

Announcements

■ Assignment 2

- Programming **due Friday**

■ Assignment 3

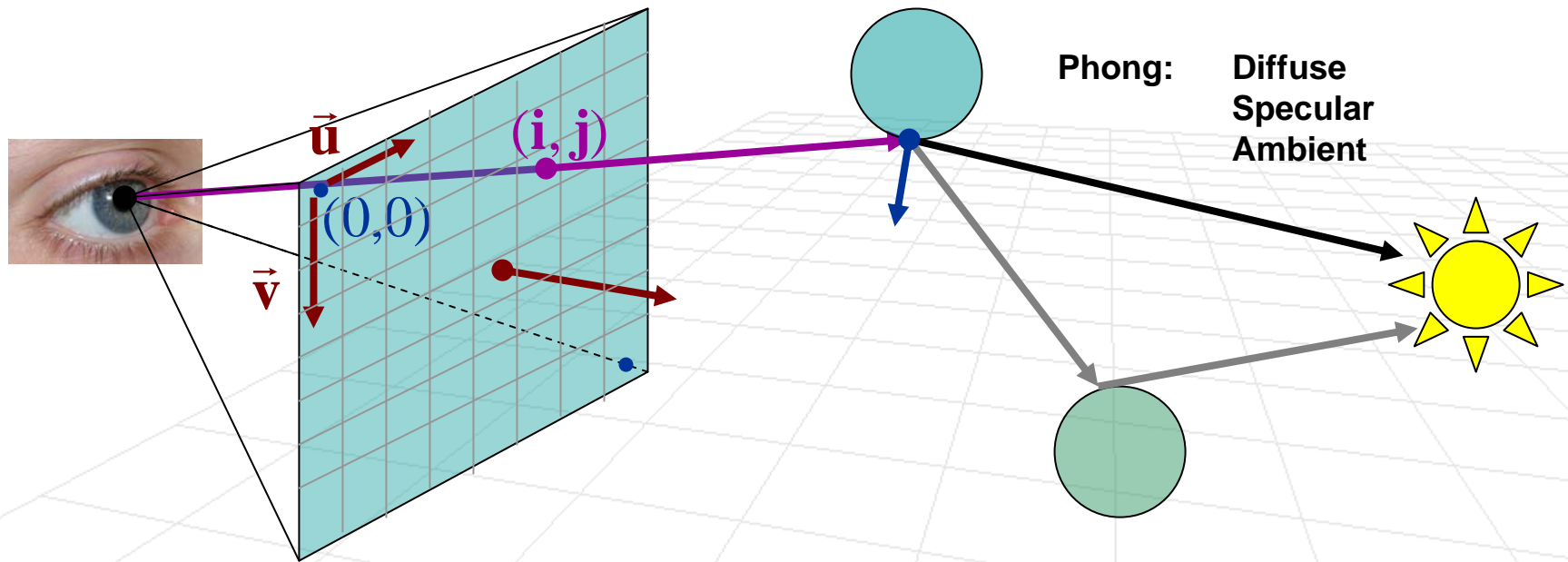
- **Programming** will be given out **first**
- **Theory** will be given out **later**
- Due dates will be shifted accordingly

■ Office Hours for Alex

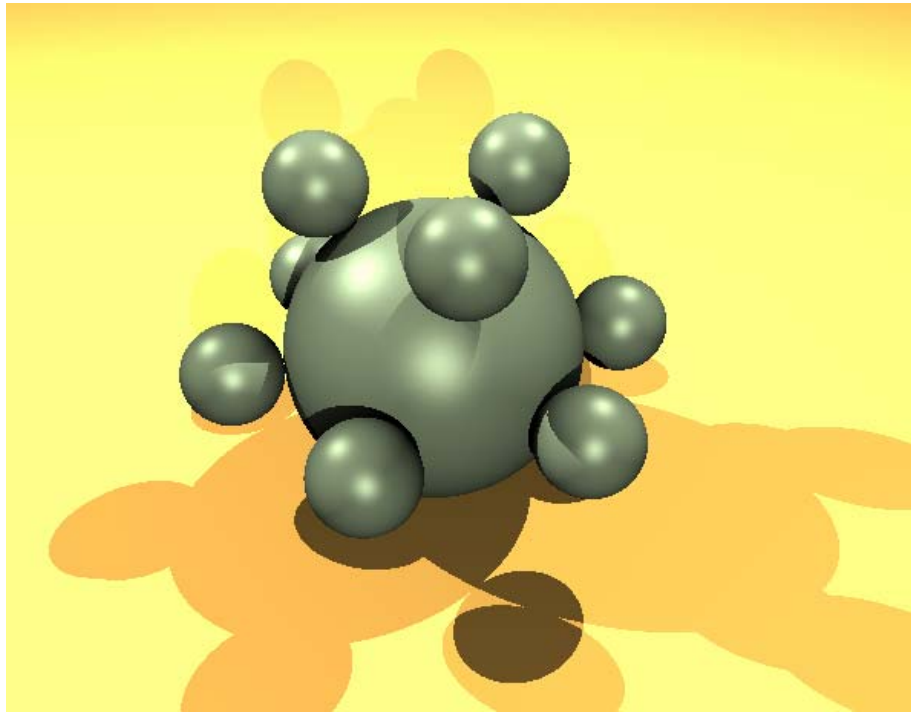
- After class **today from 11-11:45**

Ray Tracing Review

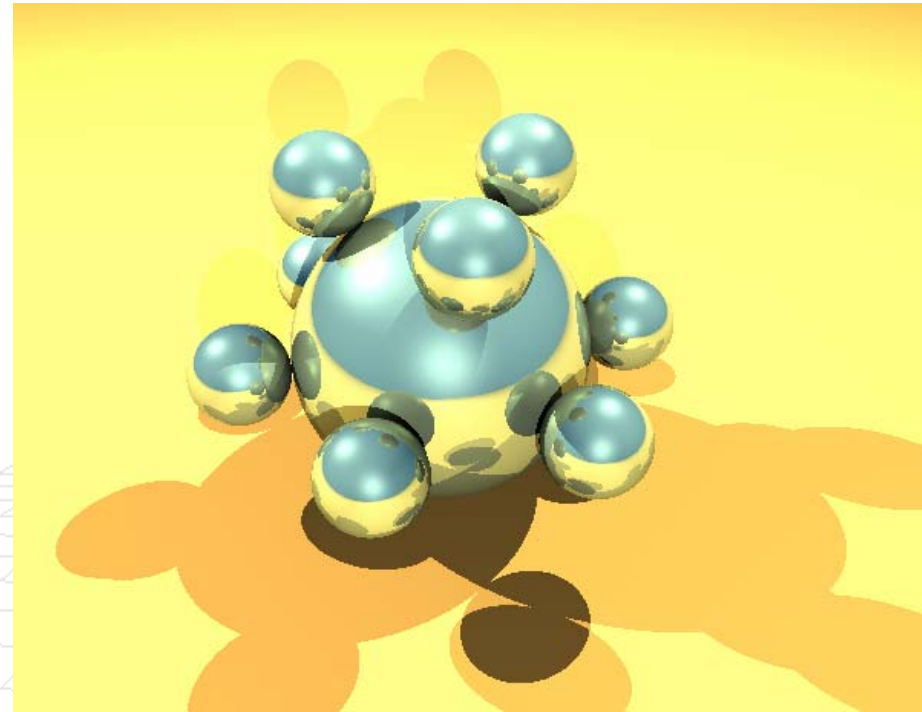
- For each pixel
 - Form a ray (a.k.a. ray casting)
 - Find intersection of this ray with objects in the scene
 - Find closest object intersection (there could be multiple object intersections for any given ray)
 - Find normal at the closest intersection point (a.k.a hit point)
 - Evaluate reflectance model at the hit point (**global** + local)



Effects of Ray Tracer Recursion



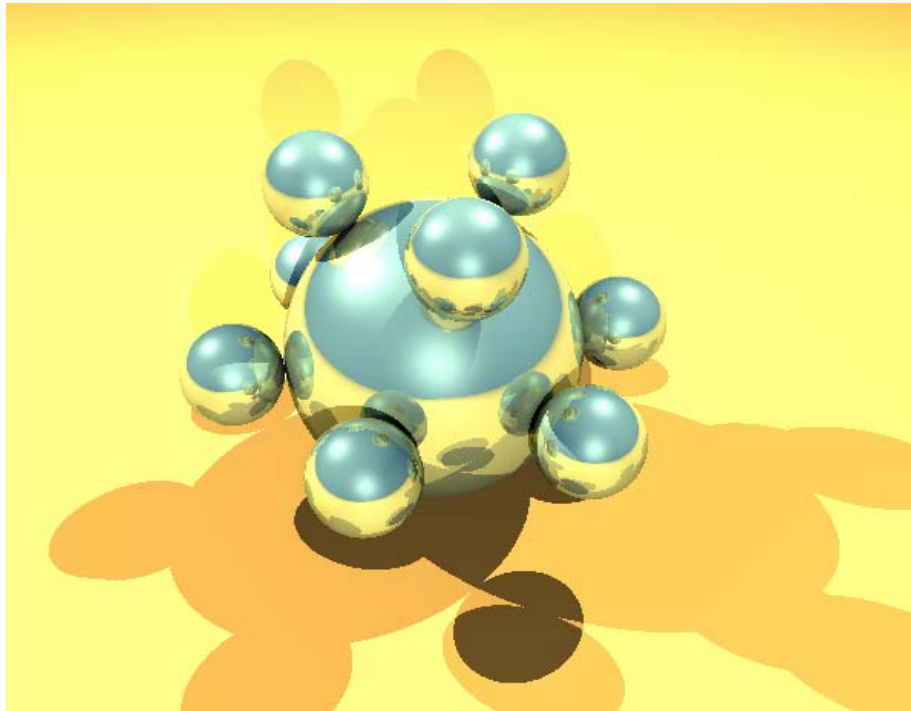
No recursive rays (local lighting)



