



CPSC 425: Computer Vision

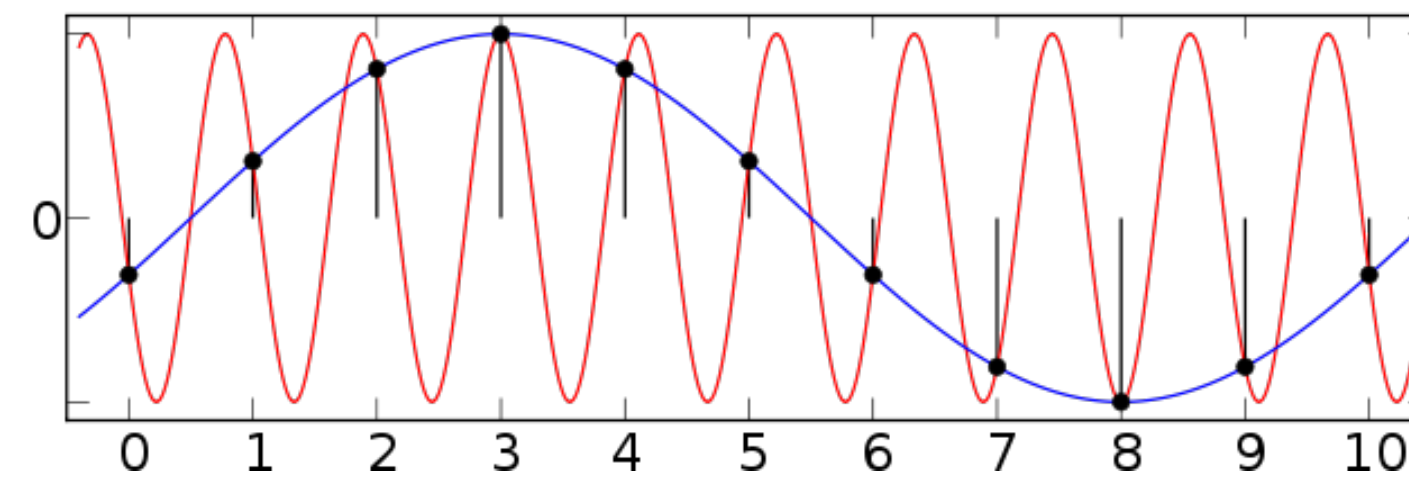


Image Credit: https://en.wikibooks.org/wiki/Analog_and_Digital_Conversion/Nyquist_Sampling_Rate

Lecture 6: Sampling

(unless otherwise stated slides are taken or adopted from **Bob Woodham**, **Jim Little** and **Fred Tung**)

Menu for Today

Topics:

- **Sampling** theory
- **Nyquist** rate
- Color **Filter Arrays**
- **Image** encoding

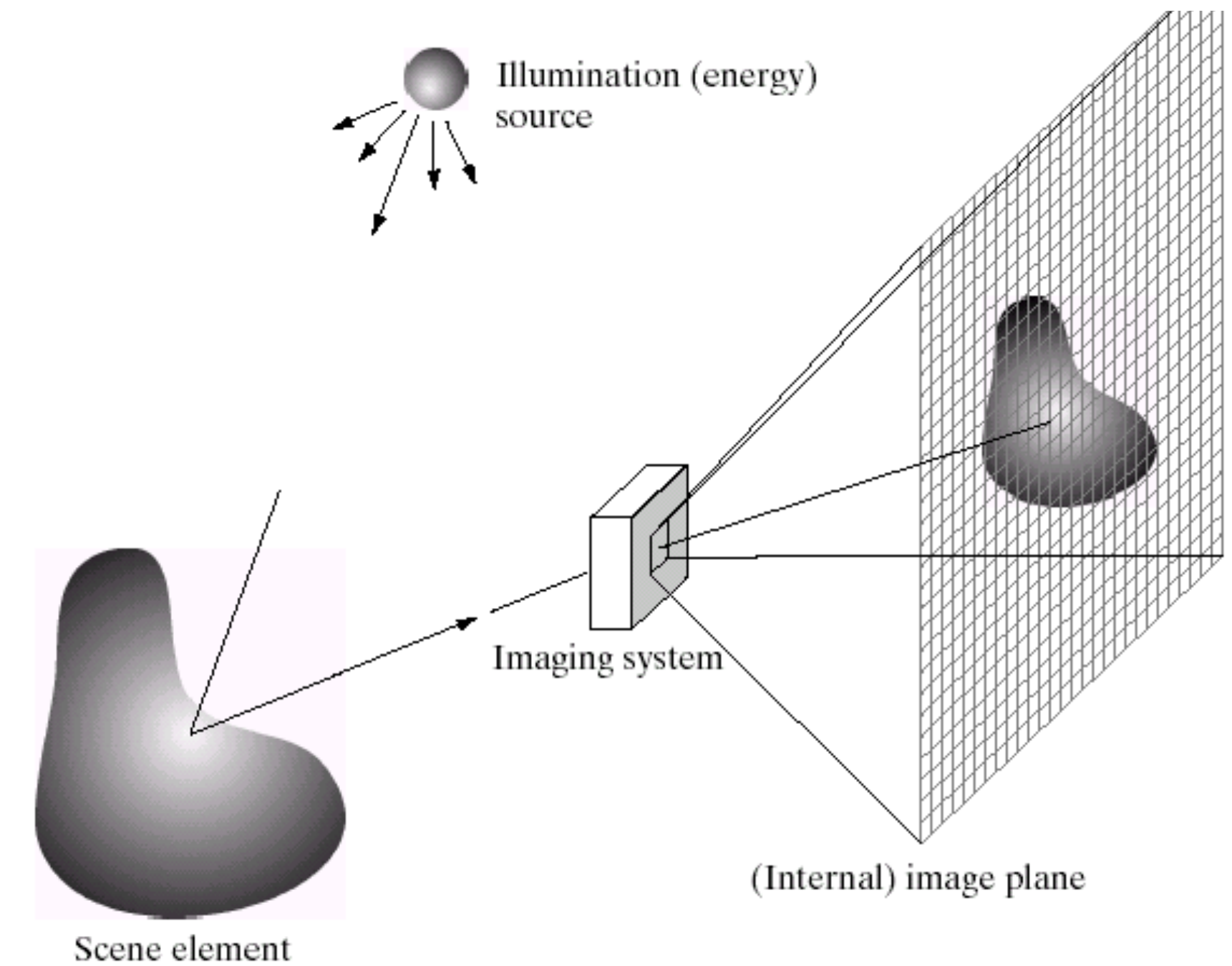
Readings:

- **Today's** Lecture: Szeliski 2.3, Forsyth & Ponce (2nd ed.) 4.5, 4.6

Reminders:

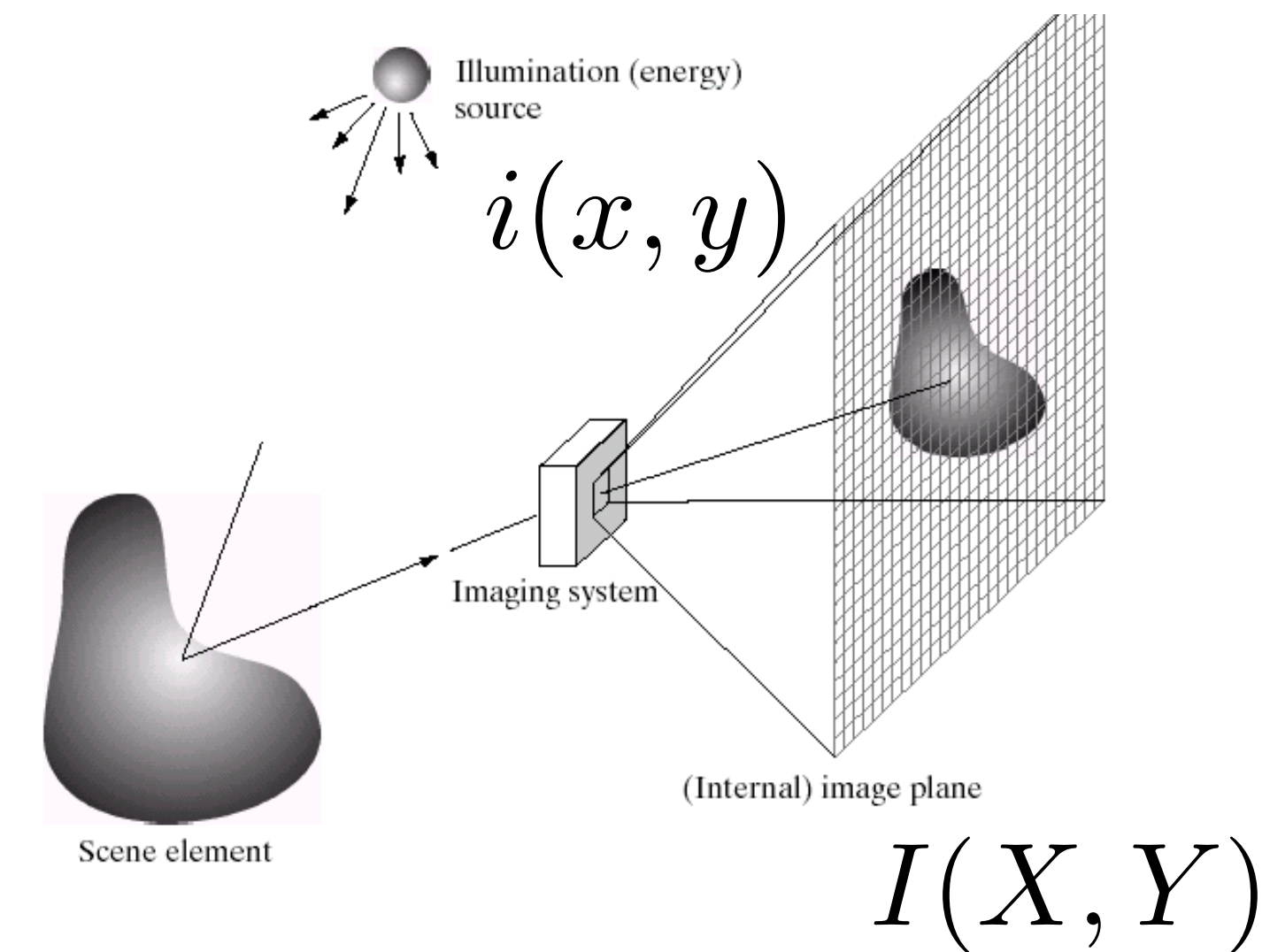
- **Assignment 1:** Image Filtering and Hybrid Images due **December 30th**

Reminder



Images are a **discrete**, or **sampled**, representation of a continuous world

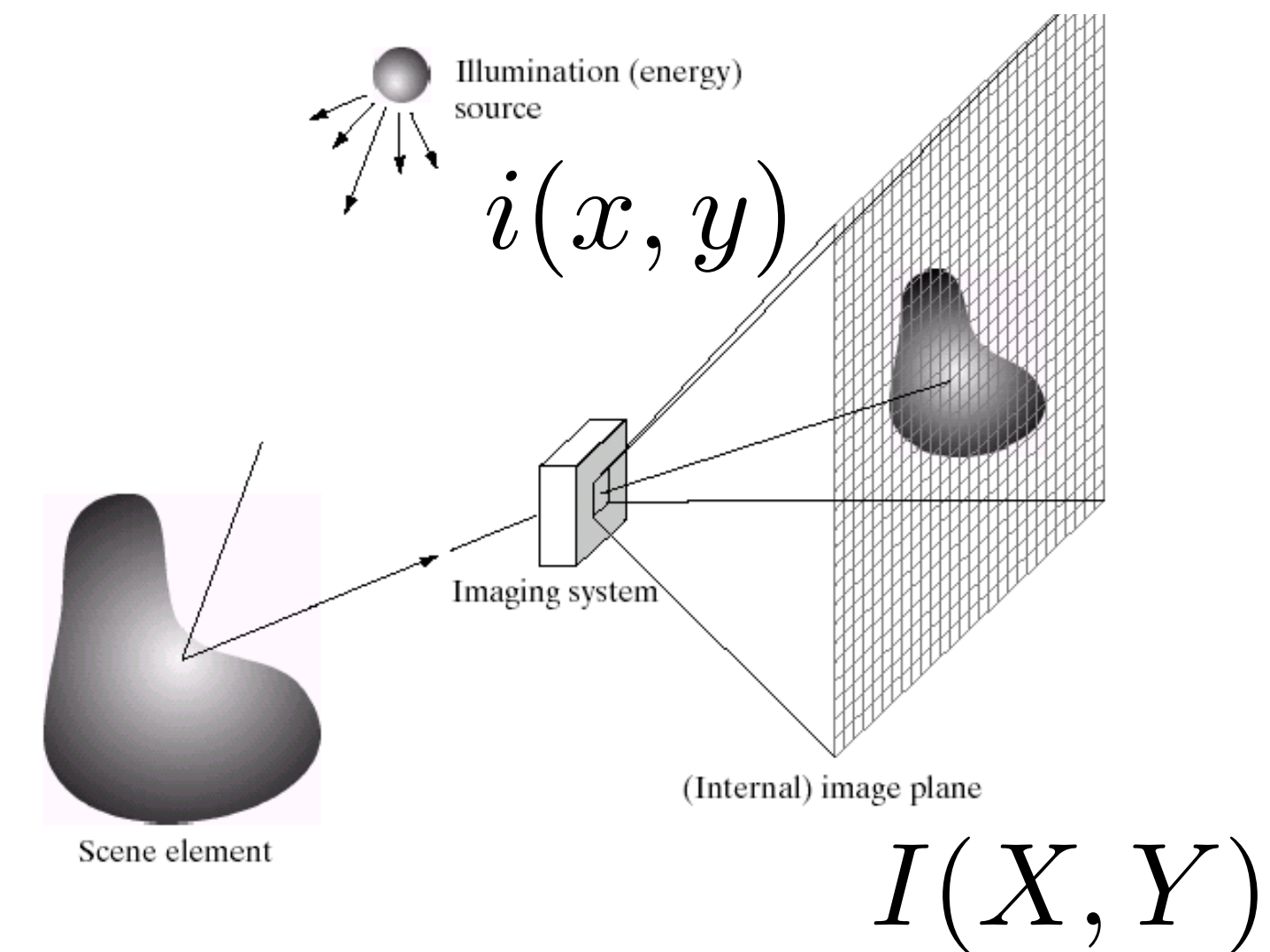
What is **Sampling**?



A **continuous function** $i(x, y, \lambda)$ is presented at the image sensor at each time instant

How do we convert this to a **digital signal** (array of numbers) $I(x, y, \lambda)$?

What is **Sampling**?



A **continuous function** $i(x, y, \lambda)$ is presented at the image sensor at each time instant

How do we convert this to a **digital signal** (array of numbers) $I(x, y, \lambda)$?

How can we **manipulate**, e.g., resample, this digital signal correctly?

Resampling Images

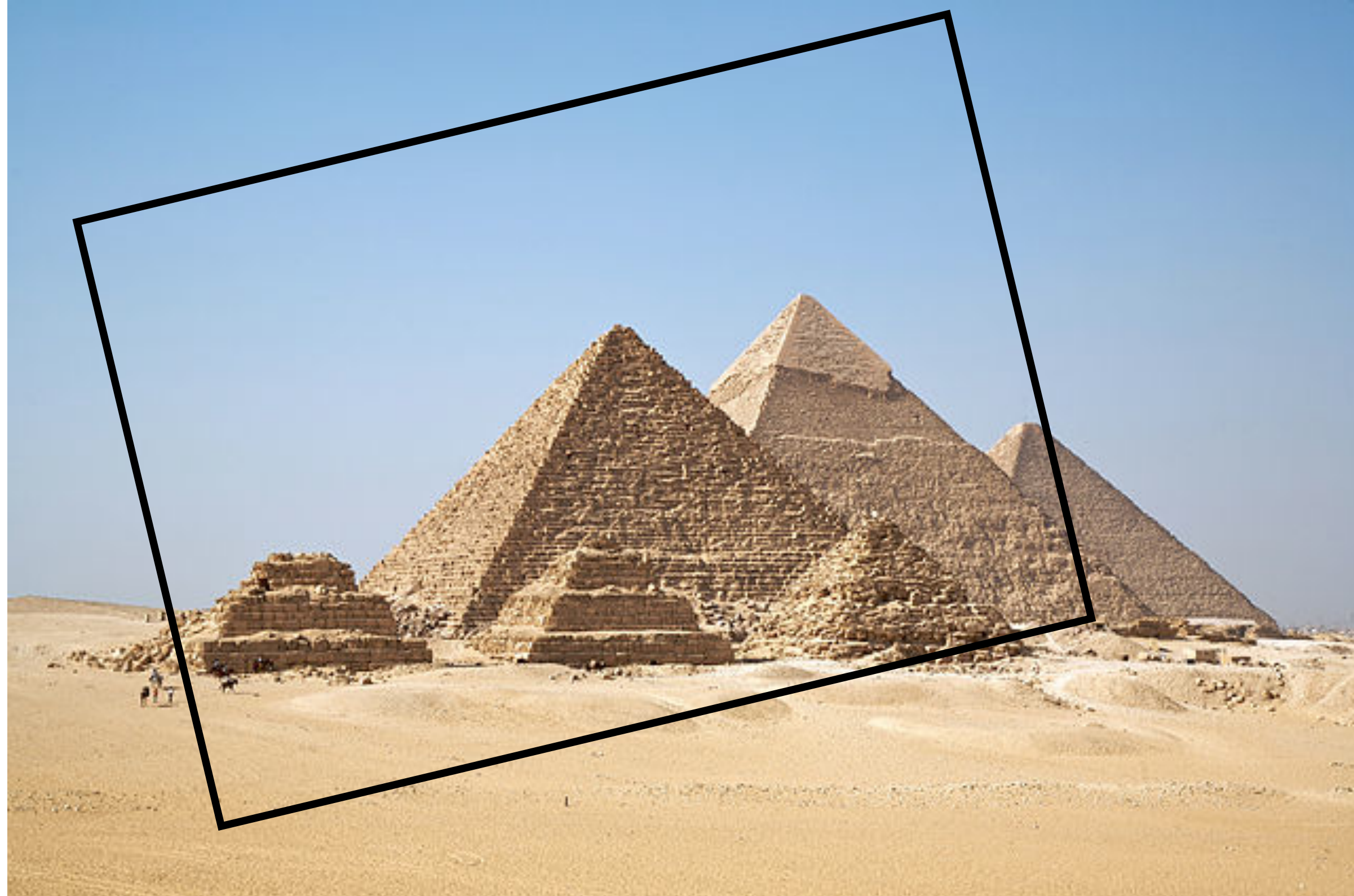
width



height

Resampling Images

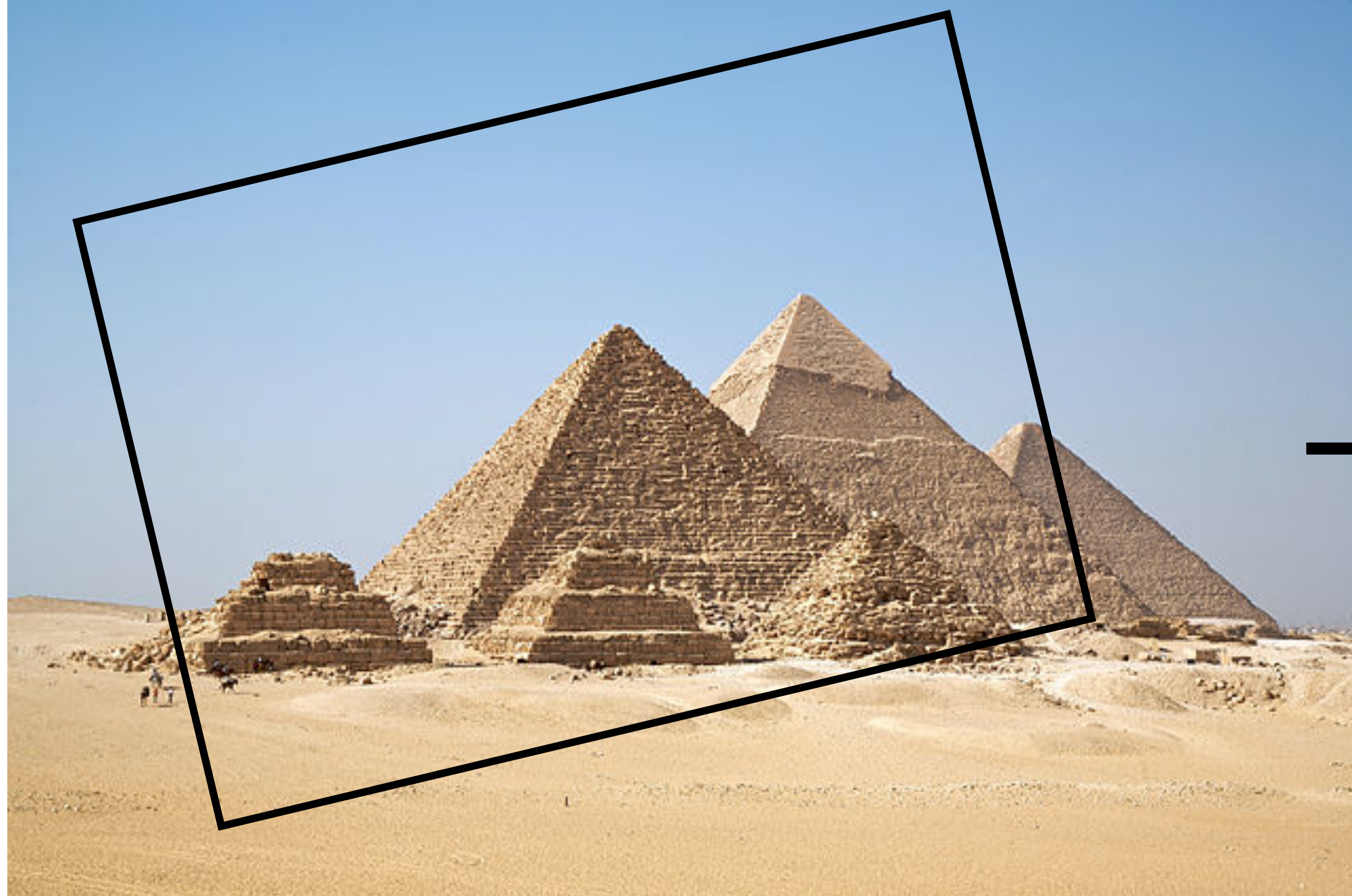
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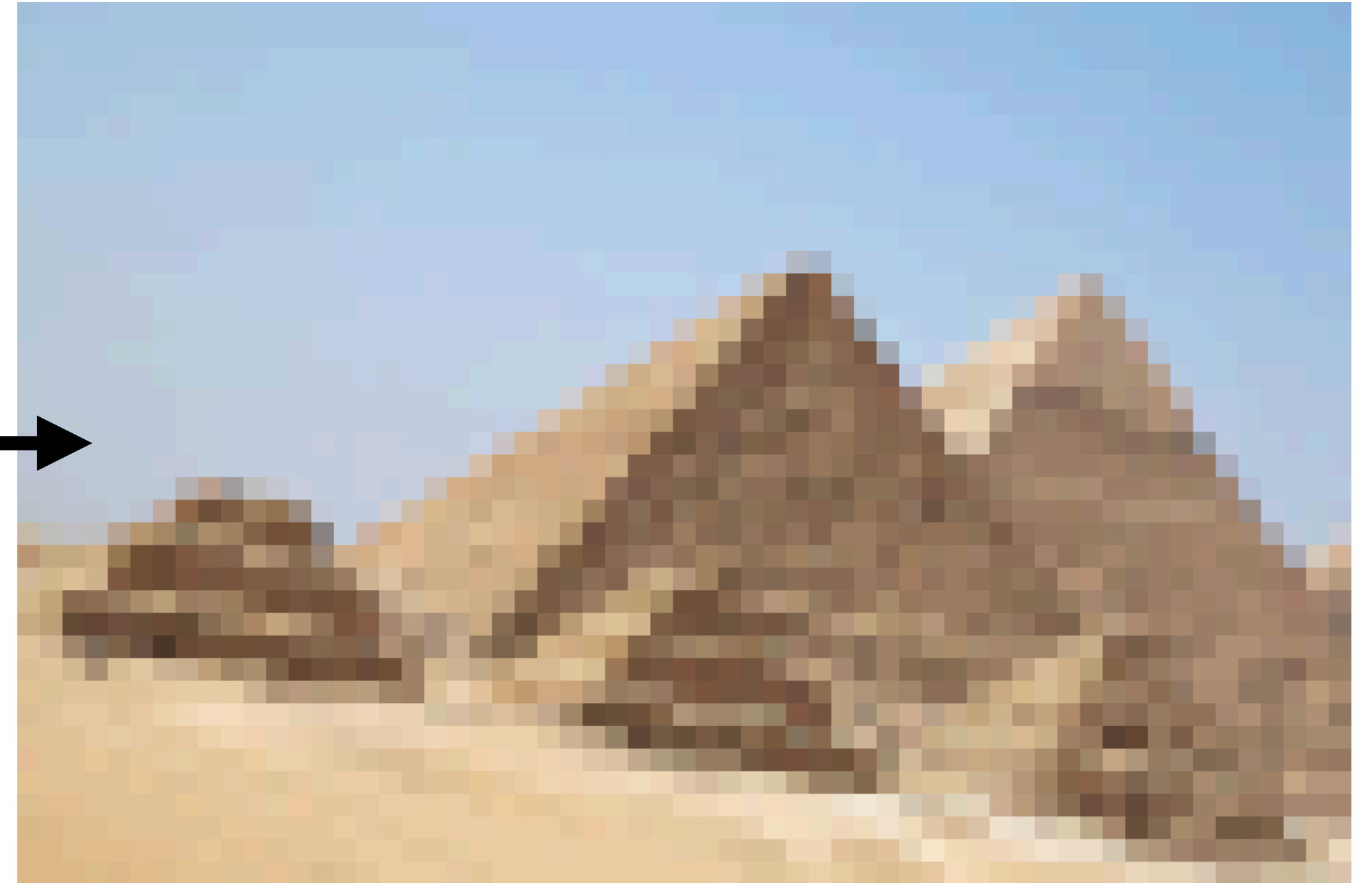
height

Resampling Images

width



10

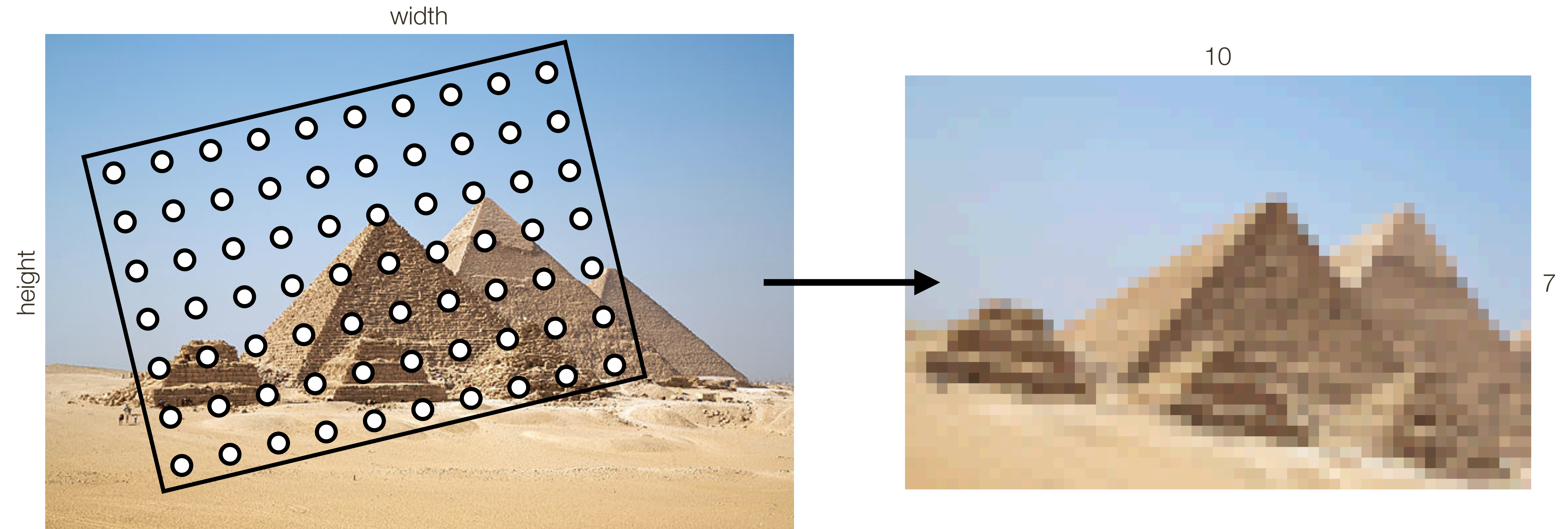


7

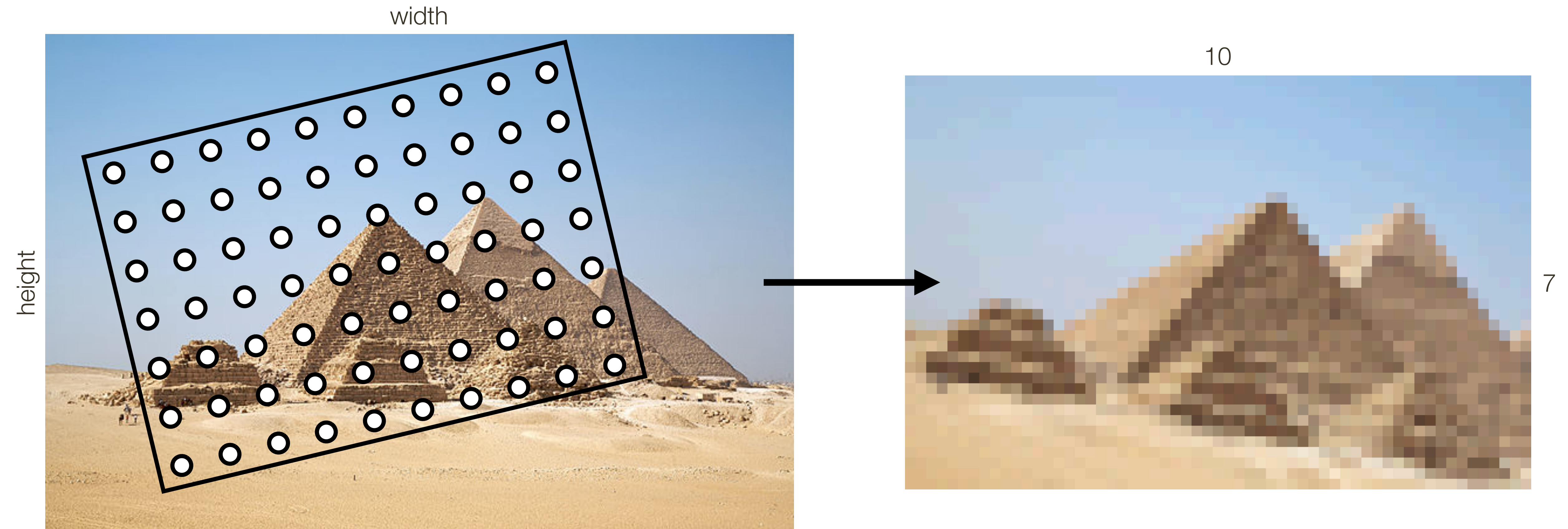


height

Resampling Images



Resampling Images



How do we correctly **generate samples** to resample or warp an image?

What types of **transformations** can we do?

