n-1)} \quad (1.46)$$

$$= \frac{1}{nr^{n-1}} - \frac{r}{nr^{n-1}r} + \frac{1}{n(n-1)r^{n-1}} \quad (1.47)$$

$$= \frac{1}{n(n-1)r^{n-1}} \quad (1.48)$$

To compute the generalization function, let us suppose  $y$  is outside the range spanned by the examples (otherwise the probability of generalization is 1). Without loss of generality assume  $y > 0$ . Let  $d$  be the distance from  $y$  to the closest observed example. Then we can compute the numerator in Equation 1.33 by replacing  $r$  with  $r+d$  in the limits of integration (since we have expanded the range of the data by adding  $y$ ), yielding

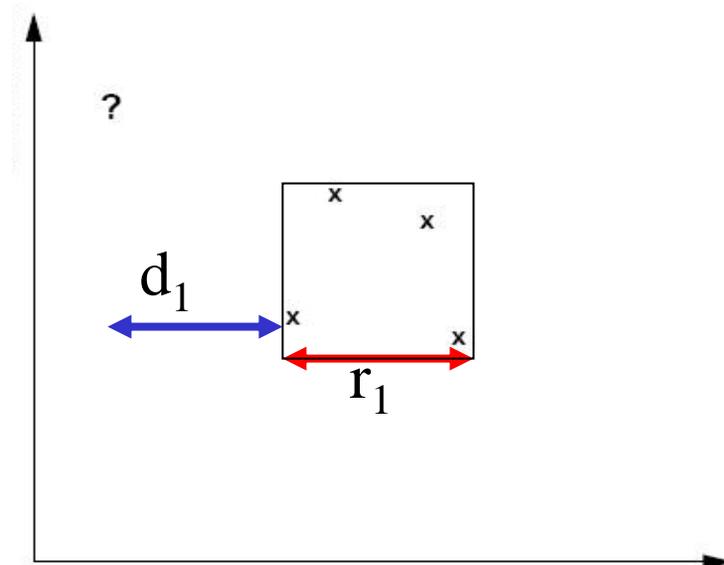
$$p(y \in C, X) = \int_{h \in \mathcal{H}_{X,y}} \frac{p(h)}{|h|^n} dh \quad (1.49)$$

$$= \int_{r+d}^{\infty} \int_0^{l-(r+d)} \frac{p(s)}{s^n} dl ds \quad (1.50)$$

$$= \frac{1}{n(n-1)(r+d)^{n-1}} \quad (1.51)$$

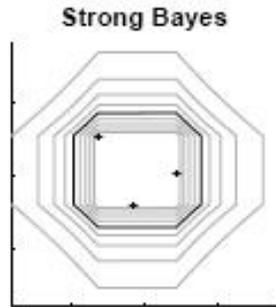
And the answer is...

$$p(y \in C|X) = \left[ \frac{1}{(1 + \tilde{d}_1/r_1)(1 + \tilde{d}_2/r_2)} \right]^{n-1}$$

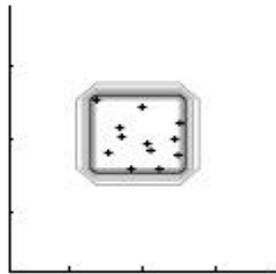
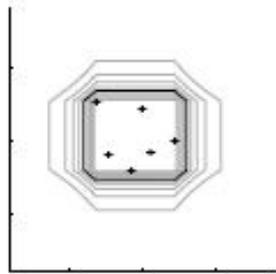


$\tilde{d}_i$  = 0 if  $y \in$  range of  $X_i$   
= distance of  $y$  from closest  $X_i$

# Behavior for $n=3, 6, 12$



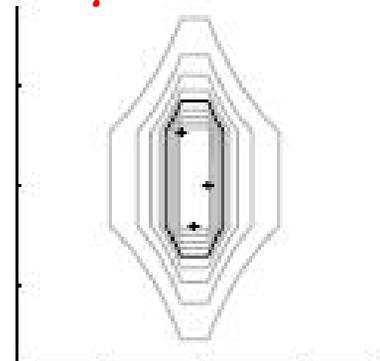
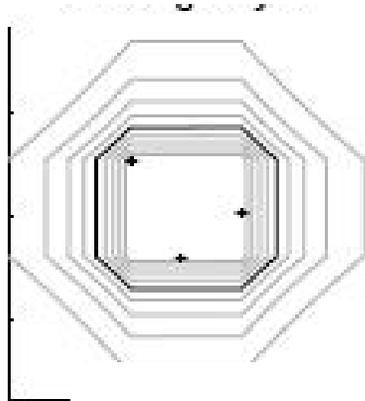
The size principle implies the smallest rectangle has highest likelihood, but there are many other consistent rectangles which are only slightly less likely. These get averaged to give a smooth generalization gradient.



