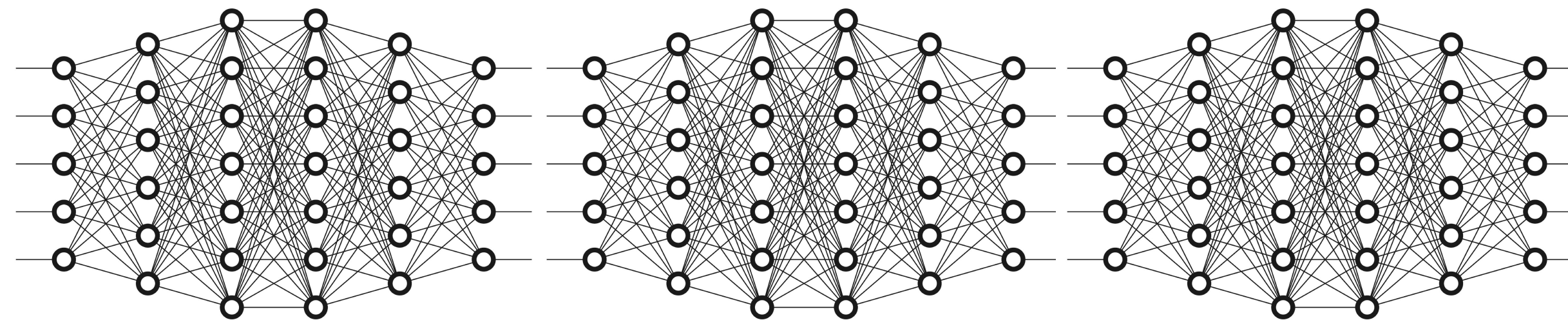




CPSC 425: Computer Vision



Lecture 33: Neural Networks

Menu for Today (November 26, 2018)

Topics:

- Neuron
- Neural Networks
- Layers and activation functions
- Backpropagation

Readings:

- **Today's** Lecture: N/A
- **Next** Lecture: N/A

Reminders:

- **Assignment 5:** Scene Recognition with Bag of Words due **last day of classes**
- Rules for **competition** are posted

Recall: Pareidolia

Pareidolia



Photo credit: reddit user [Liammm](#)

Today's “**fun**” Example: Deep Dream — Algorithmic Pareidolia



Lecture 32: Re-cap

Detection scores in the **deformable part model** are based on both appearance and location

The **deformable part model** is trained iteratively by alternating the steps

1. Assume components and part locations given; compute appearance and offset models
2. Assume appearance and offset models given; compute components and part locations

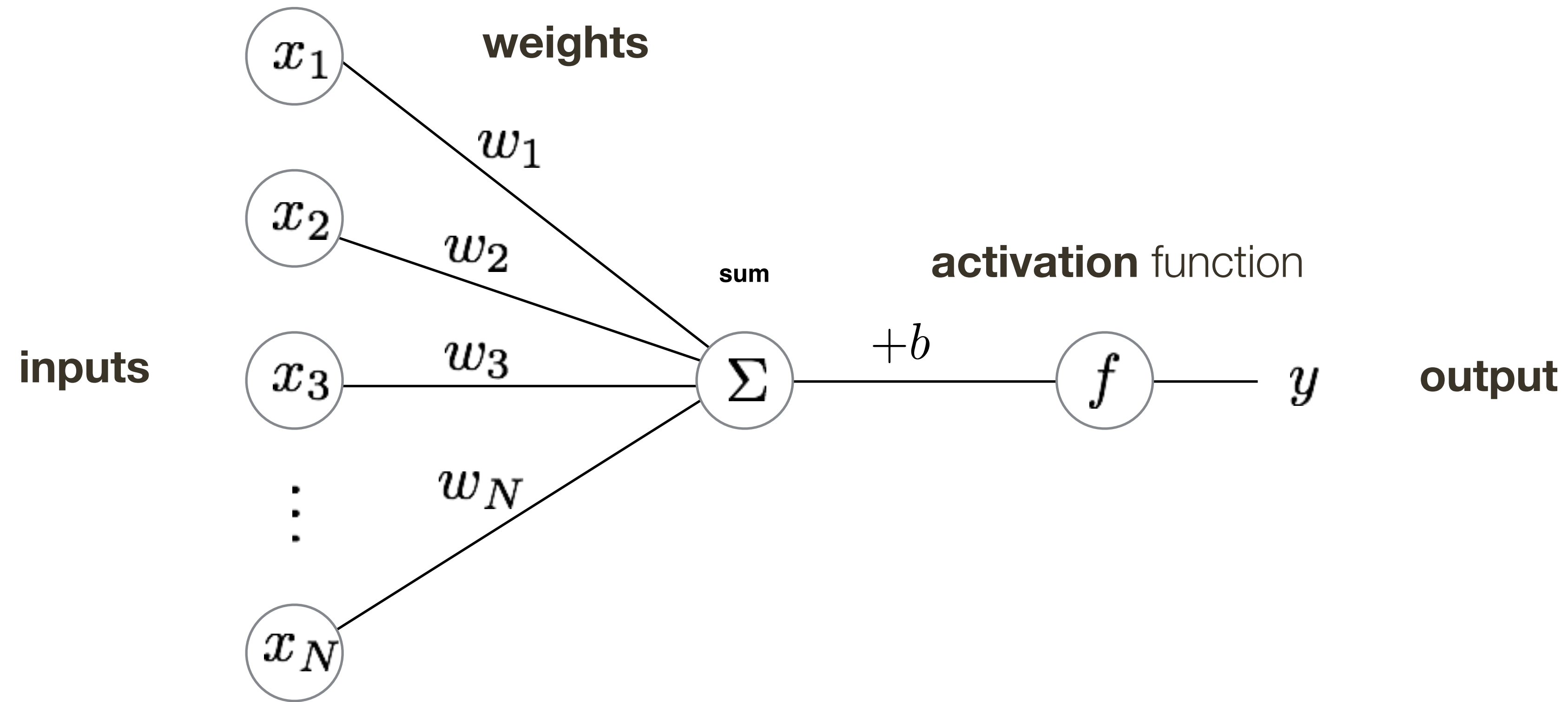
An **object proposal** algorithm generates a short list of regions with generic object-like properties that can be evaluated by an object detector in place of an exhaustive sliding window search

Warning:

Our intro to **Neural Networks** will be very light weight ...

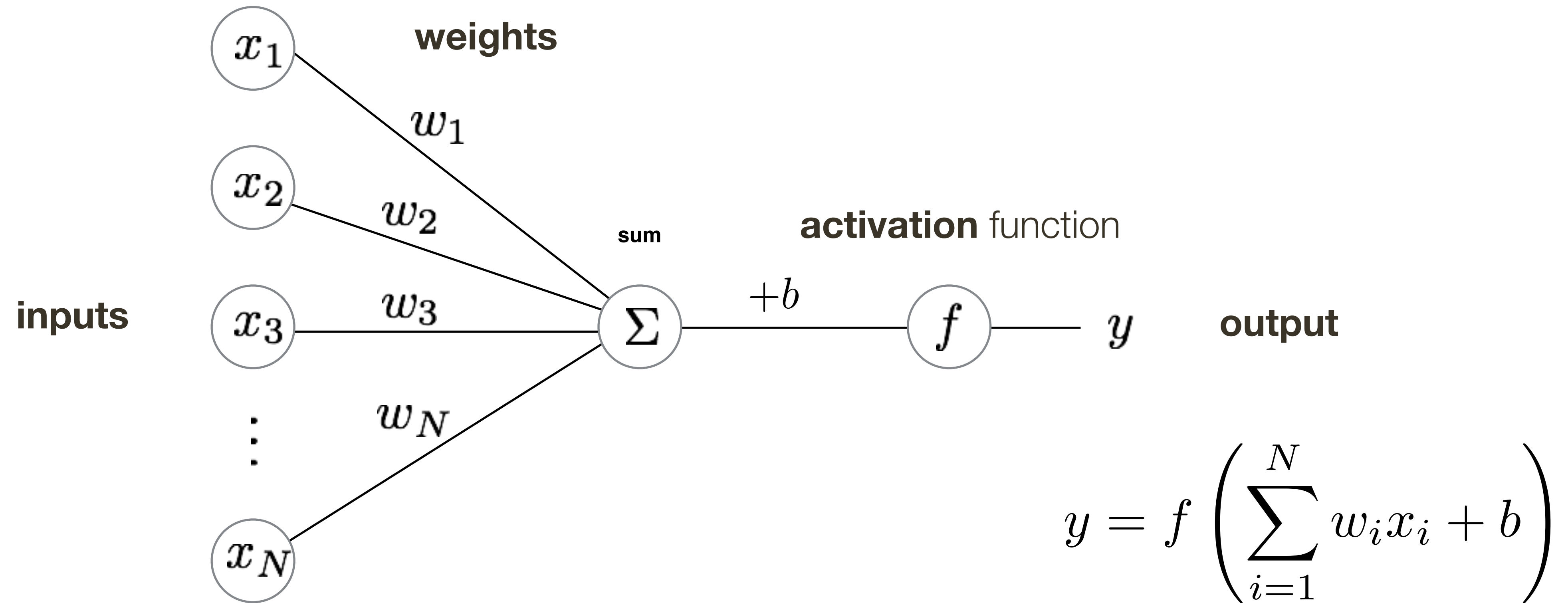
... if you want to know more, take my **CPSC 532S**