$I(X, Y)$



Filtering



$I'(X, Y)$



changes range of image function

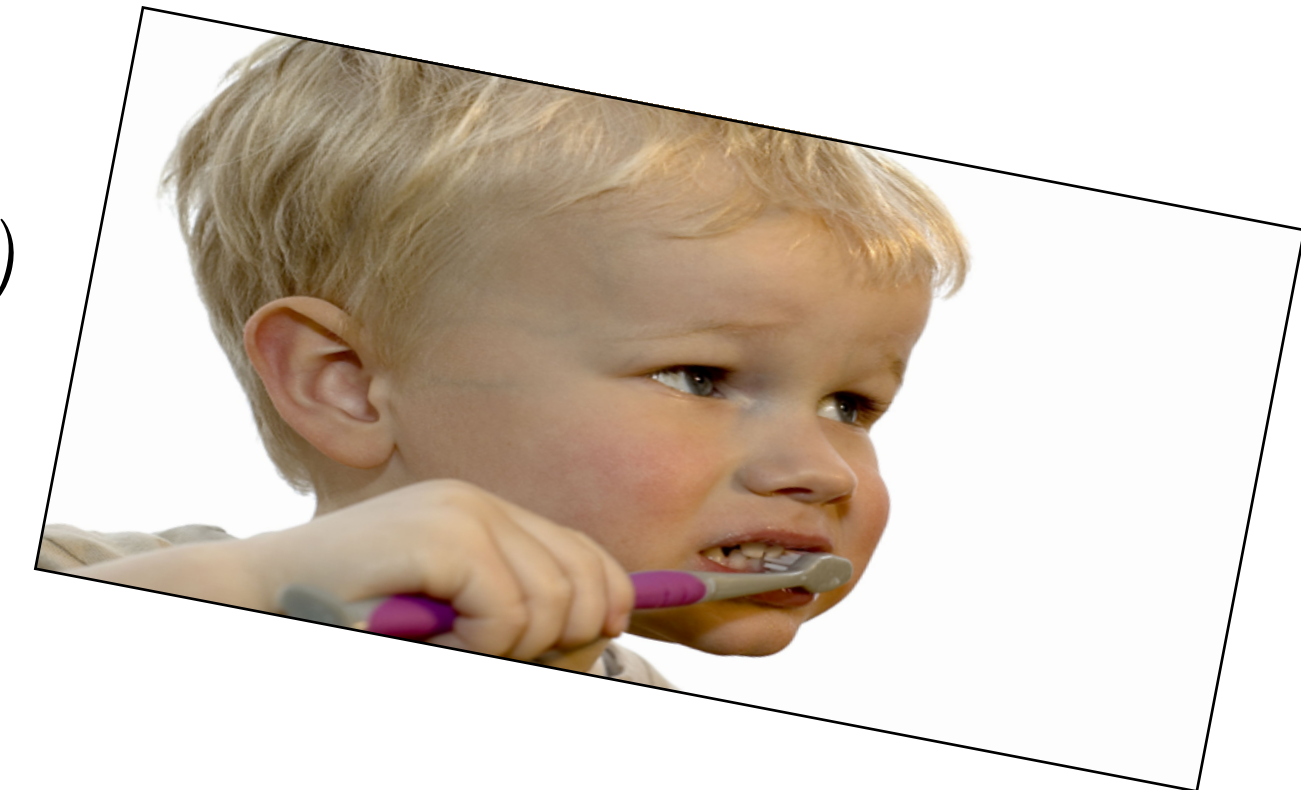
$I(X, Y)$



Warping



$I'(X, Y)$



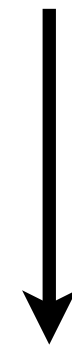
changes domain of image function

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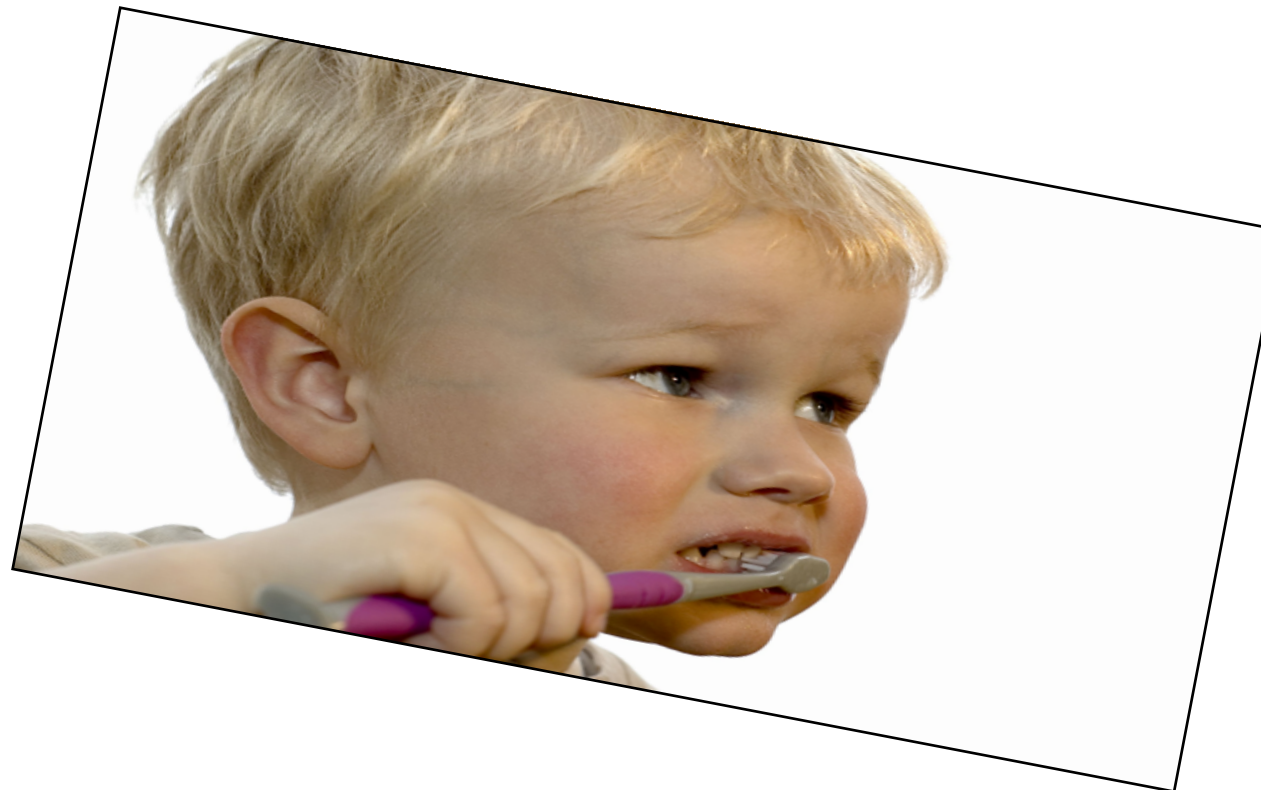
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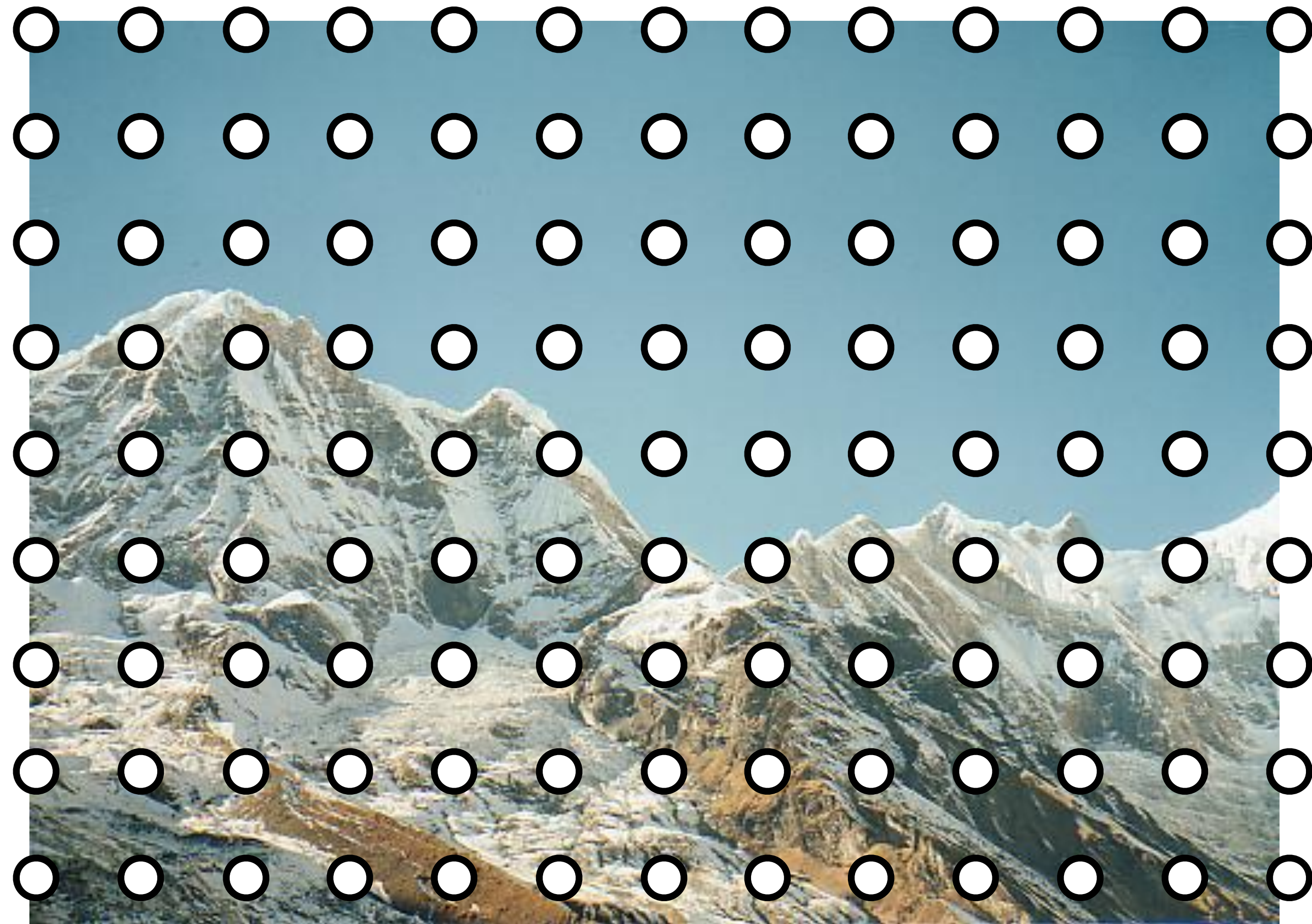
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Resampling Images

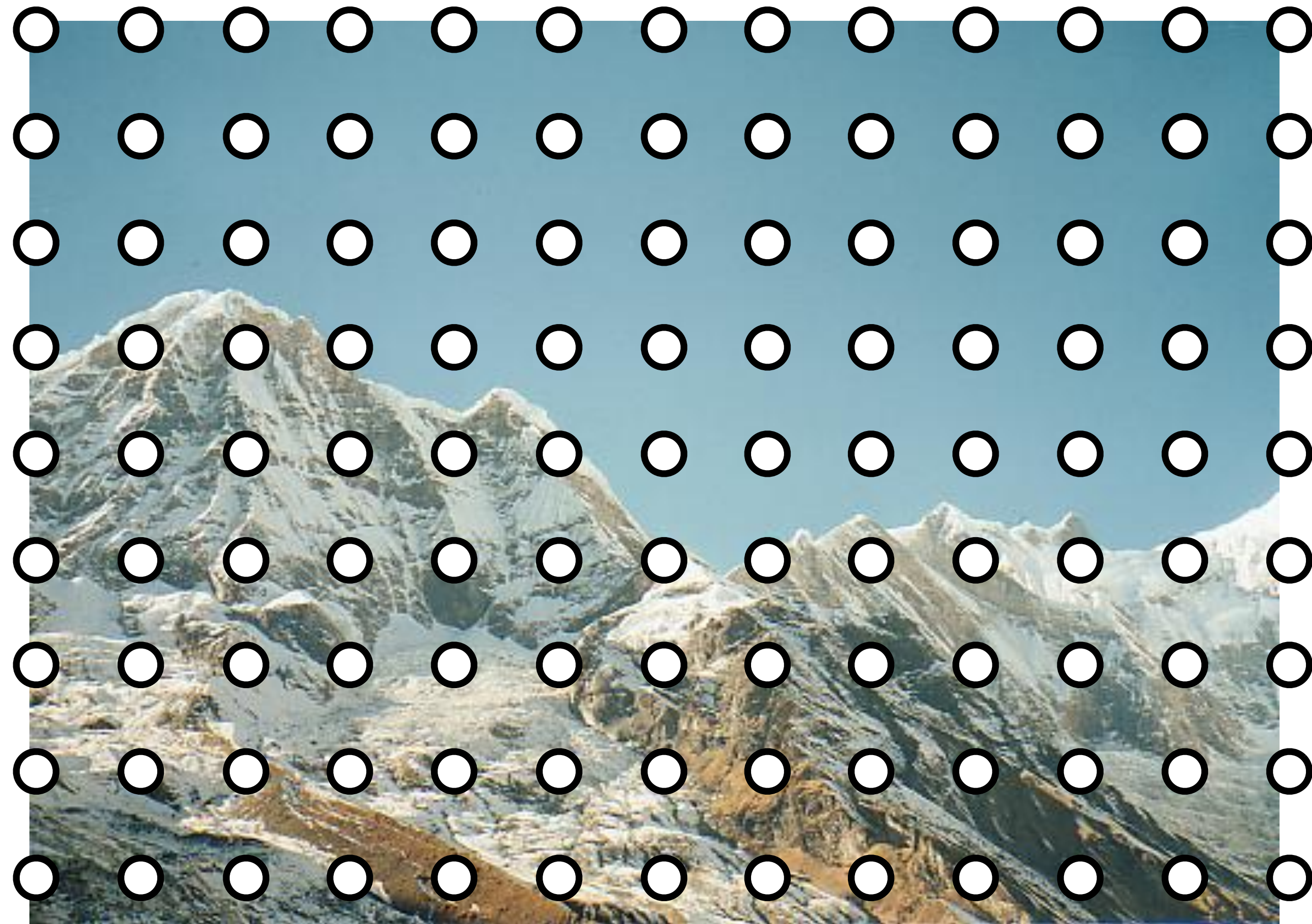
Goal: Resample the image to get a lower resolution counterpart



What is the simplest way to do this (e.g., produce image 1/5 of original size)?

Resampling Images

Goal: Resample the image to get a lower resolution counterpart



Naive Method: Form new image by taking every n -th pixel of the original image

Resampling Images

Sampling every 5-th pixel, while shifting rightwards one pixel at a time



Resampling Images

Sampling every 5-th pixel, while shifting rightwards one pixel at a time



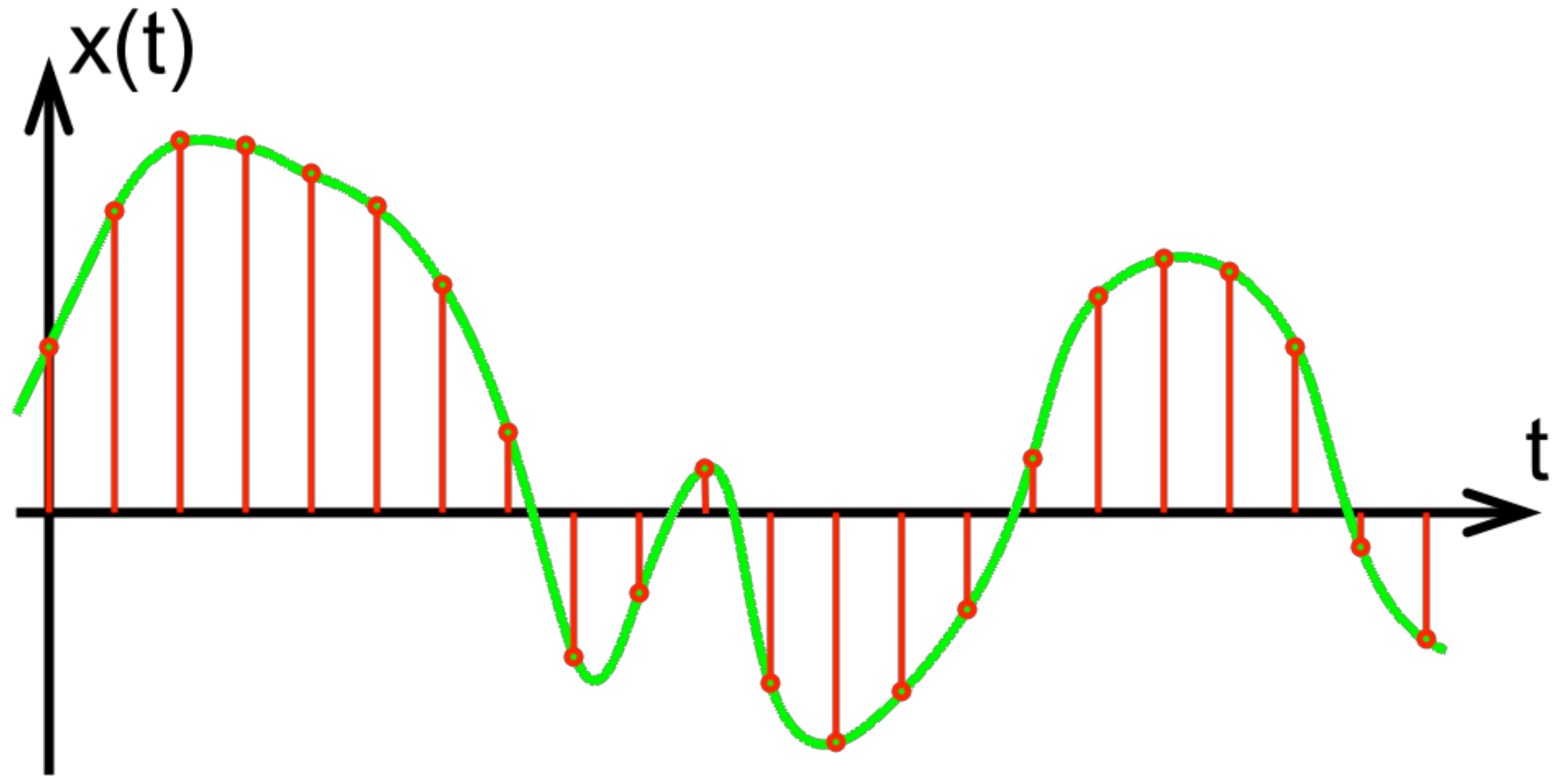
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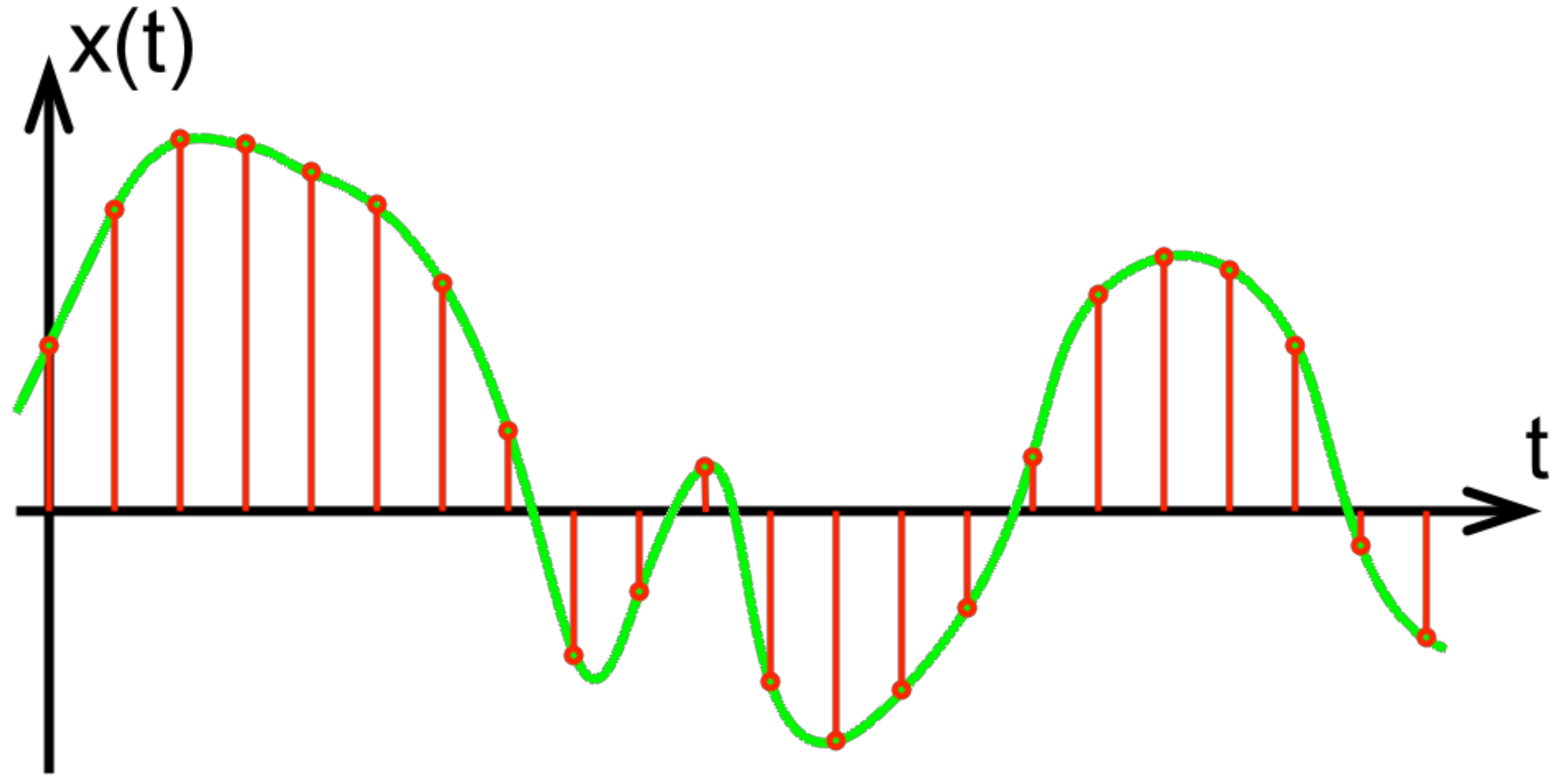
What's wrong with this method?

Example: Audio Sampling



Question: What choice/parameters do we have when sampling audio signal?

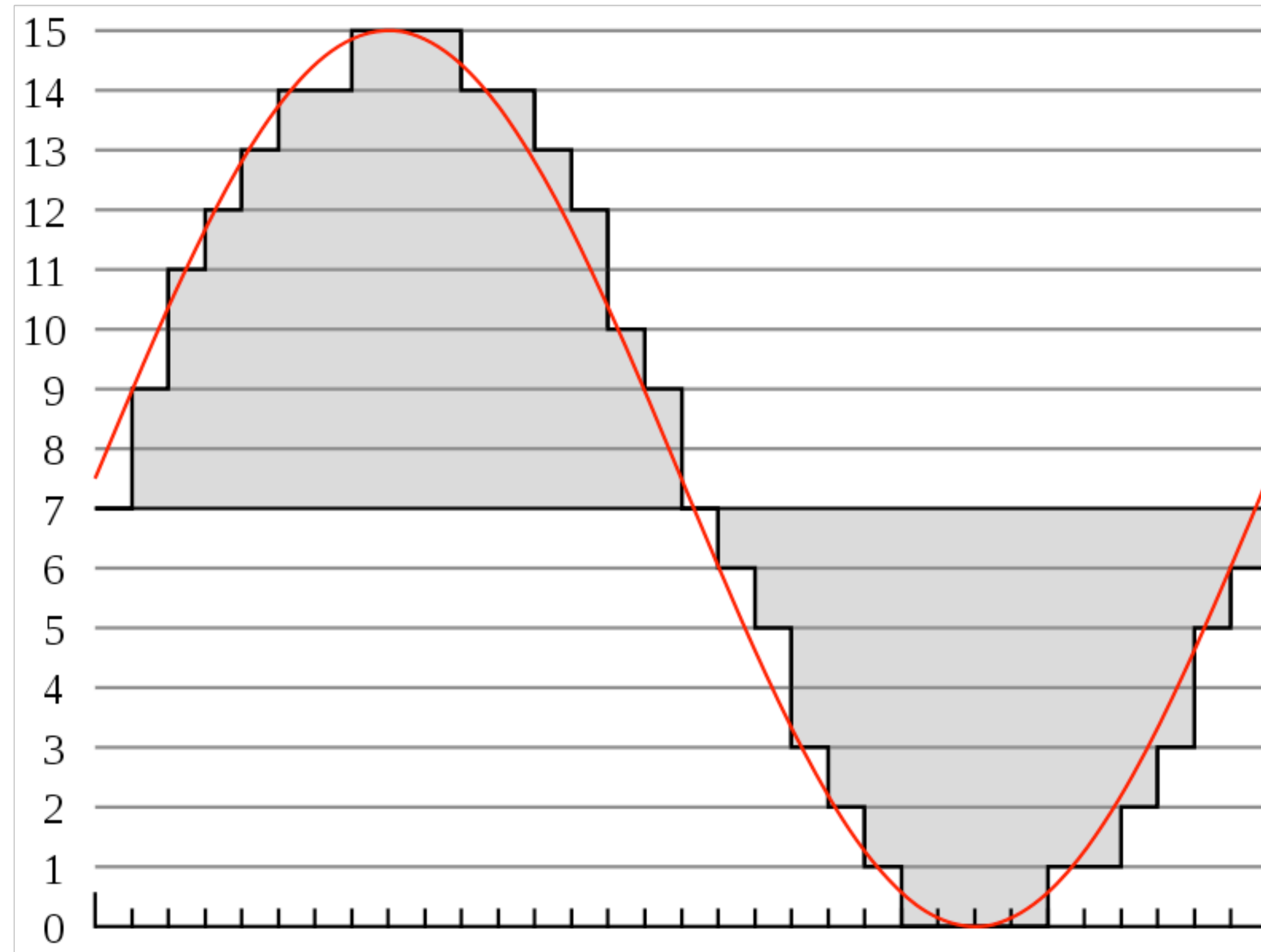
Example: Audio Sampling



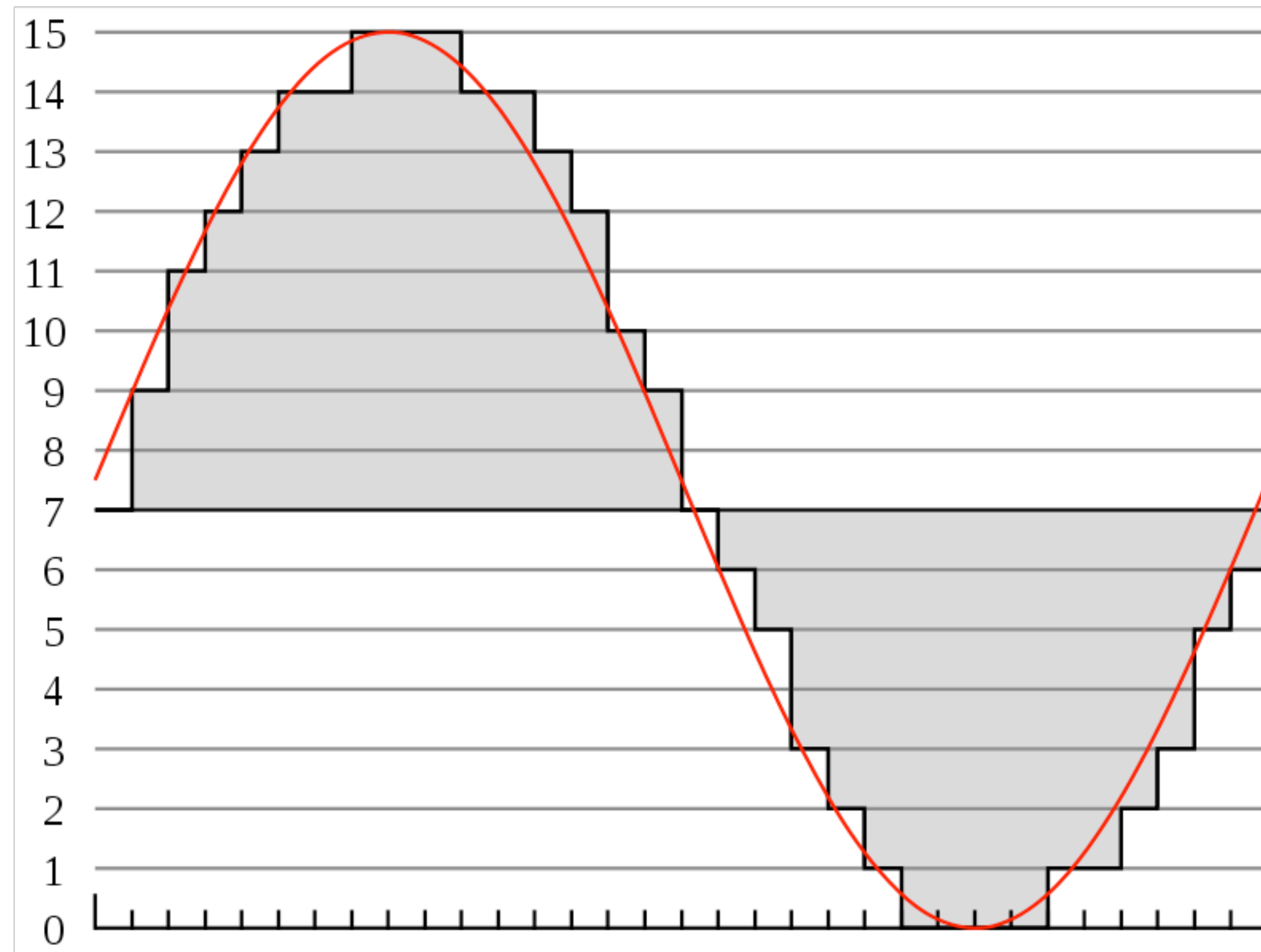
Question: What choice/parameters do we have when sampling audio signal?

Sampling rate and bit depth, e.g., 44.1 kHz (samples/second), 16 bits/sample

Example: Audio Sampling



Example: Audio Sampling



Quantization noise / error is the difference between black and red curves

Audio **Aliasing**

- Aliasing causes undesirable artifacts in audio reproduction
- e.g., if we take an audio signal and simply drop every second sample, the highest frequencies will be aliased... we hear robotic sounding distortion

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import scipy.io.wavfile as wavfile

rate, signal = wavfile.read("stevie.wav")

data=signal[0:(rate*10),:] # 10 seconds of audio

data_2=data[0:-1:2,:] # select every 2nd sample
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↓ 4

↓ 8

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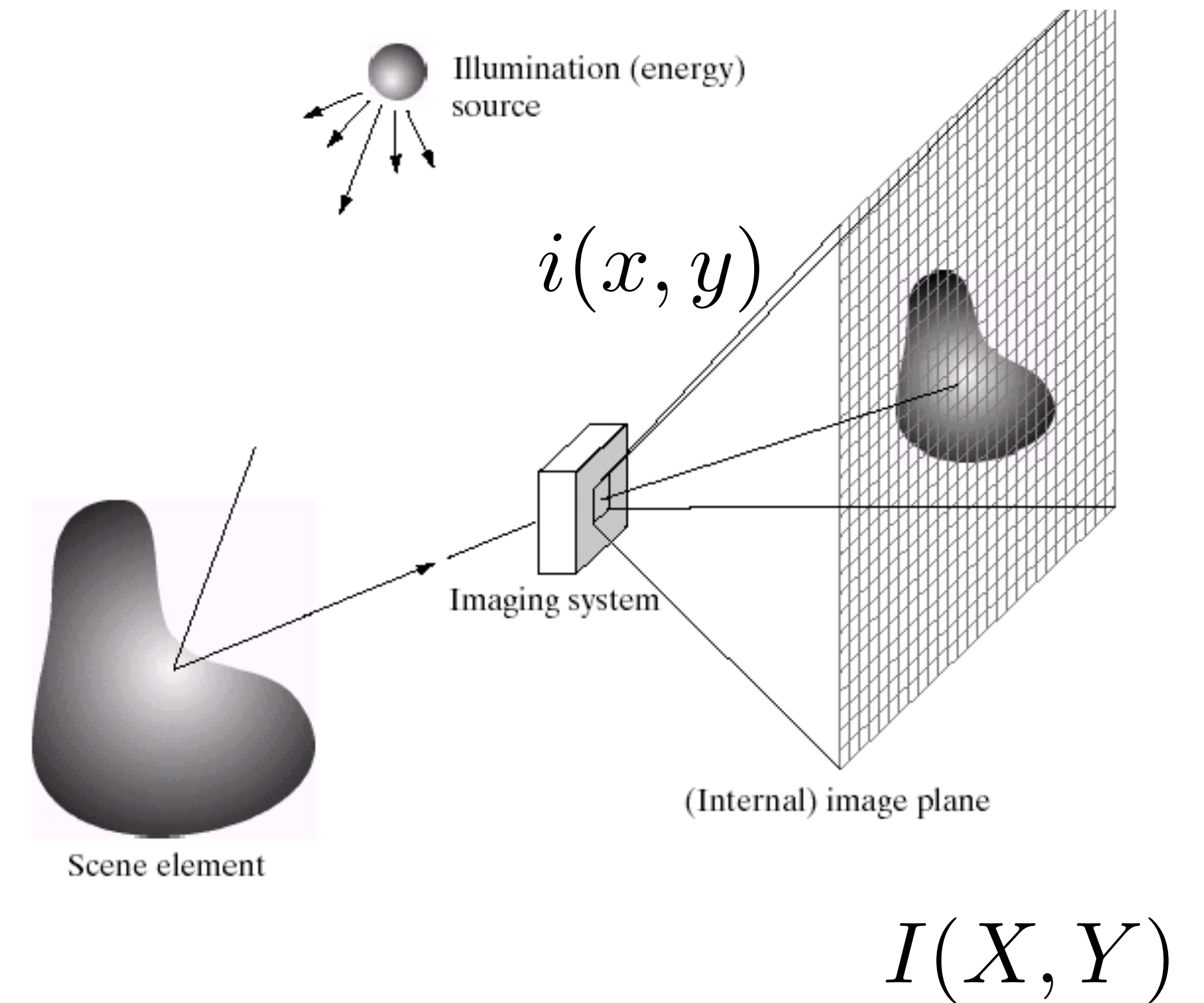
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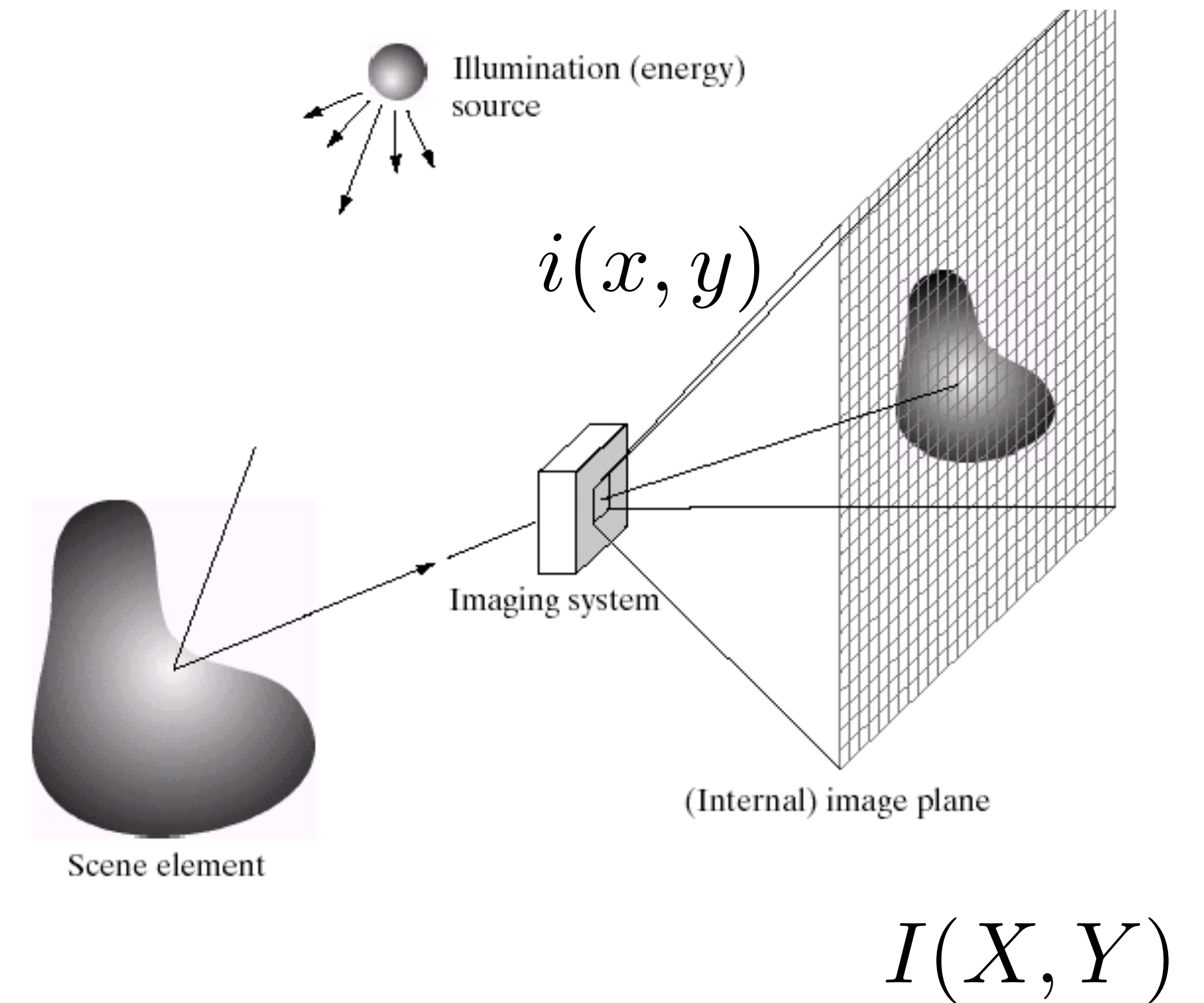
↓ 4

↓ 8

Example: Image Sampling



Example: Image Sampling



Sampling rate and bit depth (e.g., 8-bits)

Continuous Case: Observations

- $i(x, y)$ is a **real-valued function** of **real spatial variables**, x and y
- $i(x, y)$ is **bounded above and below**. That is

$$0 \leq i(x, y) \leq M$$

for some maximum brightness M

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- $i(x, y)$ is **bounded above and below**. That is

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for some maximum brightness M

- $i(x, y)$ is **bounded in extent**. That is, $i(x, y)$ is non-zero (i.e., strictly positive) over, at most, a bounded region

Pixel Bit Rate

Recall: $0 \leq i(x, y) \leq M$

We divide the range $[0, M]$ into a finite number of equivalence classes. This is called **quantization**.

