



CPSC 425: Computer Vision



Image Credit: Devi Parikh

Lecture 1: Introduction and Course Logistics

Course **logistic**

Times: Tues, Thurs 12:30-2:00pm

Locations: Pharm. Science Building, Room 1201

Instructor: Leonid Sigal



E-mail: lsigal@cs.ubc.ca

Office: ICICS 119

Course webpage: https://www.cs.ubc.ca/~lsigal/teaching18_Term2.html

Discussion: piazza.com/ubc.ca/winterterm22018/cpsc425

About **me** ...

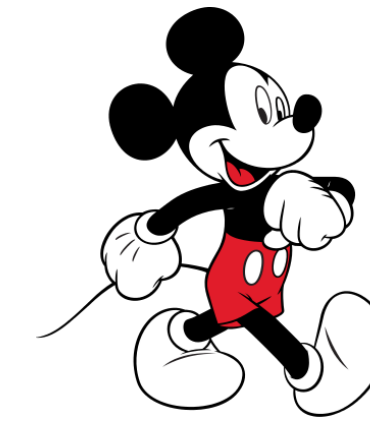
I have been working
in **Computer Vision**
for the last ~20 years

Associate Professor
2017 -



THE UNIVERSITY
OF BRITISH COLUMBIA

Senior Research Scientist
2009 - 2017



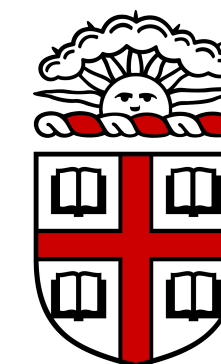
Disney Research

Postdoctoral Researcher
2007 - 2009



UNIVERSITY OF
TORONTO

PhD, MSc
2001 - 2008



BROWN

BOSTON
UNIVERSITY

Software Engineer
1999 - 2001

COGNEX

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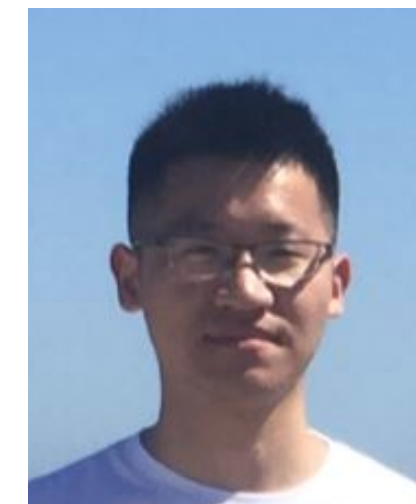
Office: ICICS 119

TAs: Borna Ghotbi



bghotbi@cs.ubc.ca

Bicheng Xu



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Tzu-Yun (Ariel) Shann



shannari@cs.ubc.ca

Alex Fan



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Course **logistic**

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Use **Piazza** for any questions related to material and assignments in the course

If you have a question, I can guarantee you that at least 10 students in the course have an identical question.

What is **Computer Vision**?

Computer vision, broadly speaking, is a research field aimed to enable computers to **process and interpret visual data**, as sighted humans can.



Image Credit: <https://www.deviantart.com/infinitecreations/art/BioMech-Eye-168367549>

What do **you** see?

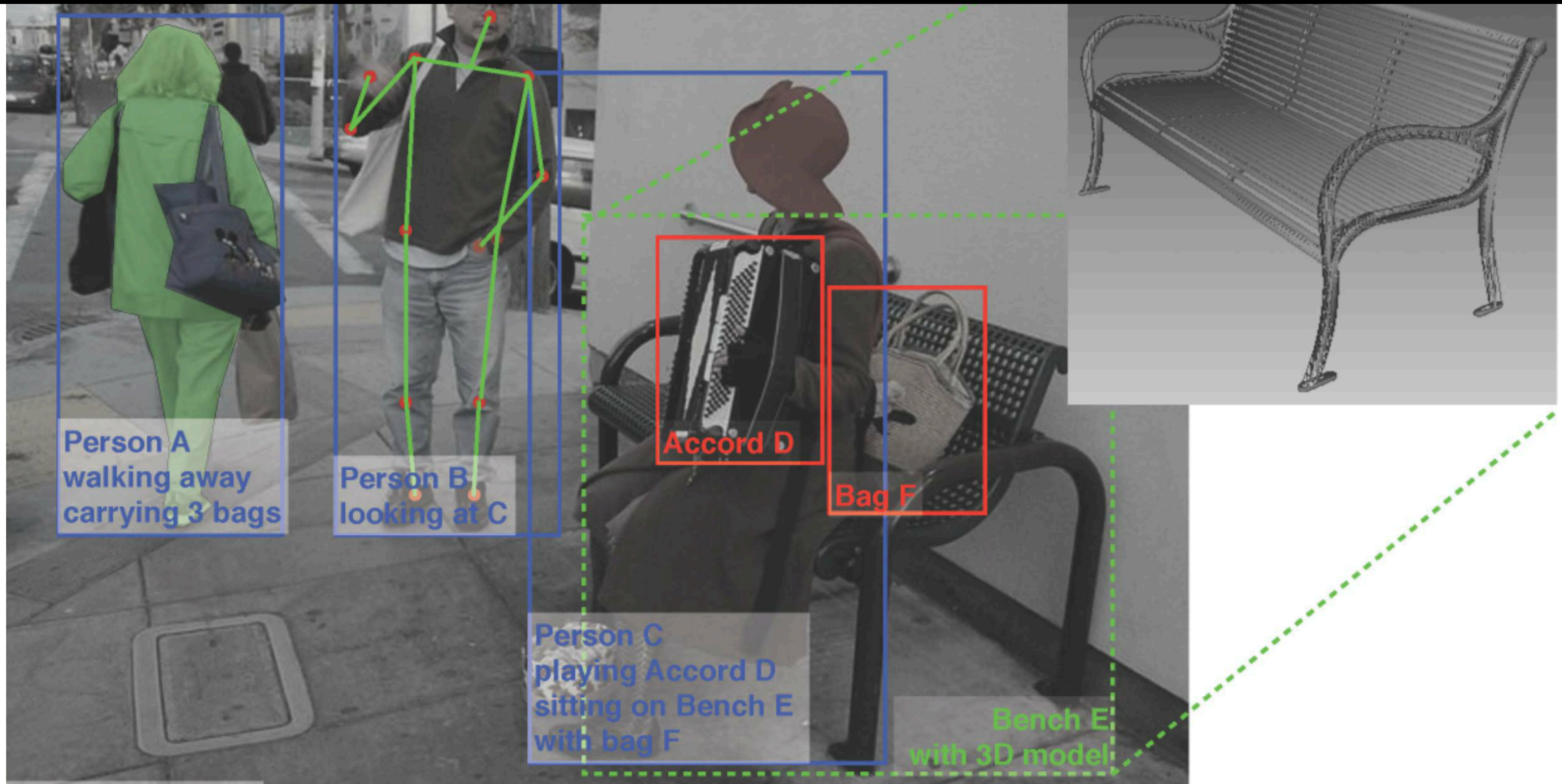


What we would like **computer to infer**?



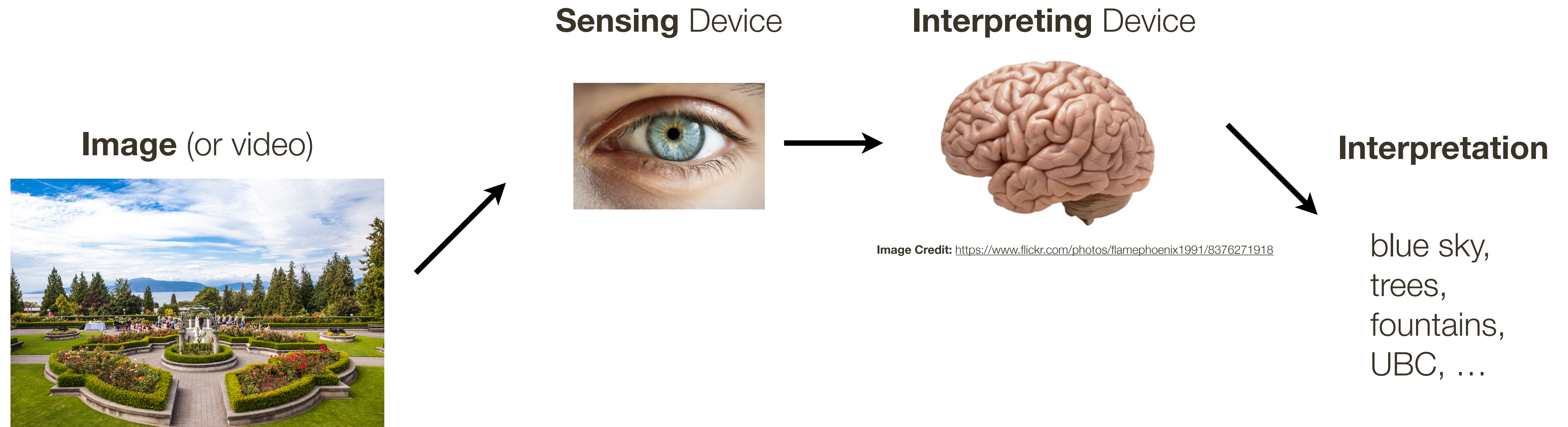
What we would like **computer to infer**?

Will person B put some money into person C's cup?



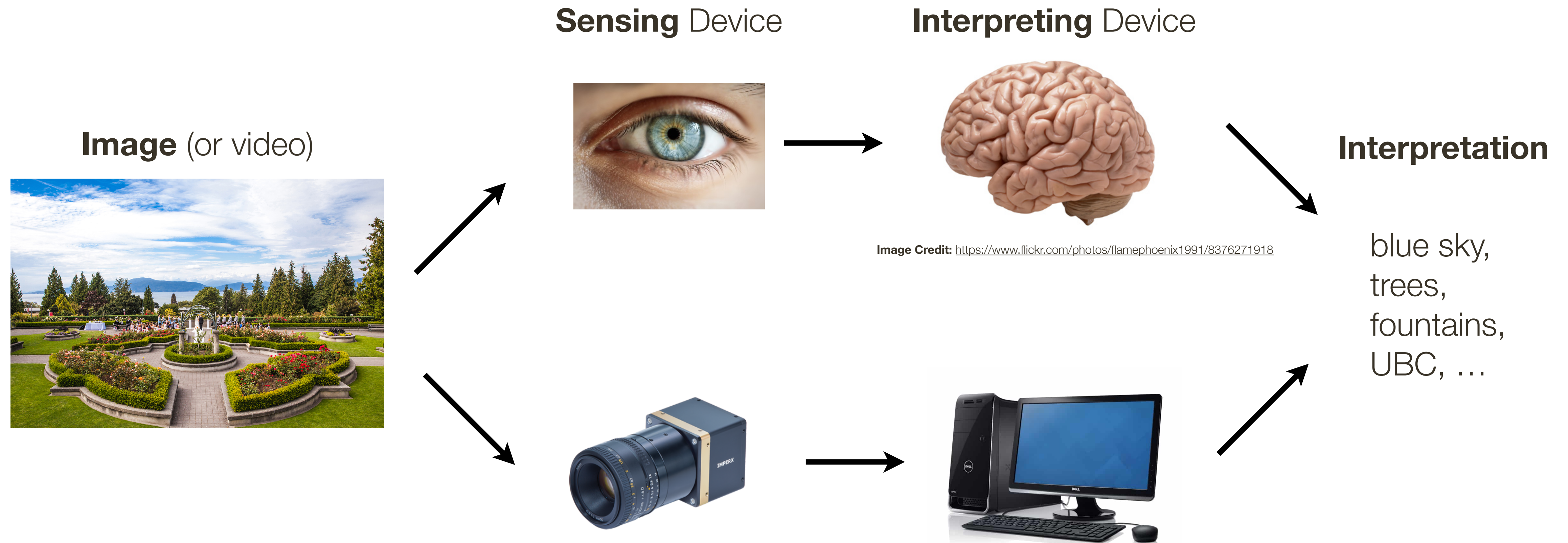
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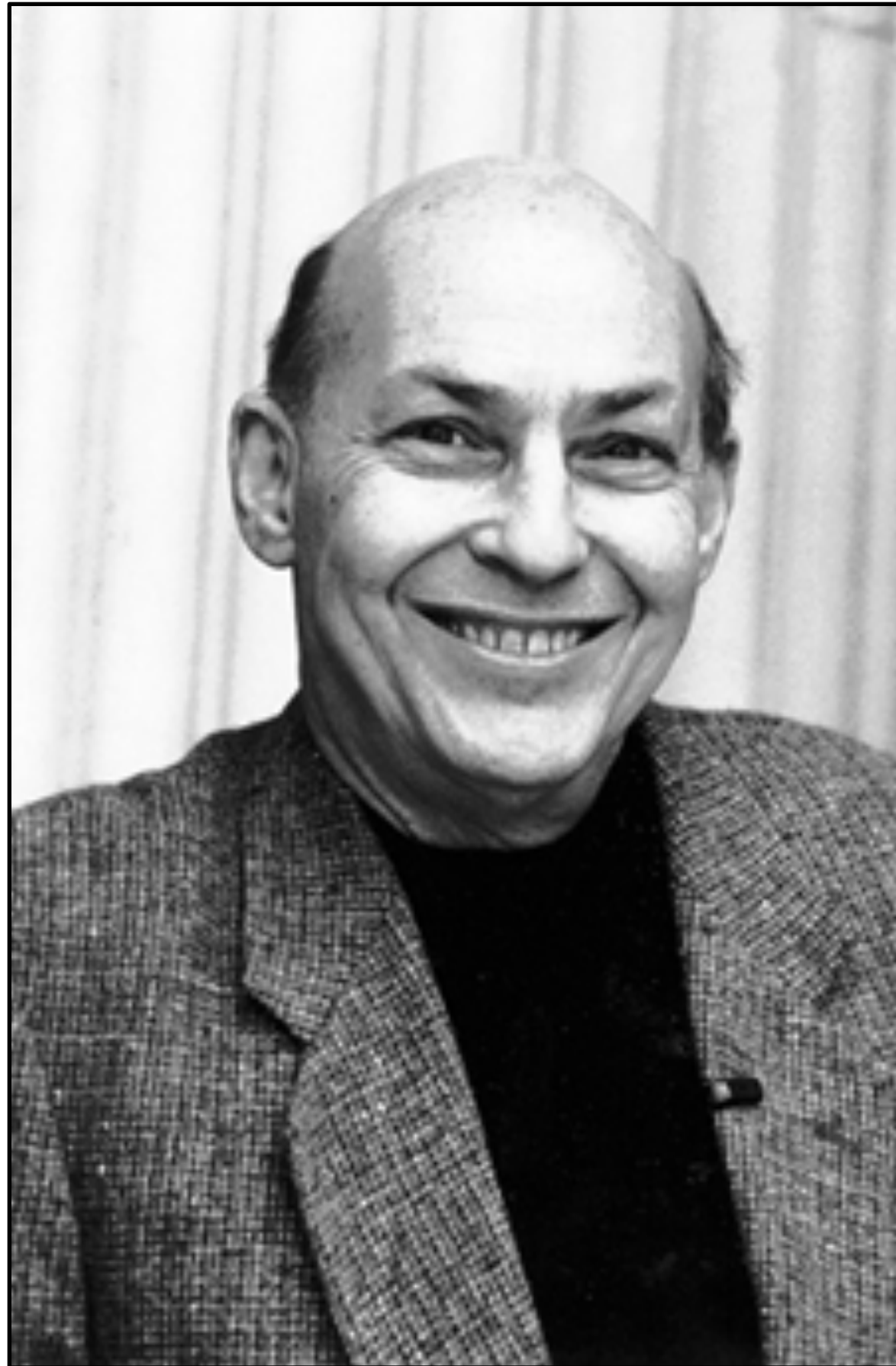


What is **Computer Vision**?

Compute vision, broadly speaking, is a research field aimed to enable computers to **process and interpret visual data**, as sighted humans can.



