

THE UNIVERSITY OF BRITISH COLUMBIA

Topics in AI (CPSC 532S): **Multimodal Learning with Vision, Language and Sound**

Lecture 4: Introduction to Computer Vision





Human Vision





objects, scenes, people

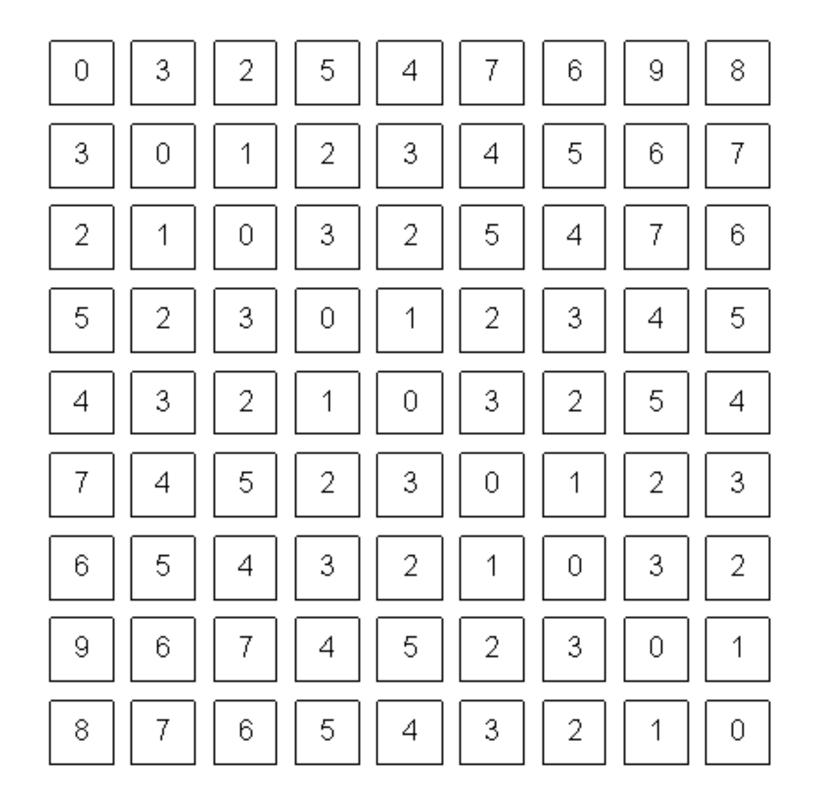
Human Vision





objects, scenes, people

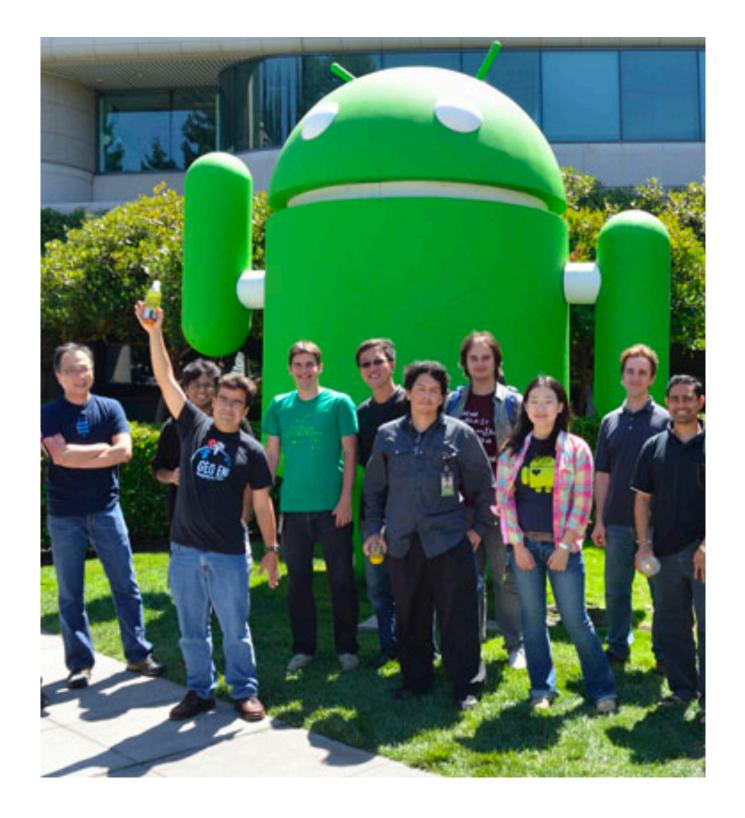
Human Vision



matrix of numbers

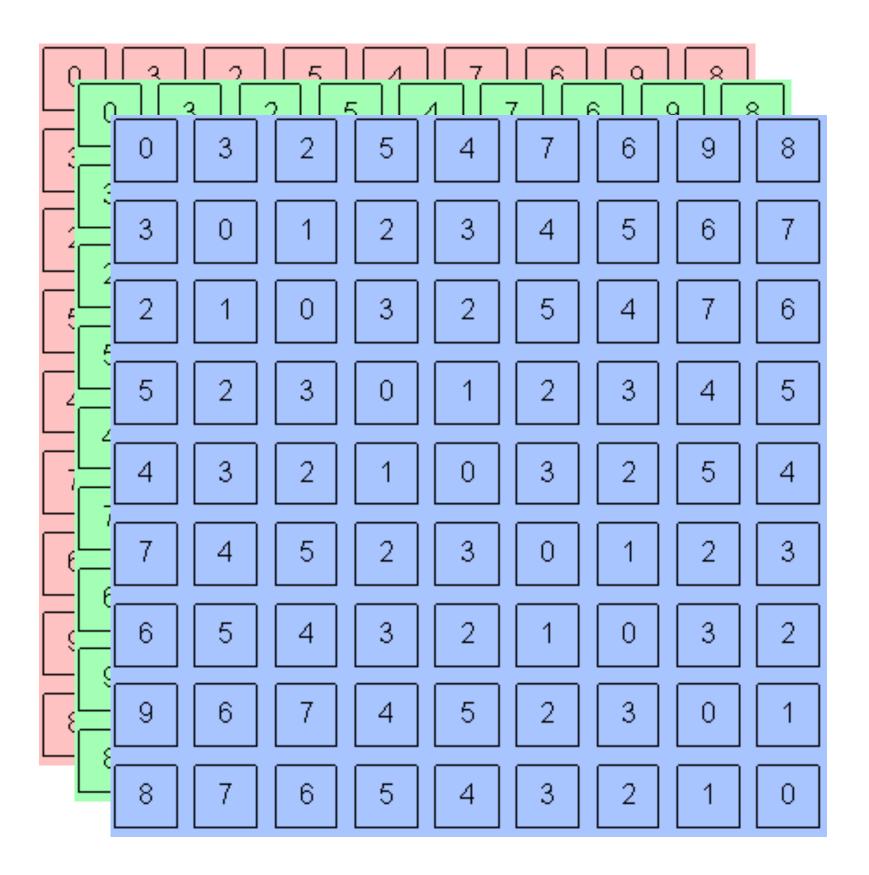
Computer Vision





objects, scenes, people

Human Vision



tensor of numbers

Computer Vision



Computer Vision





Computer vision studies the tools and theories that enable the design of machines that can extract useful information from imagery data (images and videos) toward the goal of interpreting the world

*curtesy of Peter Meer





Vision is Amazing Feat of Natural Intelligence



~ 55% of cerebral cortex in humans (13 billion neurons) are devoted to vision more human brain devoted to vision than anything else

Challenges: Viewpoint invariance



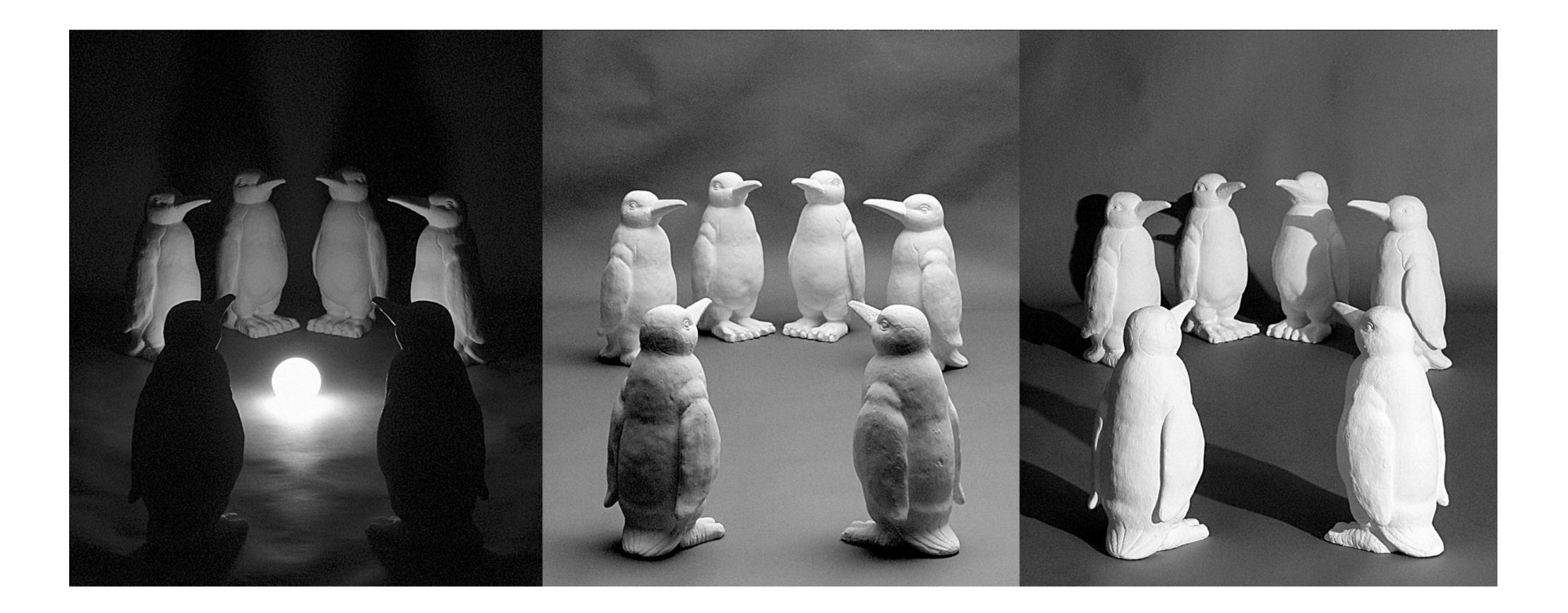
Michelangelo 1475-1564



*slide credit Fei-Fei, Fergus & Torralba



Challenges: Lighting



*image credit J. Koenderink



Challenges: Scale





*slide credit Fei-Fei, Fergus & Torralba



Challenges: Deformation



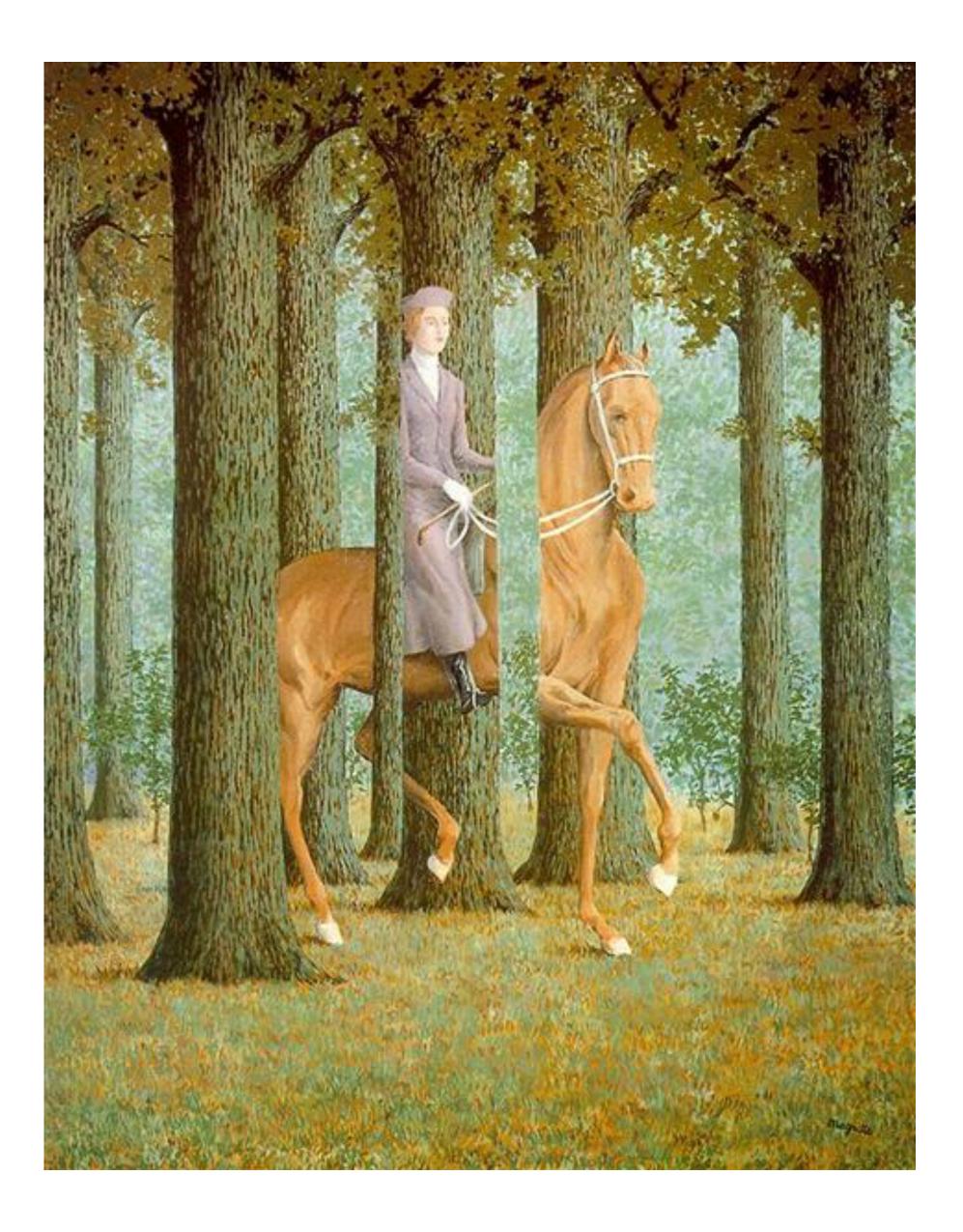


*image credit Peter Meer



Challenges: Occlusions

Rene Magritte 1965

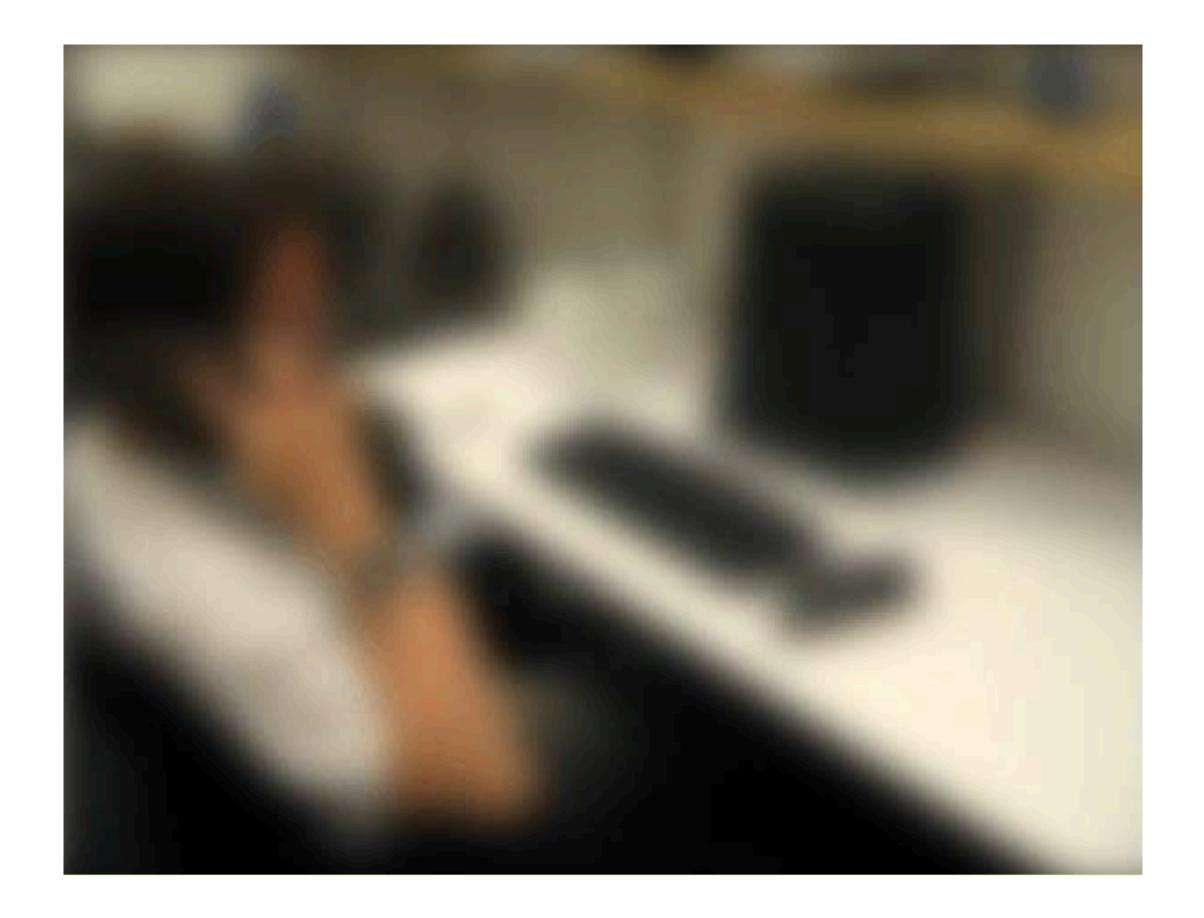


Challenges: Background clutter

Kilmeny Niland 1995



Challenges: Local ambiguity and context



*image credit Fergus & Torralba



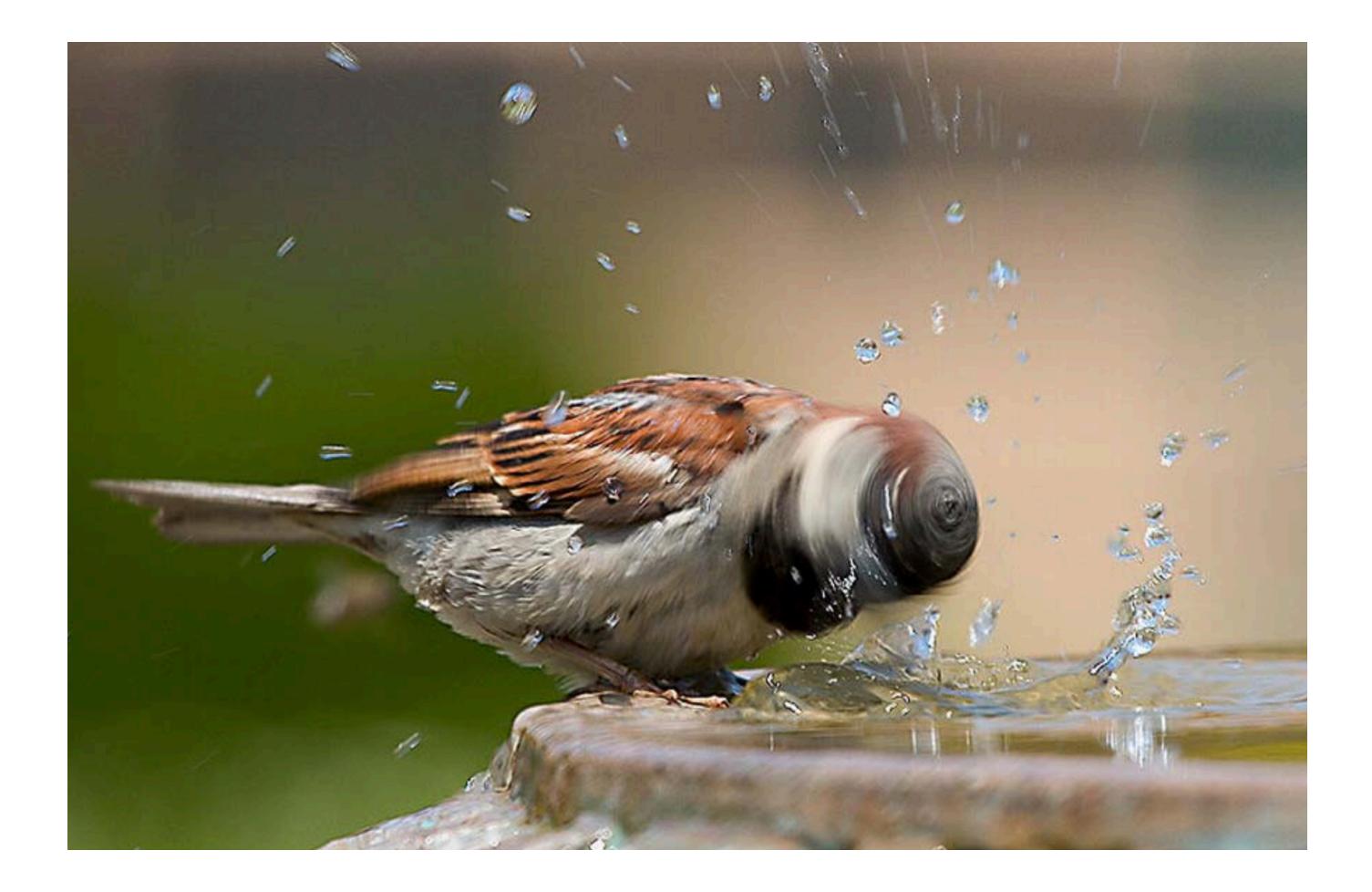
Challenges: Local ambiguity and context



*image credit Fergus & Torralba



Challenges: Motion



*image credit Peter Meer



Challenges: Object inter-class variation









*slide credit Fei-Fei, Fergus & Torralba



Human vision ...

