

Outline

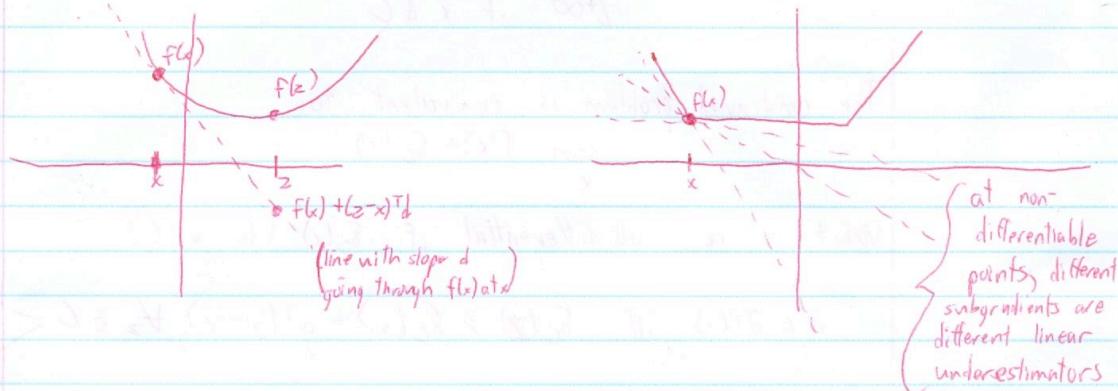
1. Optimality for Non-smooth Convex Optimization
2. Polar Cones
3. Examples

1. Optimality for Non-Smooth Convex Optimization

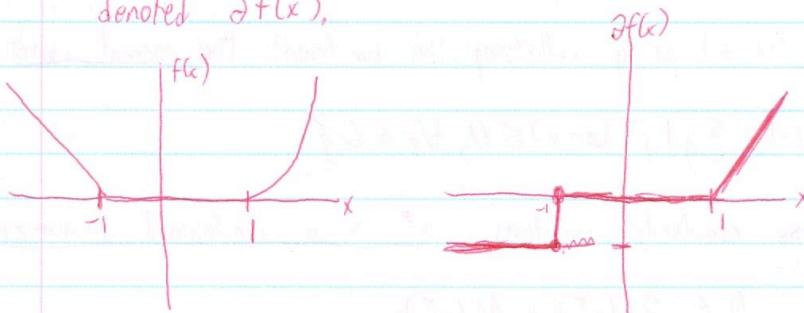
- Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be convex,

- A vector d is a subgradient of f at x if

$$f(z) \geq f(x) + (z-x)^T d, \quad \forall z \in \mathbb{R}^n$$



- The set of all subgradients of f at x is the subdifferential, denoted $\partial f(x)$,



- x^* is an unconstrained minimizer iff $0 \in \partial f(x)$

e.g. if $0 \in \partial f(x)$, then $f(z) \geq f(x) + (z-x)^T 0, \quad \forall z \in \mathbb{R}^n$
 $\Rightarrow f(z) \geq f(x), \quad \forall z \in \mathbb{R}^n$

Constrained Case

Let $C \subseteq \mathbb{R}^n$ be a non-empty convex set.

~~Maximize~~

$$\text{Consider: } \min_{\text{s.t. } x \in C} f(x)$$

We can handle this using the same optimality condition using an extended real-valued indicator function:

$$\delta_C(x) = \begin{cases} 0 & \text{if } x \in C \\ +\infty & \text{if } x \notin C \end{cases}$$

The constrained problem is equivalent to:

$$\min_x f(x) + \delta_C(x)$$

What is the sub-differential of $\delta_C(x)$ (for $x \in C$)?

$$g \in \partial f(x) \text{ iff } \delta_C(z) \geq \delta_C(x) + g^\top (z - x), \forall z \in C$$

we say $\partial f(x) = \emptyset$
if $x \notin C$
if $z \notin C$, then
reduces to $+\infty \geq \delta_C(z)$
 $+ g^\top (z - x)$

but $\delta_C(z) = \delta_C(x) = 0$, so $g \in \partial f(x)$ iff $g^\top (z - x) \leq 0, \forall z \in C$