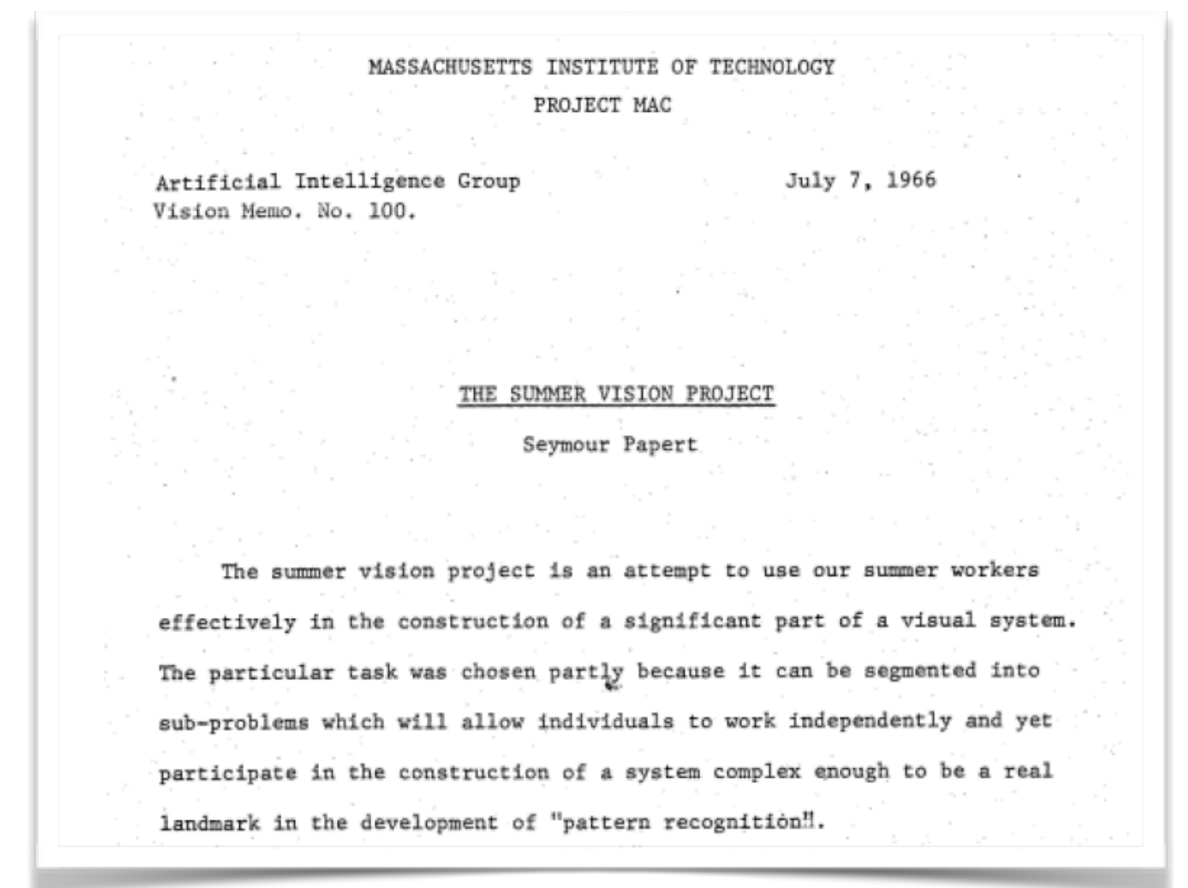
Computer vision ... the beginning ...



“spend the summer linking a camera to a computer and getting the computer to describe what it saw”

- Marvin Minsky (1966), MIT
Turing Award (1969)

... >50 years later



Computer vision ... the beginning ...



Gerald Sussman, MIT

“You’ll notice that **Sussman** never worked in vision again!” – Berthold Horn

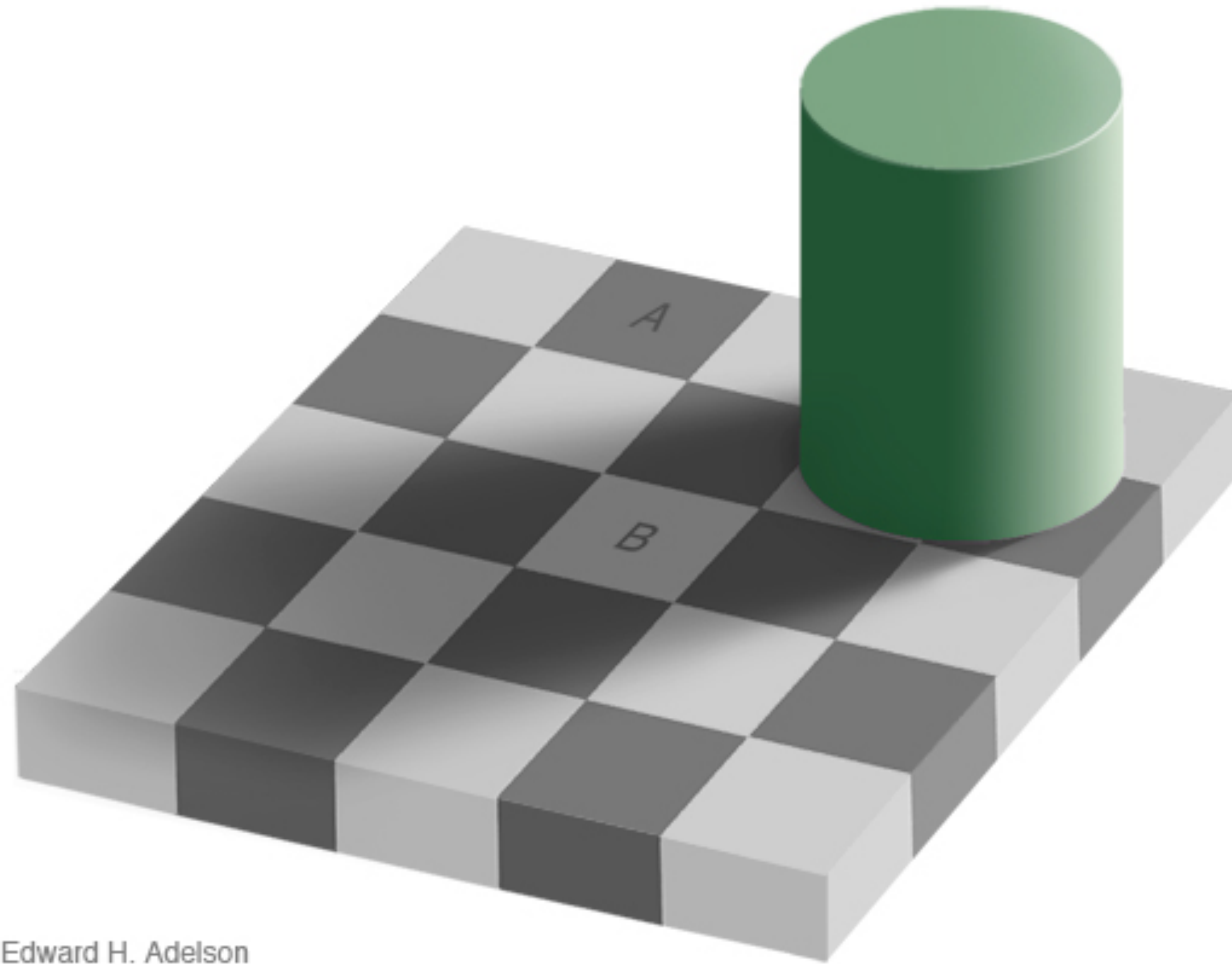
Can computers **match (or beat)** human vision?

- We've been at it for 50 years

Can computers **match (or beat)** human vision?

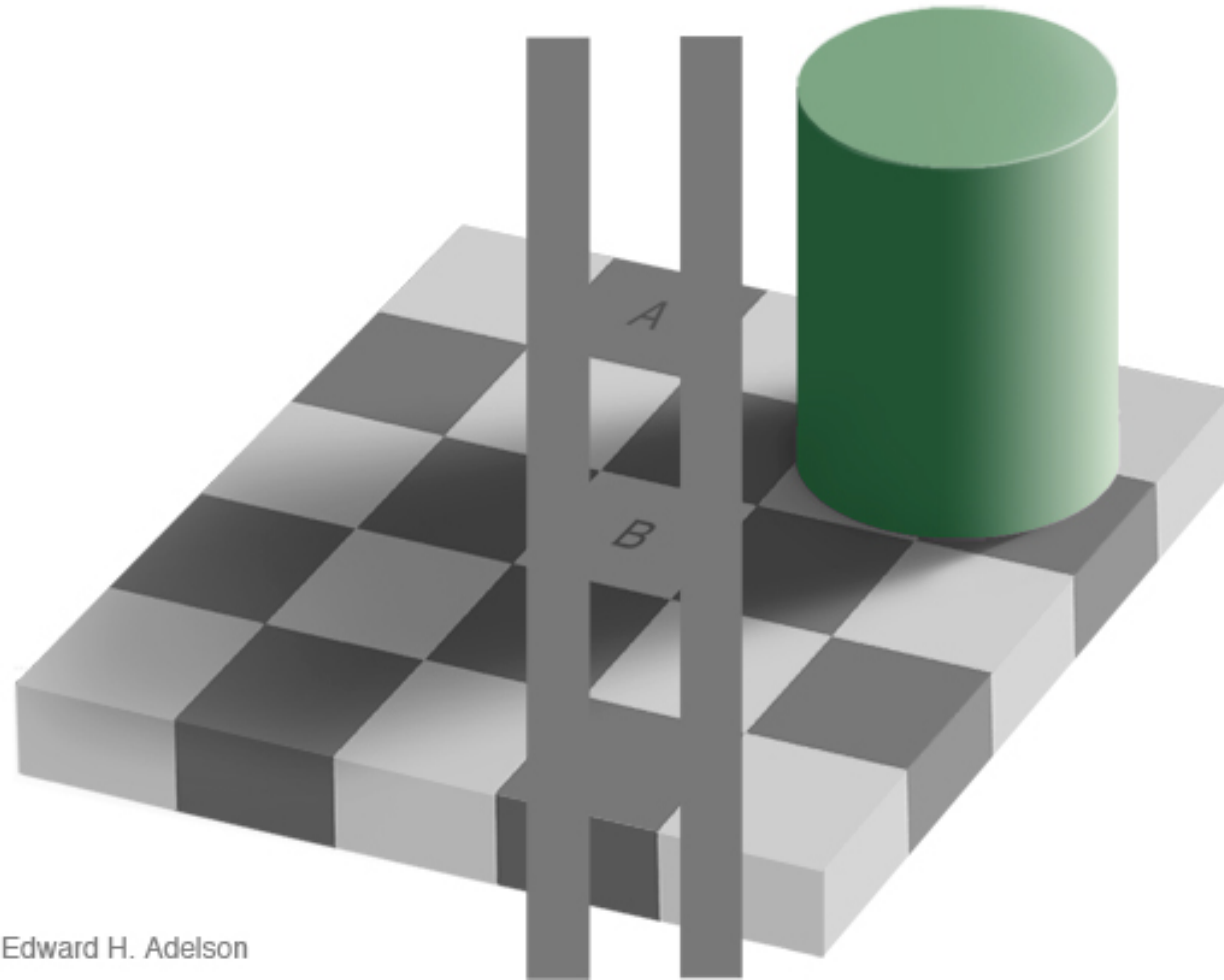
- How good is human vision?

Can computers **match (or beat)** human vision?



Edward H. Adelson

Can computers **match (or beat)** human vision?



Edward H. Adelson

Can computers **match (or beat)** human vision?

- How good is human vision?

As a measuring device not very good, as a functioning device really good

Can computers **match (or beat)** human vision?

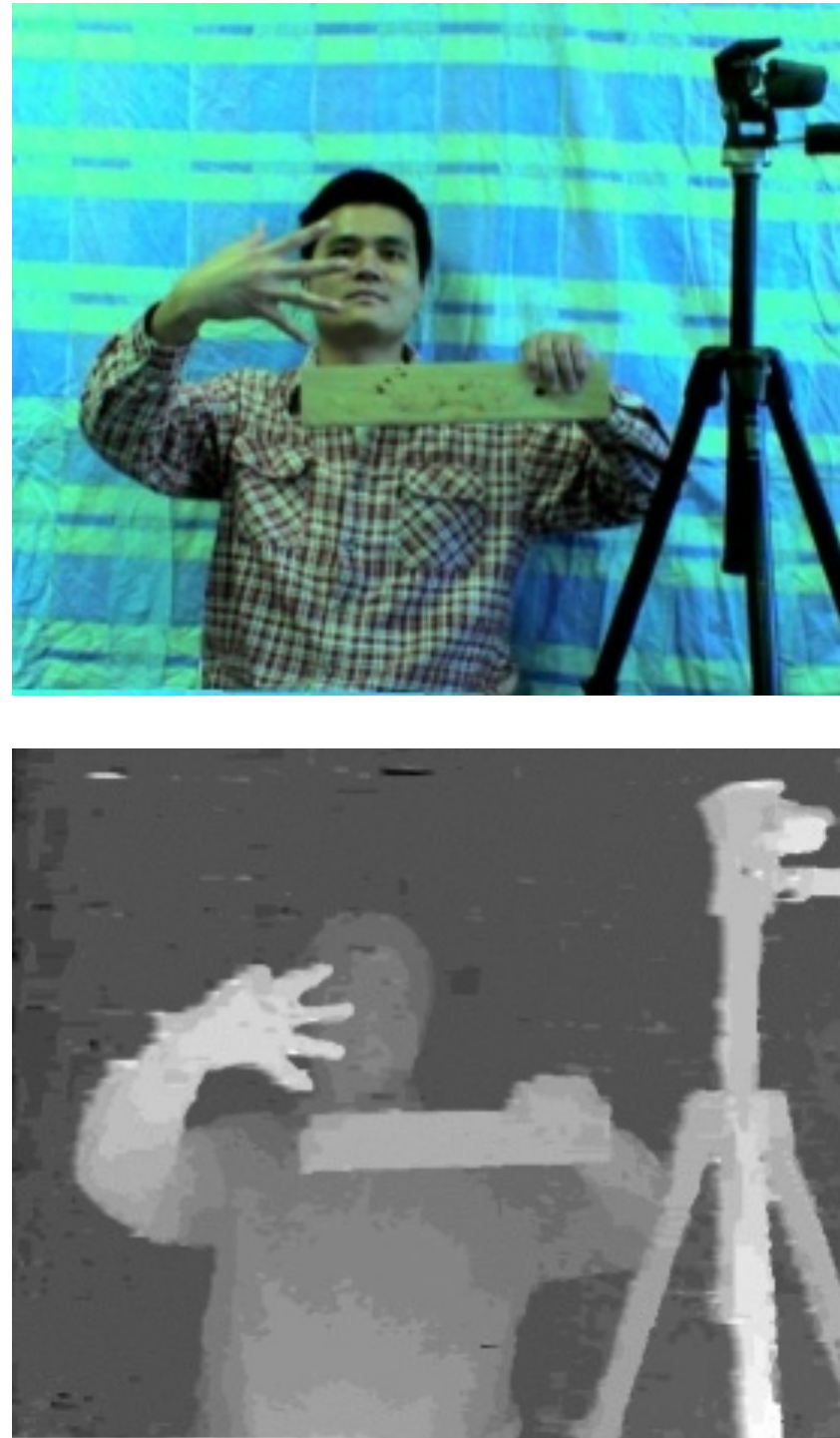
- **Yes and No** (mostly NO)