The values are called **grey-levels**.

Suppose n bits-per-pixel are available. One can divide the range $[0, M]$ into evenly spaced intervals.

Typically $n = 8$ resulting in grey-levels in the range $[0, 255]$

Sampling Theory (informal)

Question: When is $I(X, Y)$ an exact characterization of $i(x, y)$?

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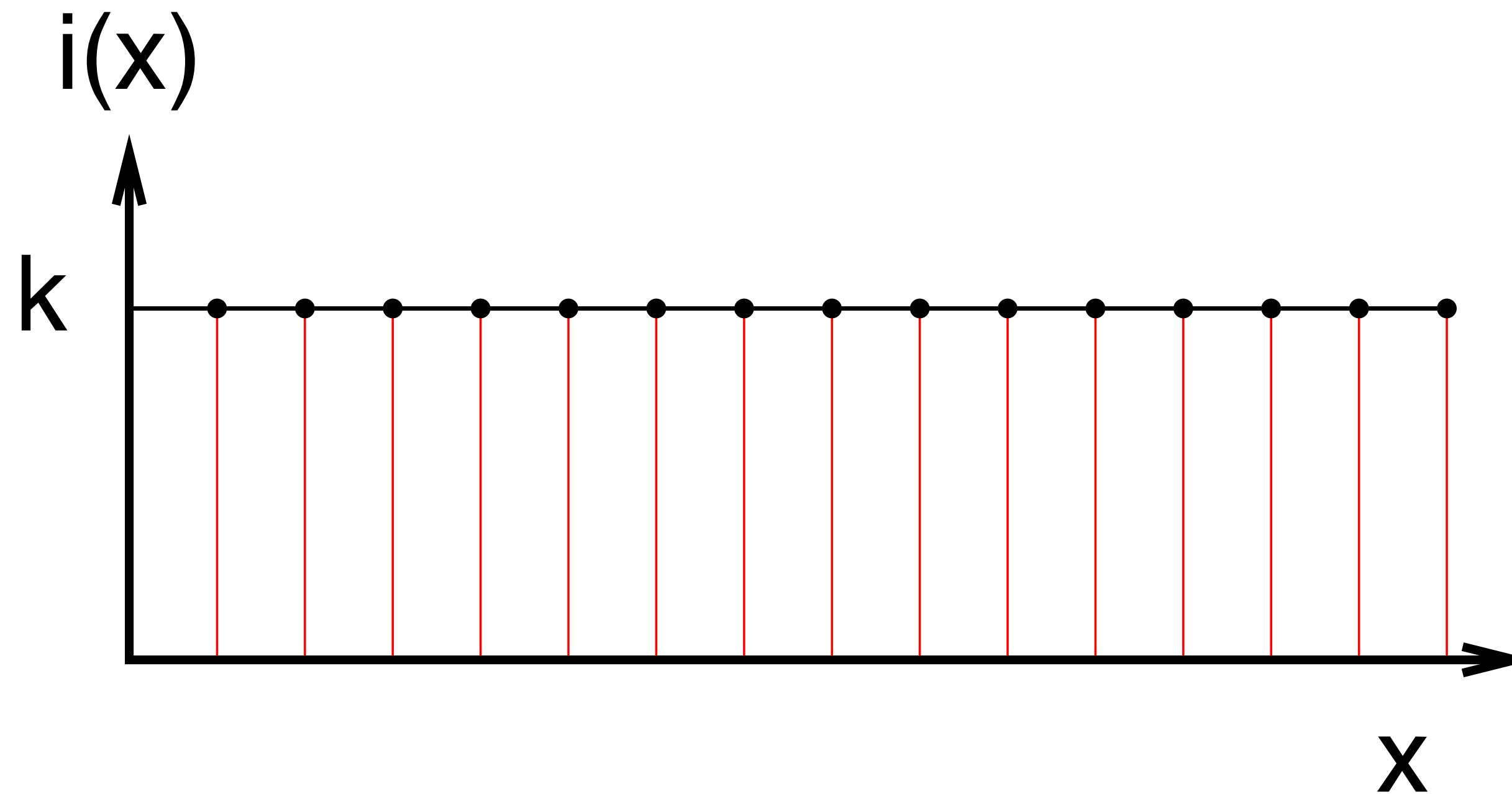
Question (modified): When can we reconstruct $i(x, y)$ exactly from $I(X, Y)$?

Intuition: Reconstruction involves some kind of **interpolation**

Heuristic: When in doubt, consider simple cases

Sampling Theory (informal)

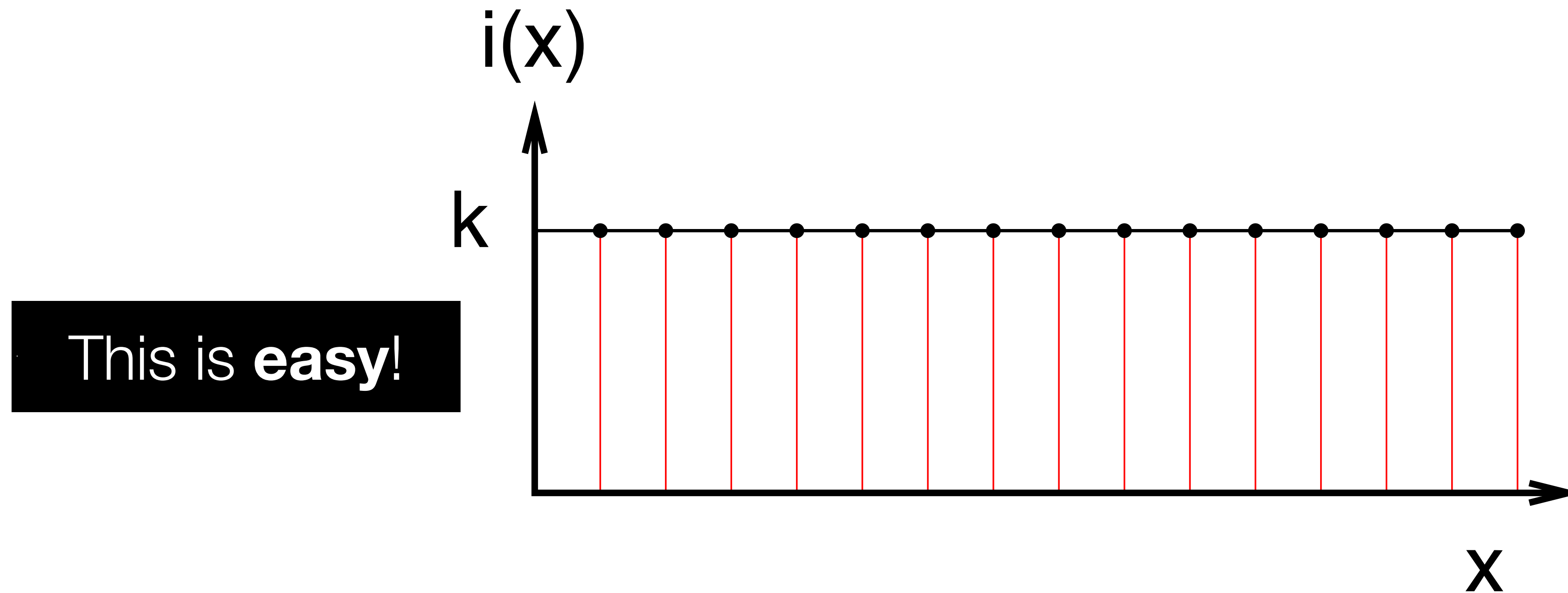
Case 0: Suppose $i(x, y) = k$ (with k being one of our gray levels)



Note: we use equidistant sampling at integer values for convenience, in general, sampling doesn't need to be equidistant

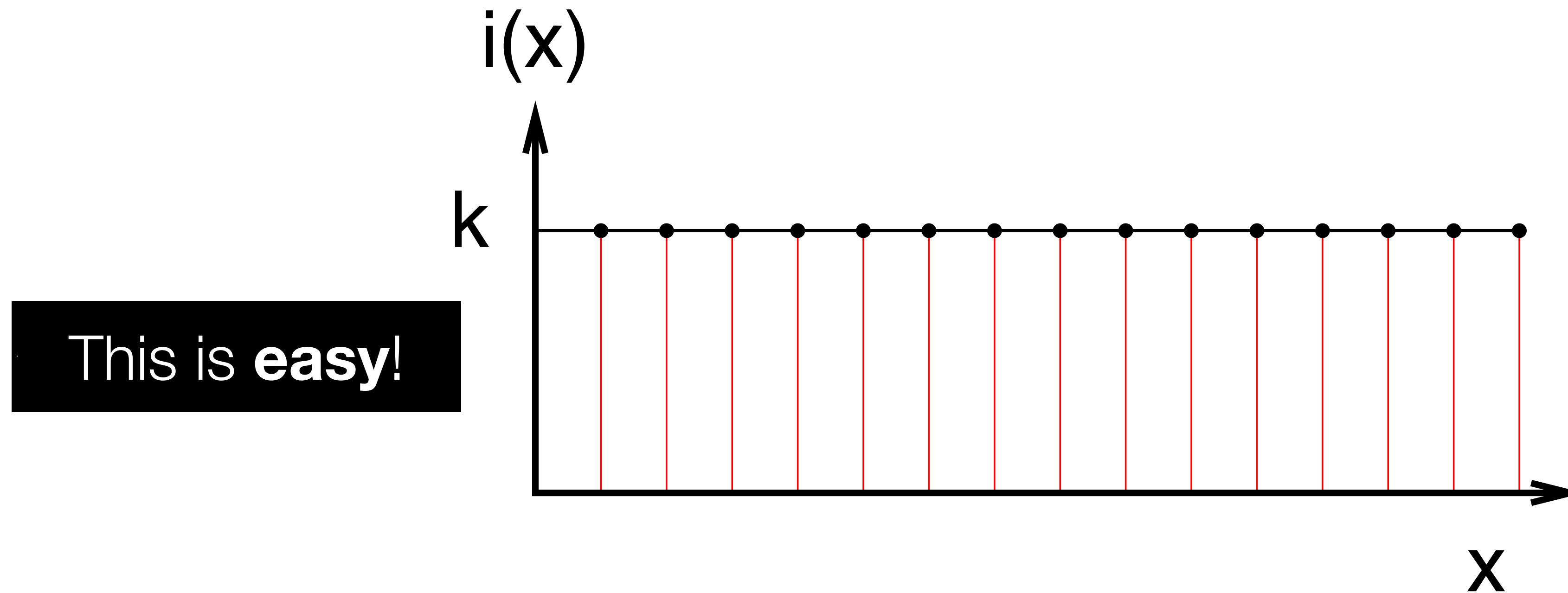
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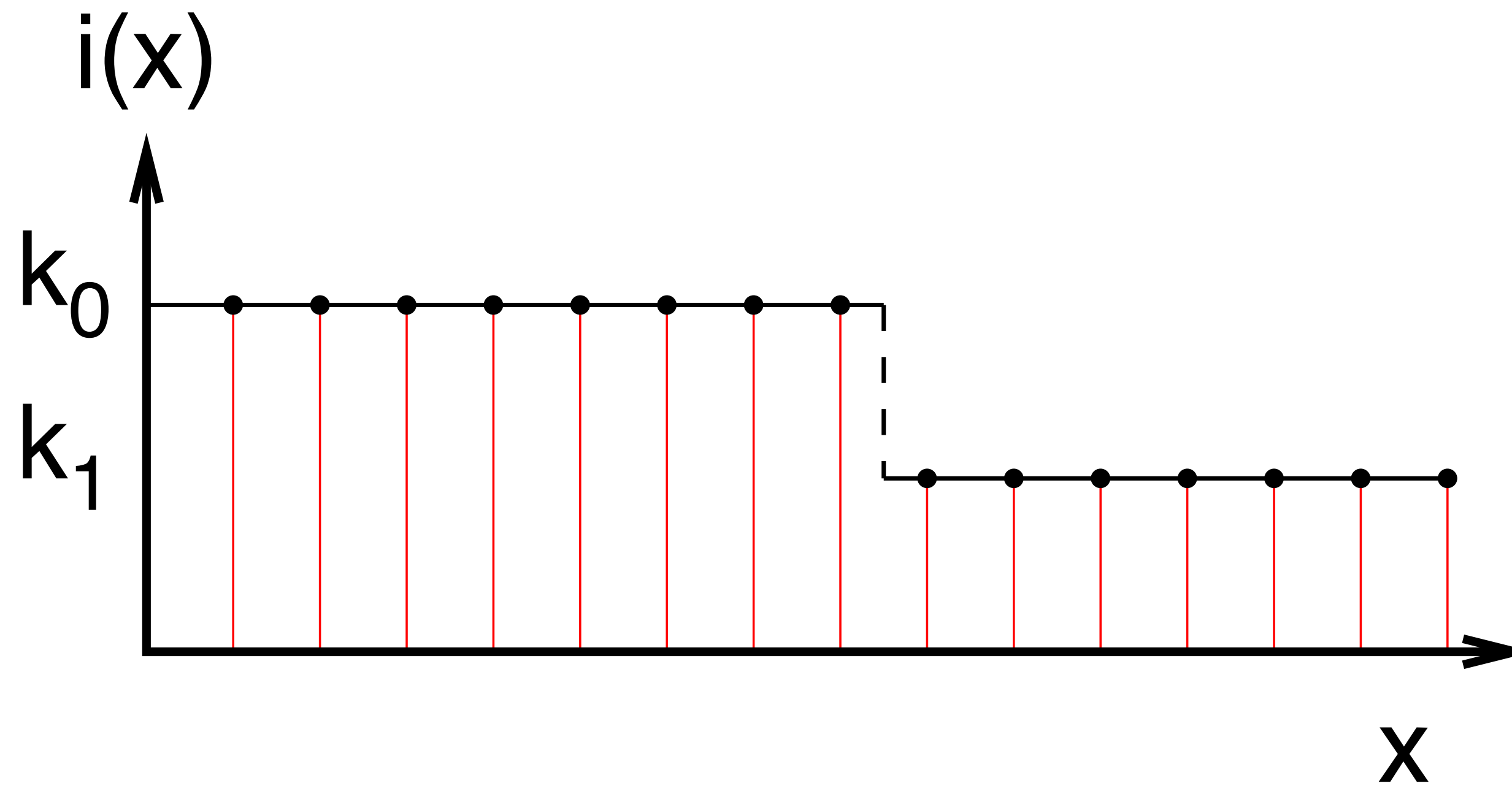
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$I(X, Y) = k$. Any standard interpolation function would give $i(x, y) = k$ for non-integer x and y (irrespective of how coarse the sampling is)

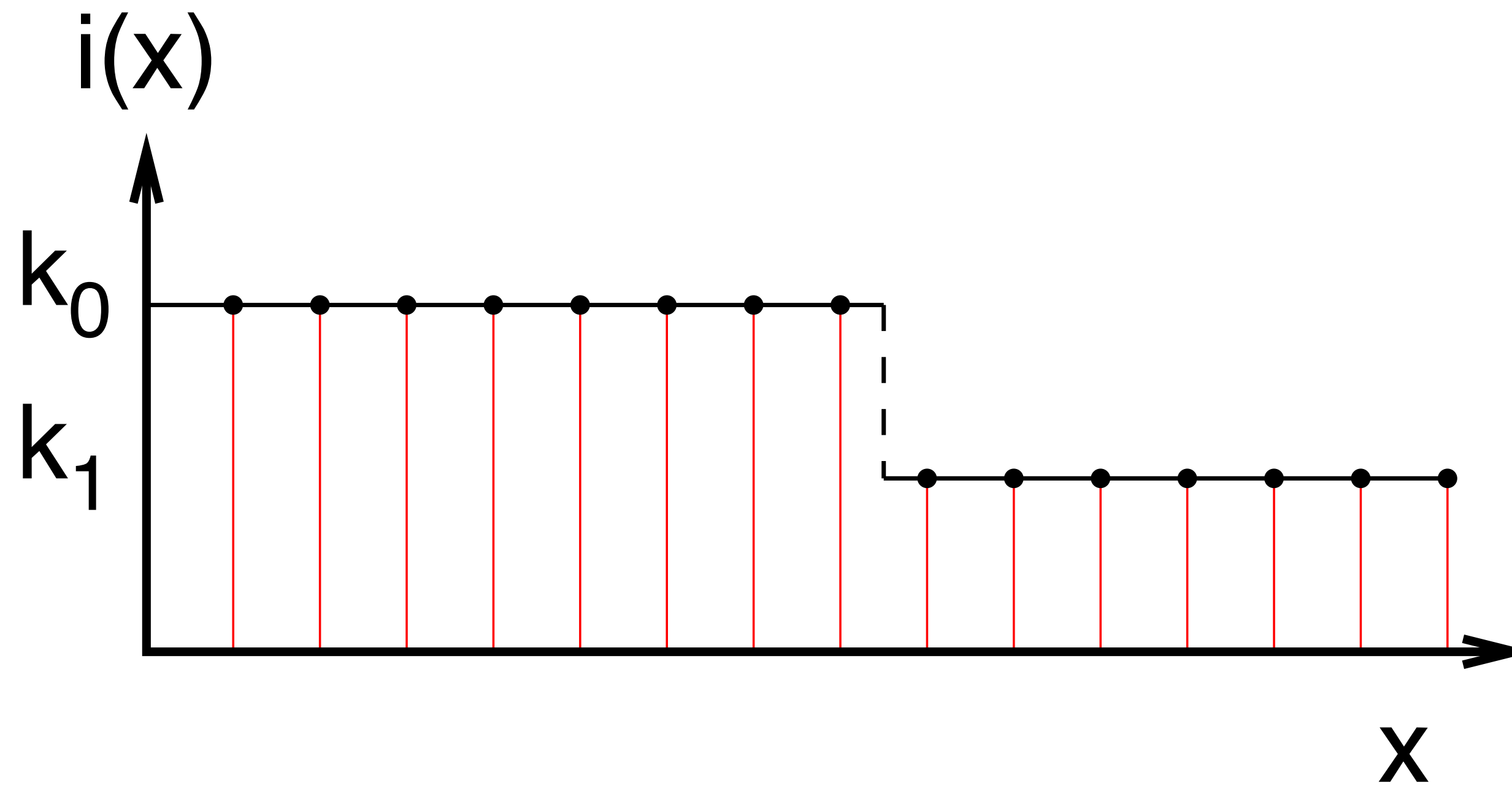
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Case 1: Suppose $i(x, y)$ has a discontinuity not falling precisely at integer x, y



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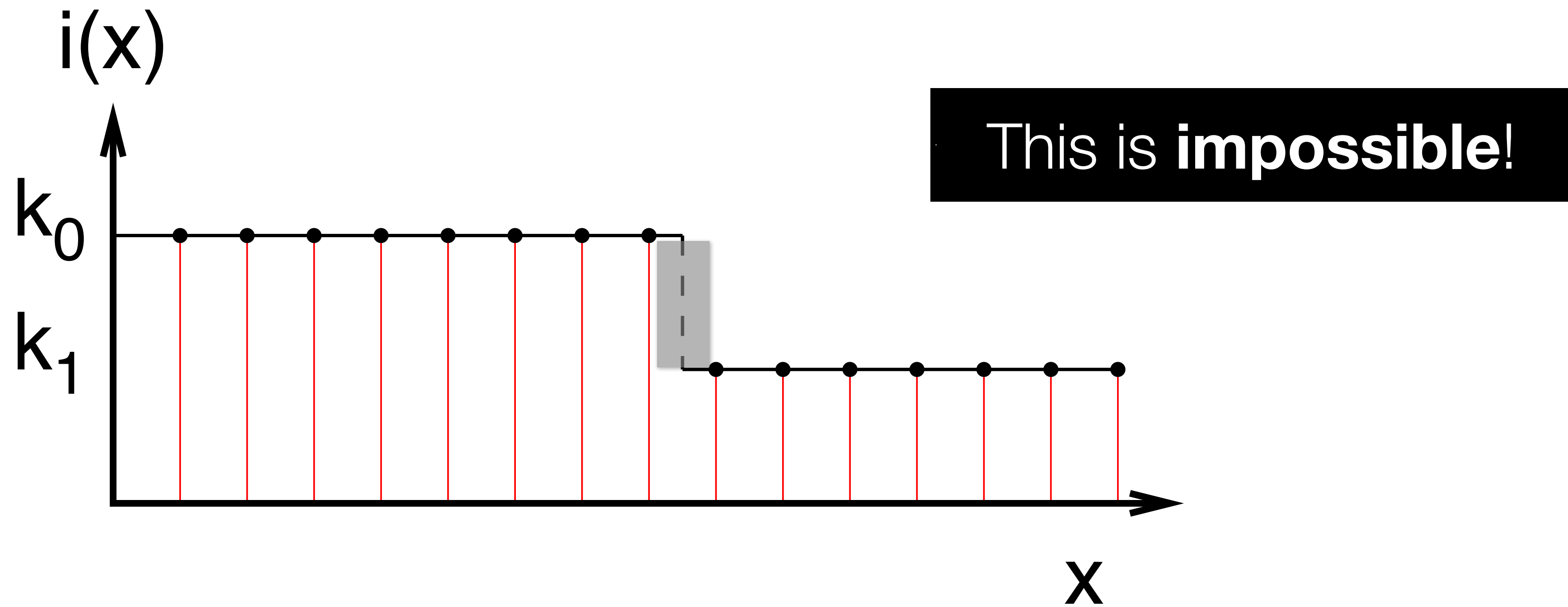
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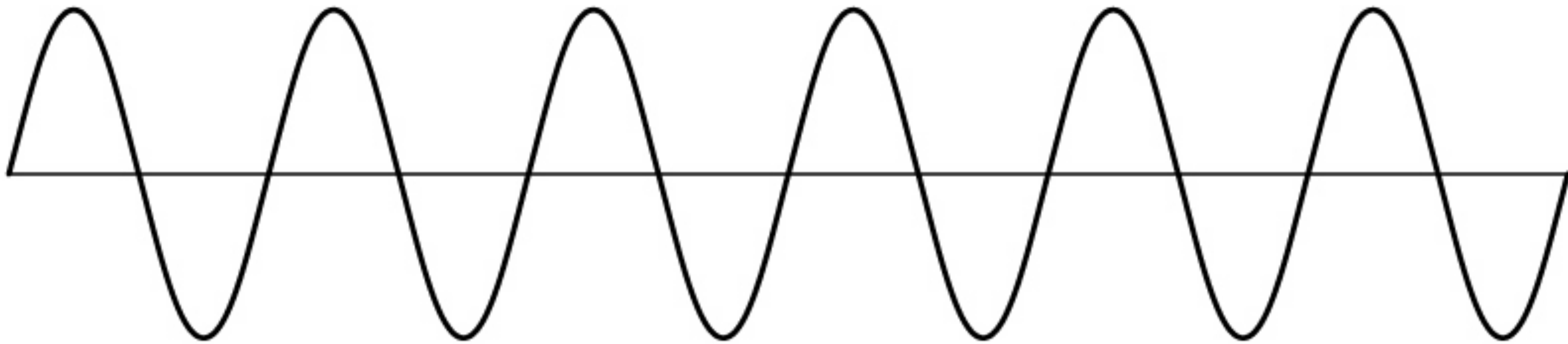
Sampling Theory (informal)

Question: How do we close the gap between “**easy**” and “**impossible?**”

Next, we build intuition based on informal argument

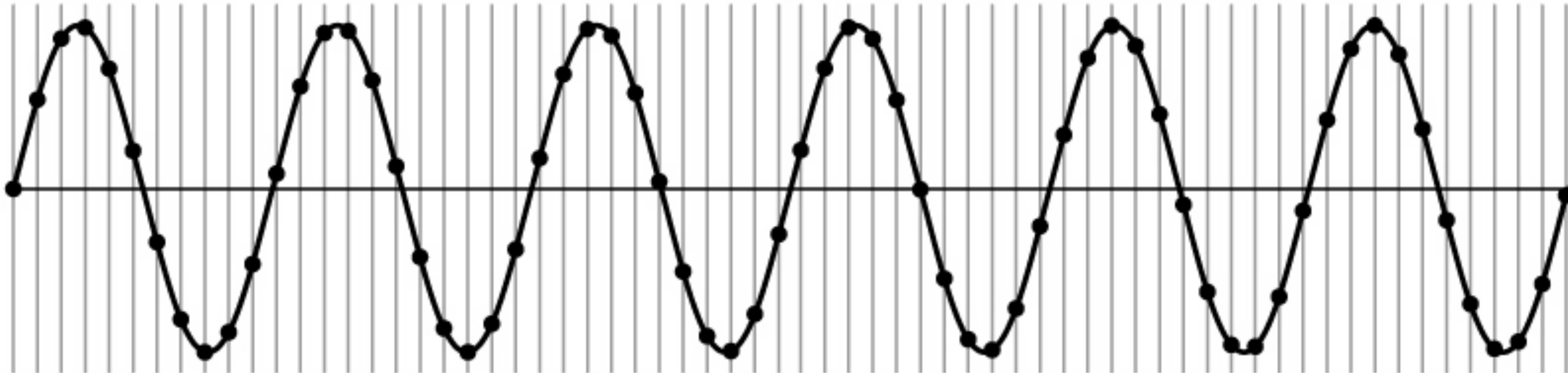
Example: A Simple Sine Wave

How do we discretize the signal?



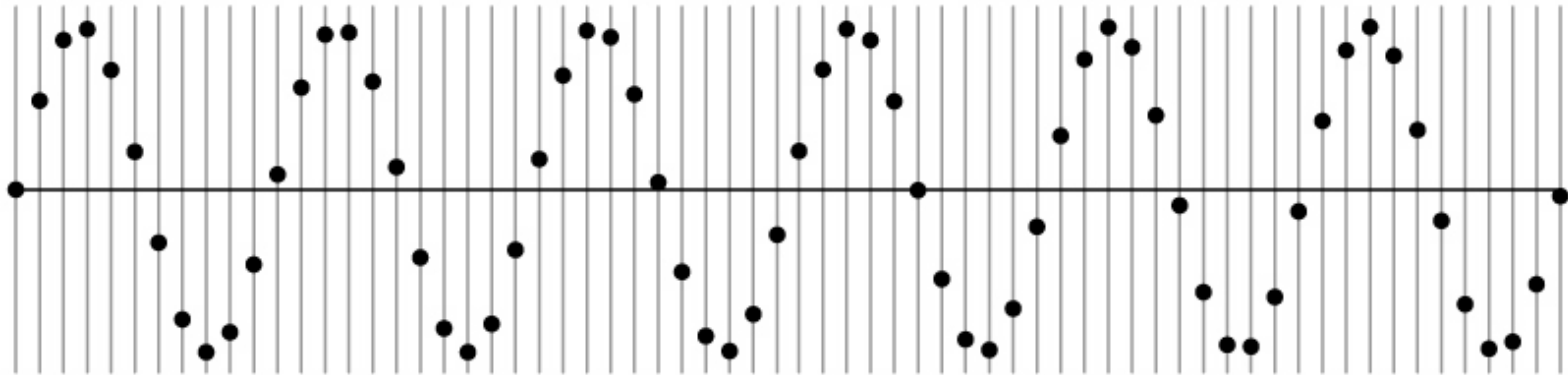
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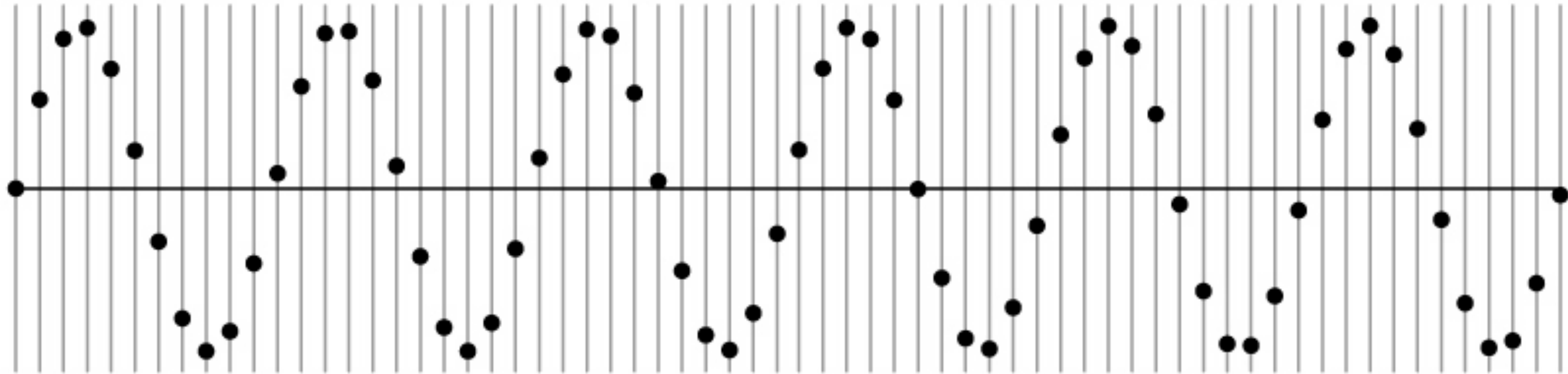
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How many samples should I take?
Can I take as many samples as I want?