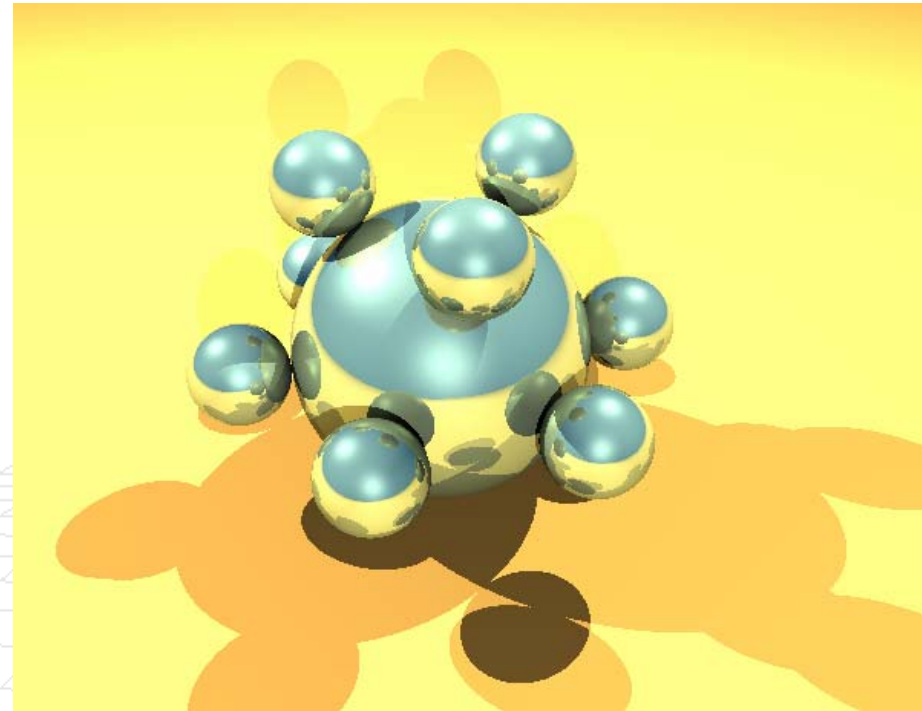
1 Level of recursive reflection

Effects of Ray Tracer Recursion

**Recursion level of 1 or 2 is usually sufficient, unless we have mirrors
That reflect in one another**

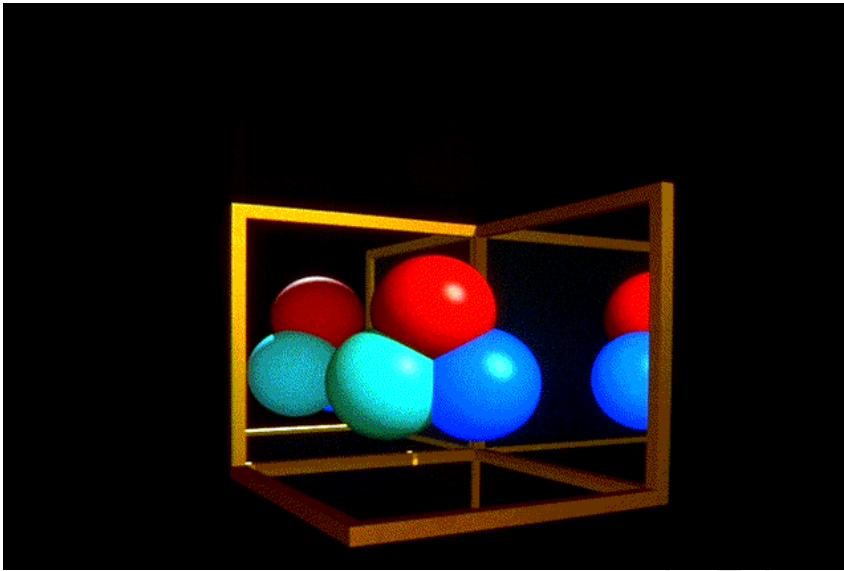


2 Levels of recursive reflection

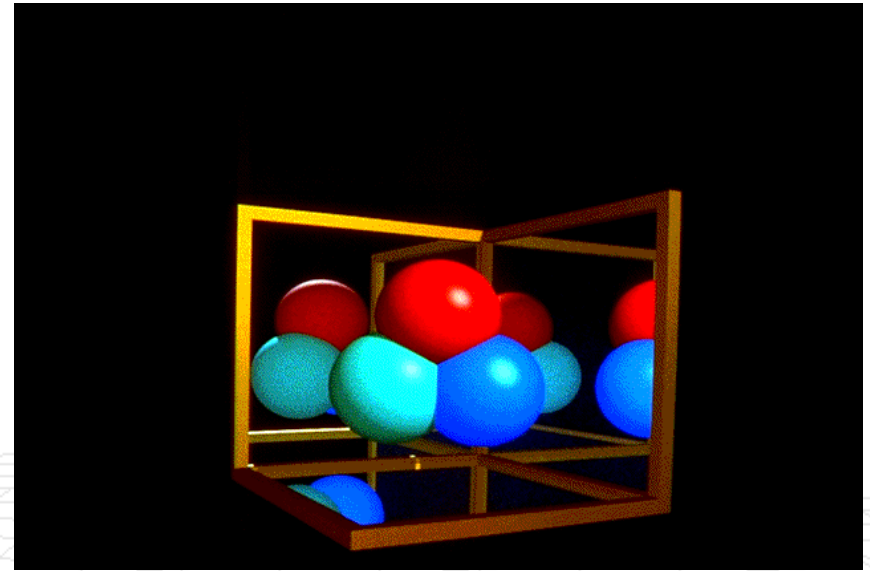


1 Level of recursive reflection

Effects of Ray Tracer Recursion



1 Level of recursive reflection



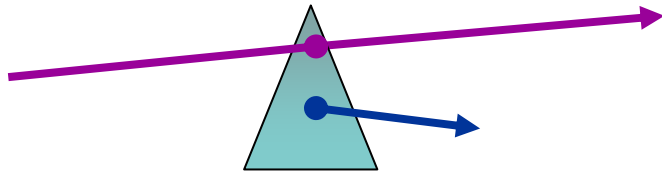
2 Levels of recursive reflection

Texture (last time this went by quickly)

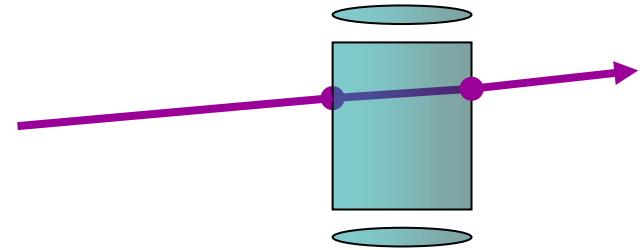
- Texture can be used to modulate diffuse and ambient reflection coefficients, as with Gouraud or Phong shading
- All we need, is a way of mapping a point on the surface (hit point) to a point in the texture space
 - e.g. given a hit point of parametric surface, we can convert the 3D point coordinates to surface parameters, and use them to get texture coordinates (as with standard texture mapping)
- Unlike with Gouraud or Phong shading models we don't need to interpolate texture coordinates over polygons
- Anti-aliasing and super-sampling we will cover later (next week)