Computer **Vision Problems**

1. Computing properties of the 3D world from visual data (***measurement***)

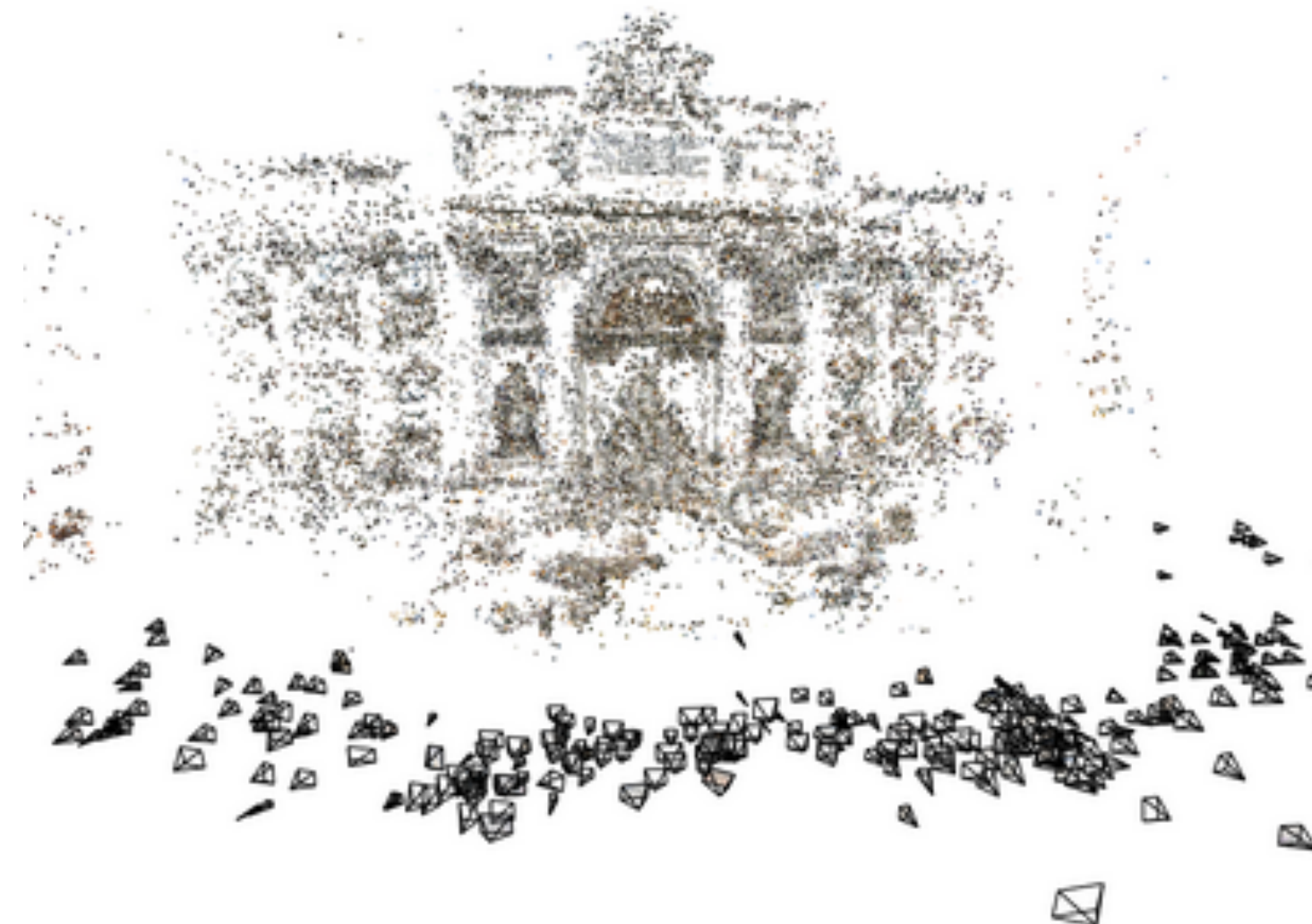
1. Vision for **Measurement**

Real-time stereo



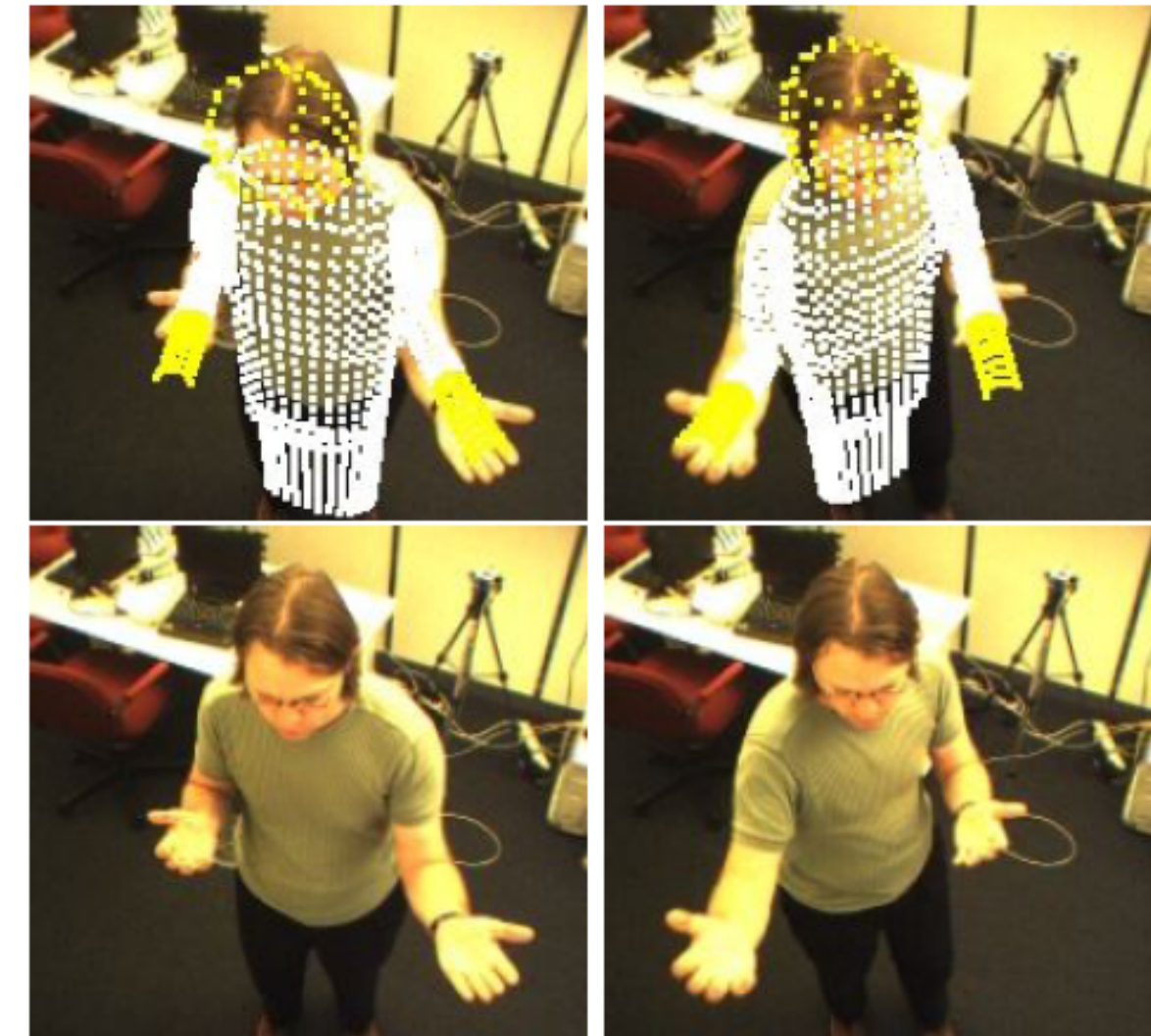
Wang et al.

Structure from motion



Snavely et al.

Tracking



Demirdjian et al.

Computer **Vision Problems**

1. Computing properties of the 3D world from visual data (***measurement***)

Ill-posed problem: real world is much more complex than what we can measure in images: 3D \rightarrow 2D

It is (literally) impossible to invert the image formation process

Computer **Vision Problems**

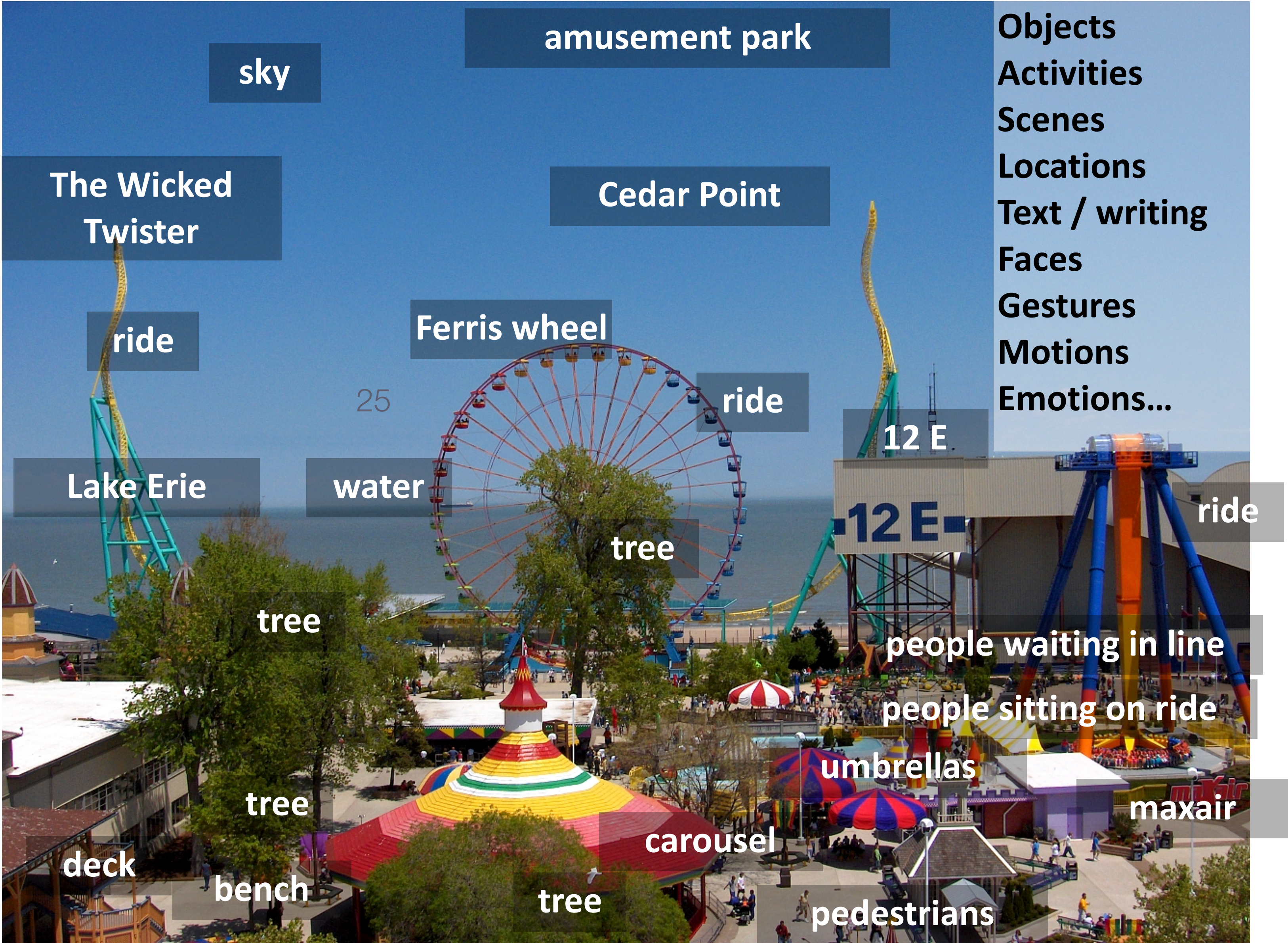
1. Computing properties of the 3D world from visual data (***measurement***)
2. Algorithms and representations to allow a machine to recognize objects, people, scenes, and activities (***perception and interpretation***)

2. Vision for **Perception and Interpretation**



Slide Credit: Kristen Grauman (UT Austin)

2. Vision for **Perception and Interpretation**



Slide Credit: Kristen Grauman (UT Austin)

Computer **Vision Problems**

1. Computing properties of the 3D world from visual data (***measurement***)
2. Algorithms and representations to allow a machine to recognize objects, people, scenes, and activities (***perception and interpretation***)

It is computationally intensive / expensive

2. Vision for **Perception and Interpretation**

~ 55% of **cerebral cortex** in humans (13 billion neurons) are devoted to vision
more human brain devoted to vision than anything else



Computer **Vision Problems**

1. Computing properties of the 3D world from visual data (***measurement***)
2. Algorithms and representations to allow a machine to recognize objects, people, scenes, and activities (***perception and interpretation***)

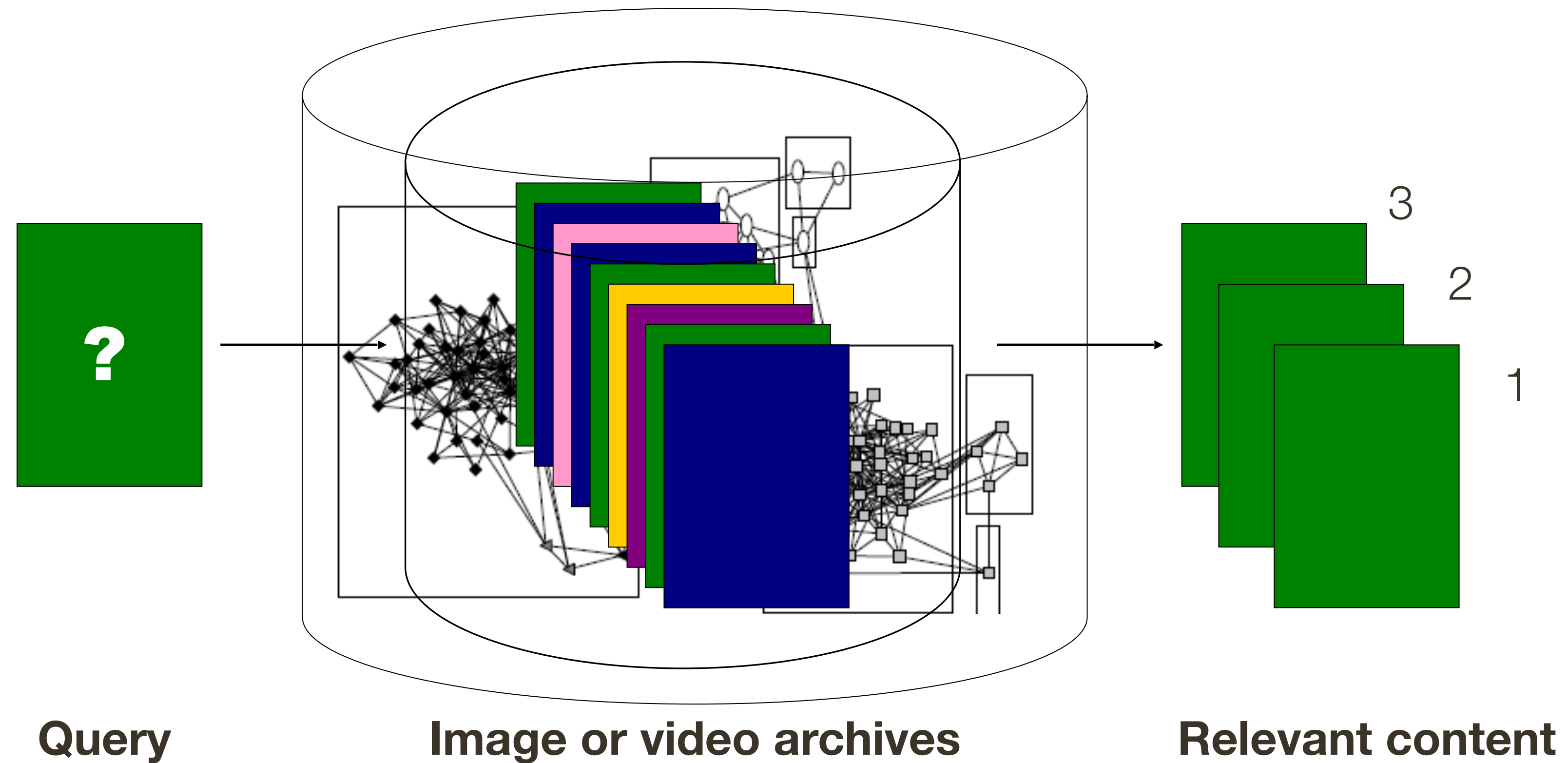
It is computationally intensive / expensive

We do not (fully) understand the processing mechanisms involved

Computer **Vision Problems**

1. Computing properties of the 3D world from visual data (***measurement***)
2. Algorithms and representations to allow a machine to recognize objects, people, scenes, and activities (***perception and interpretation***)
3. Algorithms to mine, search, and interact with visual data (***search and organization***)

3. Search and Organization



Computer **Vision Problems**

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Scale is enormous, explosion of visual content