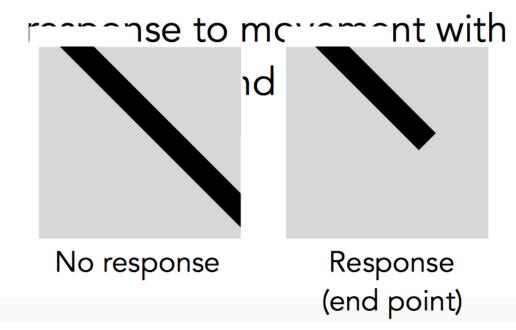
Simple cells:

Response to light orientation

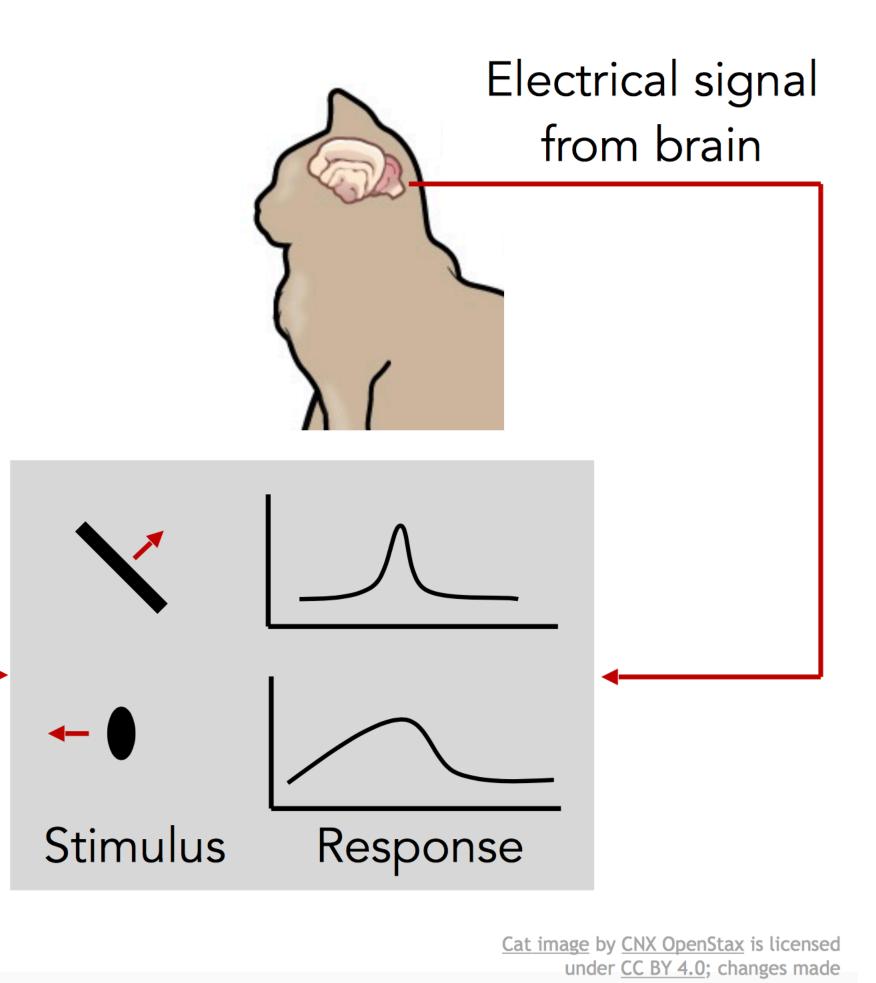
Complex cells:

Response to light orientation and movement

Hypercomplex cells:



Stimulus



* slide from Fei-Dei Li, Justin Johnson, Serena Yeung, cs231n Stanford

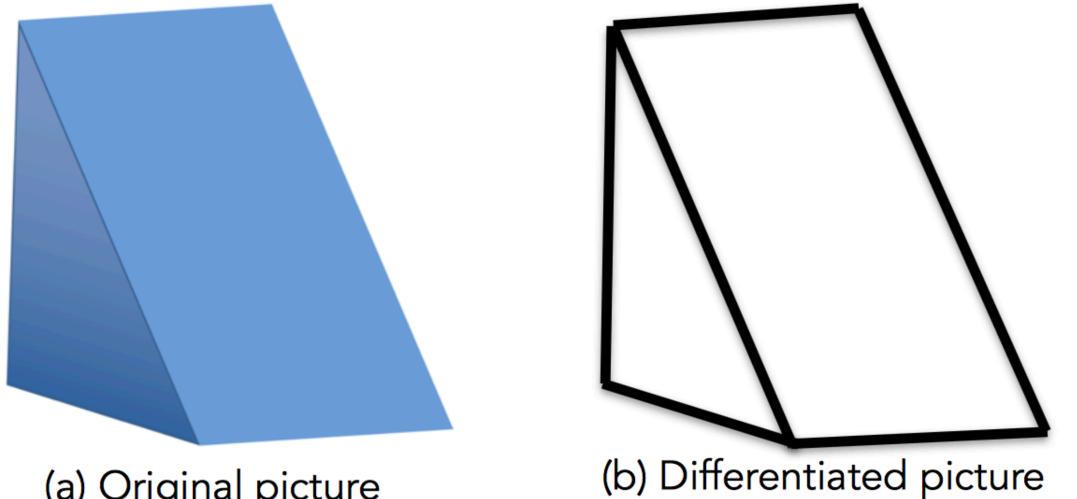




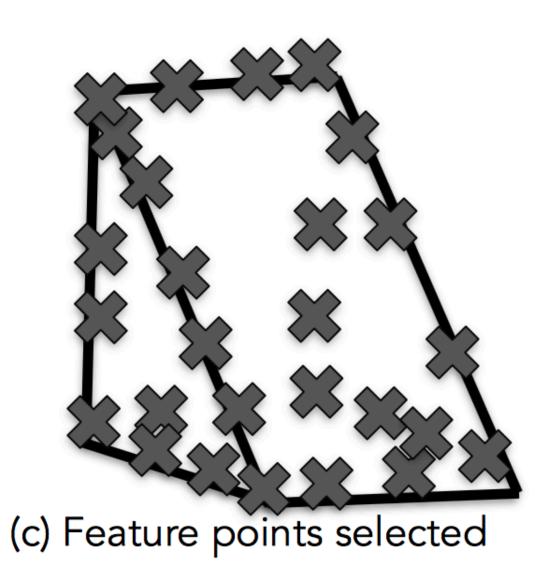
Blocks World. first thesis in computer vision, 1963

Larry Roberts

"the perception of **solid objects** is a process which can be based on the properties of three-dimensional transformations and the laws of nature"



(a) Original picture





Blocks World. first thesis in computer vision, 1963

Larry Roberts

"the perception of **solid objects** is a process which can be based on the properties of three-dimensional transformations and the laws of nature"

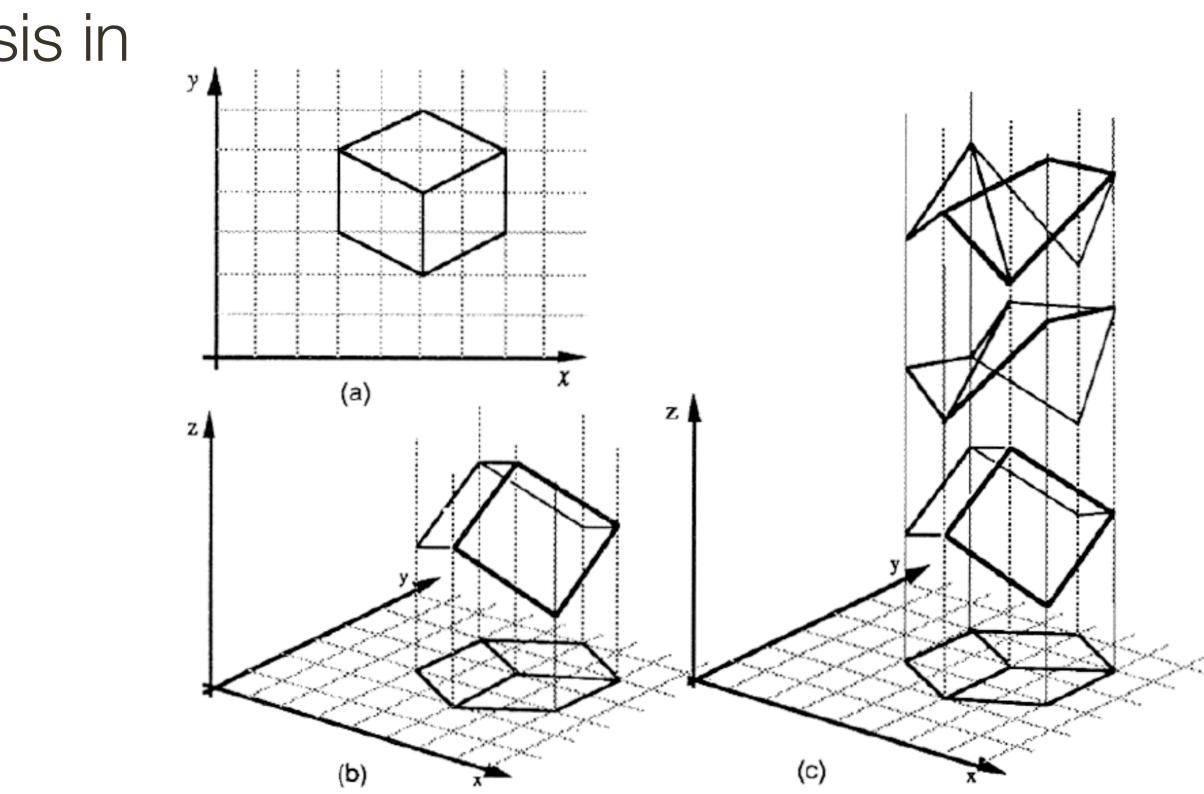
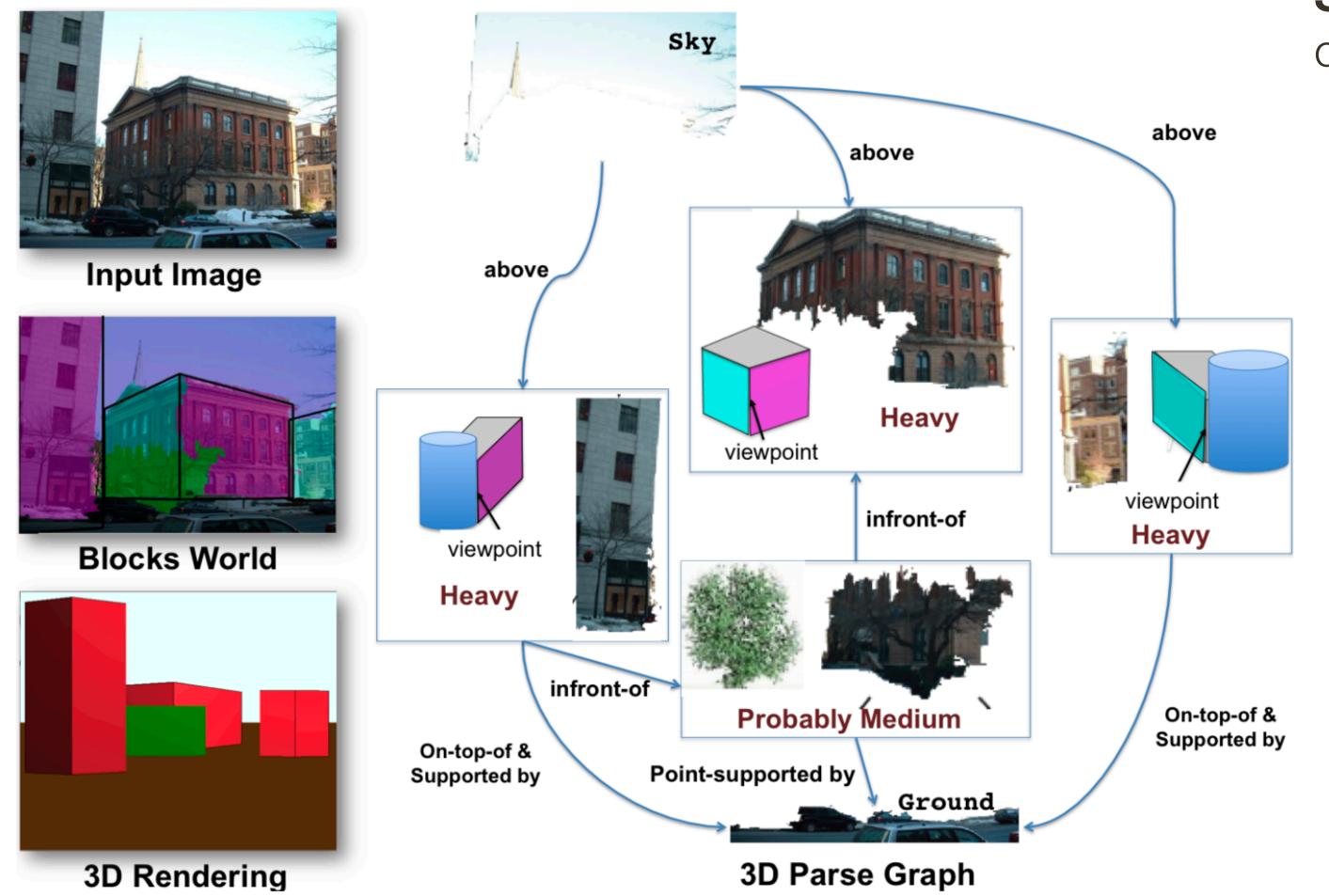


Figure 1. (a) A line drawing provides information only about the x, y coordinates of points lying along the object contours. (b) The human visual system is usually able to reconstruct an object in three dimensions given only a single 2D projection (c) Any planar line-drawing is geometrically consistent with infinitely many 3D structures.

[Since & Adelson, 1993]







Static Equilibrium: Forces and torques acting on a block should cancel each other out.

> **Support Force Constraint:** Supporting object should have enough strength to provide contact reactionary forces

Volumetric Constraints: All objects in the world must have finite volume & cannot penetrate each other

[Gupta, Efros & Hebert, 2010]









PROJECT MAC

Artificial Intelligence Group Vision Memo. No. 100.

July 7, 1966

SUMMER VISION PROJEC

Seymour Papert

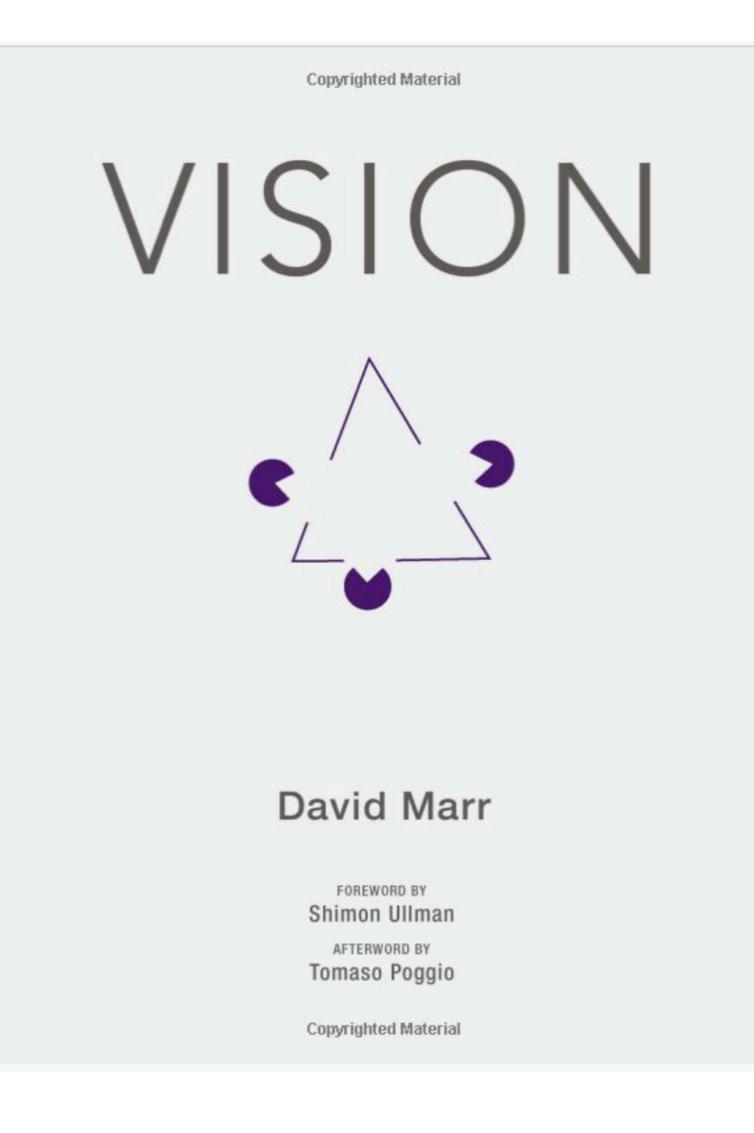
The summer vision project is an attempt to use our summer workers effectively in the construction of a significant part of a visual system. The particular task was chosen partly because it can be segmented into sub-problems which will allow individuals to work independently and yet participate in the construction of a system complex enough to be a real landmark in the development of "pattern recognition".