Intersections Algorithms

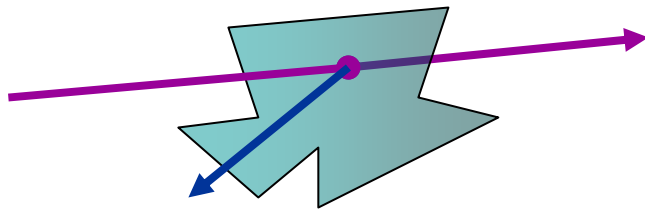
Triangles



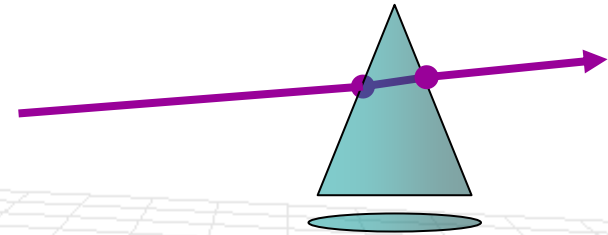
Cylinders



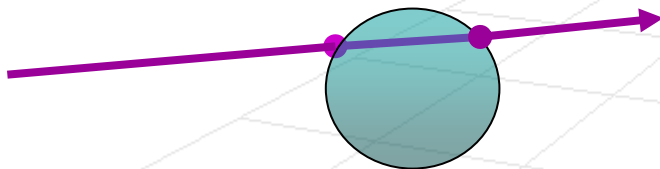
Polygonal Patches



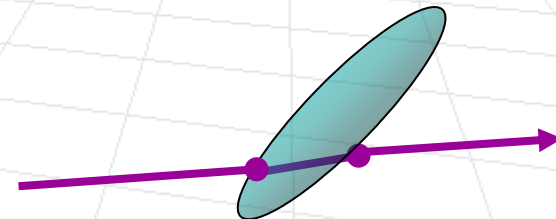
Conics



Spheres



Affinely Deformed Surfaces



Constructive Solid Geometry

Computer Graphics, CSCD18

Fall 2008

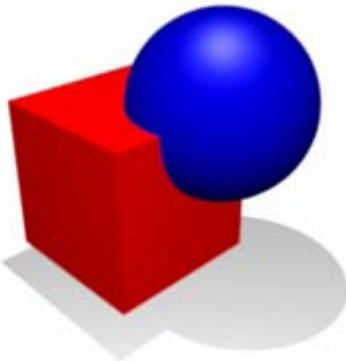
Instructor: Leonid Sigal



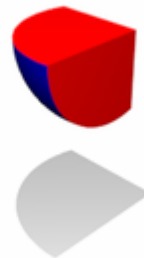
Constructive Solid Geometry

- **Idea:** construct a more expressive class of geometrical models by combining the basic geometric primitives we already studied
- To do this we define boolean operators on overlapping geometric objects

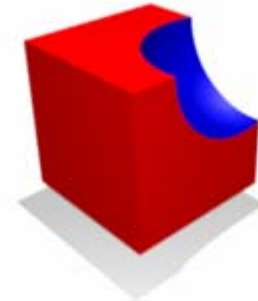
Union



Intersection

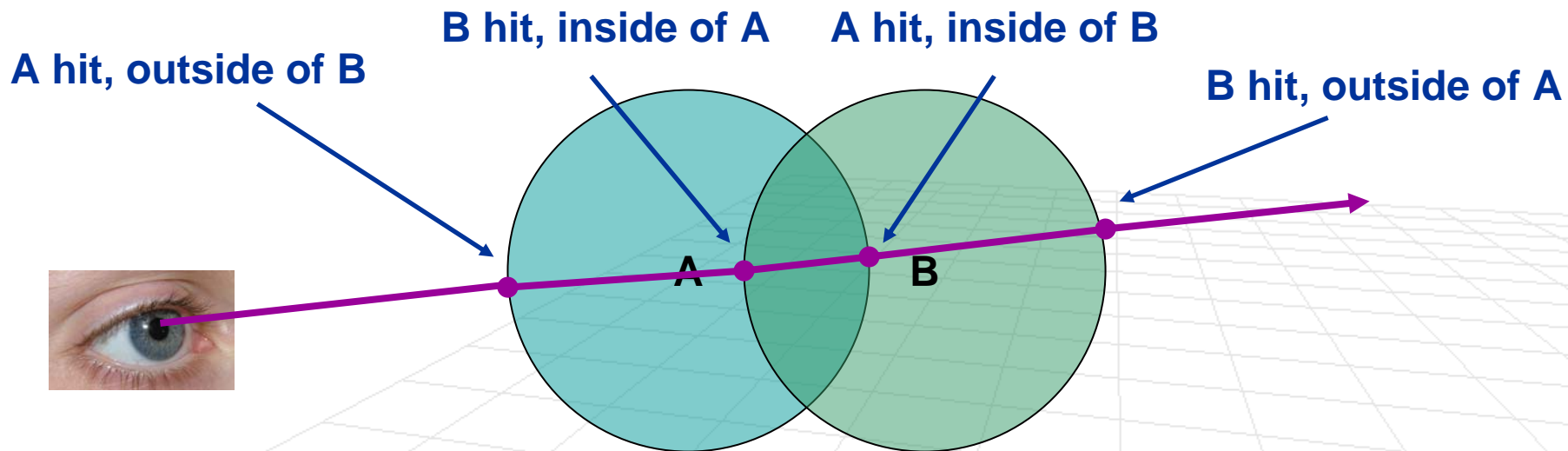


Subtraction



How do we intersect a CFG geometry?

- We can use the original intersection tests + a bit of logic

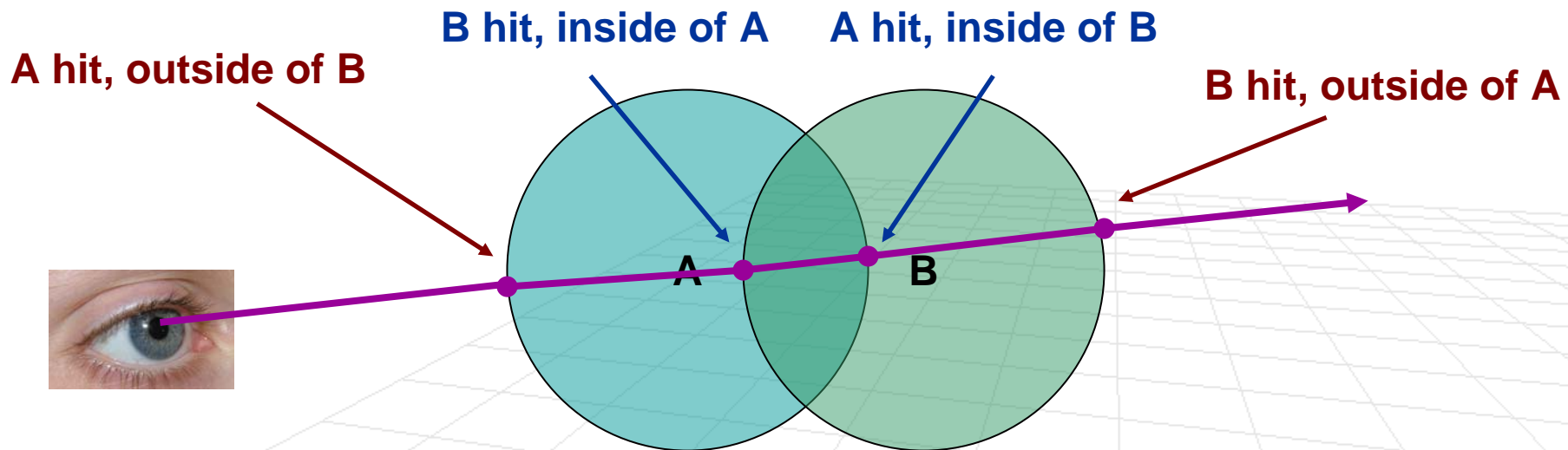


We can determine this by simple inside/outside tests

How do we intersect a CFG geometry?

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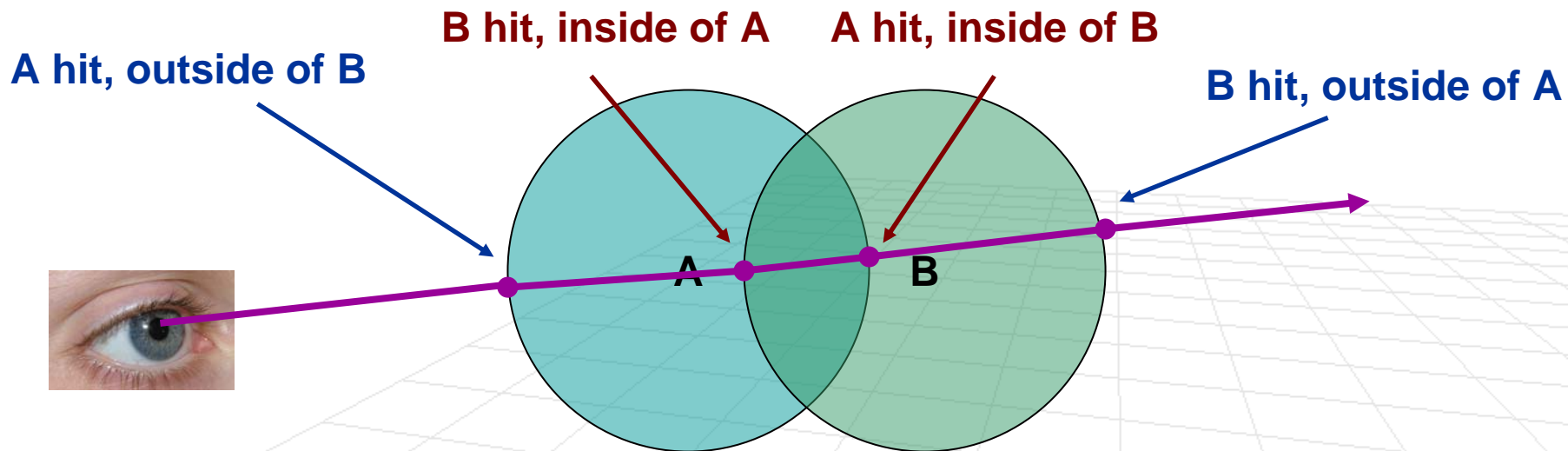
For example, for union operator we must consider



How do we intersect a CFG geometry?