A Neuron



- The basic unit of computation in a neural network is a neuron.
- A neuron accepts some number of input signals, computes their weighted sum, and applies an **activation function** (or **non-linearity**) to the sum.
- Common activation functions include sigmoid and rectified linear unit (ReLU)

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Recall: Linear Classifier

Defines a score function:

$$f(\mathbf{x}_i, \mathbf{W}, \mathbf{b}) = \mathbf{W}\mathbf{x}_i + \mathbf{b}$$

image features

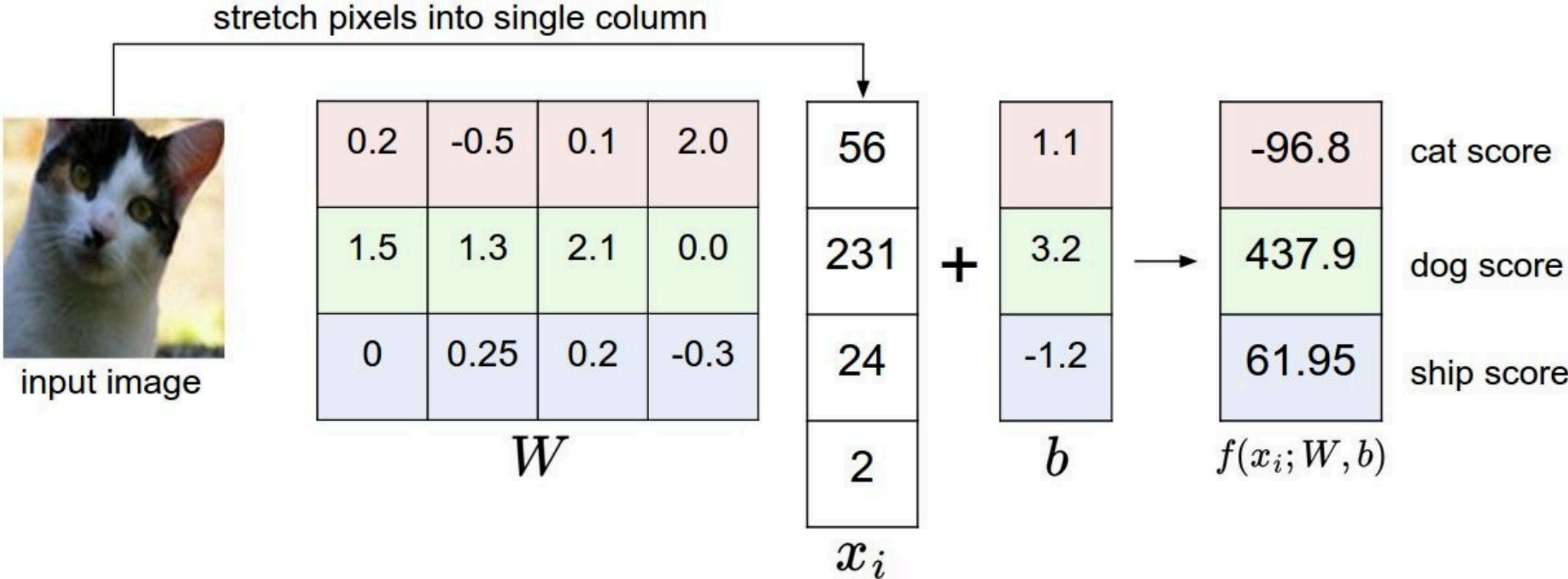
weights

(parameters)

bias vector

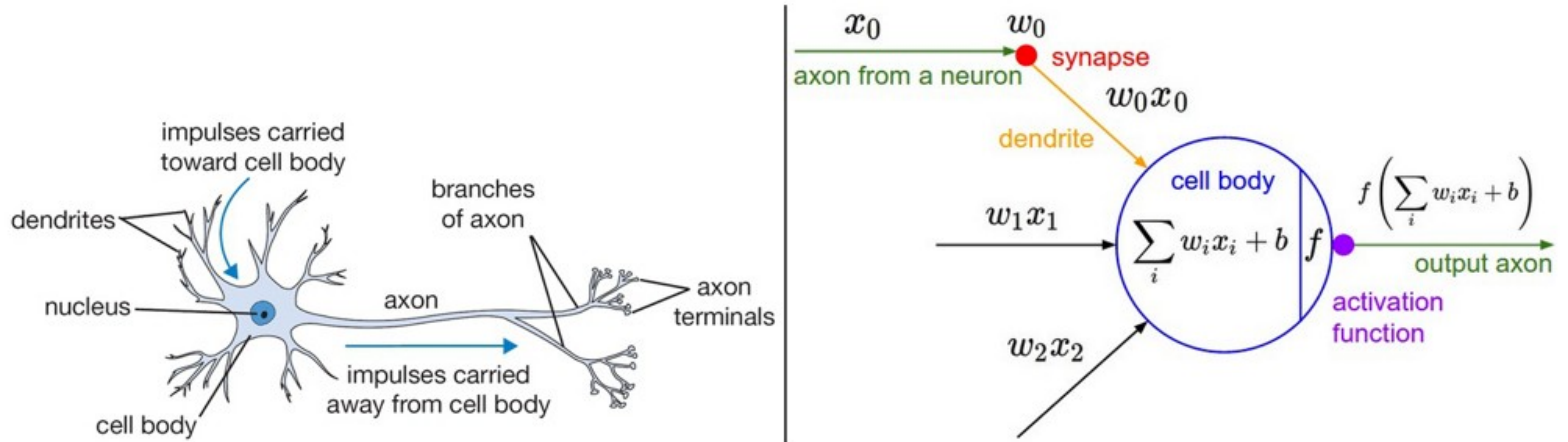
Recall: Linear Classifier

Example with an image with 4 pixels, and 3 classes (cat/dog/ship)



Aside: Inspiration from Biology

Figure credit: Fei-Fei and Karpathy



A cartoon drawing of a biological neuron (left) and its mathematical model (right).

Neural nets/perceptrons are loosely inspired by biology.

But they certainly are not a model of how the brain works, or even how neurons work.