As  $N \rightarrow \infty$ , the larger hypotheses become exponentially less likely, so we converge on the ML solution (the most specific/ MIN hypothesis)

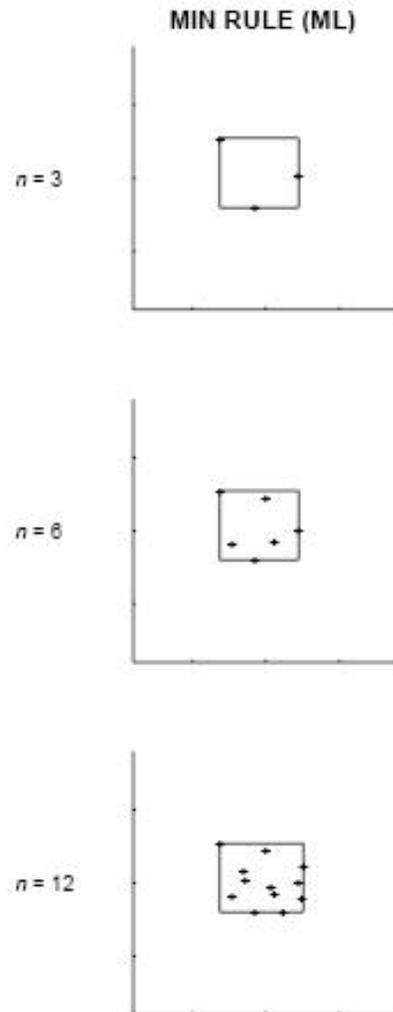
# Behavior for different shapes

- $n=3$  in both cases, but on right,  $r_1 \ll r_2$ , so we generalize more along dimension 2
- Algebraically,  $d_1/r_1$  is big, so  $p(y \in C | X)$  is small unless  $y$  is inside  $X$
- Intuitively, it would be a suspicious coincidence if the rectangle was wide but  $r_1$



$$p(y \in C | X) = \left[ \frac{1}{(1 + \tilde{d}_1/r_1)(1 + \tilde{d}_2/r_2)} \right]^{n-1}$$

# Behavior of max likelihood/ MAP



There is no generalization gradient  
(a point is either in or out of  $h$ ).

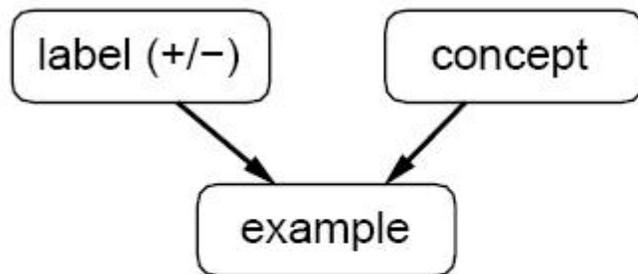
The ML/MAP hyp. is the smallest  
enclosing rectangle.

This is a good approximation to  
Bayes when  $N$  is large.

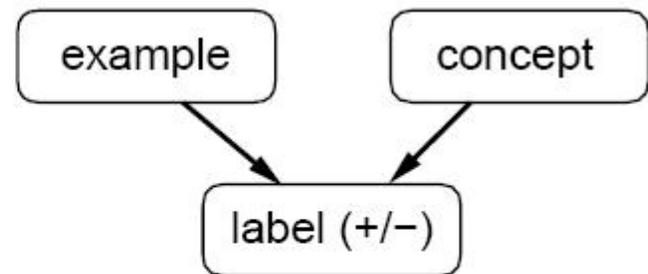
# Weak sampling

- Examples are not sampled from the concept, they are just labeled as consistent or not.