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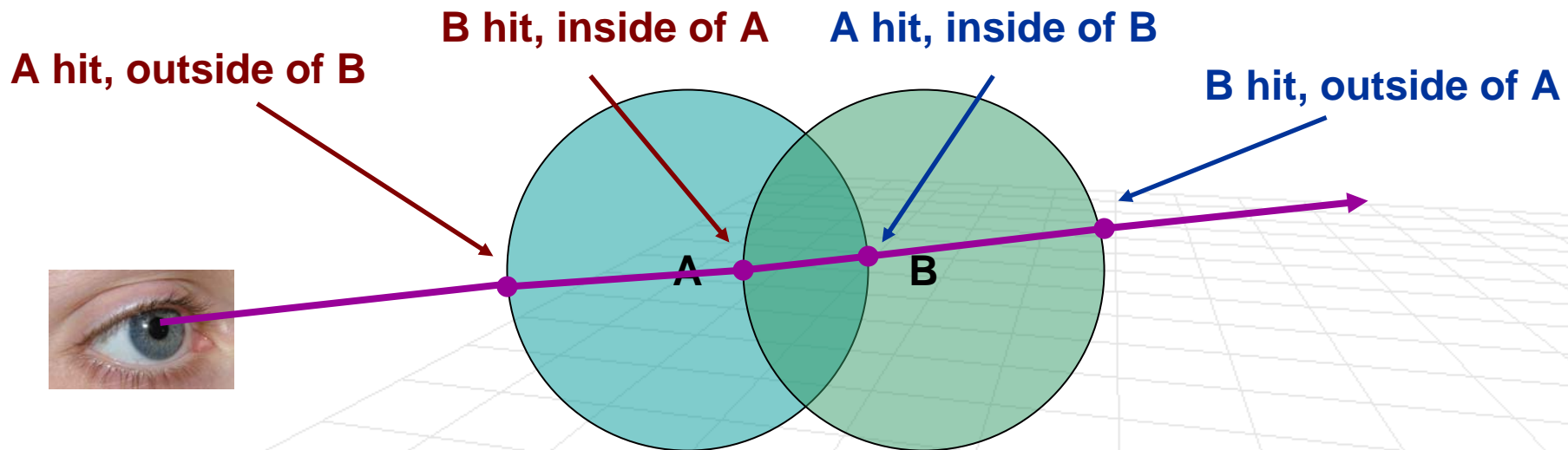
For example, for intersection operator we must consider



How do we intersect a CFG geometry?

- We can use the original intersection tests + a bit of logic

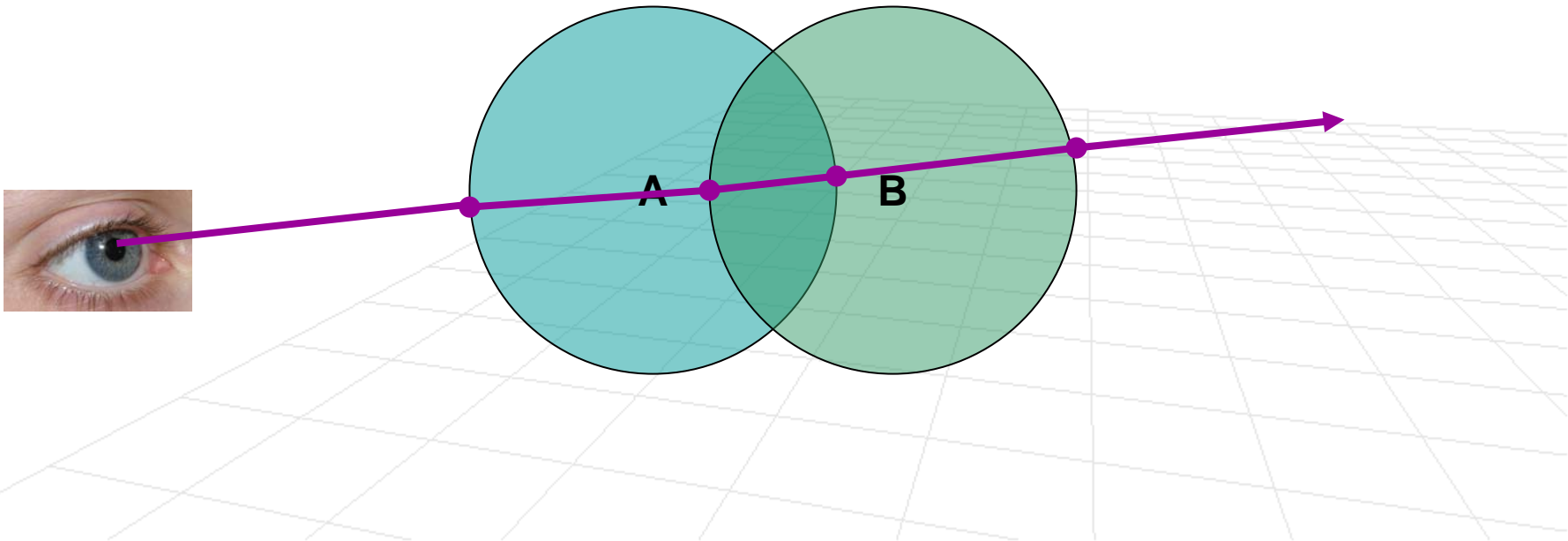
For example, for subtraction operator (assuming $A-B$) we must consider



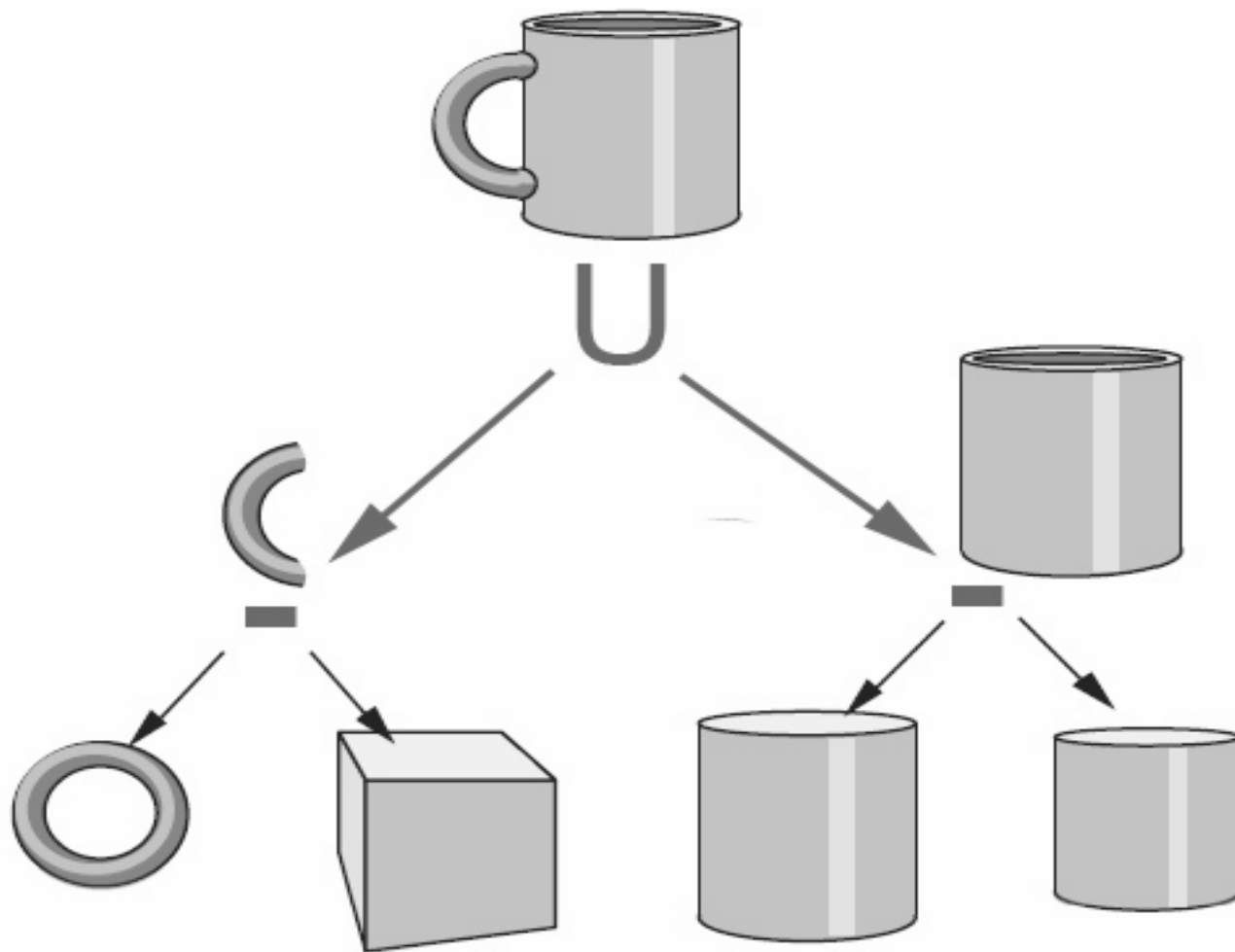
What about normals at “hit points”?