Example: A Simple Sine Wave

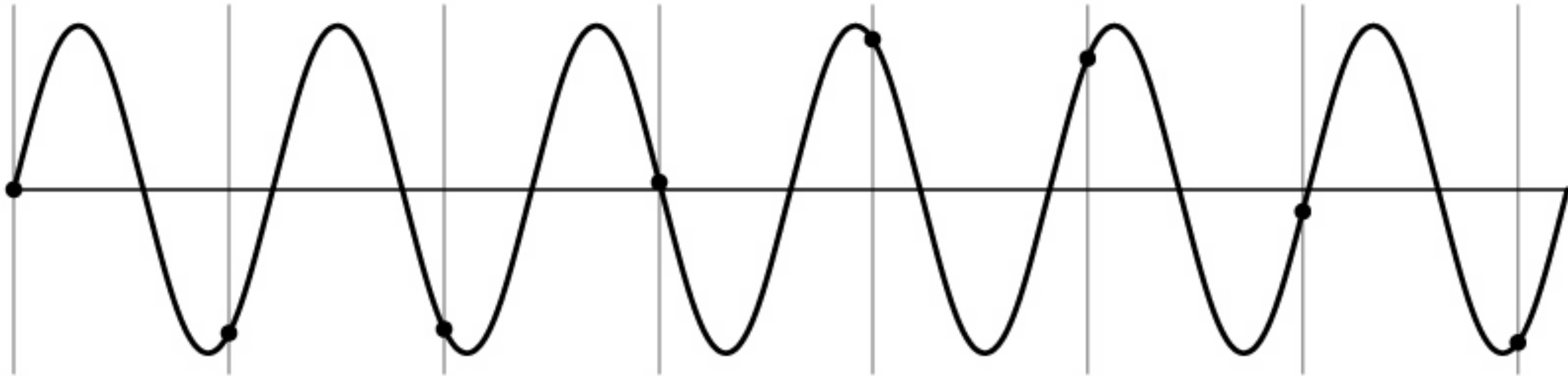
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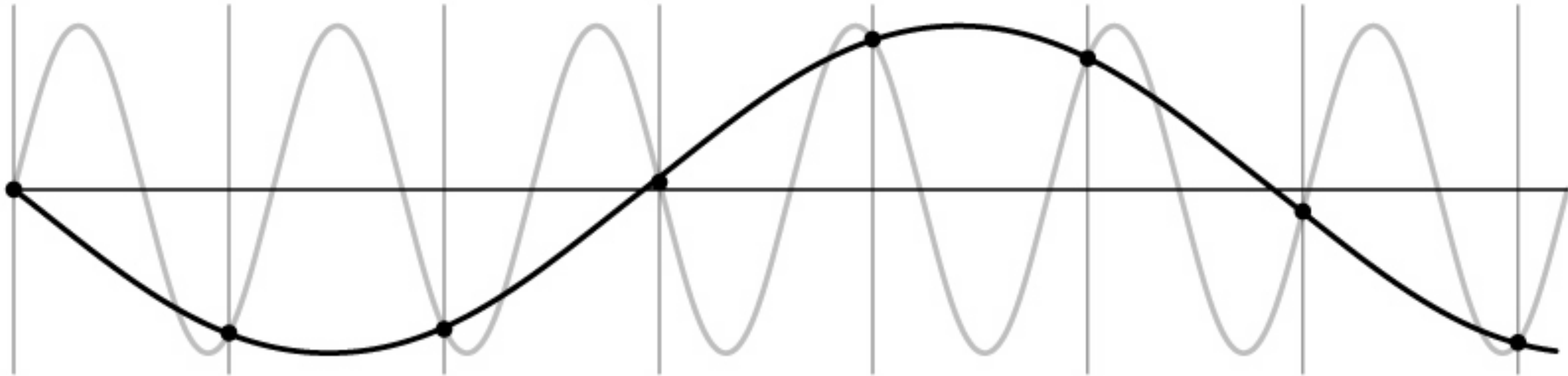
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Signal can be confused with one at lower frequency

Example: A Simple Sine Wave

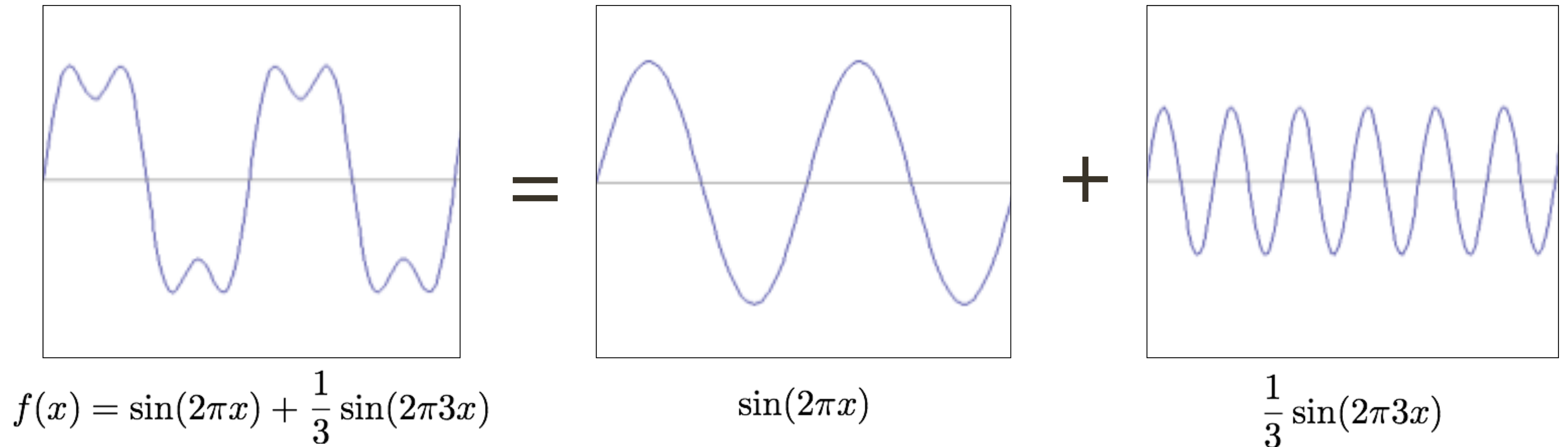
How do we discretize the signal?



Signal can be confused with one at lower frequency
— This is called “Aliasing”

Recall: **Fourier** Representation

Any signal can be written as a sum of sinusoidal functions



Nyquist Sampling Theorem

To avoid aliasing a signal must be sampled at twice the maximum frequency:

$$f_s > 2 \times f_{max}$$

where f_s is the sampling frequency, and f_{max} is the maximum frequency present in the signal

Futhermore, Nyquist's theorem states that a signal is **exactly recoverable** from its **samples** if sampled at the **Nyquist rate** (or higher)

Note: that a signal must be **bandlimited** for this to apply (i.e., it has a maximum frequency)

Sampling Theory (informal)

Exact reconstruction requires constraint on the rate at which $i(x,y)$ can change between samples

- “rate of change” means derivative
- the formal concept is **bandlimited signal**
- “bandlimit” and “constraint on derivative” are linked

Think of music

- bandlimited if it has some maximum **temporal frequency**
- the upper limit of human hearing is about 20 kHz

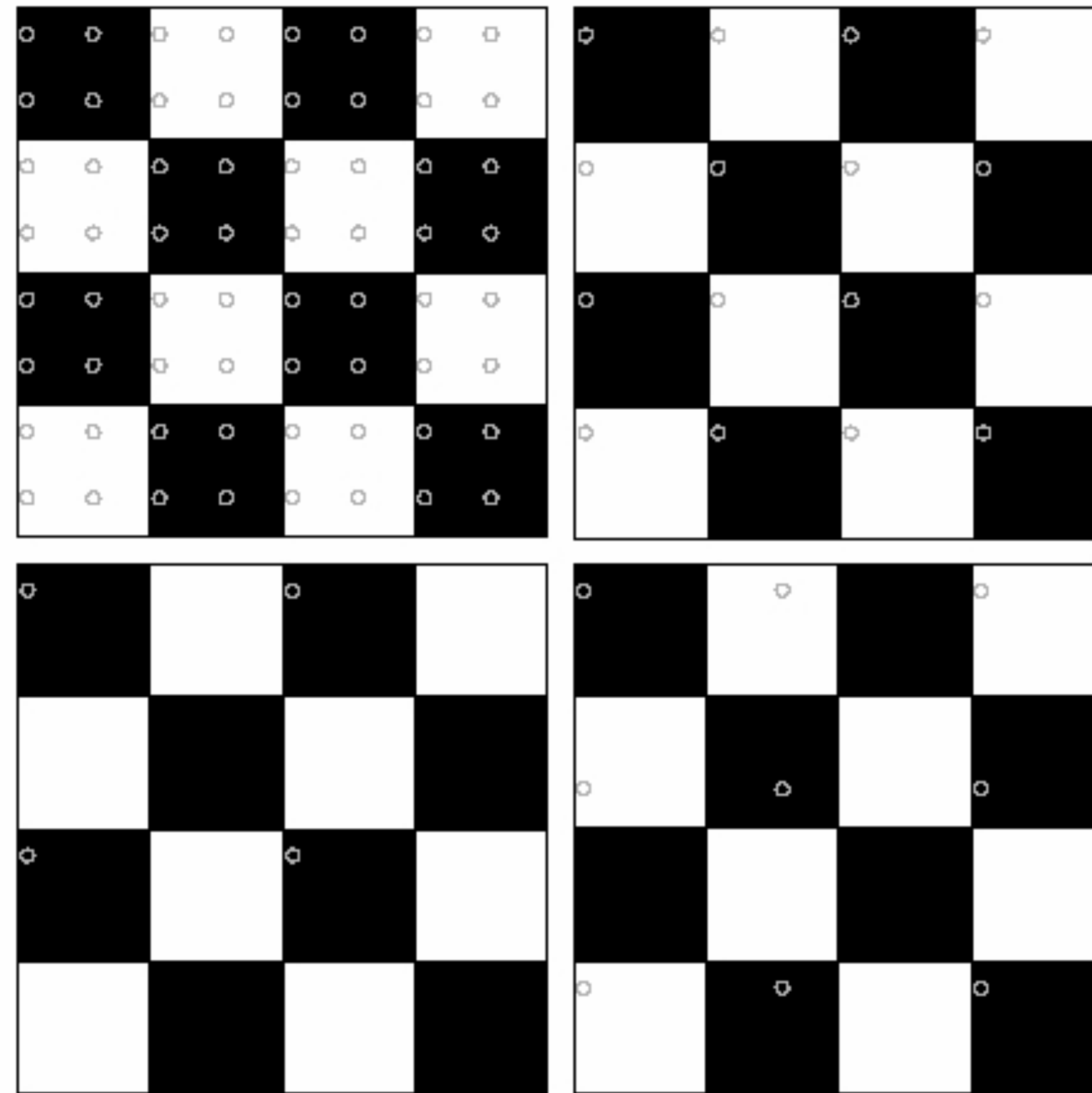
Think of imaging systems. Resolving power is measured in

- “line pairs per mm” (for a bar test pattern)
- “cycles per mm” (for a sine wave test pattern)

An image is bandlimited if it has some maximum **spatial frequency**

Sampling

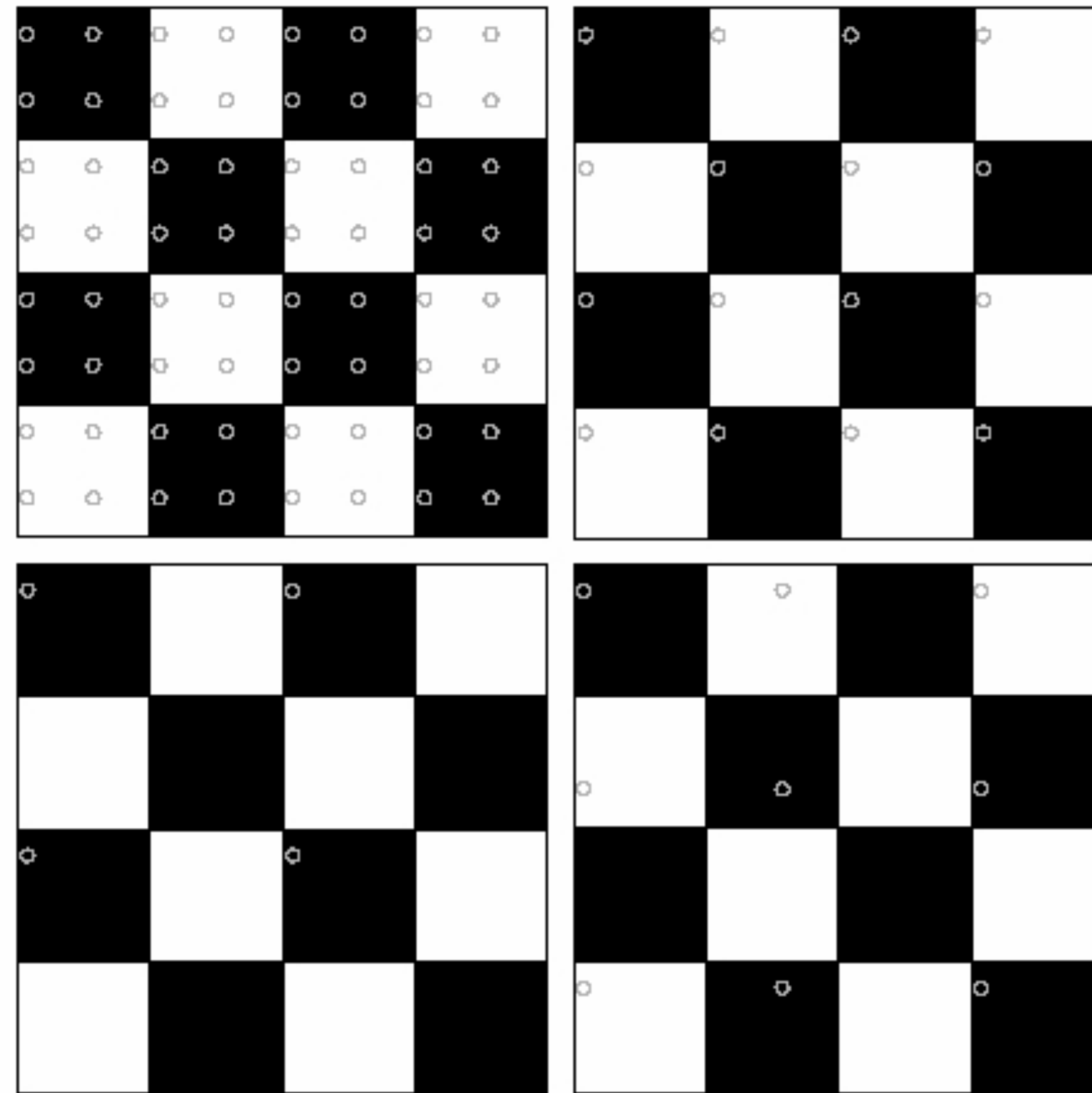
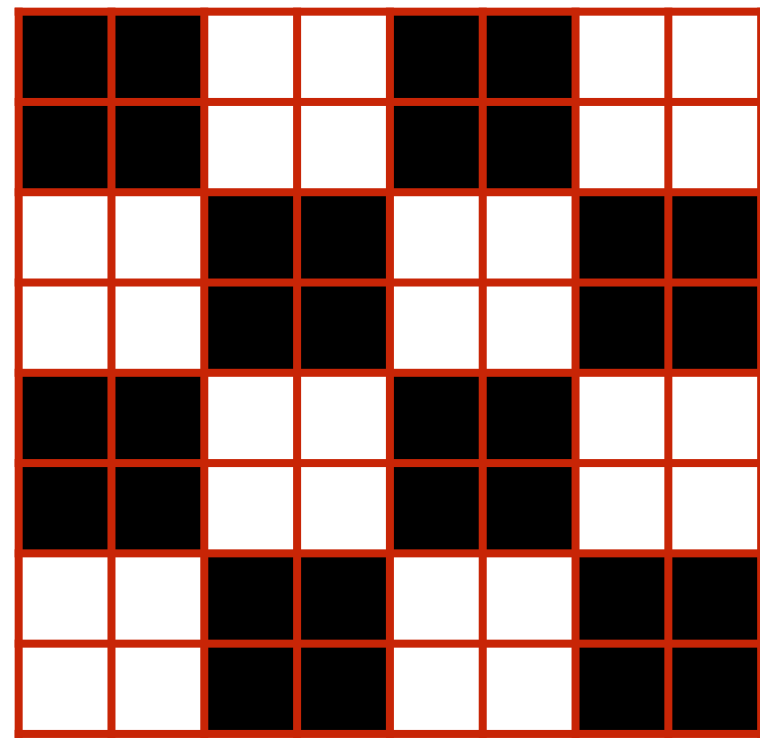
It is clear that *some* information may be lost when we work on a discrete pixel grid.



Forsyth & Ponce (2nd ed.) Figure 4.7

Sampling

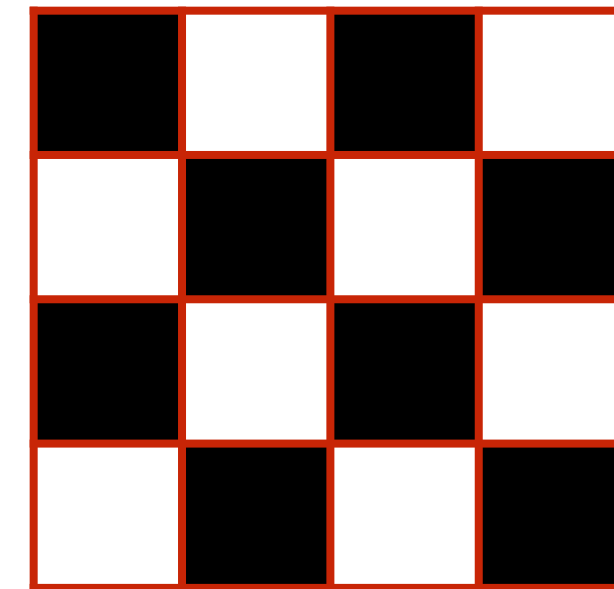
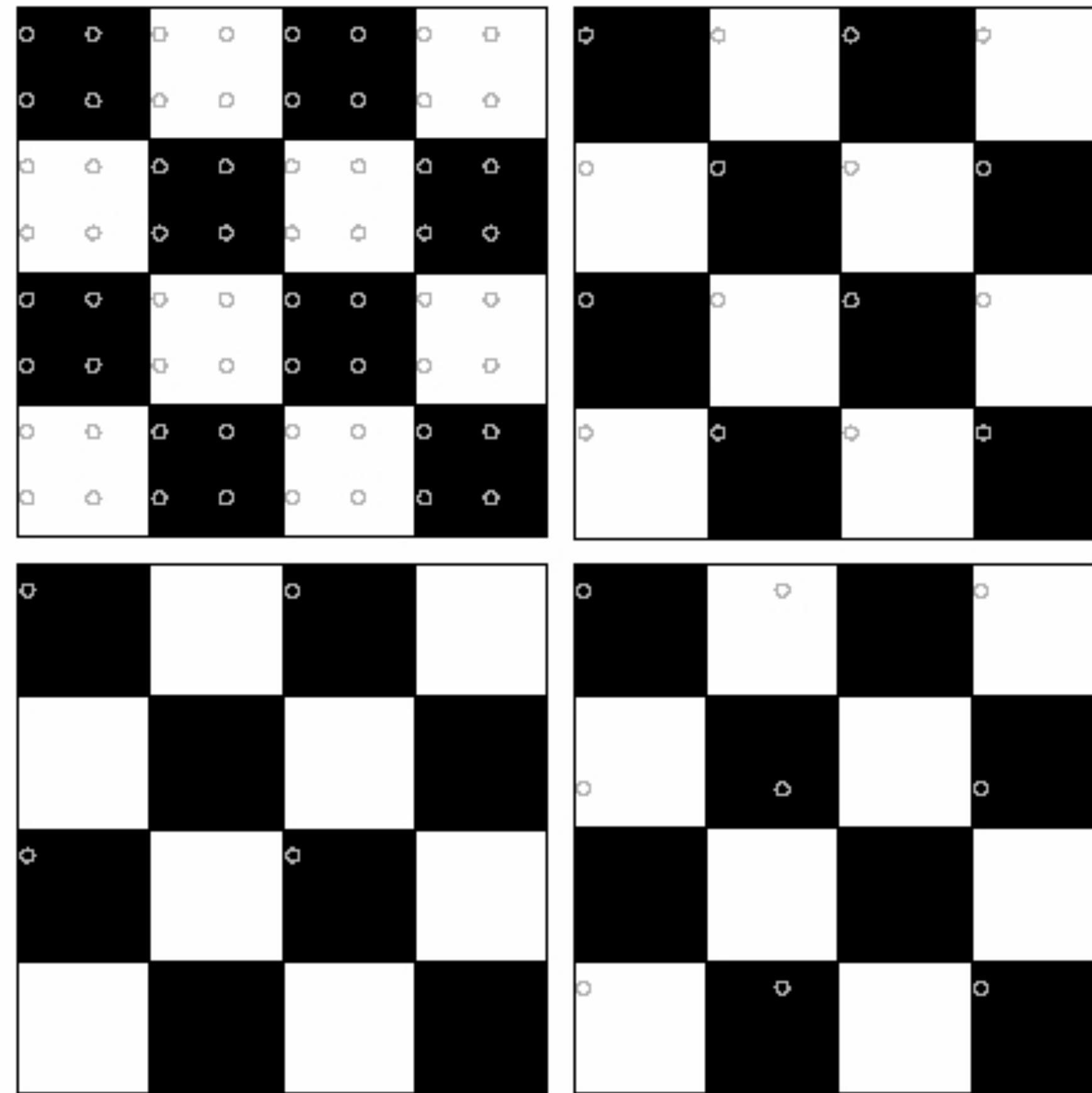
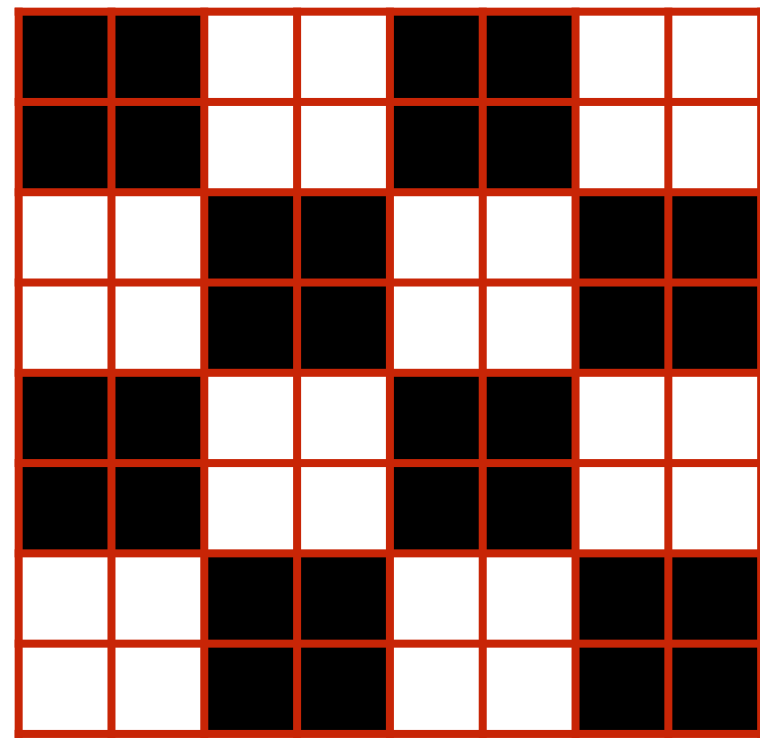
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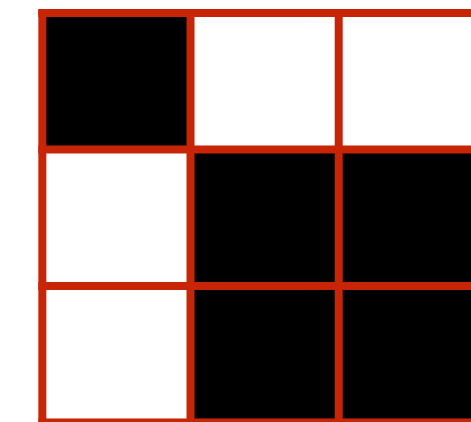
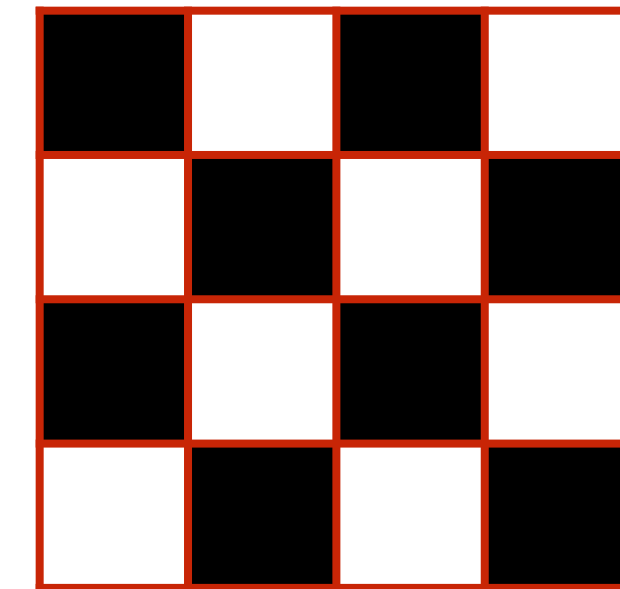
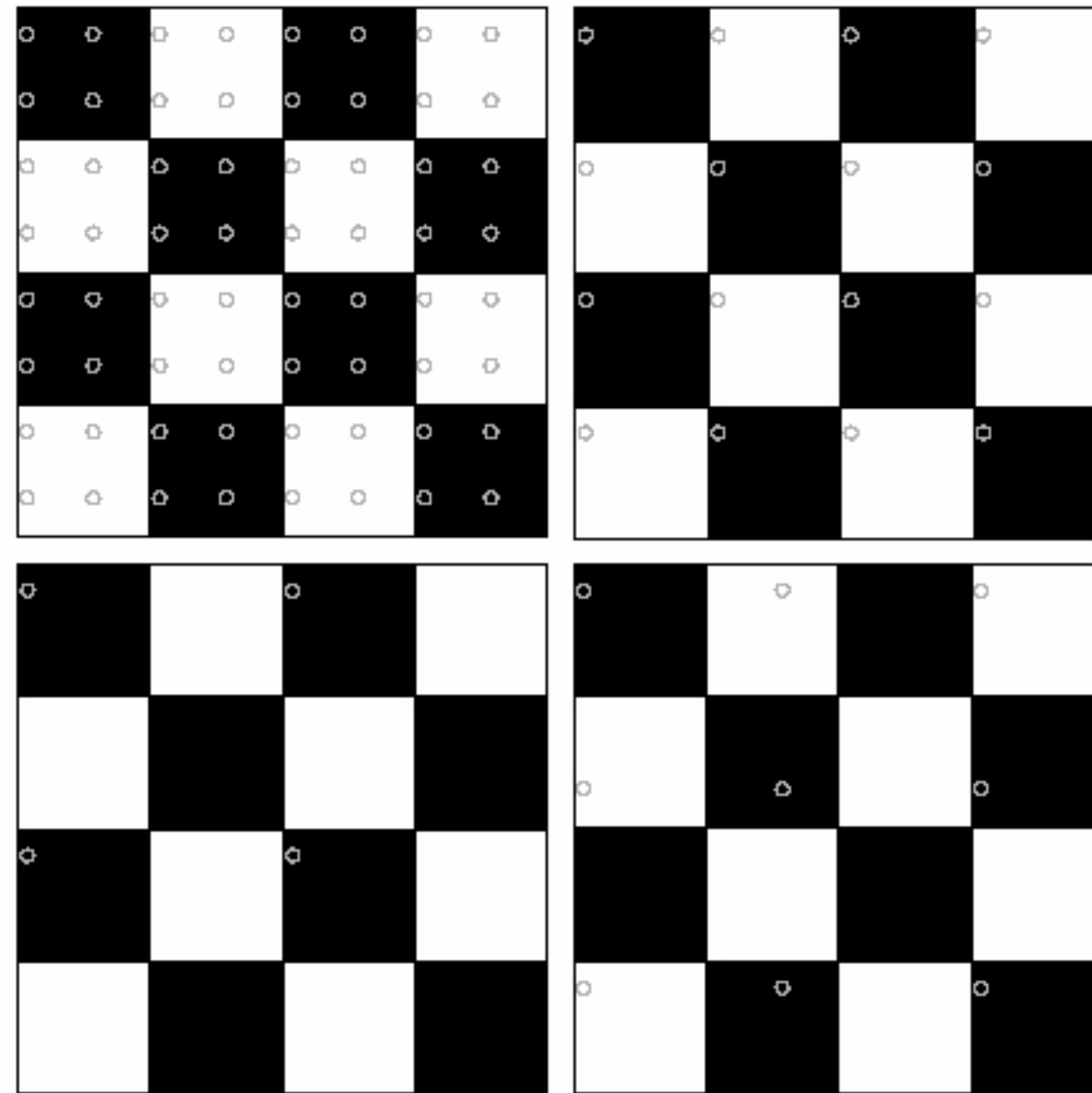
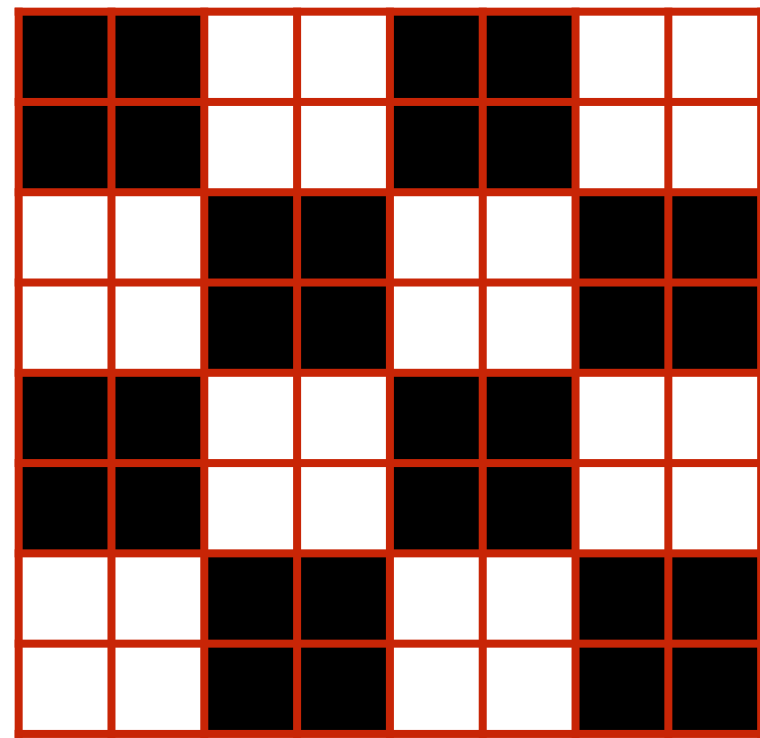
It is clear that *some* information may be lost when we work on a discrete pixel grid.