$$p(X|h) = \begin{cases} 1 & \text{if } x_1, \dots, x_n \in h \\ 0 & \text{if any } x_i \notin h \end{cases}$$



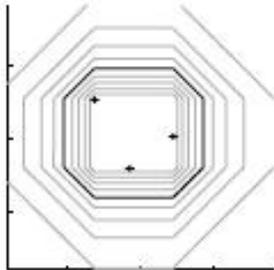
**Strong sampling**



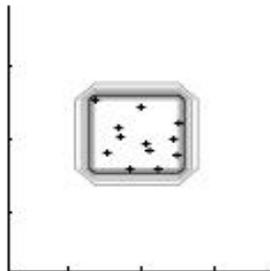
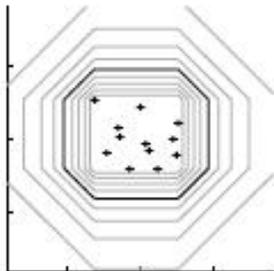
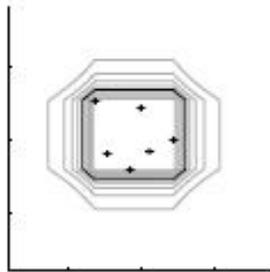
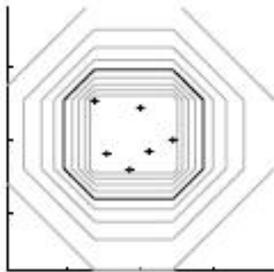
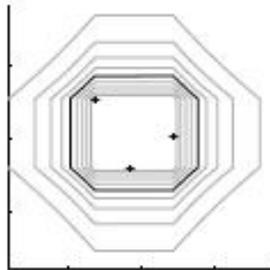
**Weak sampling**

# Behavior of weak Bayes

MAX SIM\* (Weak Bayes)



Strong Bayes



We do not get convergence to the ML hypothesis.  
If truth is a rectangle, we do not converge to it  
(not a consistent estimator).

# A more realistic example

- A discrete hypothesis space (the number game)
- A continuous hypothesis space (the healthy levels concept)
- **Word learning**



Here is a pog:



Can you give Mr. Frog all the other pogs?

# Hierarchical categories

	Vegetables	Vehicles	Animals
subordinate			
basic			
superordinate			

# Human data

Example sets:

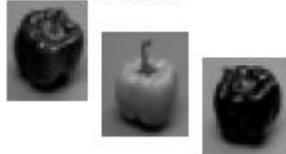
1 subordinate



3 subordinate



3 basic



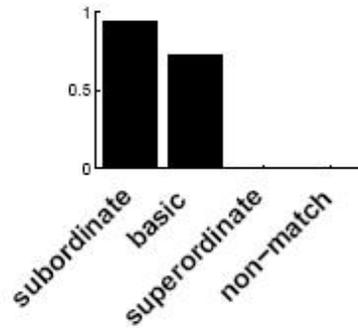
3 superordinate



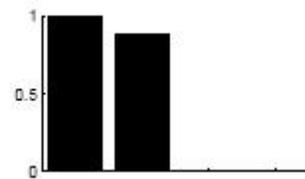
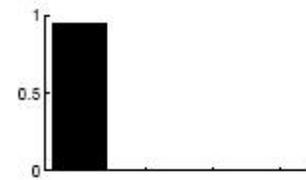
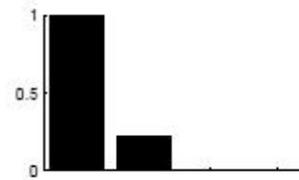
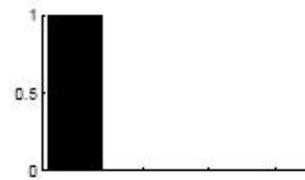
Vegetables