Activation Function: **Sigmoid**

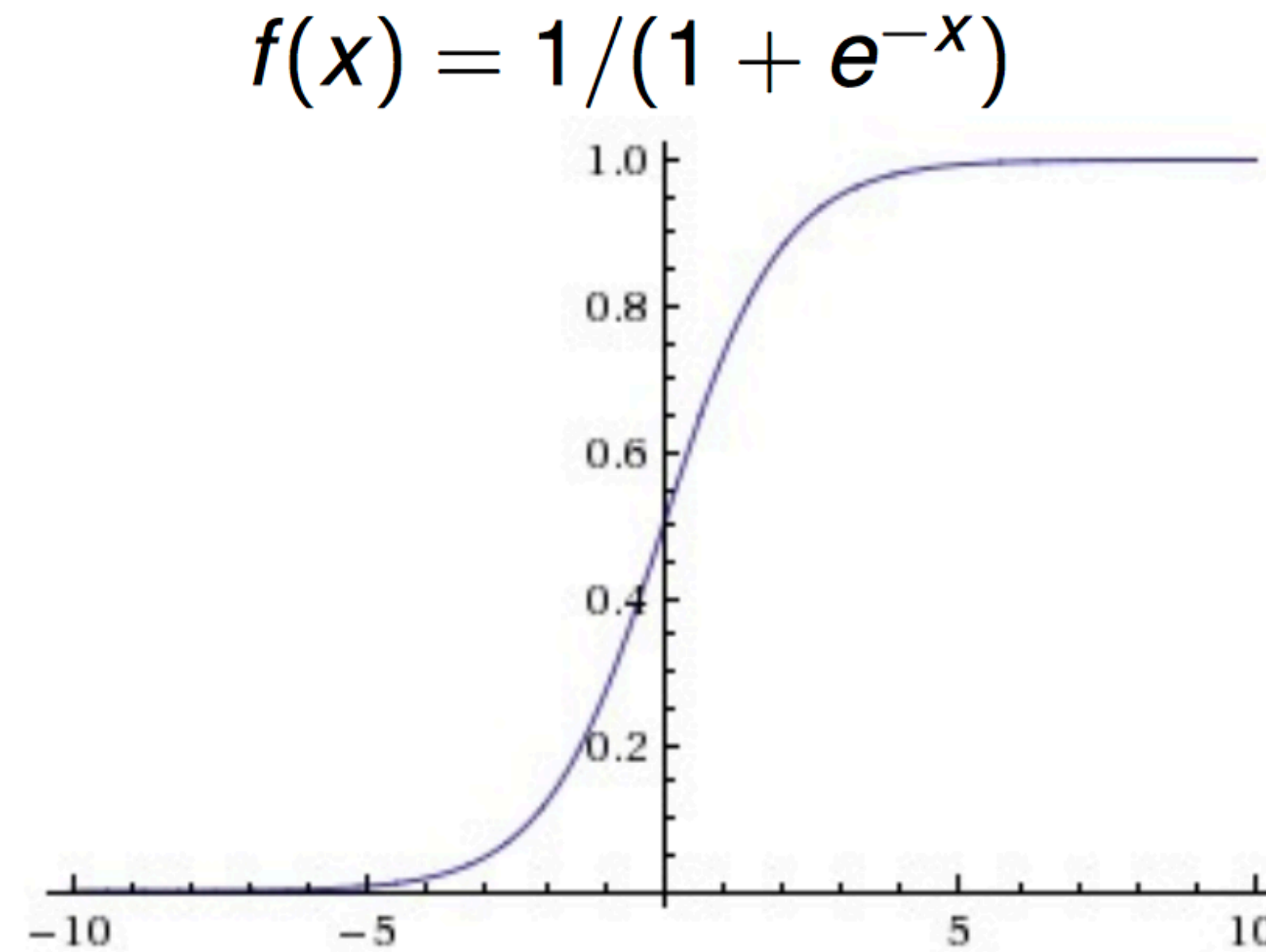


Figure credit: Fei-Fei and Karpathy

Common in many early neural networks

Biological analogy to saturated firing rate of neurons

Maps the input to the range [0, 1]

Activation Function: **ReLU** (Rectified Linear Unit)

$$f(x) = \max(0, x)$$

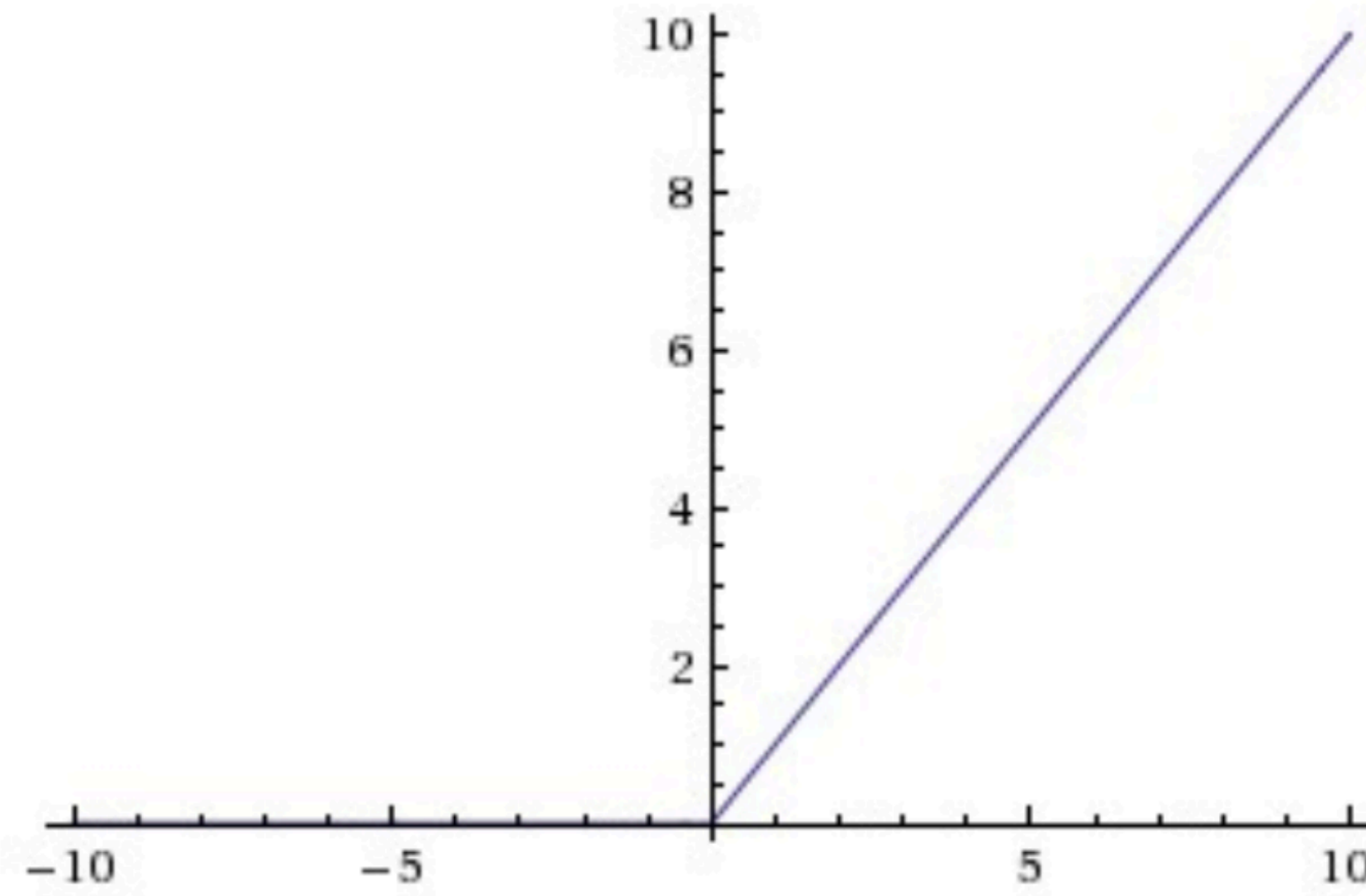
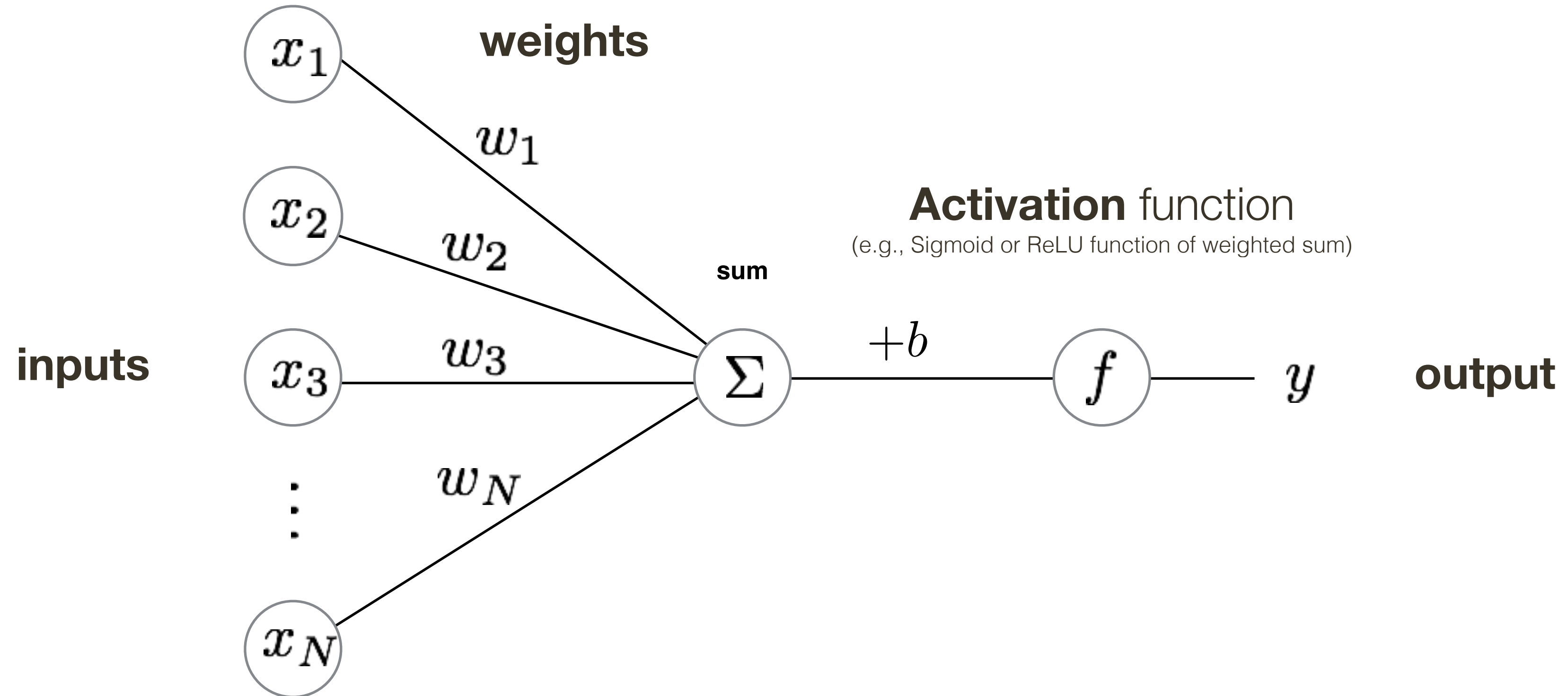