- Simple rules:

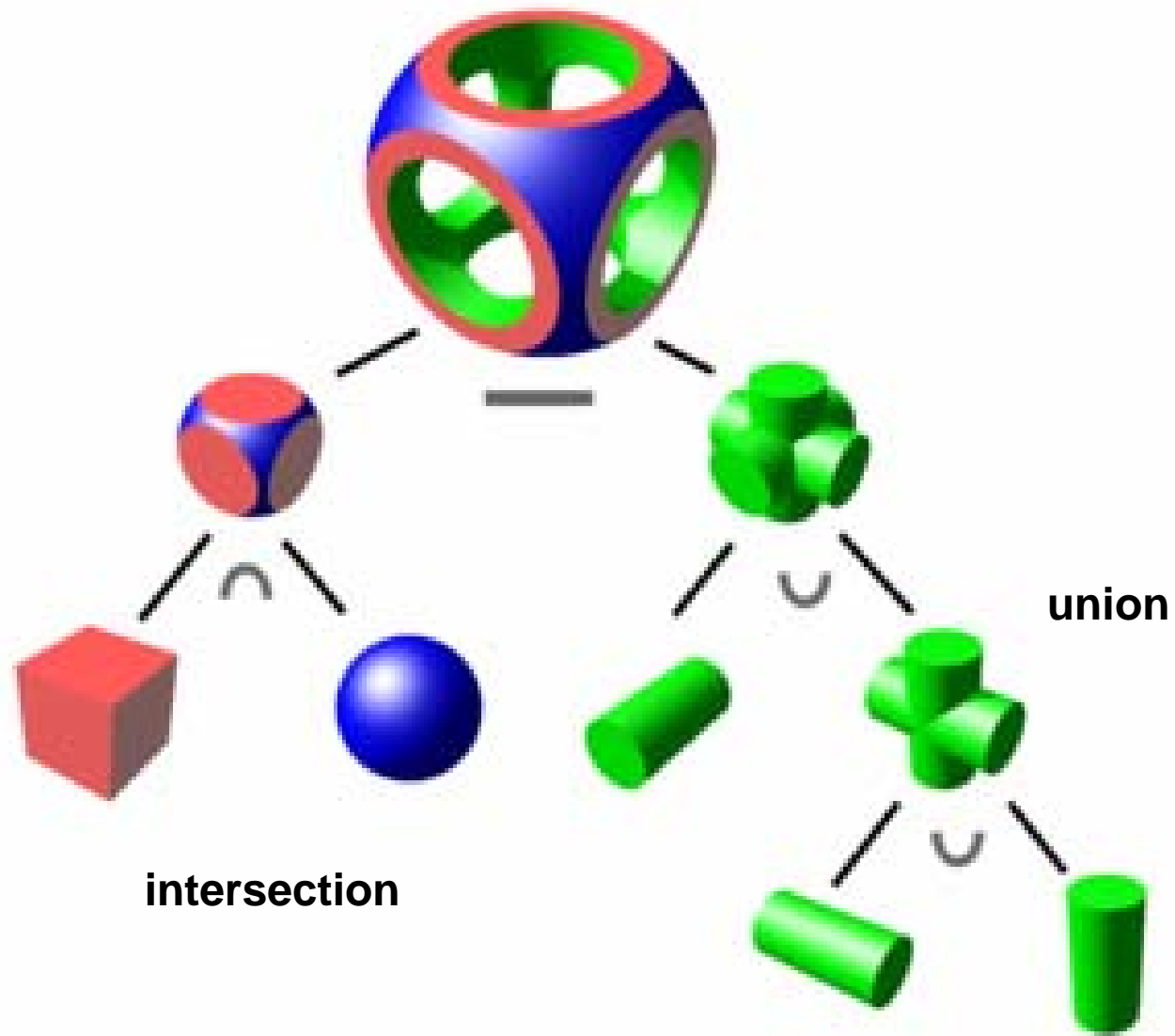
- If **object is positive**, then the computed normal at the “hit point” is **outward facing**
- If **object is negative**, then the computed normal at the “hit point” is **inward facing** (and needs to be flipped)



What can you build out of what we know?



Complex CFG



Benefits of CFG

- Builds **complex geometry** based on **simple primitives**
- Requires **no additional intersection code**
- Relatively inexpensive and easy to use in a Ray Tracer
- Naturally partitions objects and the scene in terms of hierarchical representation
 - Allows for efficient rendering

Ray Tracing

Part 3: Refraction and Shadows

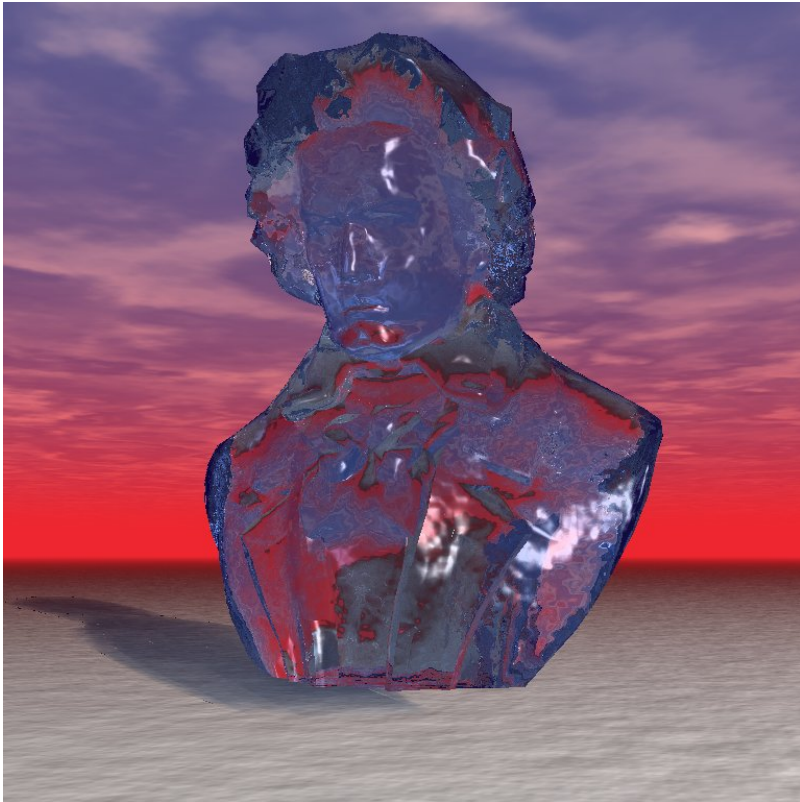
Computer Graphics, CSCD18

Fall 2008

Instructor: Leonid Sigal



What do we want to model?