Vehicles

Animals

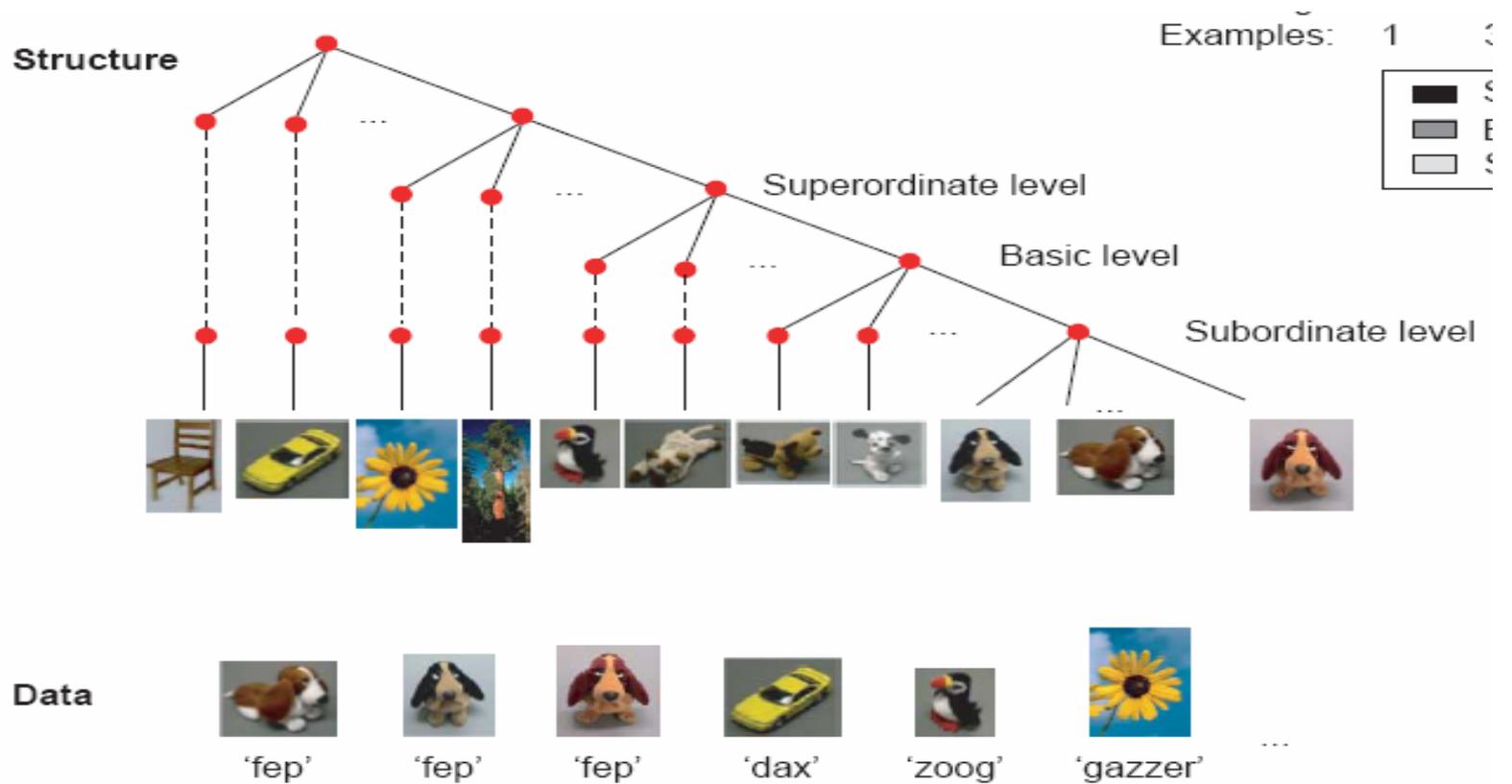


Green peppers? All peppers? All veg?



Generalize up to least common ancestor

# Hypothesis space





# Hierarchical Clustering

- Cluster based on similarities/distances
- Distance measure between instances  $\mathbf{x}^r$  and  $\mathbf{x}^s$

Minkowski ( $L_p$ ) (Euclidean for  $p = 2$ )

$$d_m(\mathbf{x}^r, \mathbf{x}^s) = \left[ \sum_{j=1}^d (x_j^r - x_j^s)^p \right]^{1/p}$$

City-block distance  $d_{cb}(\mathbf{x}^r, \mathbf{x}^s) = \sum_{j=1}^d |x_j^r - x_j^s|$

# Agglomerative Clustering

- Start with  $N$  groups each with one instance and merge two closest groups at each iteration

- Distance between two groups  $G_i$  and  $G_j$ :

- Single-link:

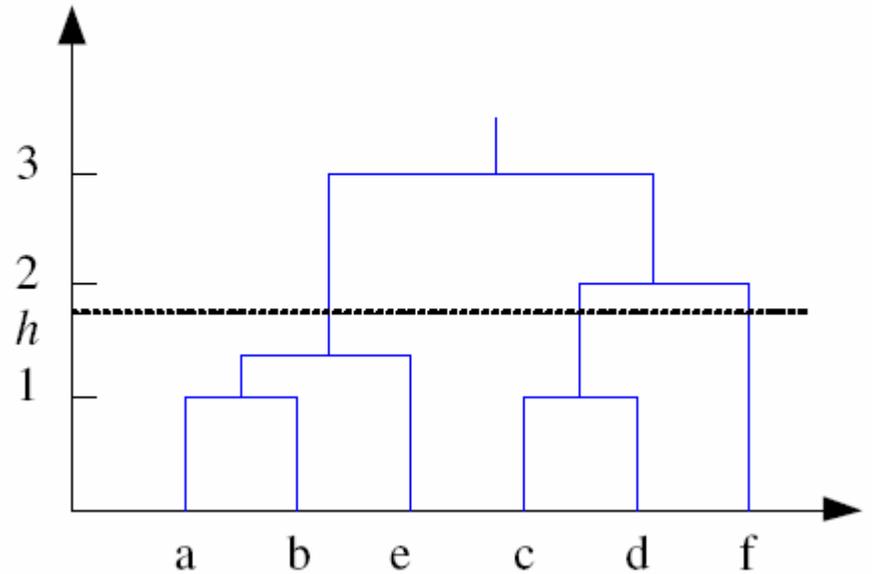
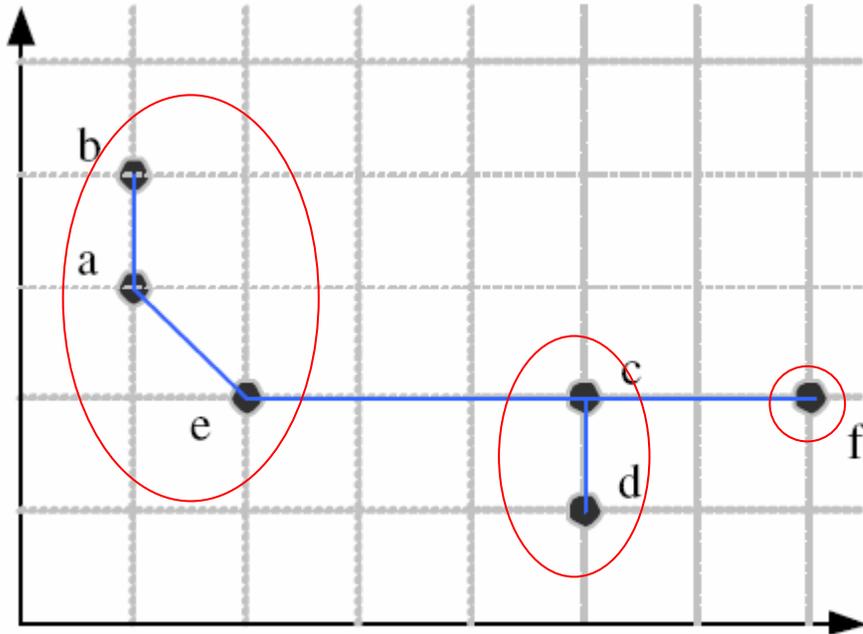
$$d(G_i, G_j) = \min_{x^r \in G_i, x^s \in G_j} d(x^r, x^s)$$