In 1966, Marvin Minsky at MIT asked his undergraduate student Gerald Jay Sussman to "spend the summer linking a camera to a computer and getting the computer to describe what it saw"

[Szeliski 2009, Computer Vision]



David Marr, 1970s



* slide from Fei-Dei Li, Justin Johnson, Serena Yeung, cs231n Stanford

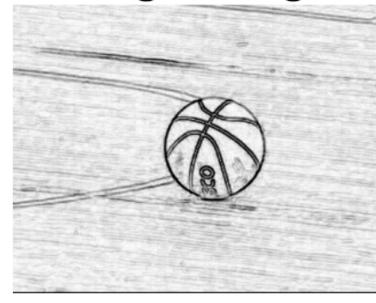
David Marr, 1970s

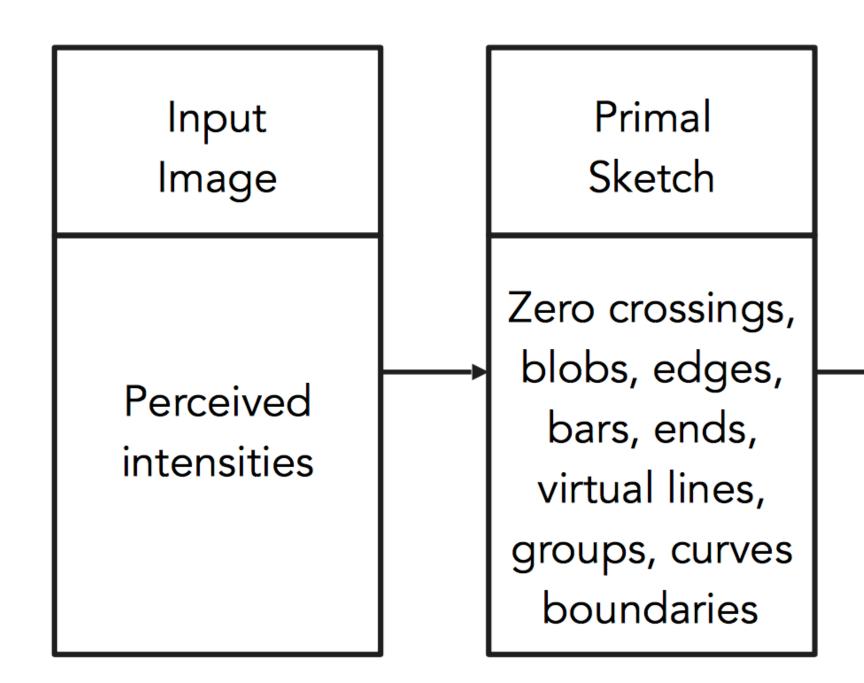
Input image



This image is CC0 1.0 public domain

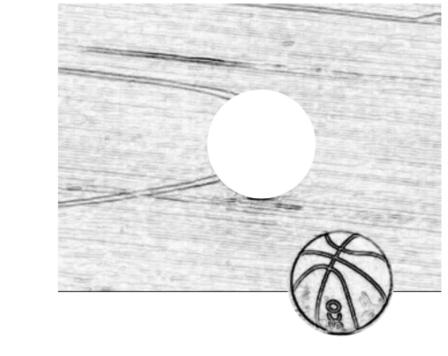
Edge image



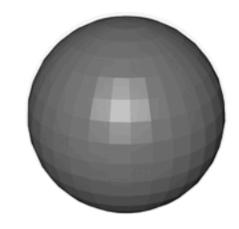


[Stages of Visual Representation, David Marr]

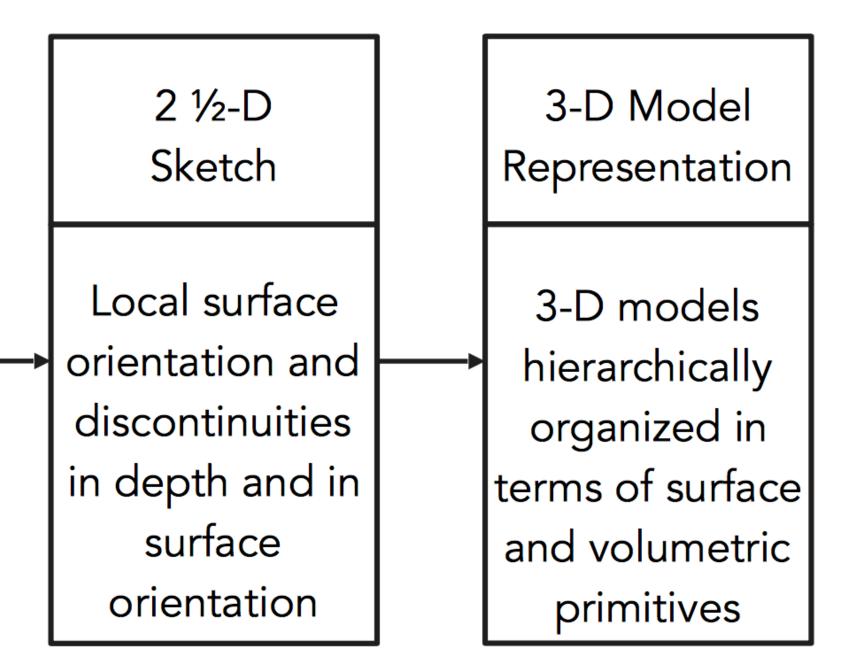
2¹/₂-D sketch



3-D model

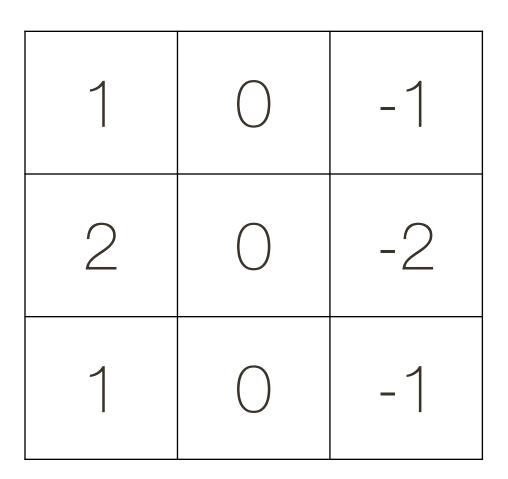


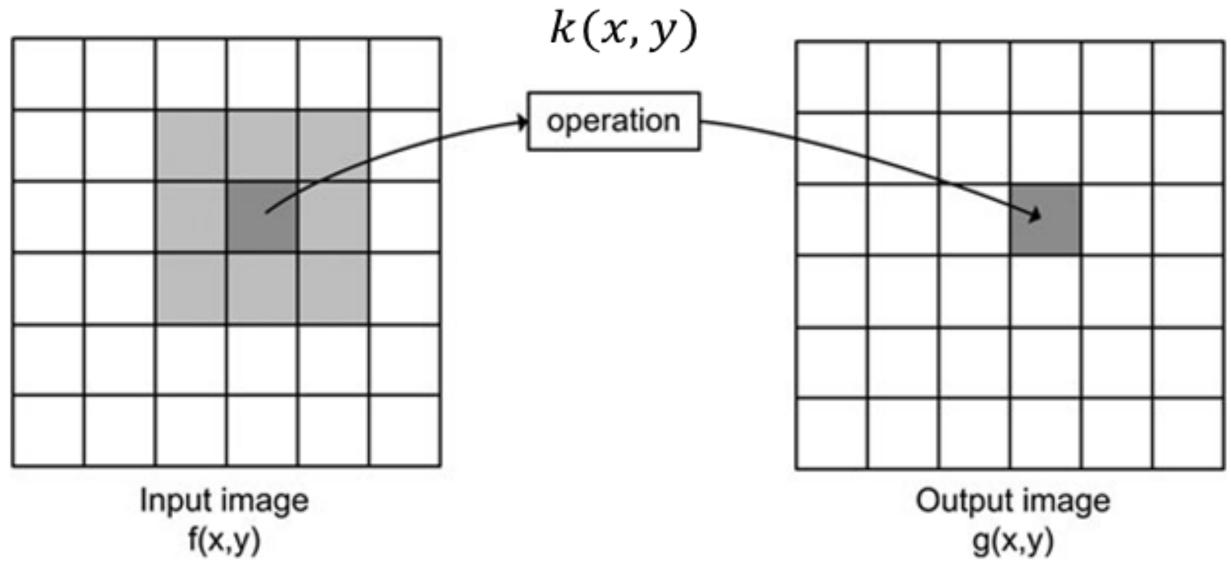
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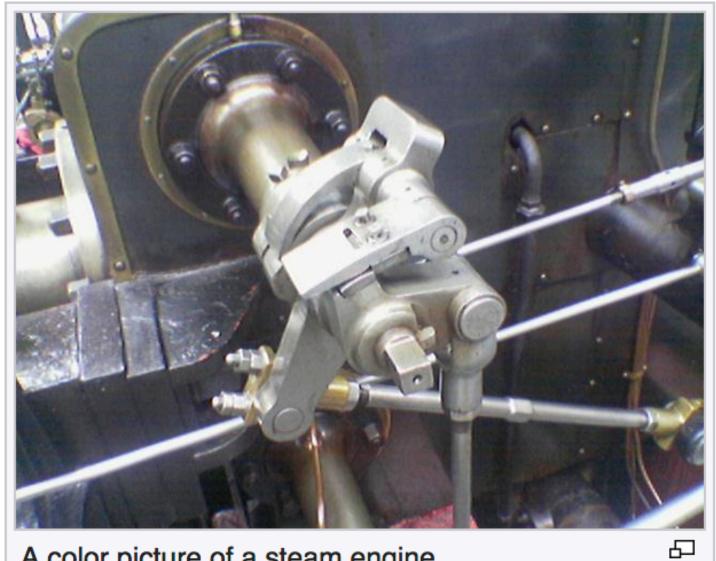


* slide from Fei-Dei Li, Justin Johnson, Serena Yeung, cs231n Stanford

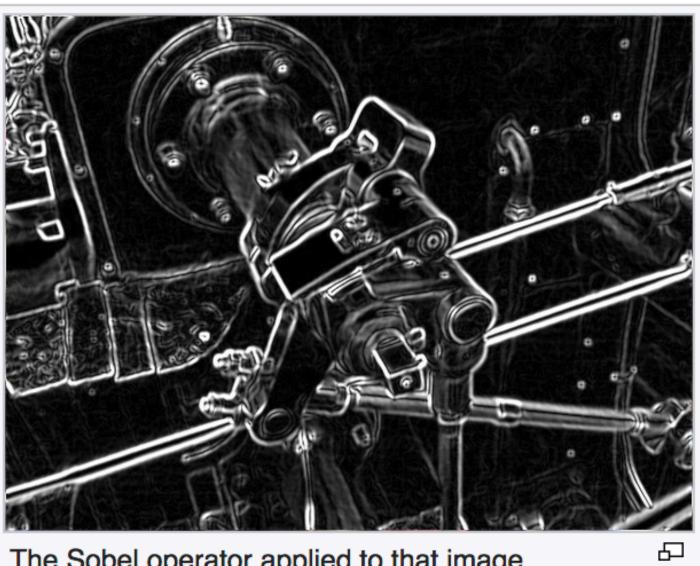
Edges







A color picture of a steam engine



The Sobel operator applied to that image

*content from V. Ordonex

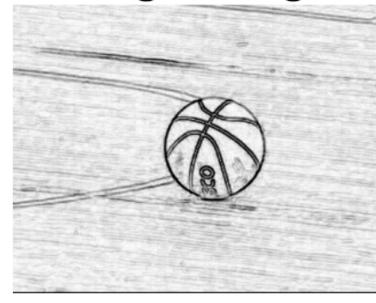
David Marr, 1970s

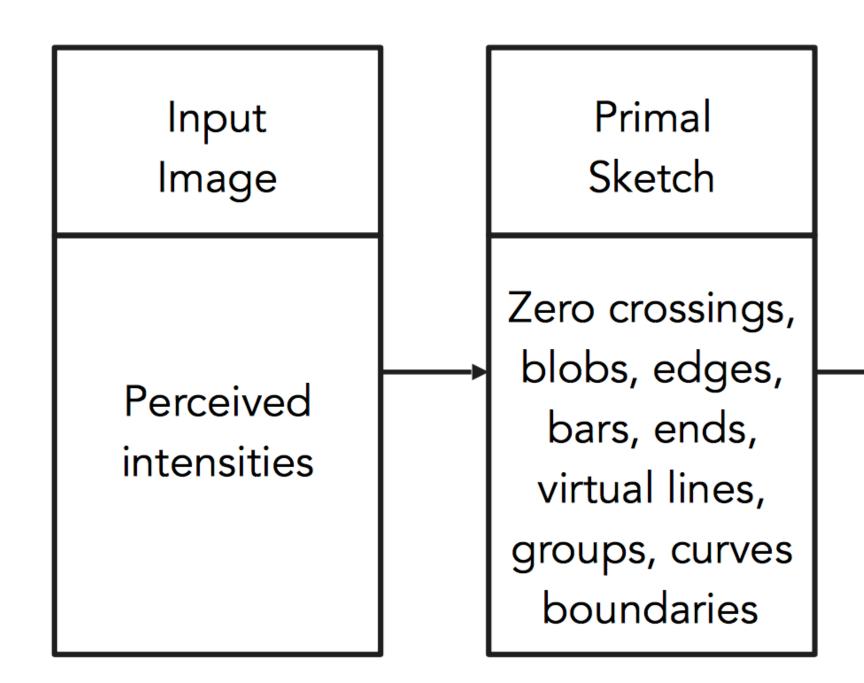
Input image



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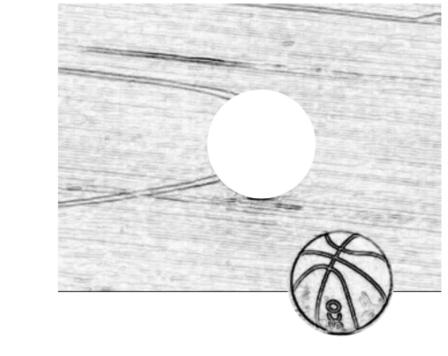
Edge image



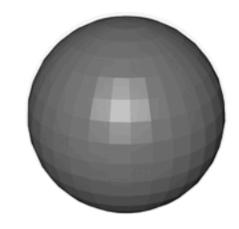


[Stages of Visual Representation, David Marr]

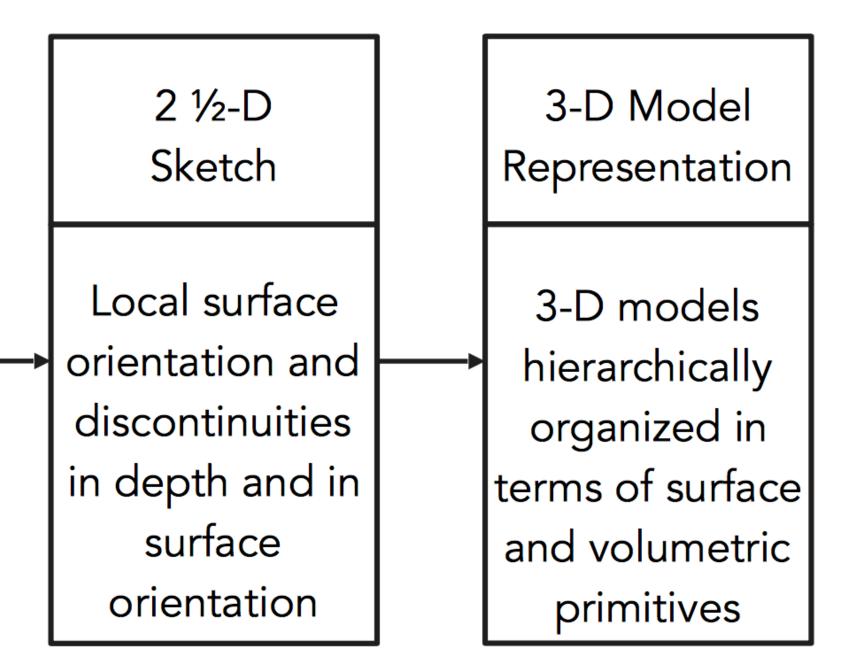
2¹/₂-D sketch



3-D model



This image is CC0 1.0 public domain



* slide from Fei-Dei Li, Justin Johnson, Serena Yeung, cs231n Stanford

Segmentation - GraphCuts



[Shi & Malik, 2000]

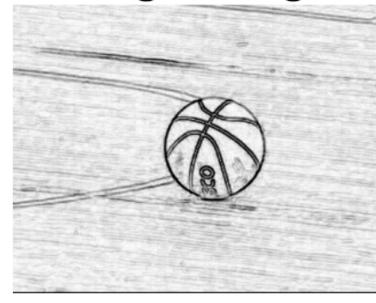
David Marr, 1970s

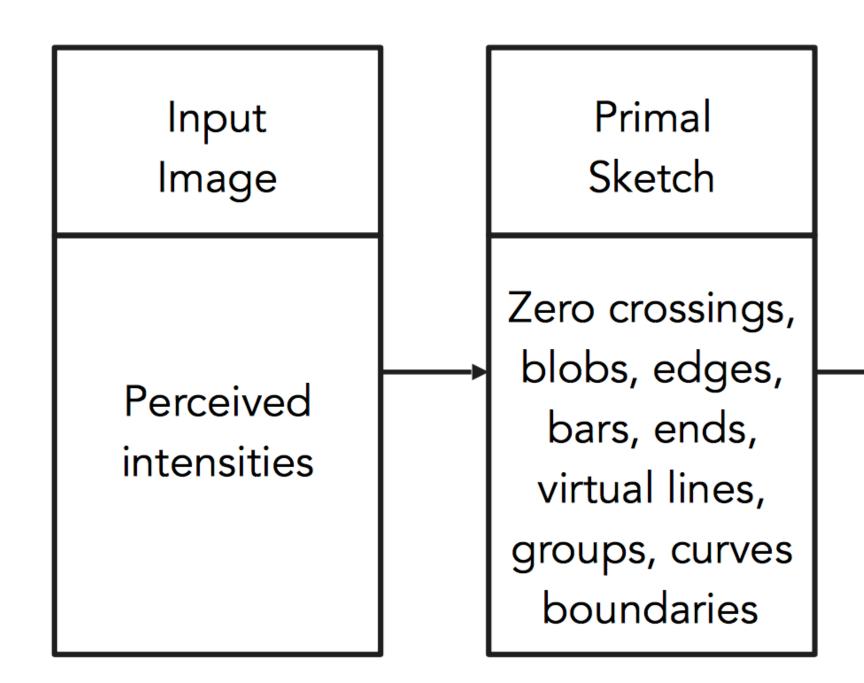
Input image



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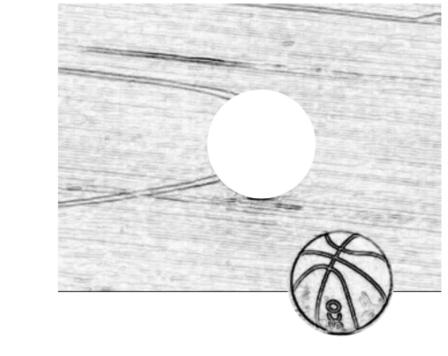
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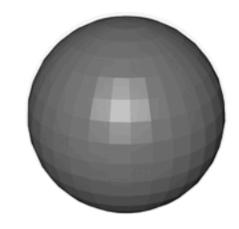


