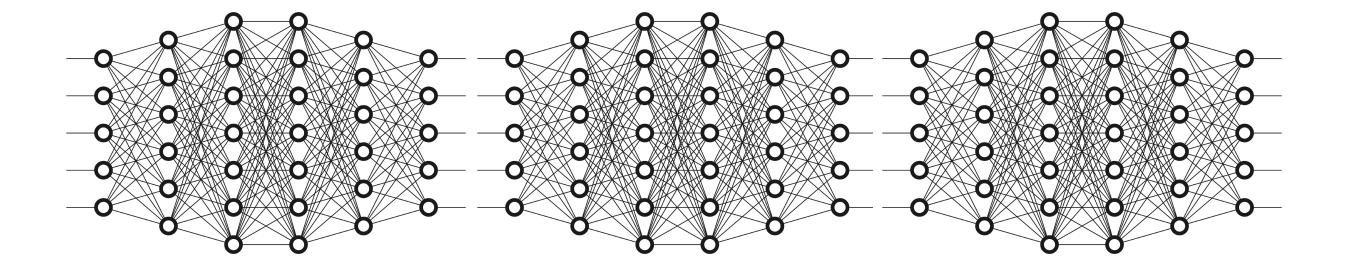


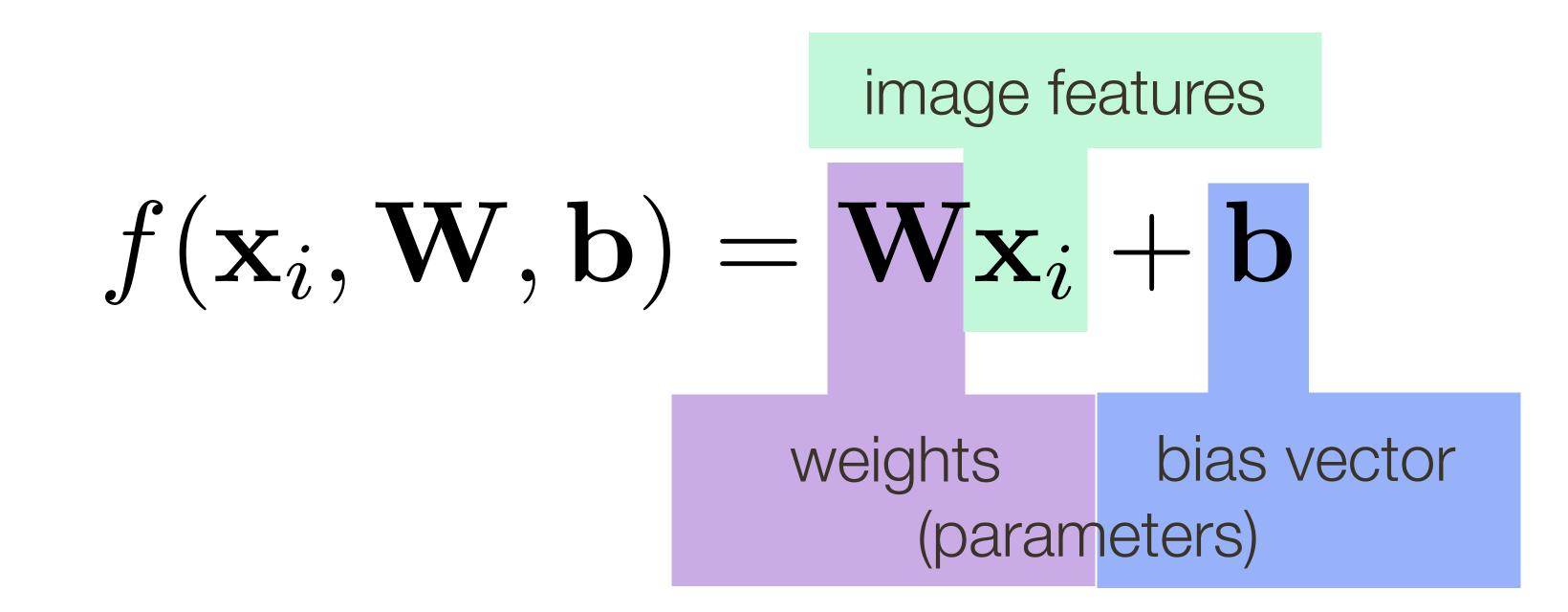
# CPSC 425: Computer Vision



Lecture 21: Neural Networks Intro

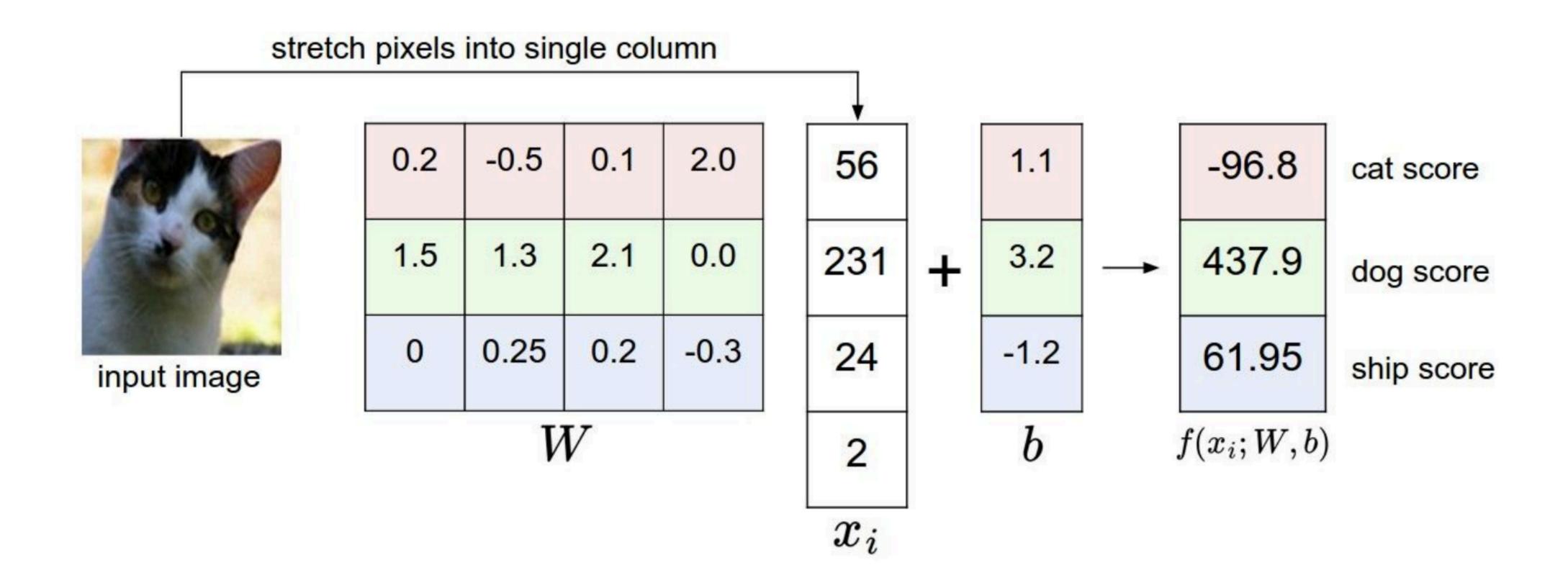
#### Recall: Linear Classifier

Defines a score function:

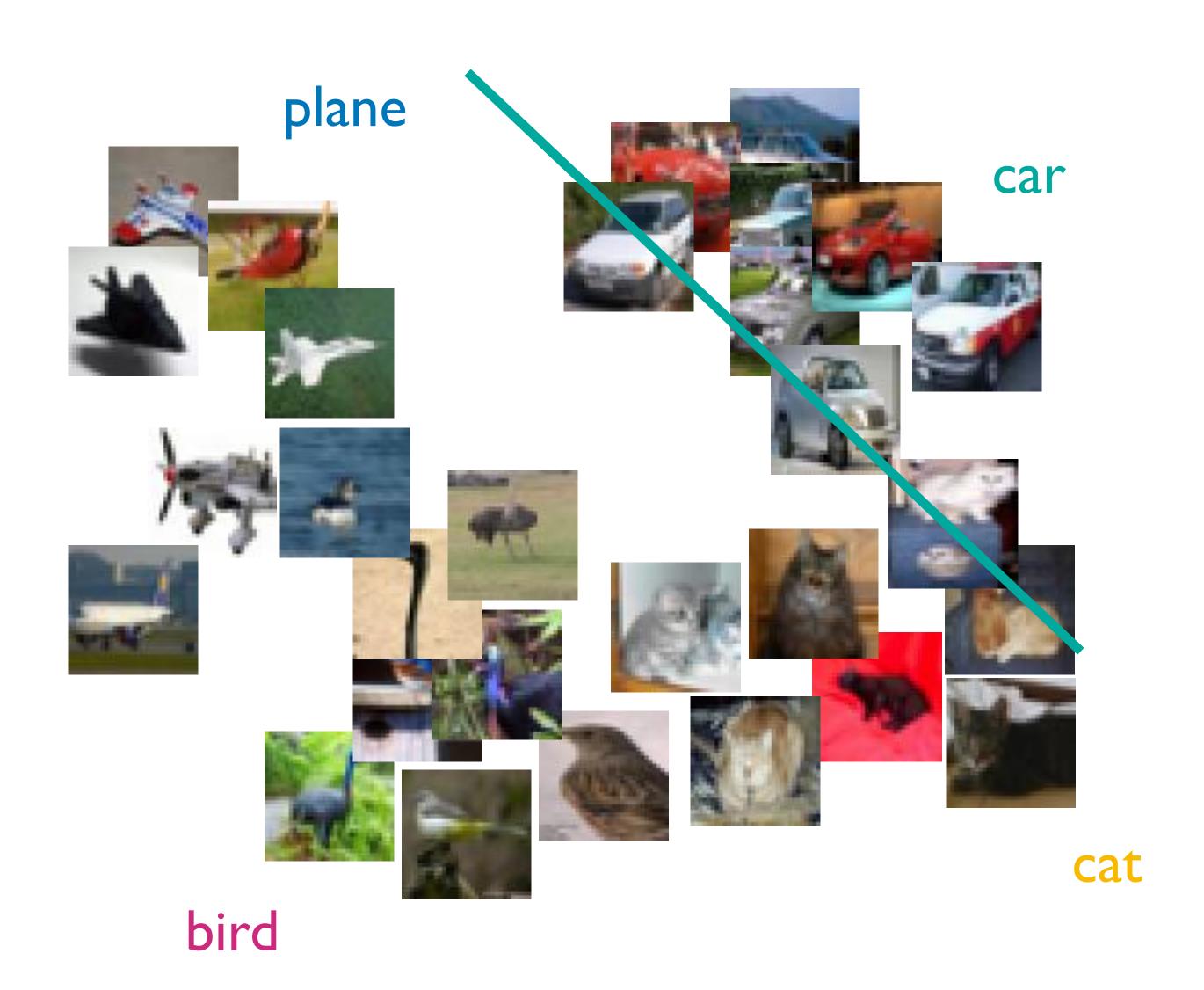


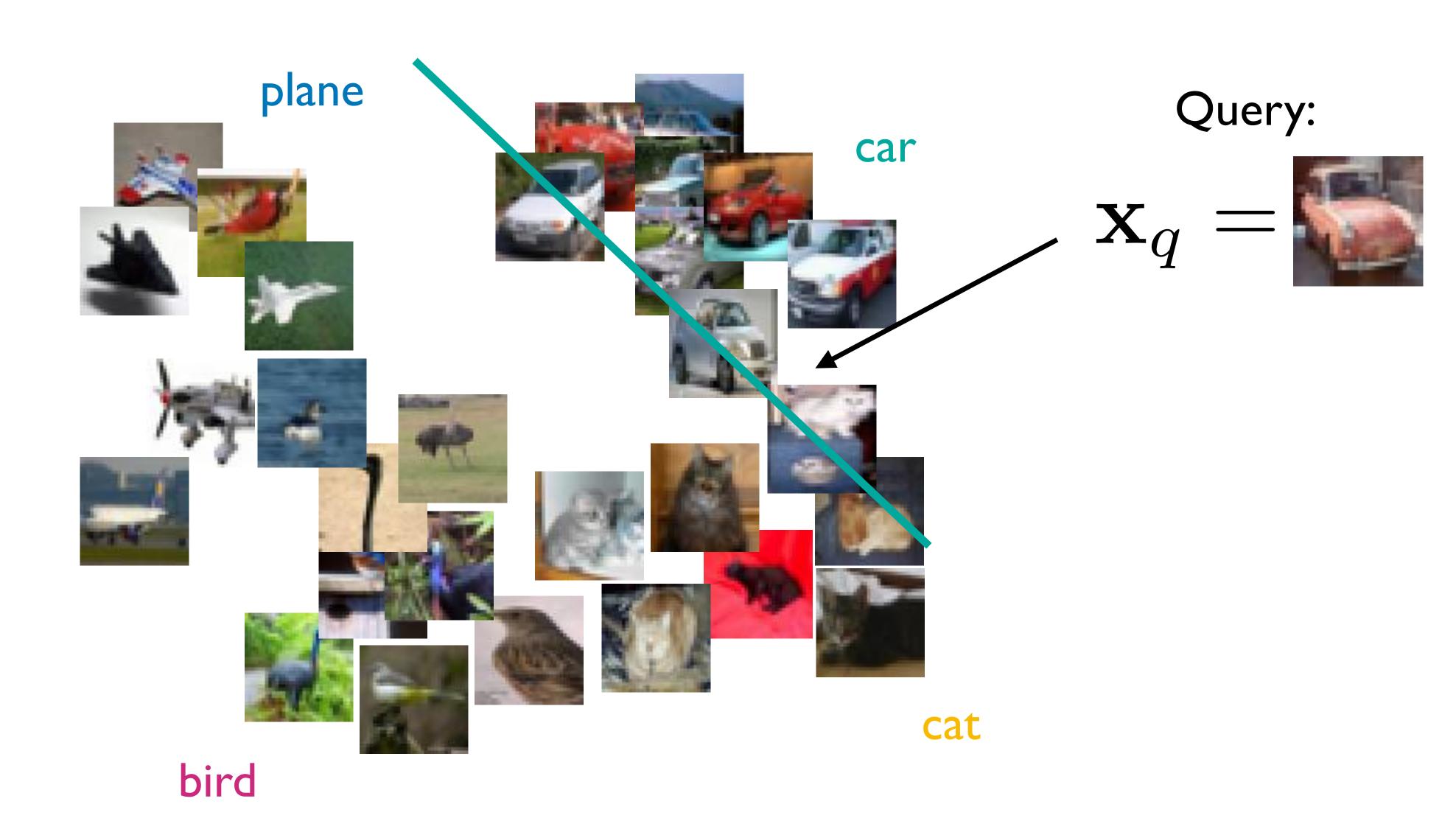
#### Recall: Linear Classifier

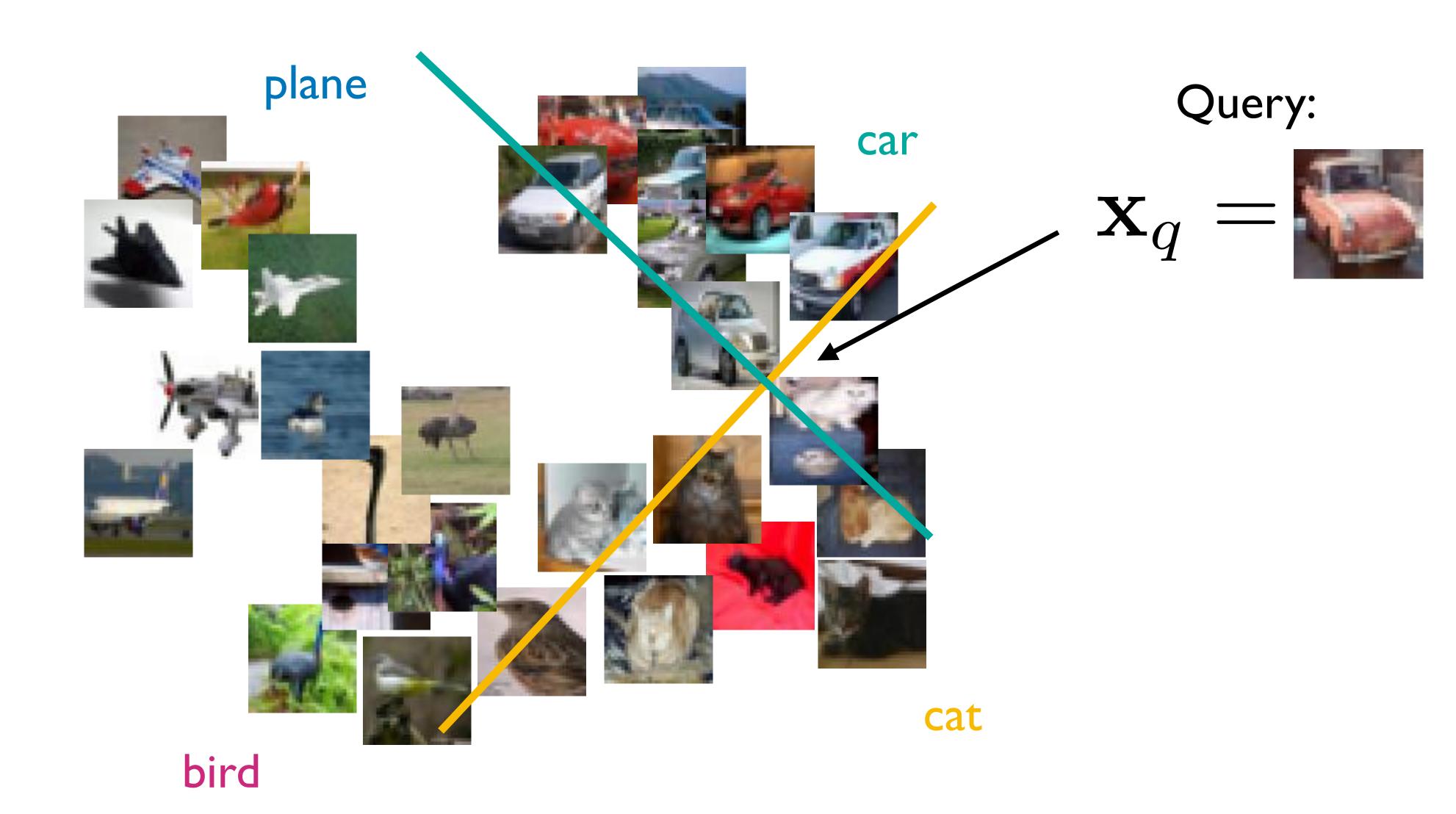
Example with an image with 4 pixels, and 3 classes (cat/dog/ship)