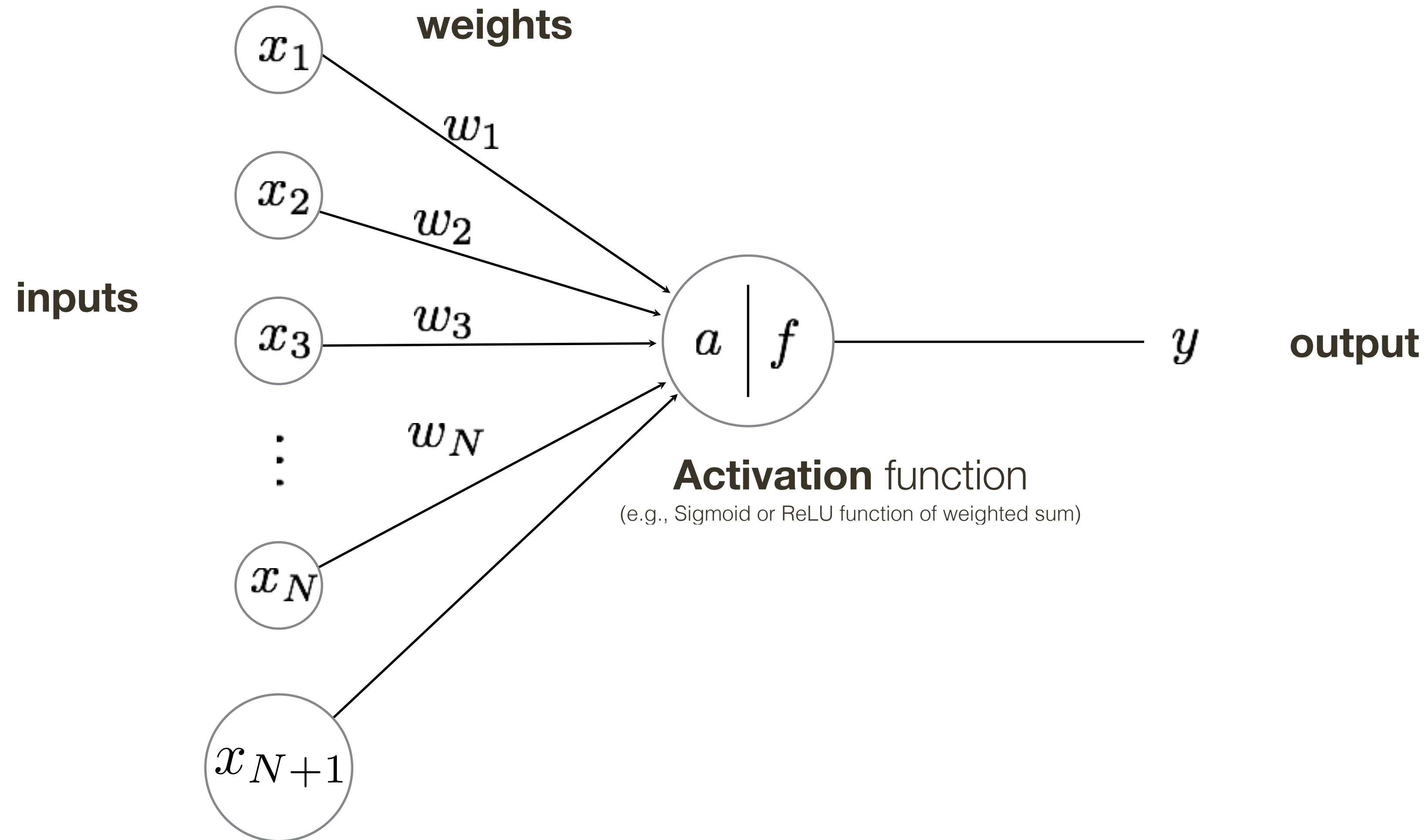
Figure credit: Fei-Fei and Karpathy

Found to accelerate convergence during learning
Used in the most recent neural networks