Forsyth & Ponce (2nd ed.) Figure 4.7

Sampling

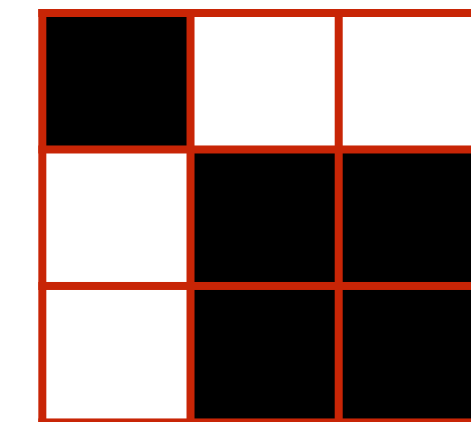
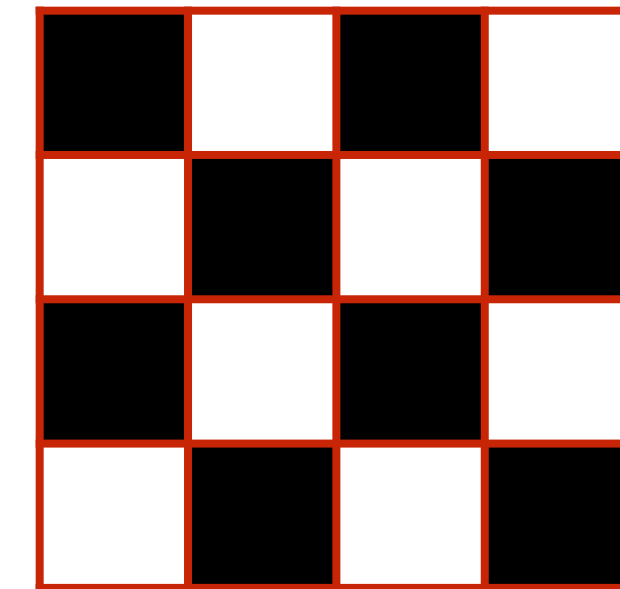
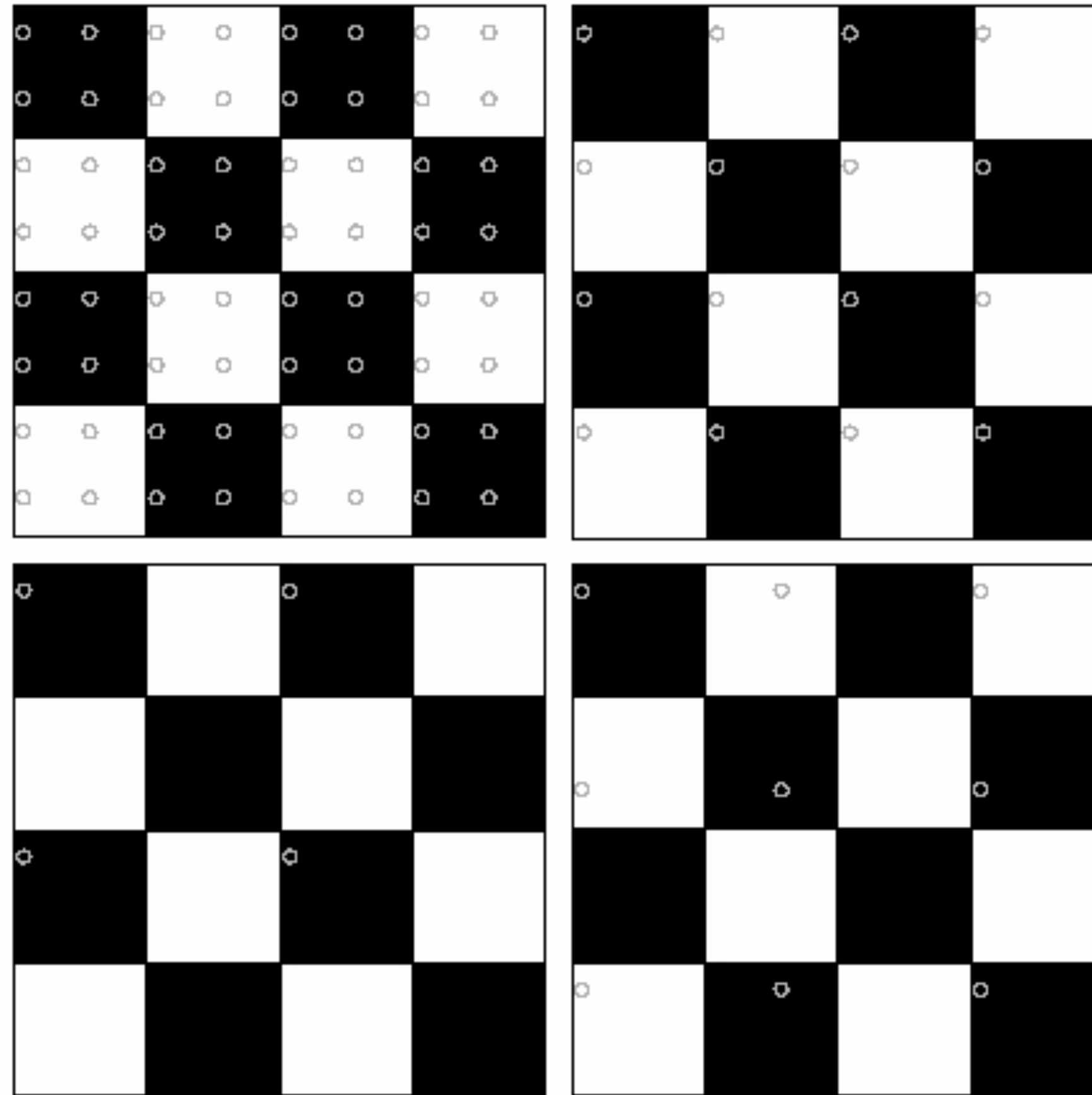
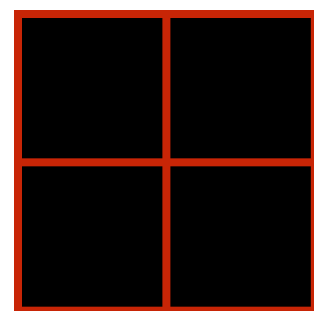
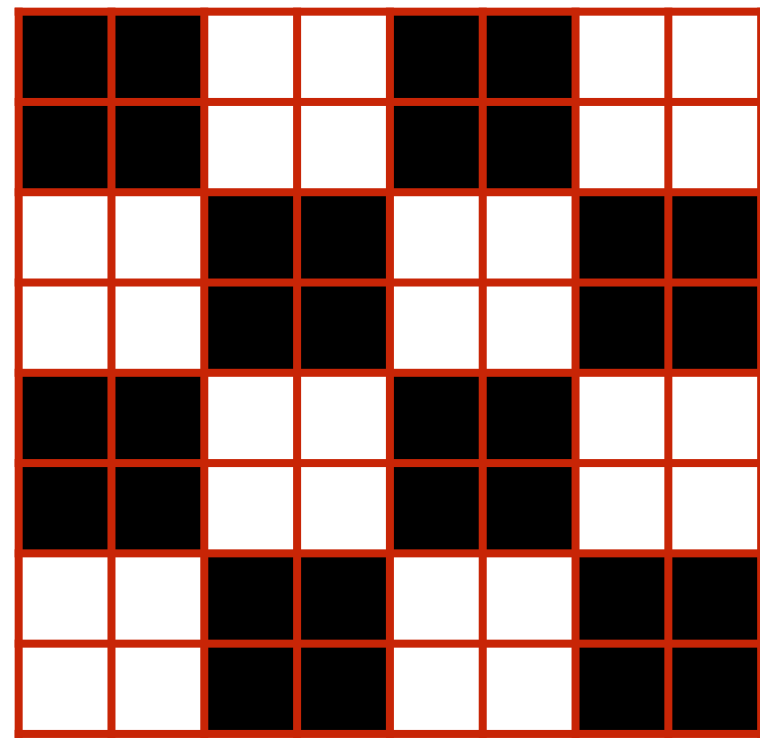
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Forsyth & Ponce (2nd ed.) Figure 4.7

Sampling

It is clear that *some* information may be lost when we work on a discrete pixel grid.



Forsyth & Ponce (2nd ed.) Figure 4.7

Resampling Images

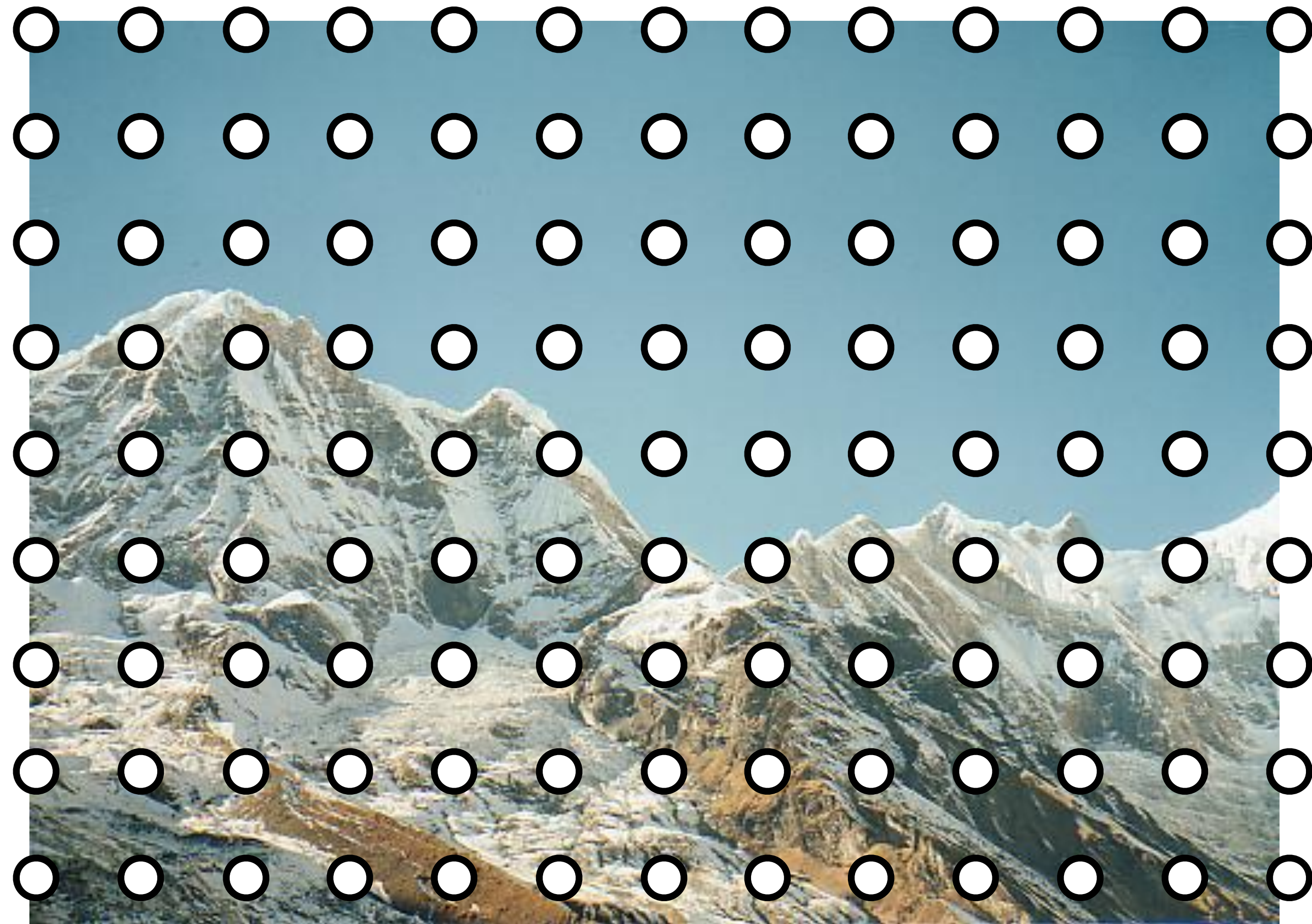
Goal: Resample the image to get a lower resolution counterpart



Naive Method: Form new image by taking every n -th pixel of the original image

Resampling Images

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Resampling Images

With correct sigma value for a Gaussian, no information is lost



Improved Method: First blur the image (with low-pass) then take n-th pixel

Resampling Images

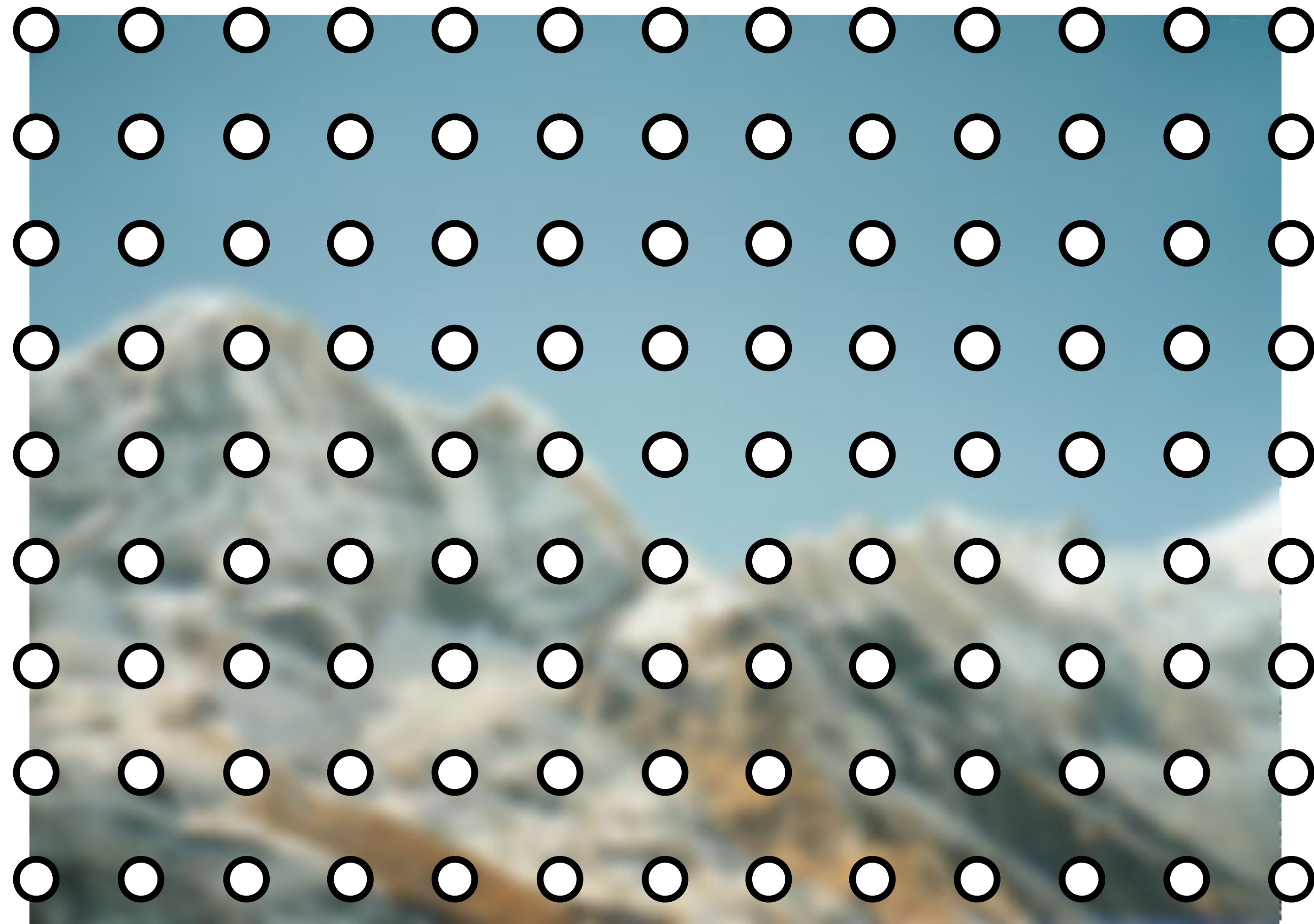
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Resampling Images

With correct sigma value for a Gaussian, no information is lost



Improved Method: First blur the image (with low-pass) then take n-th pixel

Aliasing Example

Sampling every 5th pixel with and without low-pass blur



No filtering



Gaussian Blur $\sigma = 3.0$

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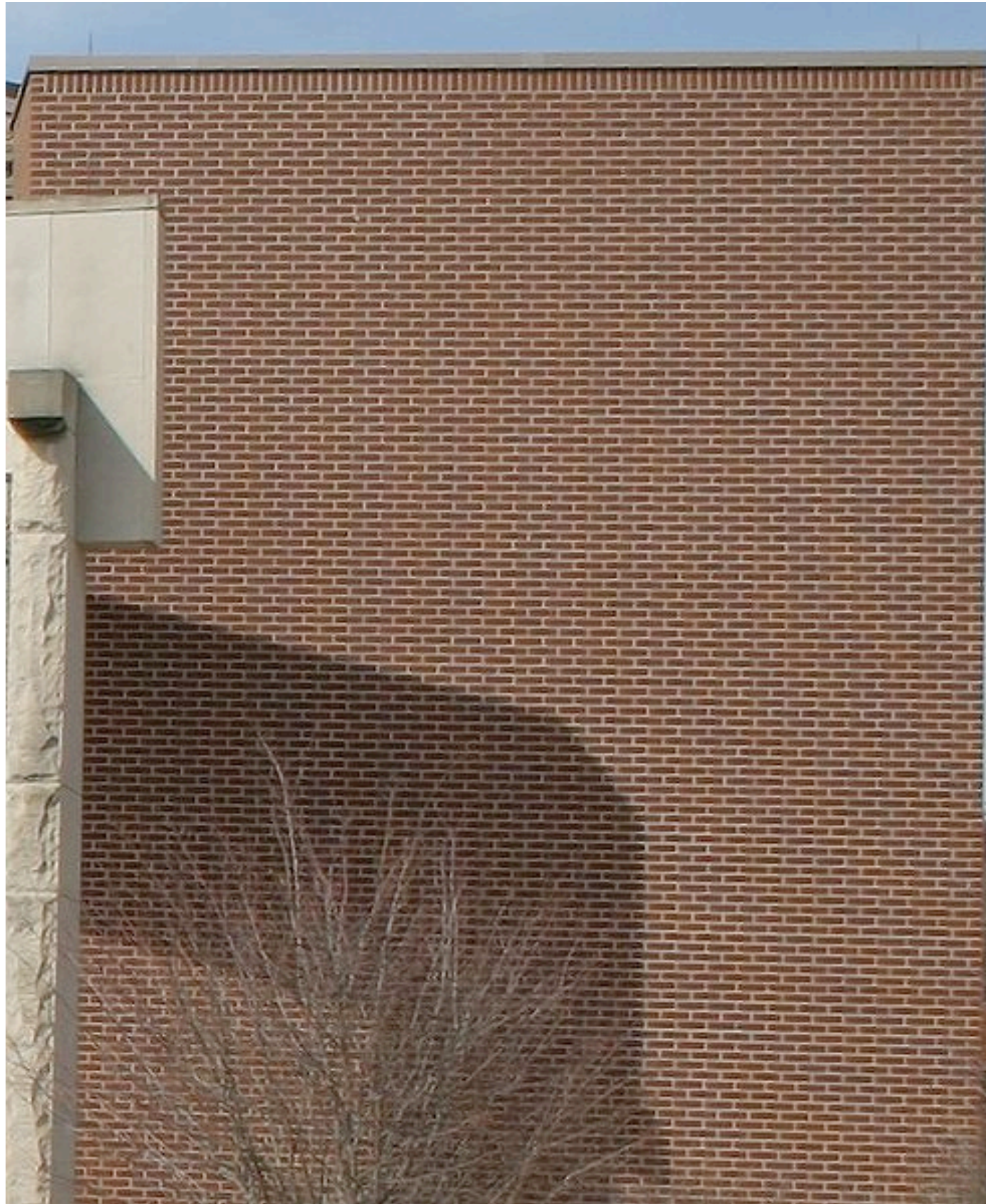


No filtering



Gaussian Blur $\sigma = 3.0$

Image Sampling and Aliasing



$$f_s > 2 \times f_{max}$$



$$f_s < 2 \times f_{max}$$

Aliasing in Photographs

This is also known as “moire”



Image Pyramids



↙ $\div 2$

↙ $\div 2$

↙ $\div 2$

Used in Graphics (Mip-map) and Vision
(for **multi-scale** processing)

$G1$



Blur with a Gaussian
kernel, then select
every 2nd pixel

$$I_s(x, y) = I(x, y) * g_\sigma(x, y)$$

Often approximations
to the Gaussian kernel
are used, e.g.,

$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

$G1$



blur



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$G1$



blur

$\div 2$



$G2$



Blur with a Gaussian kernel, then select every 2nd pixel

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$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

$G1$



blur

$\div 2$



$G2$



blur



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$G1$



blur

$\div 2$



$G2$



blur

$\div 2$



$G3$



Blur with a Gaussian kernel, then select every 2nd pixel

$$I_s(x, y) = I(x, y) * g_\sigma(x, y)$$

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$G1$



blur

$\div 2$



$G2$



blur

$\div 2$



$G3$



blur



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Often approximations to the Gaussian kernel are used, e.g.,

$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

G_1



blur

$\div 2$



G_2



blur

$\div 2$



G_3

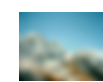


blur

$\div 2$



G_4



Gaussian Pyramid

Blur with a Gaussian kernel, then select every 2nd pixel

$$I_s(x, y) = I(x, y) * g_\sigma(x, y)$$

Often approximations to the Gaussian kernel are used, e.g.,

$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

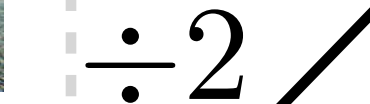
G_1



blur



$\div 2$



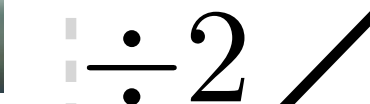
G_2



blur



$\div 2$



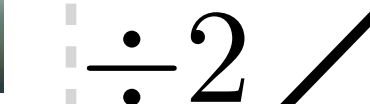
G_3



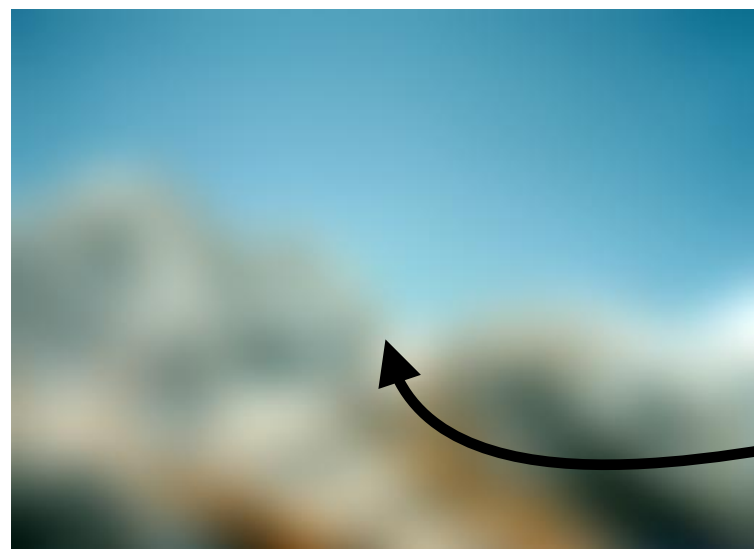
blur



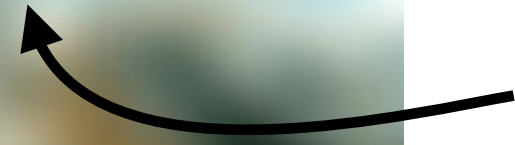
$\div 2$



G_4



Gaussian Pyramid



Blur with a Gaussian kernel, then select every 2nd pixel

$$I_s(x, y) = I(x, y) * g_\sigma(x, y)$$

Often approximations to the Gaussian kernel are used, e.g.,

$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

Sampling Theory (informal)

Question: For a bandlimited signal, what if you **oversample** (i.e., sample at greater than the Nyquist rate)

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Question: For a bandlimited signal, what if you **undersample** (i.e., sample at less than the Nyquist rate)

Answer: Two bad things happen! Things are missing (i.e., things that should be there aren't). There are artifacts (i.e., things that shouldn't be there are)

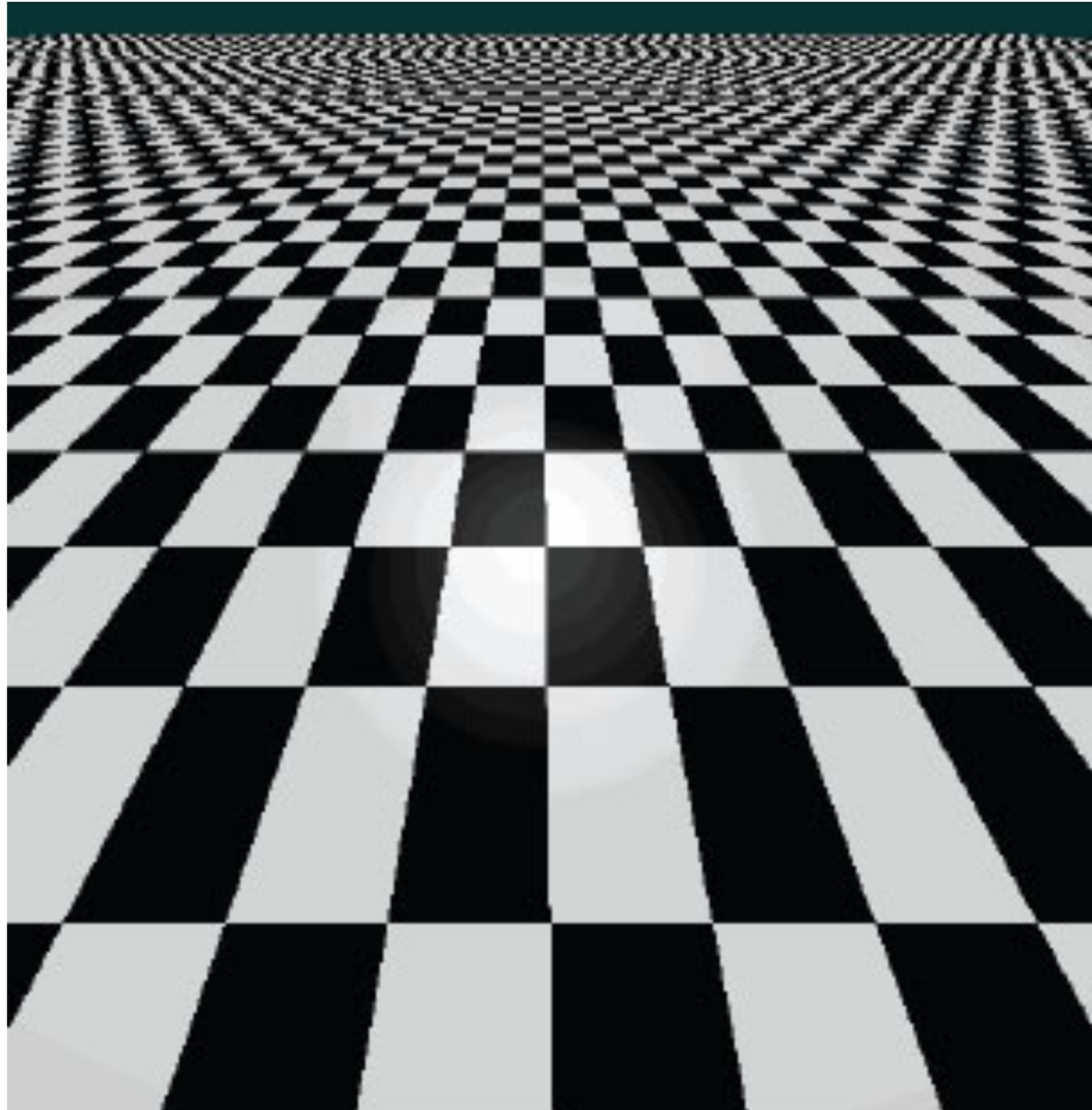
How to Prevent **Aliasing**?

1. **Reduce the maximum frequency**, by low pass filtering i.e., **Smoothing** before sampling.

How to Prevent **Aliasing**?

1. **Reduce the maximum frequency**, by low pass filtering i.e., **Smoothing** before sampling.
2. **Sample more frequently** i.e., oversampling — sample more than you think you need and average (i.e., area sampling)

Aliasing



aliasing artifacts



anti-aliasing by oversampling

Temporal Aliasing



Temporal Aliasing



Temporal Aliasing



Temporal Aliasing



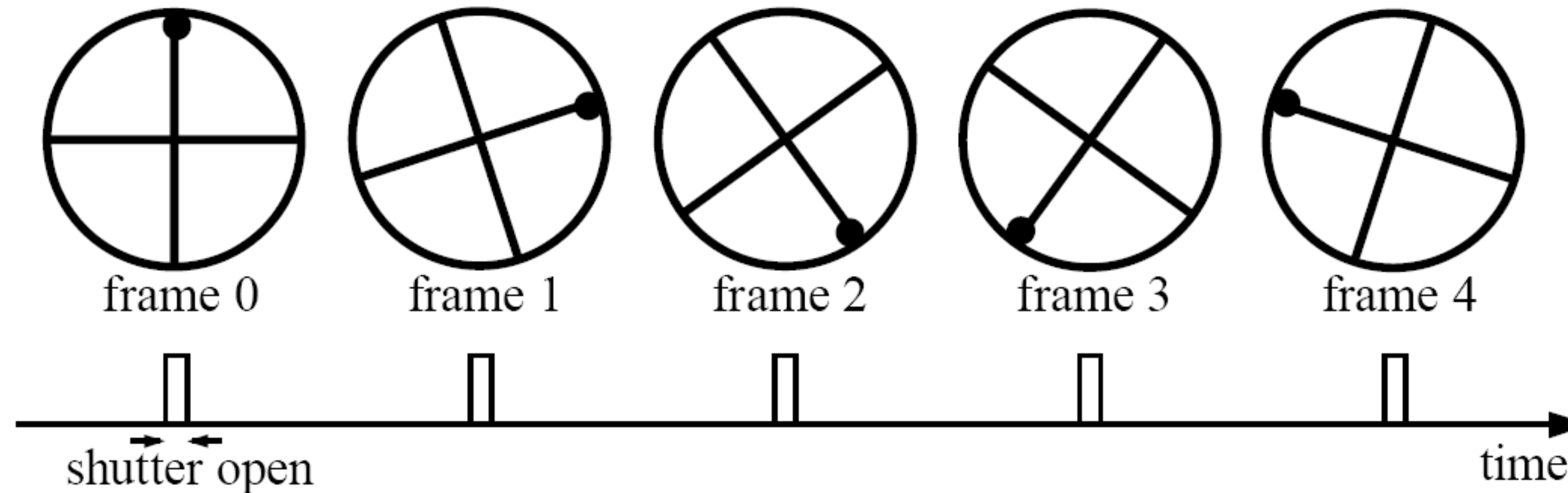
Temporal Aliasing



Temporal Aliasing

Imagine a spoked wheel moving to the right (rotating clockwise).
Mark wheel with dot so we can see what's happening.

If camera shutter is only open for a fraction of a frame time (frame time = $1/30$ sec. for video, $1/24$ sec. for film):



Without dot, wheel appears to be rotating slowly backwards!
(counterclockwise)

Sampling Theory (informal)

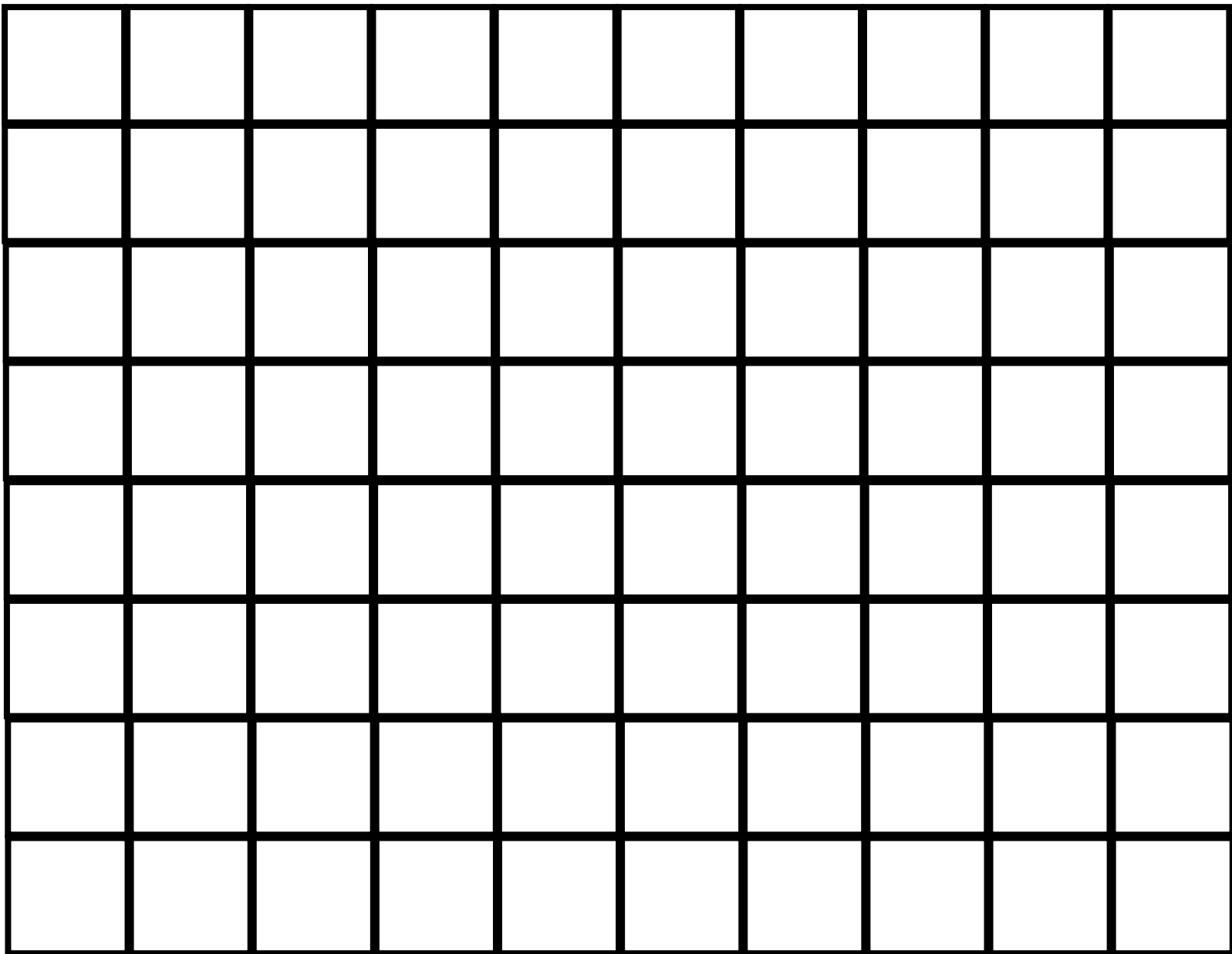
Sometimes **undersampling** is unavoidable, and there is a trade-off between “things missing” and “artifacts.”

