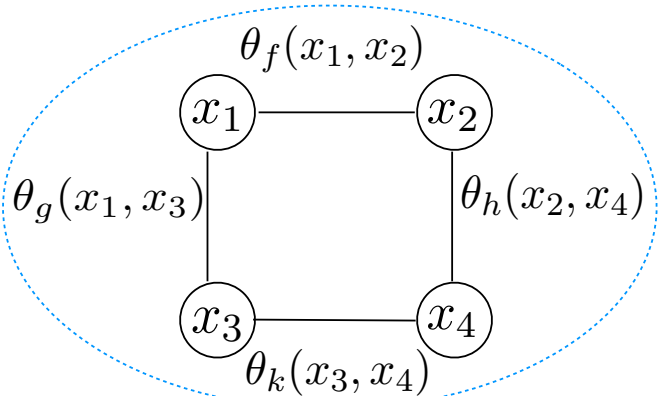
$\theta_f(x_1, x_2)$
x_1
x_2
$\theta_g(x_1, x_3)$
$\theta_h(x_2, x_4)$
x_3
x_4
$\theta_k(x_3, x_4)$