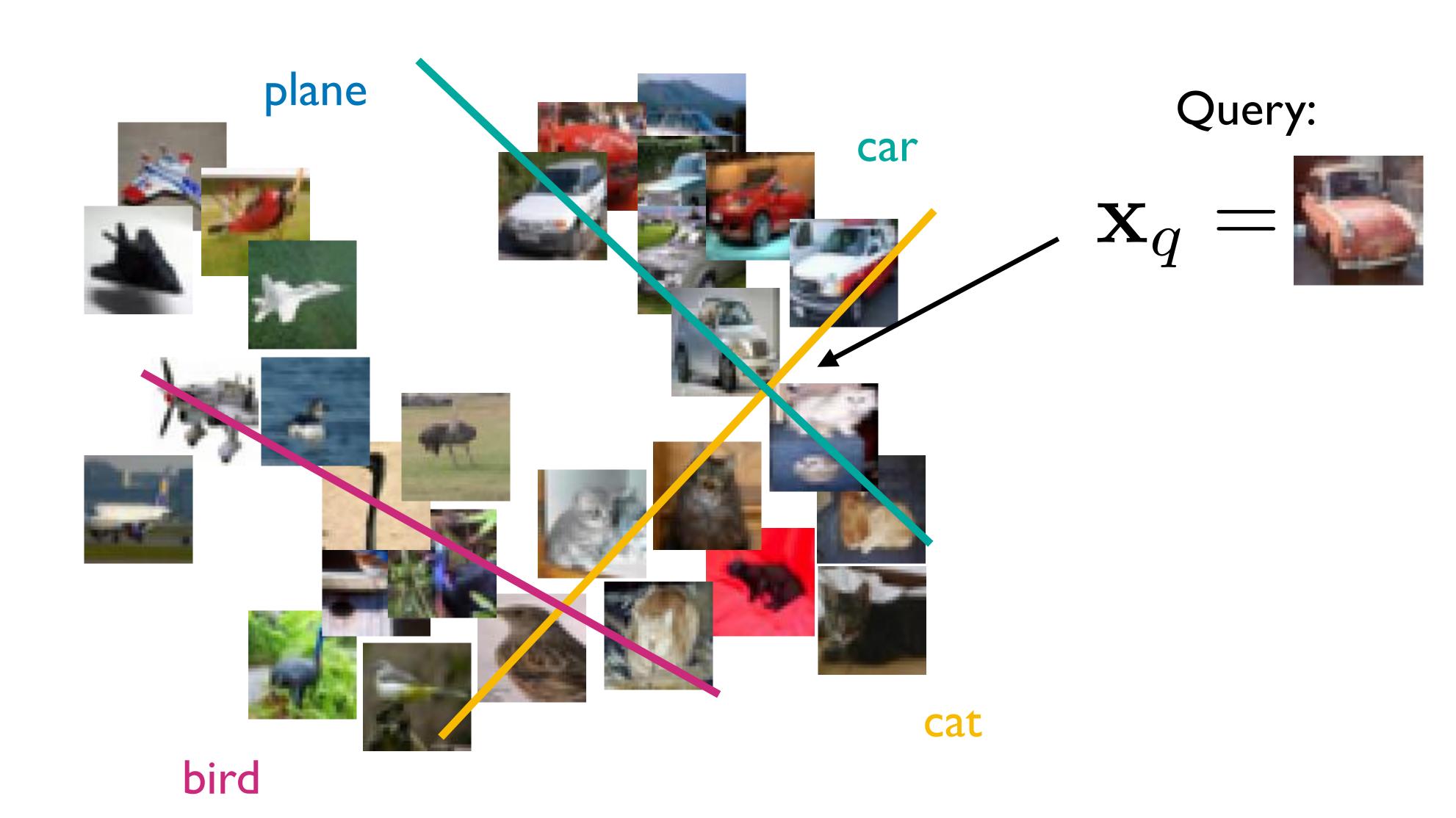


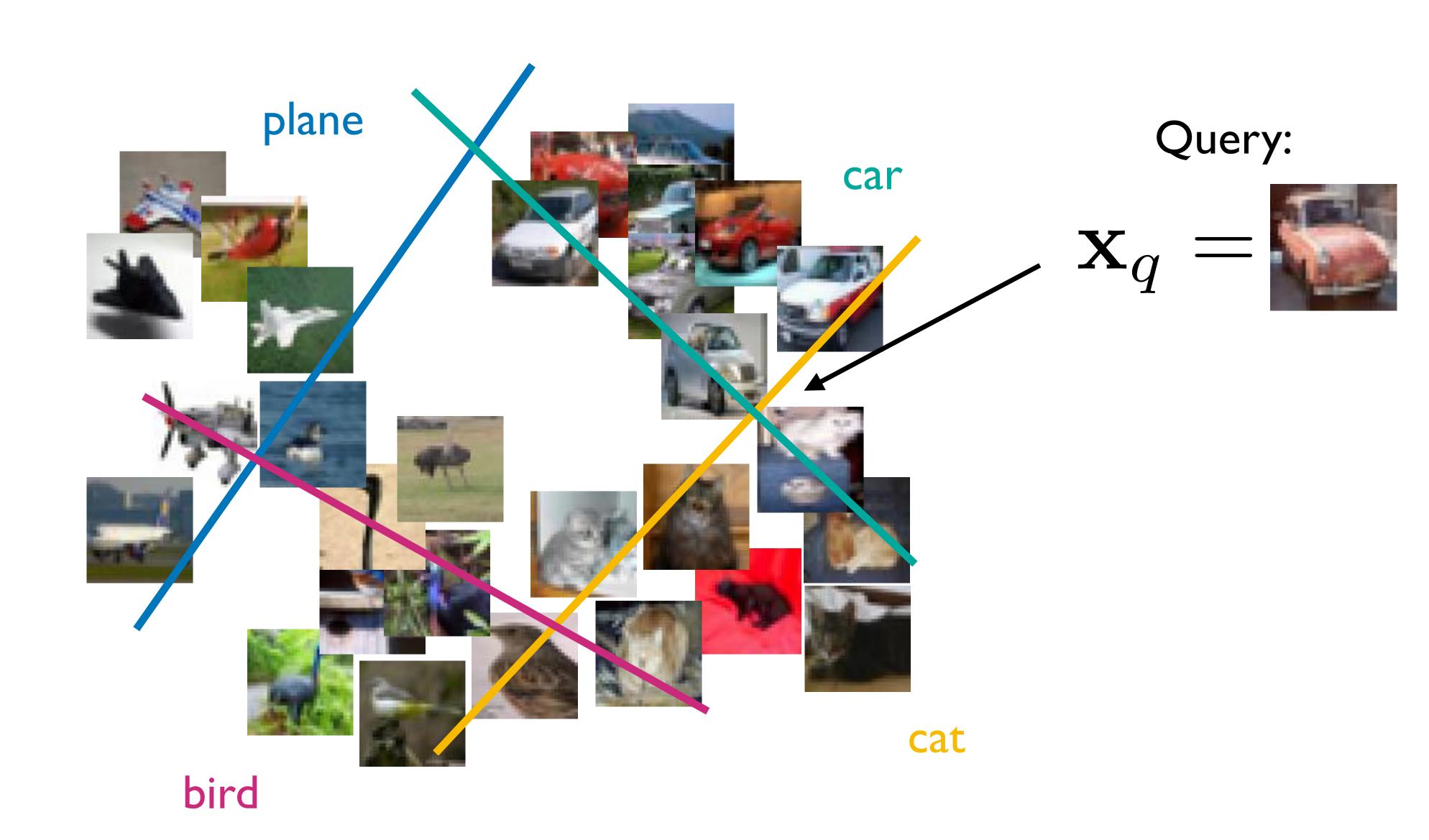




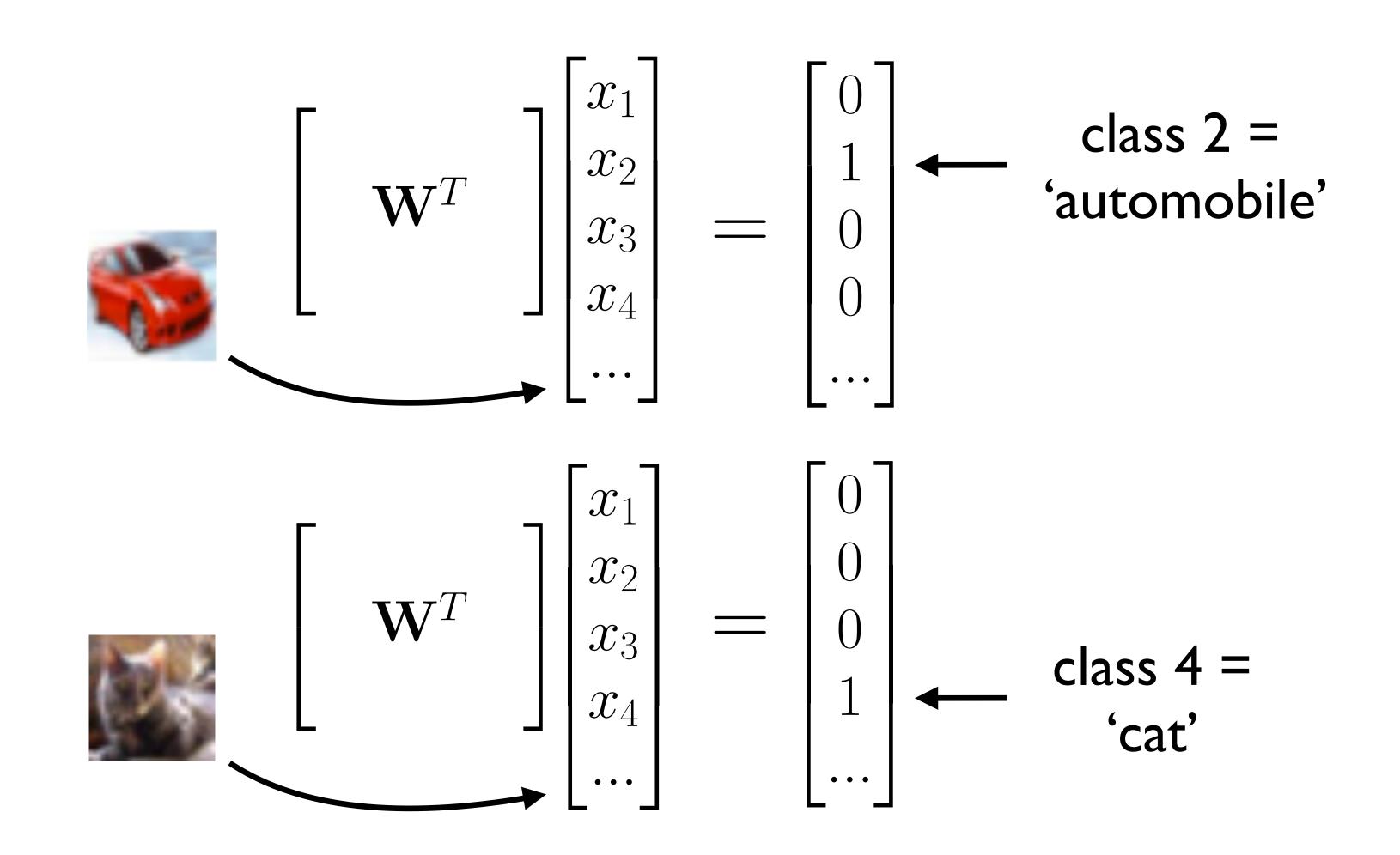




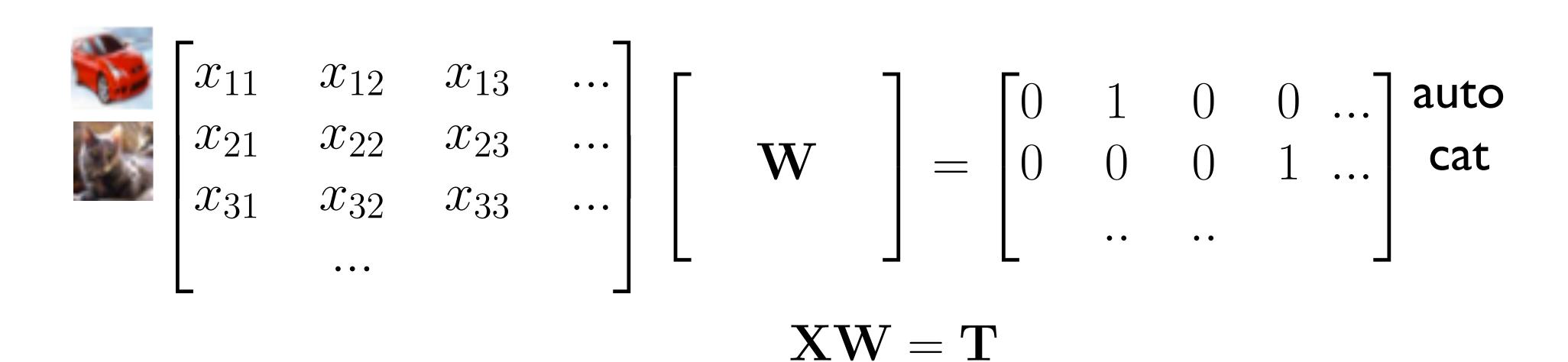




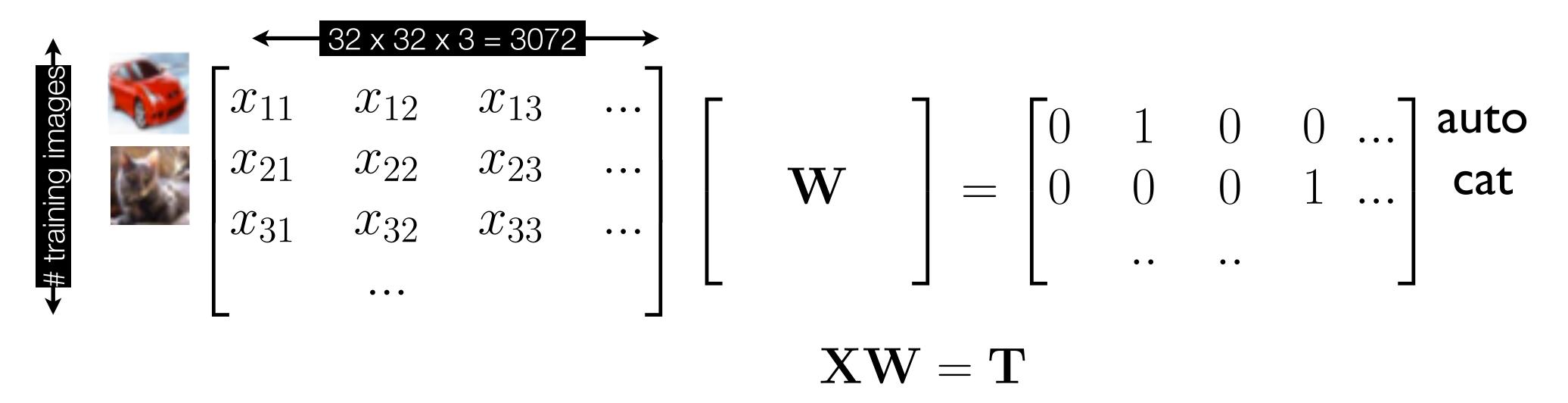
An alternative solution is to regress to one-hot targets = 1 vs all classifiers



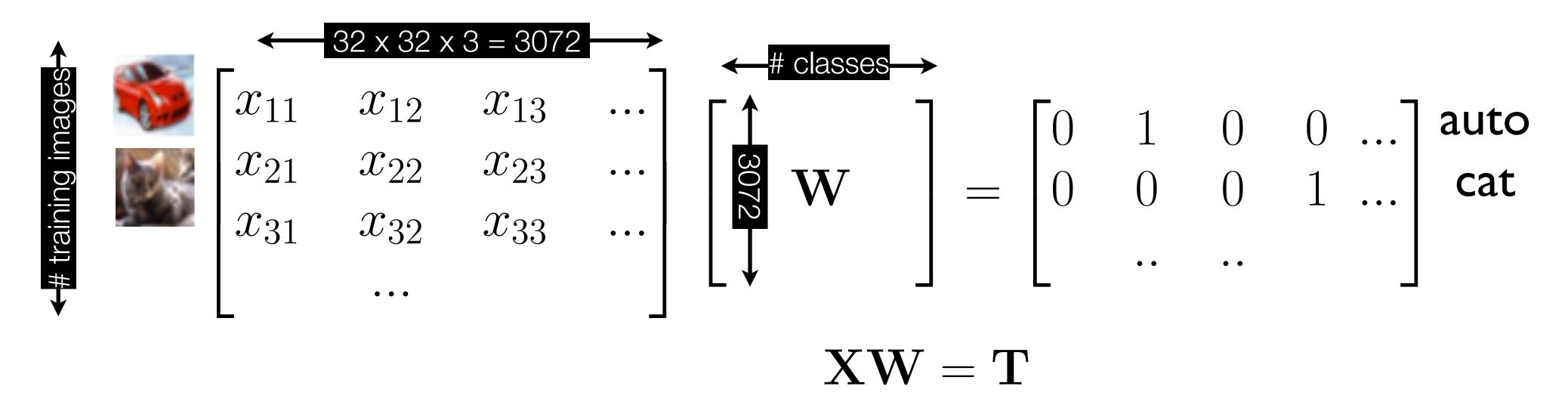
Transpose



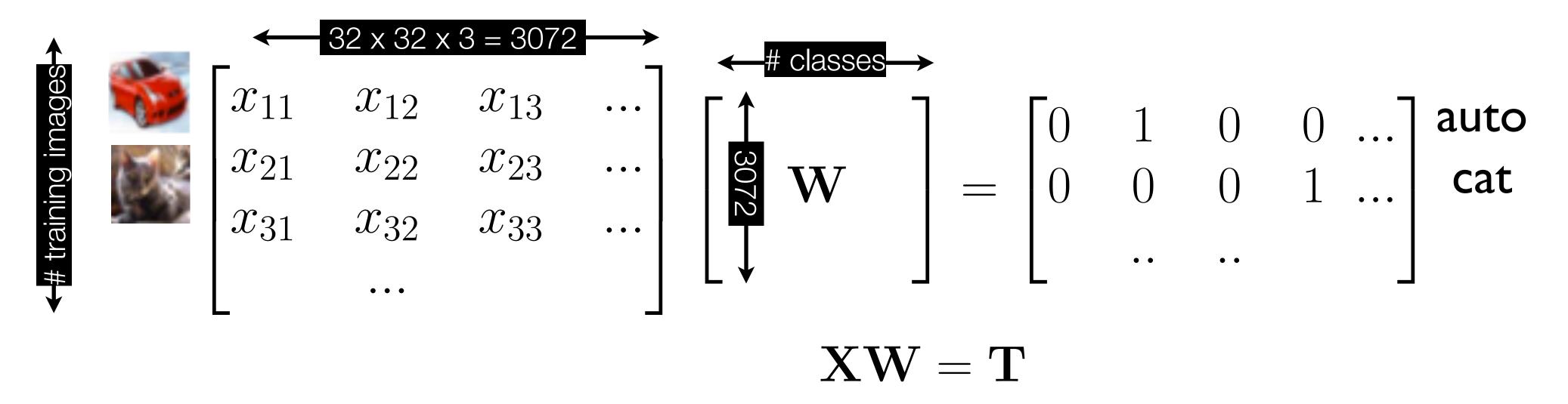
Transpose



Transpose



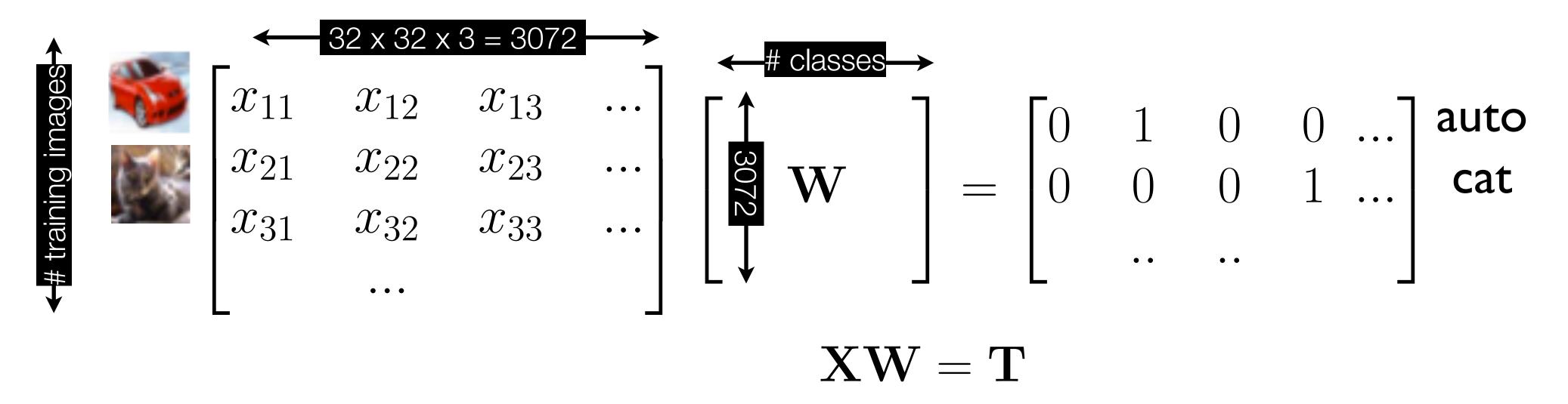
Transpose



Solve regression problem by Least Squares

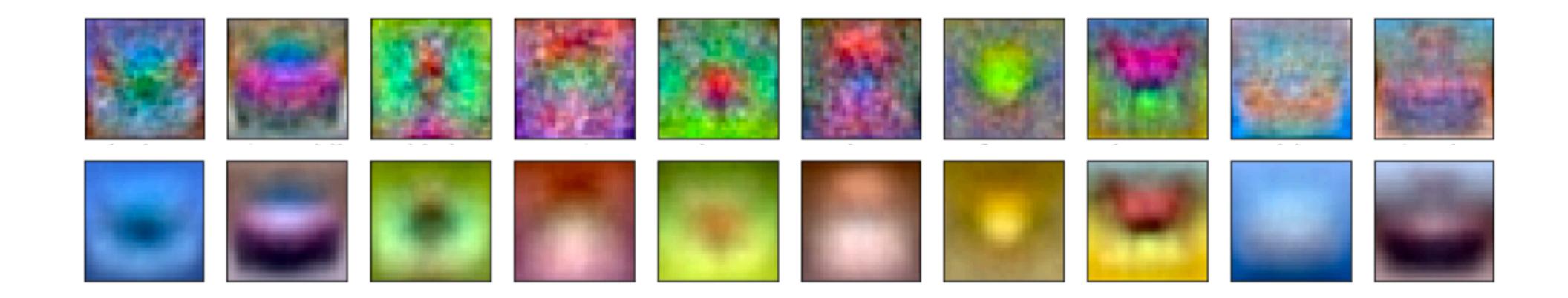
$$\mathcal{L} = |\mathbf{X}\mathbf{W} - \mathbf{T}|^2$$

Transpose



Solve regression problem by Least Squares

$$\mathcal{L} = |\mathbf{X}\mathbf{W} - \mathbf{T}|^2 + \lambda |\mathbf{W}|^2$$



Solve regression problem by Least Squares

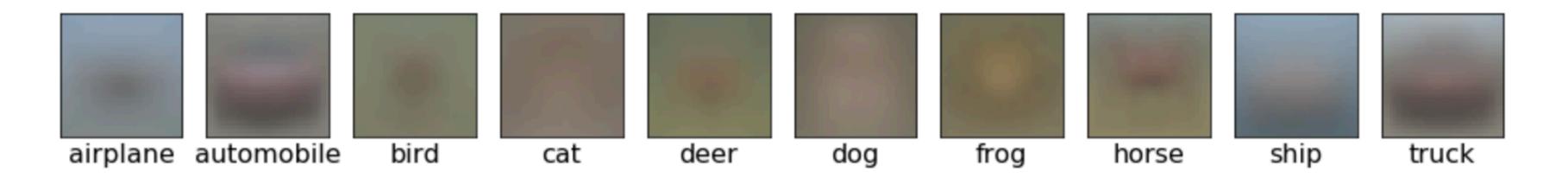
$$\mathcal{L} = |\mathbf{X}\mathbf{W} - \mathbf{T}|^2 + \lambda |\mathbf{W}|^2$$

#### Recall: Nearest Mean Classifier

Find the nearest mean and assign class:

$$c_q = \arg\min_i |\mathbf{x}_q - \mathbf{m}_i|^2$$

CIFAR10 class means:

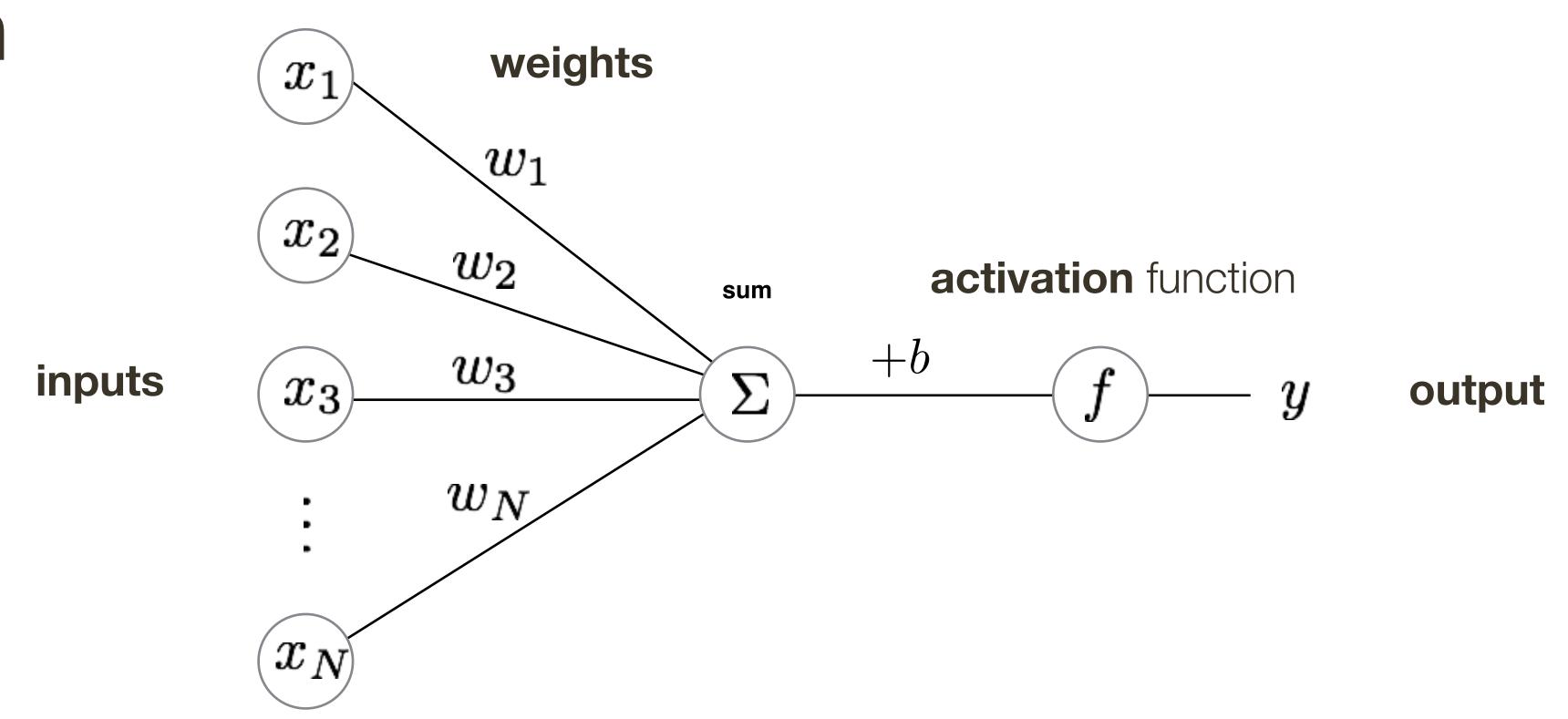


# Warning:

Our intro to Neural Networks will be very light weight ...