We call the set of g satisfying this constraint the normal cone

$$N_C(x) = \{g \mid g^\top (z - x) \leq 0, \forall z \in C\}$$

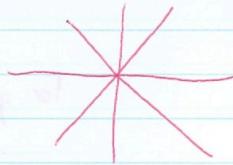
Under some regularity conditions, x^* is a constrained minimizer if

$$0 \in \partial f(x^*) + N_C(x^*)$$

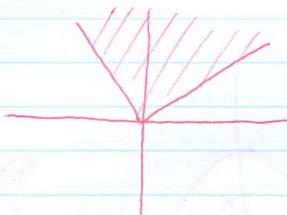
(regularity conditions: $\text{dom}(f)$ overlaps with C)
so function isn't $+\infty$ everywhere

2. Polar cones

- A cone is a set C such that $\forall x \in C, \alpha x \in C$ for $\alpha \geq 0$



- A convex cone is a set C such that $\forall x, y \in C, \alpha x + \beta y \in C$ for $\alpha \geq 0, \beta \geq 0$.

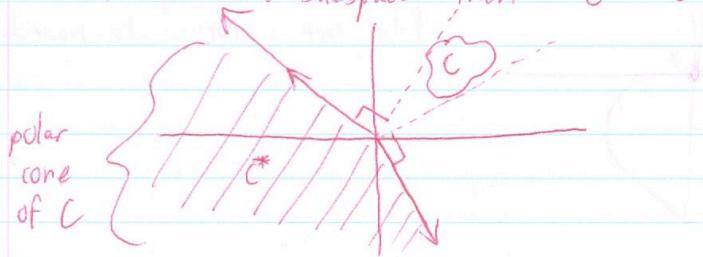


“Closed under non-negative linear combinations”

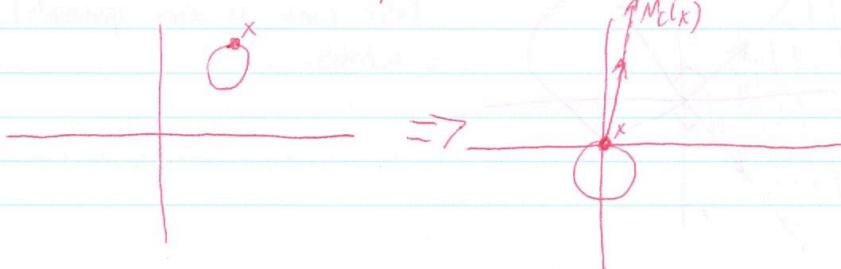
- The polar cone of a set C is the convex cone defined as:

$$C^* \triangleq \{y \mid y^T x \leq 0, \forall x \in C\}$$

- The polar cone generalizes orthogonal complement of subspaces, if C is a subspace then $C^* = C^\perp$



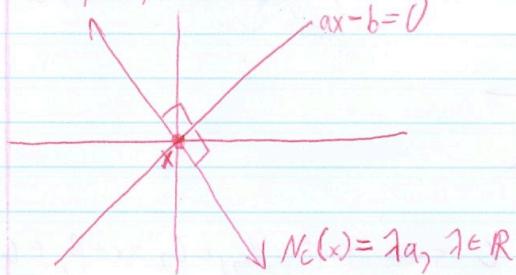
- The normal cone at x is the polar cone of $C - \{x\}$