- **Medical imaging:** usually try to maximize information content, tolerate some artifacts

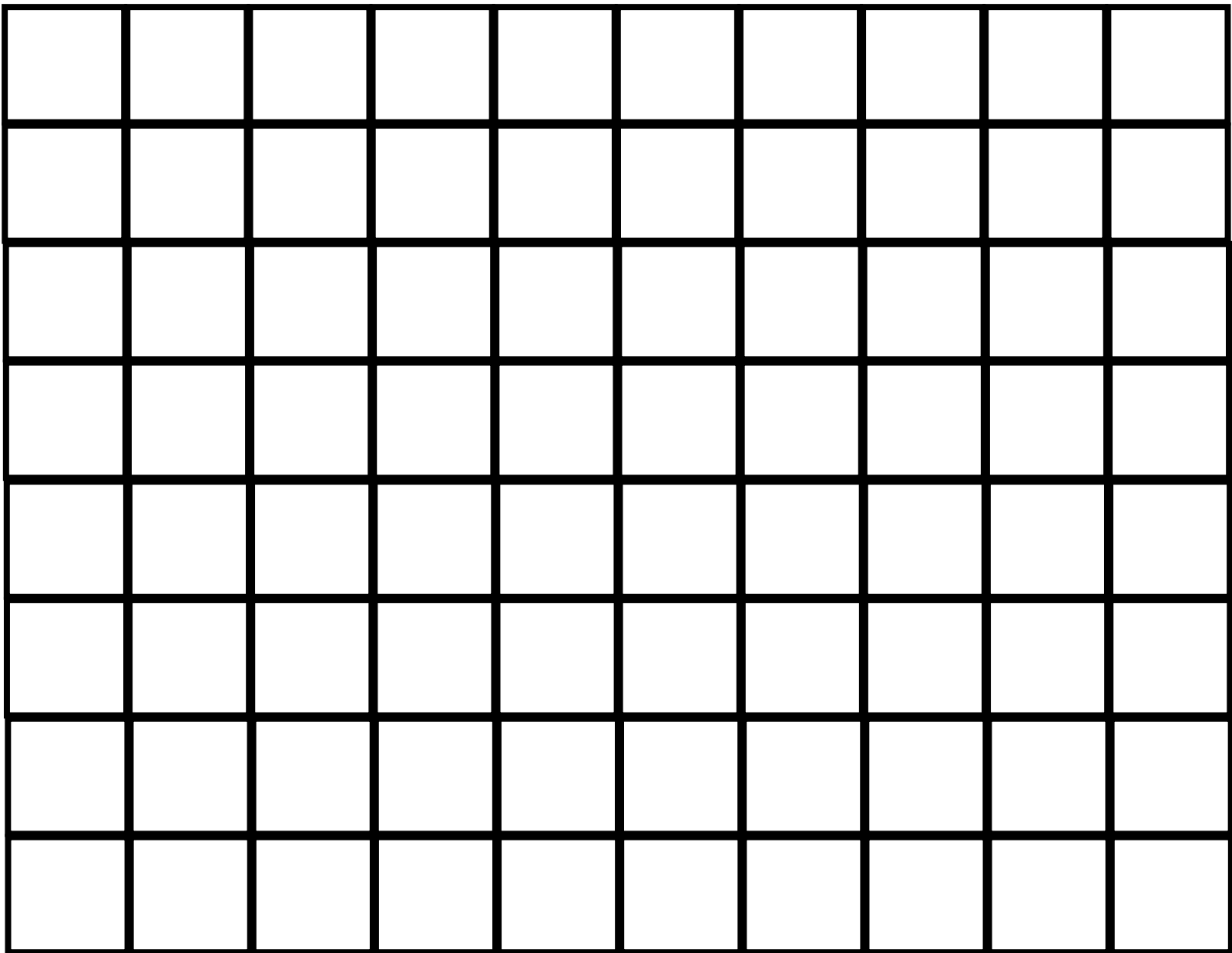
- **Computer graphics:** usually try to minimize artifacts, tolerate some information missing

Example

Sensor Resolution: 10 x 8



Sensor Resolution: 10 x 8



Example

Sensor Resolution: 10 x 8

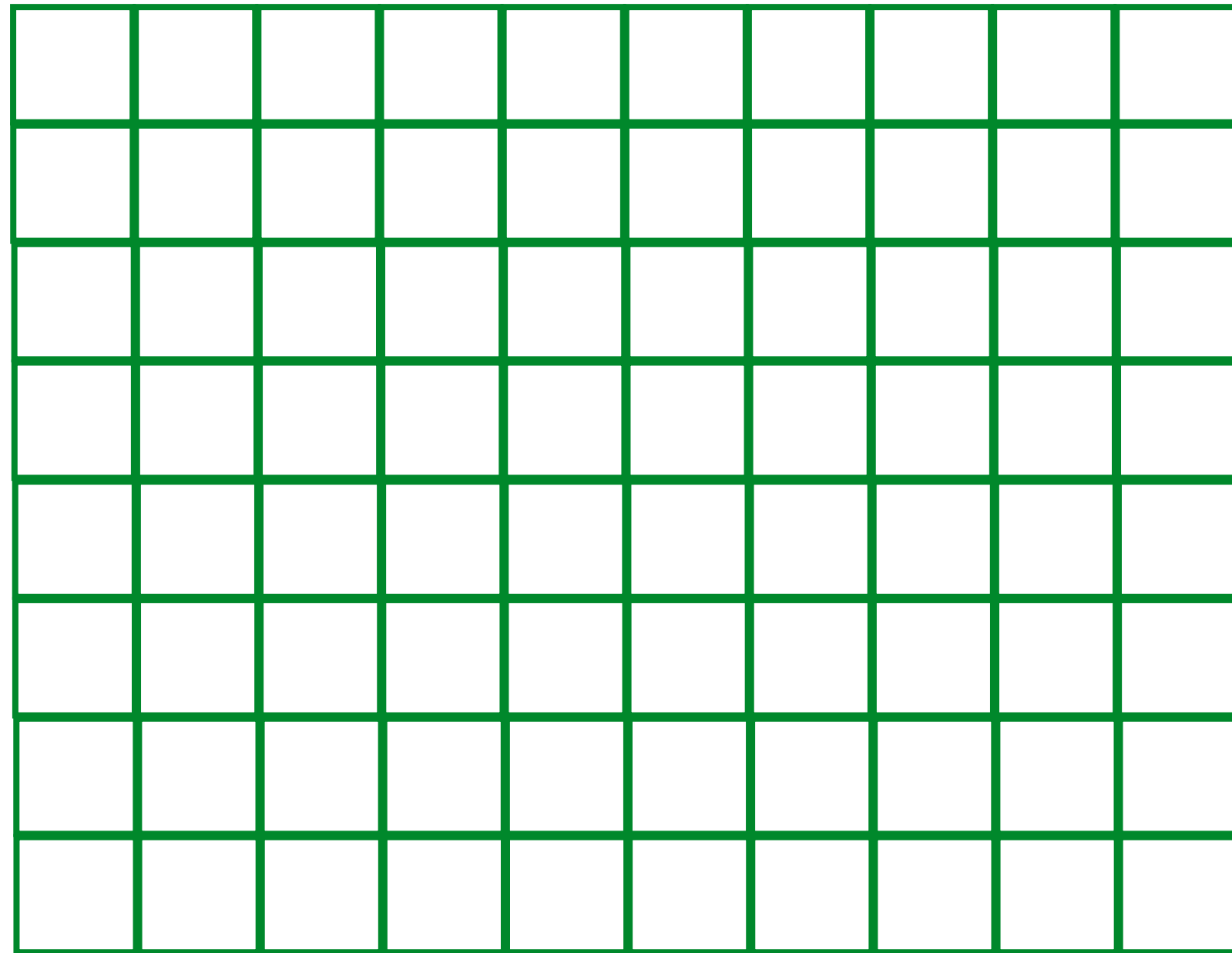


Image Resolution: 10 x 8

Sensor Resolution: 10 x 8

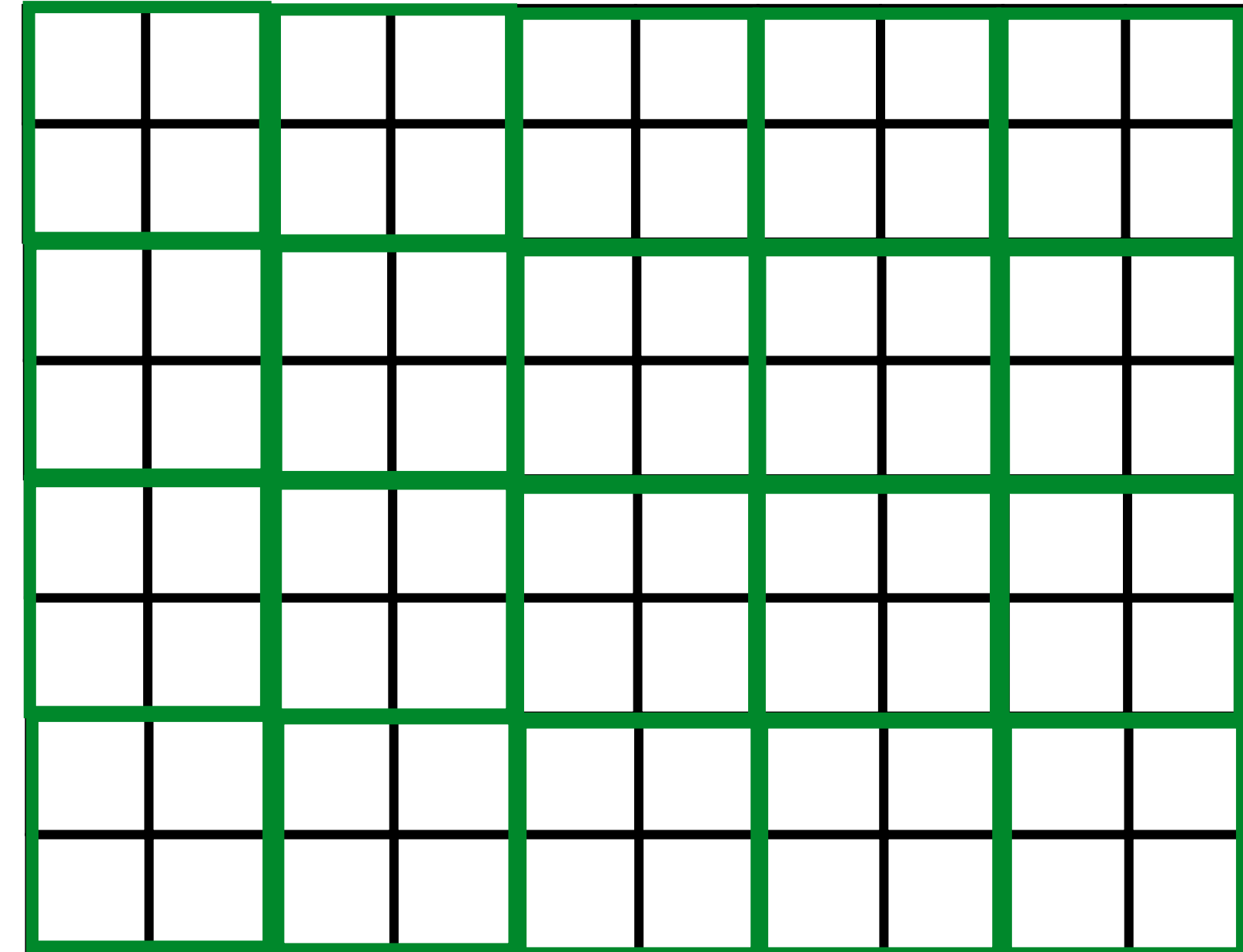
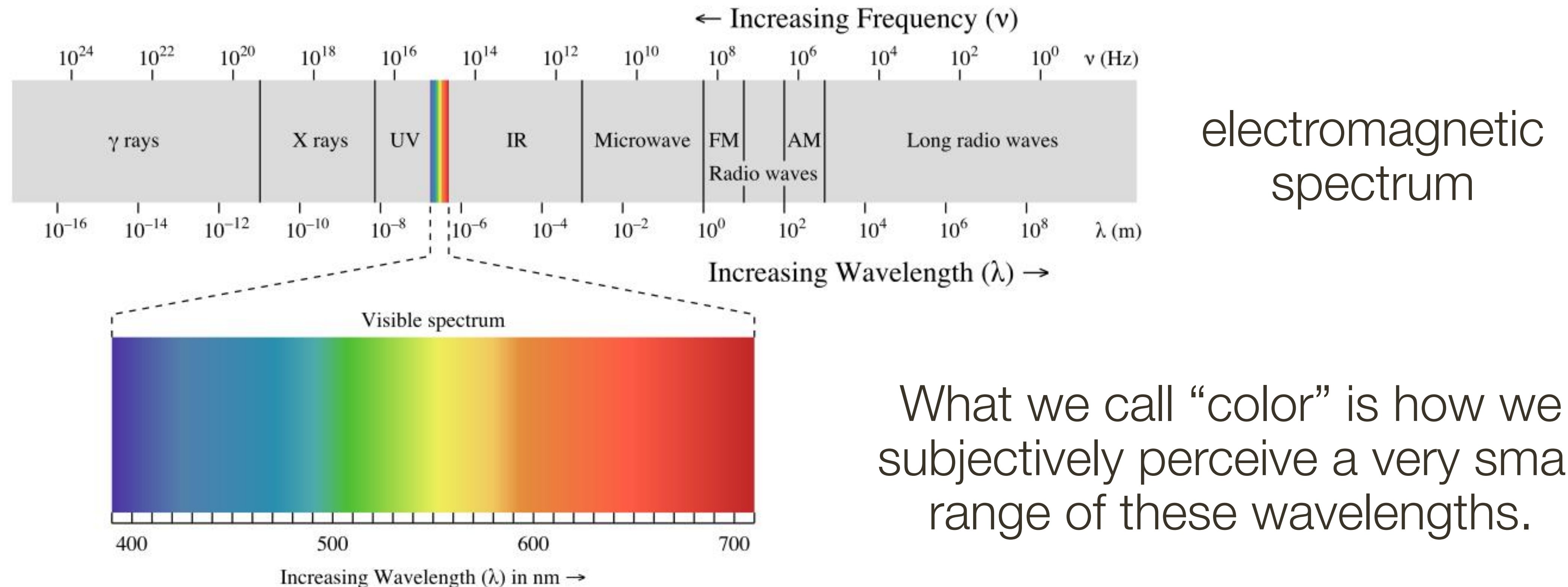


Image Resolution: 5 x 4

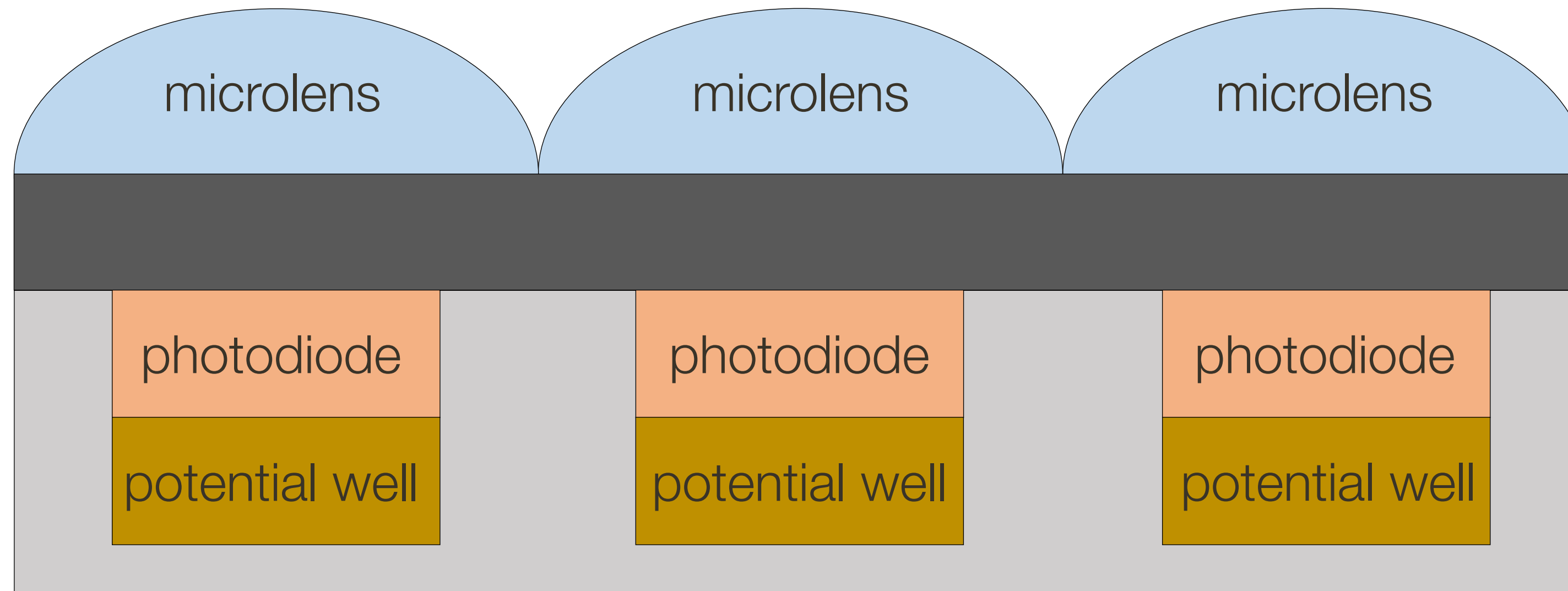
Color is an Artifact of Human Perception

“Color” is **not** an objective physical property of light (electromagnetic radiation). Instead, light is characterized by its wavelength.



What we call “color” is how we subjectively perceive a very small range of these wavelengths.

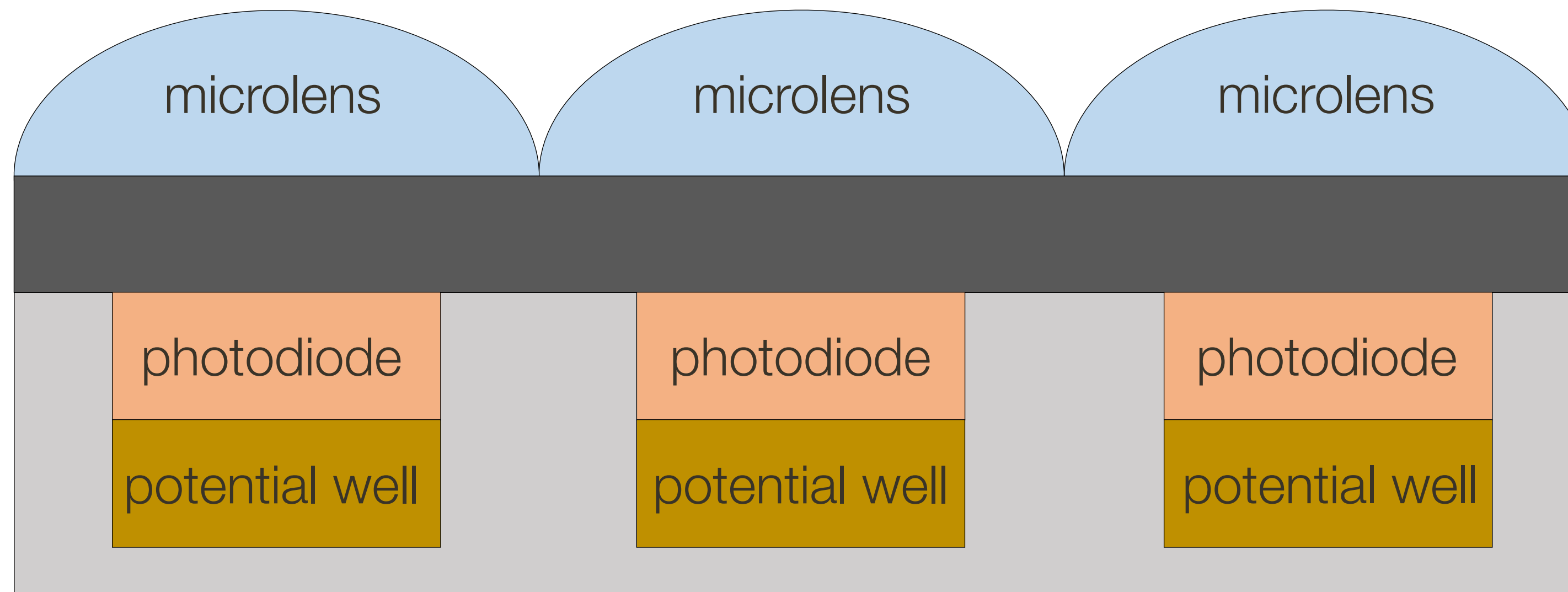
Color Filter Arrays (CFA)



Color Filter Arrays (CFA)

In addition to a camera lens,

each pixel has a microns

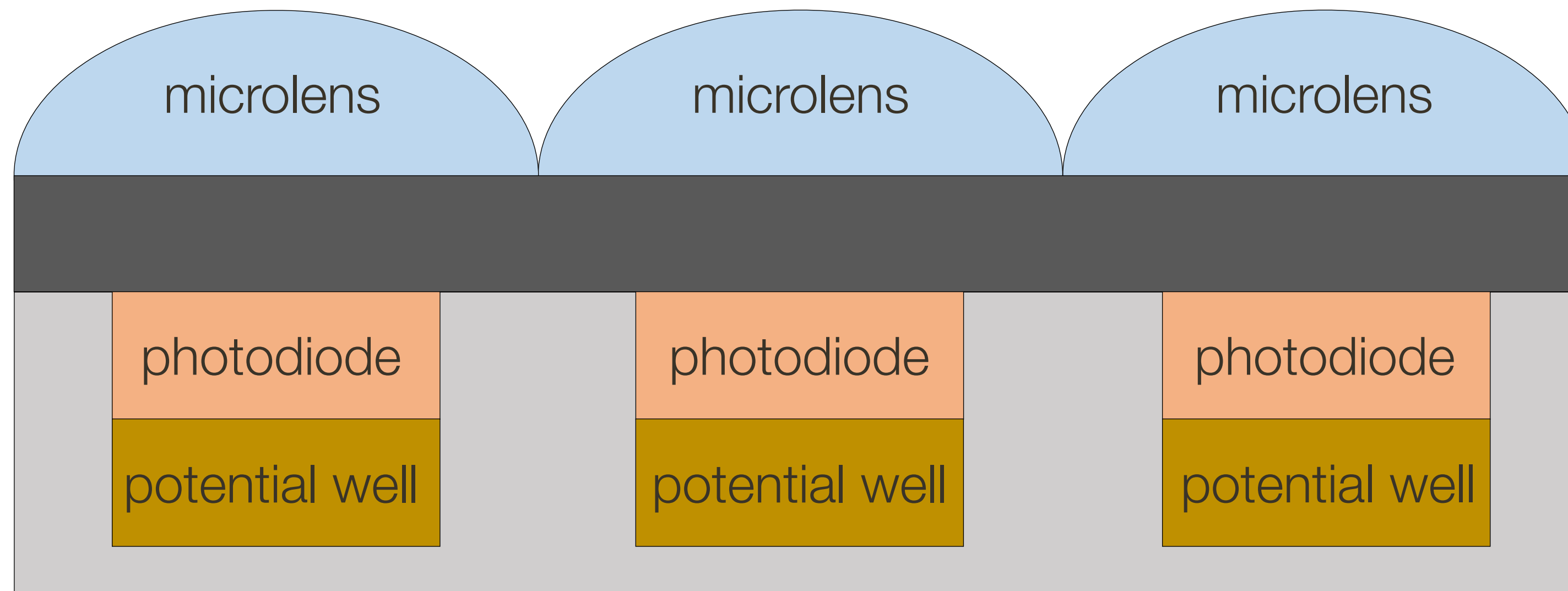


Color Filter Arrays (CFA)

In addition to a camera lens,

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Photodiode: converts
photons to electrons



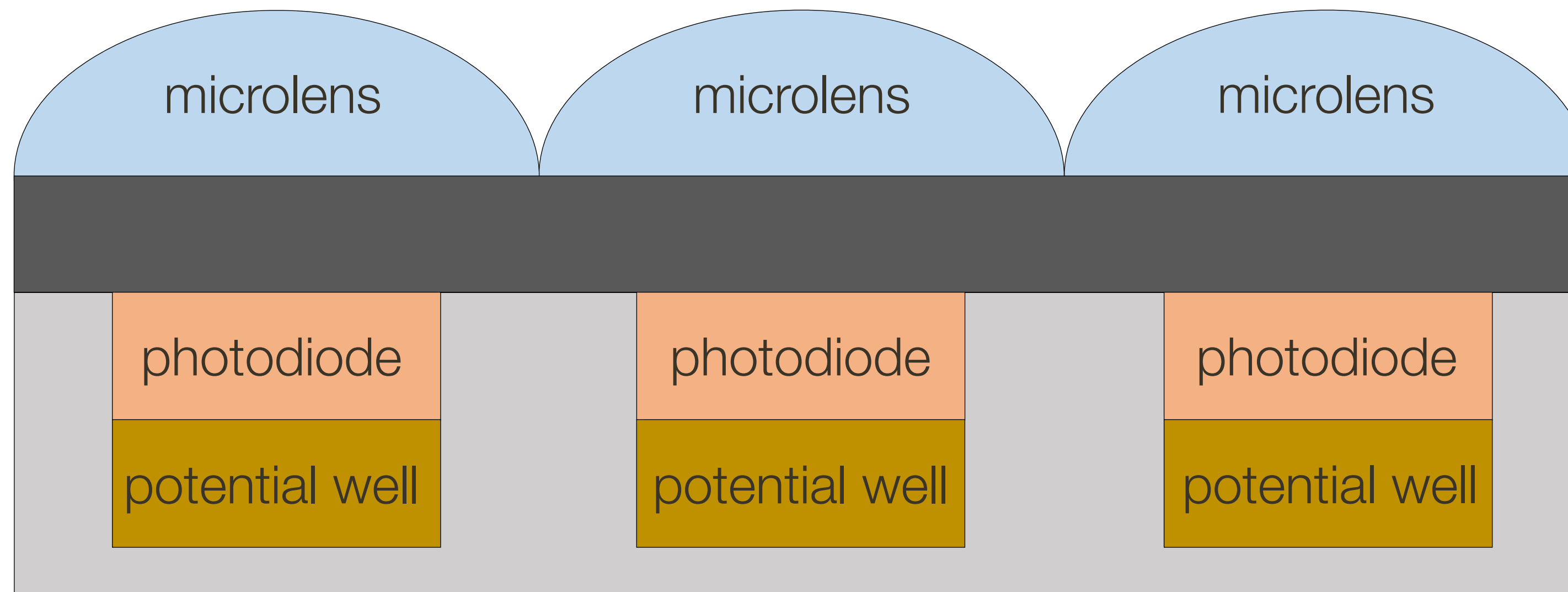
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Electrons stored in the **potential well**, until they are read off



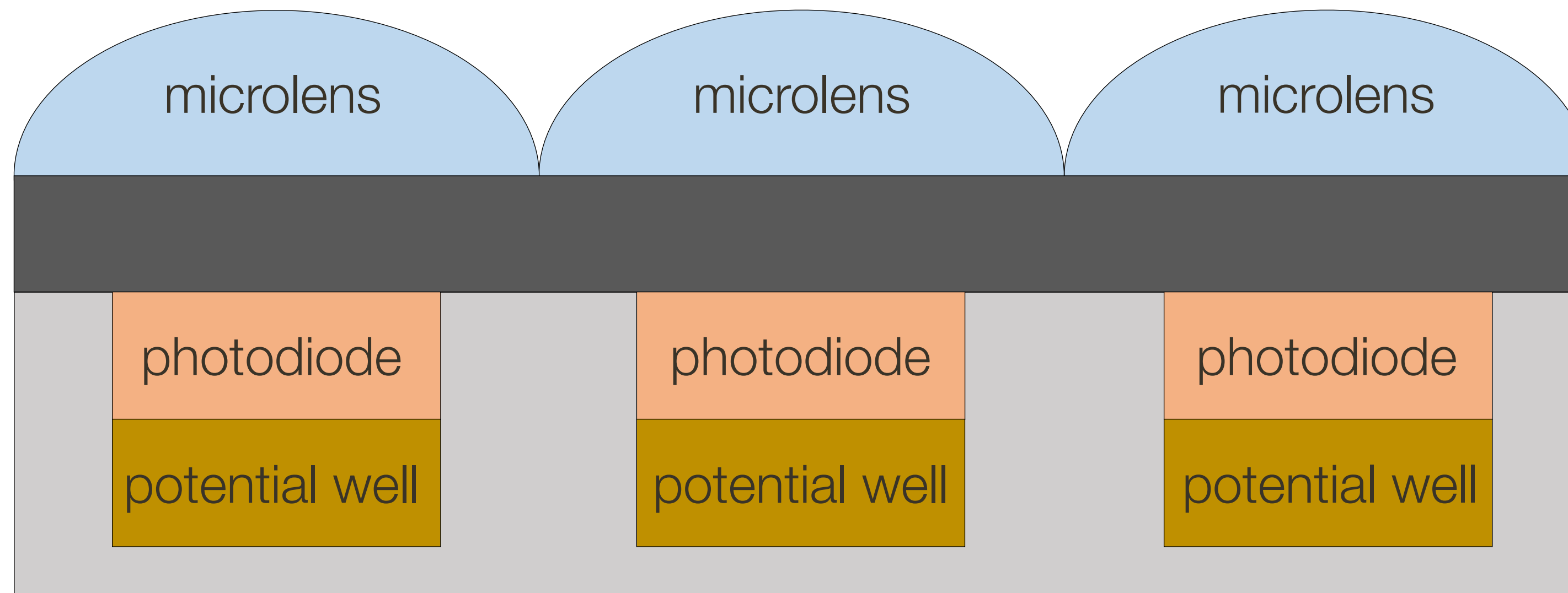
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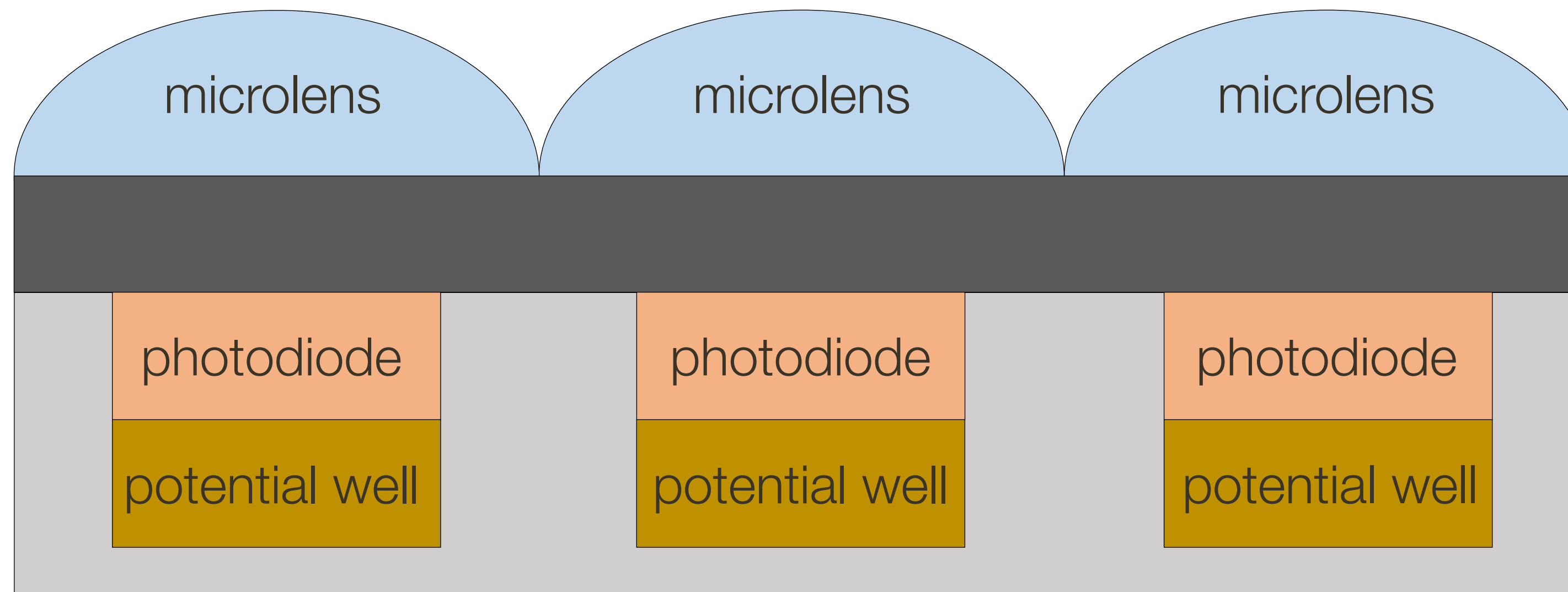
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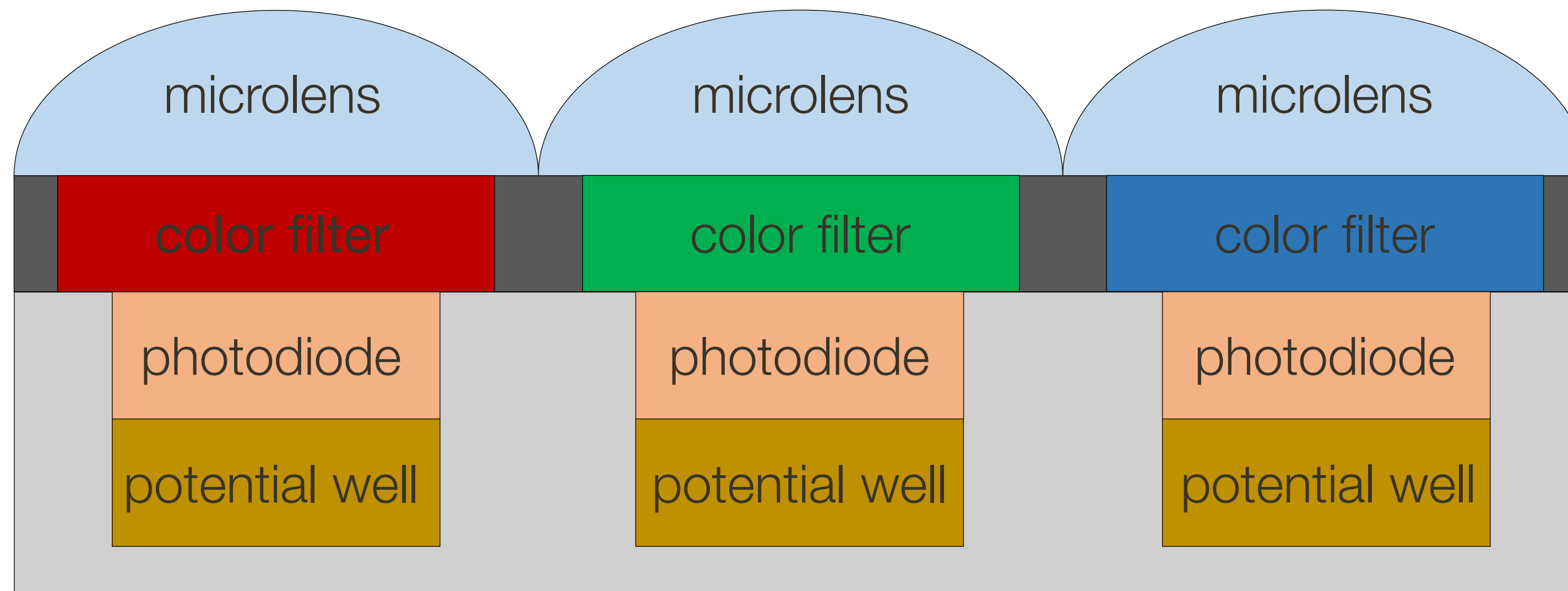
Quantum efficiency: fraction of photons being “detected” through this process
(human eye QE: 20%, film cameras QE: 10%, CCD QE: 80%)