[Stages of Visual Representation, David Marr]

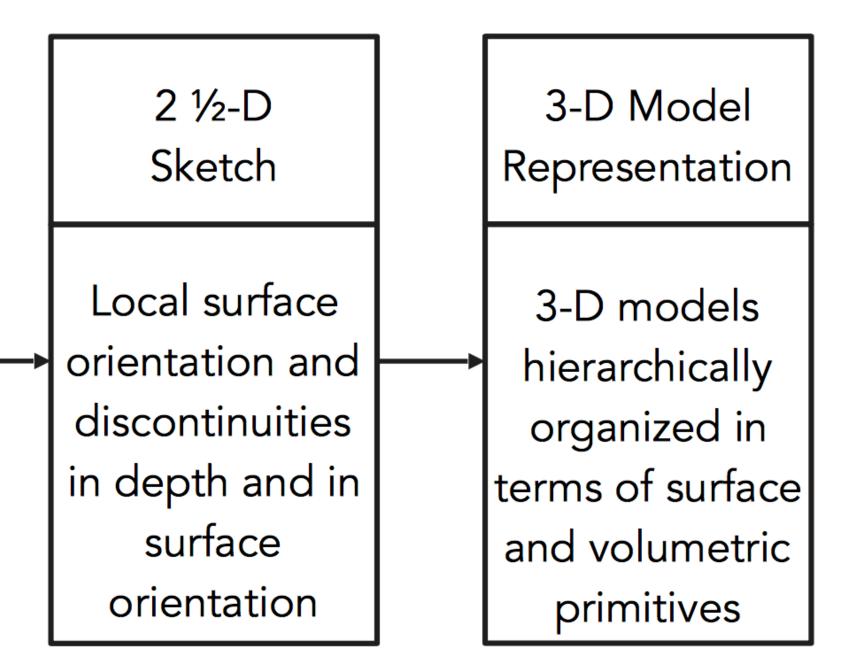
2¹/₂-D sketch



3-D model



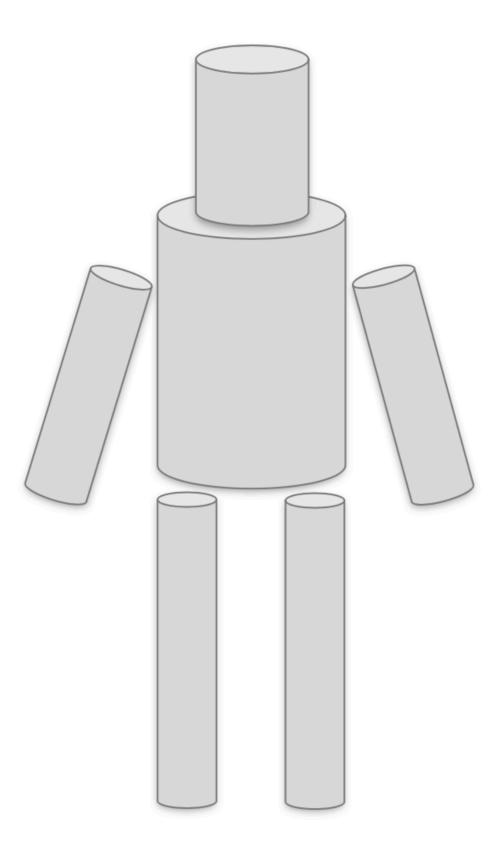
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* slide from Fei-Dei Li, Justin Johnson, Serena Yeung, cs231n Stanford

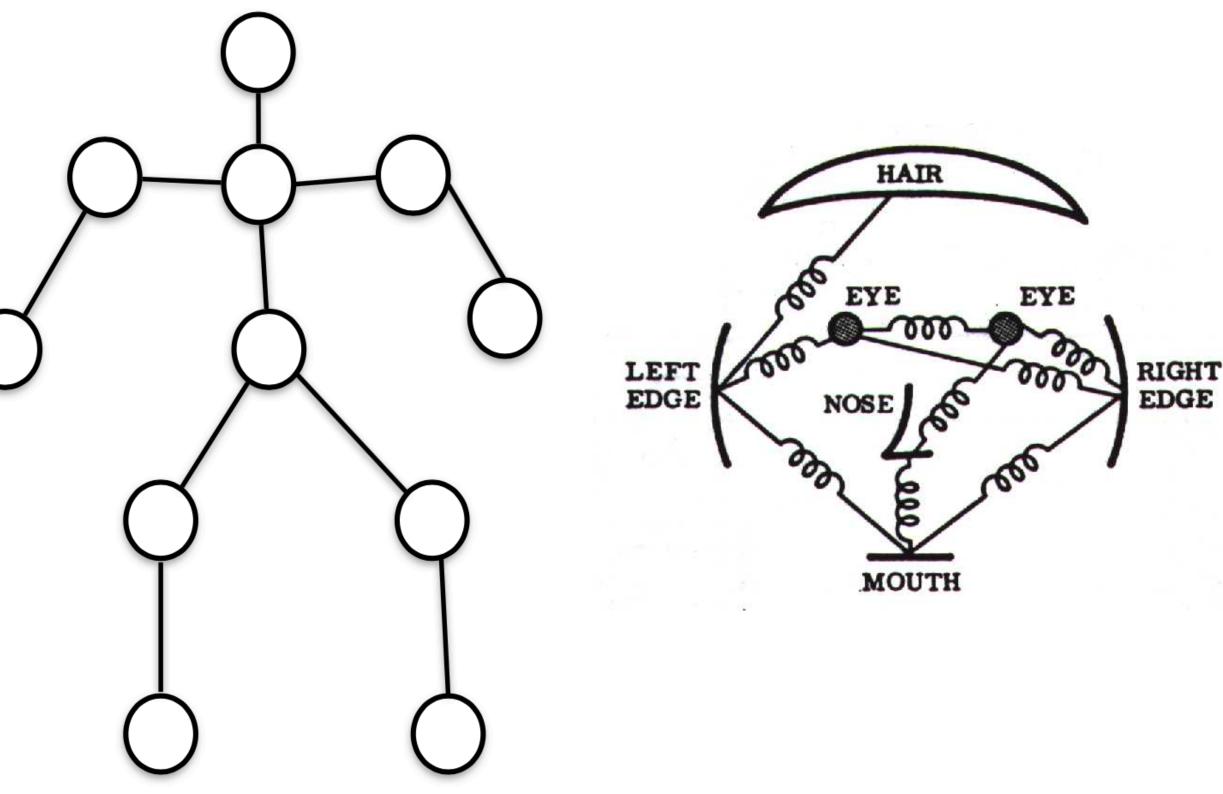
Part-based Models

Generalized Cylinders



[Brooks & Binford, 1979]

Pictorial Structures



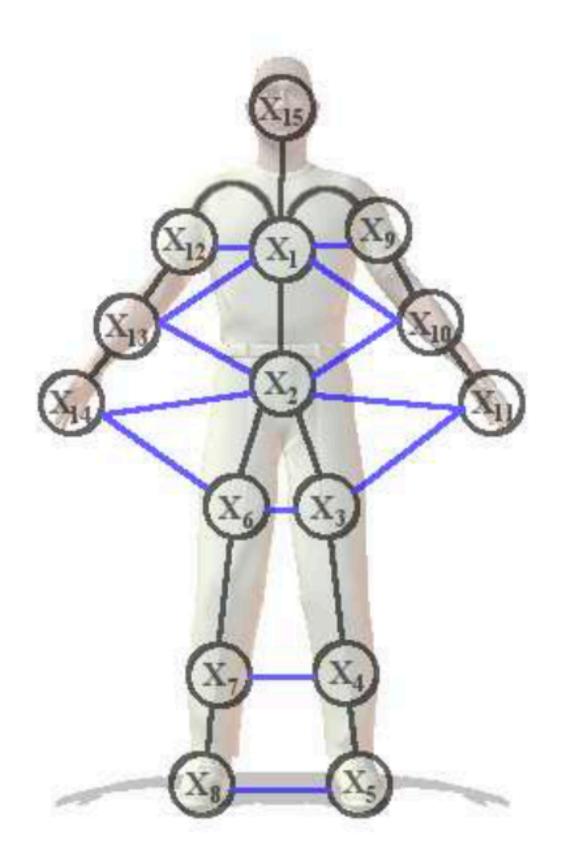
[Fischler & Elschlager, 1973]



2

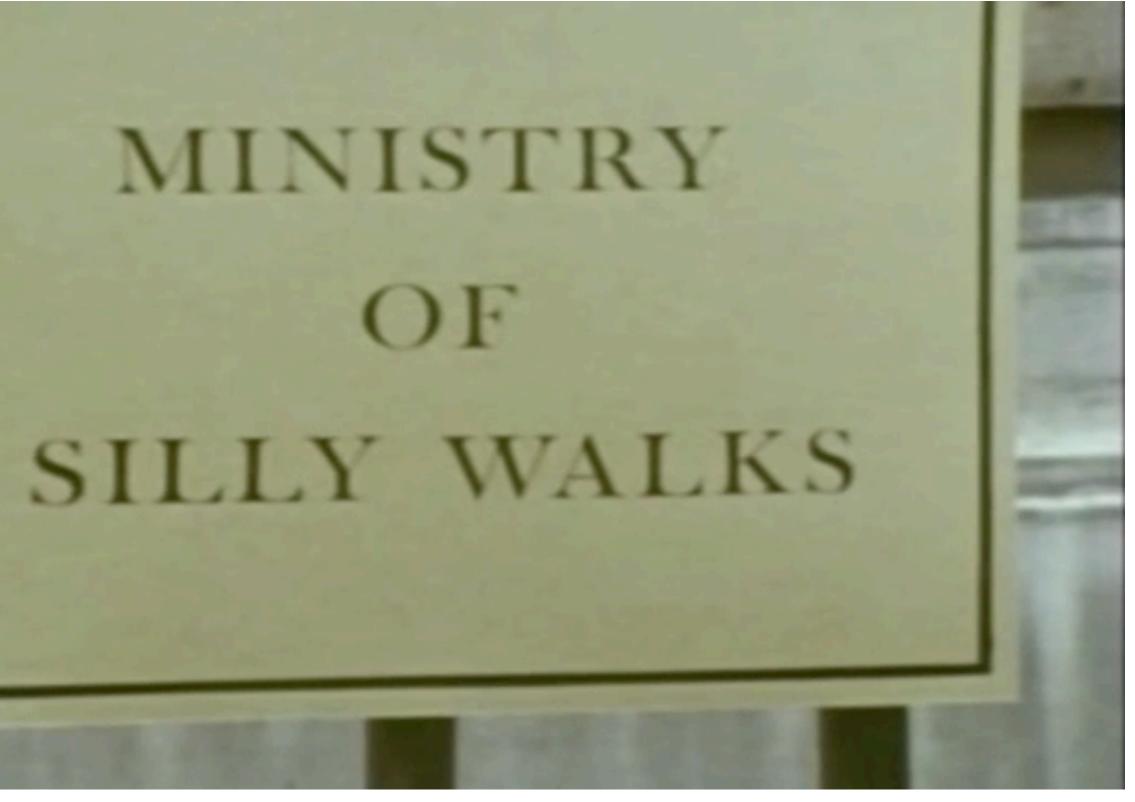
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Part-based Models



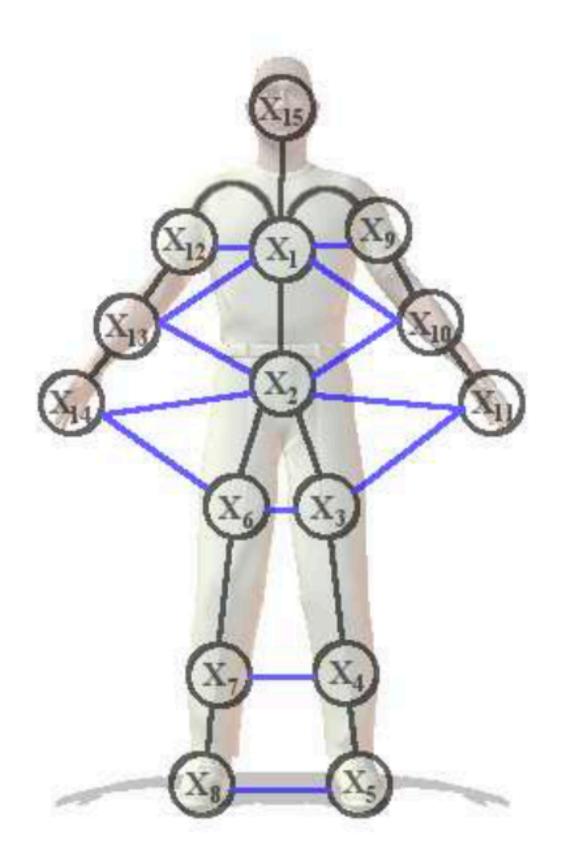


[Sigal et al. 2004]



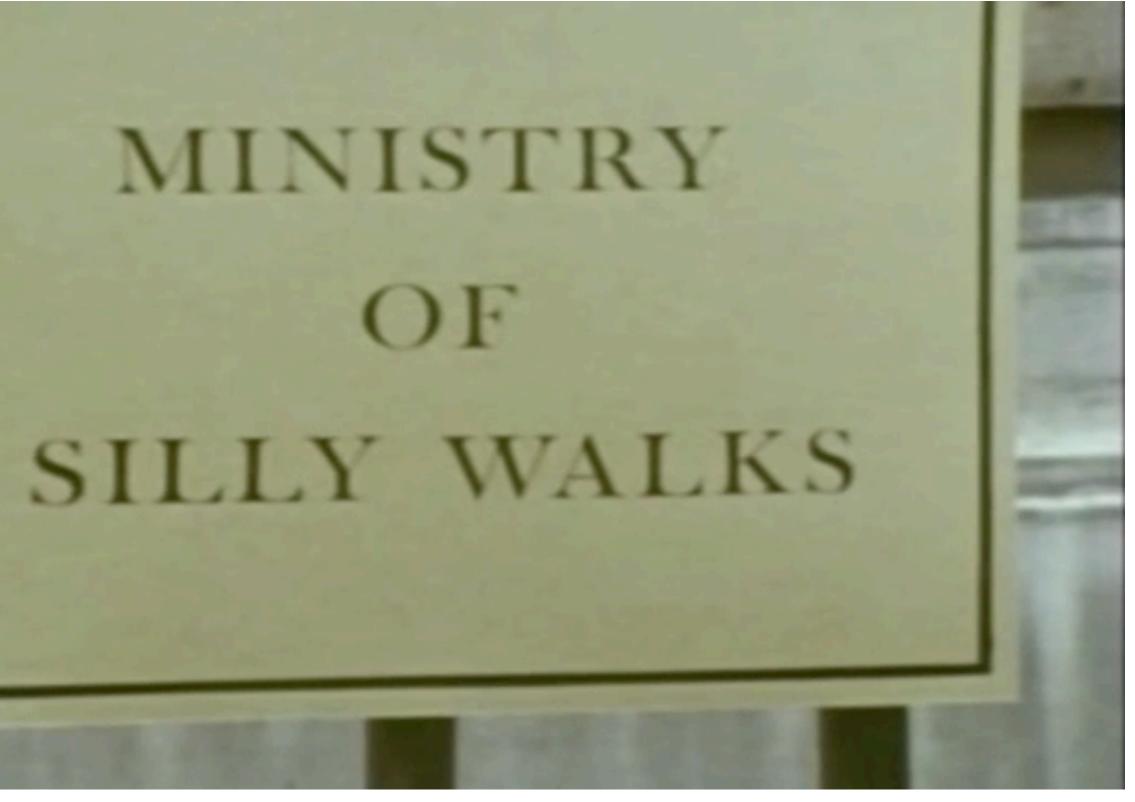
Monty Python's Ministry of Silly Walks

Part-based Models





[Sigal et al. 2004]



Monty Python's Ministry of Silly Walks

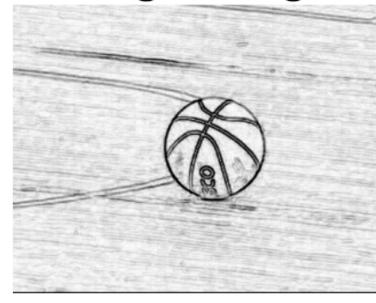
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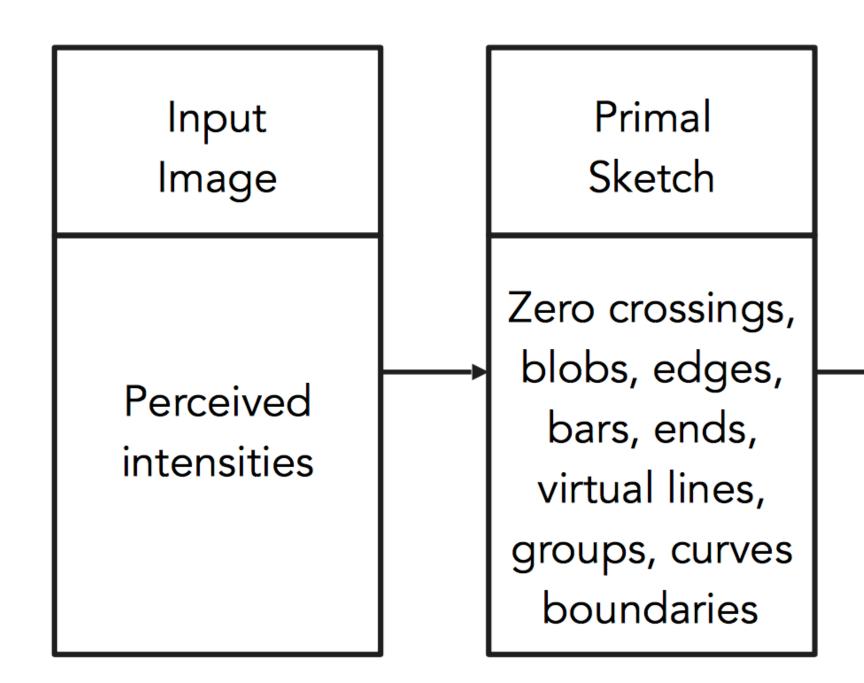
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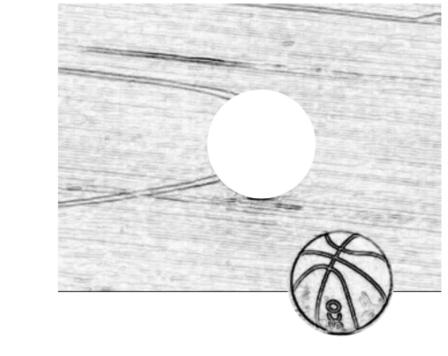
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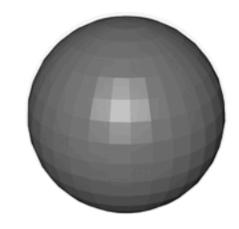