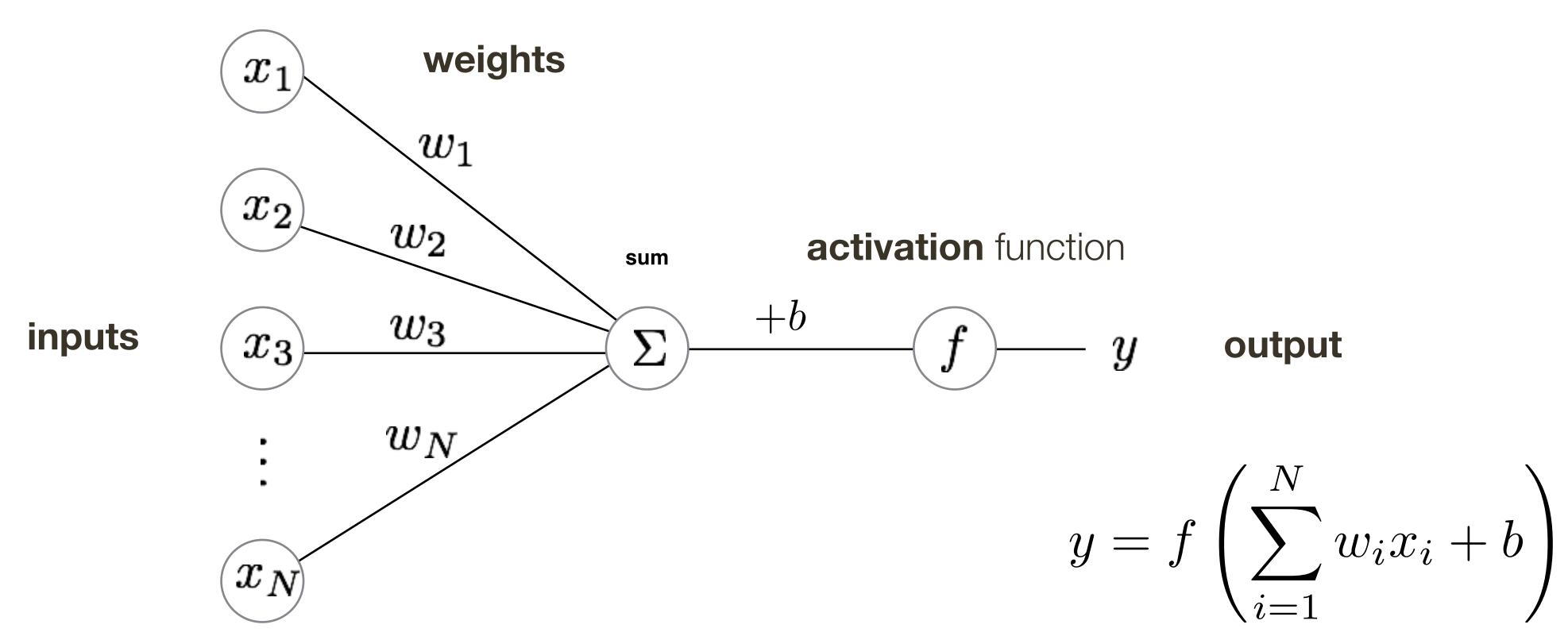
... if you want to know more, take my CPSC 532S

#### **A Neuron**



- The basic unit of computation in a neural network is a neuron.
- A neuron accepts some number of input signals, computes their weighted sum, and applies an **activation function** (or **non-linearity**) to the sum.
- Common activation functions include sigmoid and rectified linear unit (ReLU)

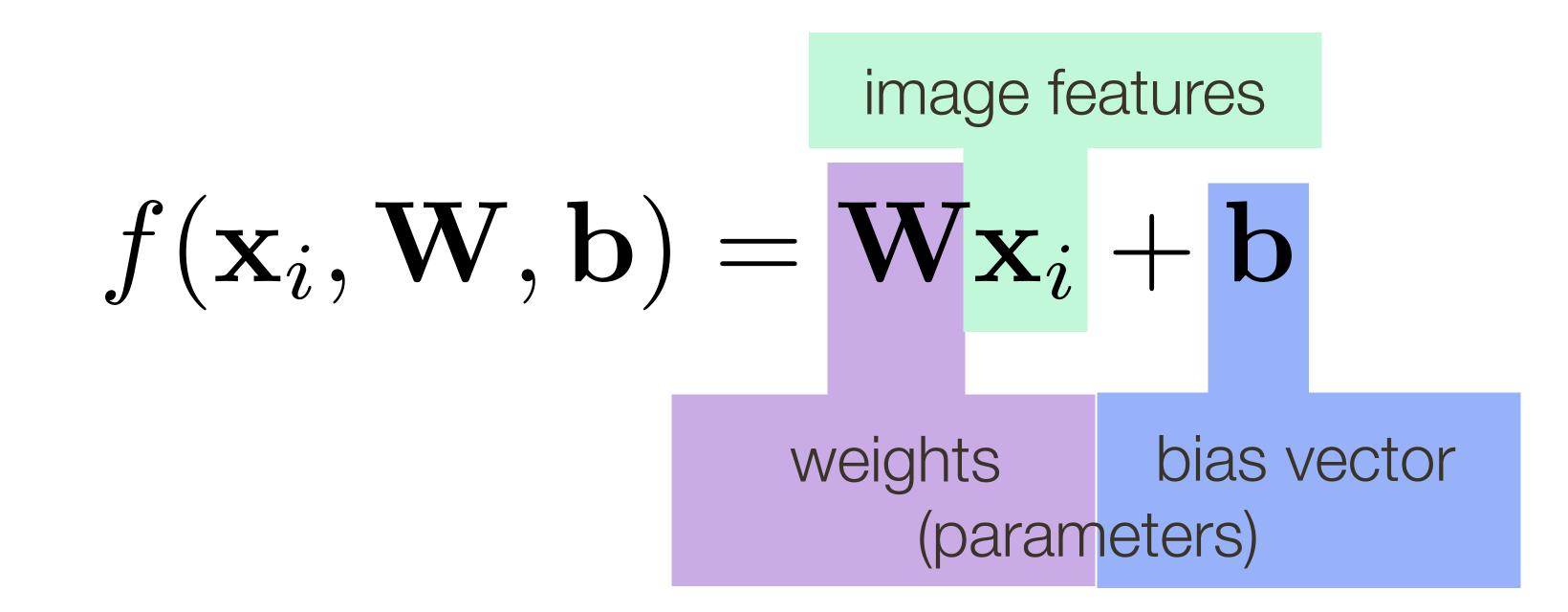
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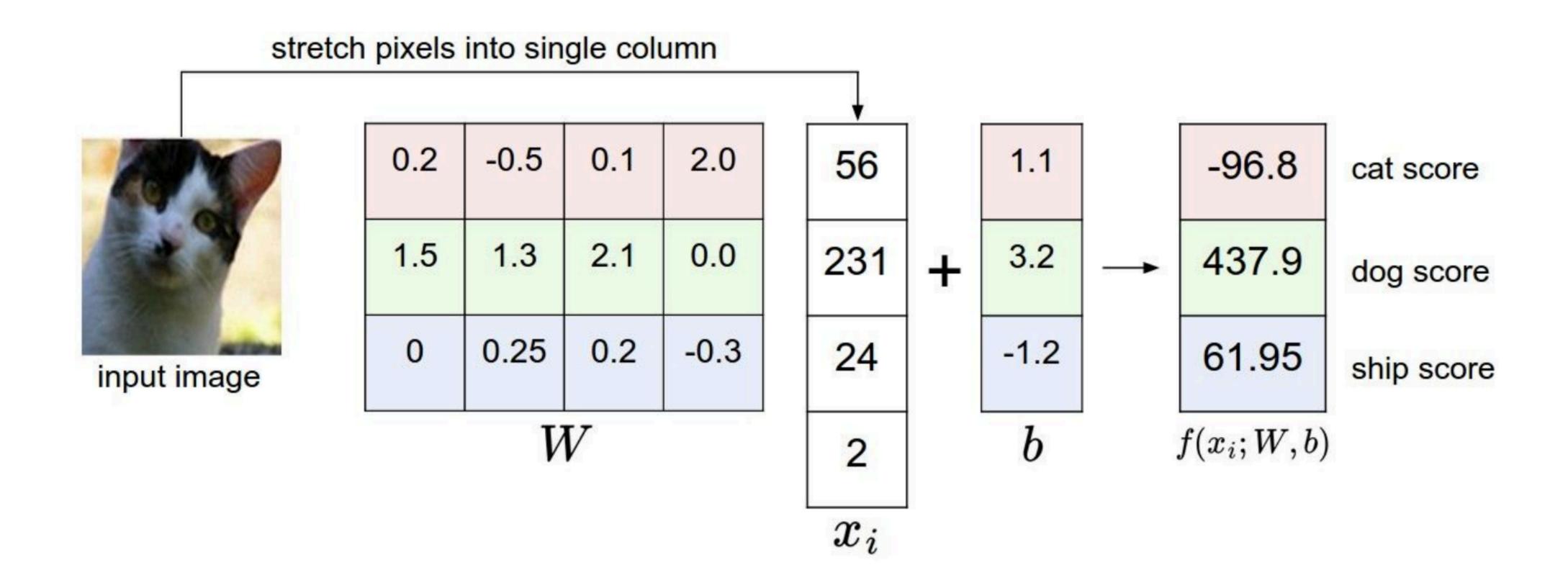
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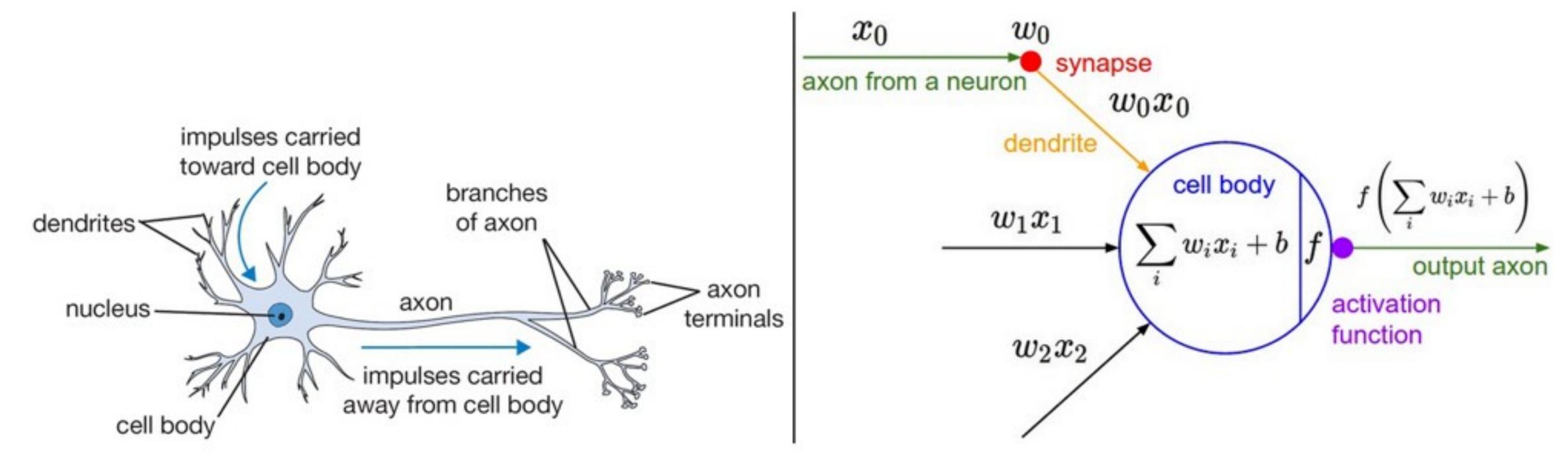
#### Recall: Linear Classifier

Example with an image with 4 pixels, and 3 classes (cat/dog/ship)



# Aside: Inspiration from Biology

Figure credit: Fei-Fei and Karpathy



A cartoon drawing of a biological neuron (left) and its mathematical model (right).

Neural nets/perceptrons are loosely inspired by biology.

But they certainly are not a model of how the brain works, or even how neurons work.

# Activation Function: Sigmoid

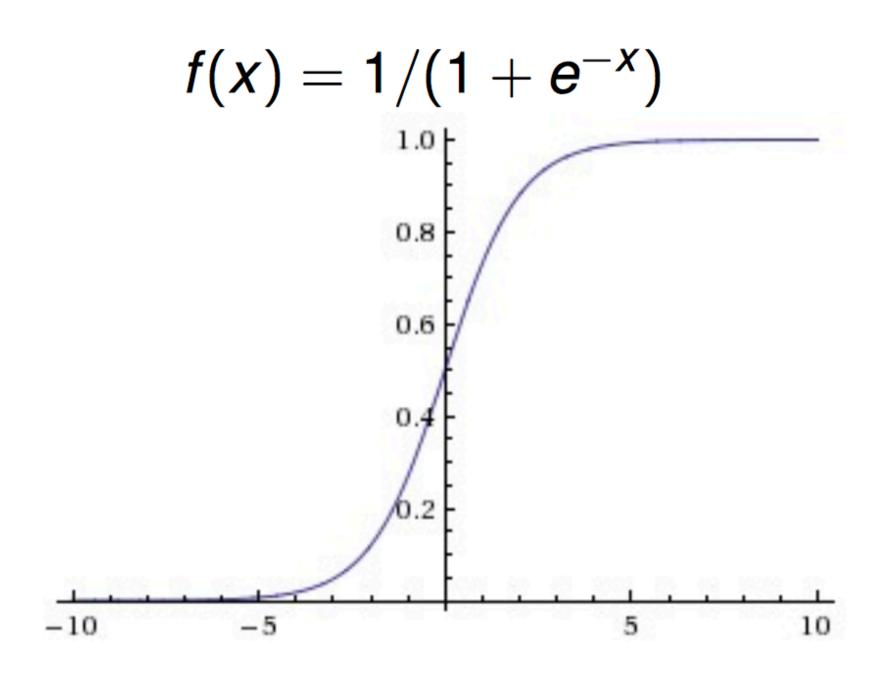


Figure credit: Fei-Fei and Karpathy

Common in many early neural networks
Biological analogy to saturated firing rate of neurons
Maps the input to the range [0,1]

# Activation Function: ReLU (Rectified Linear Unit)

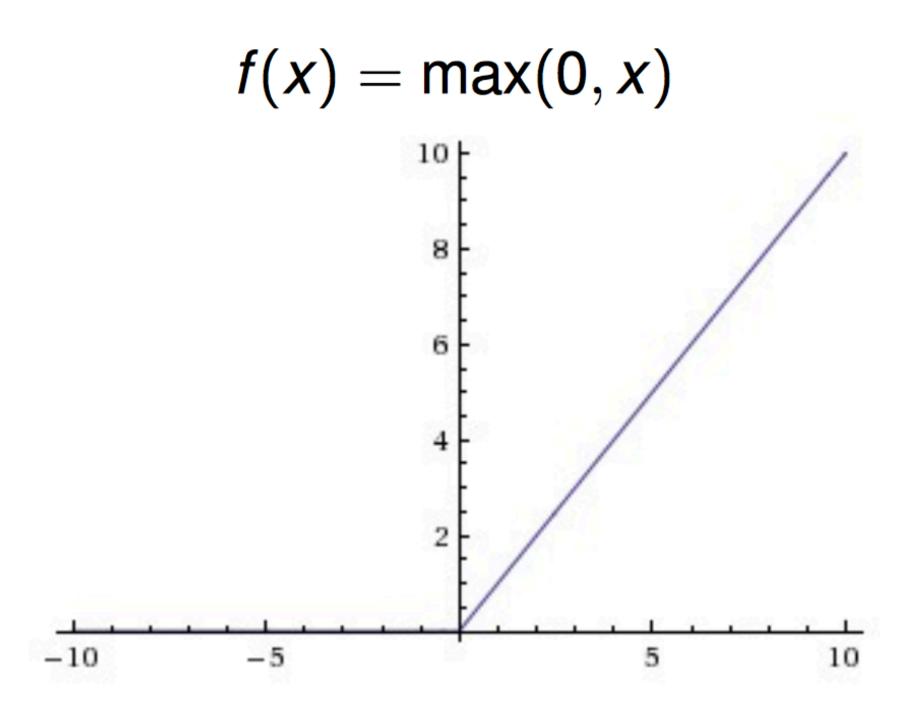
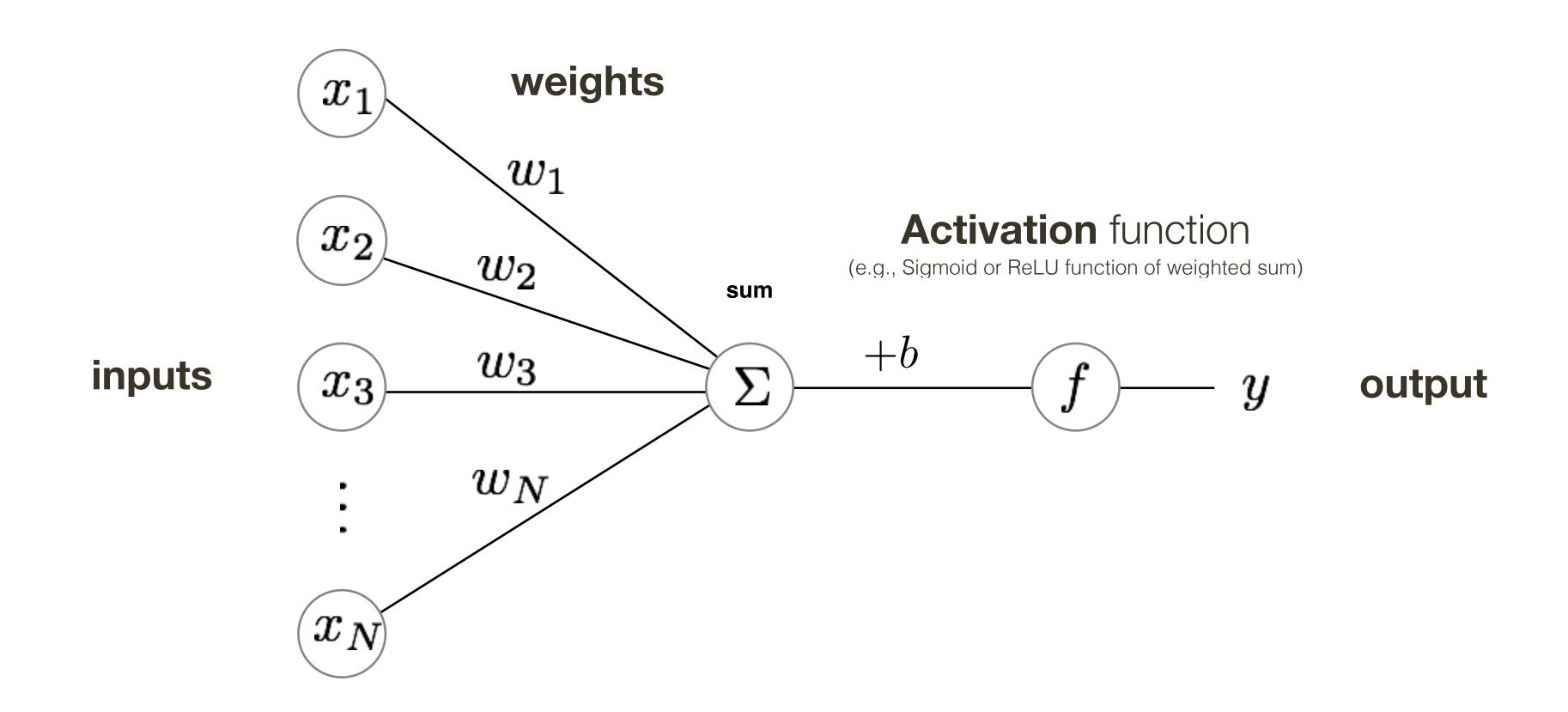
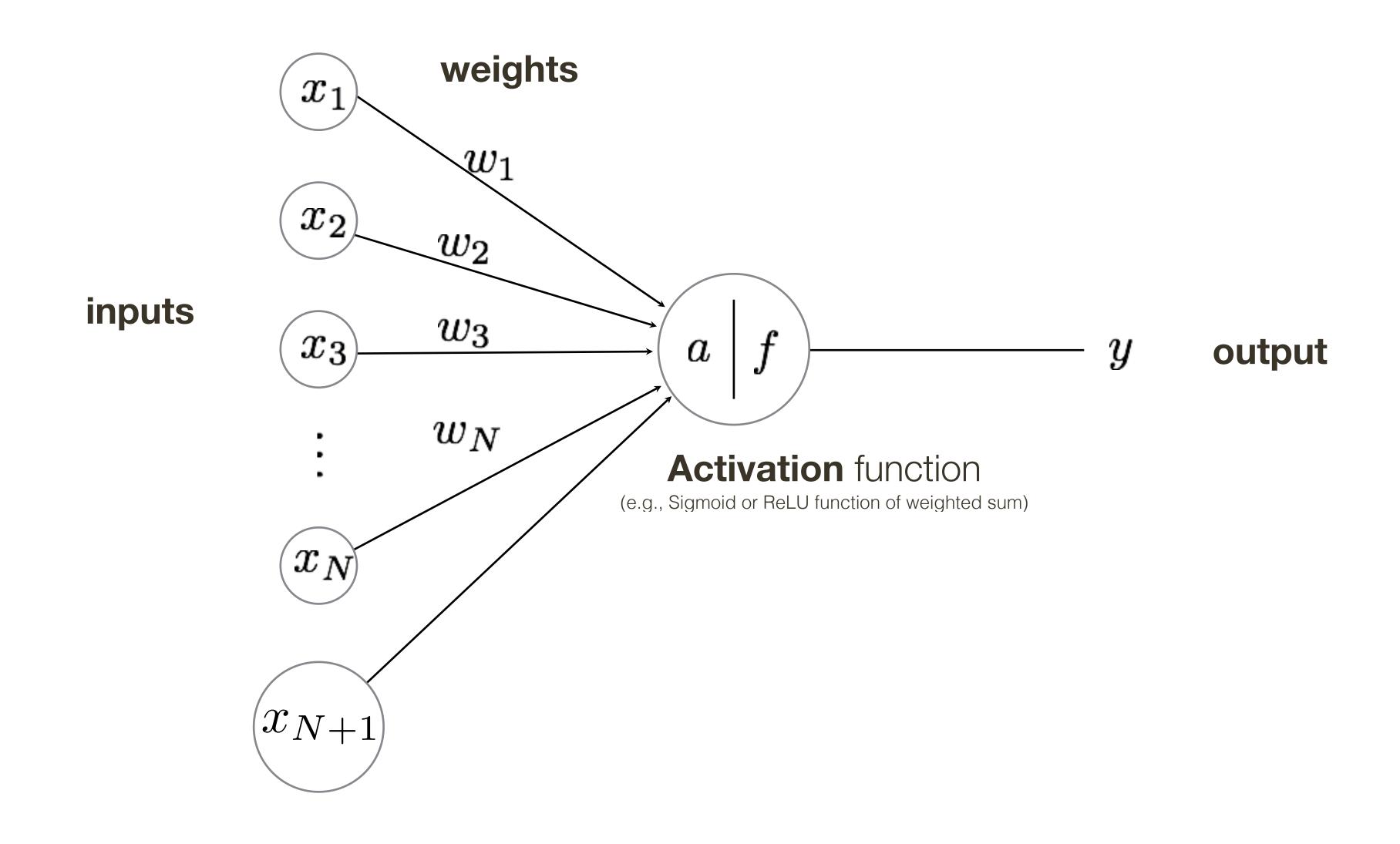


Figure credit: Fei-Fei and Karpathy

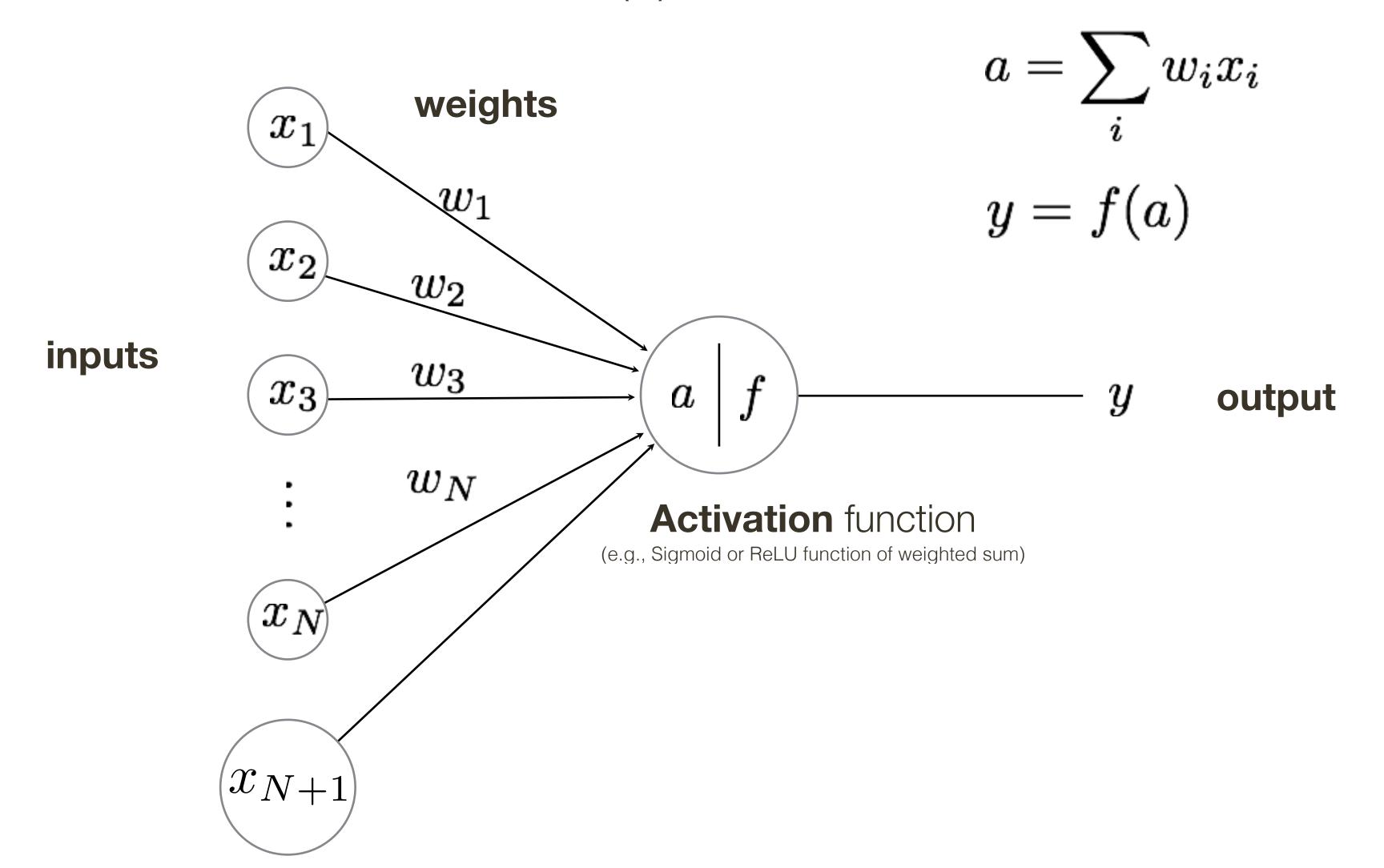
Found to accelerate convergence during learning Used in the most recent neural networks