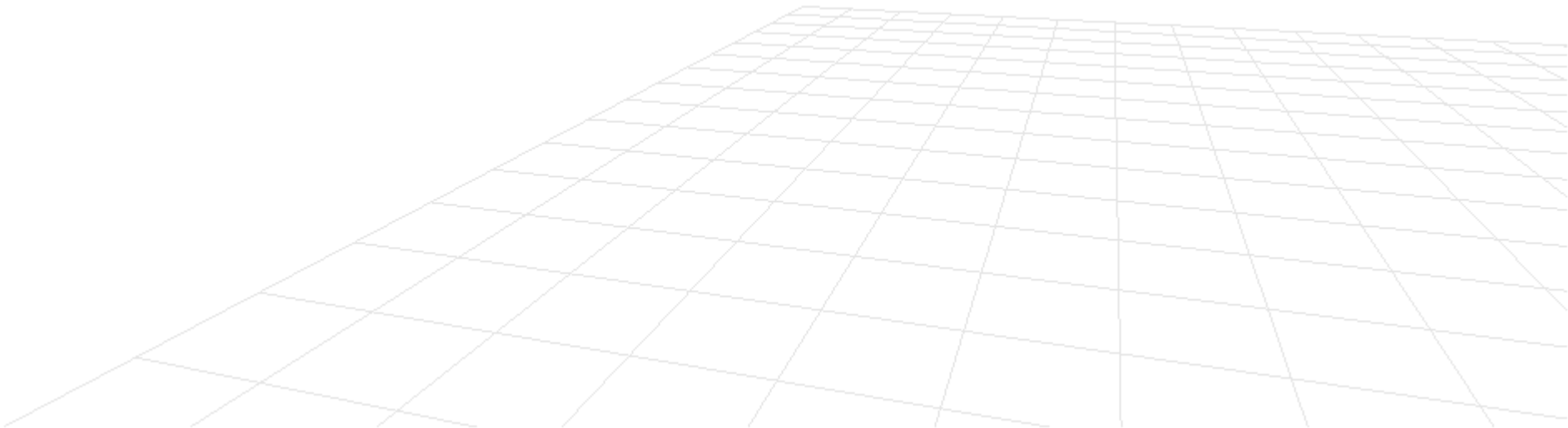


Transmission or refraction effects in semi-transparent surfaces

Transmission or Refraction

- **Physics:** light that penetrates a (partially or fully) transparent surface or material is refracted (bent) to account for change in the speed of light transmission in different media

- **Snell's law governs refractions** $\frac{\sin \theta_1}{\sin \theta_2} = \frac{c_1}{c_2}$

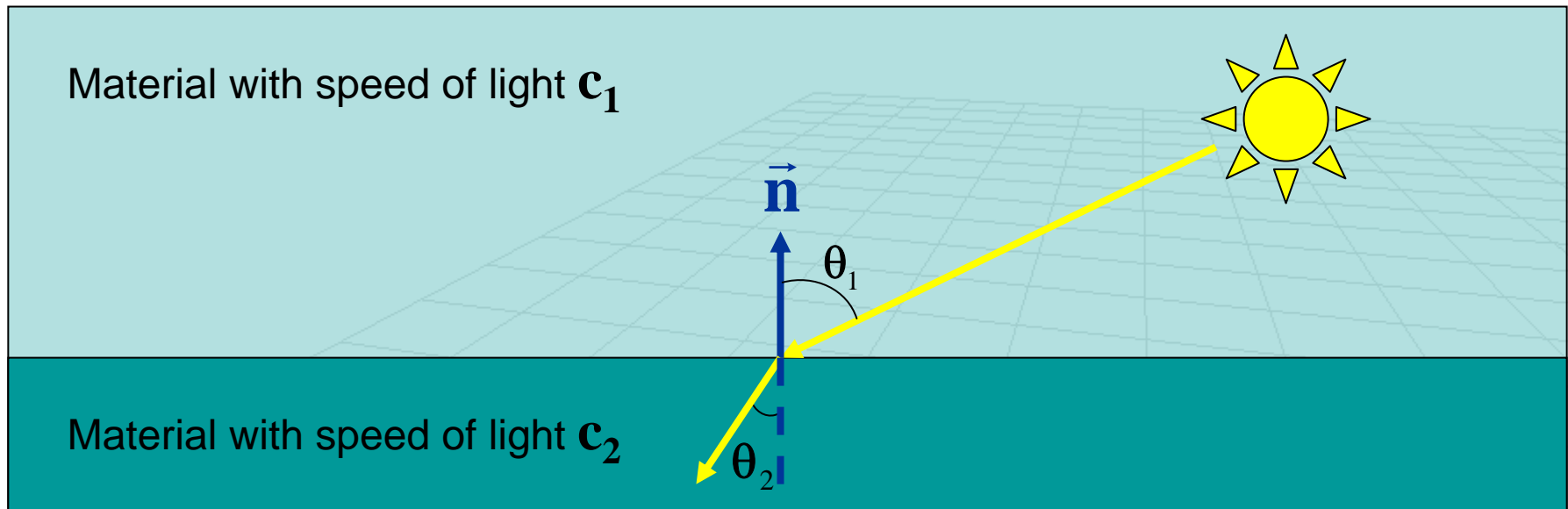


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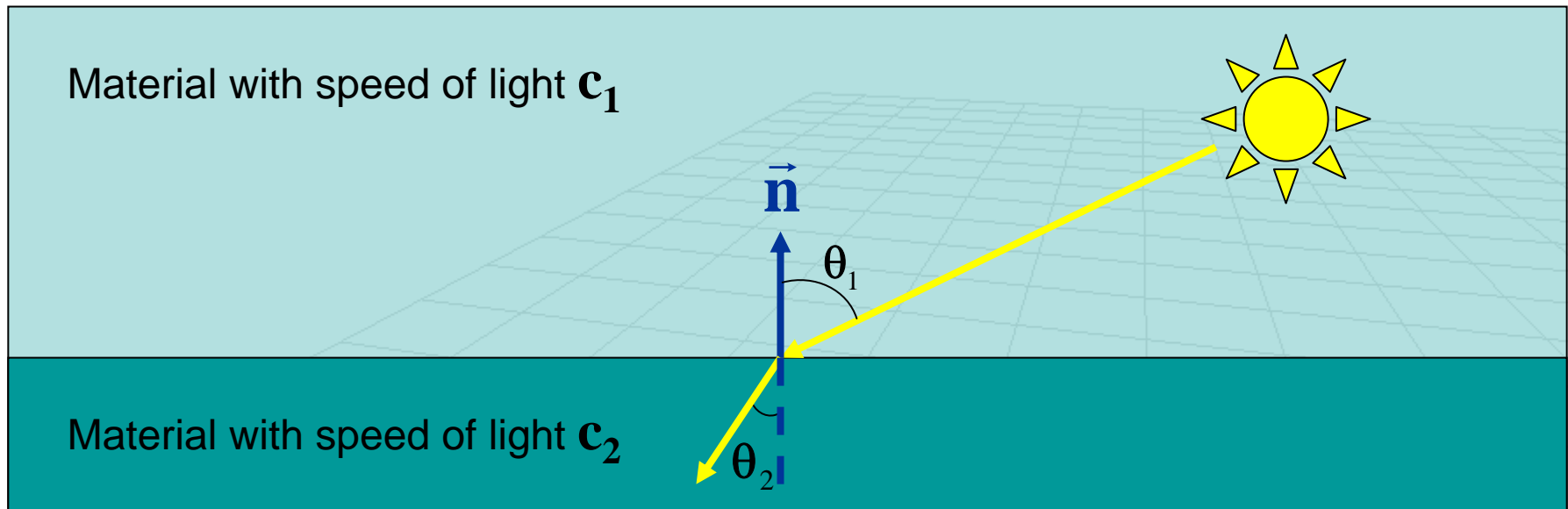
Transmission or Refraction

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index of refraction

- **Snell's law governs refractions**

$$\frac{\sin \theta_1}{\sin \theta_2} = \frac{c_1}{c_2}$$

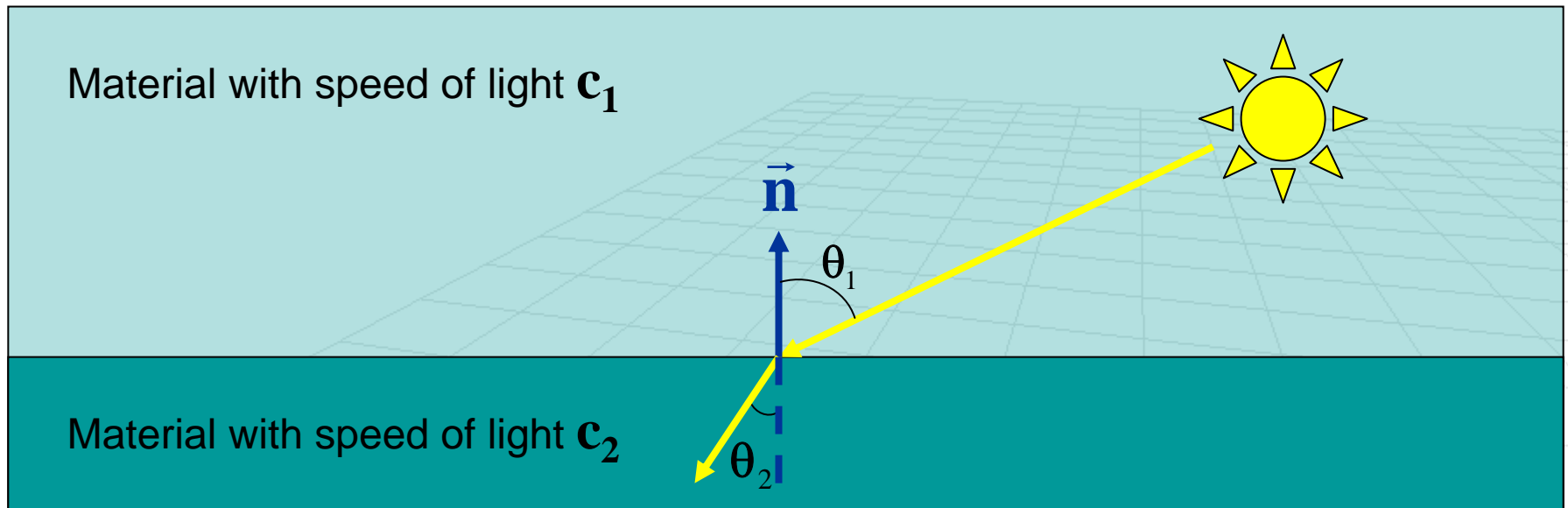


Transmission or Refraction

- For example, $\frac{c_{\text{air}}}{c_{\text{water}}} \approx 1.33$ $\frac{c_{\text{air}}}{c_{\text{glass}}} \approx 1.8$