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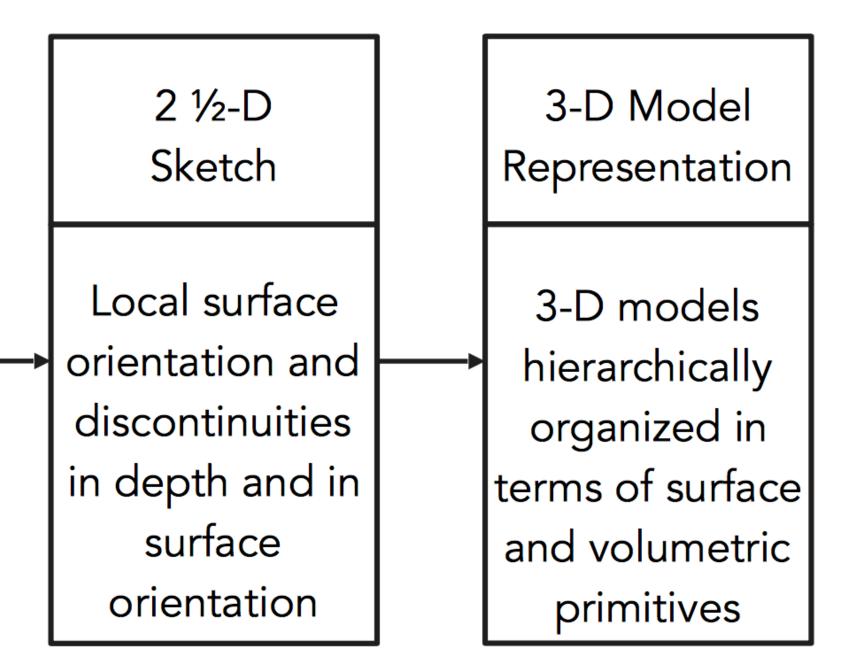
2¹/₂-D sketch



3-D model

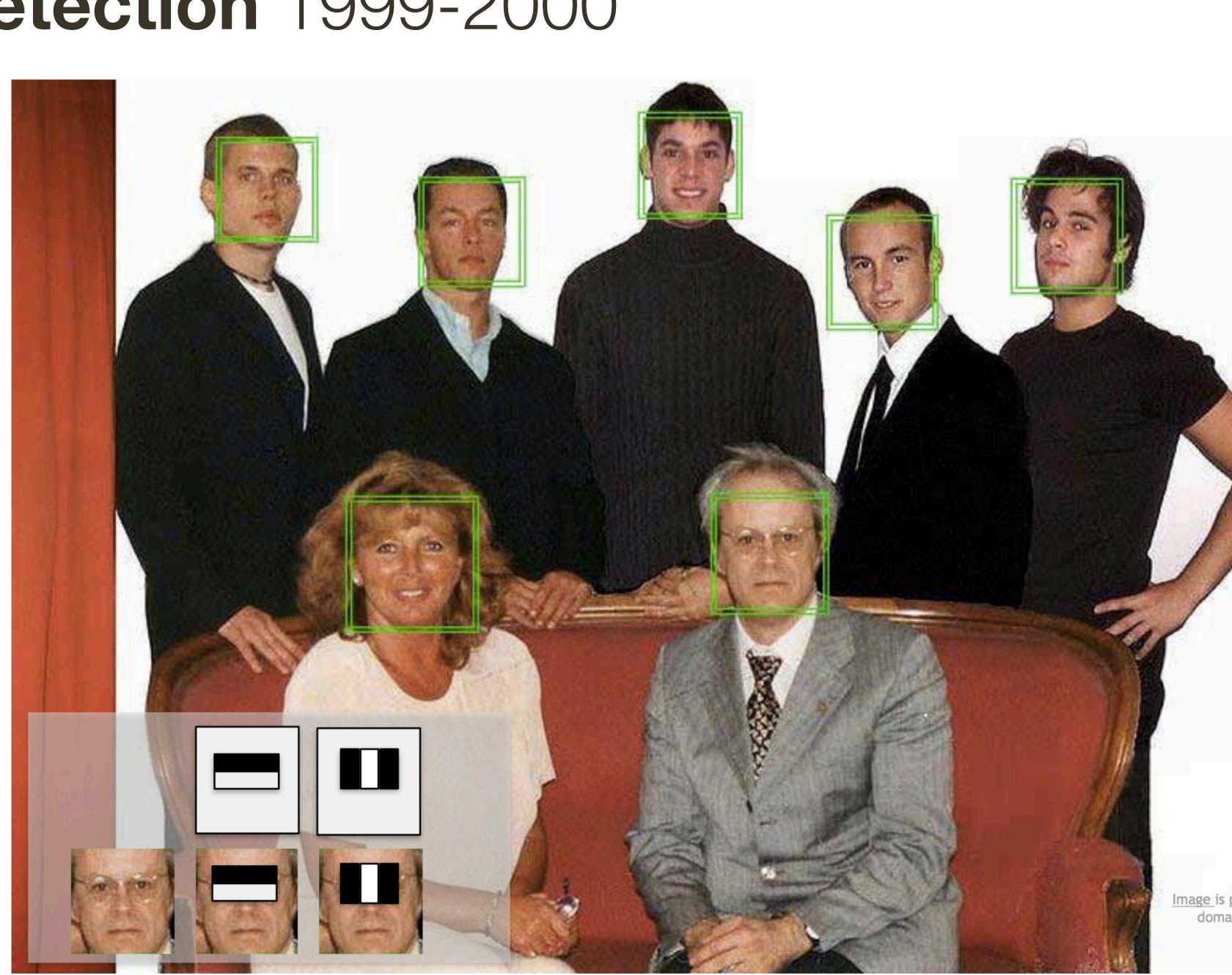


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* slide from Fei-Dei Li, Justin Johnson, Serena Yeung, cs231n Stanford

Face Detection 1999-2000



[Viola & Jones, 2001]

Image is public domain



Feature-based Vision



Image is public domain

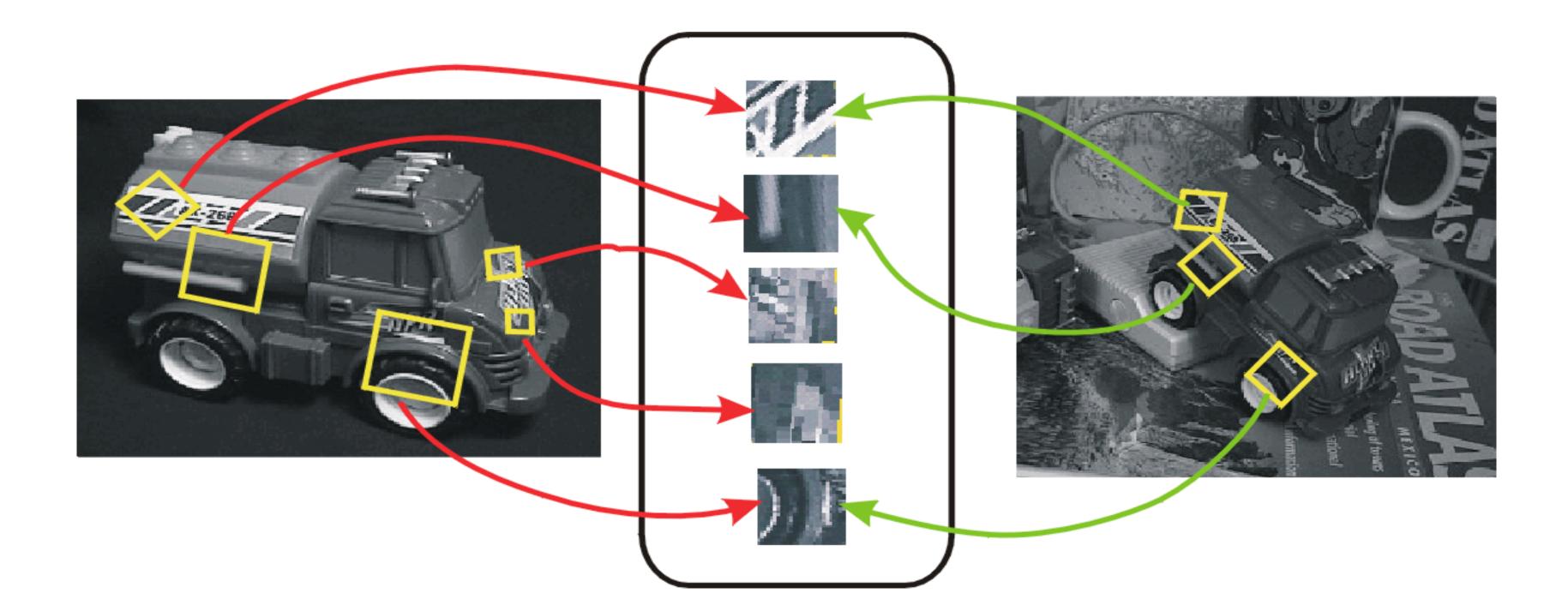
[**David Lowe**, 1999]



Image is CC BY-SA 2.0

SIFT Idea

to translation, rotation, scale and imaging parameters



[**David Lowe**, 1999]

Image content is transformed into local feature coordinates that are invariant

SIFT Discriptor

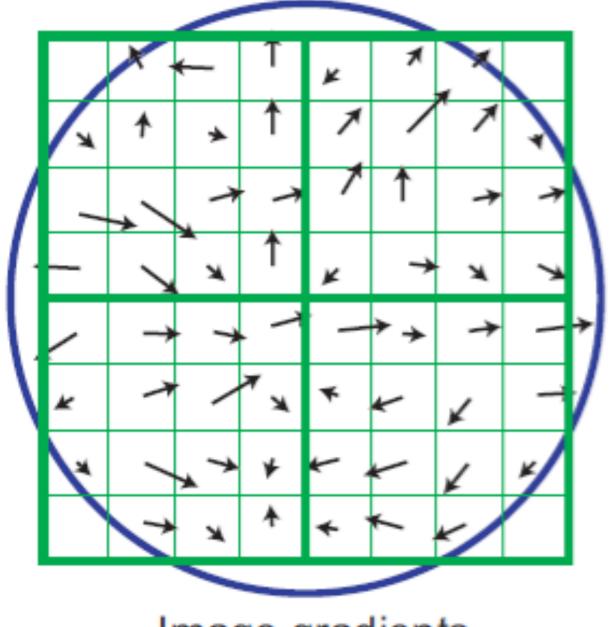
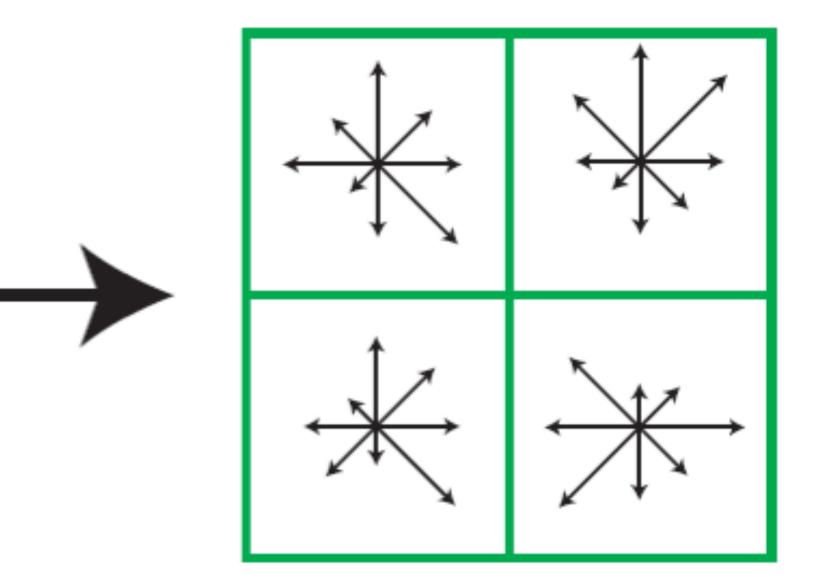


Image gradients



Keypoint descriptor

[**David Lowe**, 1999]

Massive 3D Reconstructions

[Agarwal, Furukawa, Snavely, Curless, Seitz, Szeliski, 2010]



Massive 3D Reconstructions

[Agarwal, Furukawa, Snavely, Curless, Seitz, Szeliski, 2010]



Bag-of-Words

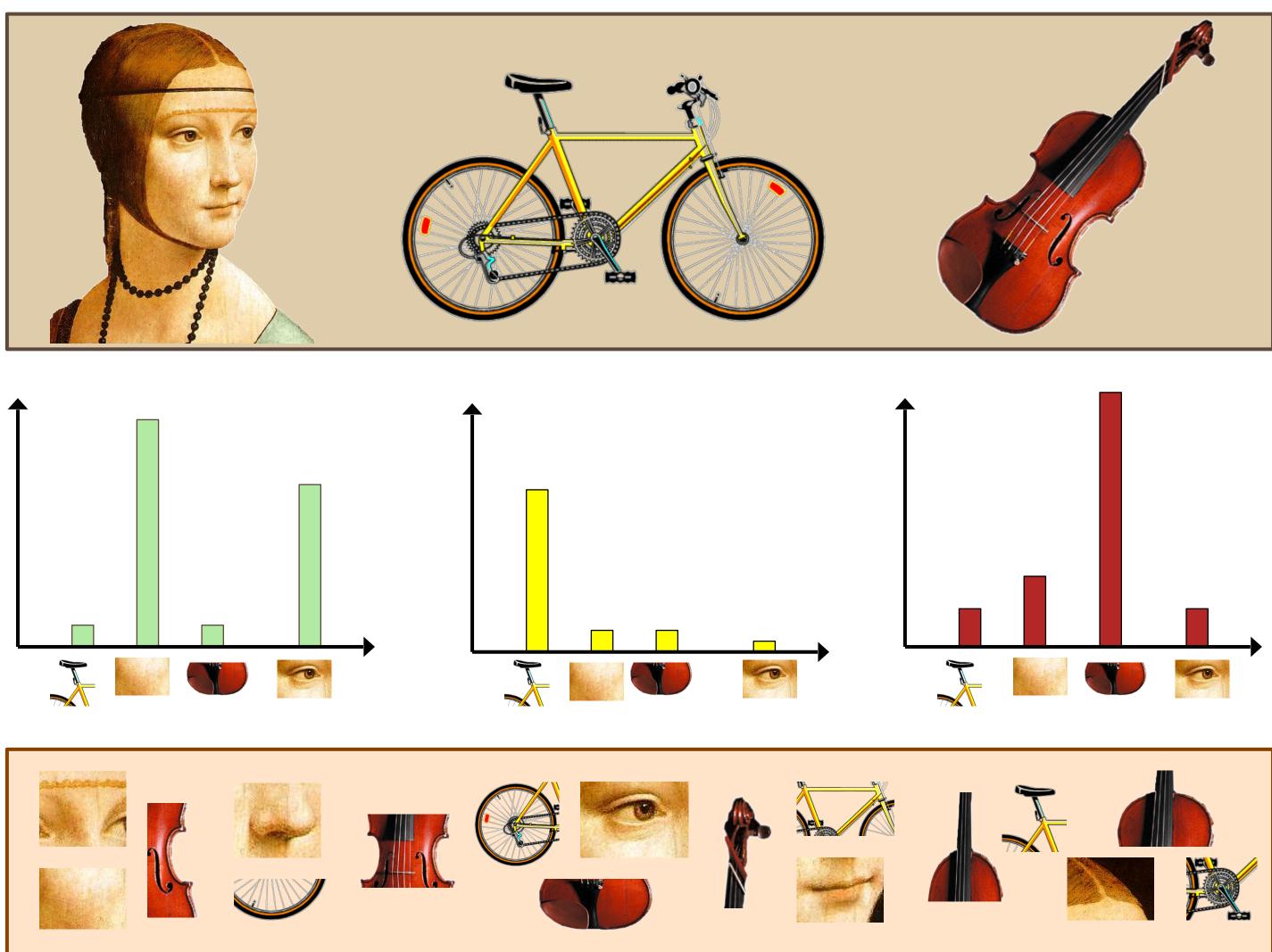
Of all the sensory impressions proceeding to the brain, the visual experiences are the dominant ones. Our perception of the world around us is based and the messages that our eyes. For a long 📁 etinal sensory, brain, image wa isual centers visual, perception, s a movie s retinal, cerebral cortex, image i eye, cell, optical discove W nerve, image that behi Hubel, Wiesel in the brain complicated the arious visual impulse cell layers of the c nd Wiesel have been able to demons hat the message about the image falling on tina undergoes a step-wise analysis in a S of nerve cells stored in columns. In this s each cell has its specific function and is responsible for a specific detail in the patiof the retinal image.

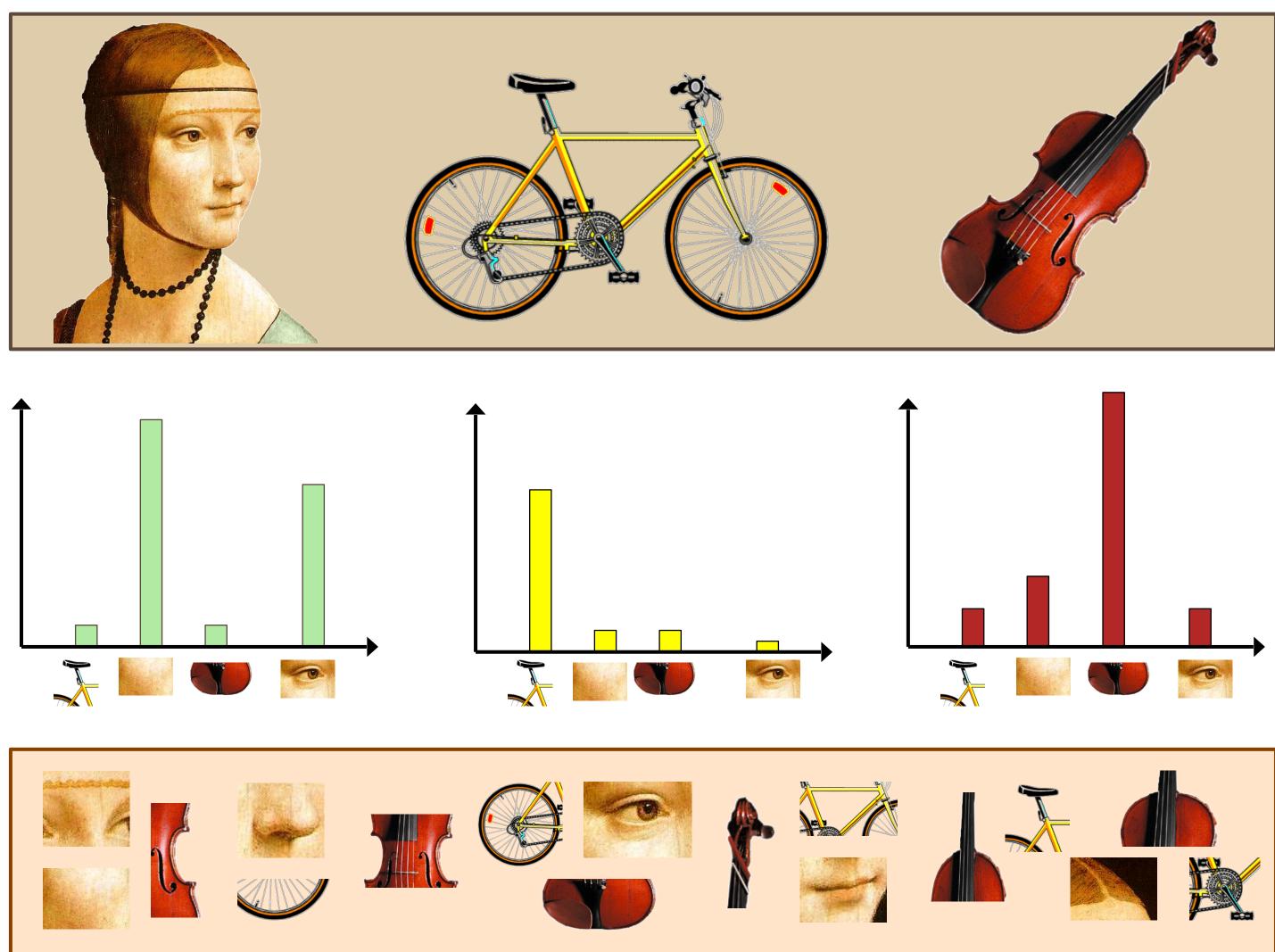
China is forecasting a trade surplus of \$90bn (£51bn) to \$100bn this year, a threefold increase on 2004's \$32bn. The Commerce Ministry said the e created by 750bn, a predicted compared China, trade, \$660bn. surplus, commerce, annoy t exports, imports, US, China's yuan, bank, domestic, delibera agrees foreign, increase, yuan is c trade, value governor 2 also needeo demand so mo. the country. China increa yuan against the dollar by 2.1% in nd permitted it to trade within a narrow the US wants the yuan to be allowed le freely. However, Beijing has made it cle that it will take its time and tread careful before allowing the yuan to rise further in value.