A Neuron

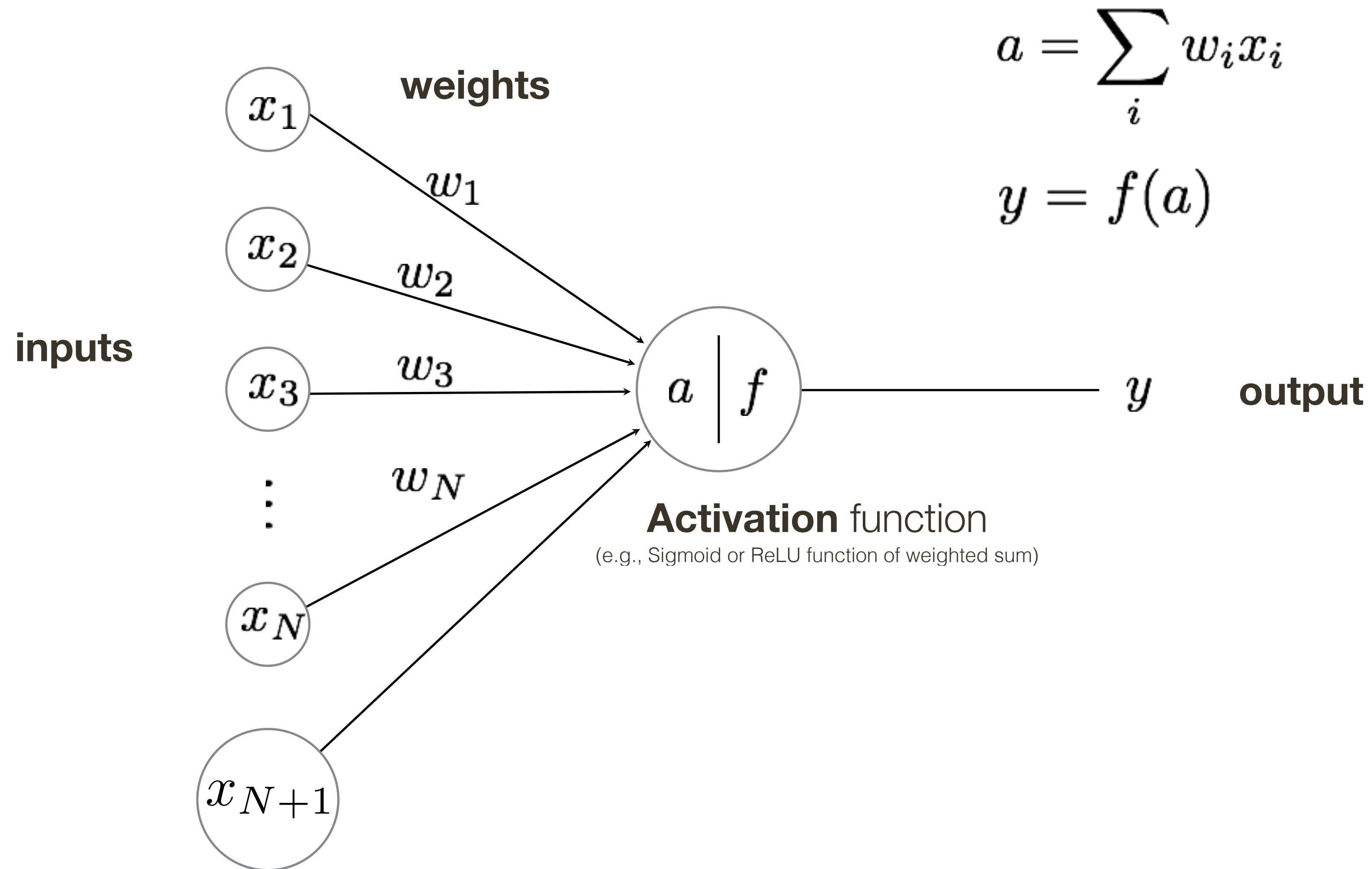


A Neuron ... another way to draw it ...



A Neuron ... another way to draw it ...

(1) Combine the sum and activation function

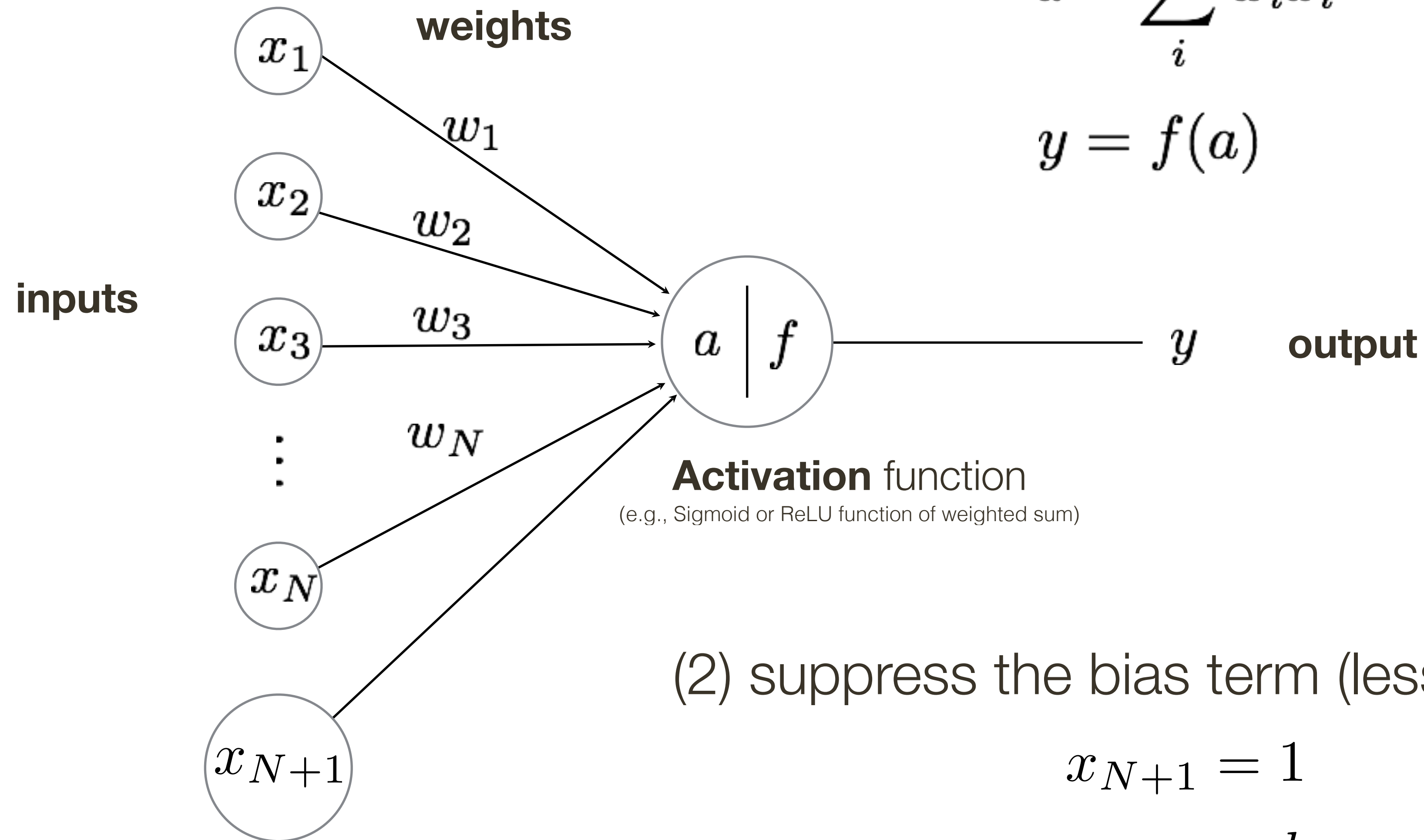


A Neuron ... another way to draw it ...

(1) Combine the sum and activation function

$$a = \sum_i w_i x_i$$

$$y = f(a)$$



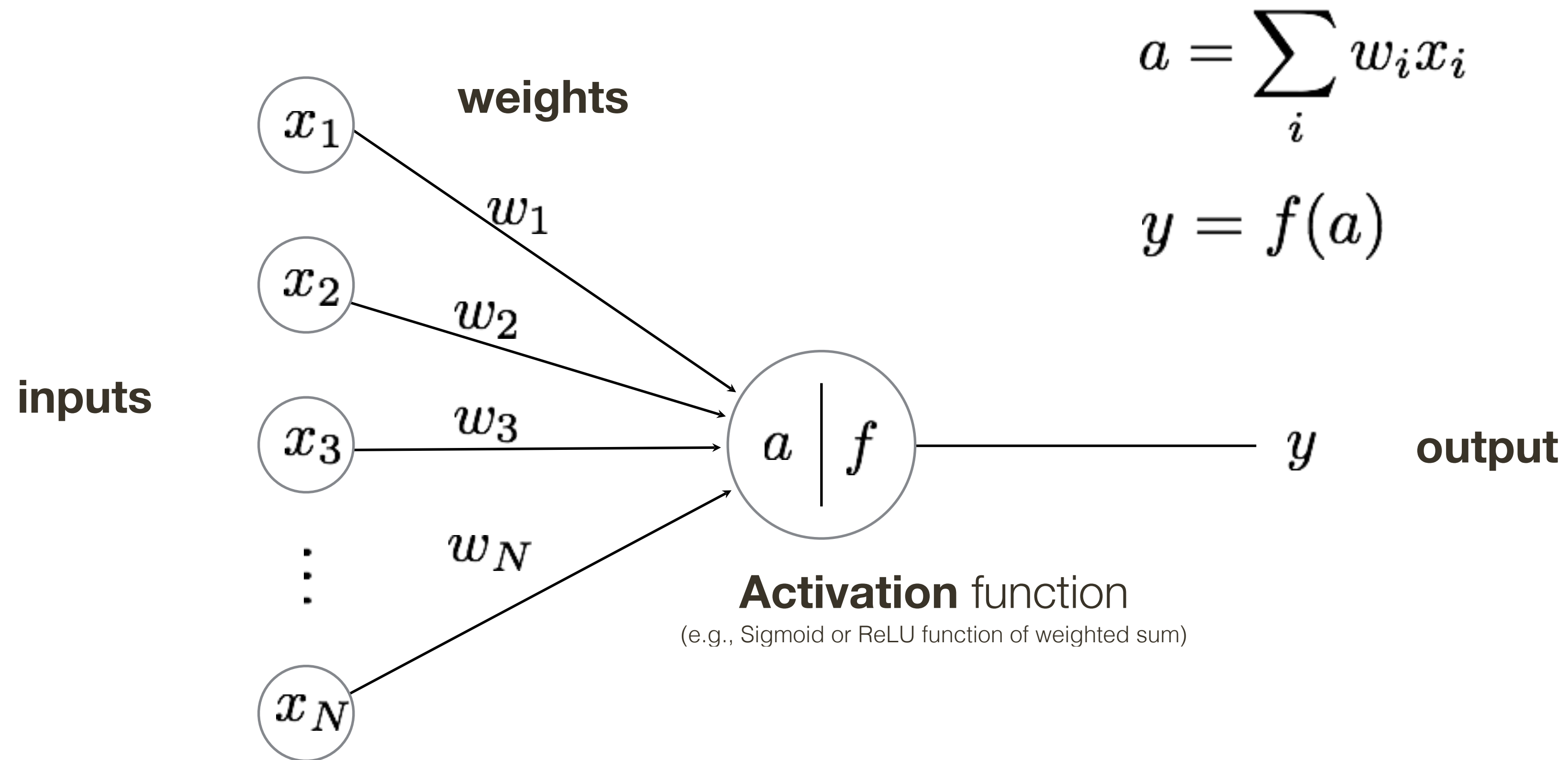
(2) suppress the bias term (less clutter)