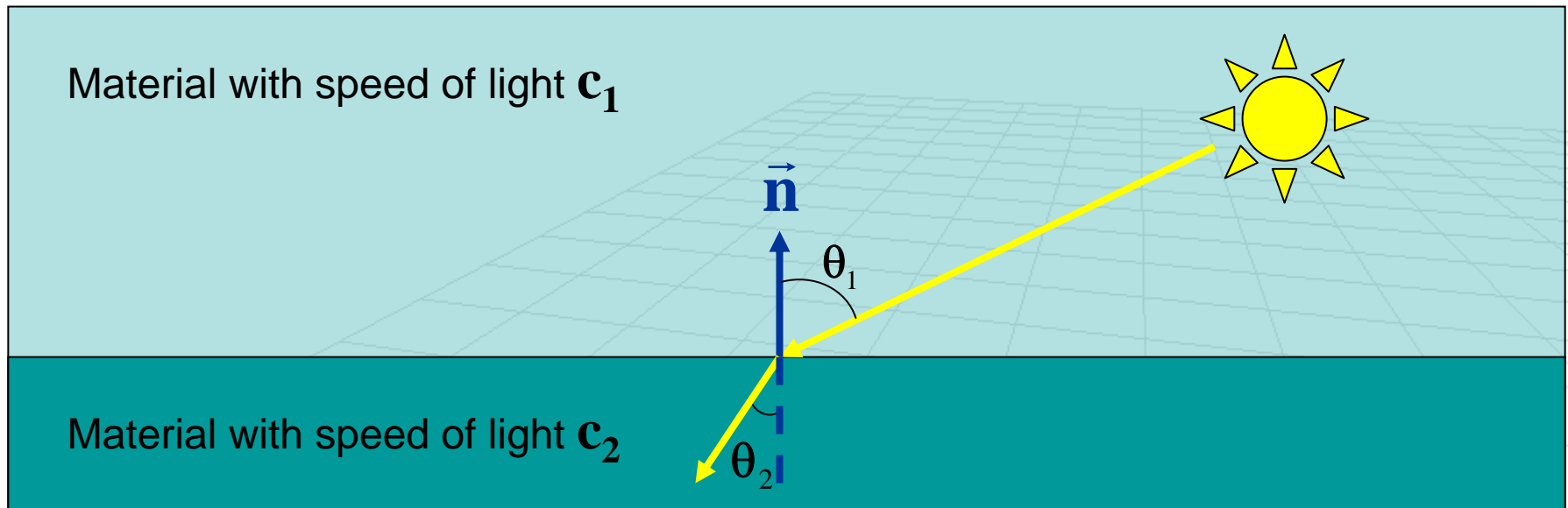
$c_2 < c_1$ light bends toward the normal (eg. air to water)

$c_2 > c_1$ light bends away from the normal (eg. water to air)



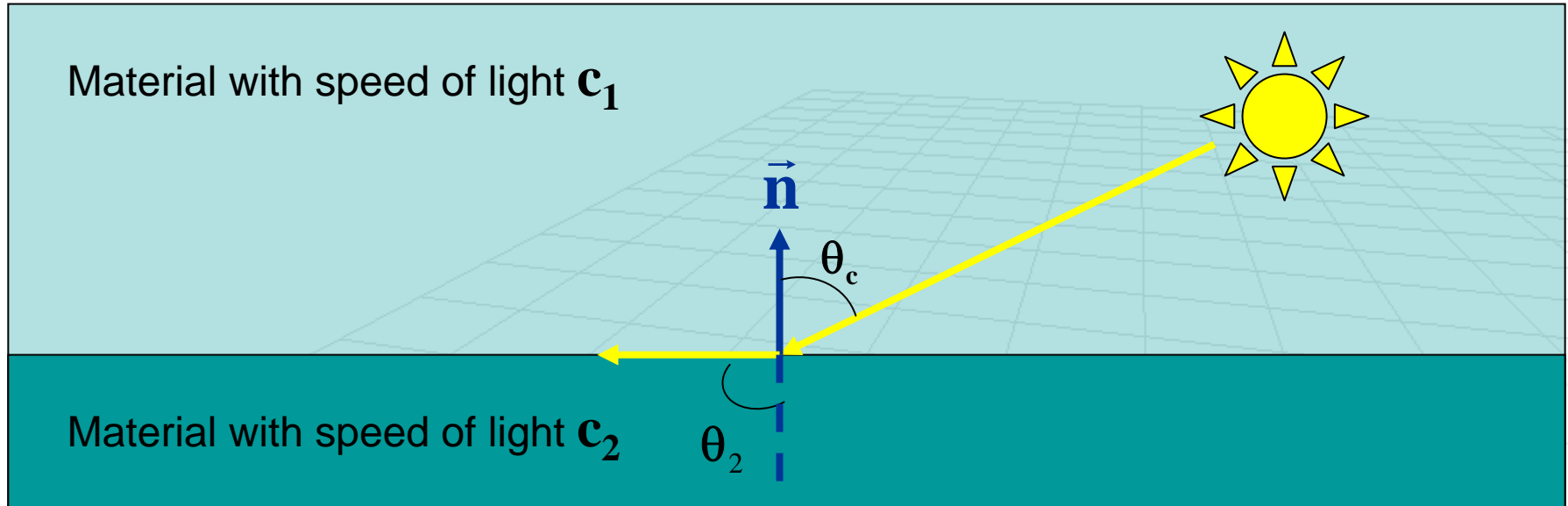
Common Indices of Refraction

Material	Index of Refraction
<i>vacuum</i>	1.0
<i>ice</i>	1.309
<i>water</i>	1.333
<i>ethyl alcohol</i>	1.36
<i>glass</i>	1.5–1.6
<i>diamond</i>	2.417



Transmission or Refraction

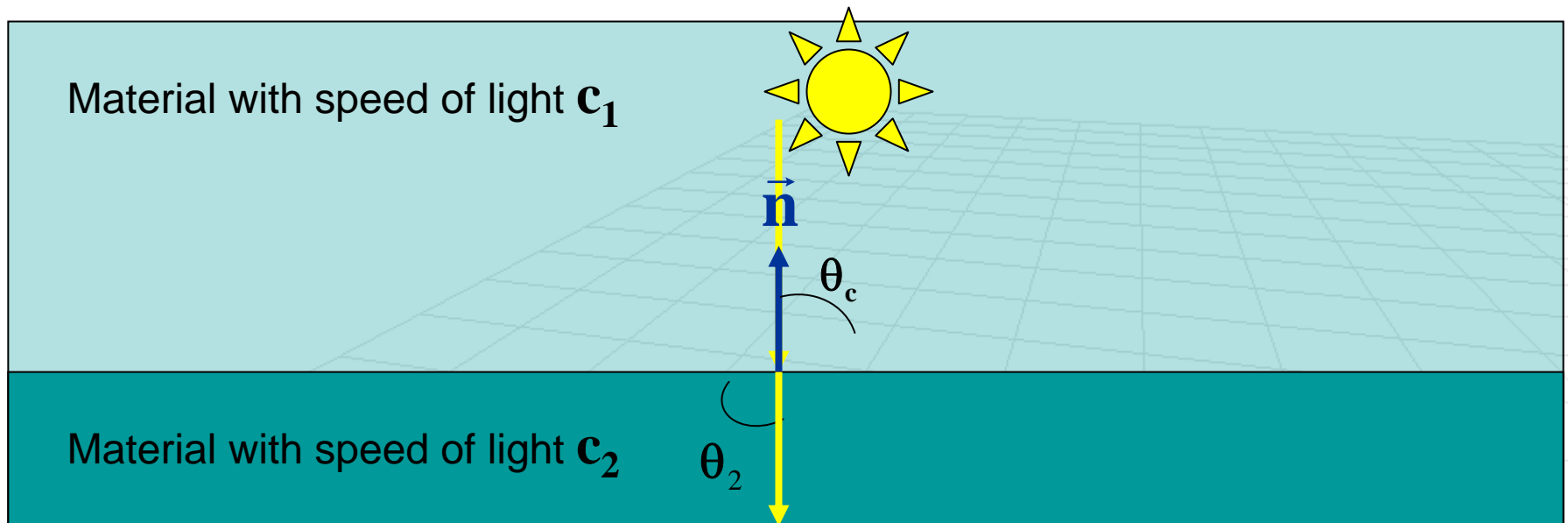
- Critical angle (for $c_2 > c_1$)
 - As incoming angle approaches critical angle, the outgoing angle approaches 90 degrees
 - No light enters the material