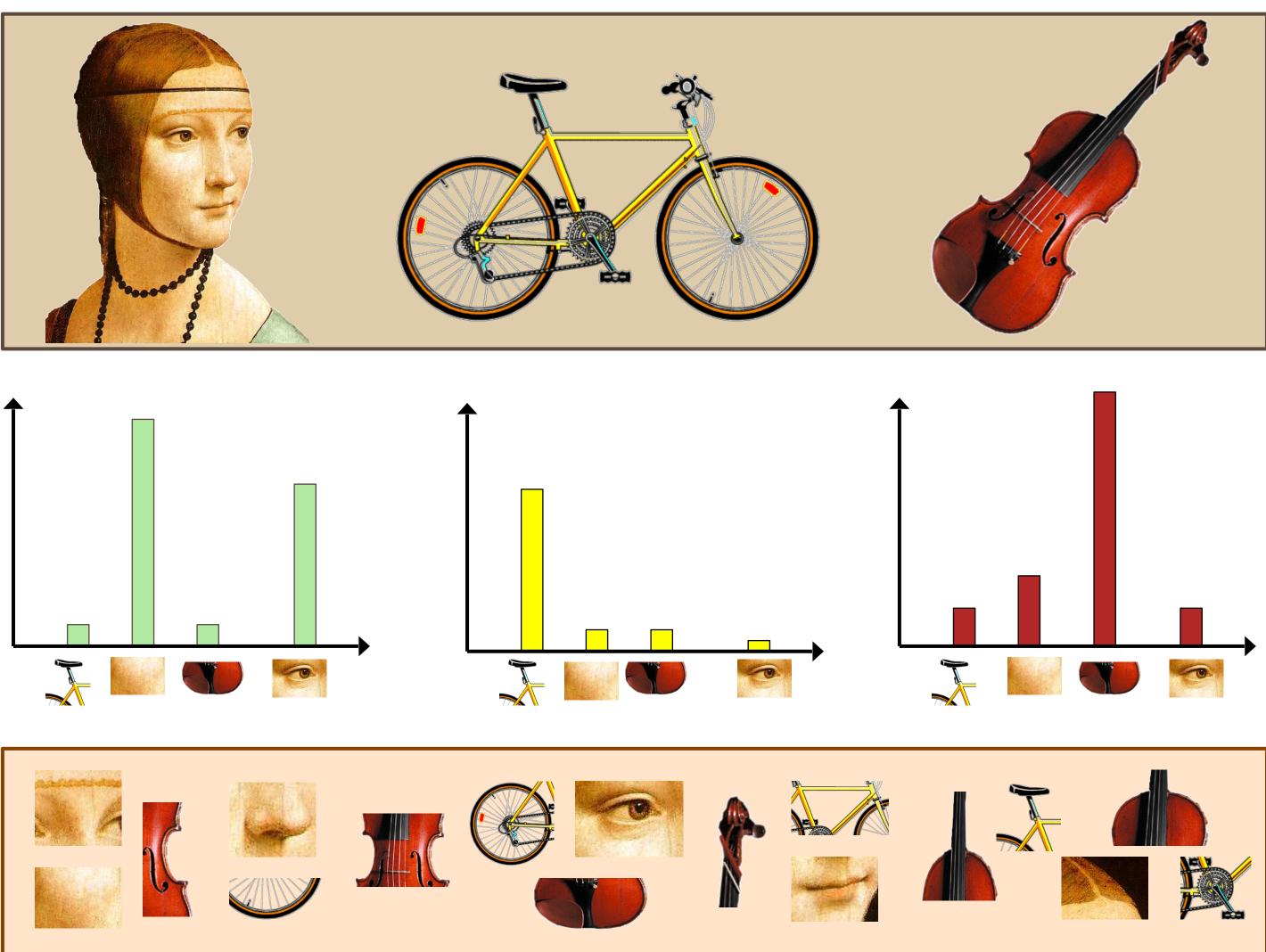
but



Bag-of-Visual-Words

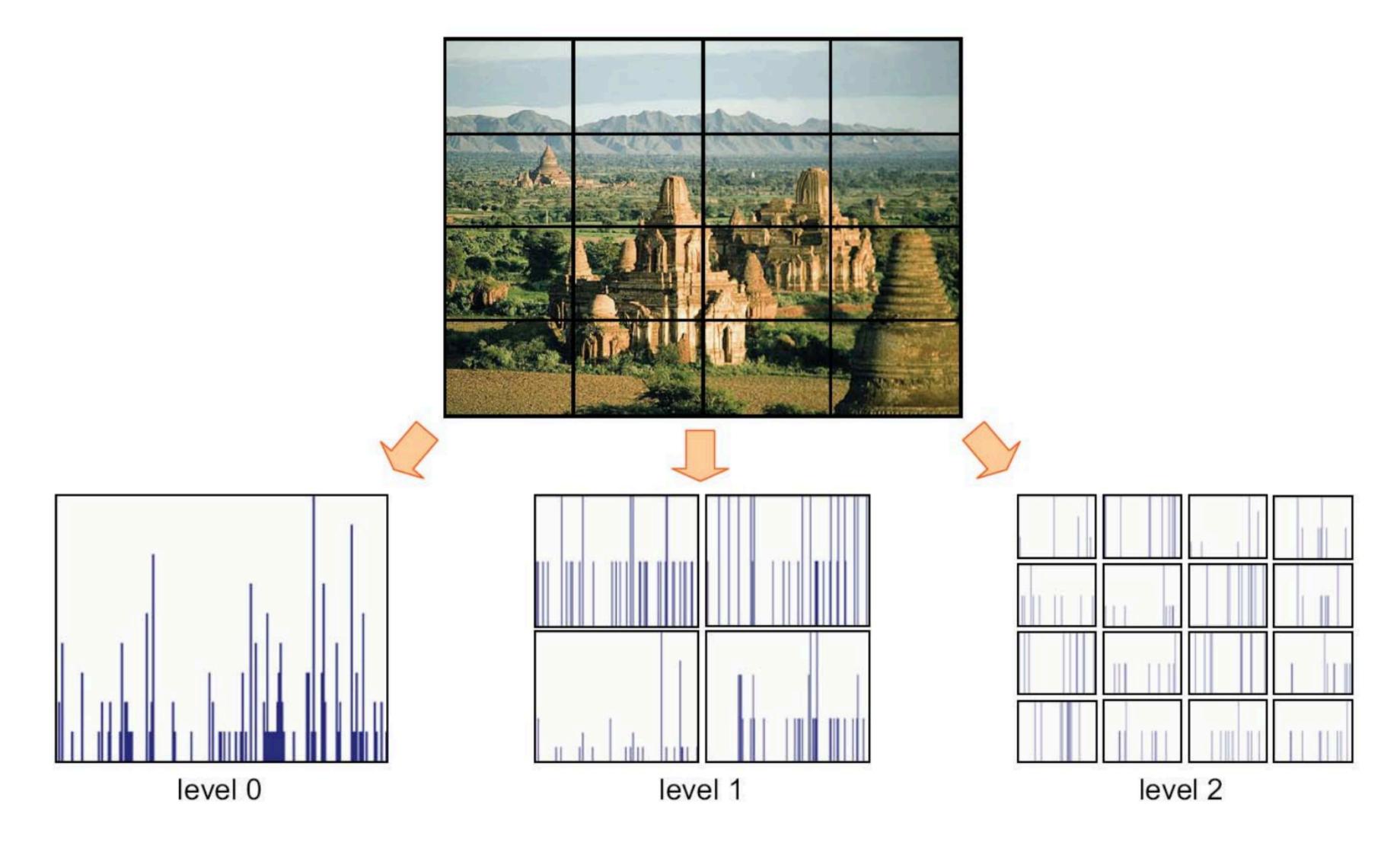






*slide credit Li Fei-Fei

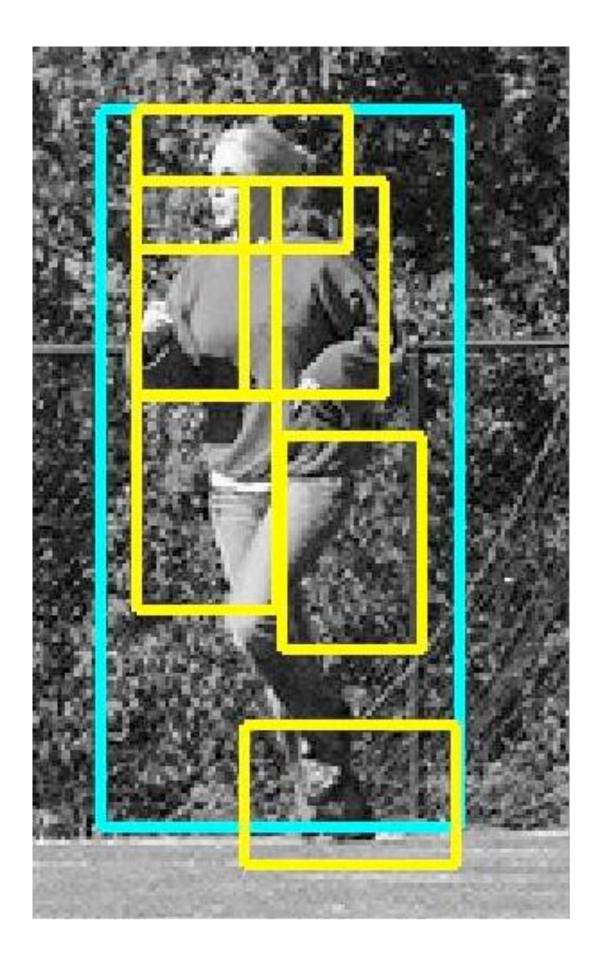
Beyond Bag of Features

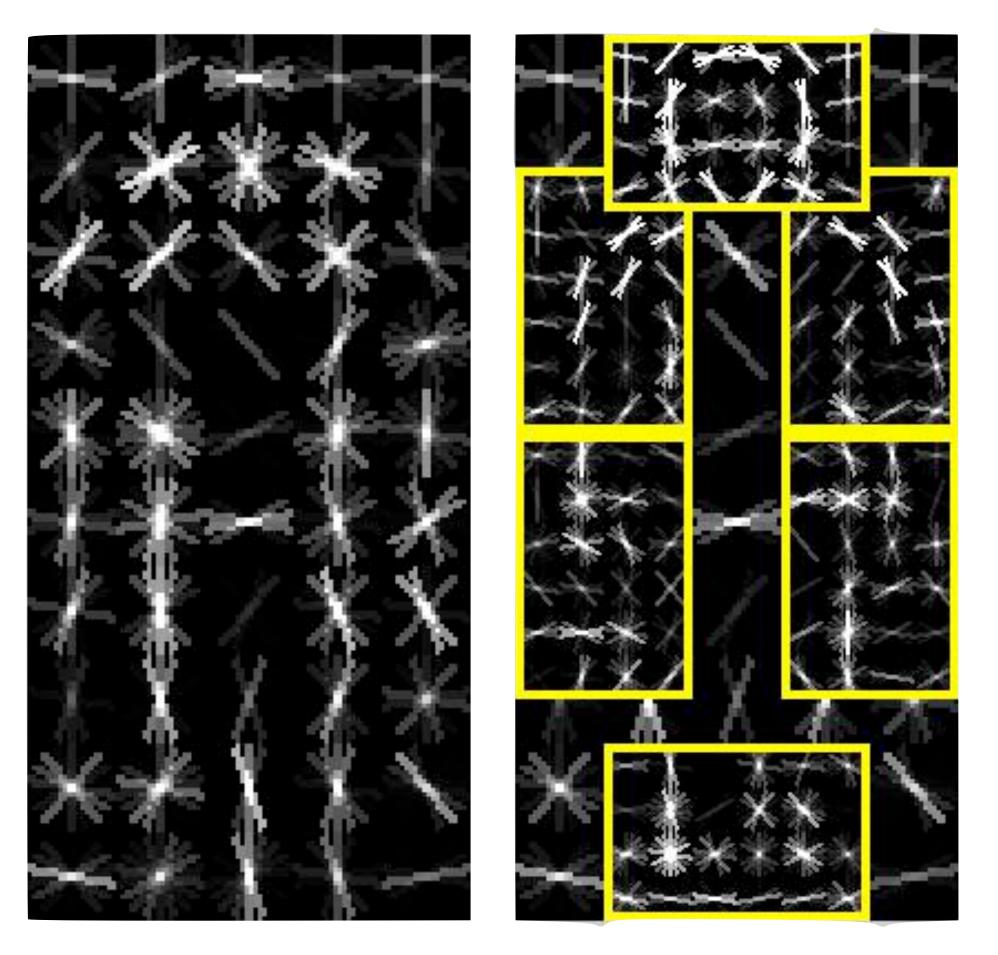


[Lazebnik, Schmid, Ponce, 2006]



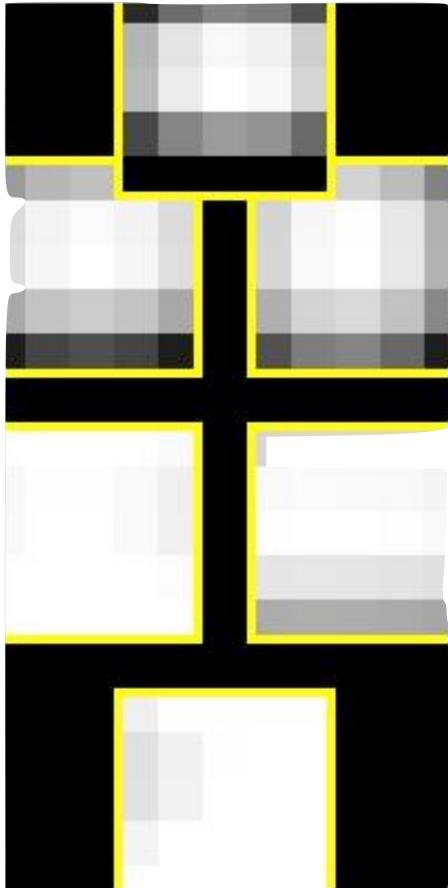
Deformable Part Models





Root Filter Part Filters

Detection



Deformations

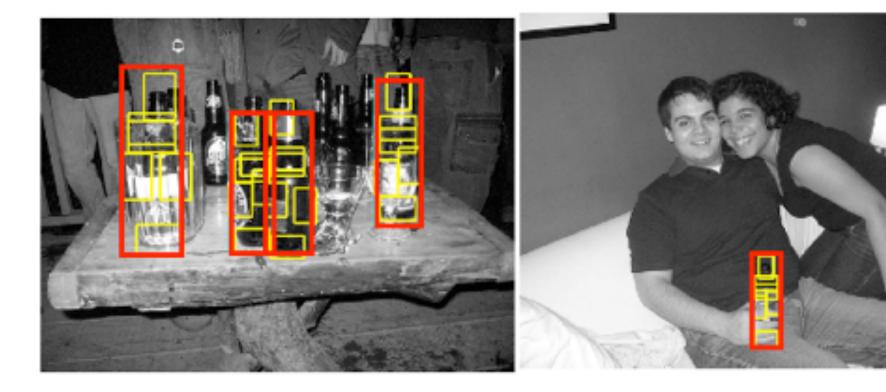
[Felzenswalb, McAllester, Ramanan, 2009]