- Complete-link:

$$d(G_i, G_j) = \max_{x^r \in G_i, x^s \in G_j} d(x^r, x^s)$$

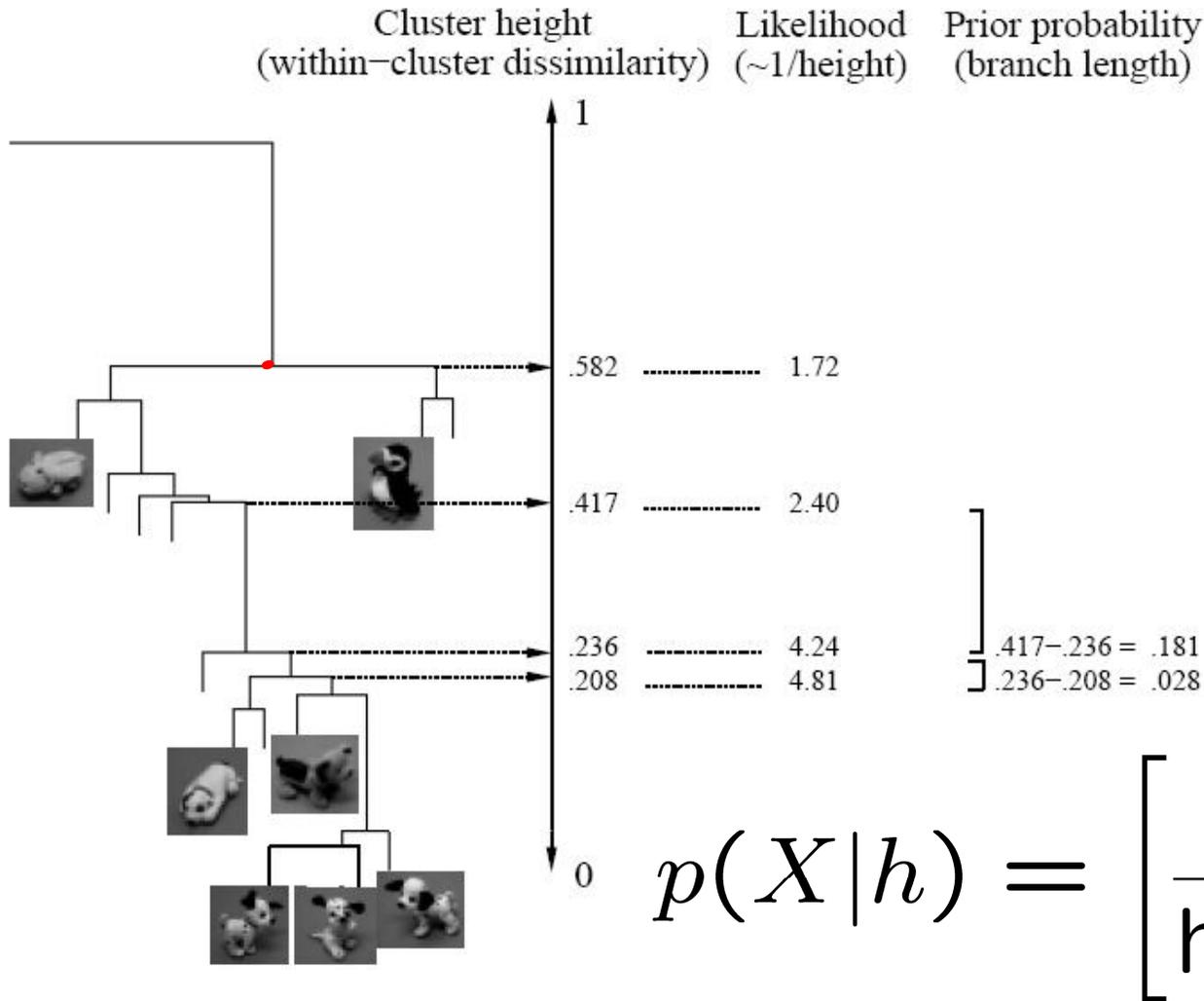
- Average-link, centroid

# Example: Single-Link Clustering



*Dendrogram*

# Prior/ likelihood

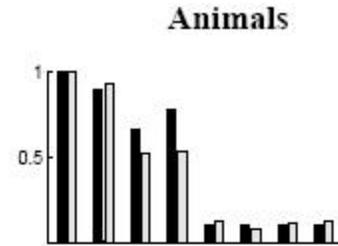
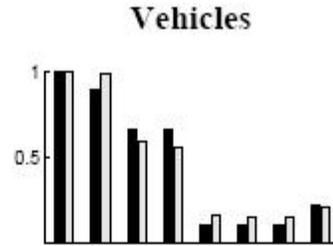
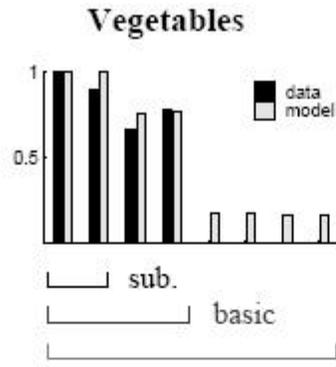