### **A Neuron**

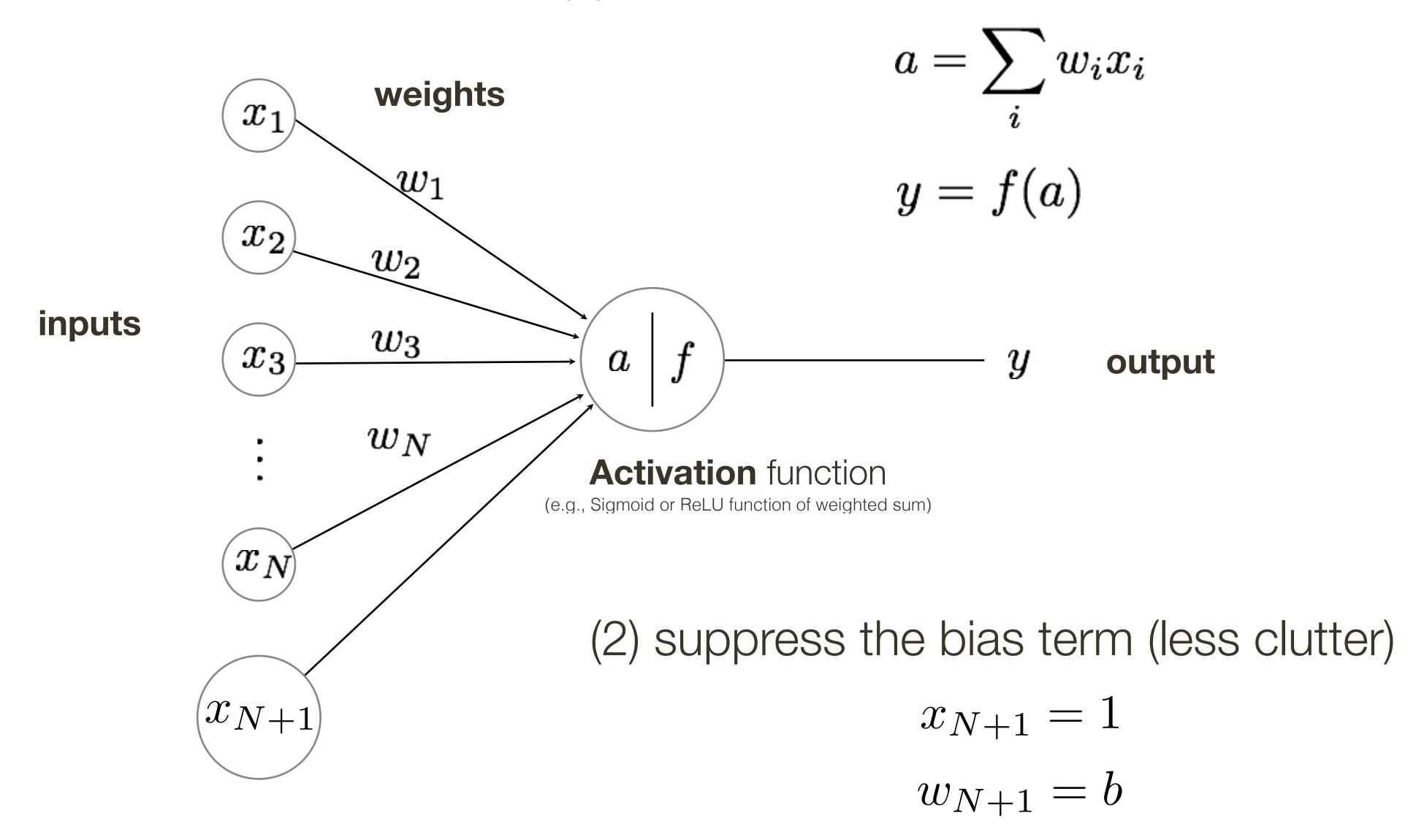




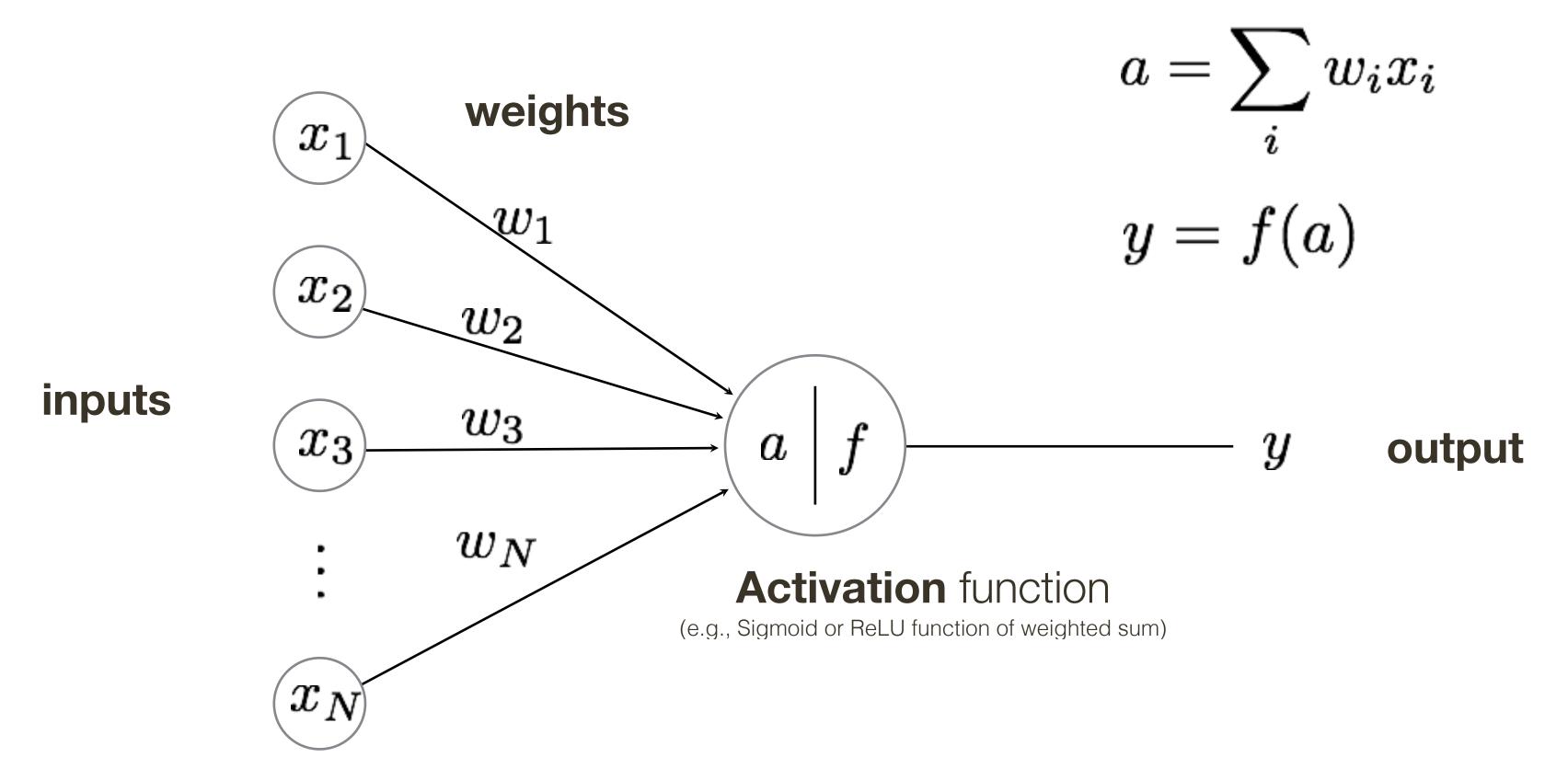
(1) Combine the sum and activation function



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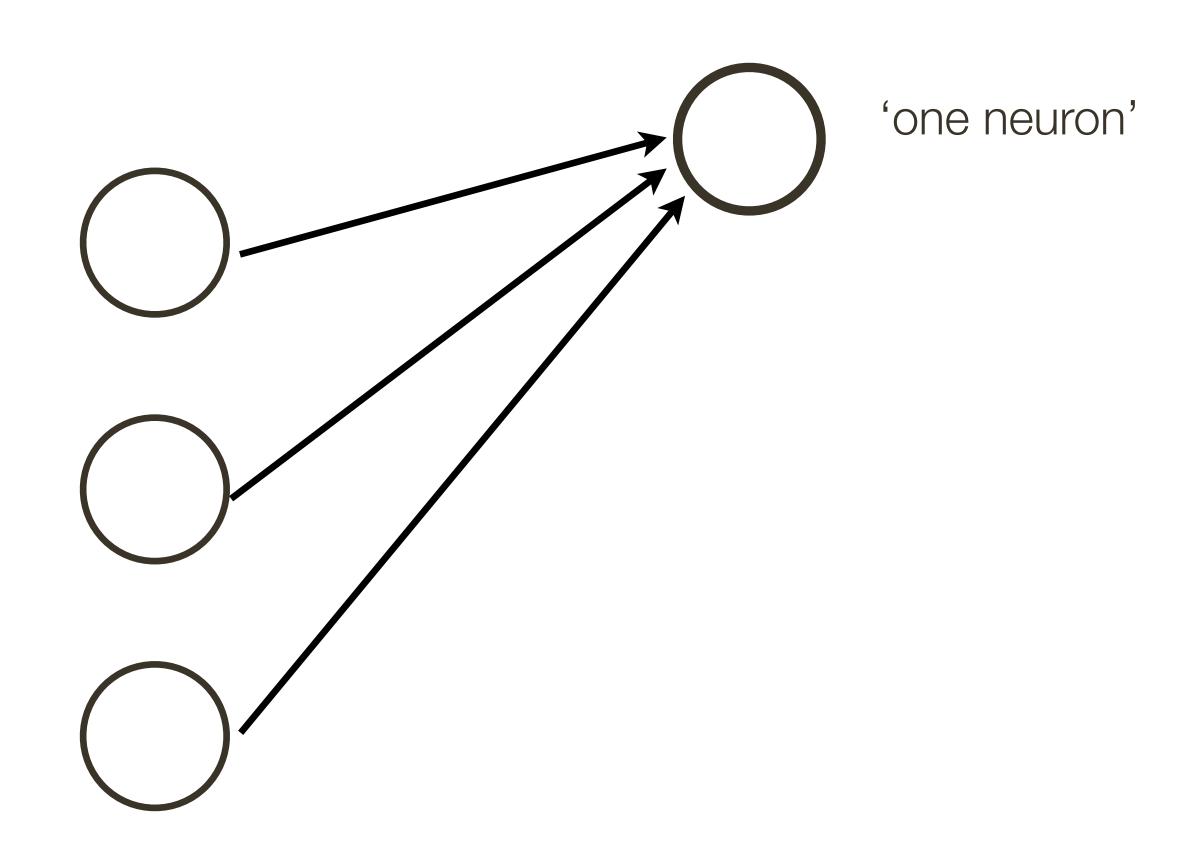
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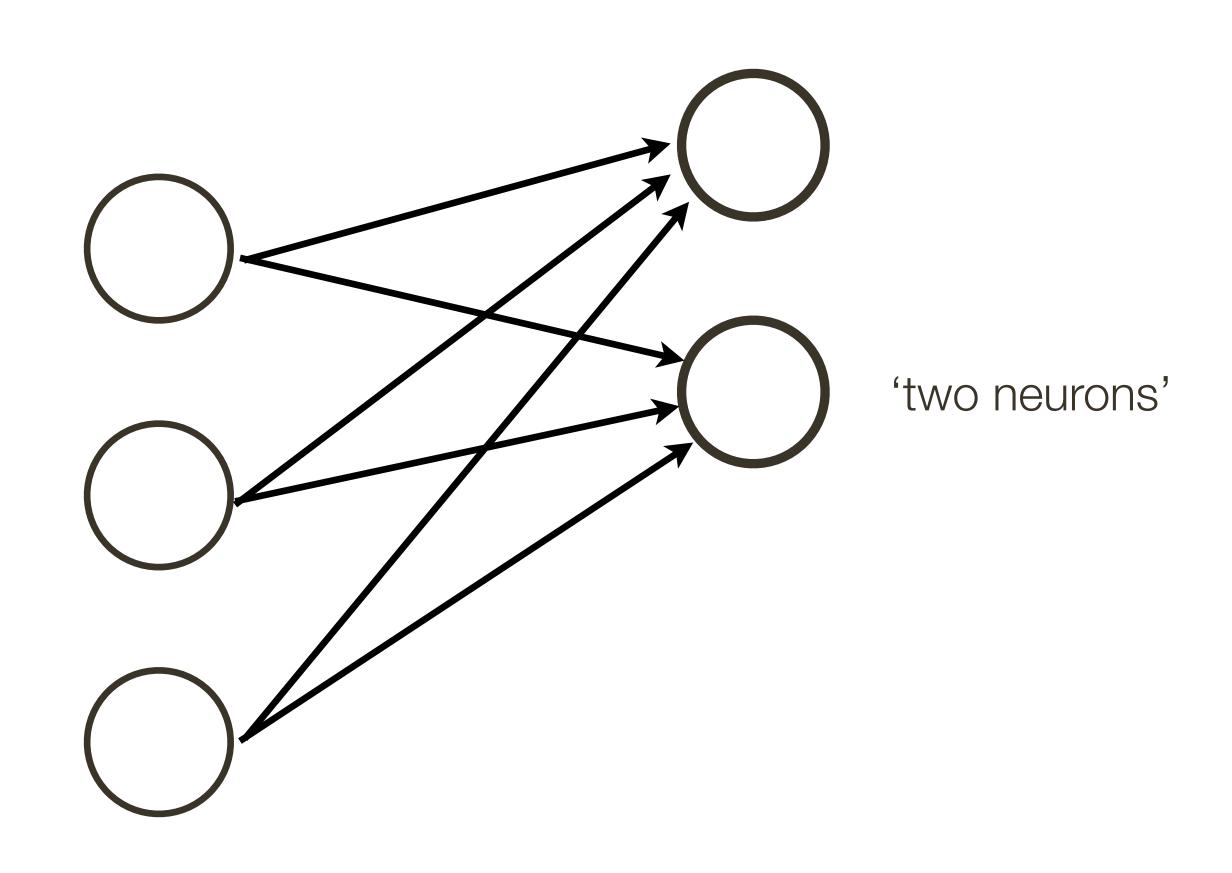


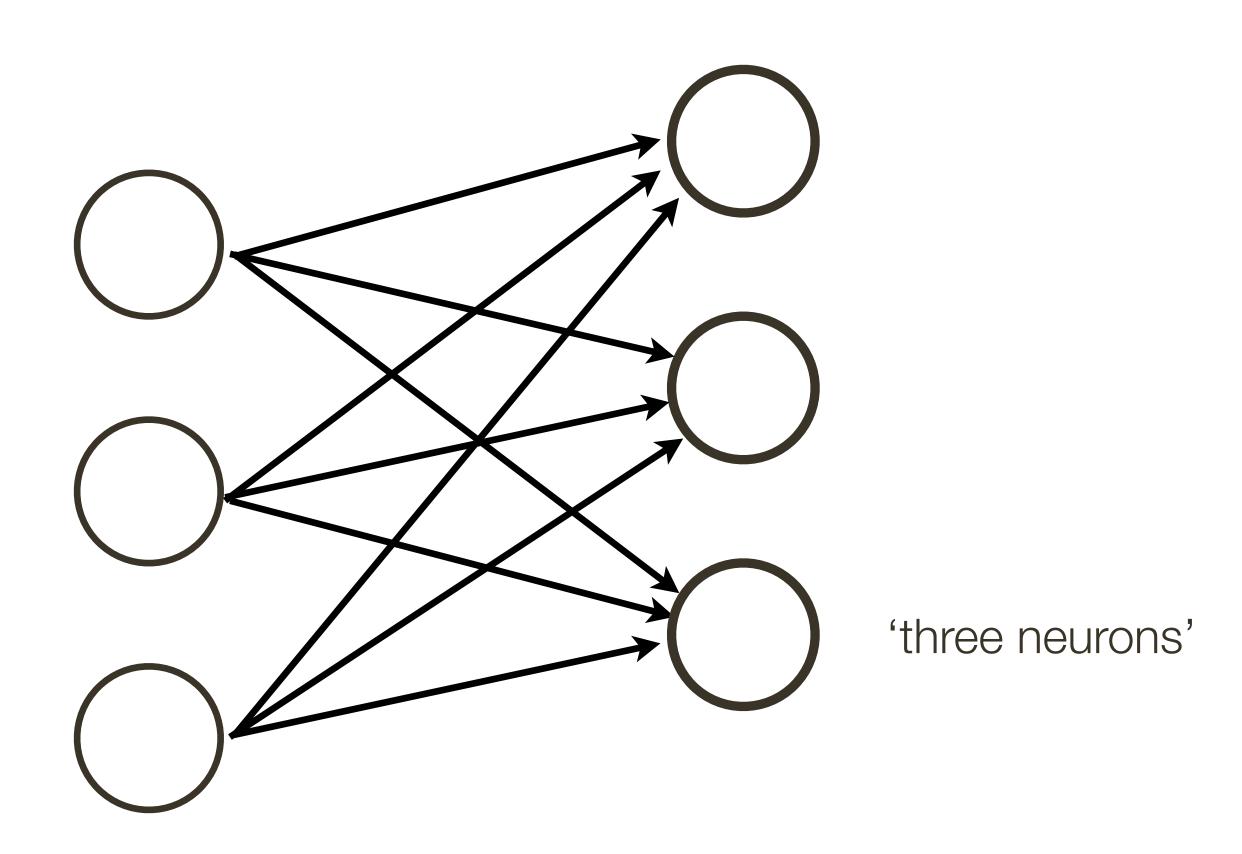
(2) suppress the bias term (less clutter)