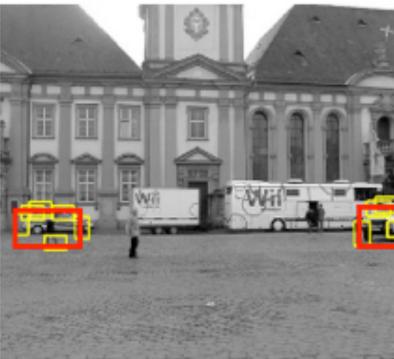
Deformable Part Models



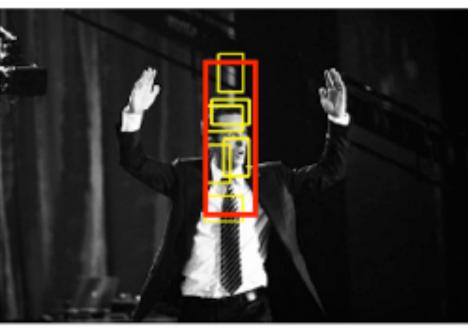


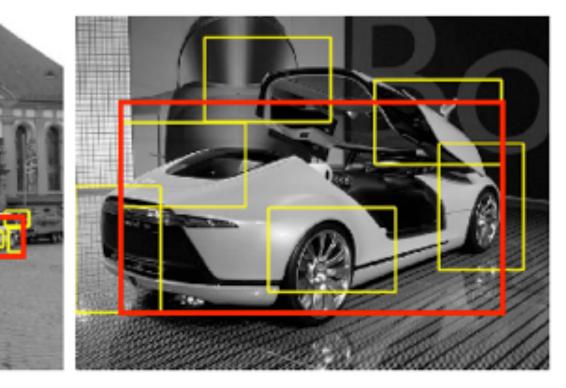


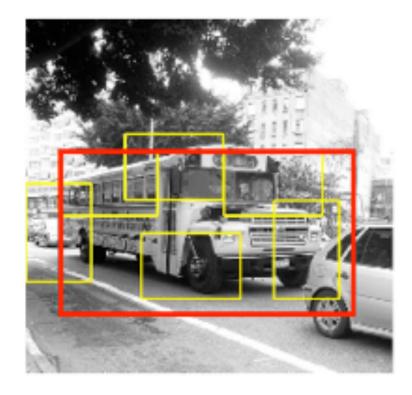








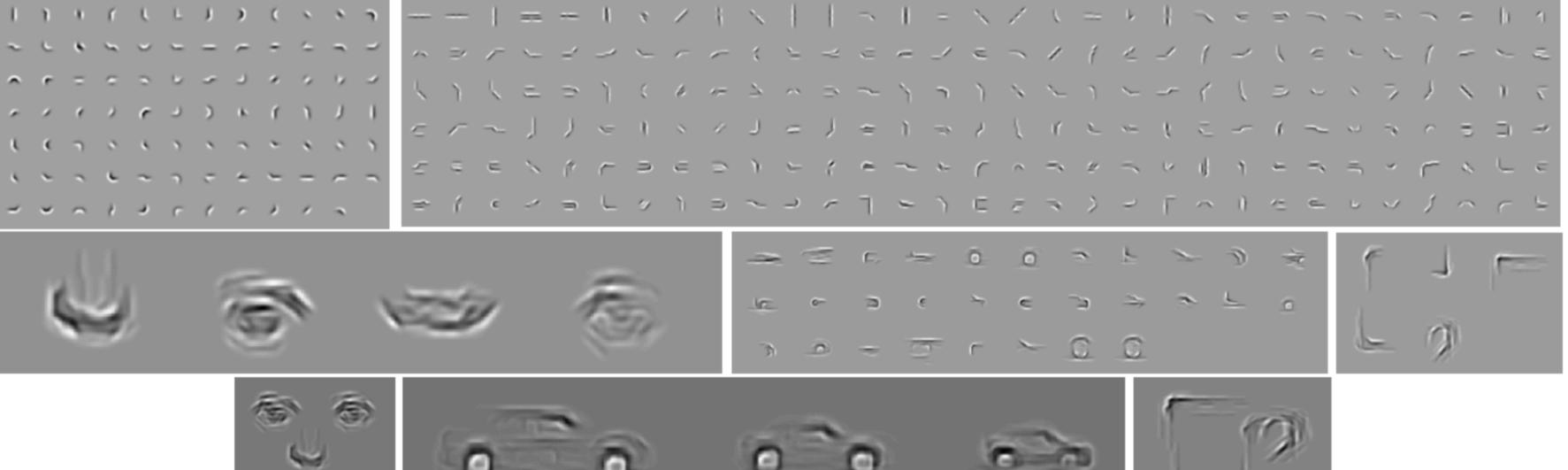




[Felzenswalb, McAllester, Ramanan, 2009]

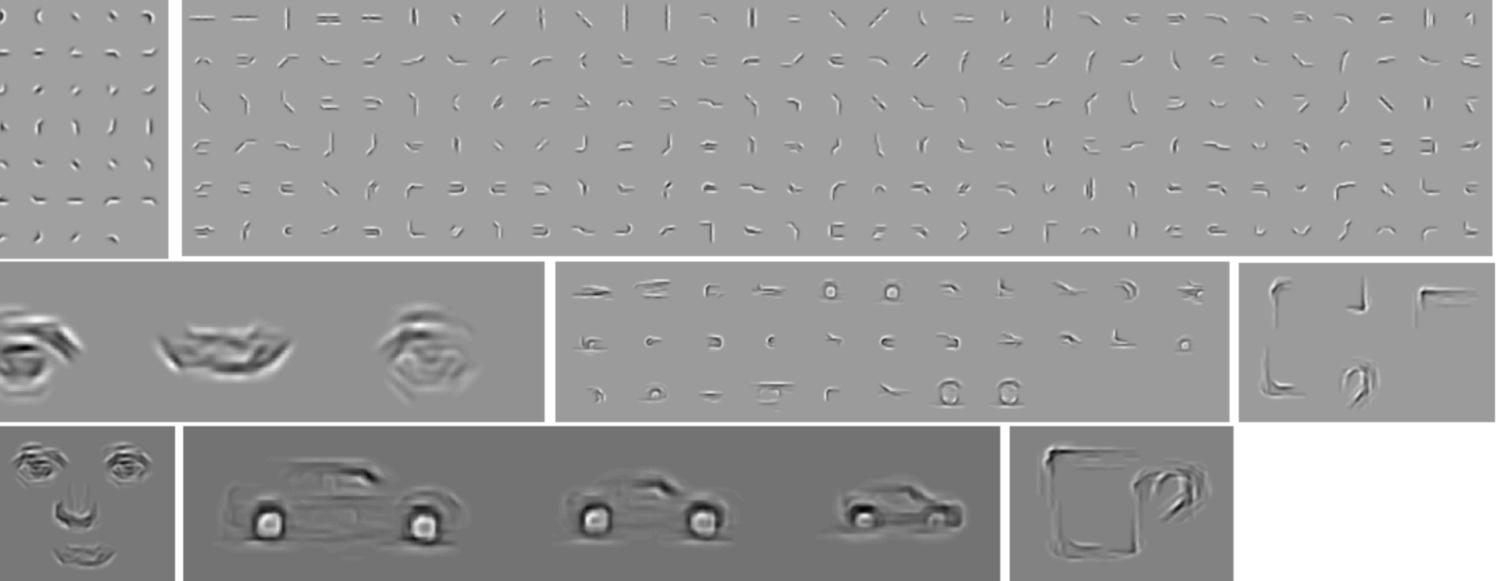


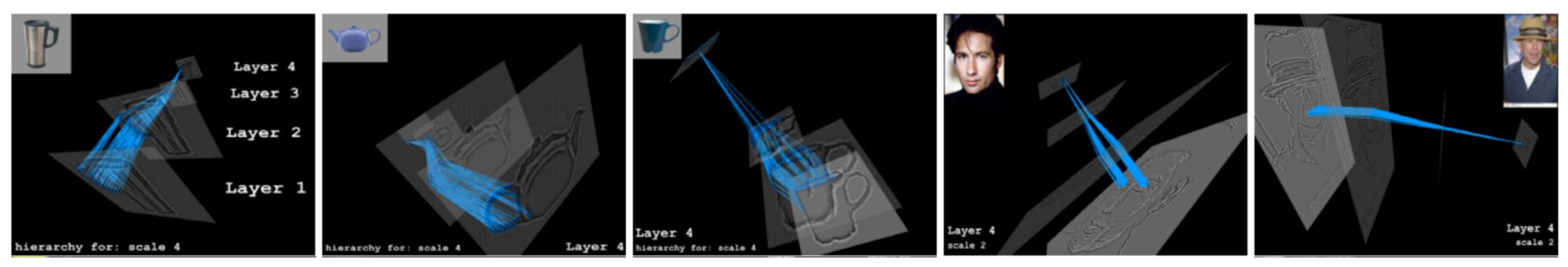
Hierarchical Models











[Fidler, Leonardis, CVPR 2007]

PASCAL Visual Object Challenge (VOC)

Image is CC BY-SA 3.0

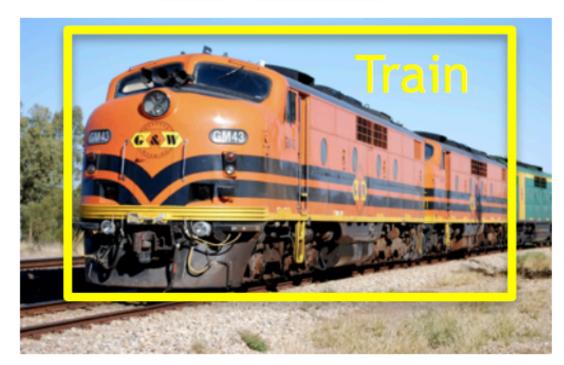
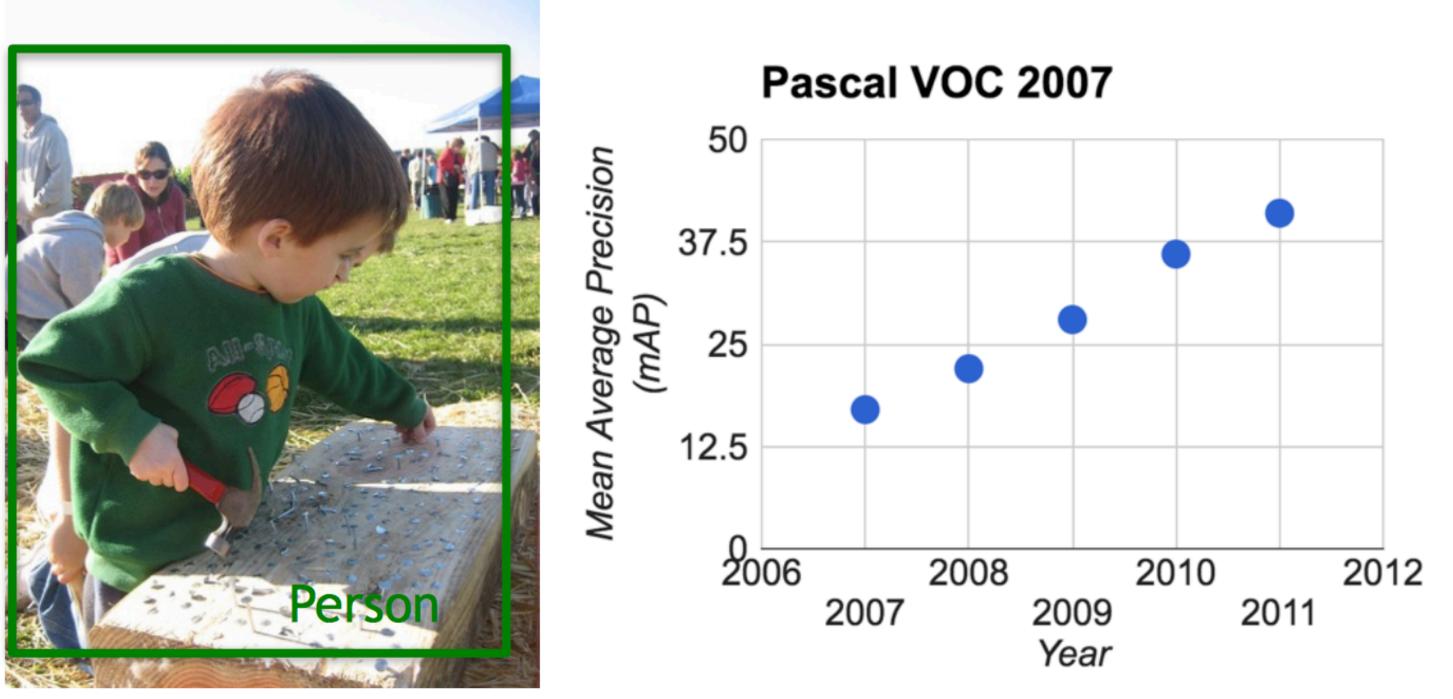




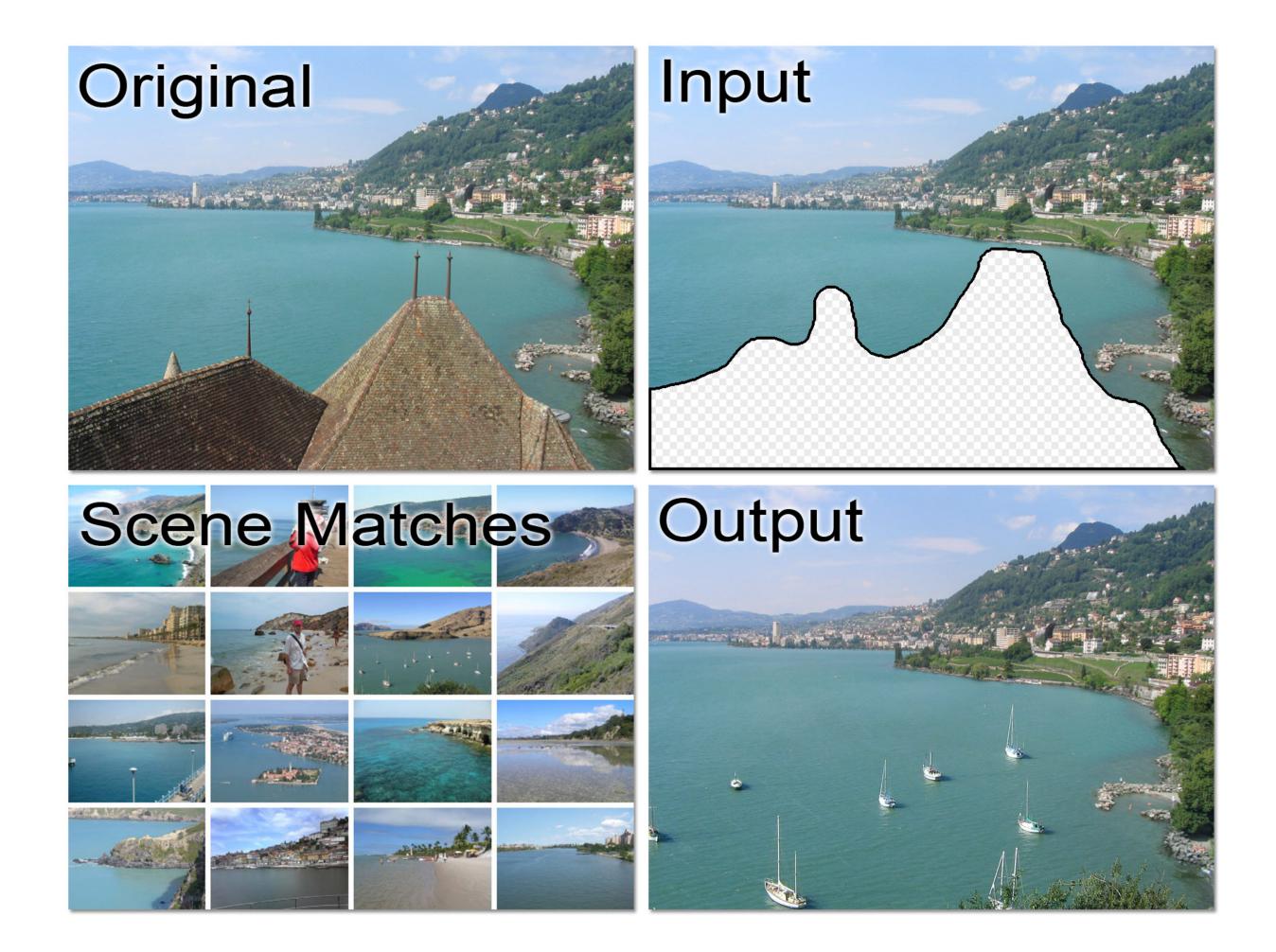
Image is CC0 1.0 public domain



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[Everingham et al. 2006-2012]

Effectiveness of **Data**



[Hays, Efros, ACM Siggraph 2007]



[Hays, Efros, CVPR 2008]

ImageNet Bechmark

IM GENET

22K categories and **14M** images

- - Invertebrate
 Materials
 Structures

- - Tree
 Artifact
 Scenes
- Fish Flower Tools Indoor



www.image-net.org

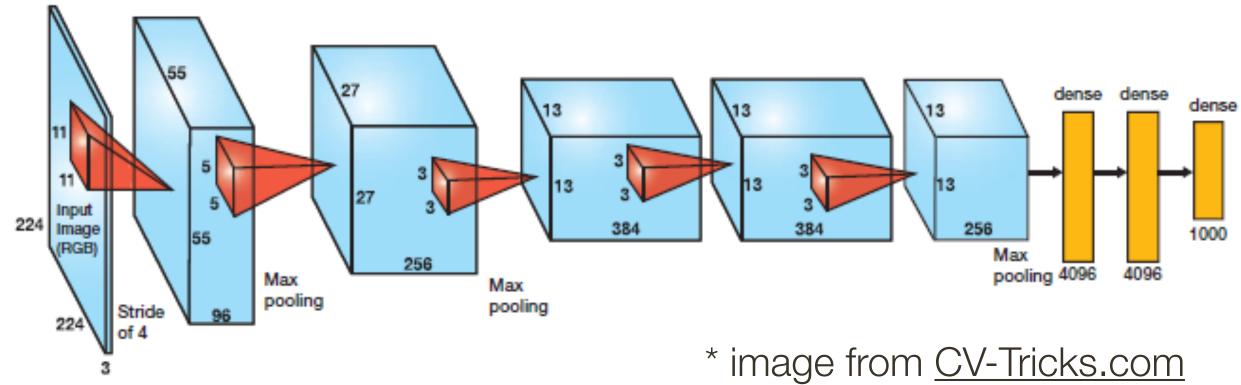
Animals• Plants• Structures• Person• Bird• Tree• Artifact• Scenes

- Mammal Food Appliances Geological Formations

 - Sport Activities

Deng, Dong, Socher, Li, Li, & Fei-Fei, 2009

AlexNet on ImageNet



ImageNet Classification with Deep Convolutional Neural Networks

Alex Krizhevsky University of Toronto kriz@cs.utoronto.ca

Ilya Sutskever University of Toronto ilya@cs.utoronto.ca

Geoffrey E. Hinton University of Toronto hinton@cs.utoronto.ca

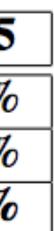
Abstract

We trained a large, deep convolutional neural network to classify the 1.2 million high-resolution images in the ImageNet LSVRC-2010 contest into the 1000 different classes. On the test data, we achieved top-1 and top-5 error rates of 37.5% and 17.0% which is considerably better than the previous state-of-the-art. The neural network, which has 60 million parameters and 650,000 neurons, consists of five convolutional layers, some of which are followed by max-pooling layers, and three fully-connected layers with a final 1000-way softmax. To make training faster, we used non-saturating neurons and a very efficient GPU implementation of the convolution operation. To reduce overfitting in the fully-connected layers we employed a recently-developed regularization method called "dropout" that proved to be very effective. We also entered a variant of this model in the ILSVRC-2012 competition and achieved a winning top-5 test error rate of 15.3%, compared to 26.2% achieved by the second-best entry.