Examples of Polar Cones and Normal Cones

Linear

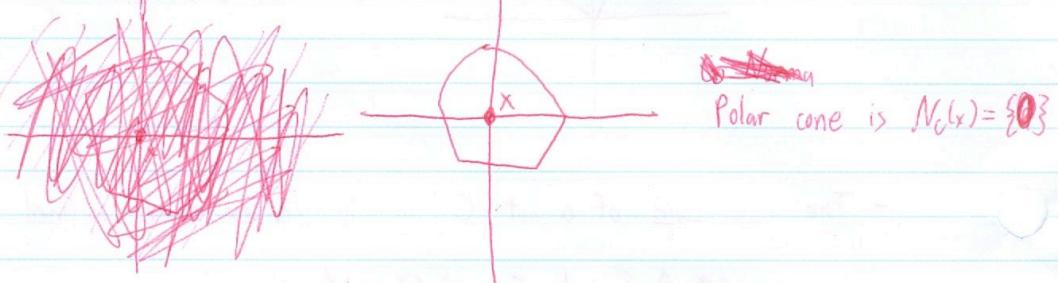
1 Equality constraints



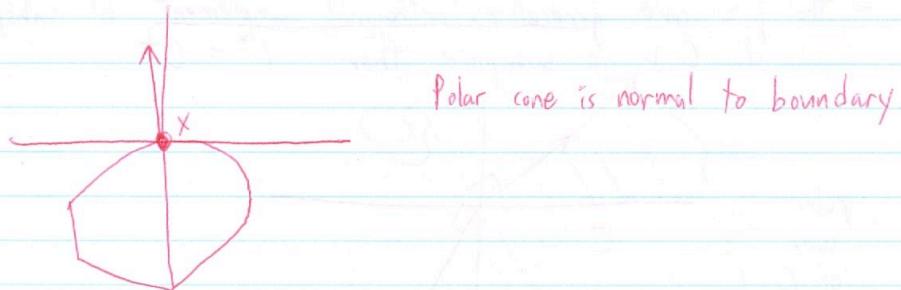
For general ^{linear} equality constraint $Ax = b$,
 $N_c(x) = R(A^T)$

Row-space of A
 (for y to be feasible, it
 must be in null-space of A)

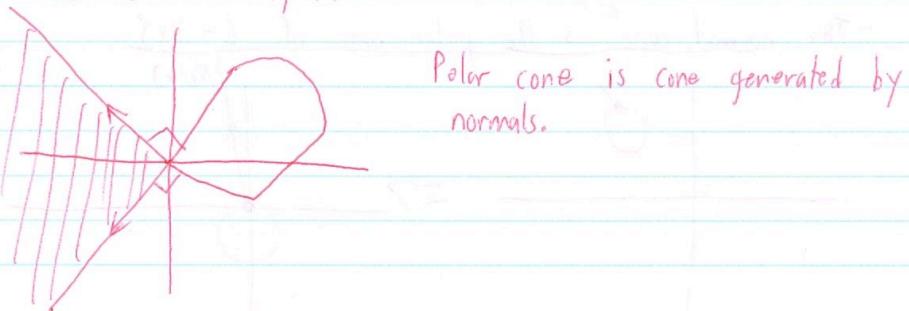
2 Interior point



3. Smooth Boundary Point



4. Non-smooth Boundary Point



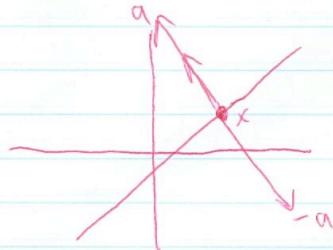
Examples

1. $\min f(x)$ (differentiable, convex)
 s.t. $x \in \mathbb{R}^n$

- normal cone is $\{v \mid \nabla f(x) = v\}$, so we get the usual $\nabla f(x) = 0$

2. $\min f(x)$ (differentiable, convex)
 s.t. $a^T x = b$

- normal cone is $\{\lambda a \mid \lambda \in \mathbb{R}\}$, so we get $\nabla f(x) + \lambda a = 0$ for some $\lambda \in \mathbb{R}$



Lagrange multiplier
Lagrangian

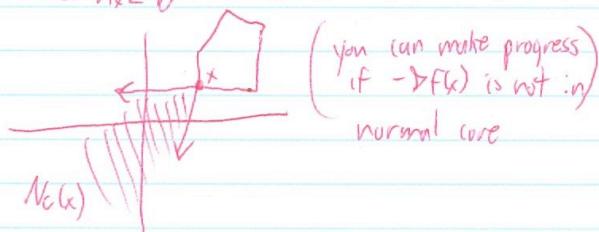
you can make progress if $\nabla f(x)$ is not parallel to a

3. $\min \|x\|_1$
 s.t. $Ax = b$

- normal cone is $\{s \mid s = \sum_i \lambda_i a_i \in R(A^T)\}$, $\nabla f(x) = \text{sgn}(x) = \begin{cases} +1 & \text{if } x > 0 \\ -1 & \text{if } x < 0 \\ [-1, 1] & \text{if } x = 0 \end{cases}$

so we get $\nabla f(x) + R(A^T) = 0$
 $0 \in \text{sgn}(x) + R(A^T) = 0$

4. $\min f(x)$ (convex)
 s.t. $Ax \leq b$



normal cone is

$$\{s \mid s = \sum_{i \in A(x)} \lambda_i a_i, \lambda_i \geq 0\}$$

(active set)

so we get $\nabla f(x) + \sum_{i \in A(x)} \lambda_i a_i = 0$

for some $\lambda_i \geq 0$.