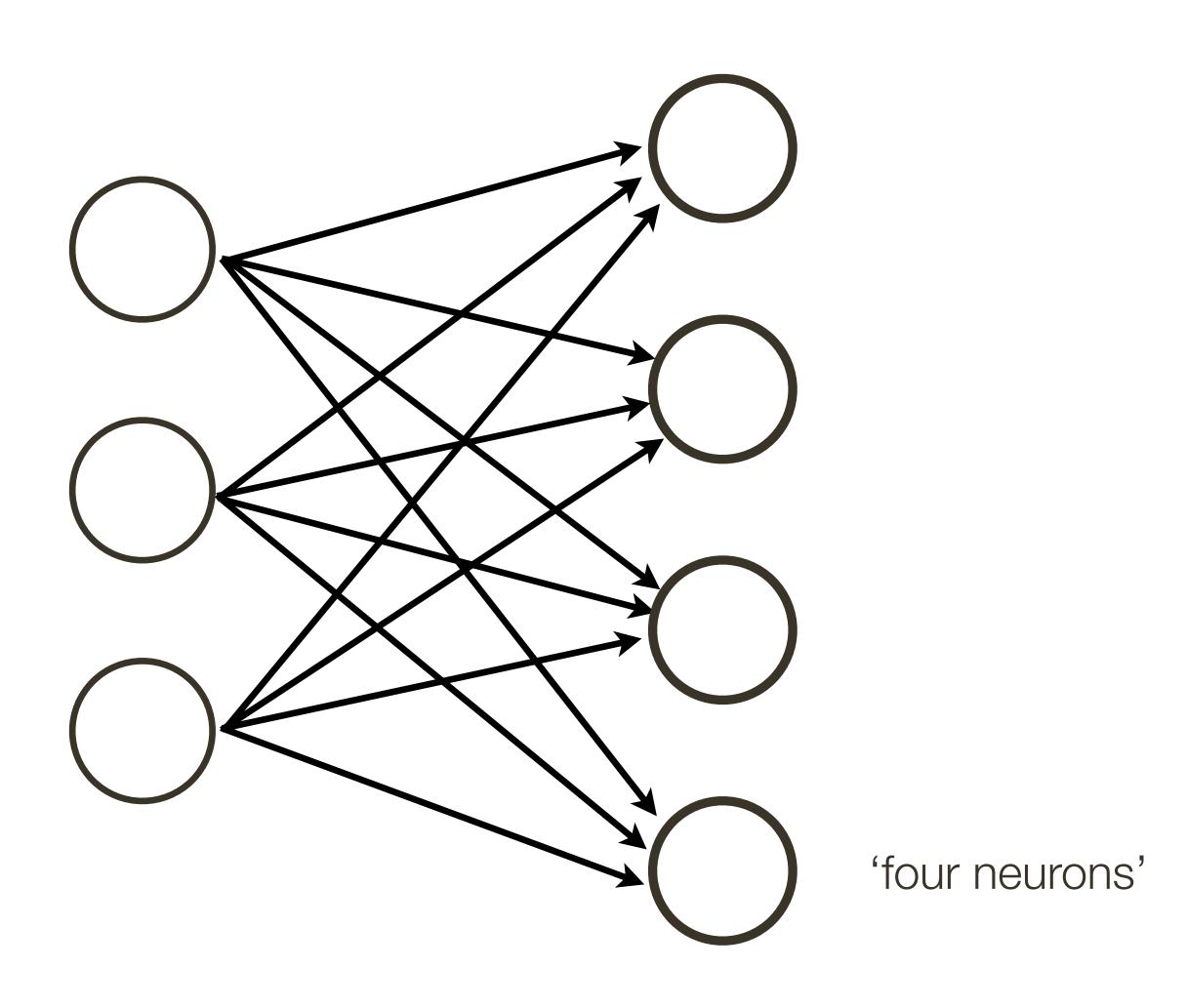
$$x_{N+1} = 1$$

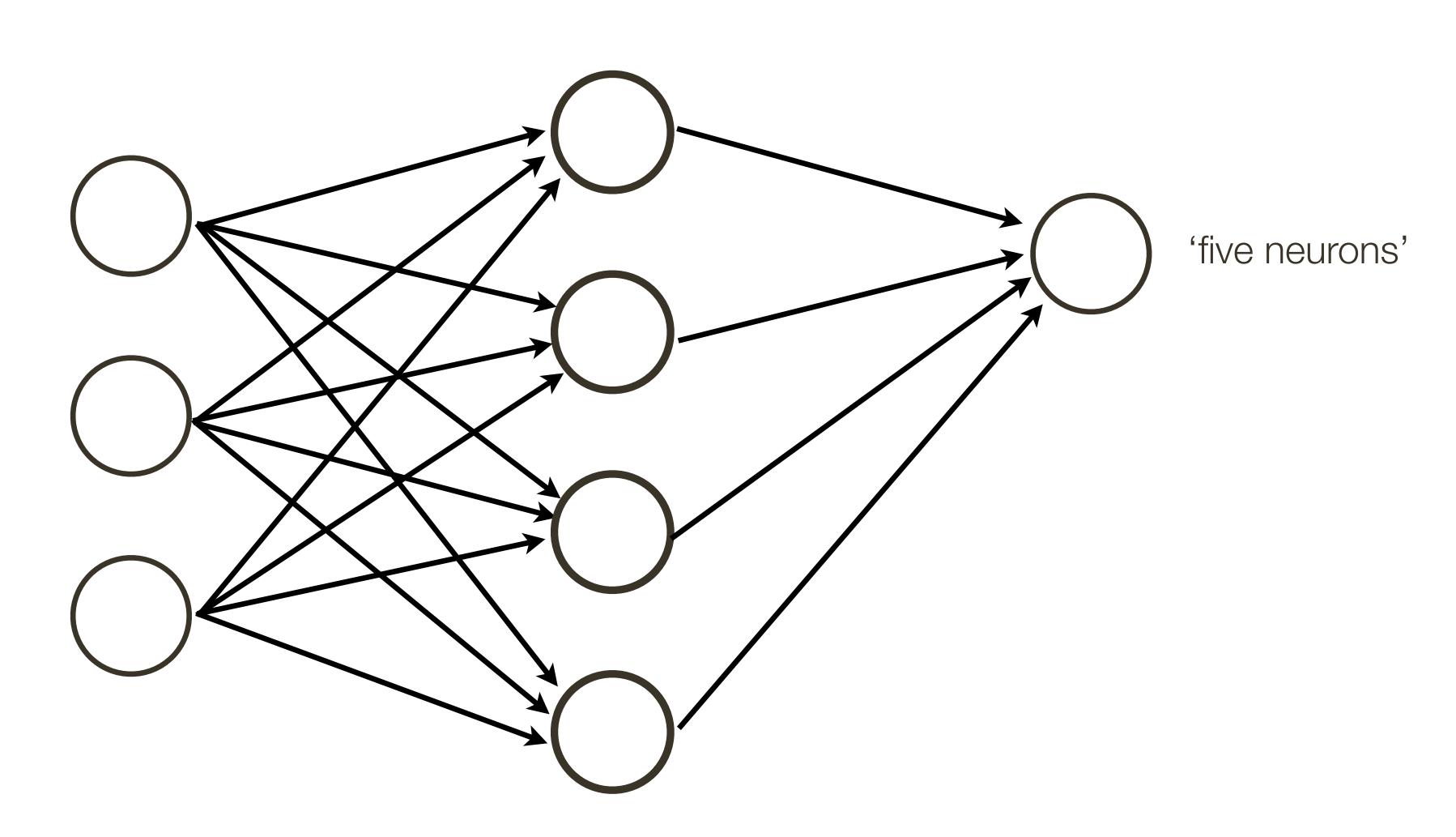
$$w_{N+1} = b$$

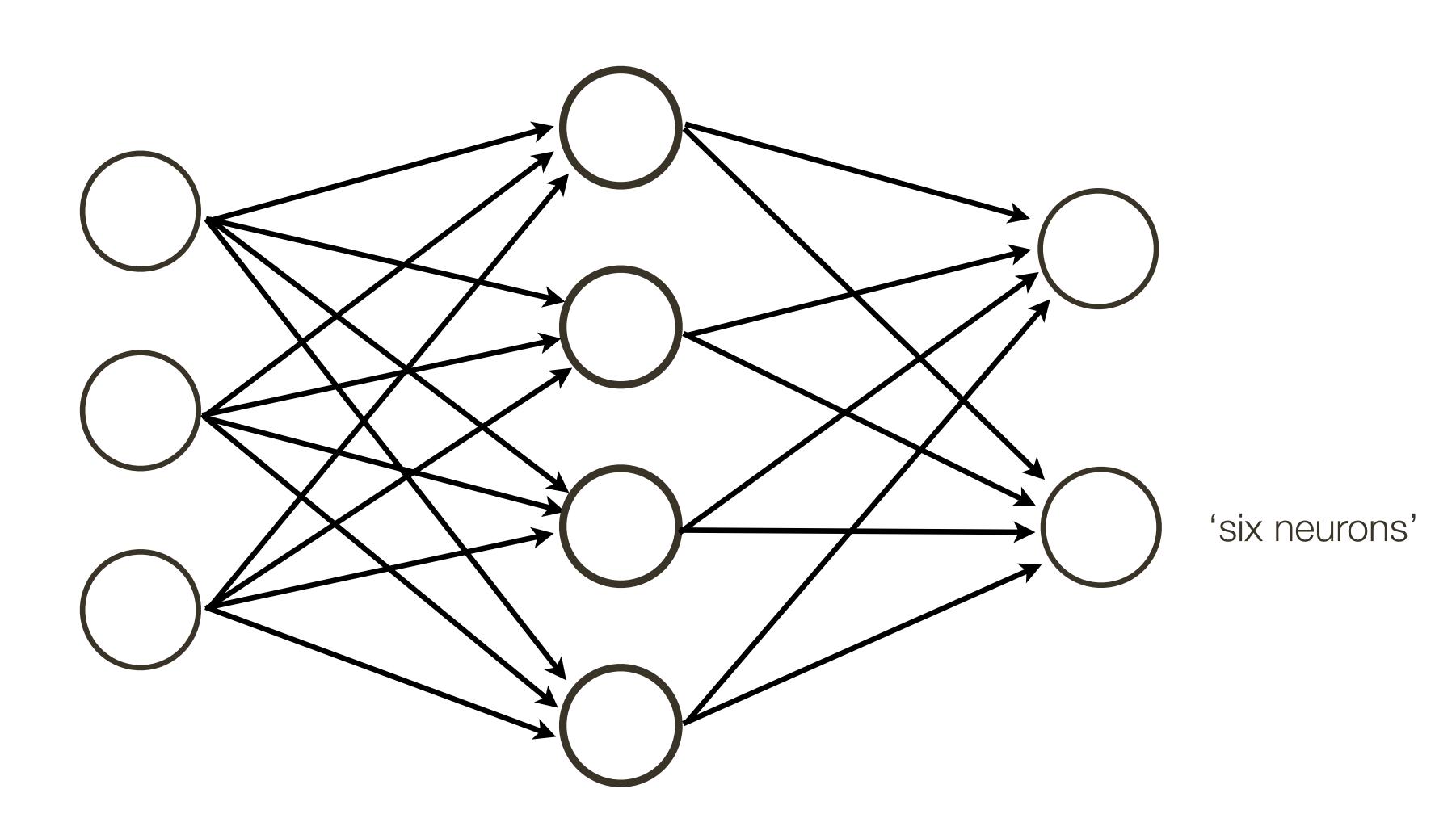




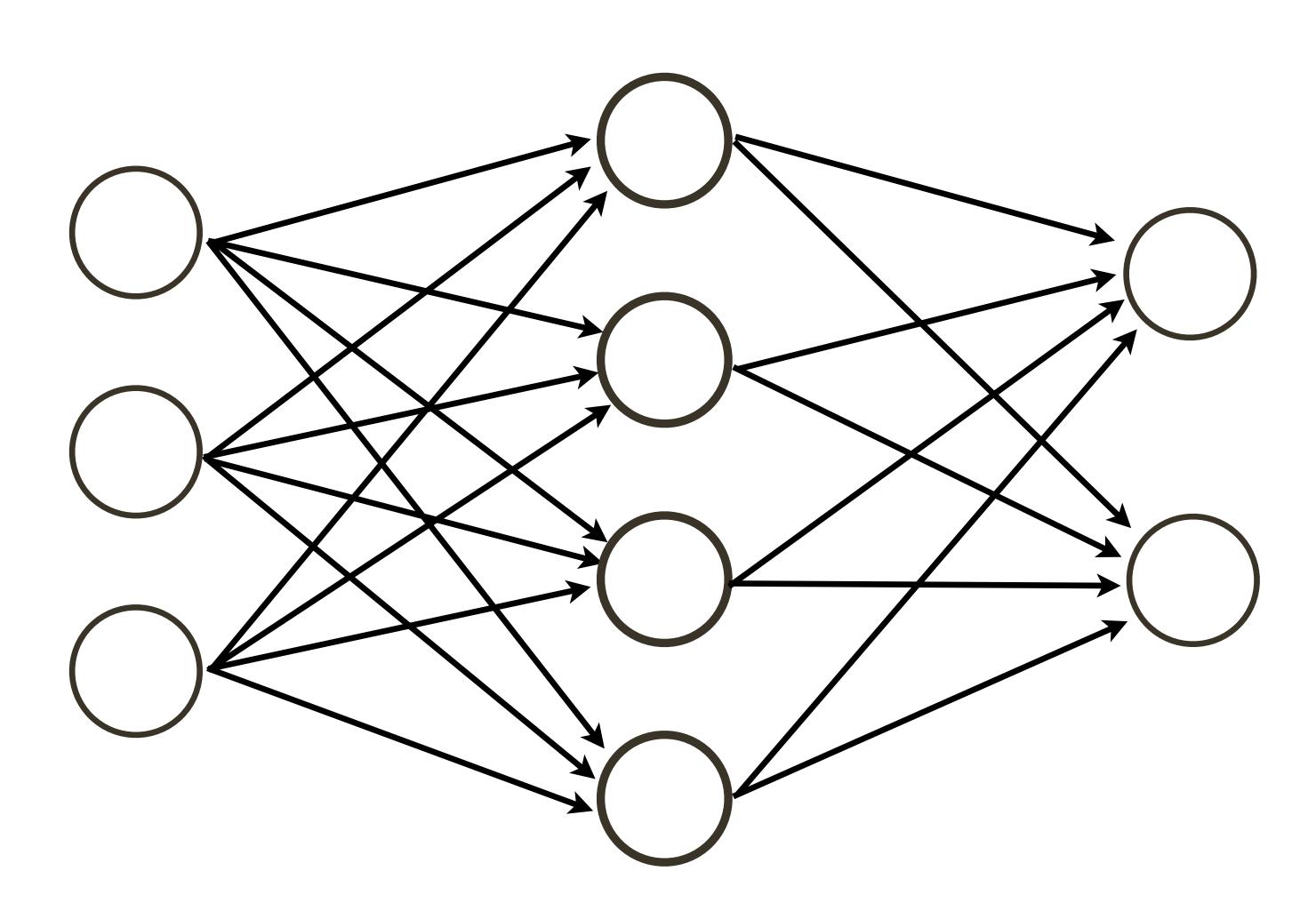




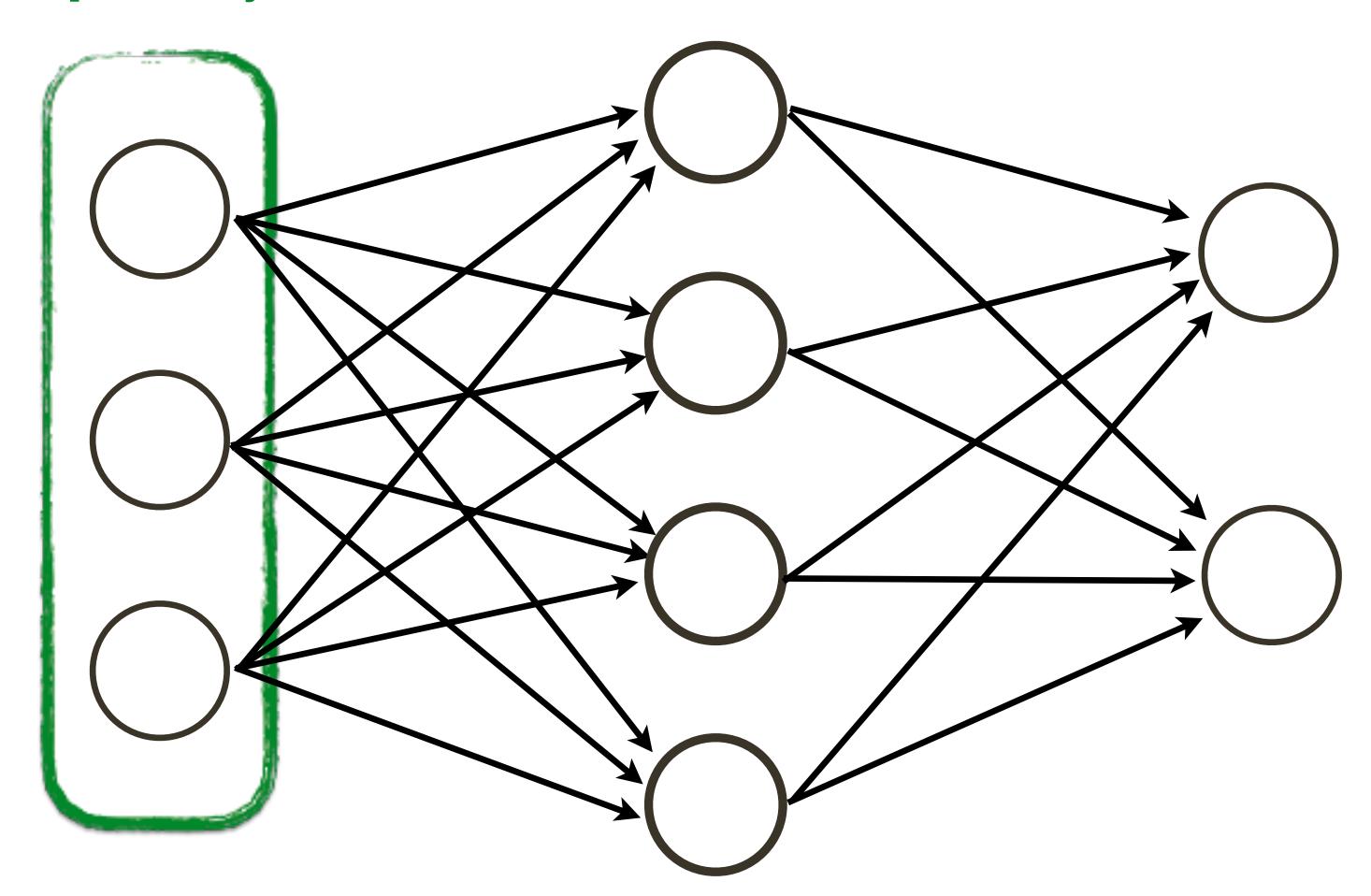




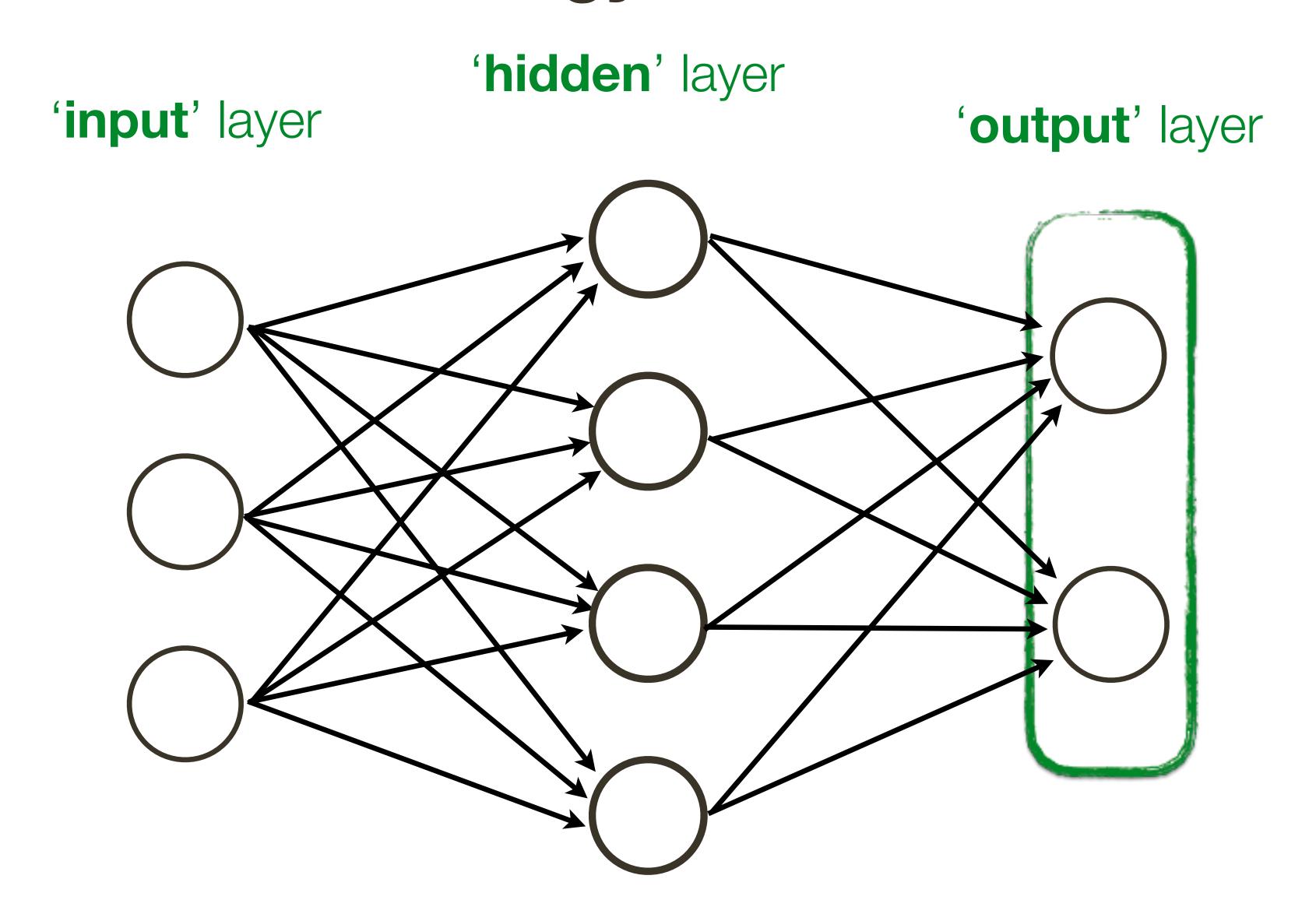
This network is also called a Multi-layer Perceptron (MLP)

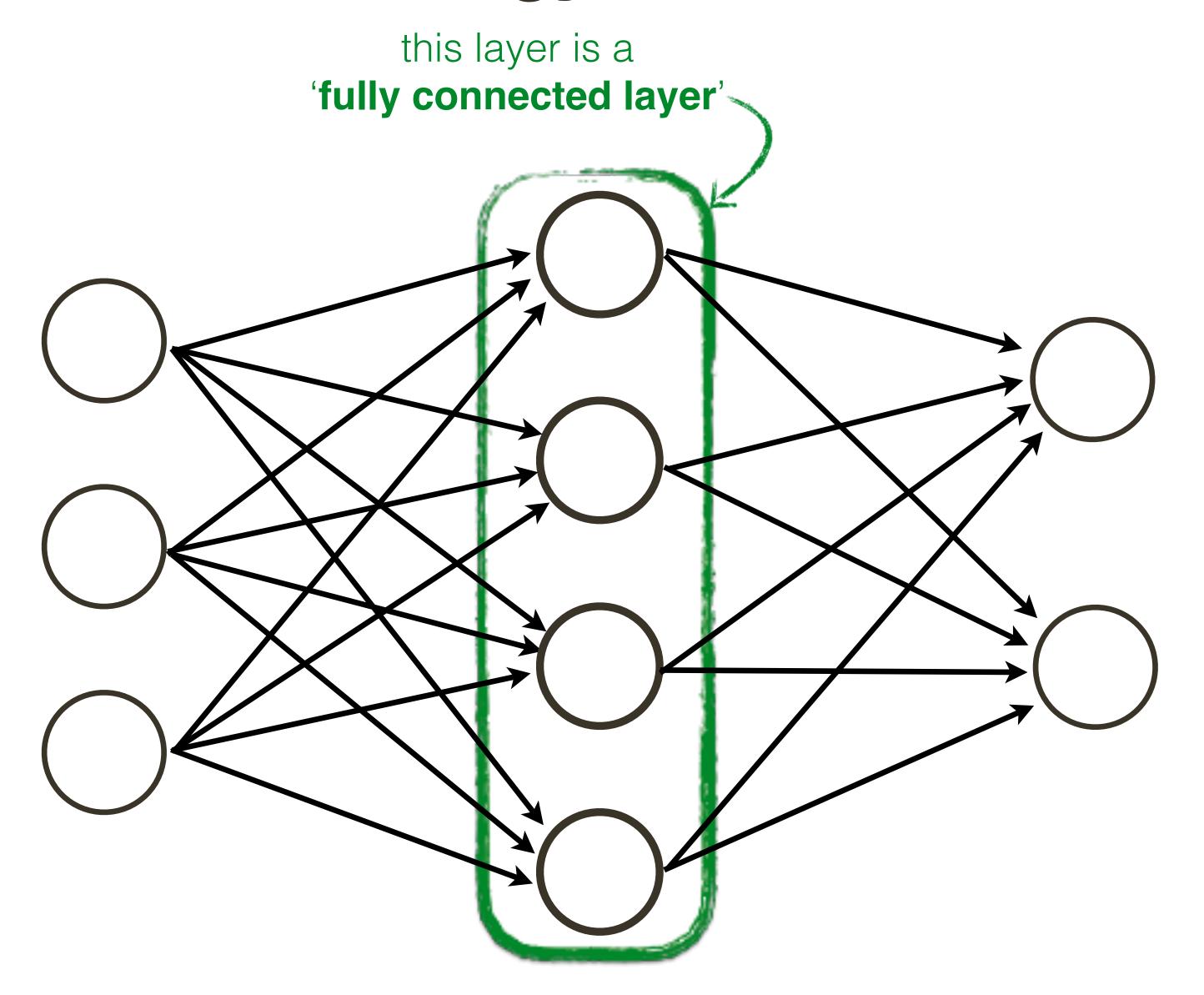


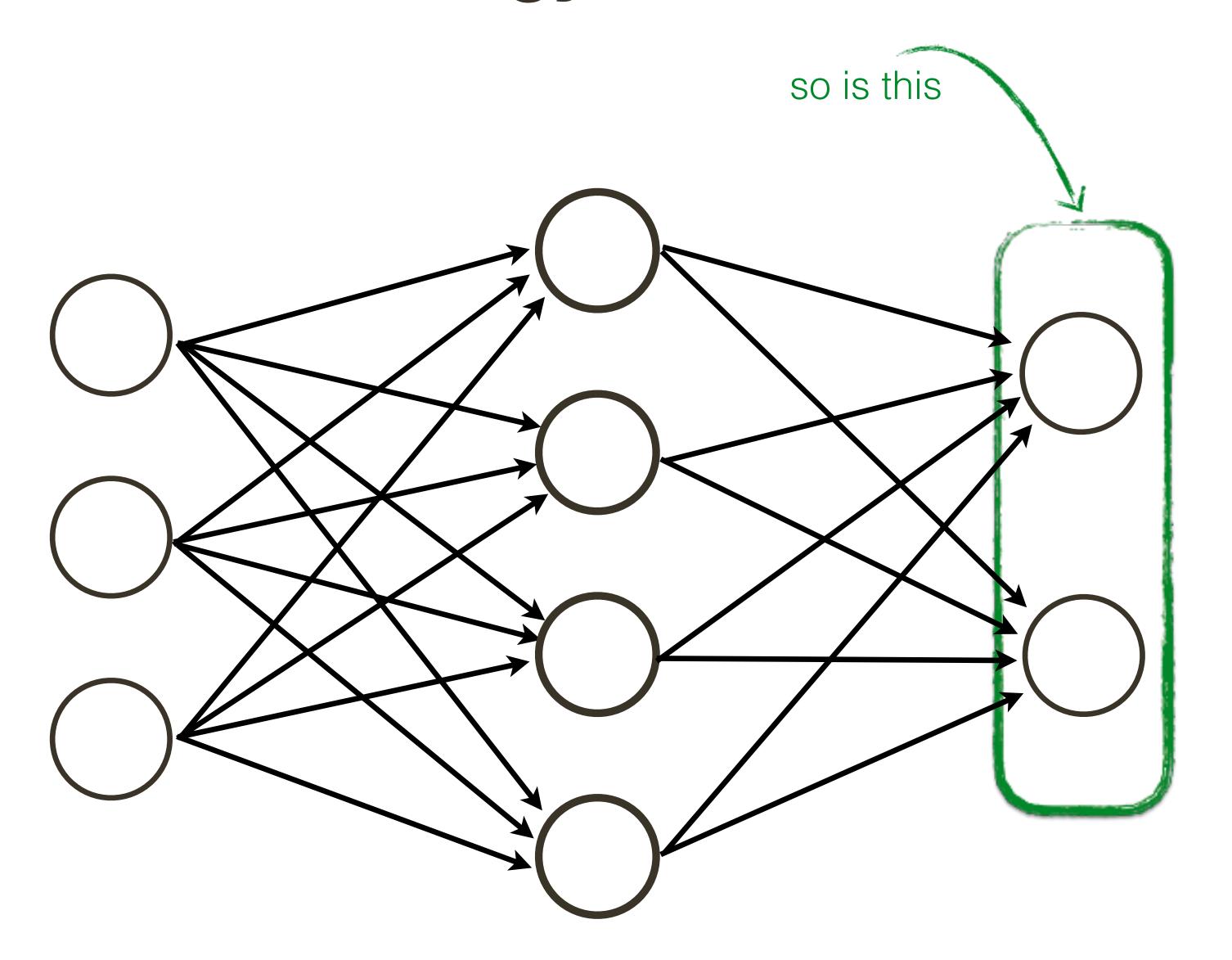
'input' layer



'hidden' layer 'input' layer







A neural network comprises neurons connected in an acyclic graph. The outputs of neurons can become inputs to other neurons. Neural networks typically contain multiple layers of neurons.

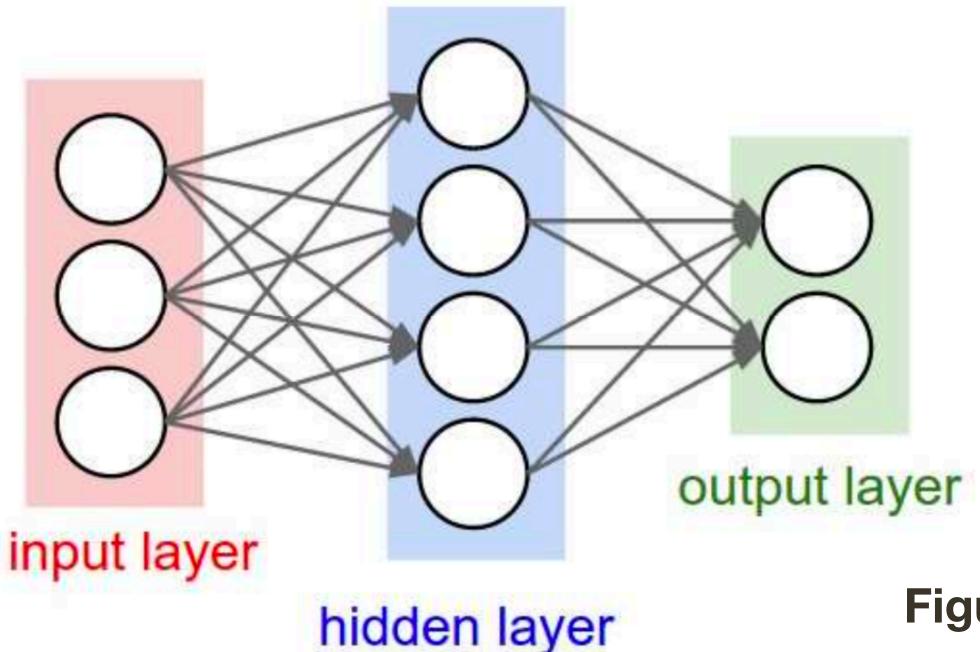


Figure credit: Fei-Fei and Karpathy

Example of a neural network with three inputs, a single hidden layer of four neurons, and an output layer of two neurons

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Question: What does a hidden unit do?

Answer: It can be thought of as classifier or a feature.

Question: Why have many layers?

**Answer:** 1) More layers = more complex functional mapping

2) More efficient due to distributed representation

A neural network comprises neurons connected in an acyclic graph. The outputs of neurons can become inputs to other neurons. Neural networks typically contain multiple layers of neurons.