3. Search and Organization



*from iStock by GettyImages

Snapchat



31.7 Million
/ hour

WhatsApp



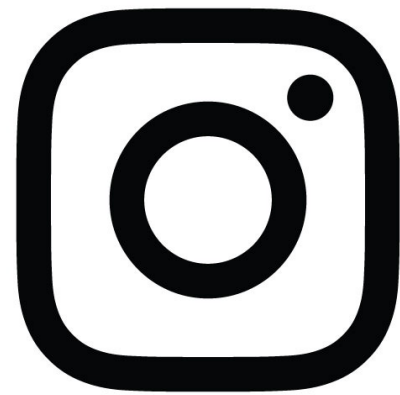
29.2 Million
/ hour

Facebook



14.6 Million
/ hour

Instagram



2.9 Million
/ hour

Flickr



0.2 Million
/ hour



18K hours
/ hour

3. Search and Organization



> 85% of all web content is multimedia content of visual form

*from iStock by GettyImages

Snapchat



31.7 Million

WhatsApp



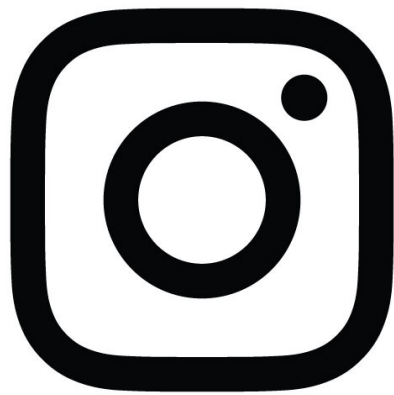
29.2 Million

Facebook



14.6 Million
our

Instagram



2.9 Million
/ hour

Flickr



0.2 Million
/ hour



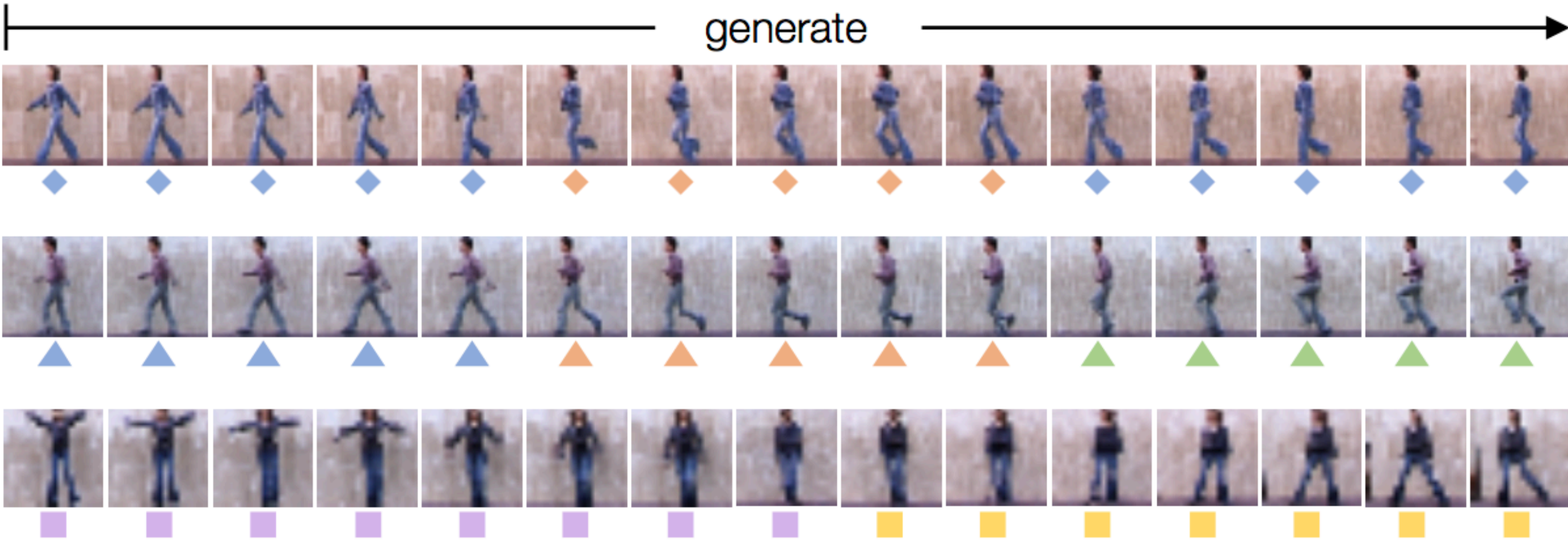
18K hours
/ hour

Computer **Vision Problems**

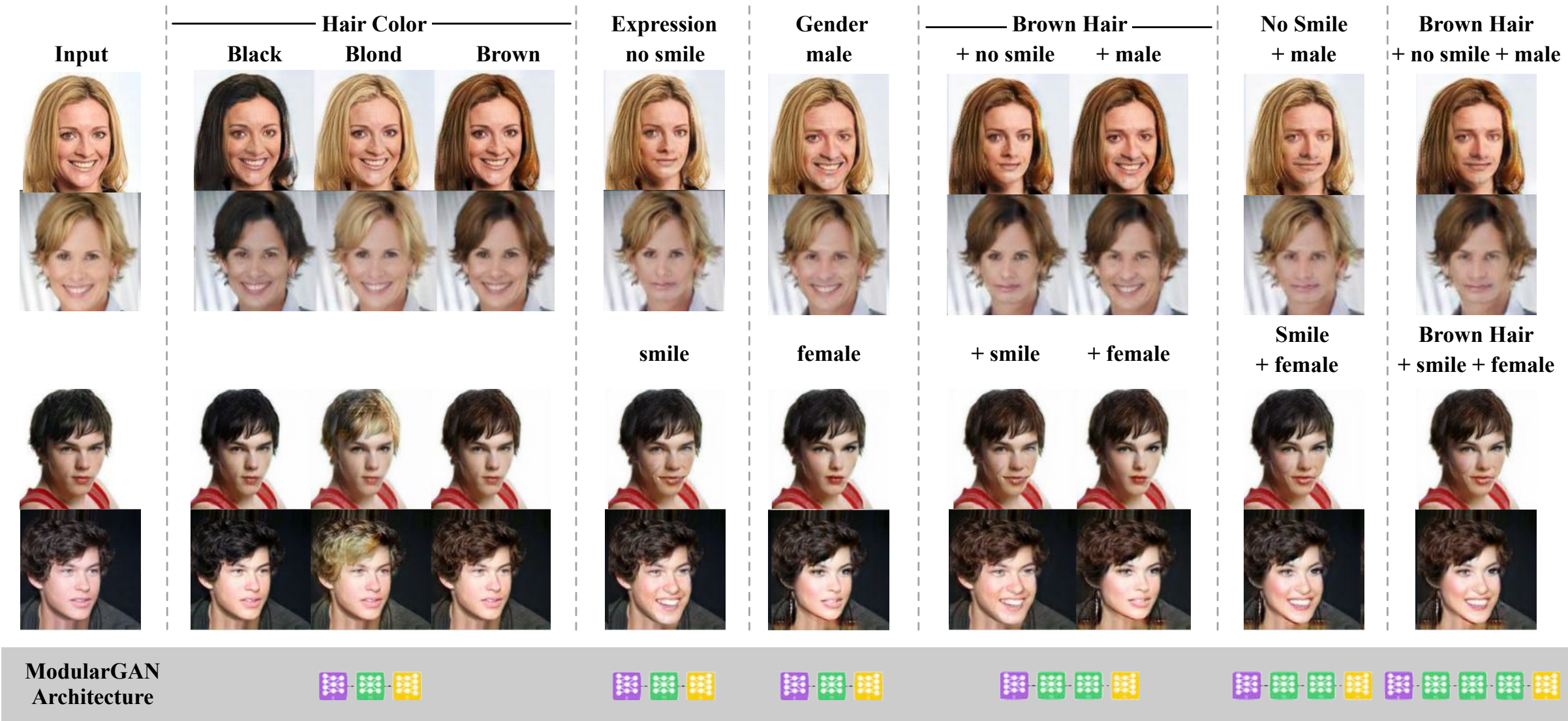
1. Computing properties of the 3D world from visual data (***measurement***)
2. Algorithms and representations to allow a machine to recognize objects, people, scenes, and activities (***perception and interpretation***)
3. Algorithms to mine, search, and interact with visual data (***search and organization***)
4. Algorithms for manipulation or creation of image or video content (***visual imagination***)

4. Visual Imagination

Identity = \blacklozenge | \blacktriangle | \blacksquare Action = \bullet walking | \bullet running | \bullet skipping | \bullet jumping jack | \bullet side step



He et al. ECCV 2018

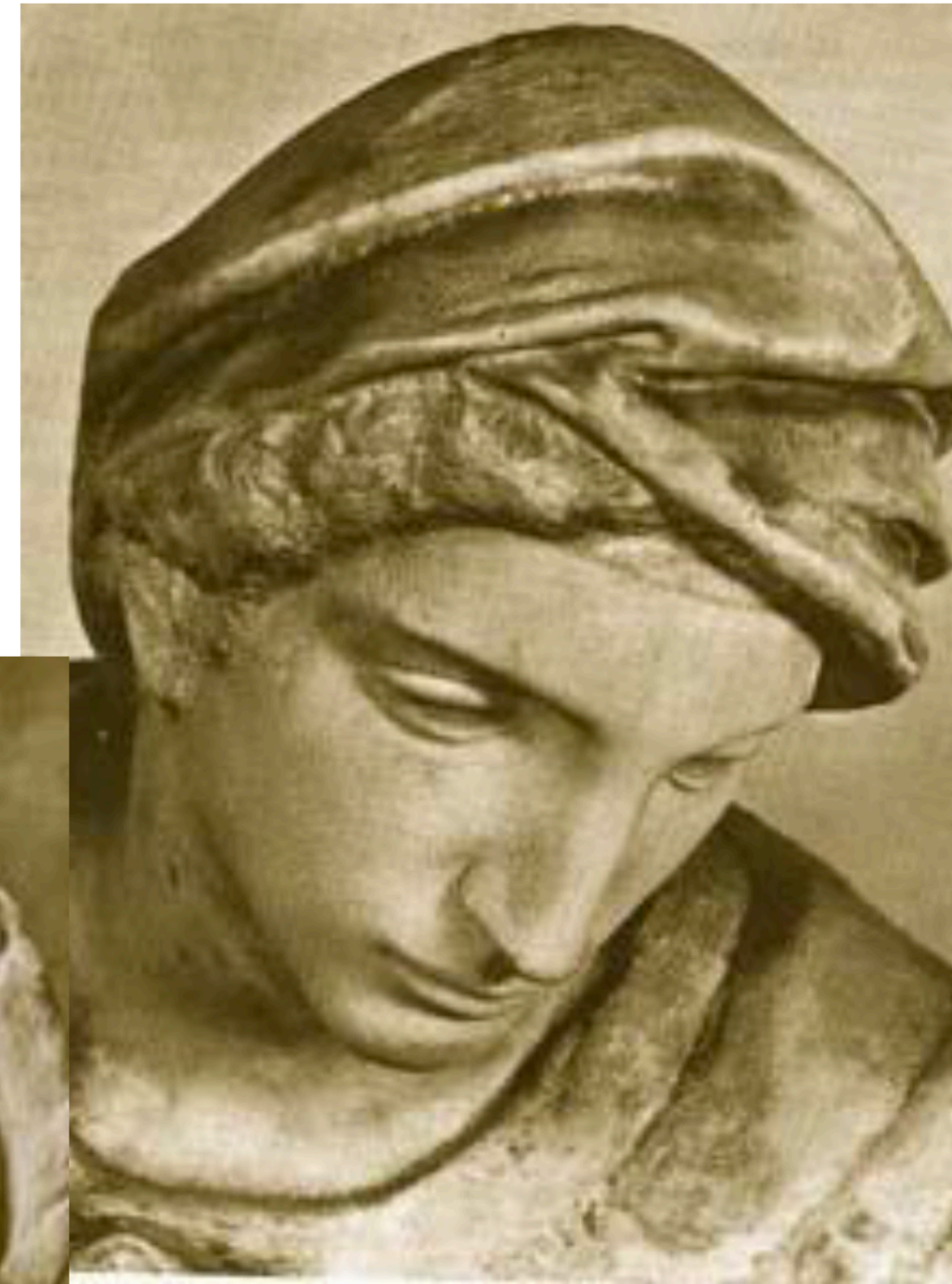


Zhao et al. ECCV 2018

Computer **Vision Problems**

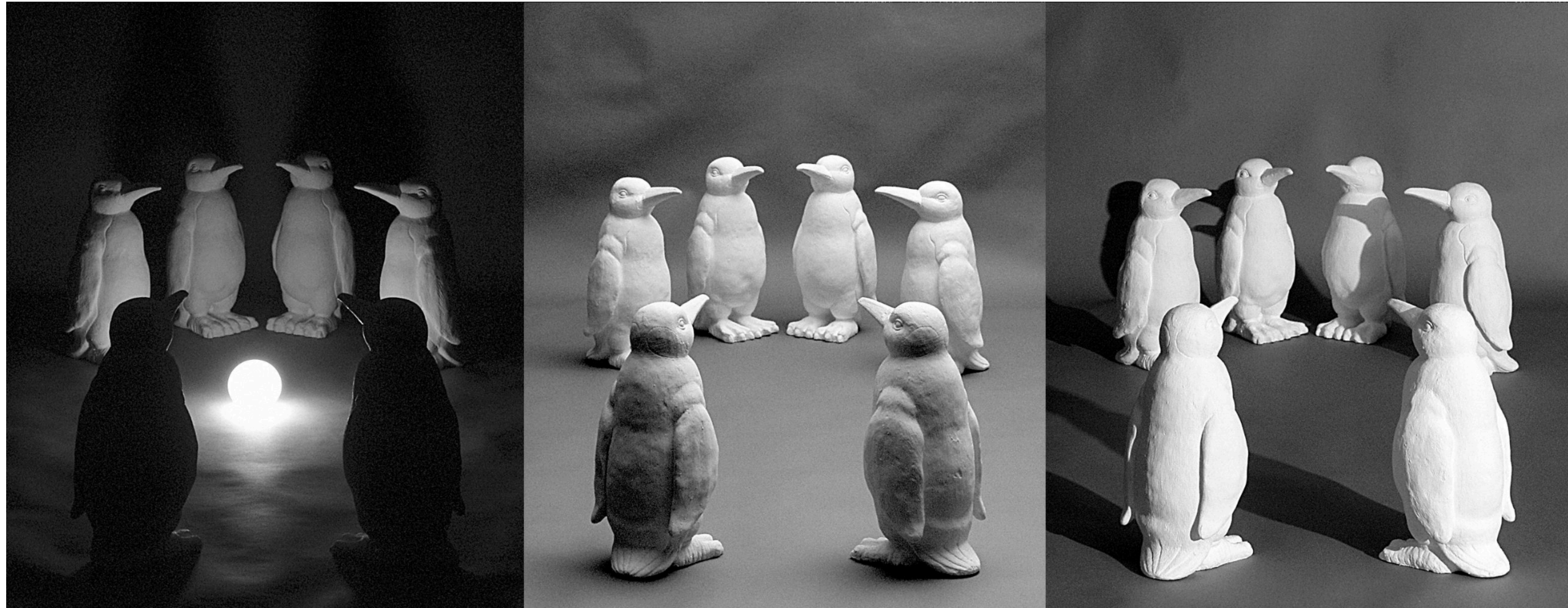
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Challenges: Viewpoint invariance



Michelangelo 1475-1564

Challenges: Lighting



Challenges: Scale



Challenges: Deformation



Challenges: Occlusions

Rene Magritte 1965



Challenges: Background clutter

Kilmeny Niland 1995



Challenges: Local ambiguity and context



Challenges: Local ambiguity and context



Challenges: Motion



Challenges: Object inter-class variation



Can computers **match (or beat)** human vision?

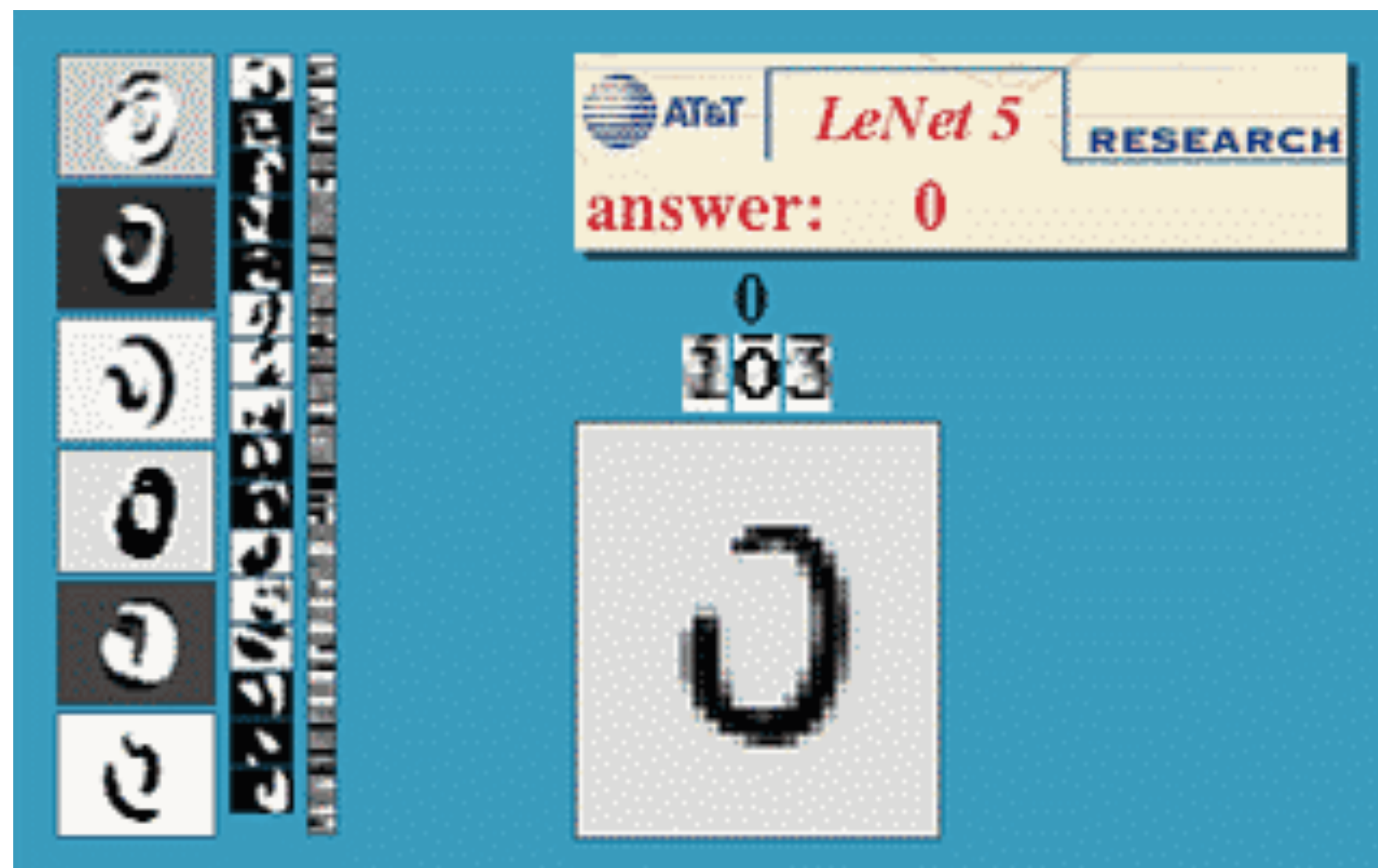
- **Yes and No** (mostly NO)
- Let's see some examples of state-of-the-art and where it is used