$$x_{N+1} = 1$$

$$w_{N+1} = b$$

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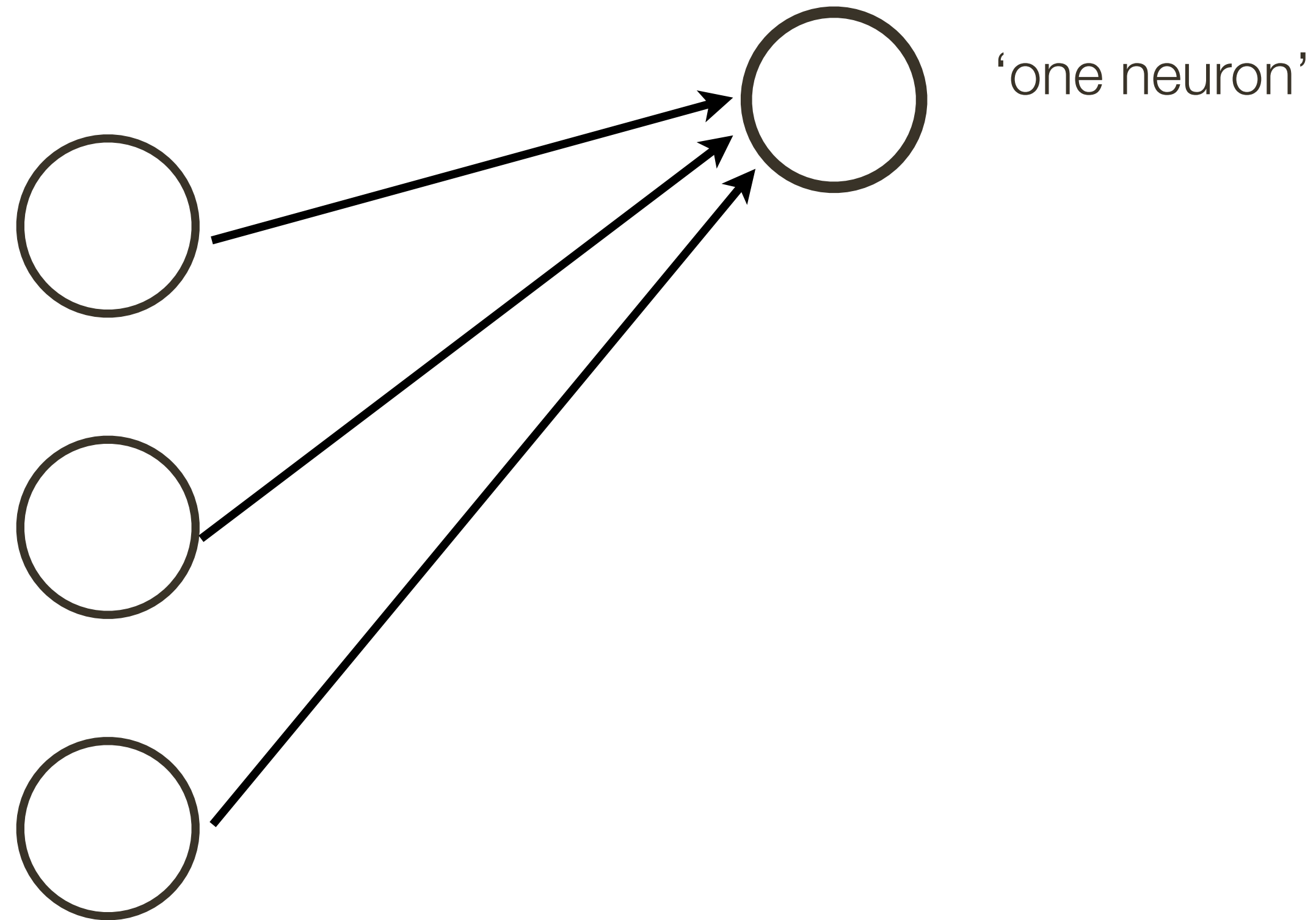
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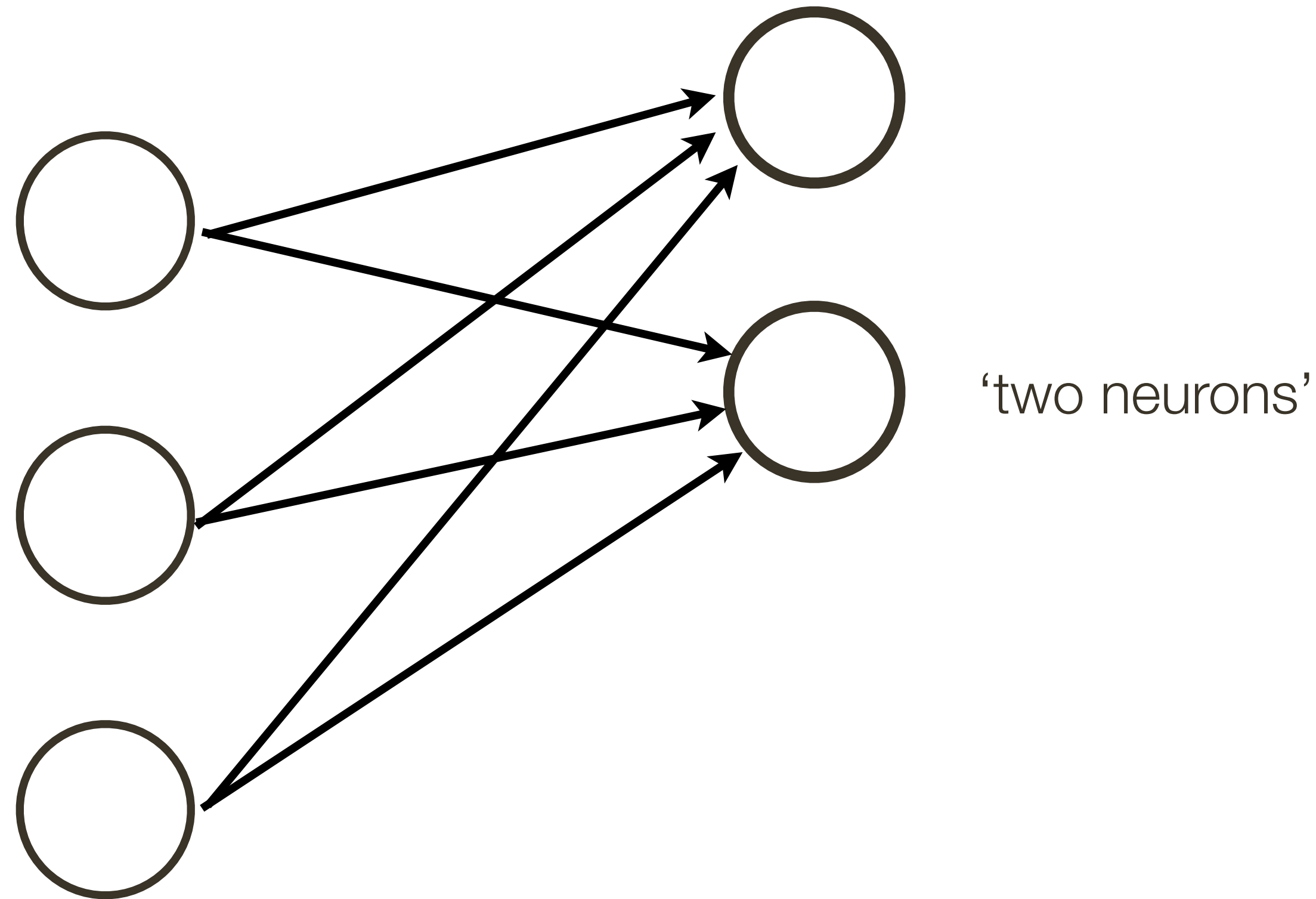
Neural Network