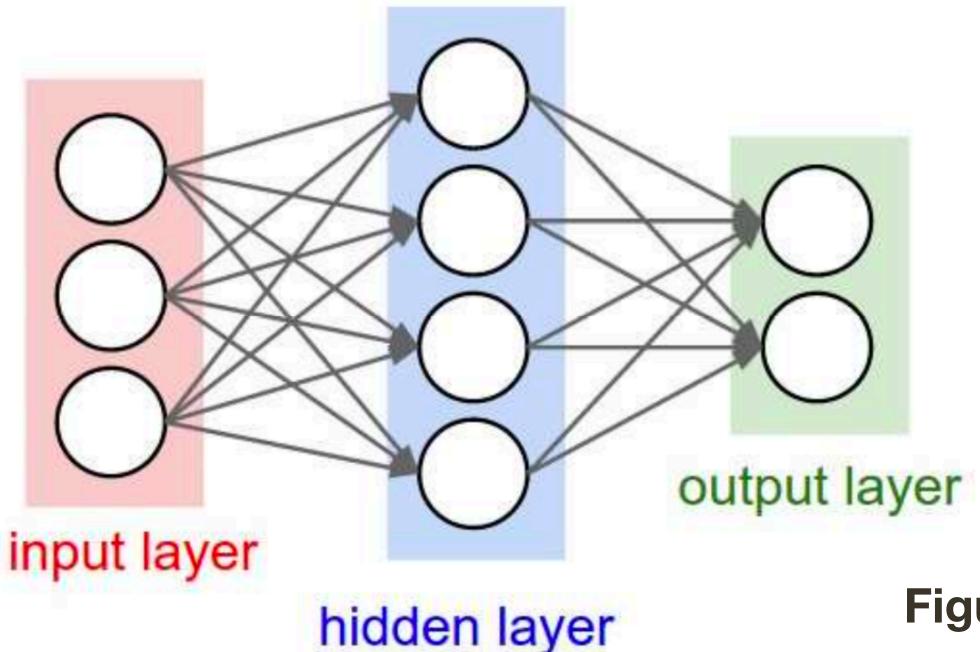
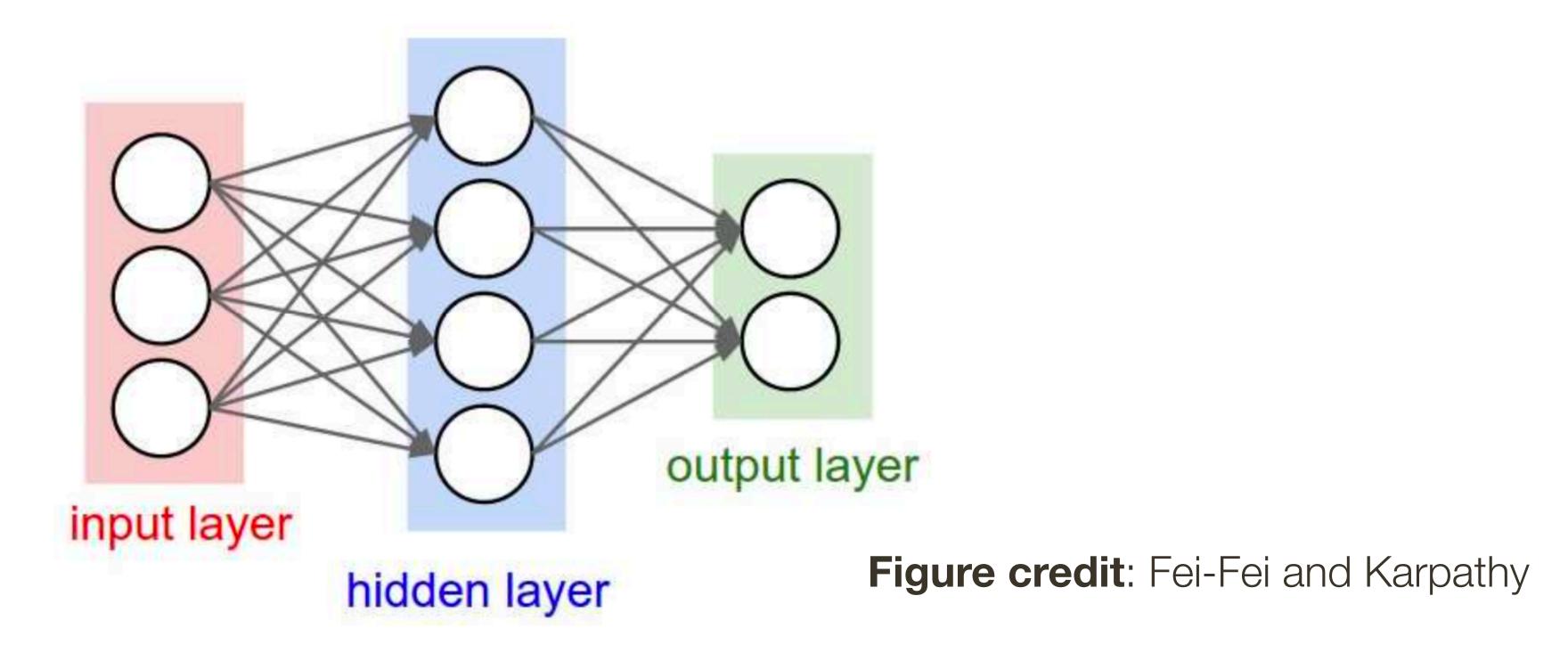


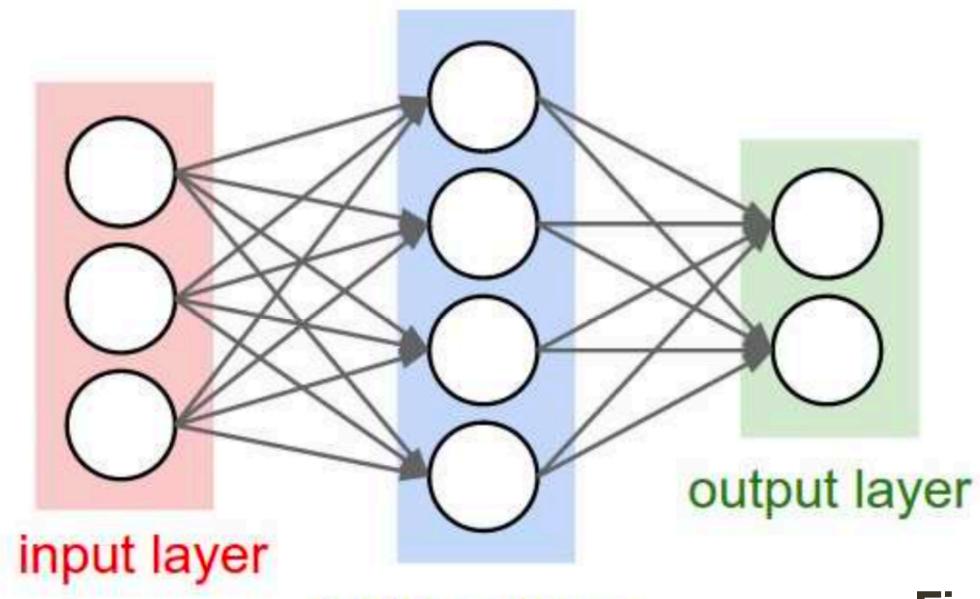
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Example of a neural network with three inputs, a single hidden layer of four neurons, and an output layer of two neurons

**Note**: each neuron will have its own vector of weights and a bias, its easier to think of all neurons in a layer as a single entity with a matrix of weights (size = number of inputs x number of neurons) and a vector of biases (size = number of neurons)



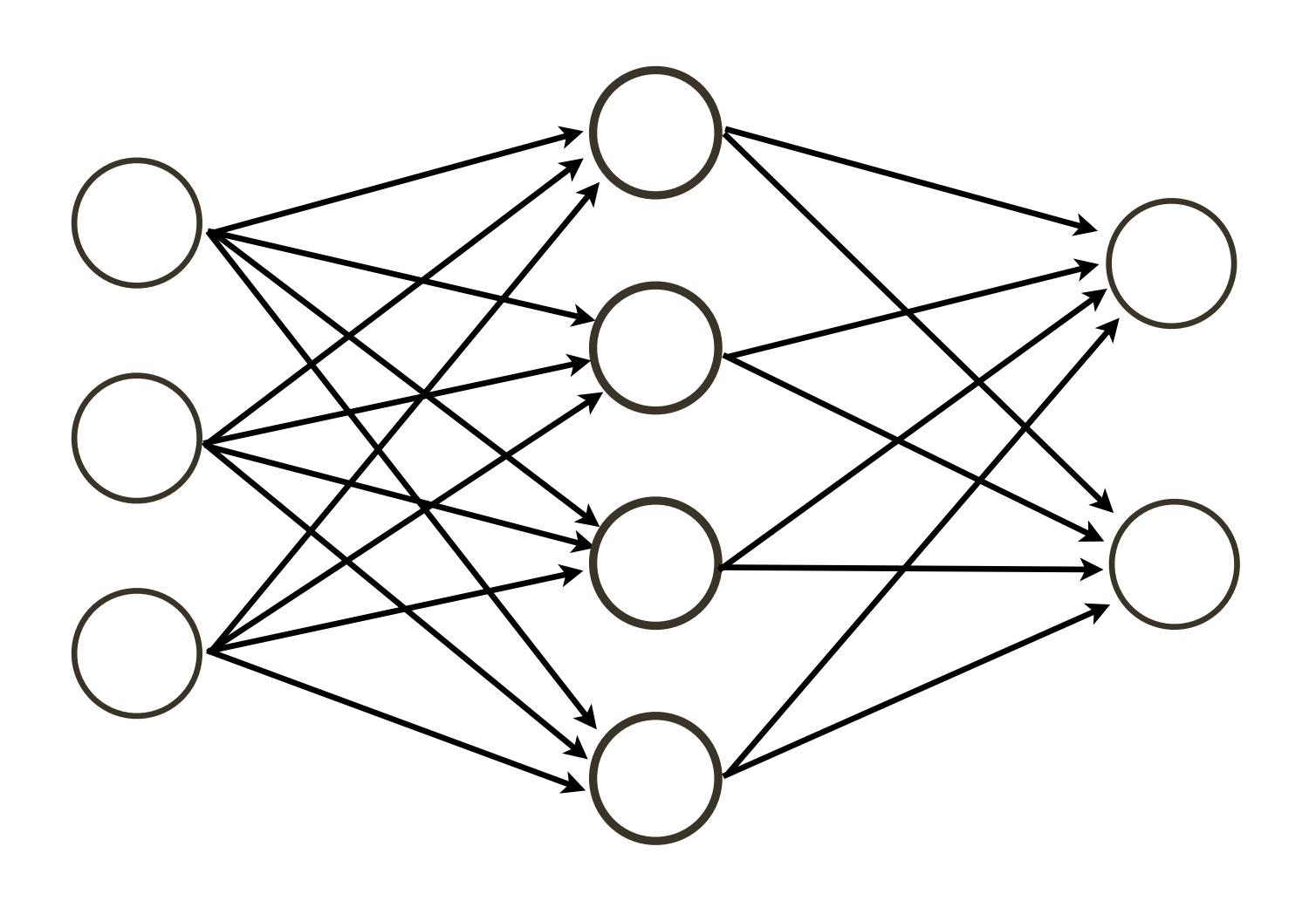
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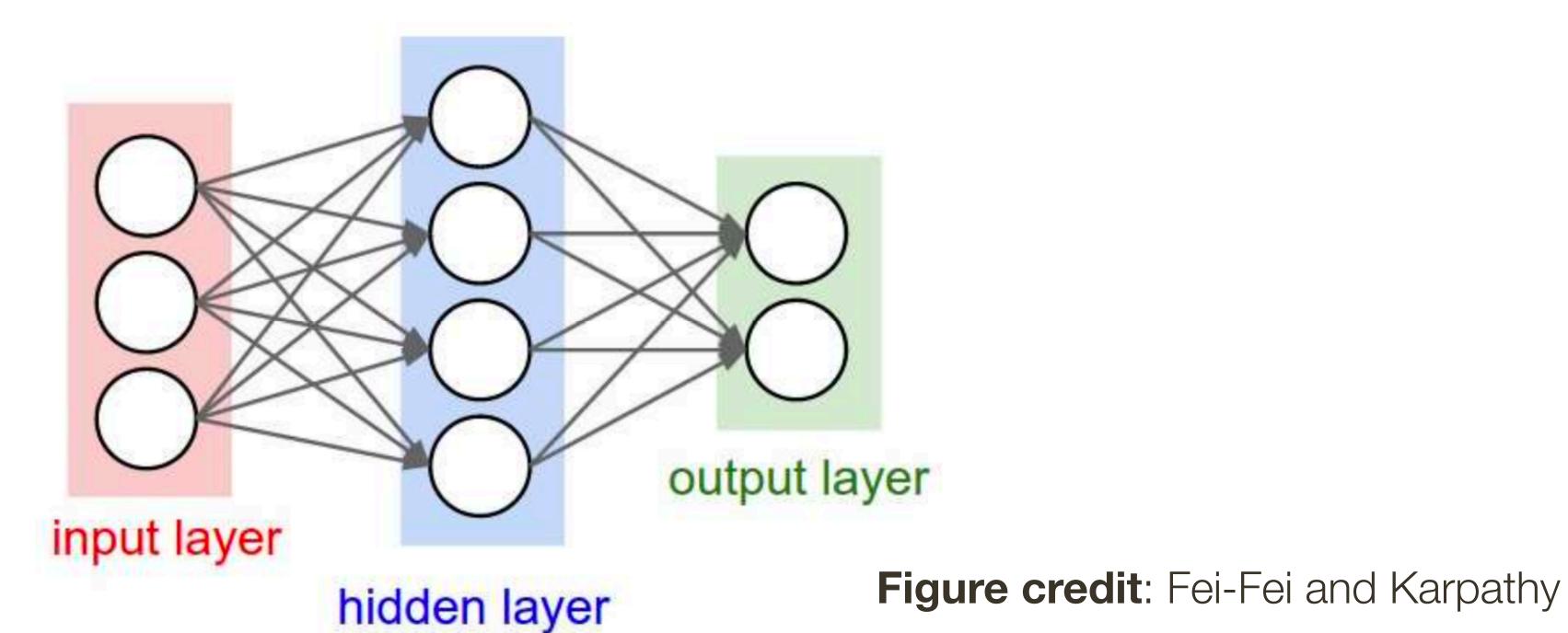
hidden layer

$$\hat{\mathbf{y}} = f(\mathbf{x}, \mathbf{W}_1, \mathbf{W}_2, \mathbf{b}_1, \mathbf{b}_2) = \sigma \left( \mathbf{W}_2^{(2 \times 4)} \sigma \left( \mathbf{W}_1^{(4 \times 3)} \mathbf{x} + \mathbf{b}_1^{(4)} \right) + \mathbf{b}_2^{(2)} \right)$$

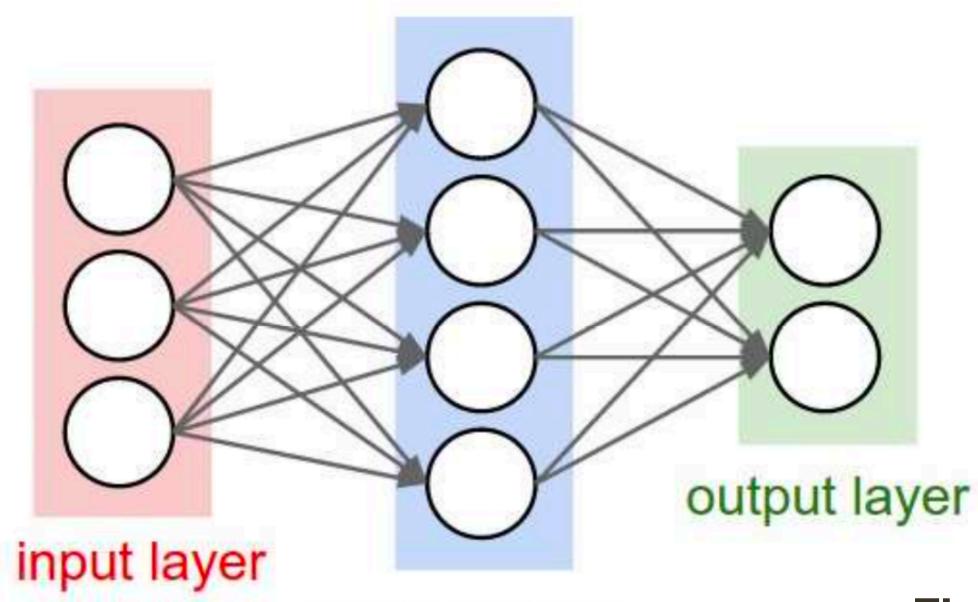
Why can't we have linear activation functions? Why have non-linear activations?



$$\hat{\mathbf{y}} = f(\mathbf{x}, \mathbf{W}_1, \mathbf{W}_2, \mathbf{b}_1, \mathbf{b}_2) = \sigma \left( \mathbf{W}_2^{(2 \times 4)} \sigma \left( \mathbf{W}_1^{(4 \times 3)} \mathbf{x} + \mathbf{b}_1^{(4)} \right) + \mathbf{b}_2^{(2)} \right)$$



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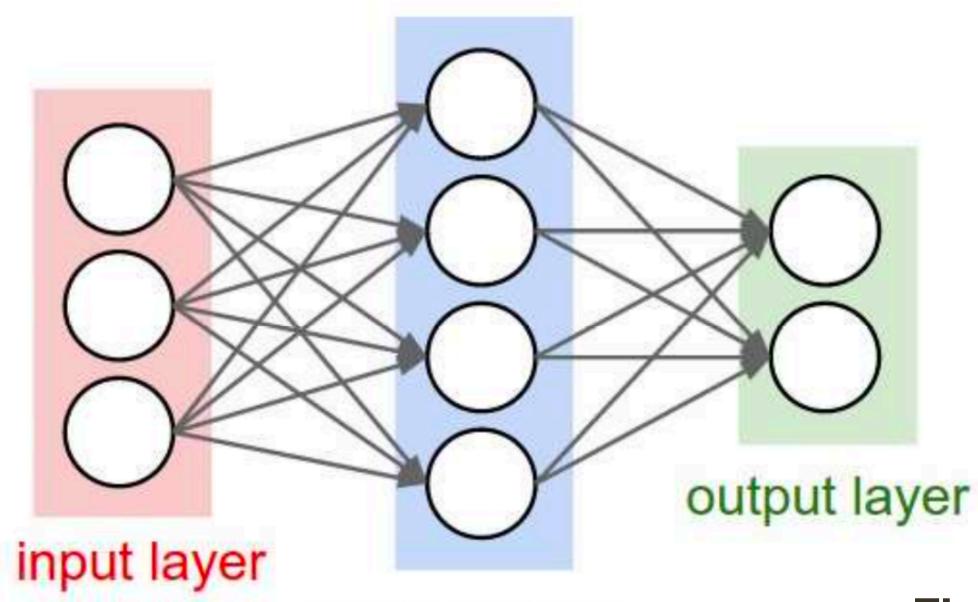


hidden layer

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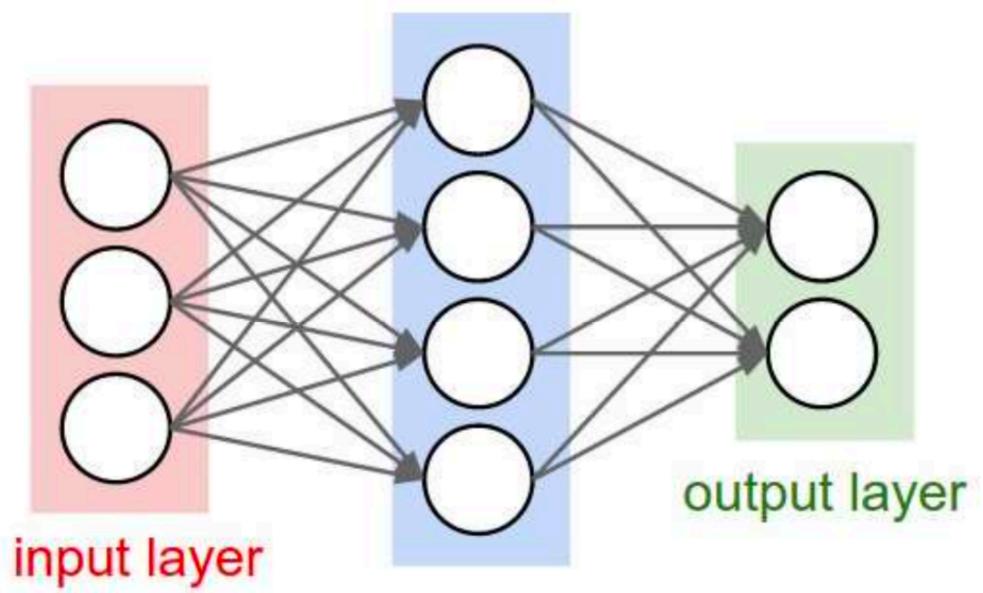
$$= \mathbf{W}_2^{(2 \times 4)} \left( \mathbf{W}_1^{(4 \times 3)} \mathbf{x} + \mathbf{b}_1^{(4)} \right) + \mathbf{b}_2^{(2)}$$

$$= \mathbf{W}_2^{(2 \times 4)} \mathbf{W}_1^{(4 \times 3)} \mathbf{x} + \mathbf{W}_2^{(2 \times 4)} \mathbf{b}_1^{(4)} + \mathbf{b}_2^{(2)}$$



hidden layer

$$\hat{\mathbf{y}} = f(\mathbf{x}, \mathbf{W}_1, \mathbf{W}_2, \mathbf{b}_1, \mathbf{b}_2) = \sigma \left( \mathbf{W}_2^{(2 \times 4)} \sigma \left( \mathbf{W}_1^{(4 \times 3)} \mathbf{x} + \mathbf{b}_1^{(4)} \right) + \mathbf{b}_2^{(2)} \right) \\
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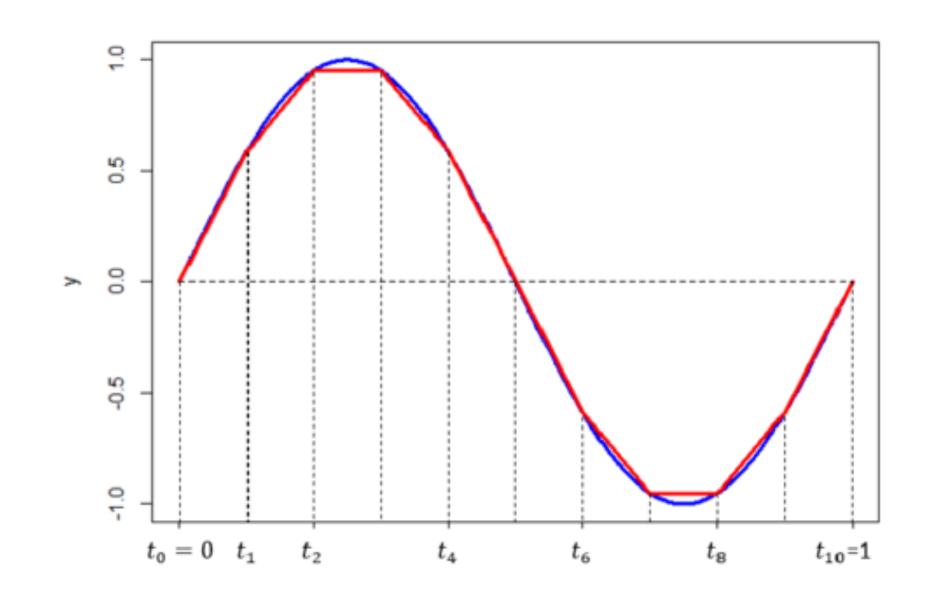
hidden layer

Non-linear activation is required to provably make the Neural Net a universal function approximator

**Intuition**: with ReLU activation, we effectively get a linear spline approximation to any function.

Optimization of neural net parameters = finding slops and transitions of linear pieces

The quality of approximation depends on the number of linear segments



Number of linear segments for large input dimension:  $\Omega(2^{\frac{2}{3}Ln})$ 

## Light Theory: Neural Network as Universal Approximator

**Universal Approximation Theorem**: Single hidden layer can approximate any continuous function with compact support to arbitrary accuracy, when the width goes to infinity.

[Hornik et al., 1989]

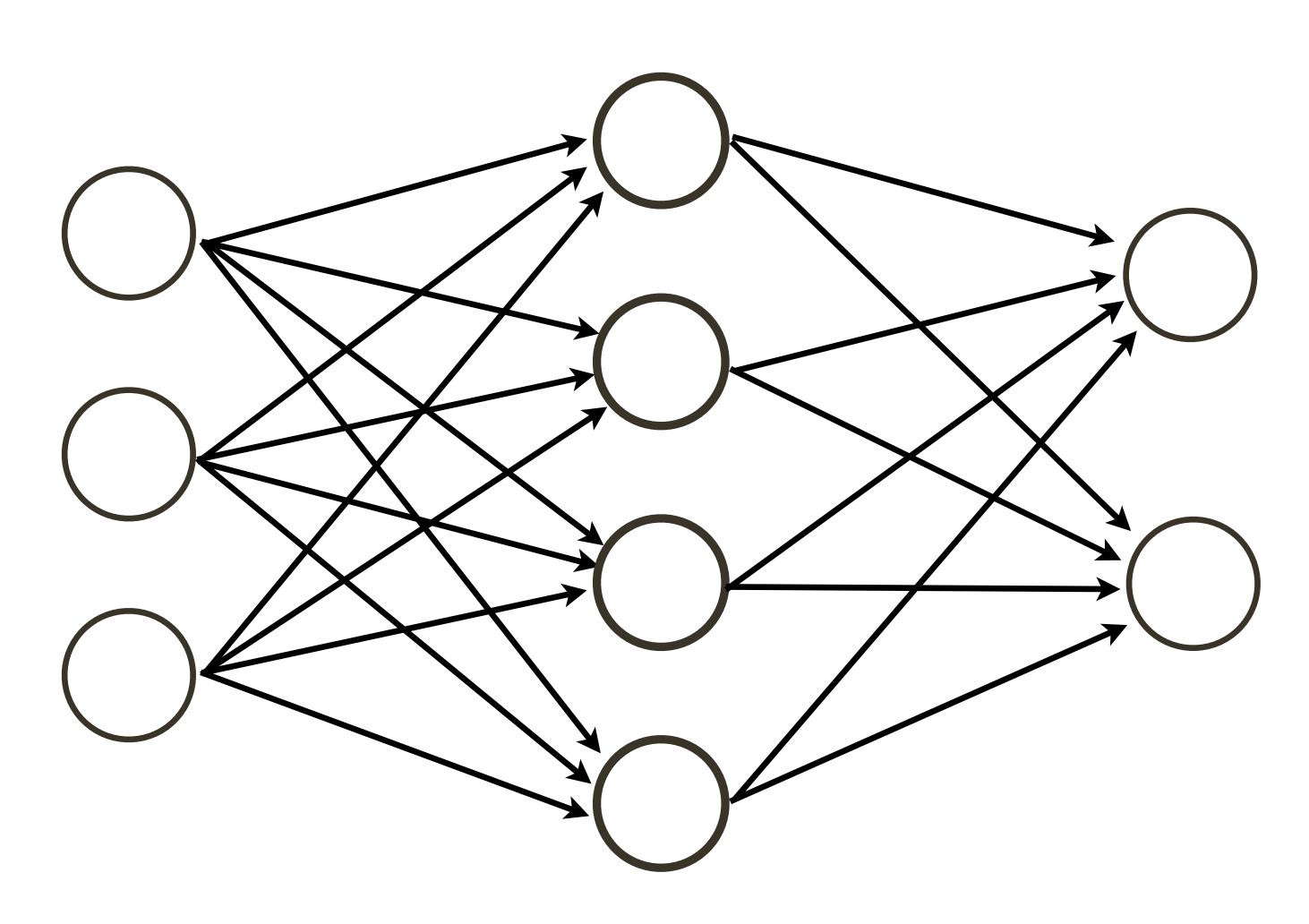
**Universal Approximation Theorem (revised)**: A network of infinite depth with a hidden layer of size d+1 neurons, where d is the dimension of the input space, can approximate any continuous function.