Color Filter Arrays (CFA)

Issue: Color Filter Array (SFA) by itself has no way of distinguishing wavelengths of light, just ability to record the amount of light incident on an element

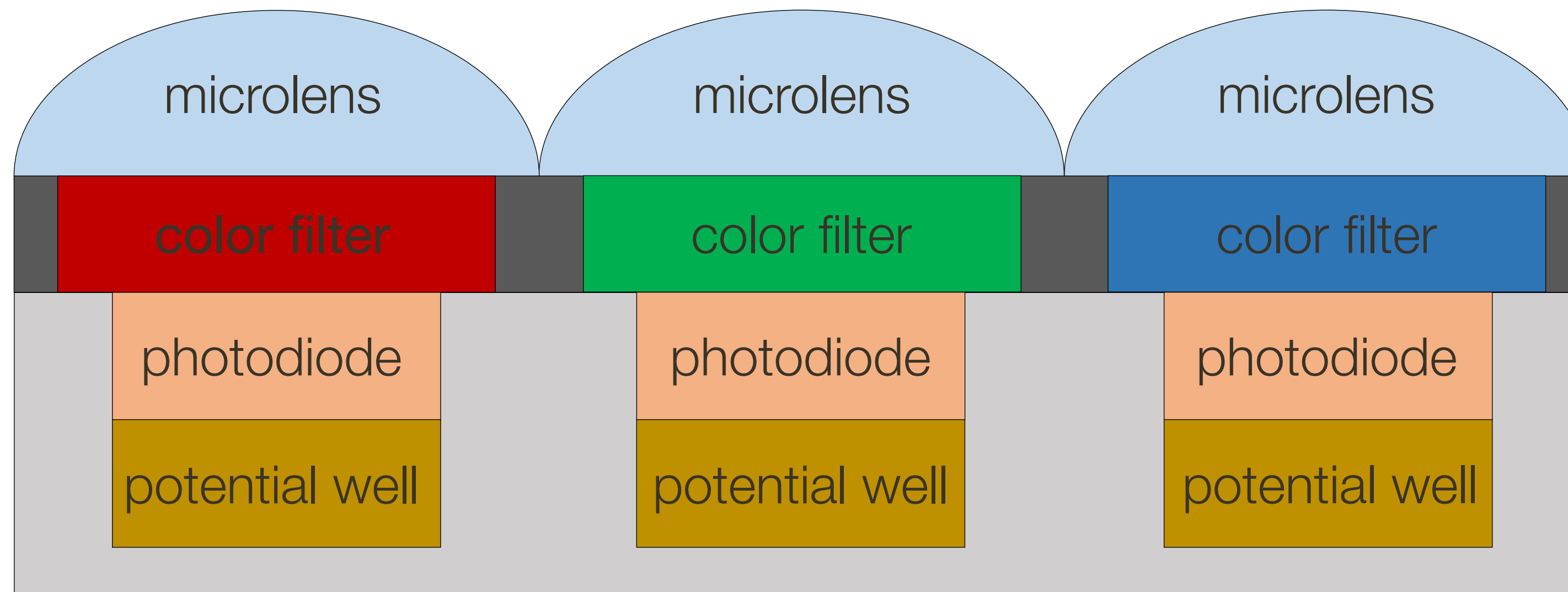


Color Filter Arrays (CFA)



Color Filter Arrays (CFA)

Implication: Only certain wavelengths of light are recorded at a given pixel



Color Filters

Two **design choices**:

- What spectral sensitivity functions $f(\lambda)$ to use for each color filter?
- How to spatially arrange (“**mosaic**”) different color filters?

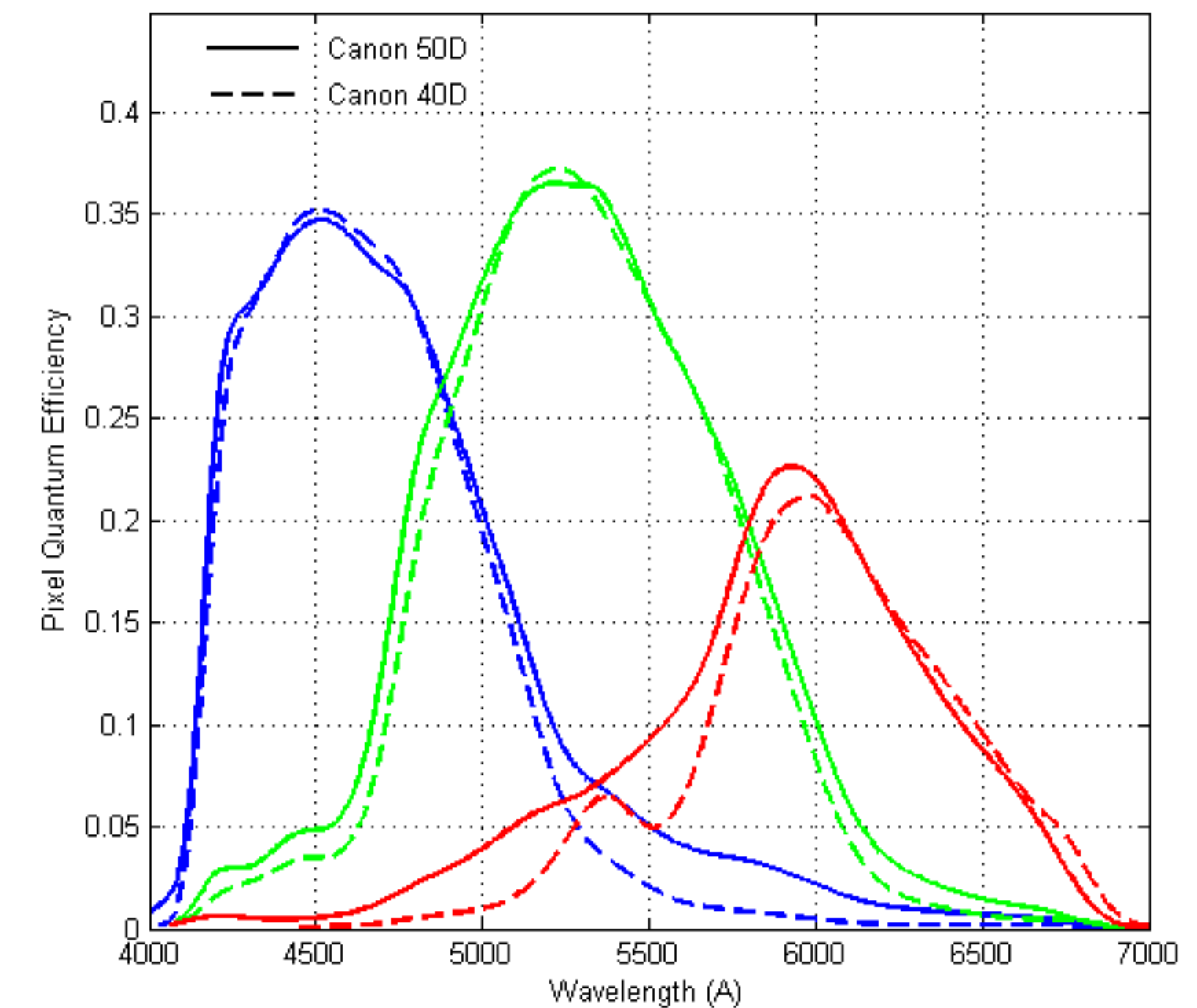
Color Filters

Two **design choices**:

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Generally do not
match human
sensitivity

Canon 50D

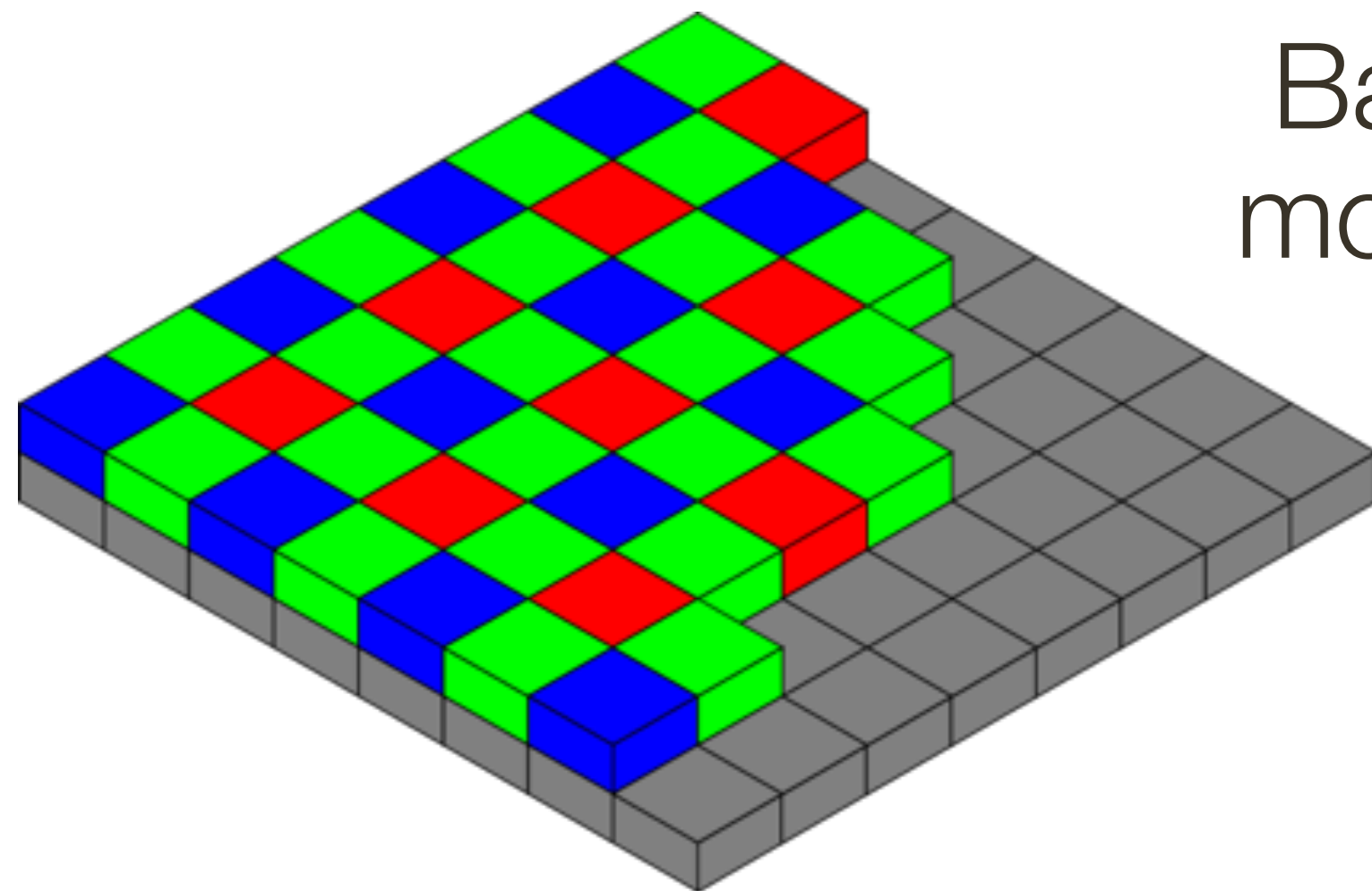


$f(\lambda)$

Color Filters

Two **design choices**:

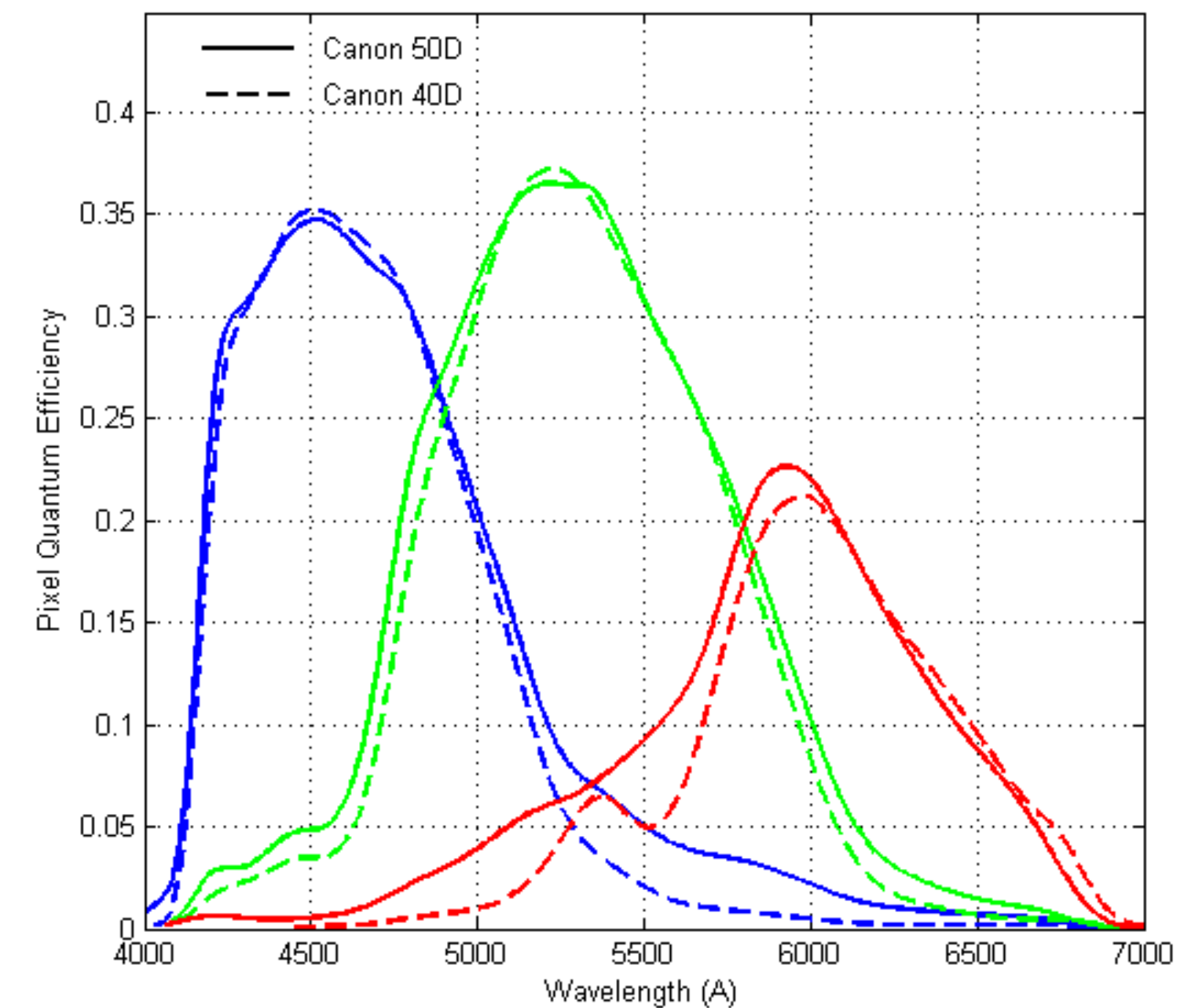
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Bayer
mosaic

Generally do not
match human
sensitivity

Canon 50D

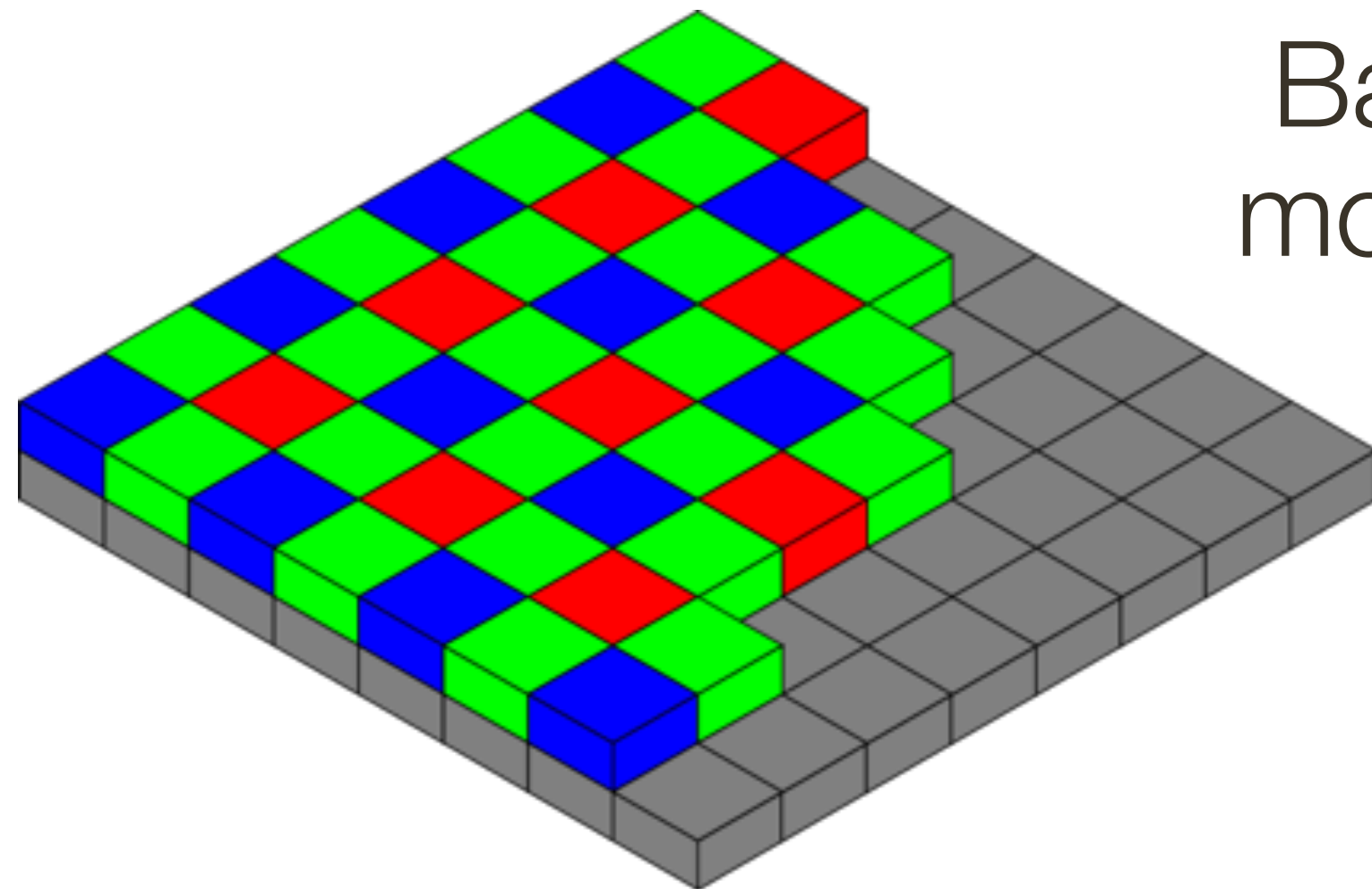


$$f(\lambda)$$

Color Filters

Two **design choices**:

- What spectral sensitivity functions $f(\lambda)$ to use for each color filter?
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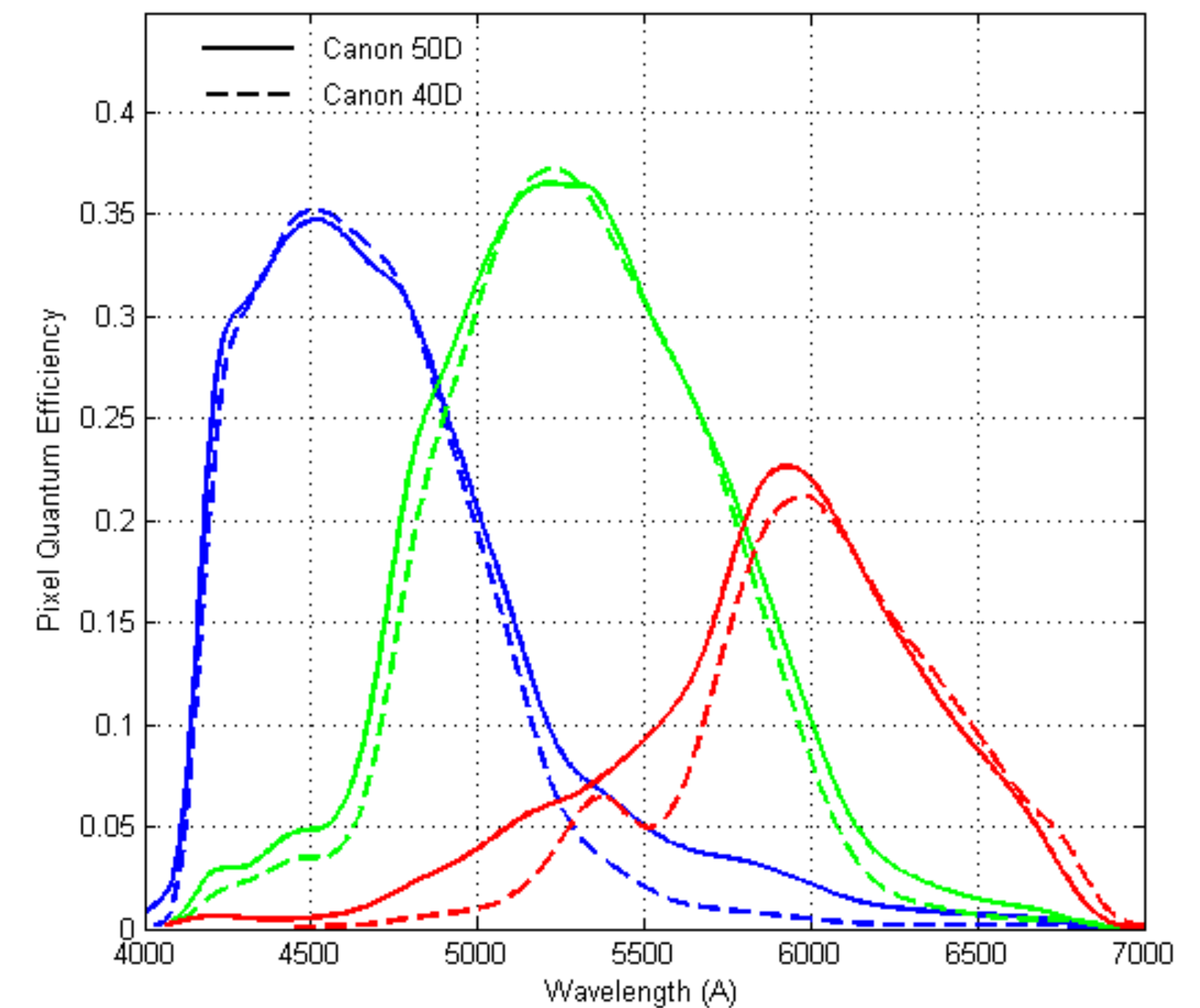


Bayer
mosaic

Why more
green pixels?

Generally do not
match human
sensitivity

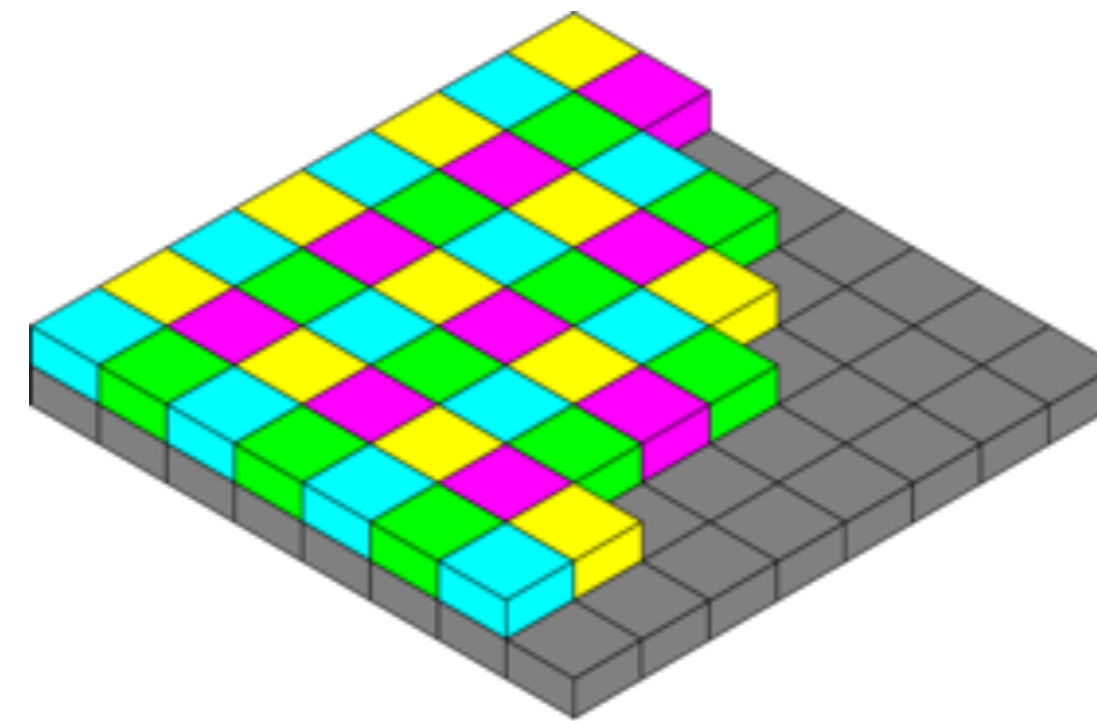
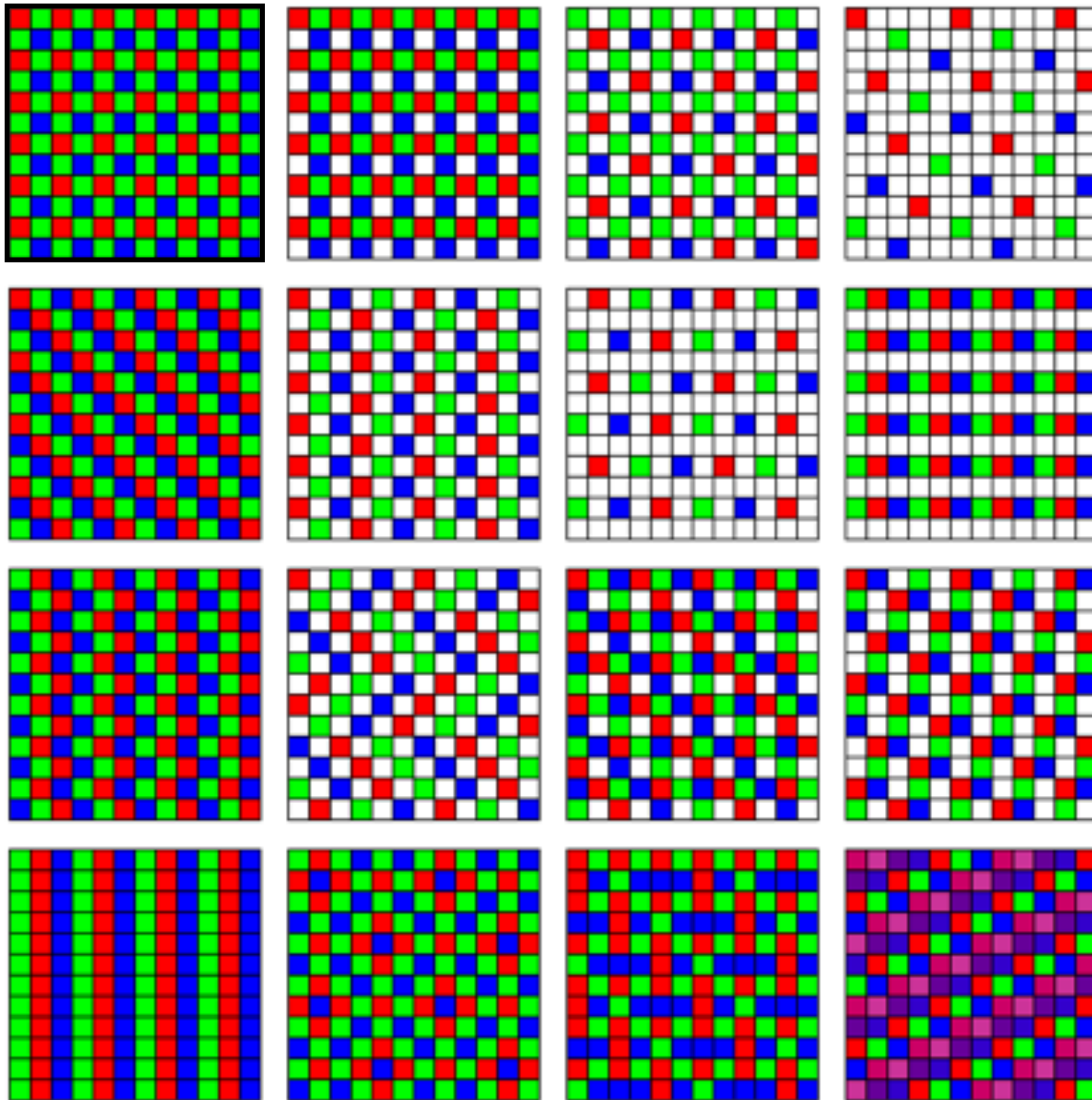
Canon 50D



$f(\lambda)$

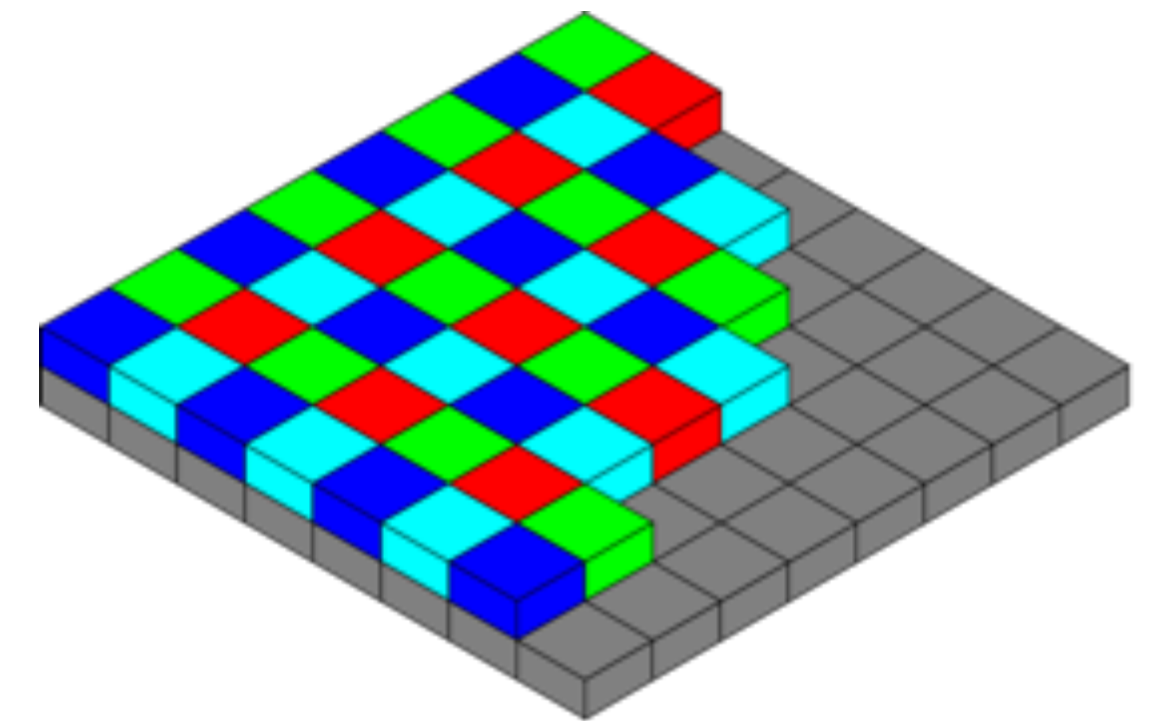
Different Color Filter Arrays (CFAs)

Finding the “**best**” CFA mosaic is an active research area.