Model	Top-1	Top-5
Sparse coding [2]	47.1%	28.2%
SIFT + FVs [24]	45.7%	25.7%
CNN	37.5%	17.0%

Model	Top-1 (val)	Top-5 (val)	Top-5 (test)
SIFT + FVs [7]			26.2%
1 CNN	40.7%	18.2%	
5 CNNs	38.1%	16.4%	16.4%
1 CNN*	39.0%	16.6%	
7 CNNs*	36.7%	15.4%	15.3%

[Krizhevsky, Sutskever, Hinton, NIPS 2012]

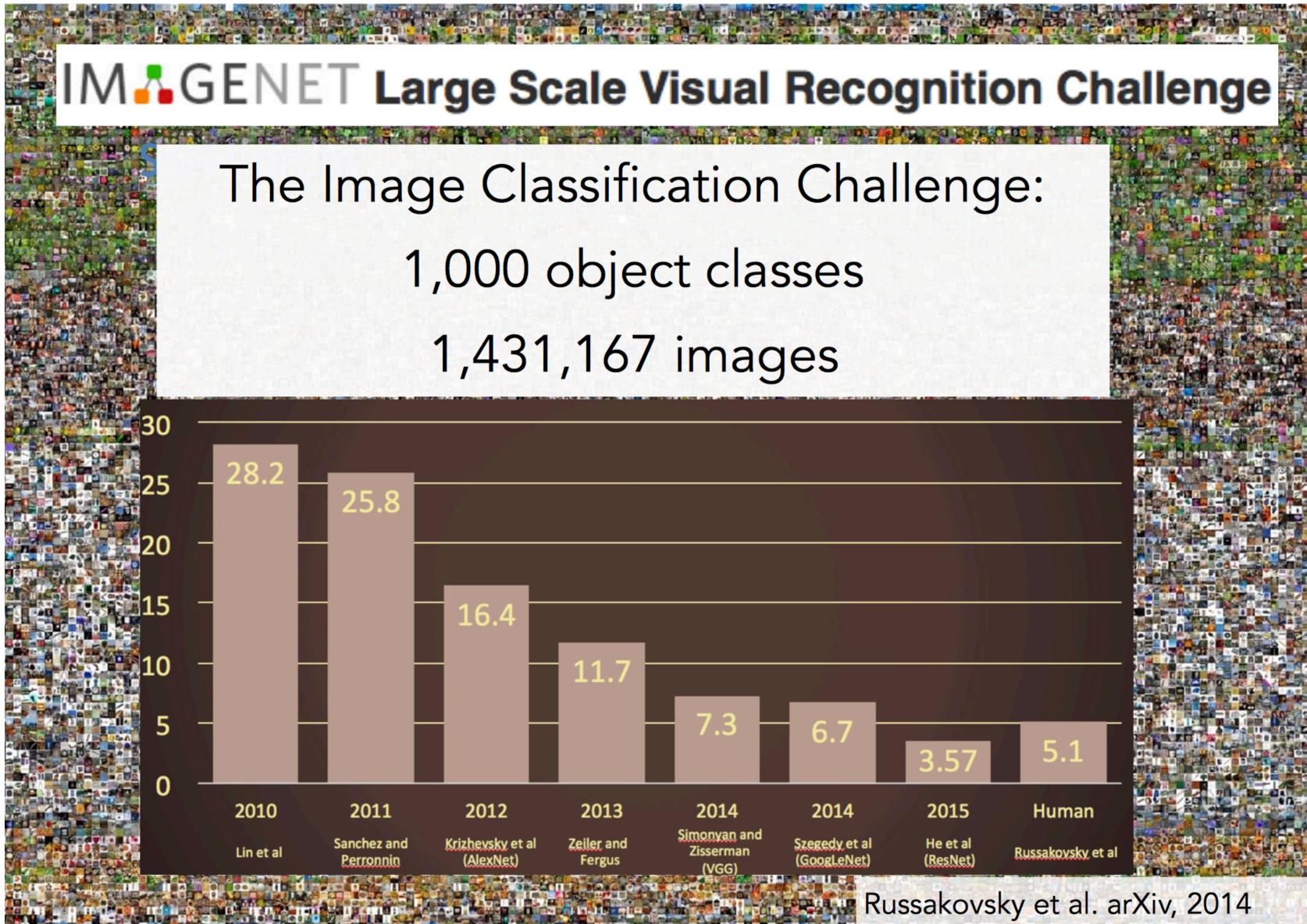








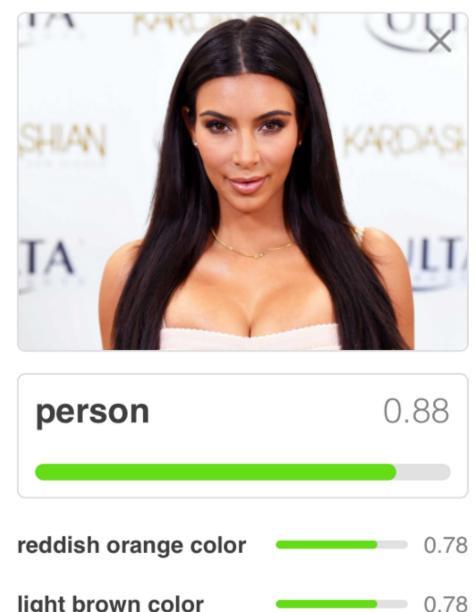
Success of **Deep Learning**



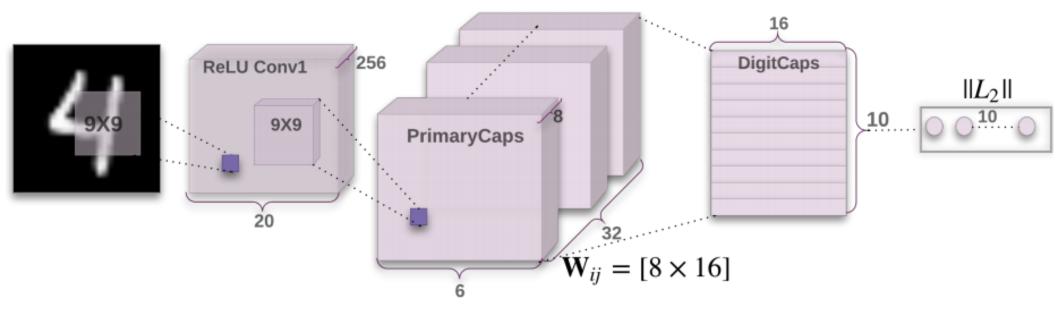
Final thought ...

- Model based, compositional, primitives, inverse graphics
- Hand-crafted features for given invariances & matching
- Hand-crafted features with learned statistical models on top
- Joint learning of features and statistical models for recognition

CapsuleNET Going back to inverse graphics



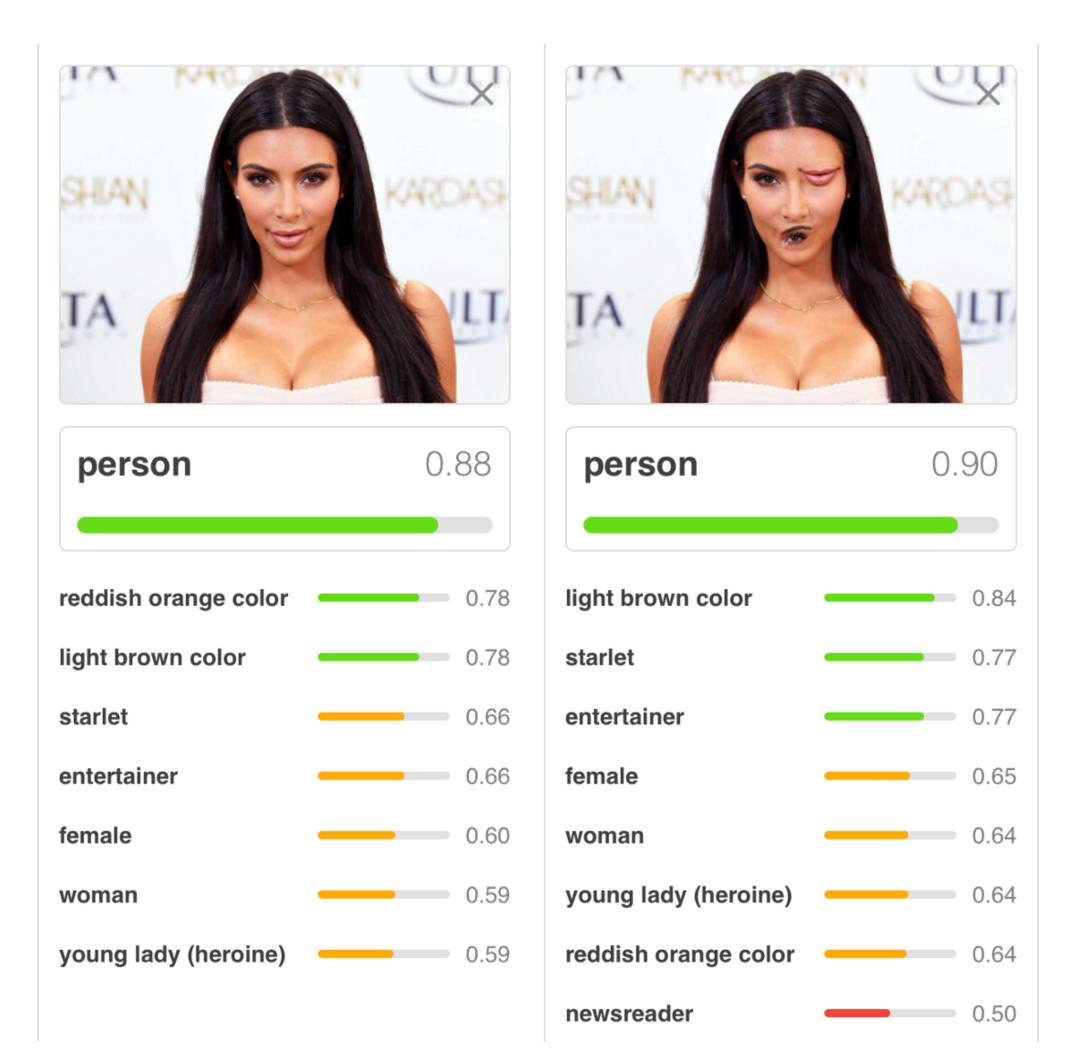
light brown color	0.78
starlet	0.66
entertainer	0.66
female	0.60
woman	0.59
young lady (heroine)	0.59

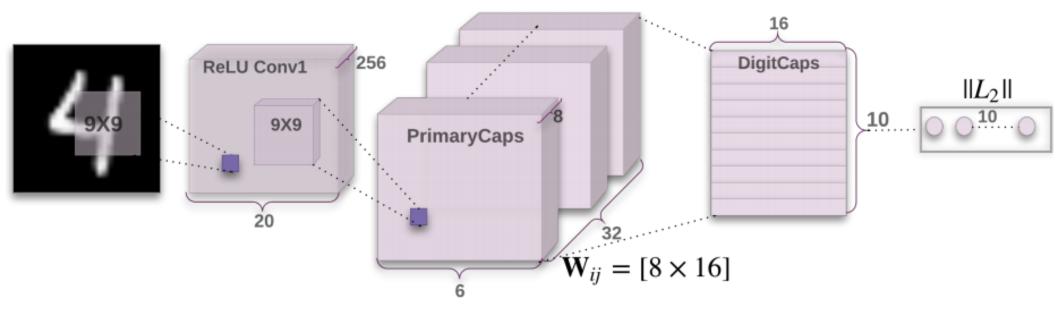


[Sabour, Frosst, Hinton, NIPS 2017]

*image credit medium.com

CapsuleNET Going **back to inverse** graphics

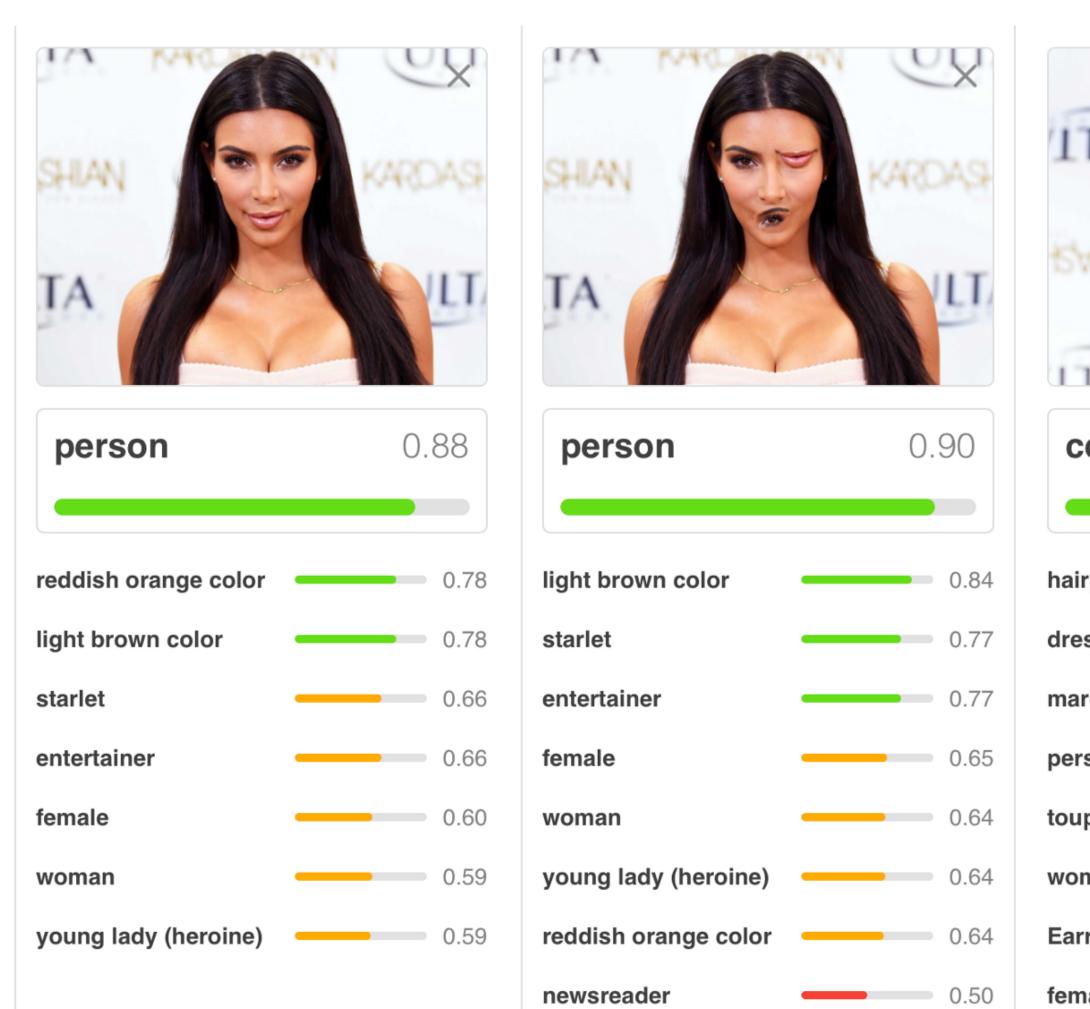


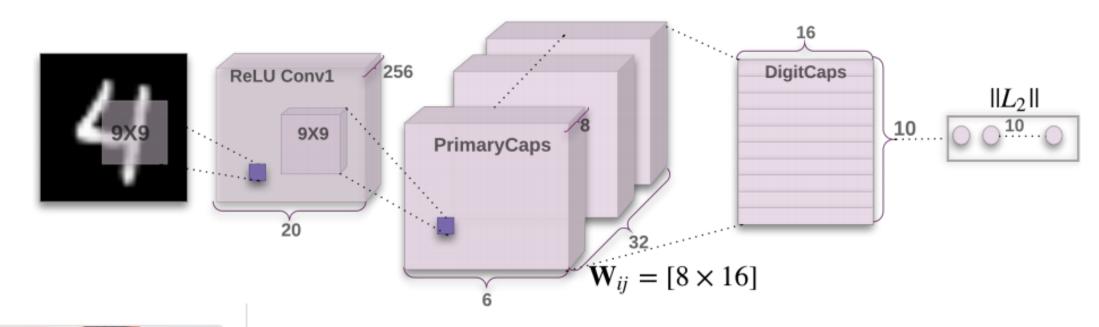


[Sabour, Frosst, Hinton, NIPS 2017]

*image credit <u>medium.com</u>

CapsuleNET Going back to inverse graphics





\times VI **Wills KVCDV**2 110 V/I

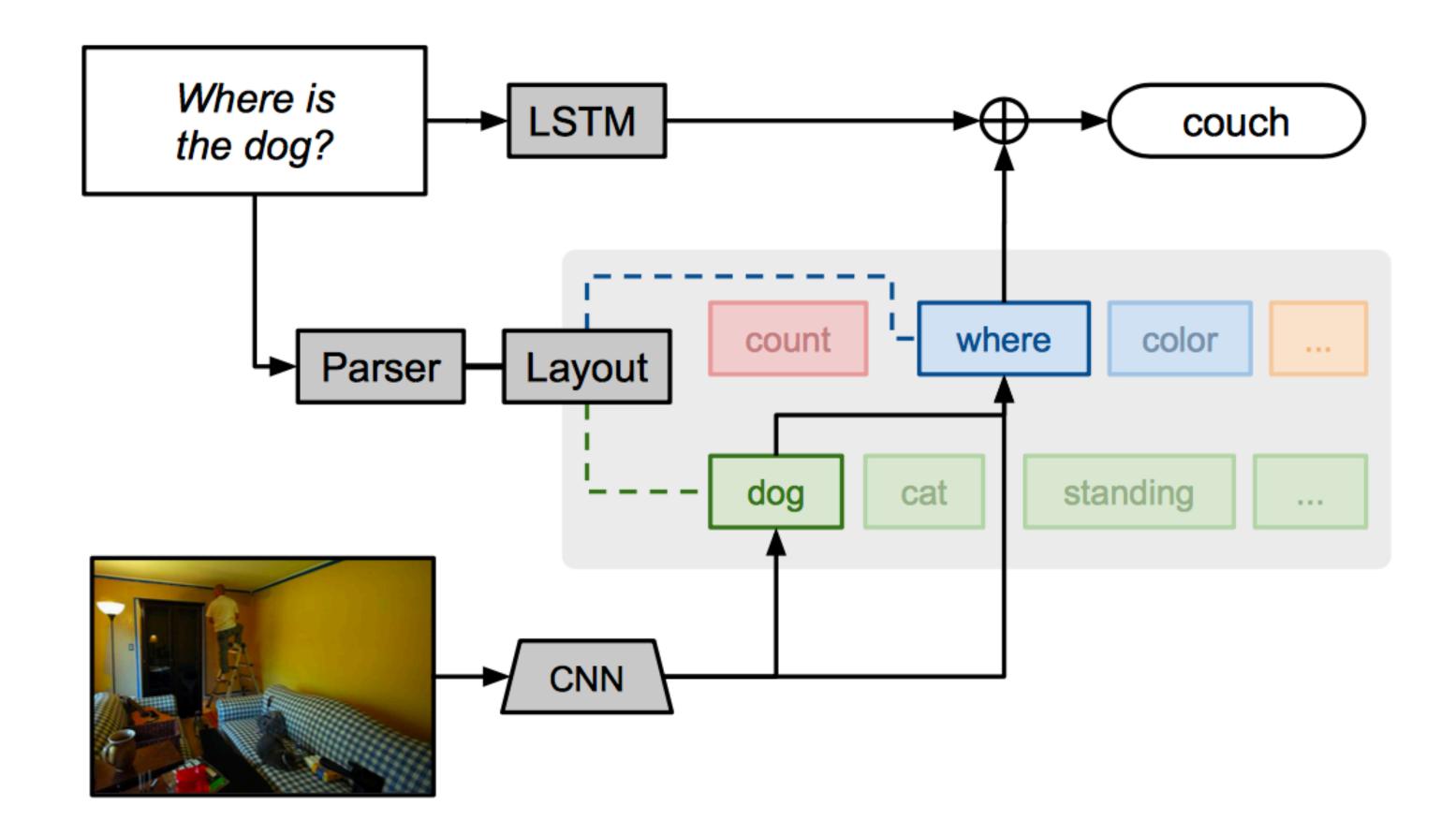
oal black color		0.79	
irpiece (hair)			0.71
ess			0.71
roon color			0.71
rson			0.58
ipee (hairpiece)			0.58
man			0.56
rrings	_		0.55
nale			0.50

[Sabour, Frosst, Hinton, NIPS 2017]

*image credit <u>medium.com</u>



Neural Modular Networks



[Andreas, Rohrbach, Darrell, Klein, CVPR 2016]