Optical Character Recognition (**OCR**)

Technology to convert **scanned documents to text**
(comes with any scanner now days)



Yann LeCun



Digit recognition, AT&T labs
<http://www.research.att.com/~yann/>



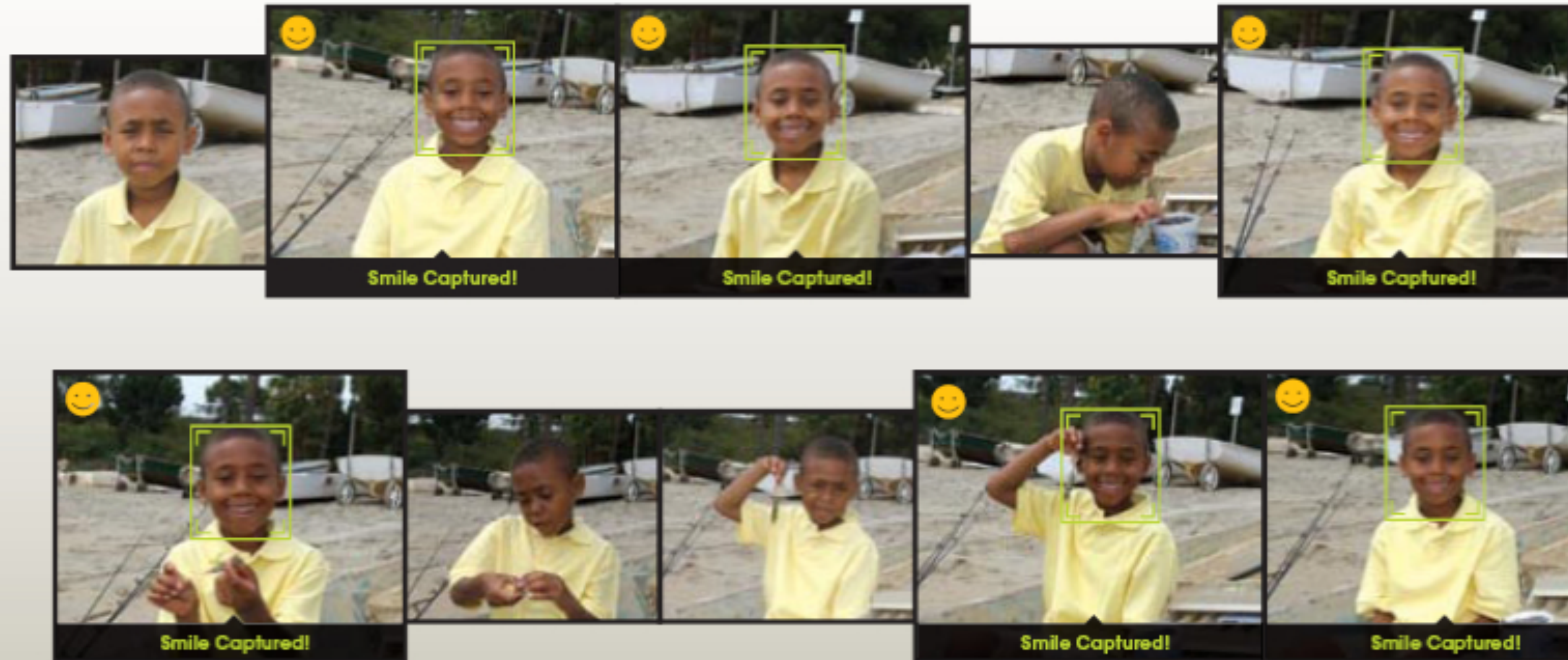
License plate readers
http://en.wikipedia.org/wiki/Automatic_number_plate_recognition

Face Detection

Technology available in any digital camera now
(one of the first big commercial successes of vision algorithms)



Smile Detection



Face Recognition



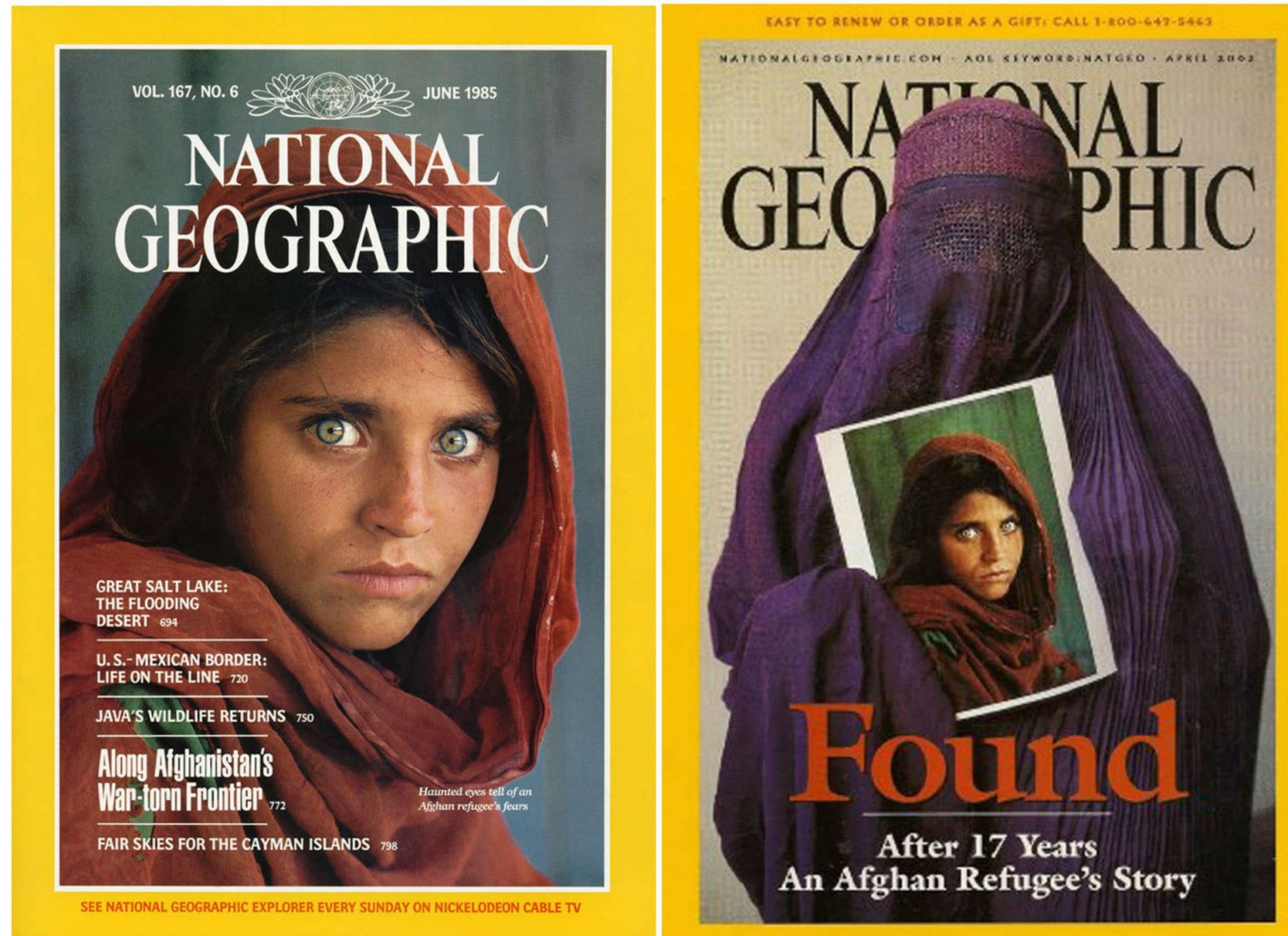
Facebook

Apple's iPhoto



<http://www.apple.com/ilife/iphoto/>

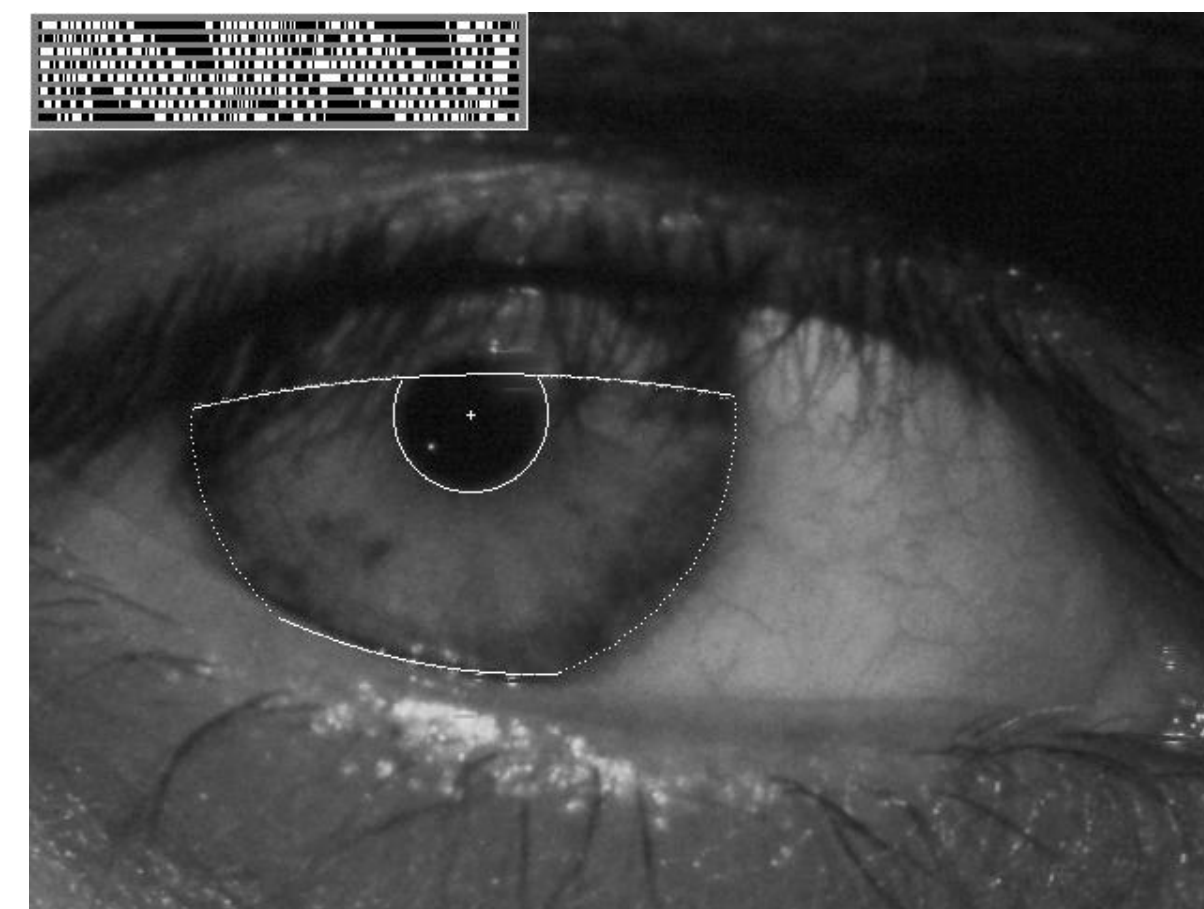
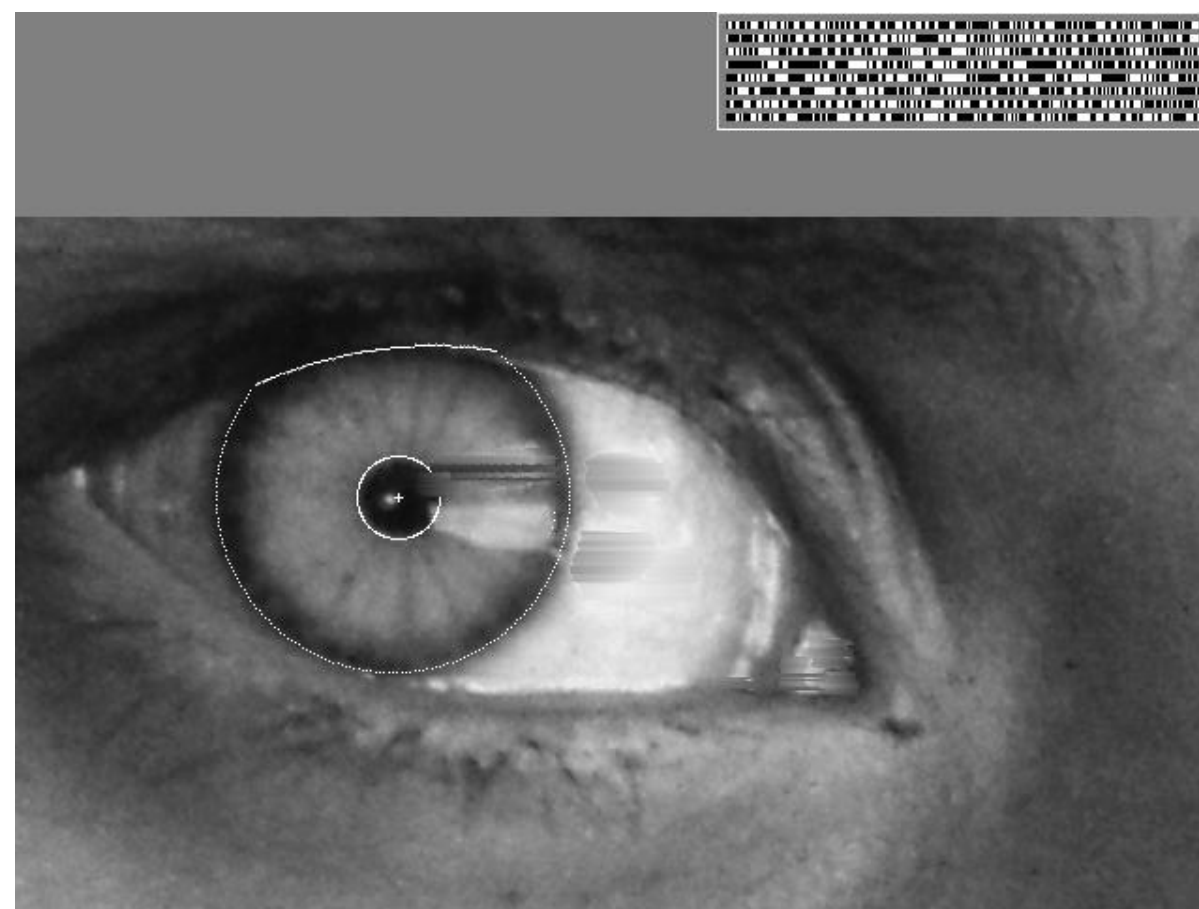
Vision for **Biometrics**



Vision for **Biometrics**



“How the Afghan Girl was Identified by Her Iris Patterns” Read the [story wikipedia](#)



Vision for **Biometrics**



Fingerprint scanners on many new laptops,
other devices

iPhone X Face ID



Face recognition systems are not part of
widely used technologies

How it works and how to fool it:

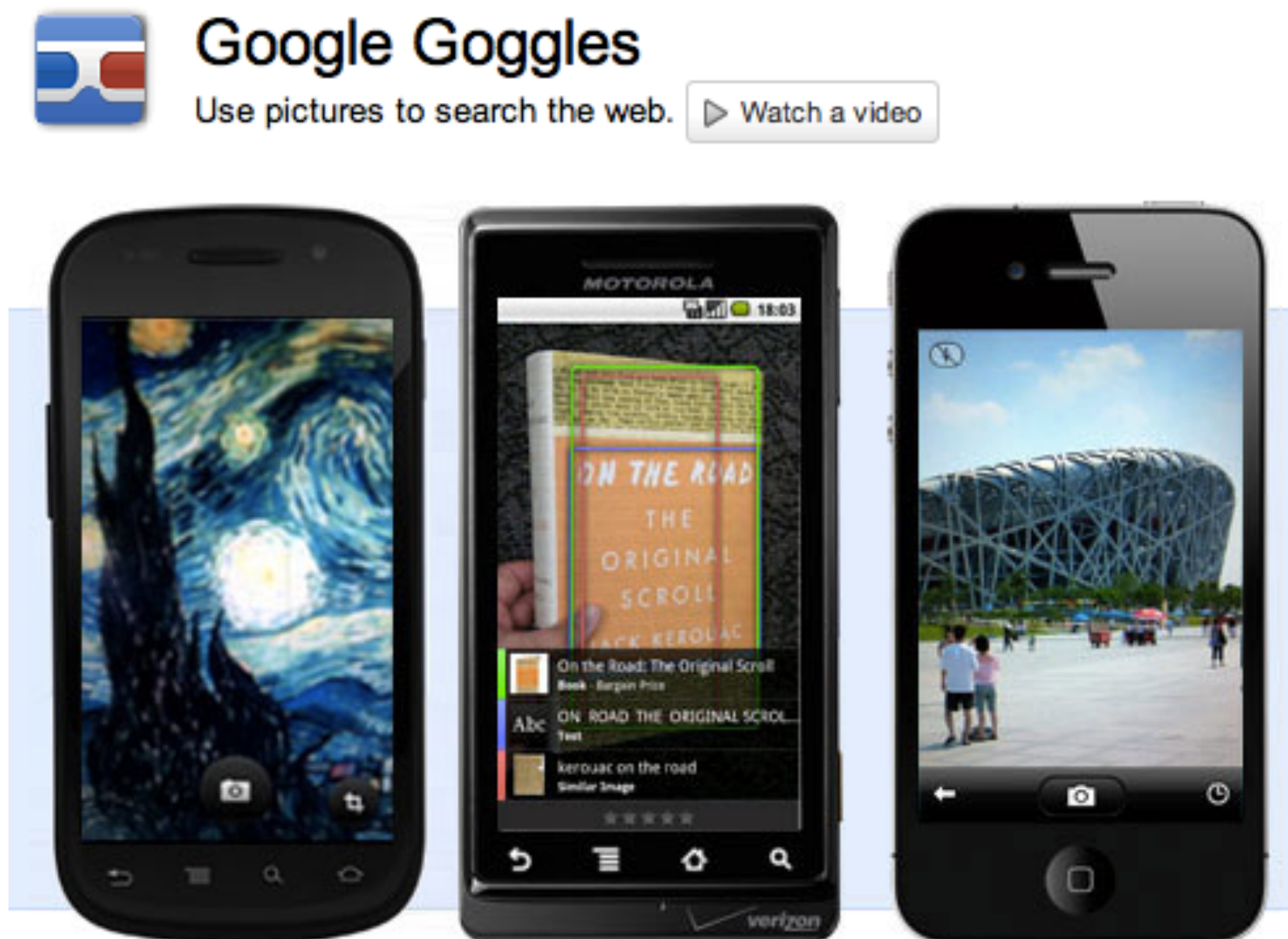
<https://www.youtube.com/watch?v=FhbMLmsCax0>