Connect a bunch of neurons together — a collection of connected neurons



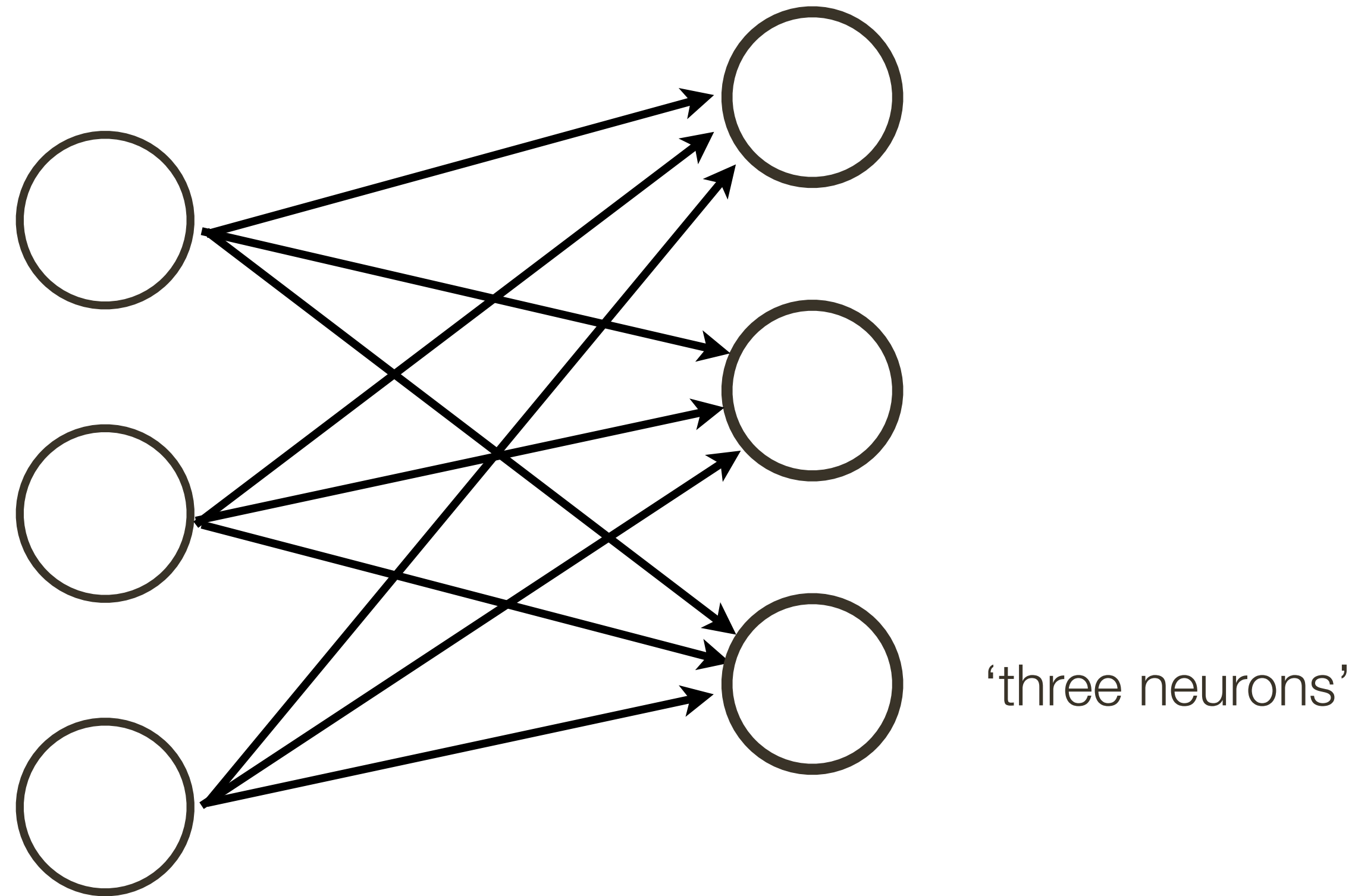
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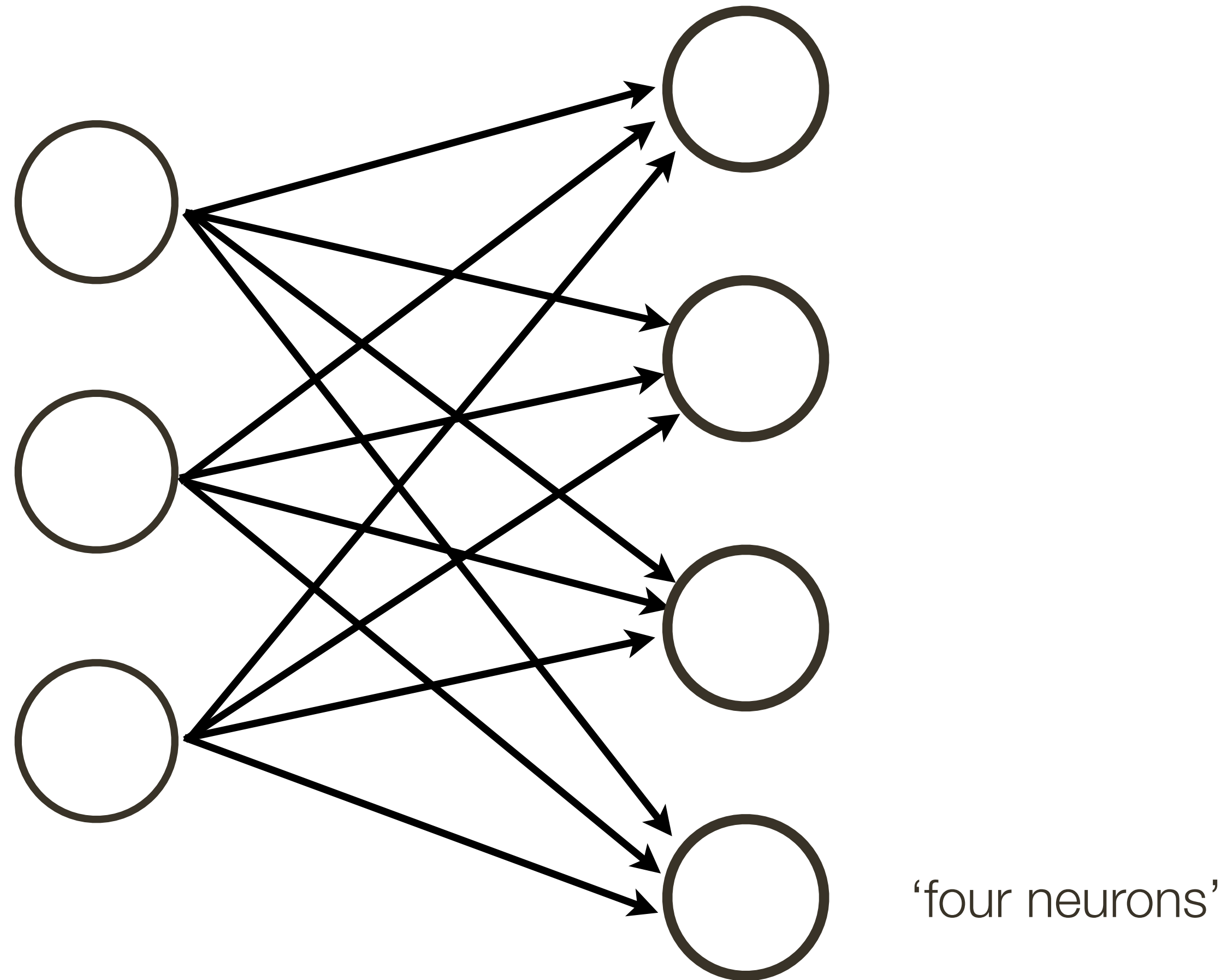