CYGM

Canon IXUS, Powershot



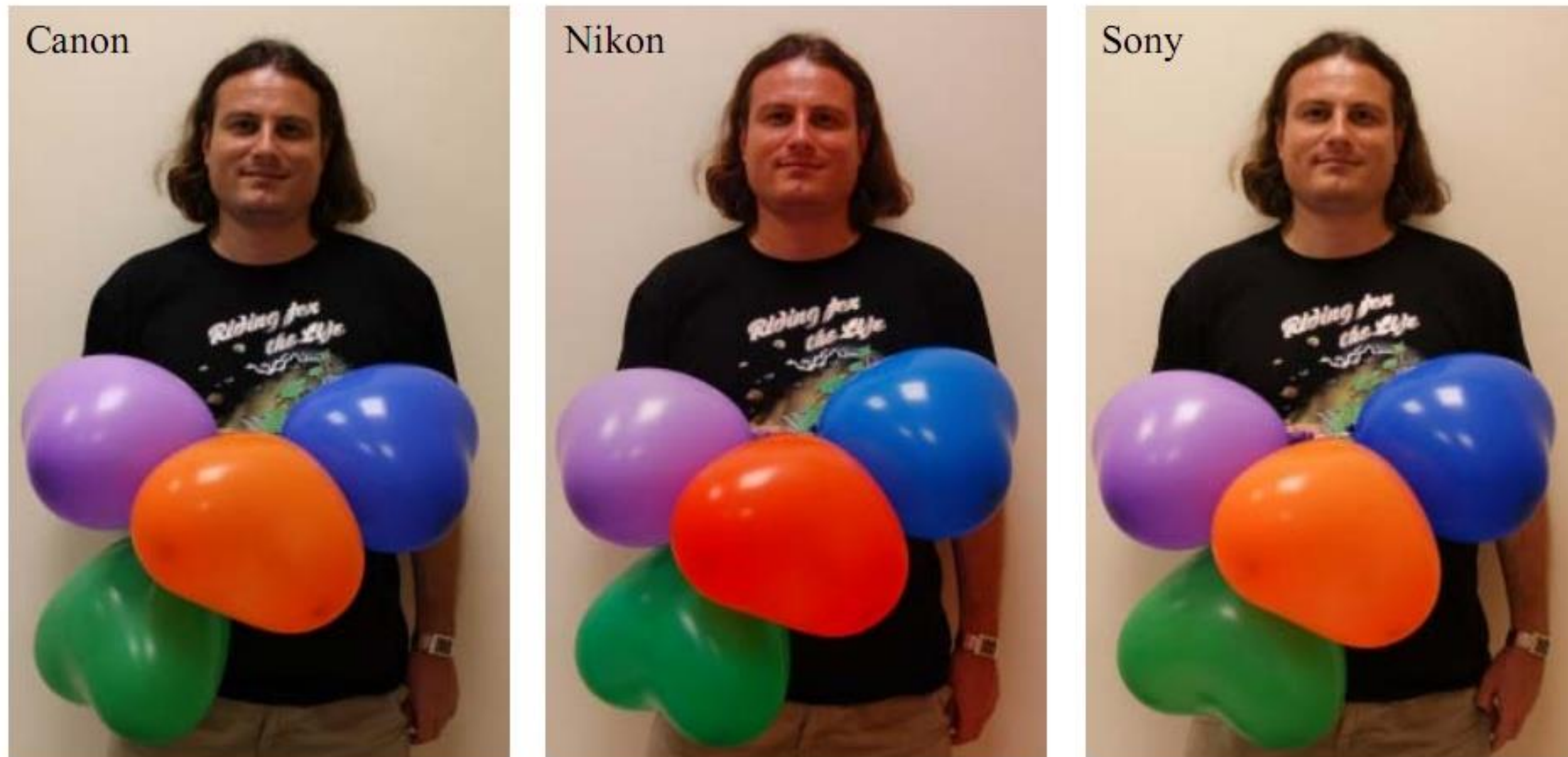
RGBE

Sony Cyber-shot

How would you go about designing your own CFA? What criteria would you consider?

Many **Different Spectral Sensitivity** Functions

Each camera has its more or less unique, and most of the time secret, SSF



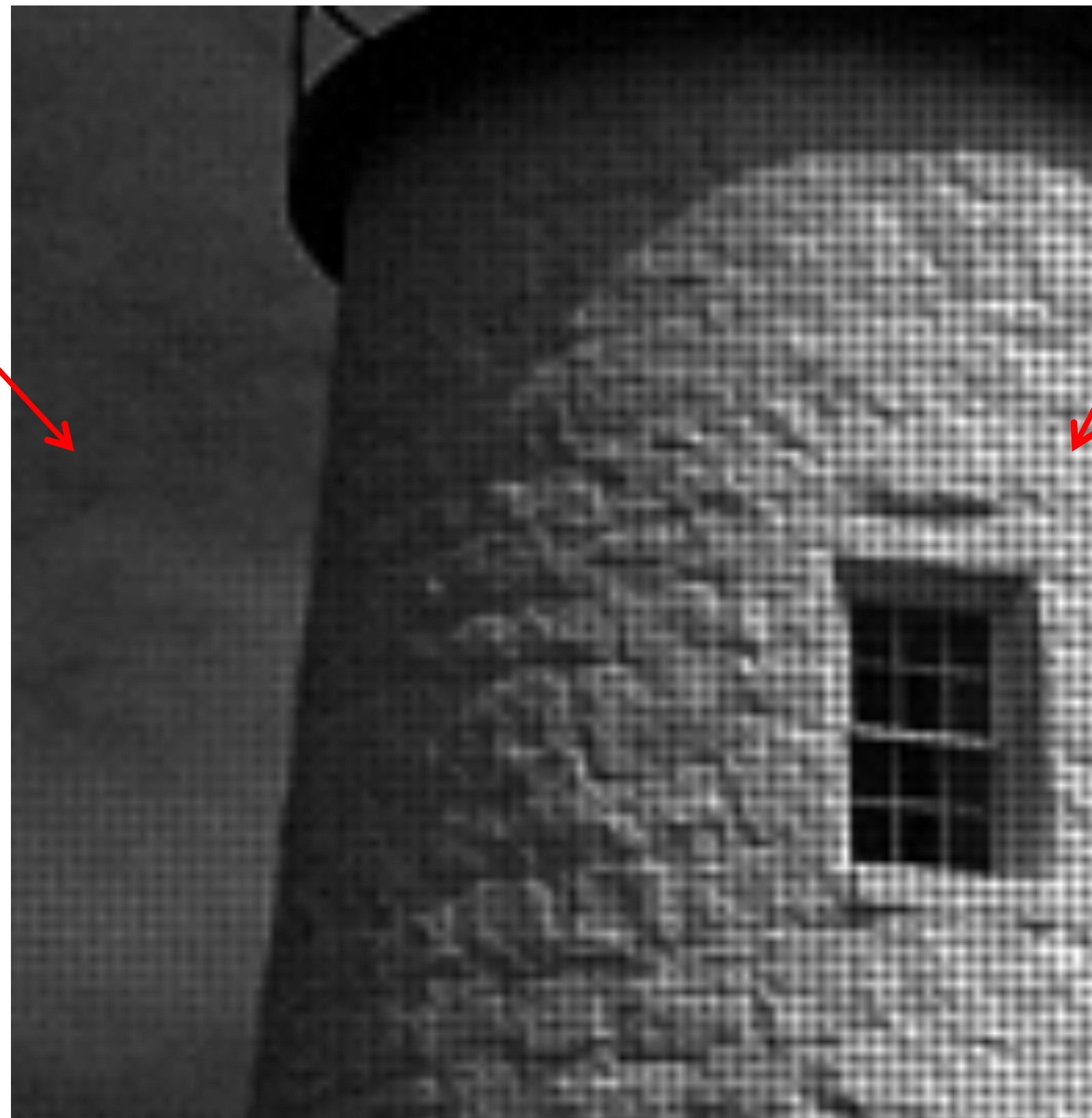
Same scene captured using 3 different cameras with identical settings

RAW Bayer Image

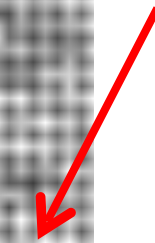
After all of this, what does an image look like?



lots of noise



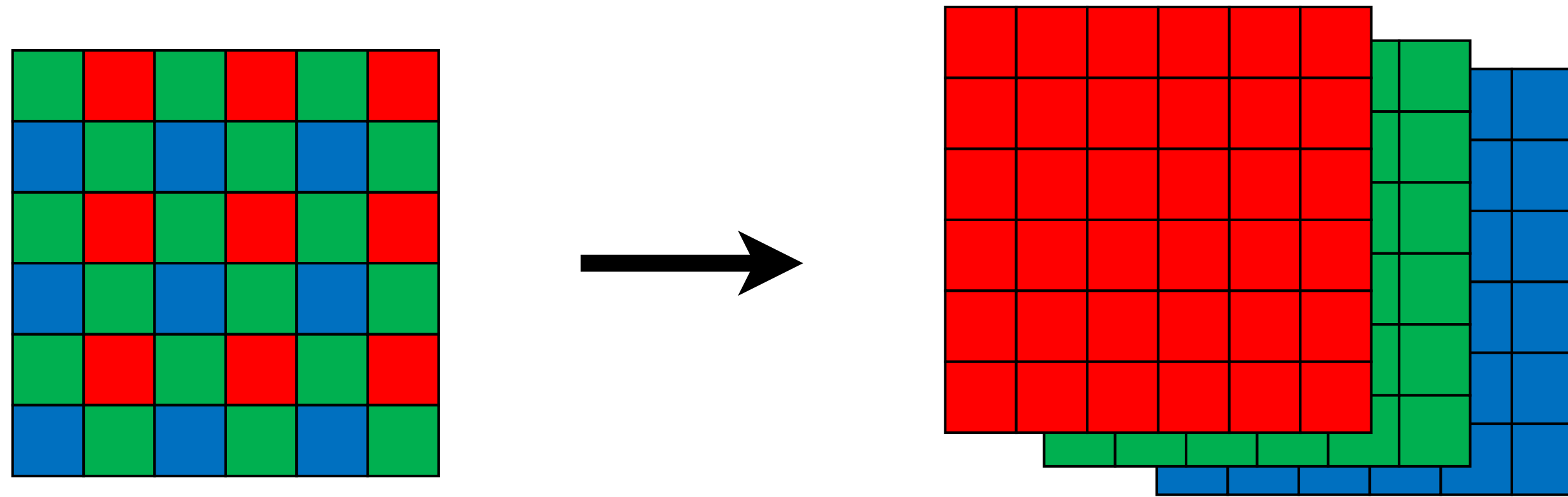
mosaicking artifacts



- Kind of disappointing
- We call this the RAW image

CFA Demosicing

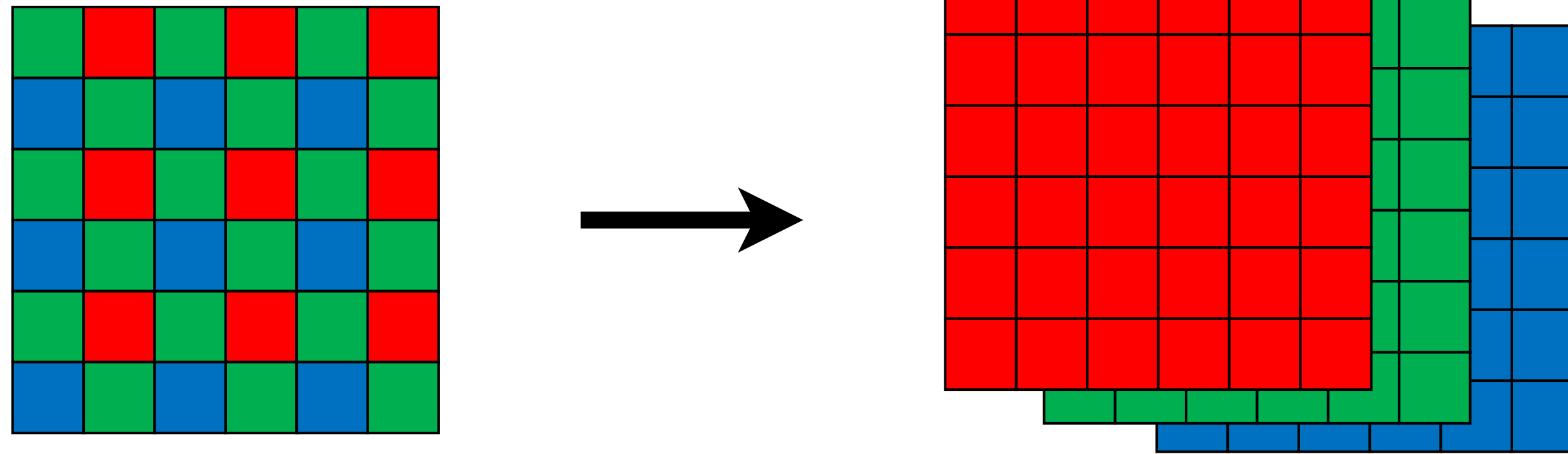
Produce full RGB image from mosaiced sensor output



Any ideas on how to do this?

CFA Demosicing

Produce full RGB image from mosaiced sensor output

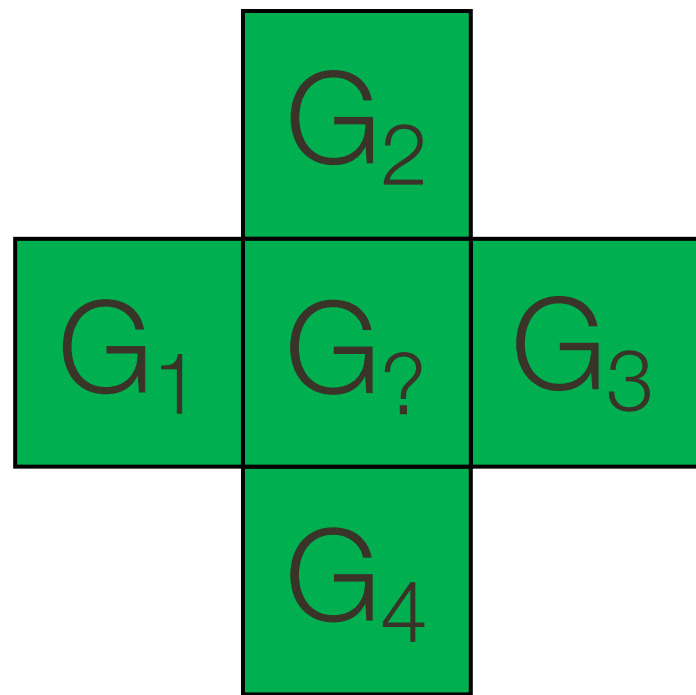


Interpolate from neighbors:

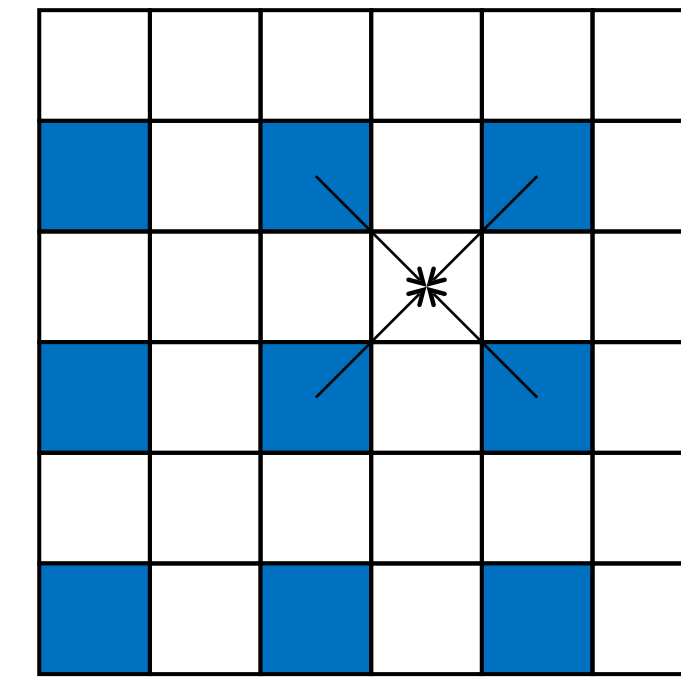
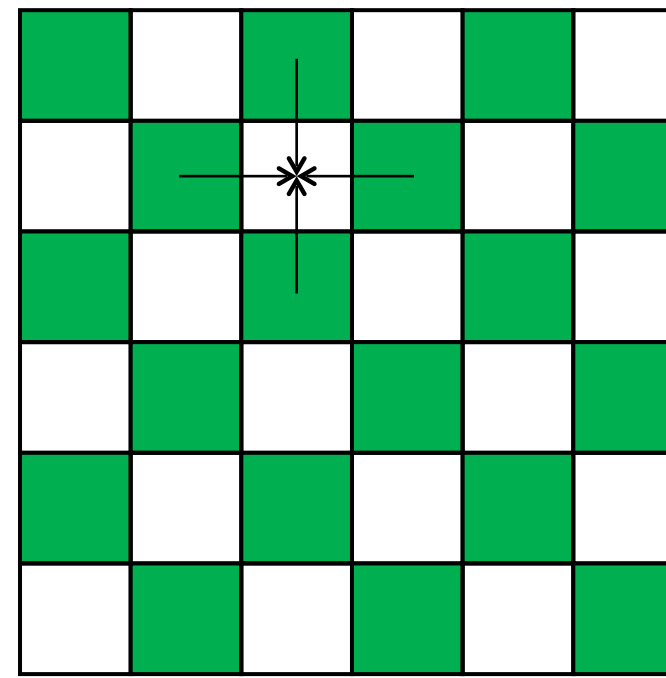
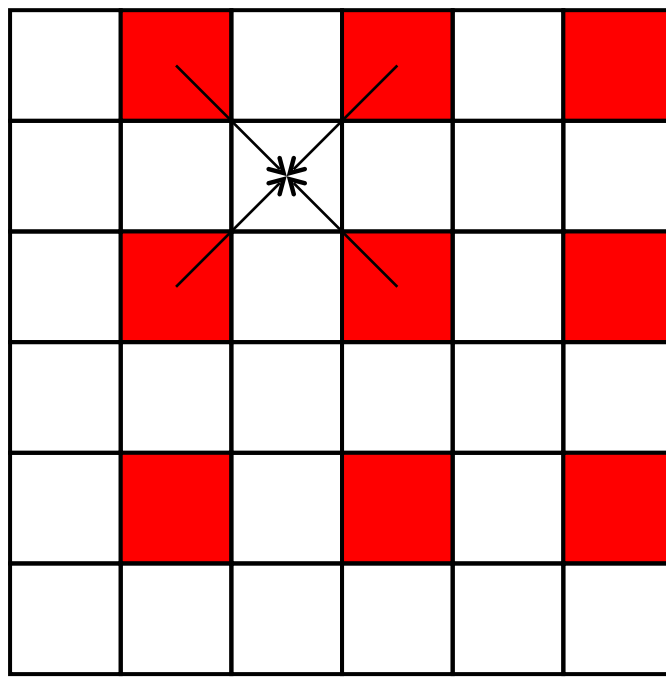
- Bilinear interpolation (needs 4 neighbors)
- Bicubic interpolation (needs more neighbors, may overblur)
- Edge-aware interpolation (e.g., Bilateral)

Demosaicing by Bilinear Interpolation

Bilinear interpolation: Simply average your 4 neighbors.

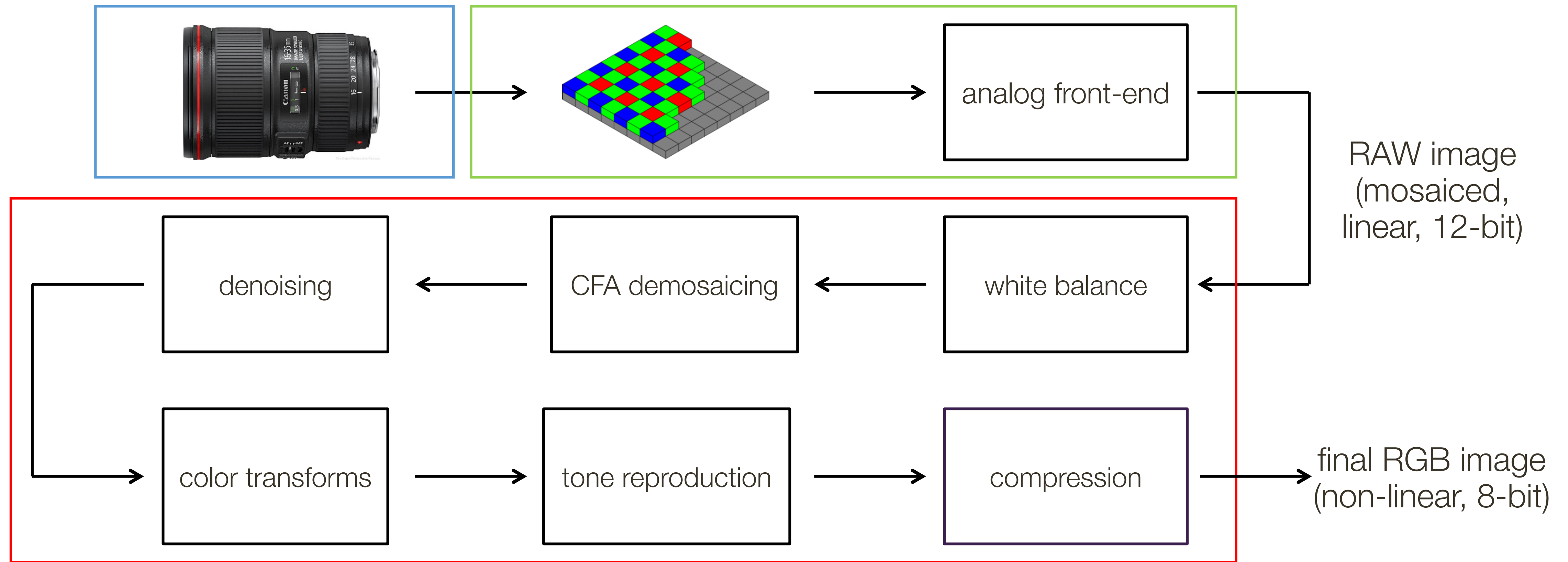

$$G_{?} = \frac{G_1 + G_2 + G_3 + G_4}{4}$$

Neighborhood changes for different channels:



(in camera) **Image** Processing Pipeline

The sequence of image processing operations applied by the camera's image signal processor (ISP) to convert a RAW image into a “conventional” image.



(in camera) **White** balance

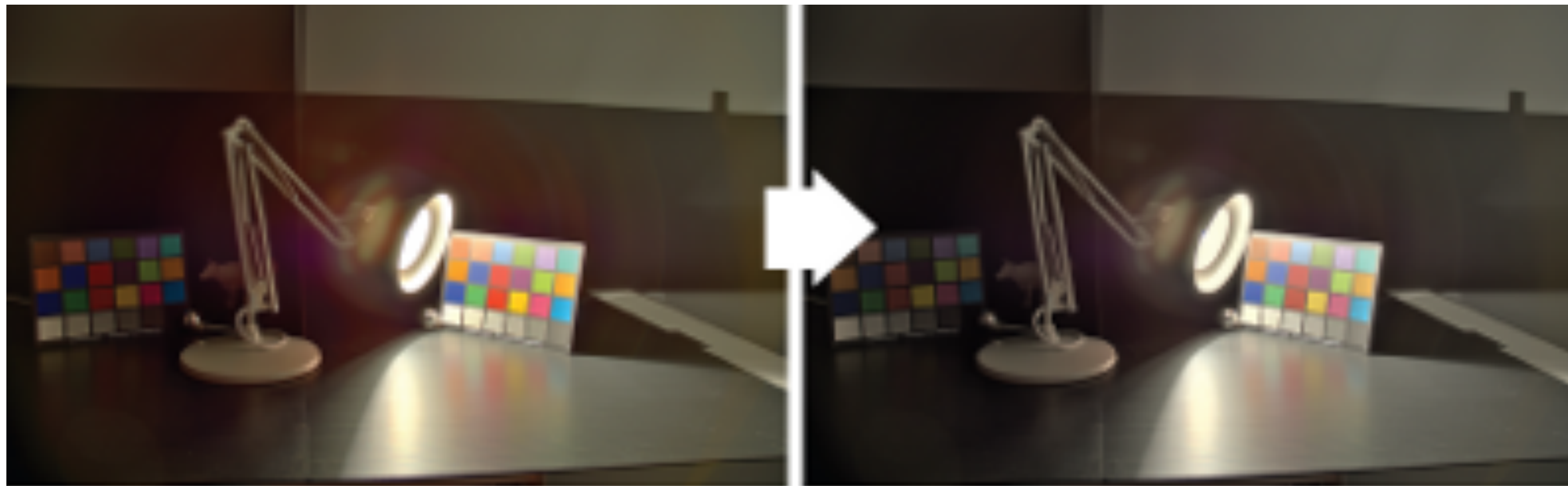


(in camera) **White** balance

R: 200 **R-correction:** + 55
G: 255 **G-correction:** + 0
B: 190 **B-correction:** + 65

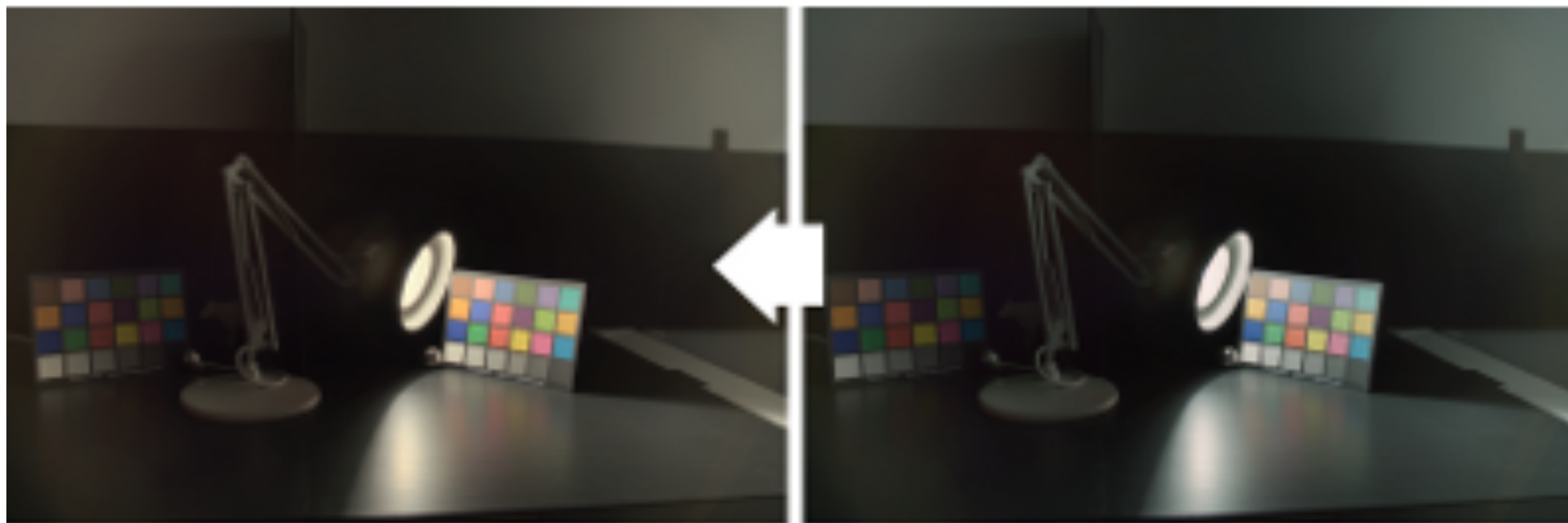


(in camera) **Tone** reproduction



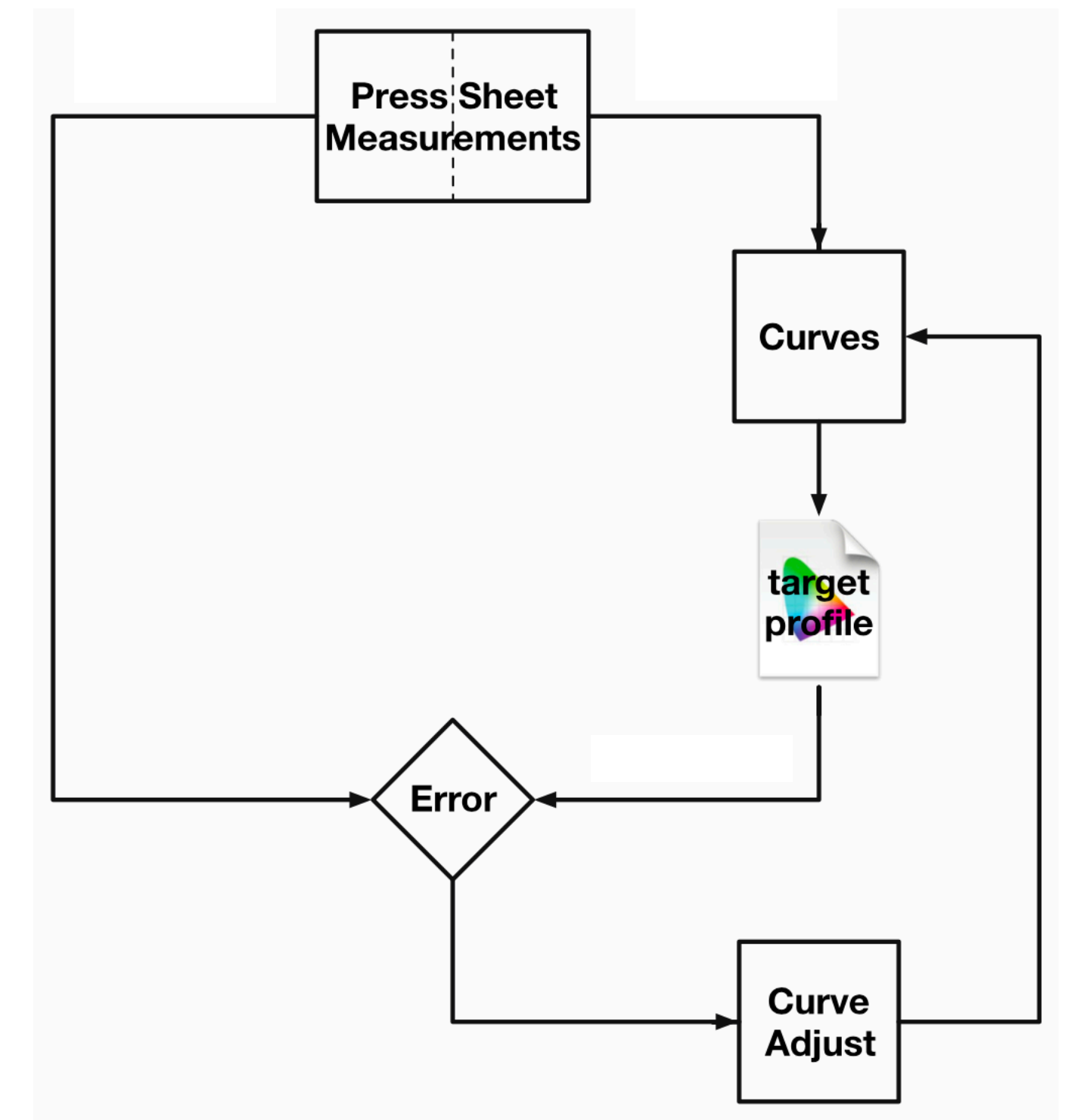
Tonemapped with
Li et al. 2005

Corrected
saturation reduced



Corrected
saturation enhanced

Tonemapped with
Reinhard et al. 2012



Summary

“Color” is **not** an objective physical property of light (electromagnetic radiation). Instead, light is characterized by its wavelength.

Color Filter Arrays (CFAs) allow capturing of mosaiced color information; the layout of the mosaic is called **Bayer** pattern.

Demosaicing is the process of taking the RAW image and interpolating missing color pixels per channel