[ Lu et al., NIPS 2017 ]

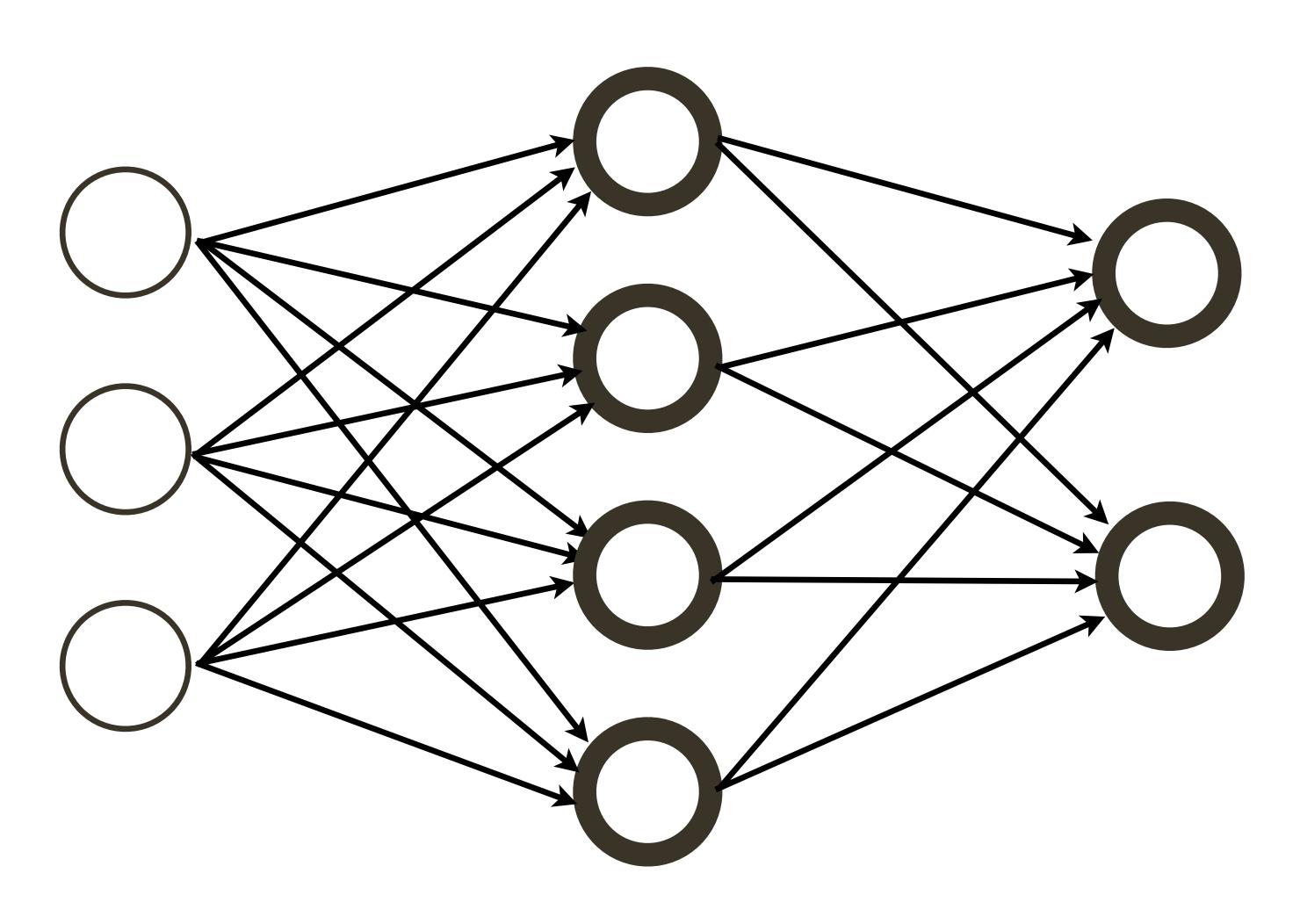
Universal Approximation Theorem (further revised): ResNet with a single hidden unit and infinite depth can approximate any continuous function.

[Lin and Jegelka, NIPS 2018]

How many neurons?



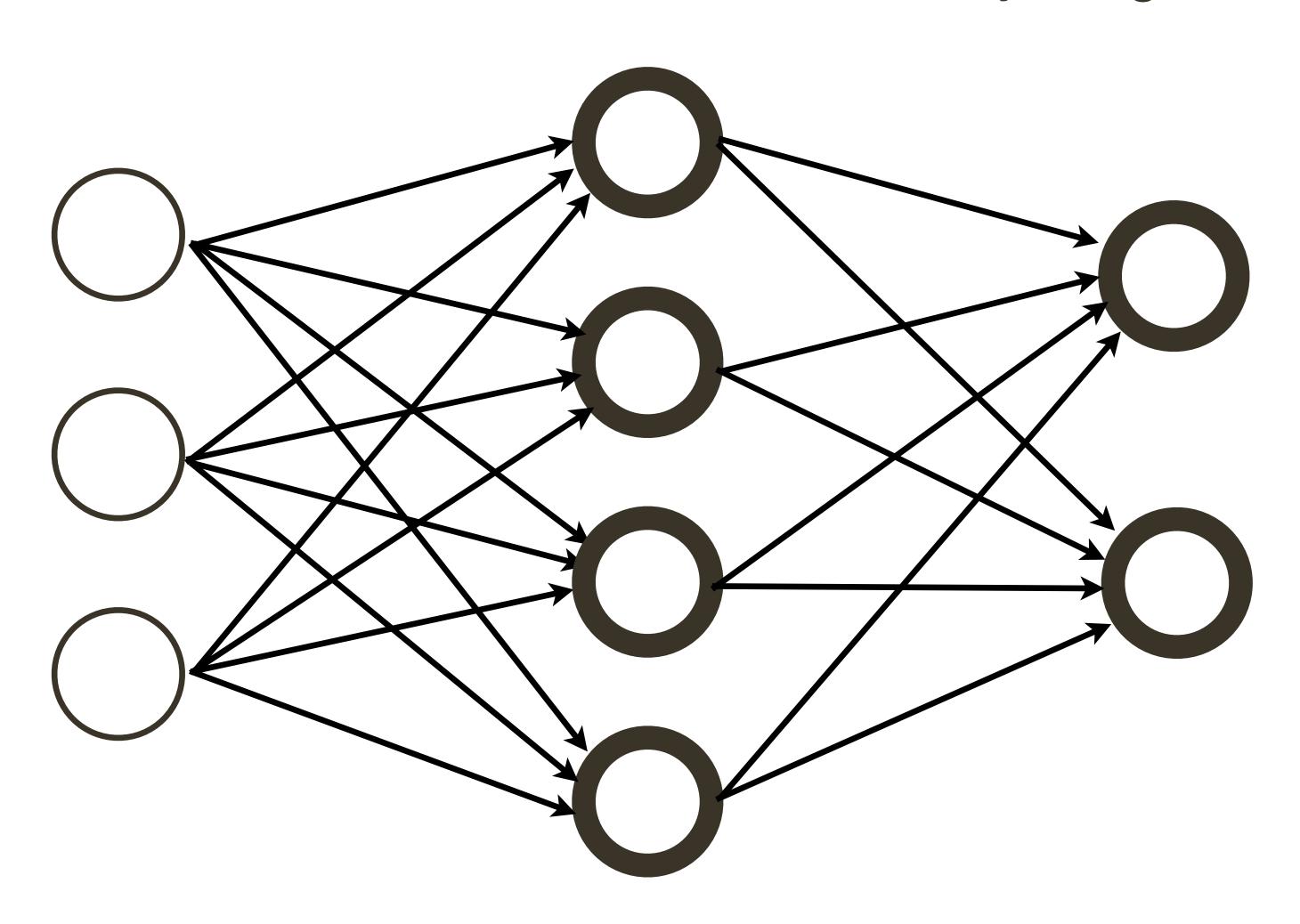
How many neurons? 4+2=6



How many neurons? 4+2=6

$$4+2 = 6$$

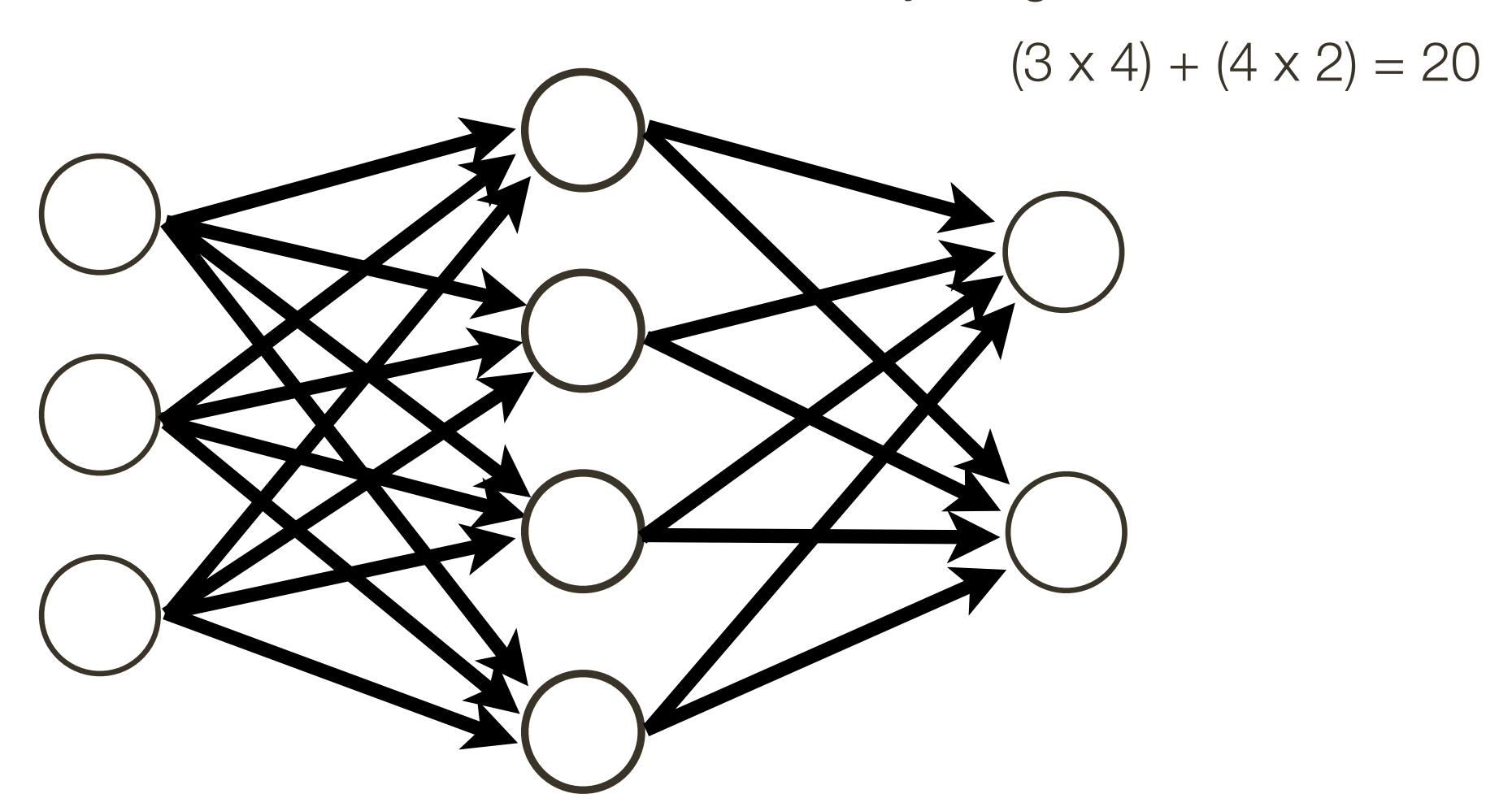
How many weights?



How many neurons? 4+2=6

$$4+2=6$$

How many weights?



How many neurons? 4+2=6

How many weights?

 $(3 \times 4) + (4 \times 2) = 20$ 

How many learnable parameters?

How many neurons? 4+2=6

How many weights?

$$(3 \times 4) + (4 \times 2) = 20$$

$$20 + 4 + 2 = 26$$
How many learnable parameters?

Modern **convolutional neural networks** contain 10-20 layers and on the order of 100 million parameters

Training a neural network requires estimating a large number of parameters

When training a neural network, the final output will be some loss (error) function

- e.g. cross-entropy loss: 
$$\mathcal{L} = -\sum_i y_i \log(\hat{y}_i)$$
  $\hat{y}_i = \frac{e^{f_{y_i}}}{\sum_j e^{f_{y_j}}}$ 

which defines loss for i-th training example with true class index  $y_i$ ; and  $f_j$  is the j-th element of the vector of class scores coming from neural net.

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$$c_1 = -2.85$$
 $c_2 = 0.86$ 
 $c_3 = 0.28$ 

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$$exp$$

$$0.058$$

$$0.058$$

$$sum to 1$$

$$0.016$$

$$0.0353$$

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$$\mathcal{L} = -\sum_i y_i \log(\hat{y}_i)$$
  $\hat{y}_i = \frac{e^{f_{y_i}}}{\sum_j e^{f_{y_j}}}$  softmax function multi-class classifier

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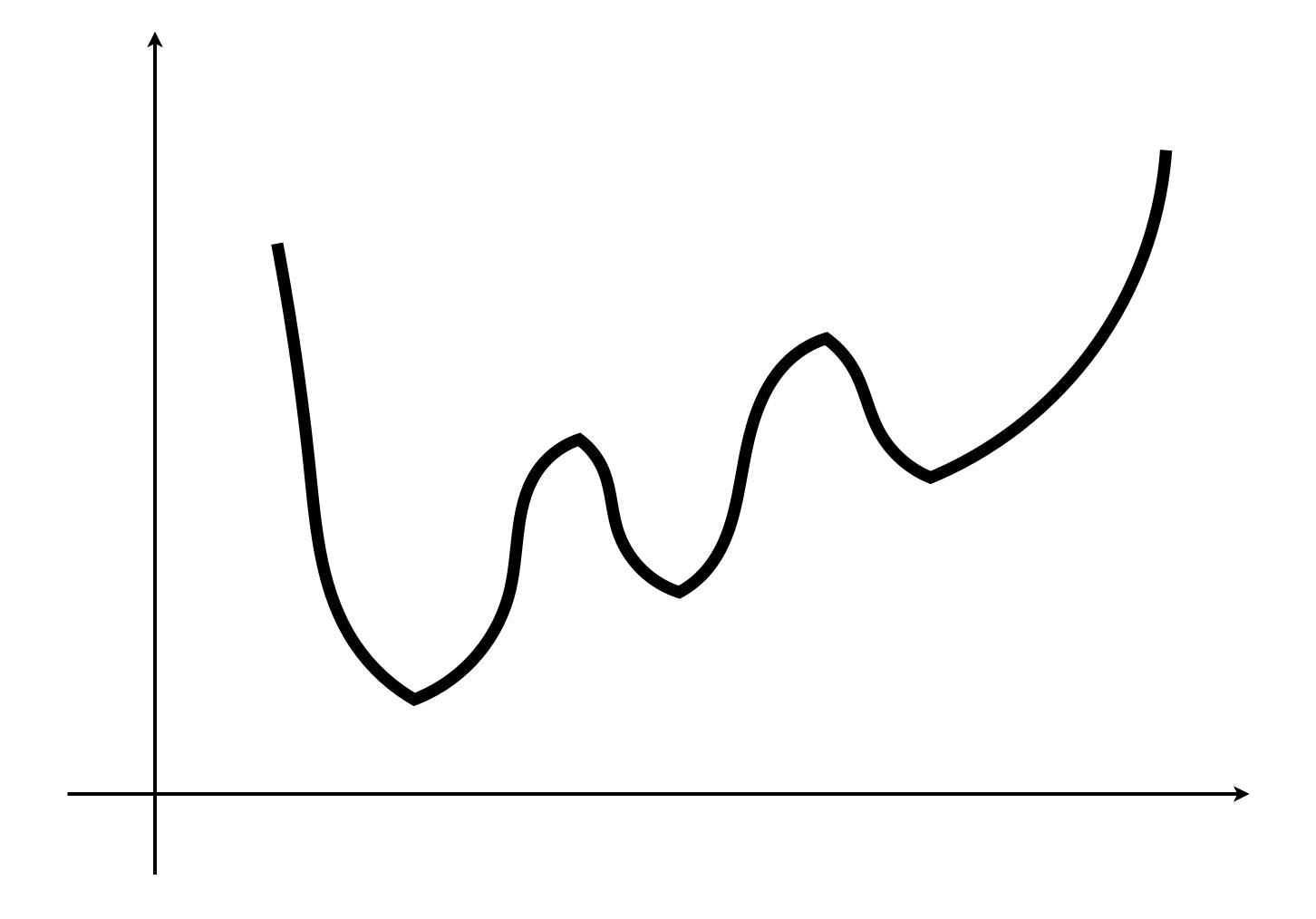
$$c_{10} = 0.016$$

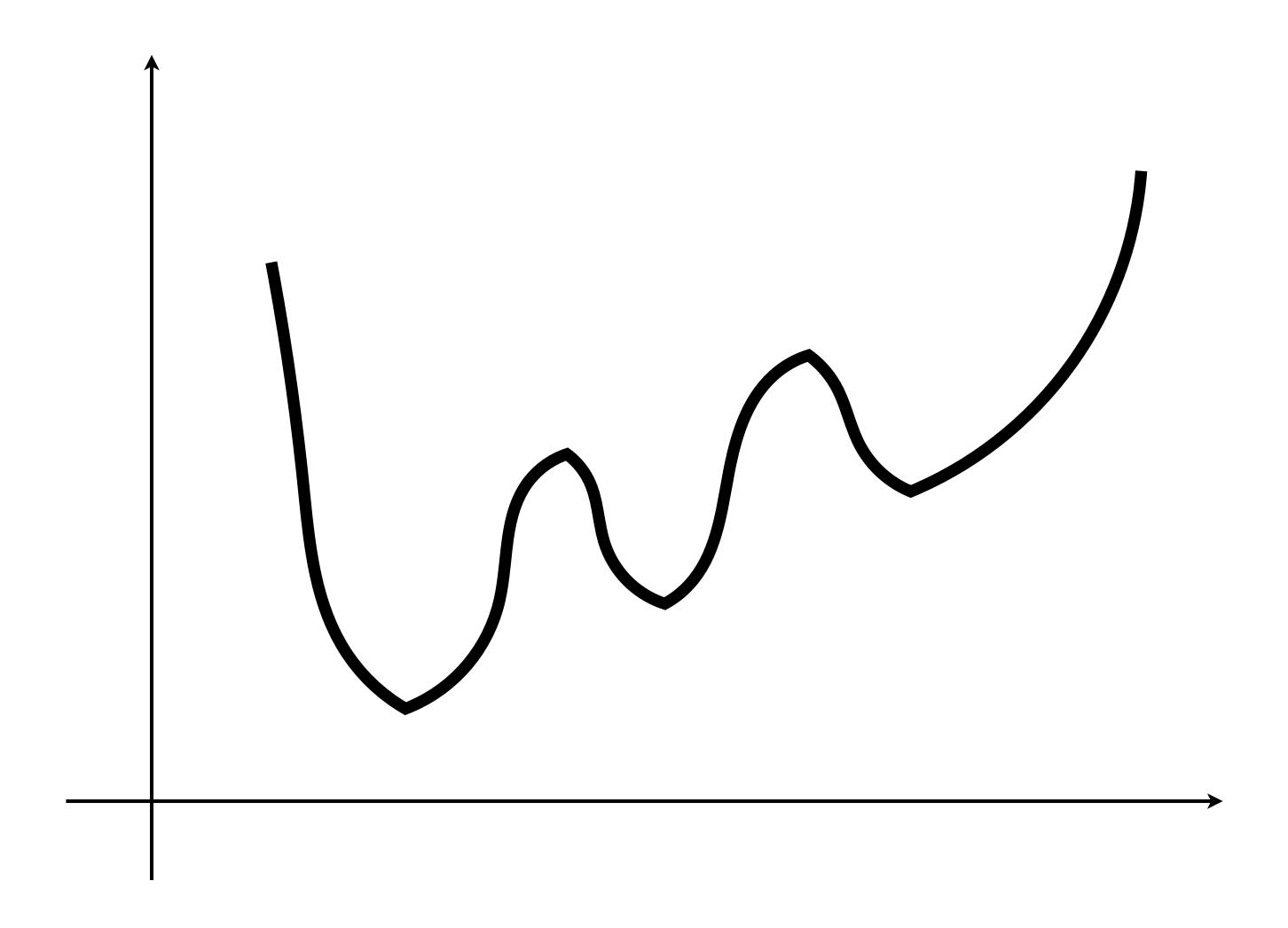
When training a neural network, the final output will be some loss (error) function

- e.g. cross-entropy loss: 
$$\mathcal{L} = -\sum_i y_i \log(\hat{y}_i)$$
  $\hat{y}_i = \frac{e^{f_{y_i}}}{\sum_j e^{f_{y_j}}}$ 

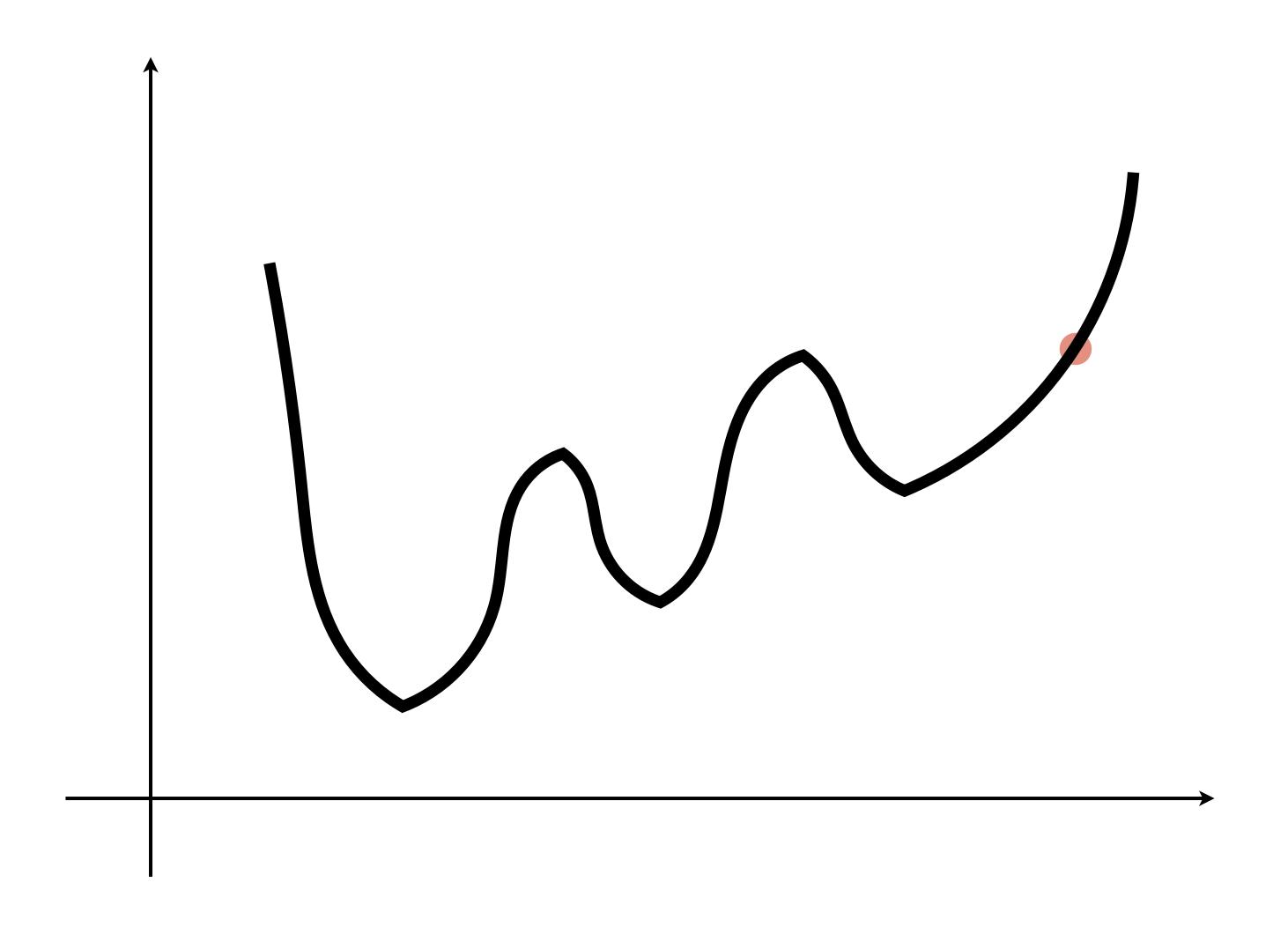
which defines loss for i-th training example with true class index  $y_i$ ; and  $f_j$  is the j-th element of the vector of class scores coming from neural net.