Object Recognition (in supermarkets)



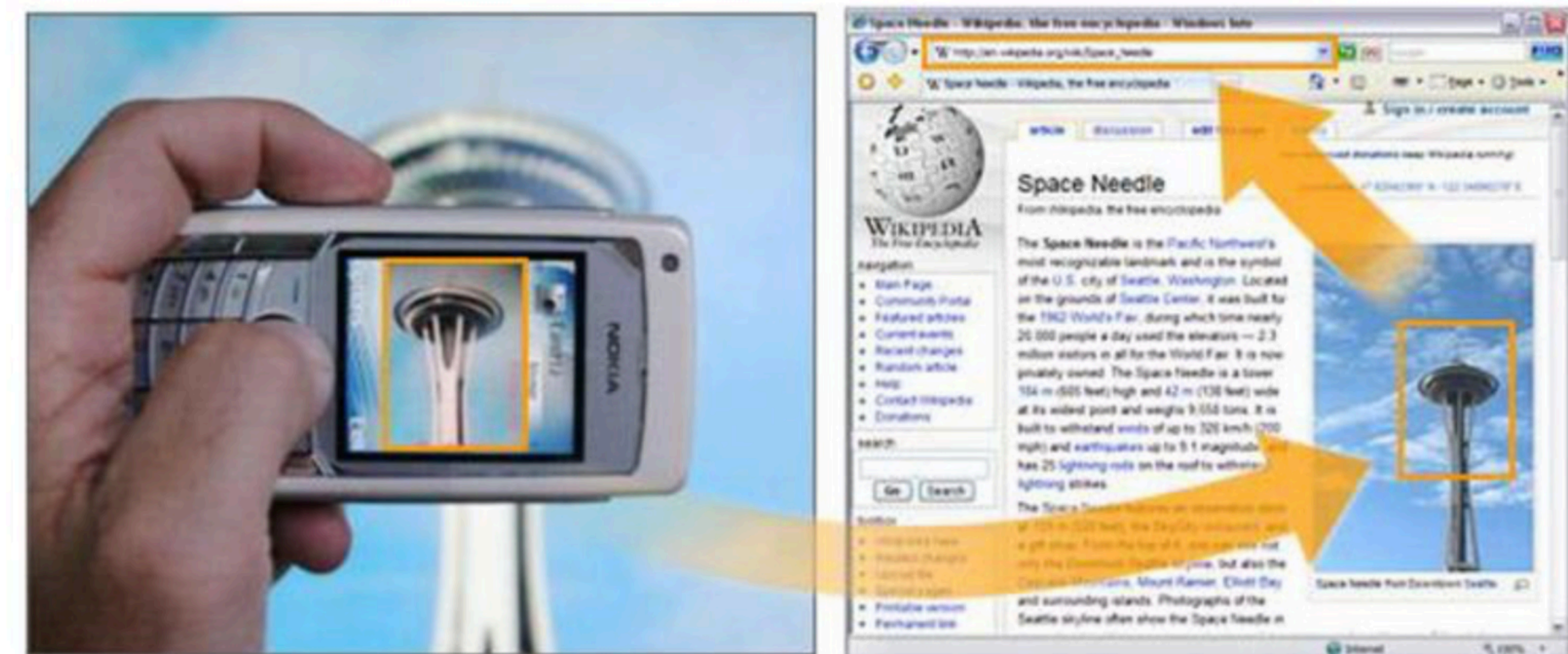
<https://www.youtube.com/watch?v=NrmMk1Myrxc>

Object Recognition (in mobile devices)



Nokia's Point & Find

<https://www.youtube.com/watch?v=8SdwVCUJ0QE>



https://en.wikipedia.org/wiki/Nokia_Point_&_Find

3D **Urban Modeling** and Virtual Tourism



[Agarwal, Furukawa, Snavely, Curless, Seitz, Szeliski, 2010]

Visual Special Effects (**VFX**): Shape and Motion Capture



The Matrix movies, ESC Entertainment, XYZRGB, NRC



Pirates of the Caribbean, Industrial Light and Magic



Vision in **Sports**



Sportvision first down line
Nice [explanation](http://www.howstuffworks.com) on www.howstuffworks.com

Slide Credit: Stephen Seitz (University of Washington)

<http://www.sportvision.com/video.html>

Automotive Safety and Smart Cars



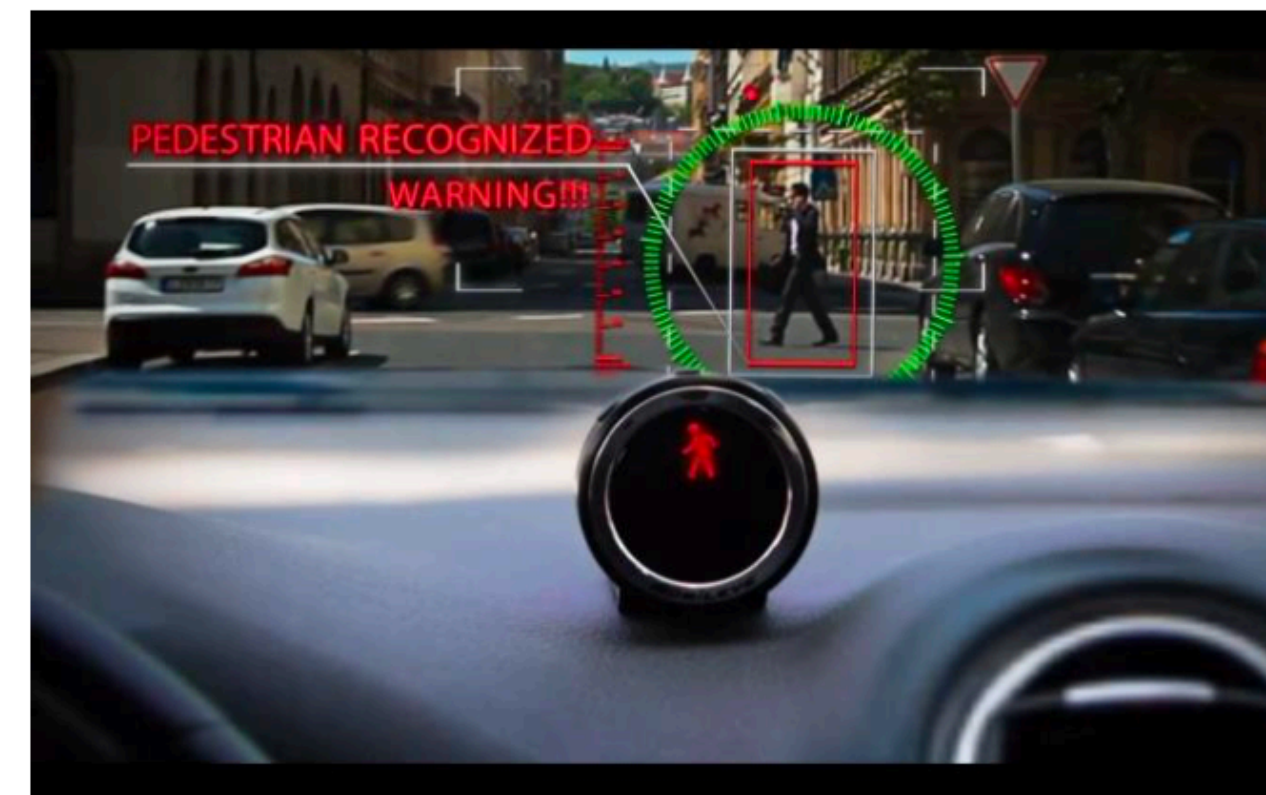
Tesla's Autopilot

A screenshot of the Mobileye website. The main heading is "Our Vision. Your Safety." Below it is a diagram of a car with three camera fields of view: "rear looking camera", "forward looking camera", and "side looking camera". To the right is a "News" section with headlines like "Mobileye Advanced Technologies Power Volvo Cars World First Collision Warning With Auto Brake System" and "Volvo: New Collision Warning with Auto Brake Helps Prevent Rear-end". Below the main heading are three product sections: "EyeQ Vision on a Chip" with an image of the chip, "Vision Applications" with an image of a pedestrian, and "AWS Advance Warning System" with an image of a car's dashboard display showing a warning. Each section has a "read more" link.

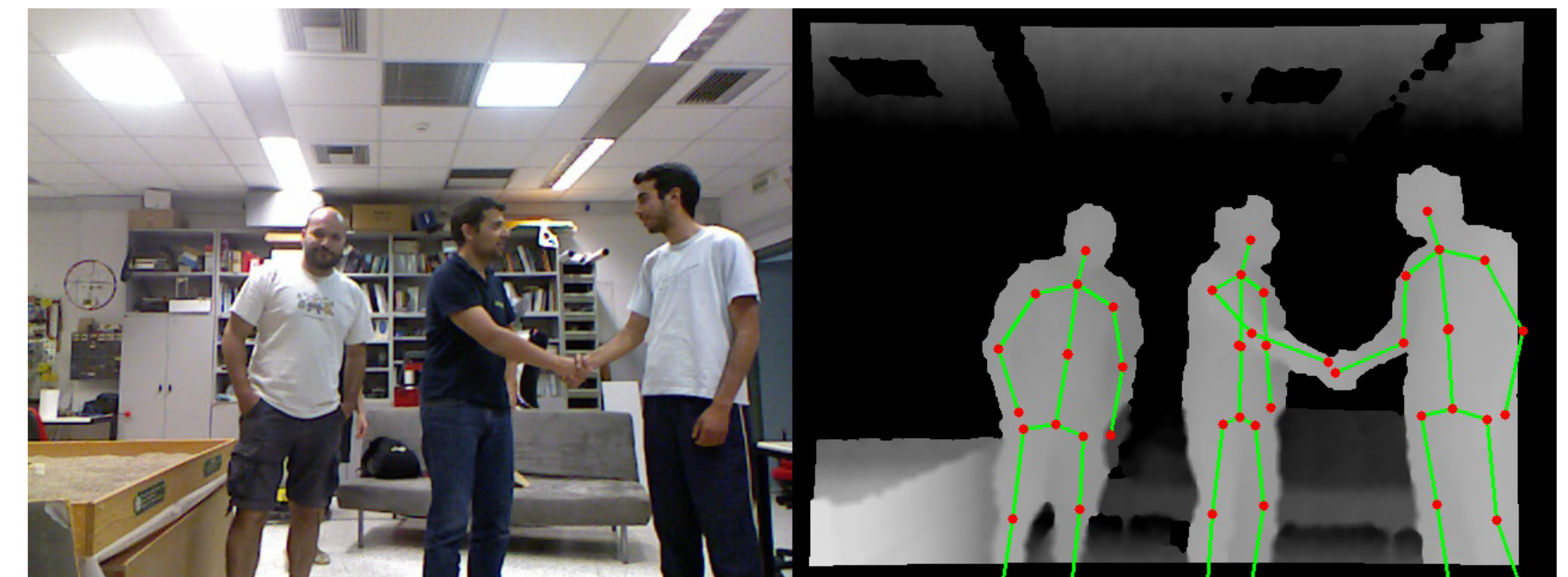
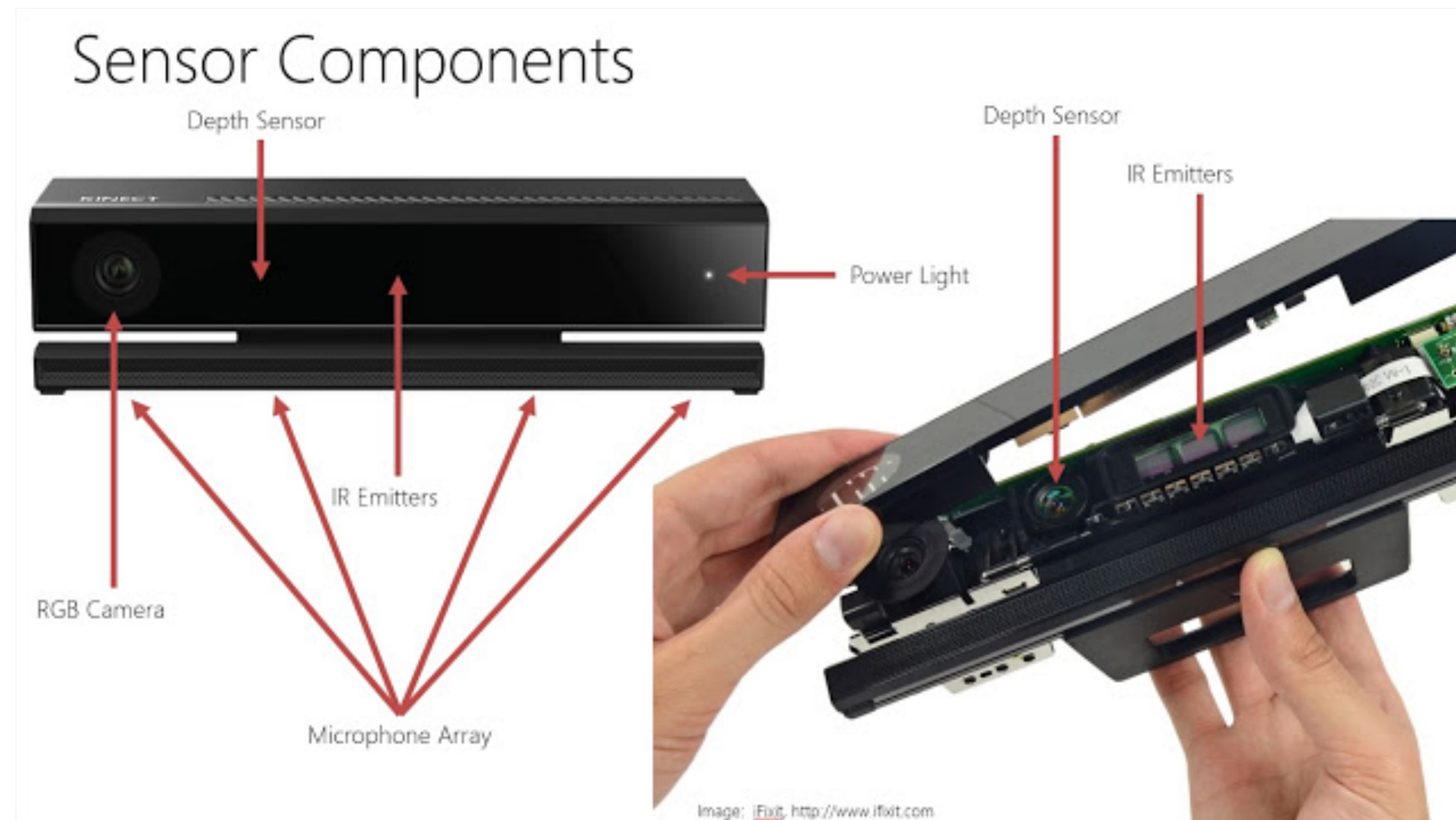
Google Self-driving Cars