Transmission or Refraction

- Special case

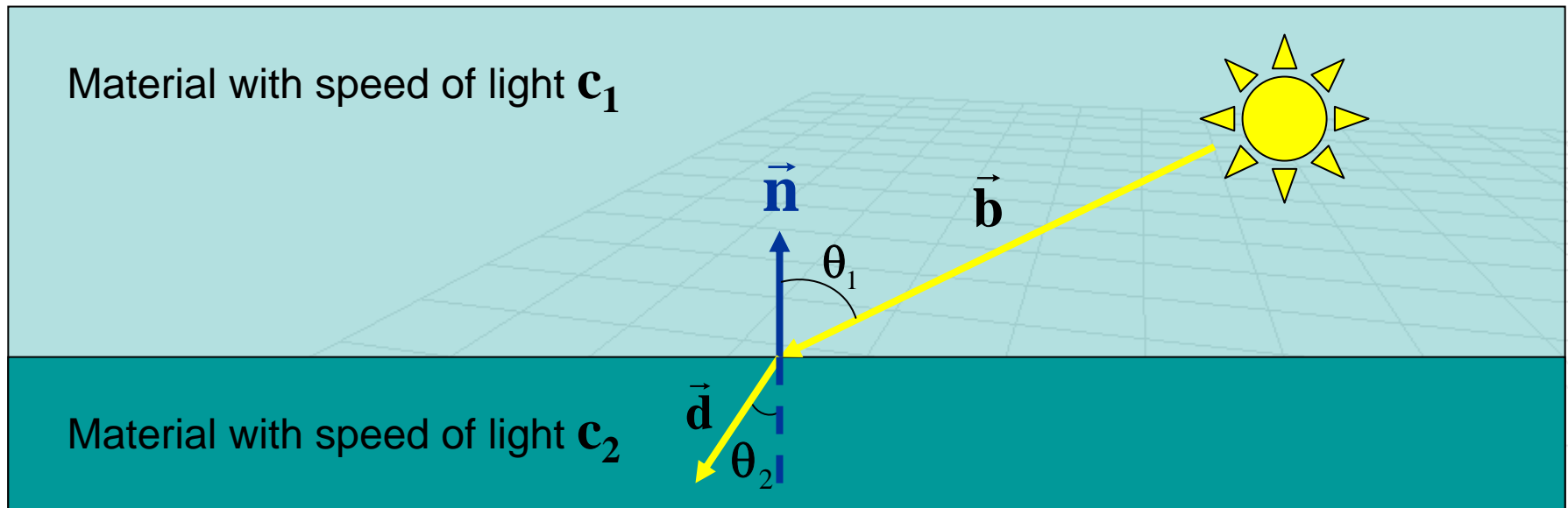
- If incoming angle is 0 the outgoing angle is also 0
- No light bending



Refraction in Ray Tracing

- We can treat global refraction/transmission just like global specular reflection (i.e. cast one ray)
 - Need to keep track of the speed of light in the current medium
- Perfect refraction direction

$$\vec{d} = \frac{c_2}{c_1} \vec{b} + \left(\frac{c_2}{c_1} (\vec{n} \cdot \vec{b}) - \left(1 - \left[\frac{c_2}{c_1} \right]^2 \left(1 - (\vec{n} \cdot \vec{b})^2 \right) \right)^{1/2} \right) \vec{n}$$



More complex scene with refraction



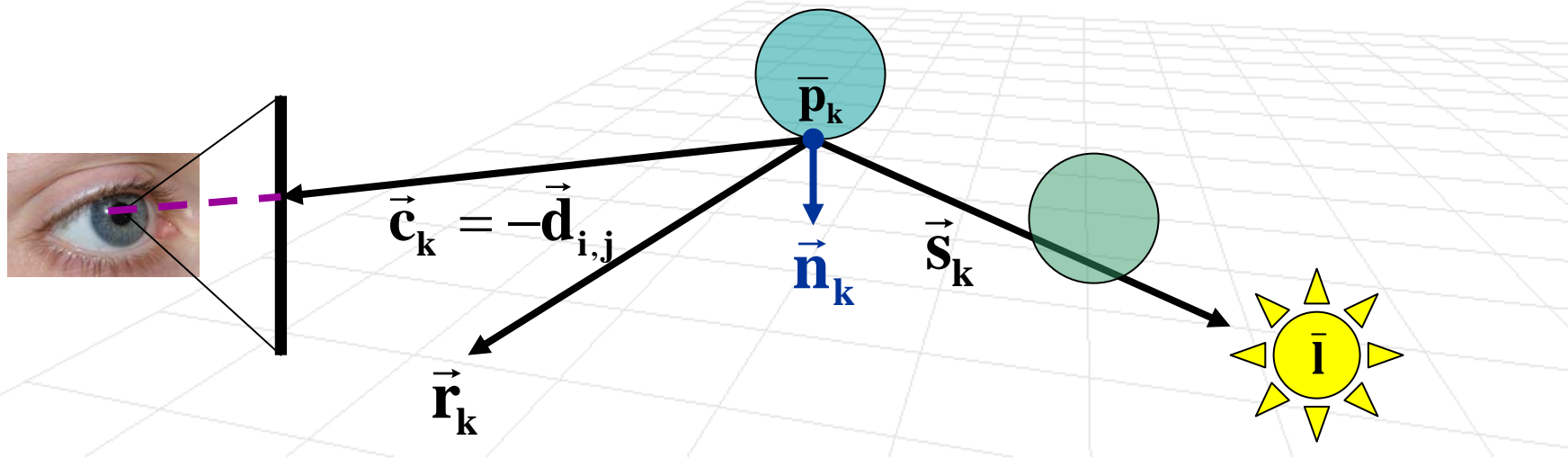
Shadows

- Easy to deal with in ray tracing
 - When point is in shadow, turn off local reflection
- To do so, cast a ray towards a light source

$$\bar{\mathbf{r}}(\lambda) = \bar{\mathbf{p}}_k + \lambda(\bar{\mathbf{I}} - \bar{\mathbf{p}}_k)$$

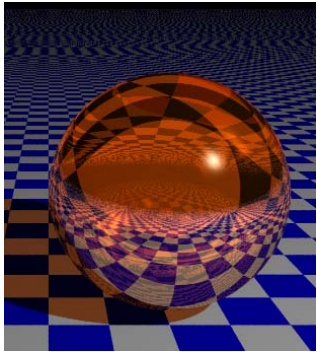
if there is a hit point $0 \leq \lambda \leq 1$, turn off local reflection
(diffuse and specular components of Phong)

$$\mathbf{E}_k = \mathbf{r}_d \mathbf{I}_d \max(0, \vec{\mathbf{s}}_k \cdot \vec{\mathbf{n}}_k) + \mathbf{r}_a \mathbf{I}_a + \mathbf{r}_s \mathbf{I}_s \max(0, \vec{\mathbf{r}}_k \cdot \vec{\mathbf{c}}_k)^\alpha + \mathbf{r}_g \mathbf{I}_{\text{spec}}$$



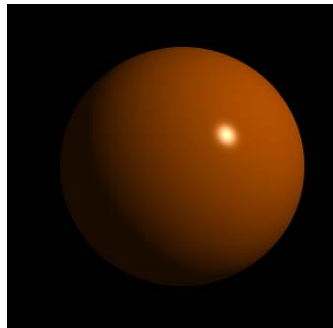
Review of Ray Tracer Shading

**Final
Image**



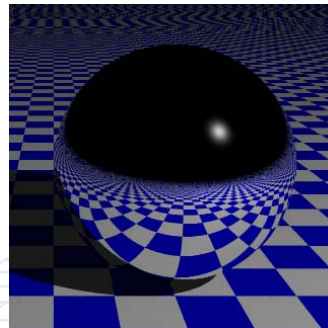
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**Local
Lighting
Phong**



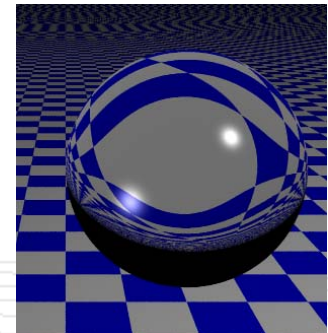
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**Global
Reflections
(and shadows)**



+

Refractions



[images from lecture notes by John Dingliana]