We want to compute the **gradient** of the loss with respect to the network parameters so that we can incrementally adjust the network parameters

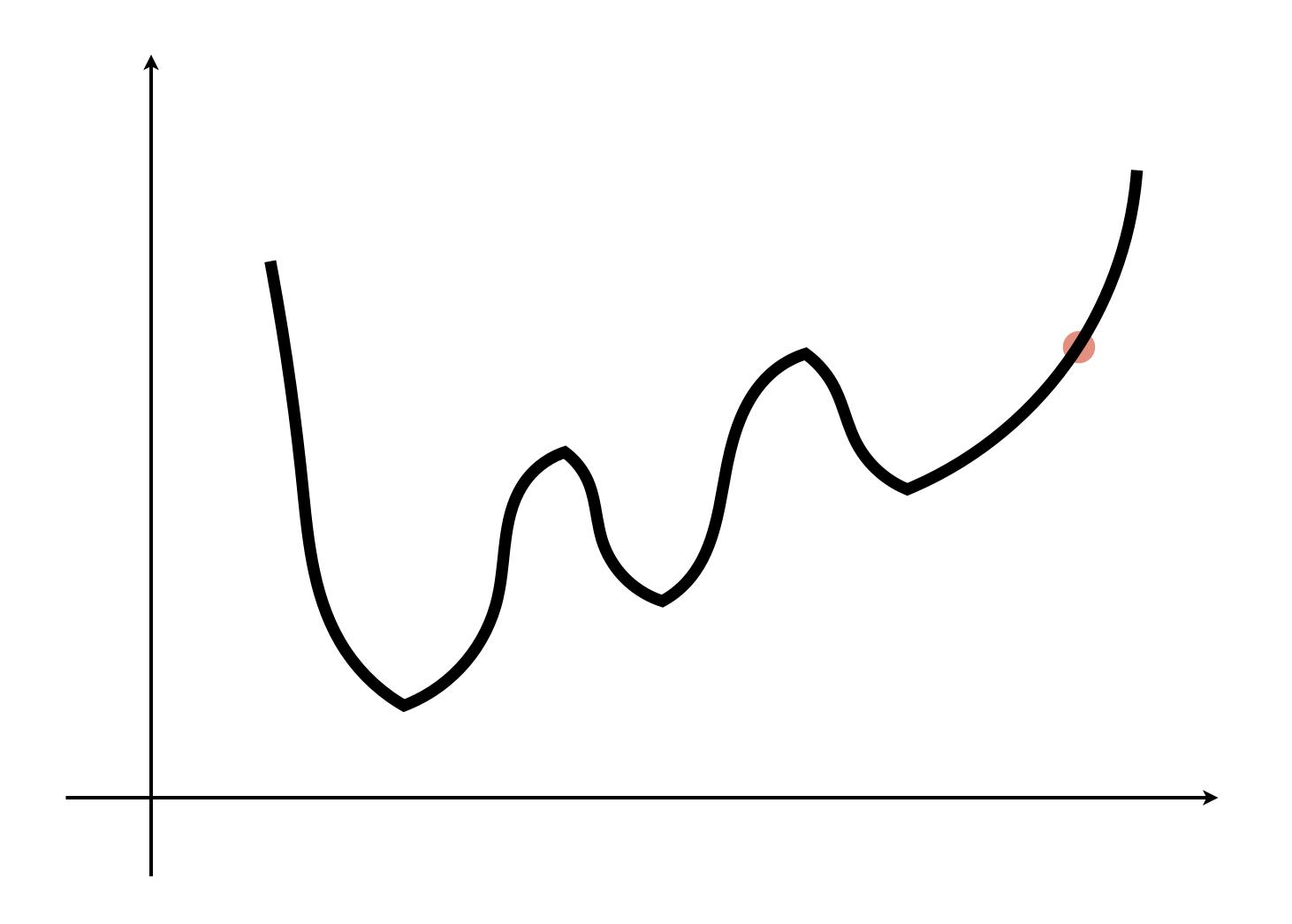




1. Start from random value of  $\mathbf{W}_0, \mathbf{b}_0$ 



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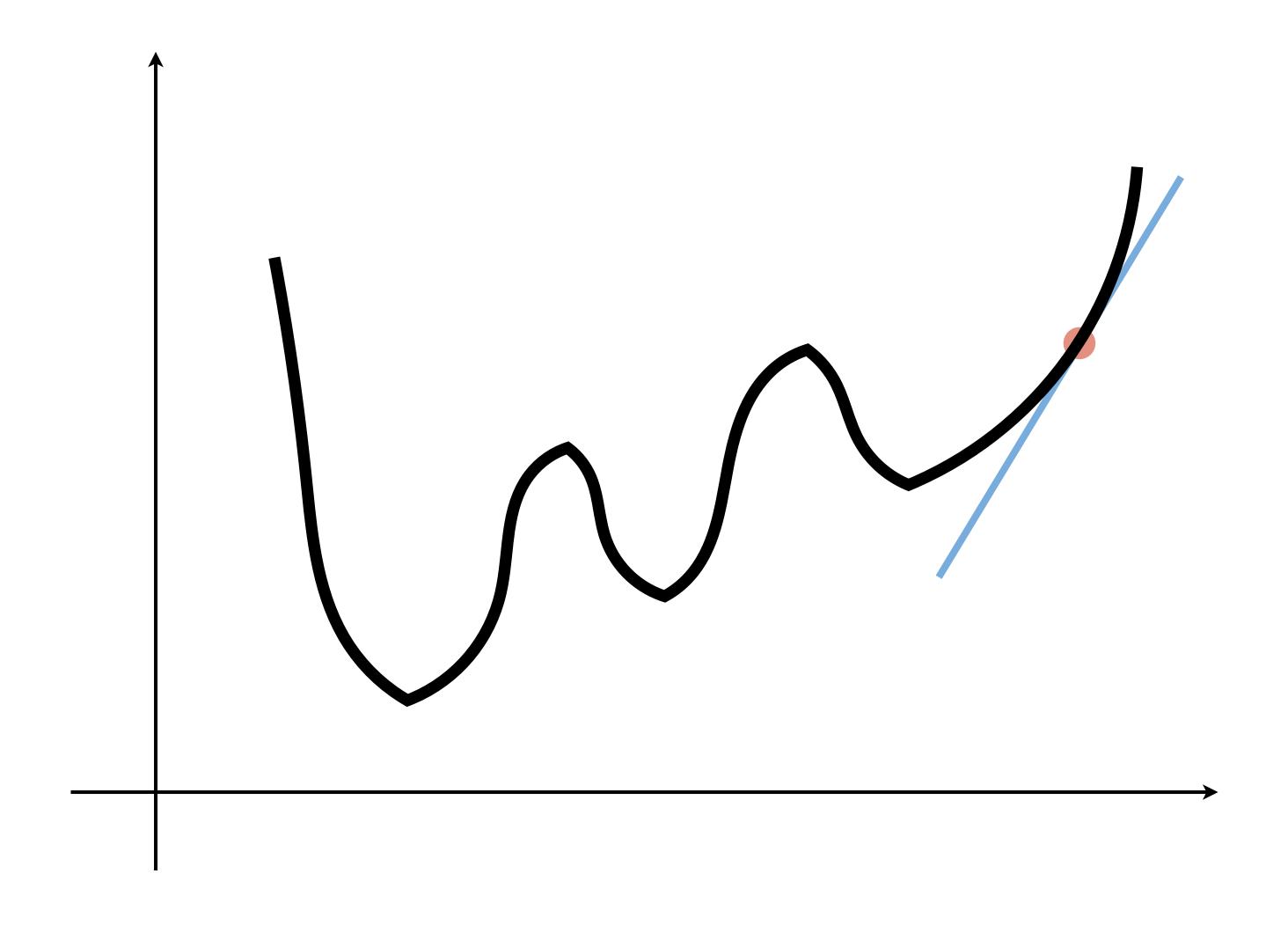


1. Start from random value of  $\mathbf{W}_0, \mathbf{b}_0$ 

For k = 0 to max number of iterations

2. Compute gradient of the loss with respect to previous (initial) parameters:

$$\left. 
abla \left. \mathcal{L}(\mathbf{W}, \mathbf{b}) \right|_{\mathbf{W} = \mathbf{W}_k, \mathbf{b} = \mathbf{b}_k}$$

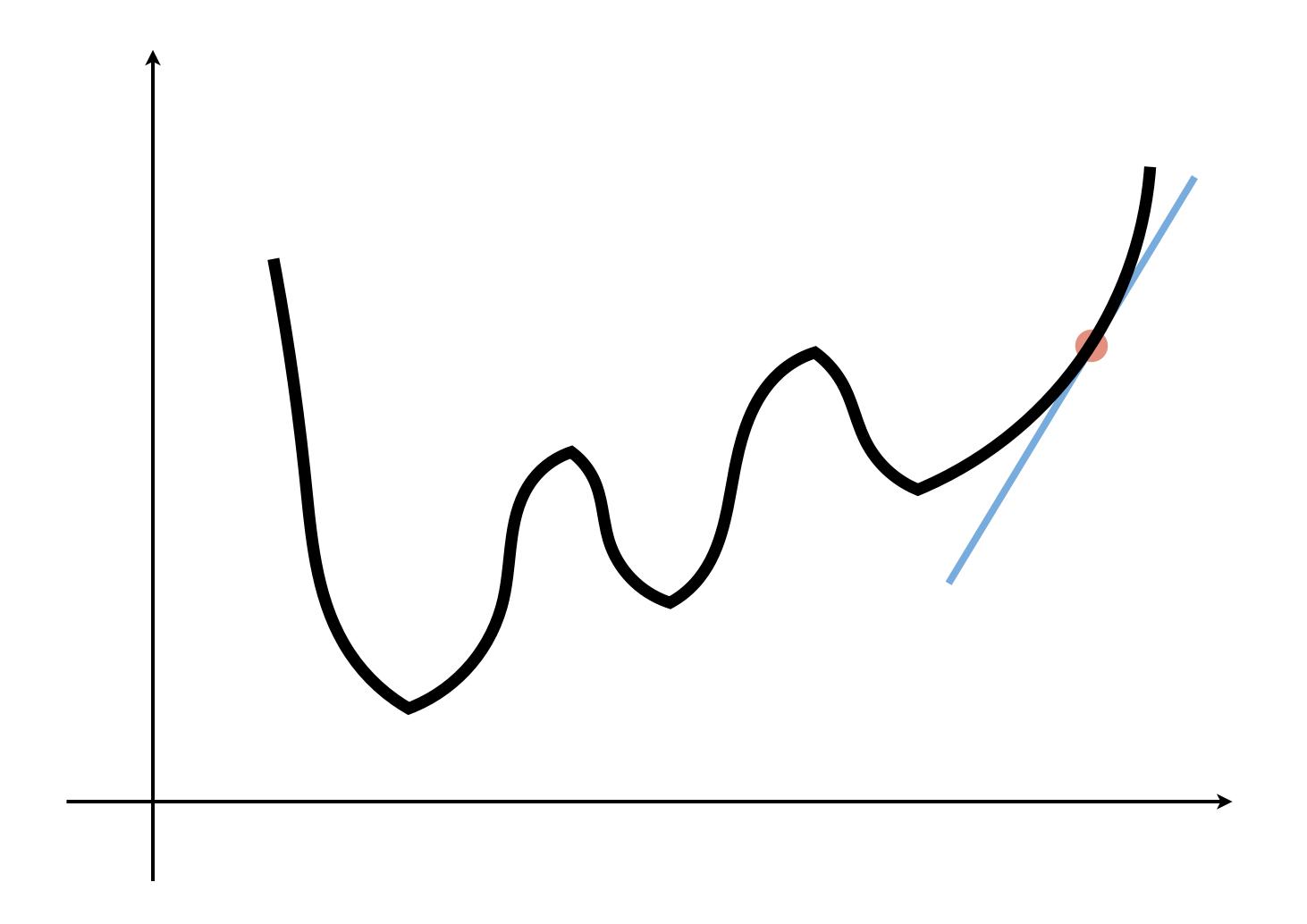


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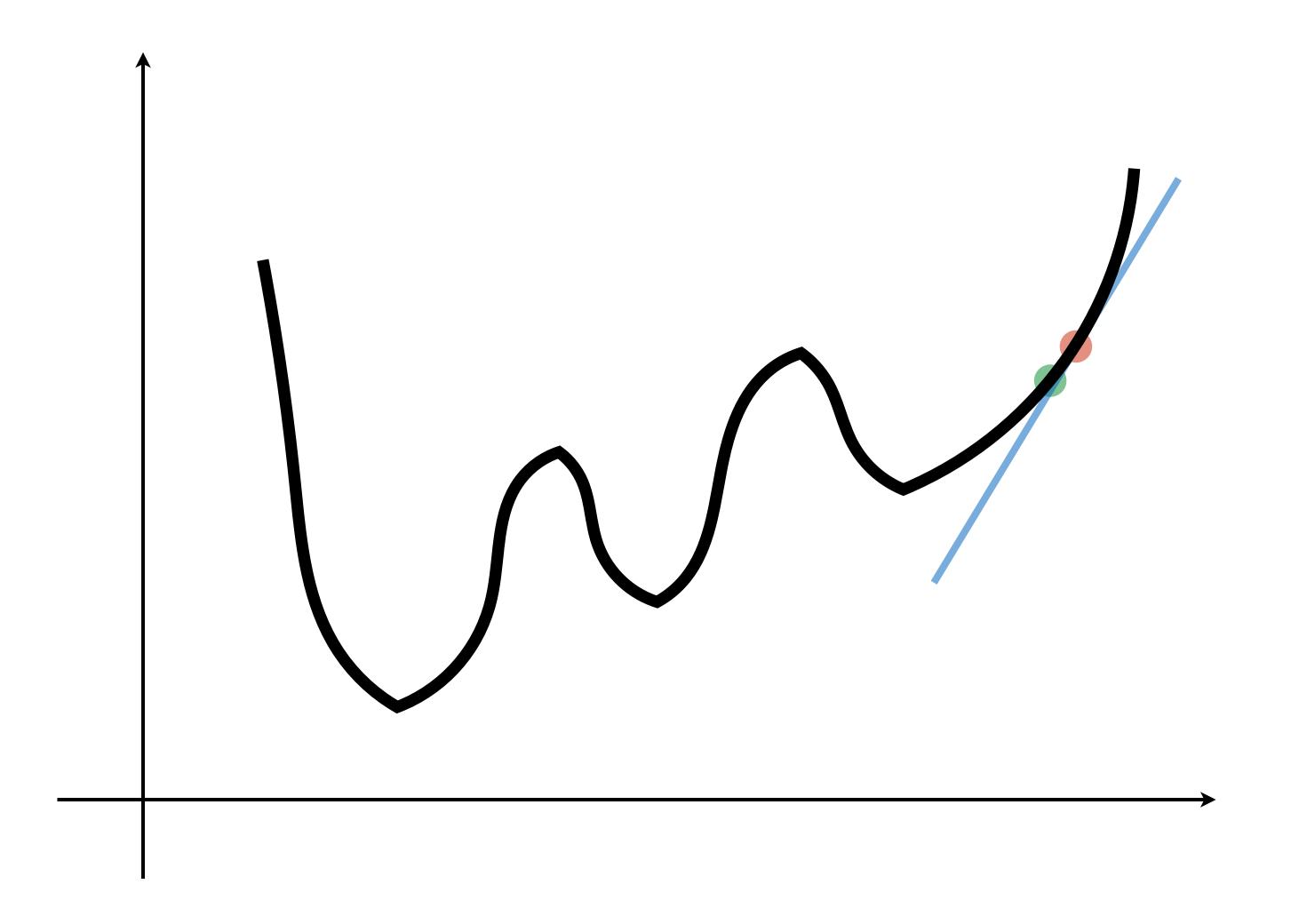
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$$\mathbf{W}_{k+1} = \mathbf{W}_k - \lambda \left. \frac{\partial \mathcal{L}(\mathbf{W}, \mathbf{b})}{\partial \mathbf{W}} \right|_{\mathbf{W} = \mathbf{W}_k, \mathbf{b} = \mathbf{b}_k}$$

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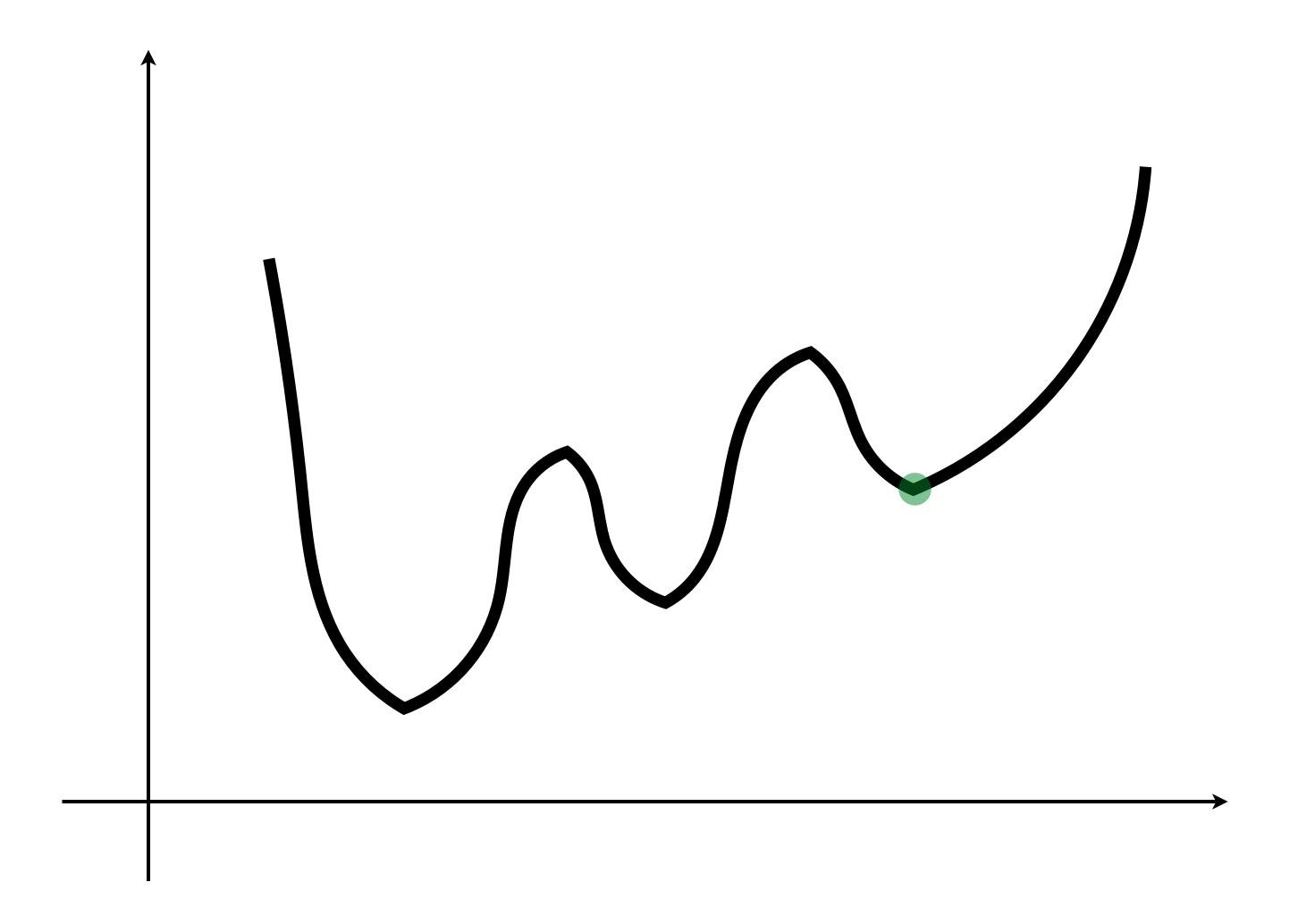
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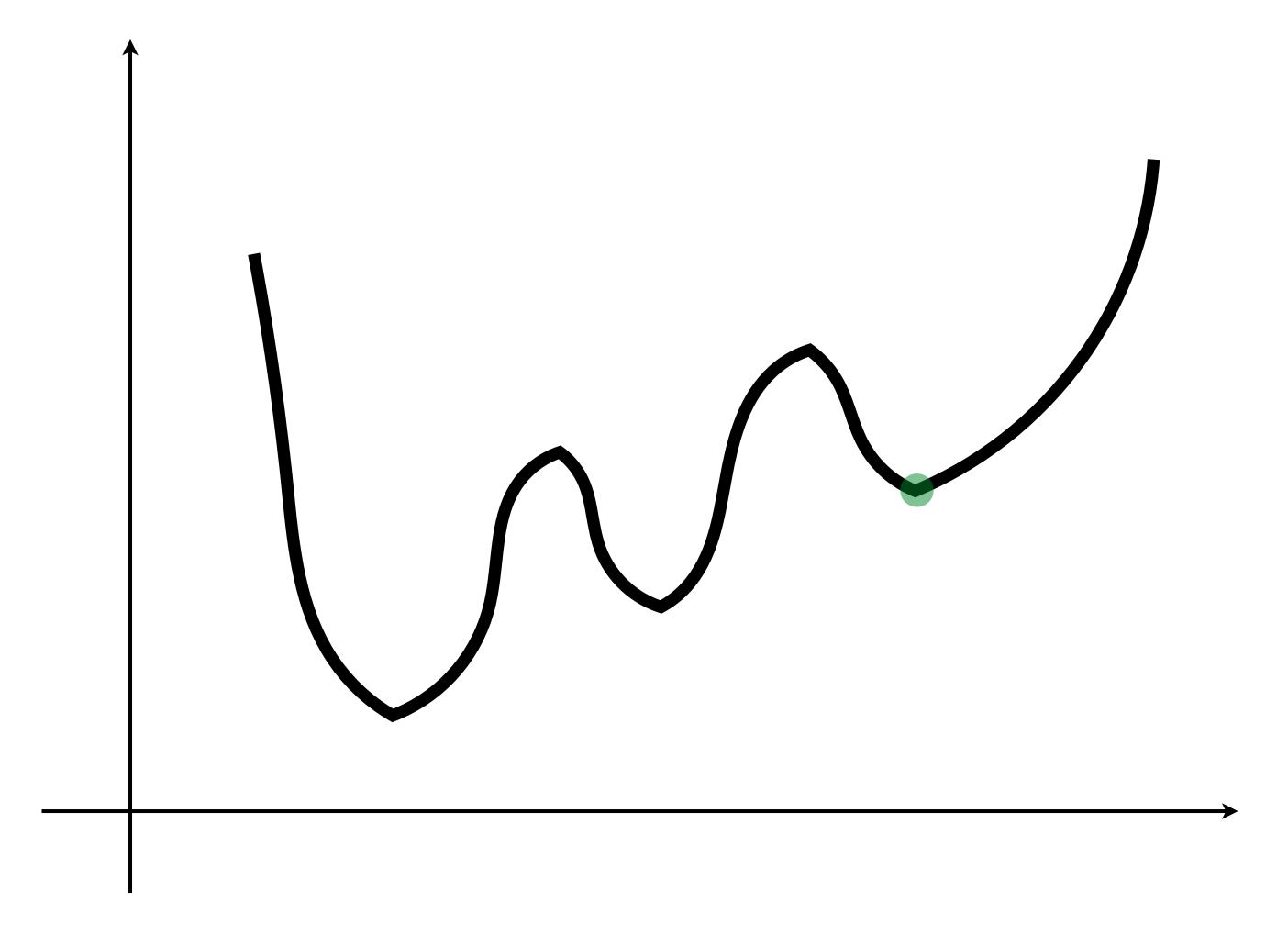
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 $\lambda$  - is the learning rate

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