Mobileye



Interactive Games: **Kinect**



Vision for Robotics, Space Exploration

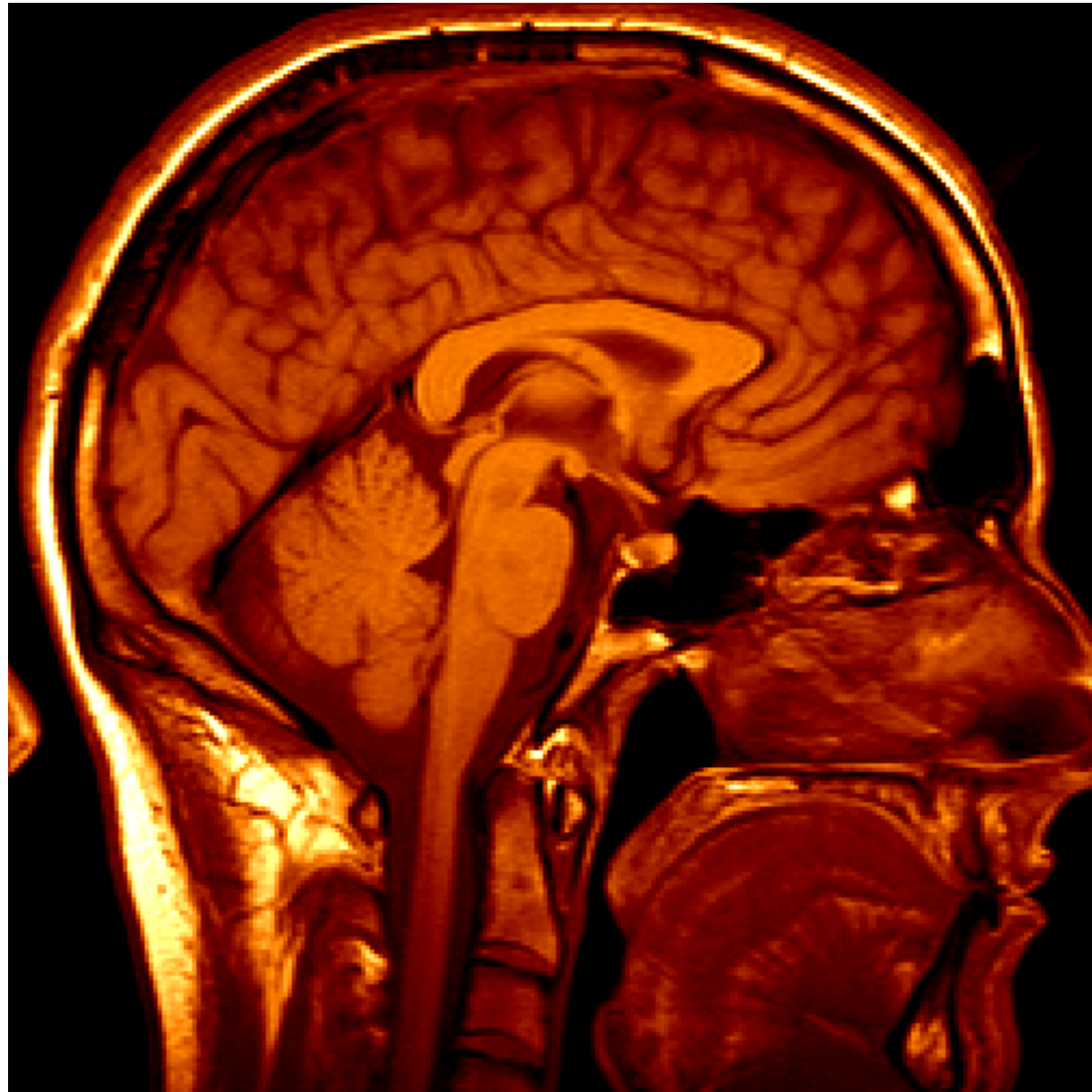


[NASA'S Mars Exploration Rover Spirit](#) captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

Vision systems (JPL) used for several tasks

- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read “[Computer Vision on Mars](#)” by Matthies et al.

Vision for **Medical Imaging**

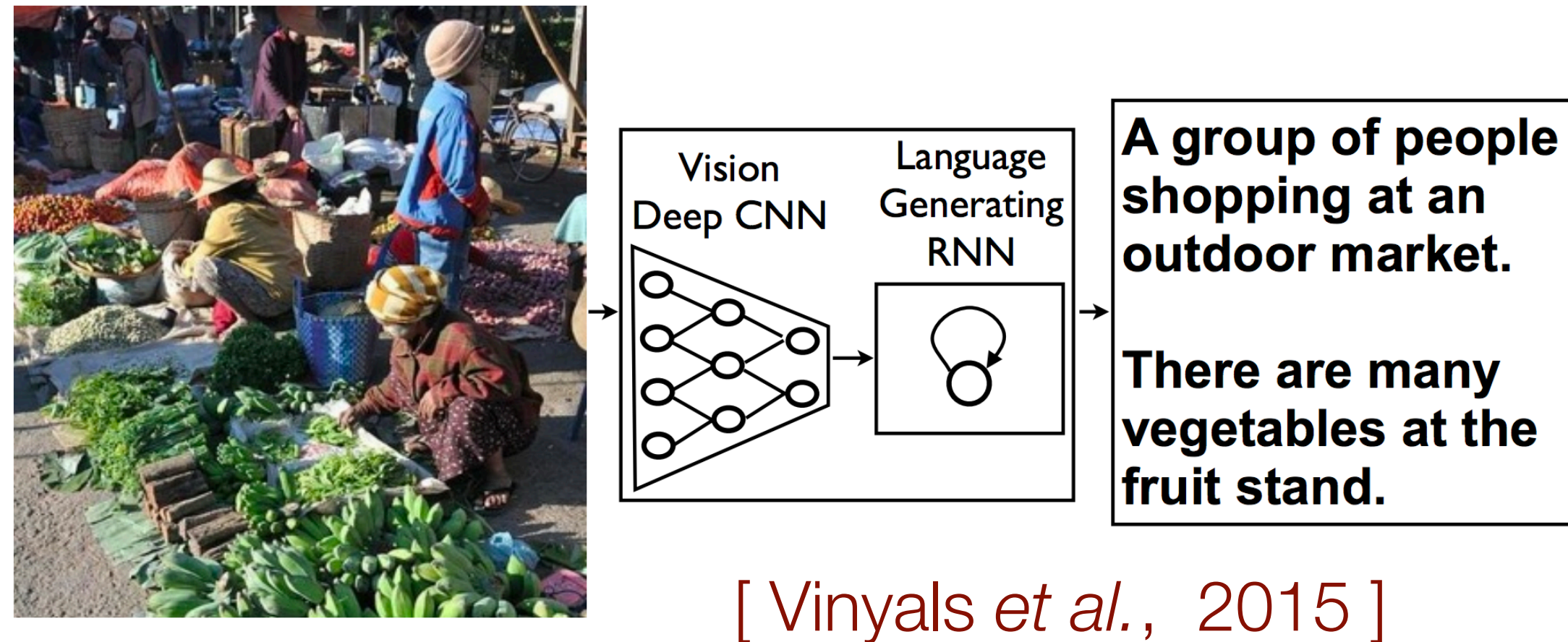


3D imaging
MRI, CT



Image guided surgery
[Grimson et al., MIT](#)

Captioning and Visual Question Answering



Q1: *What color is the bowl ?*

GT answer: *White*

Predicted answer: *White*

Rank of GT: 1

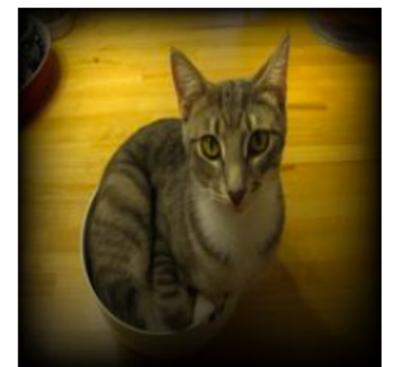


Q2: *Do you see any people?*

GT answer: *No*

Predicted answer: *No, just the cat*

Rank of GT: 2



Q3: *What color is the cat ?*

GT answer: *Grey, white, and black*

Predicted answer: *Grey, black and white*

Rank of GT: 6



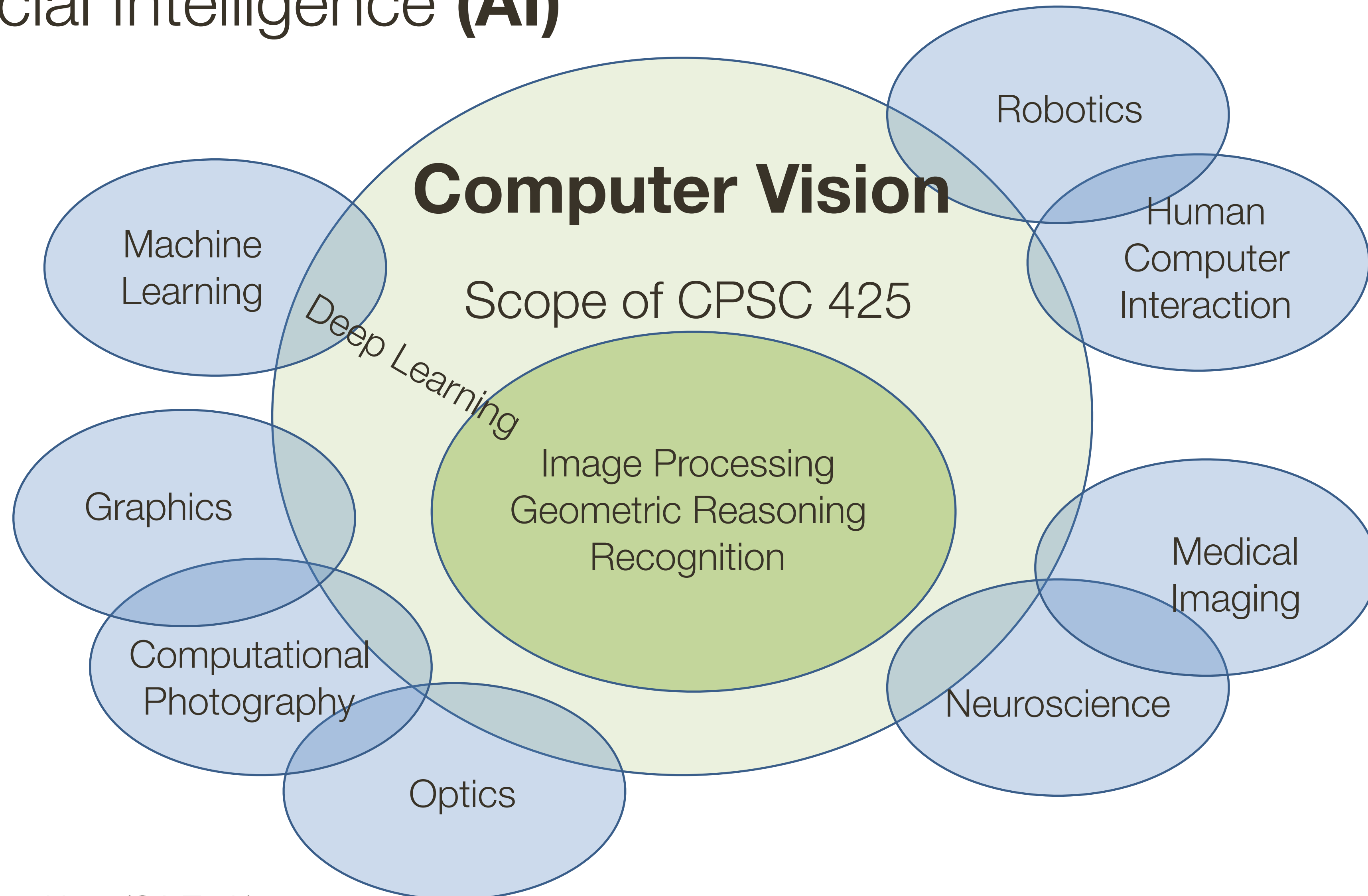
Demo: <http://vqa.clouddcv.org>

Demo: <http://demo.visualdialog.org>

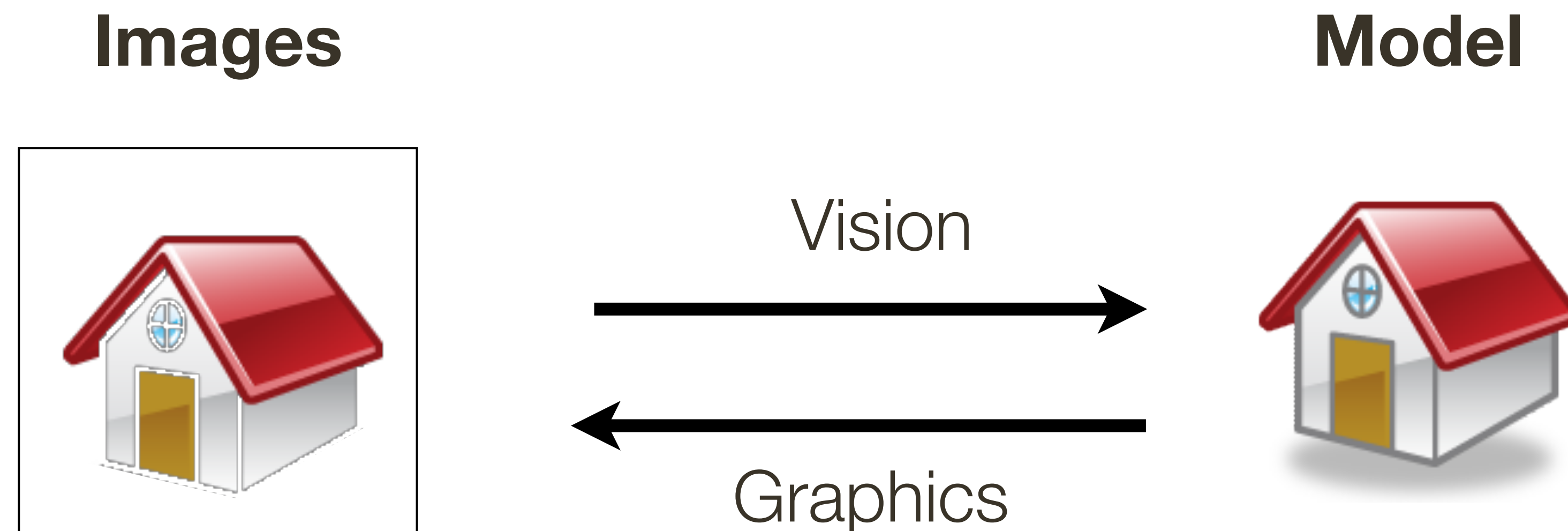
[Seo *et al.*, NIPS 2017]

Related Disciplines

Artificial Intelligence (AI)



Related Disciplines: Vision and Graphics



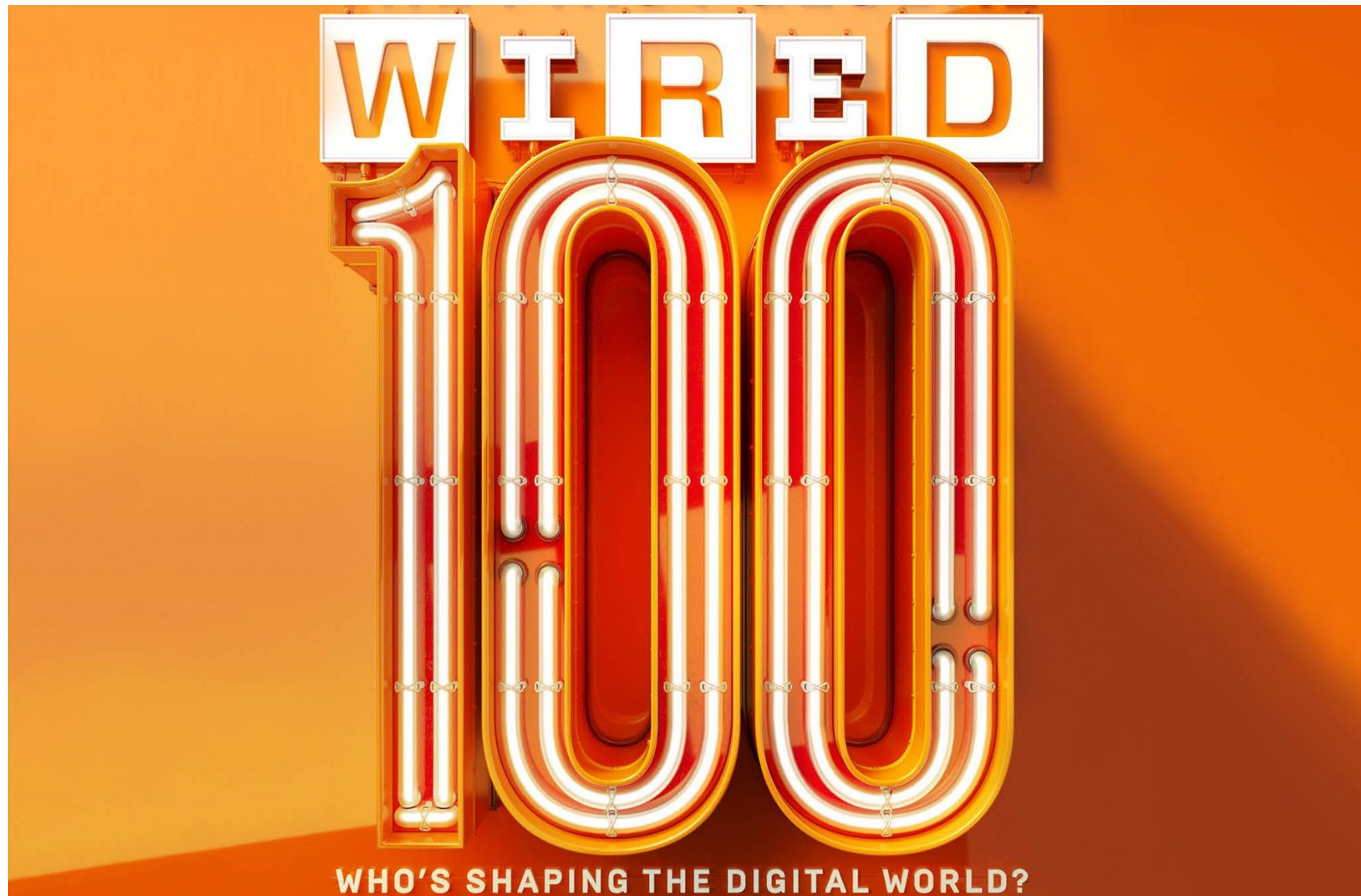
Inverse problems: analysis and synthesis

(it is sometimes useful to think about computer **vision as inverse graphics**)

Why Study Computer Vision?