$$p(h) = \text{height}(\text{parent}(h)) - \text{height}(h)$$

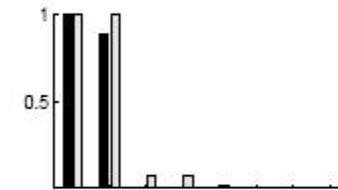
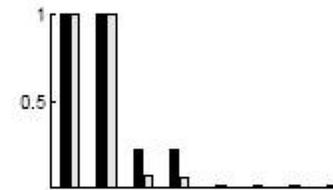
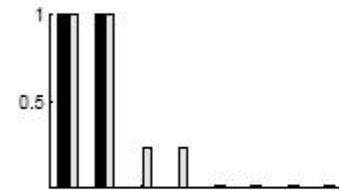
## Strong Bayes (w/ basic-level bias)

Example sets:

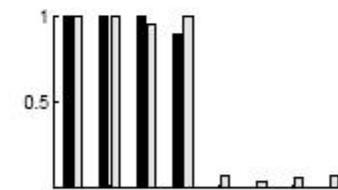
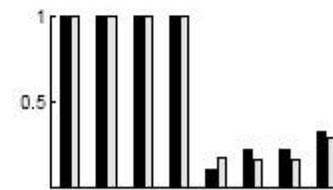
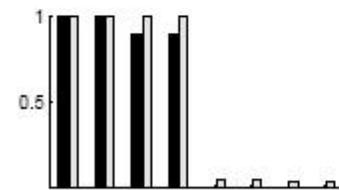
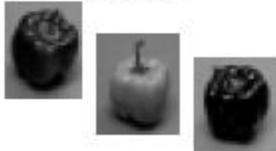
1 subordinate



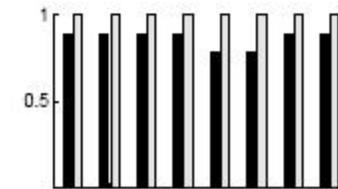
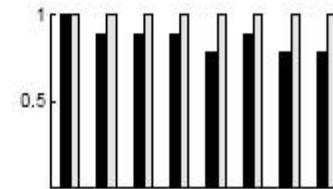
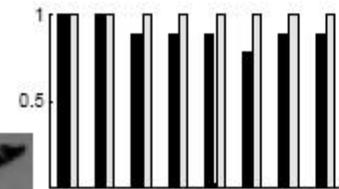
3 subordinate



3 basic



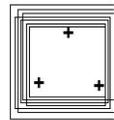
3 superordinate



# Word learning vs healthy levels

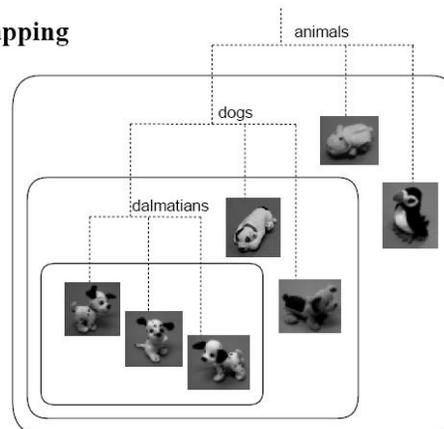
- In the word domain, after about  $N=3$  we have an "aha" moment (rule-like learning), but for healthy levels, we need a large sample size, because in the former, hypotheses differ dramatically in size, so we rapidly prefer the smallest consistent, whereas latter averages many.

*Healthy levels:*  
densely overlapping  
hypotheses



---

*Word learning:*  
sparsely overlapping  
hypotheses



# Rules and exemplars in the number game

- Hyp. space is a mixture of sparse (mathematical concepts) and dense (intervals) hypotheses.
- If data supports mathematical rule (eg  $X=\{16,8,2,64\}$ ), we rapidly learn a rule, otherwise (eg  $X=\{6,23,19,20\}$ ) we learn by similarity, and need many examples to get sharp boundary.