It is one of the **most exciting areas of research** in computer science

Among the **fastest growing technologies** in the industry today



Wired's 100 **Most Influential People** in the World

63. Yann Lecun

Director of AI research, Facebook, Menlo Park

LeCun is a leading expert in deep learning and heads up what, for Facebook, could be a hugely significant source of revenue: understanding its user's intentions.

62. Richard Branson

Founder, Virgin Group, London

Branson saw his personal fortune grow £550 million when Alaska Air bought Virgin America for \$2.6 billion in April. He is pressing on with civilian space travel with [Virgin Galactic](#).

61. Taylor Swift

Entertainer, Los Angeles



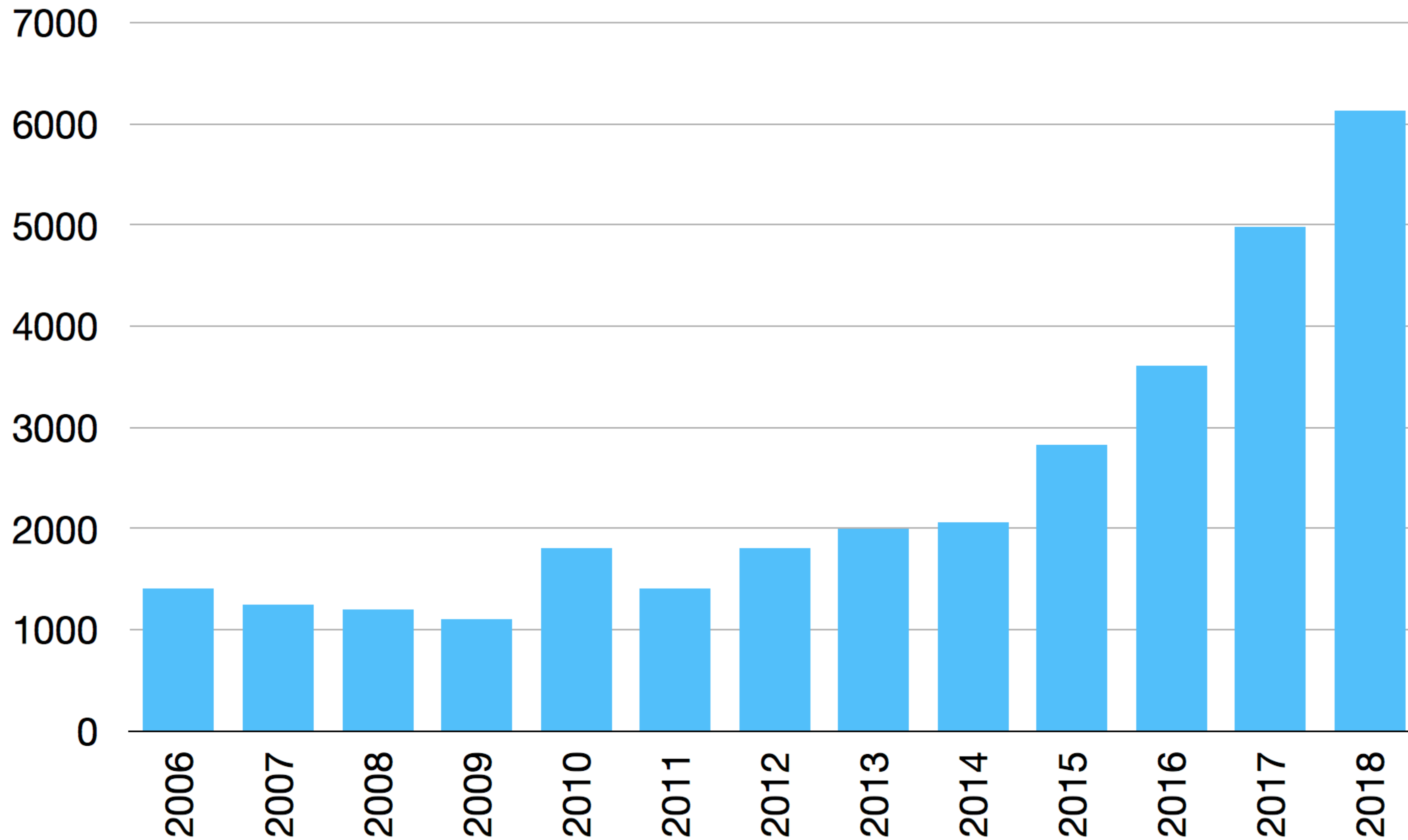


CVPR 2018

Salt Lake City



CVPR Attendance



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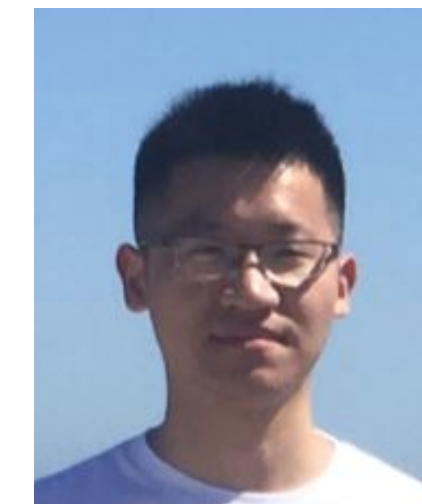
bghotbi@cs.ubc.ca

Tzu-Yun Shann



shannari@cs.ubc.ca

Bicheng Xu



bichengx@cs.ubc.ca

Alex Fan



fan@cs.ubc.ca

Course webpage: https://www.cs.ubc.ca/~lsigal/teaching18_Term2.html

Discussion: piazza.com/ubc.ca/winterterm22018/cpsc425

Topics Covered

- Image Processing (Linear Filtering, Convolution)
- Filters as Templates
- Image Feature Detection (Edges & Corners)
- Texture & Colour
- Image Feature Description (SIFT)
- Model Fitting (RANSAC, The Hough Transform)
- Camera Models, Stereo Geometry
- Motion and Optical Flow
- Clustering and Image Segmentation
- Learning and Image Classification
- Deep Learning Introduction

Course Origins

CPSC 425 was originally developed by **Bob Woodham** and has evolved over the years. Much of the material this year is adapted from material prepared by Bob, as well extensions developed by others who taught this course

Previously taught by:

- 2018-2019 Term 1 by **Leonid Sigal**
- 2016-2017 Term 2 by **Jim Little**
- 2015-2016 Term 2 by **Fred Tung**
- 2015-2015 Term 2 by **Jim Little**

Note: This is my 2nd time teaching CPSC 425

Course Origins

The course is very **broad**, but relatively **shallow** introduction to a very diverse and complex field that draws material from geometry, statistics, AI, machine learning, computer graphics, psychology and many others.

- This means we will cover many topics and different algorithms
- I will give you as much background and connection tissue as I can
 - ... but, there is no “linear” way to learn the material we will cover
 - ... I will not be able to go into depth on some of the topics

How to do **Well** in the **Course**?

- It is easy to think that material is easy and course requires no studying
- Part of your job should be going over the slides and carefully analyzing not just what is on them, but the underlying assumptions, algorithmic steps and so on
- Don't strive for “**template matching**” strive for true “**understanding**”

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$$Ax + By = C$$

Grading Criteria



In-class **clicker questions**: 10%

Programming Assignments: 25%



5 graded and 1 ungraded (optional) assignment

Midterm Exam (February 14th): 25%



Final Exam (TBD): 40%

Clicker Questions

Bring your i>Clickers to class

Register your remote: <https://canvas.ubc.ca/> before the next class
(we will test them during next lecture)

There will be clicker questions (not in every lecture):

- 1/2 point for participation
- 1/2 point for correct answer

*not all clicker quizzes are worth the same # of points, depends on # of questions.

The clicker questions contribute 10% to your total grade

Missing Quiz Policy: If you miss a quiz for a legitimate and documented reason, that quiz will be dropped (legitimate reasons: illness, conference travel, etc.) You are required to contact instructor and provide proof within 1 week of missed quiz.

Assignments

There will be **6 assignments** in total (5 marked)

- Approximately 1 every 2 weeks
- You will hand these in by 11:59pm on the due date ([read hand in instructions and late policy on course webpage](#))



You will use the **Python**, with the following libraries:
Python Imaging Library (PIL), NumPy, Matplotlib, SciPy,
Scikit-Learn

- Assignment 0 (which is ungraded) will introduce you to this.

Assignments contribute 25% to your final score (each graded assignment is 5% of your grade)

Midterm Exam

[Tentatively] on **Thursday, February 14th**

- Here in class during the lecture period
- Closed book, no notes allowed

Multiple choice, true / false and short answer questions

- Aimed to test your “understanding” of the content of the course

The Midterm exam will contribute 25% to your final score

Final Exam

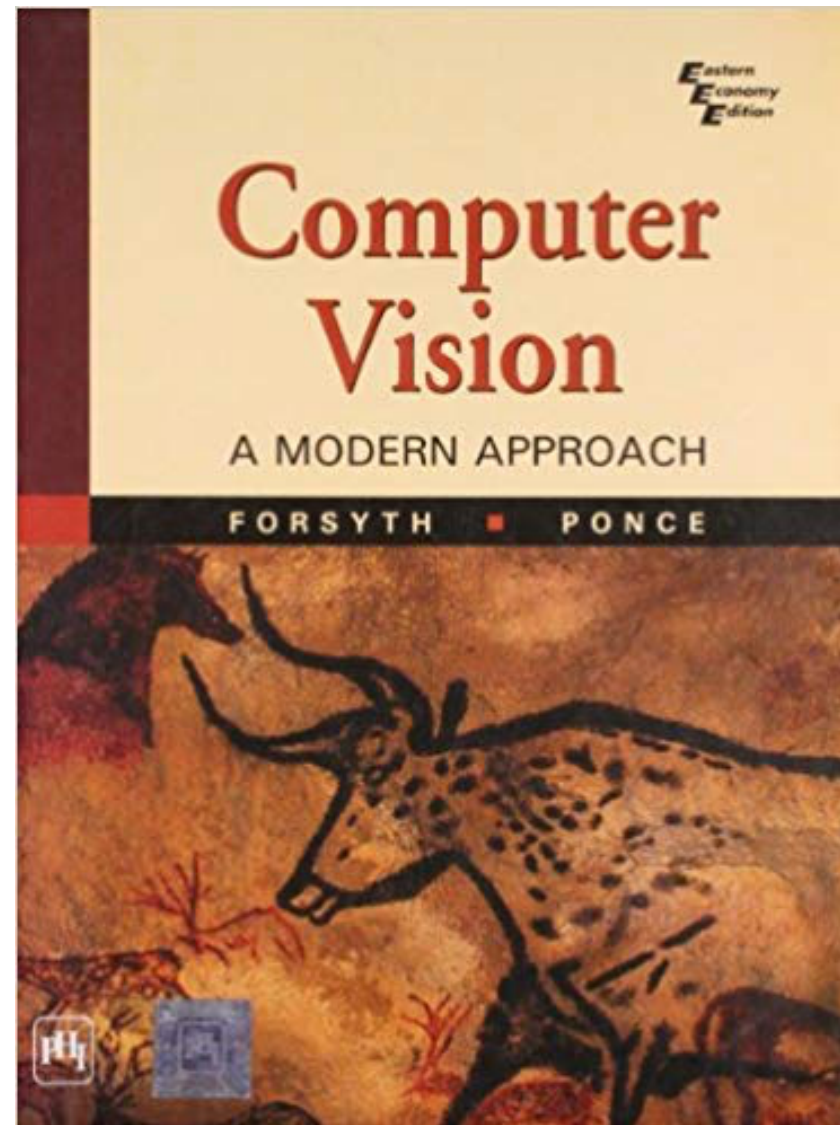
The Final exam is held during the regular examination period, **April 8 — April 26, 2019**, and is scheduled by the Registrar's Office

Similar to the midterm but longer and with more extensive short/medium answer questions

The Final exam will contribute 40% to your final score

Textbooks

The course uses the following textbook, which is recommended (but **not required**):

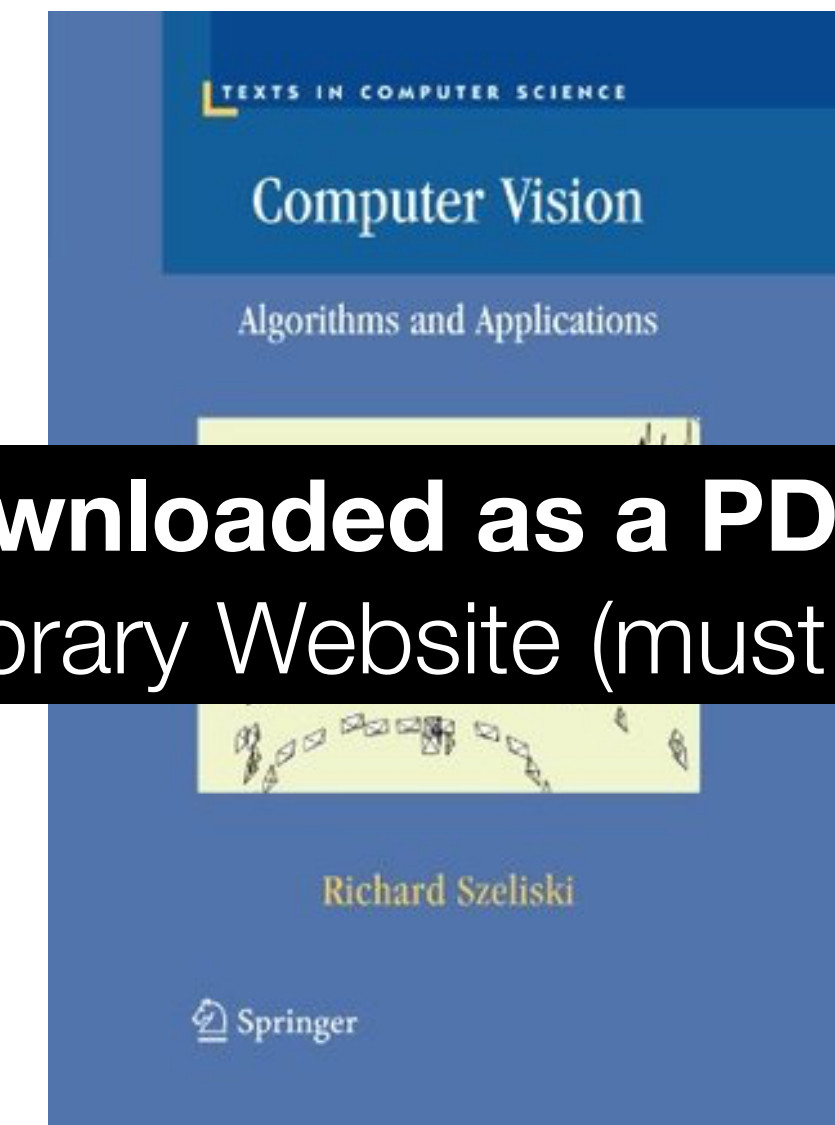


Computer Vision: A Modern Approach (2nd edition)

By: D. Forsyth & J. Ponce

Publisher: Pearson

Pub. Date: 2012



Can be **freely downloaded as a PDF** from SpringeLink, through UBC Library Website (must login using CWL).

Computer Vision: Algorithms and Applications

By: R. Szeliski

Publisher: Springer

Pub. Date: 2010

Readings

You will be assigned **readings**.

- Sometimes you will be assigned readings from other sources

Ideally, you want read the assigned reading **before coming** to the lecture

- Reading assignments will be posted on course webpage
- They will also be mentioned in class

Prepare for the **Next Lecture**

Readings:

- **Next** Lecture: Forsyth & Ponce (2nd ed.) 1.1.1 — 1.1.3

Reminders:

- Start working on **Assignment 0** (ungraded) due Wednesday, **September 12**
- **[optional]** Watch TED talk by Prof. Fei-Fei Li
<https://www.youtube.com/watch?v=40riCqvRoMs>