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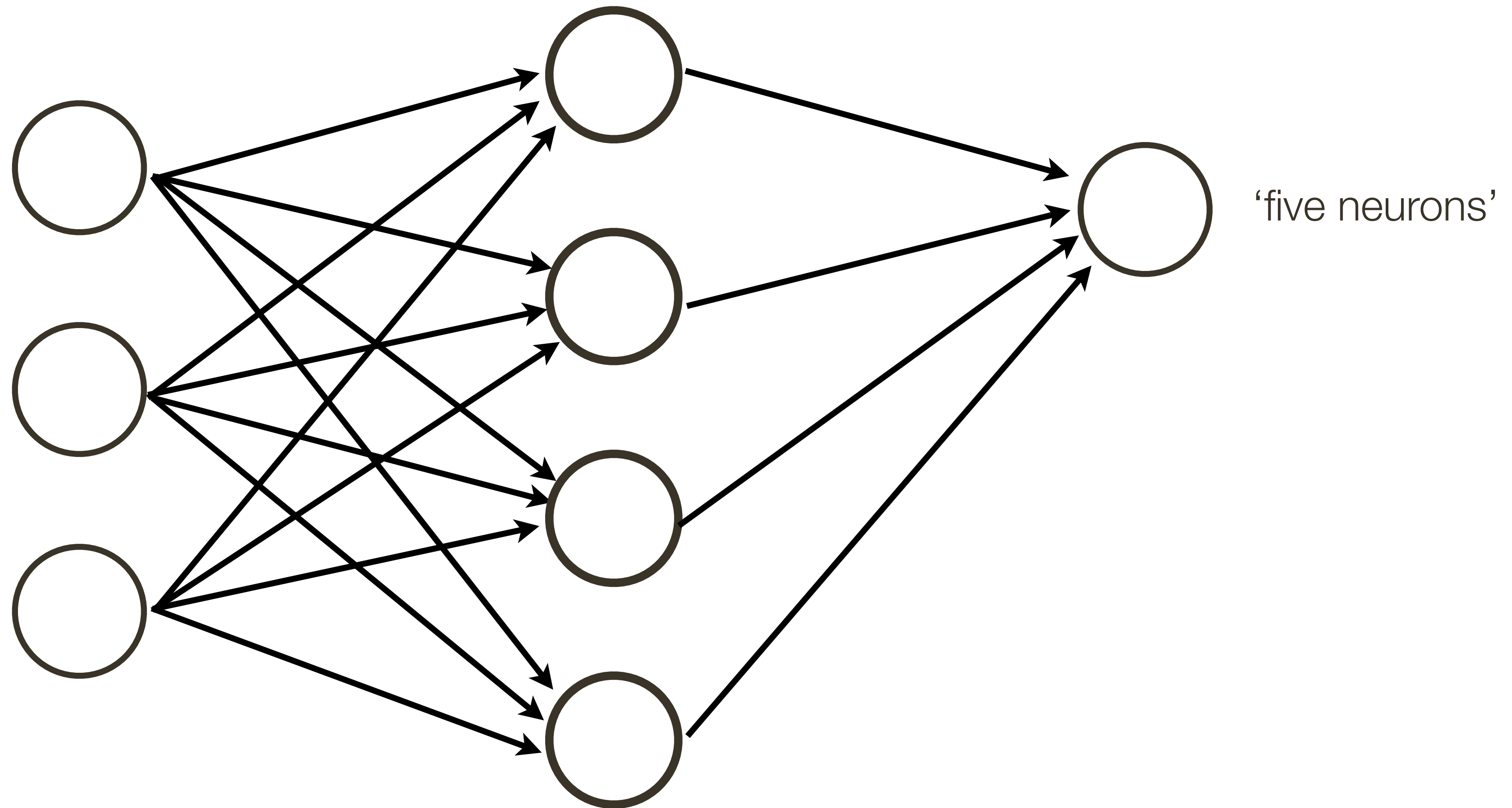
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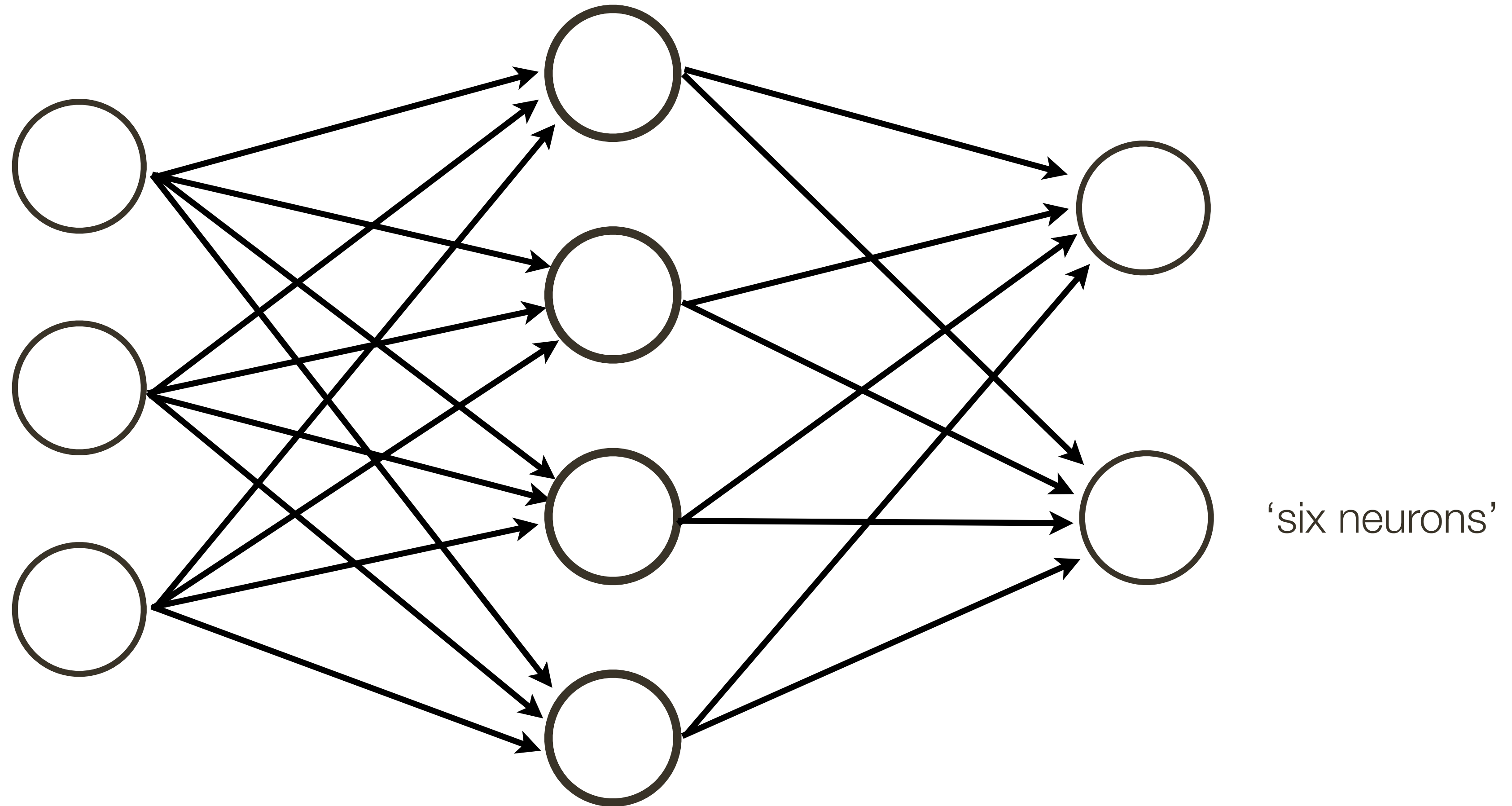
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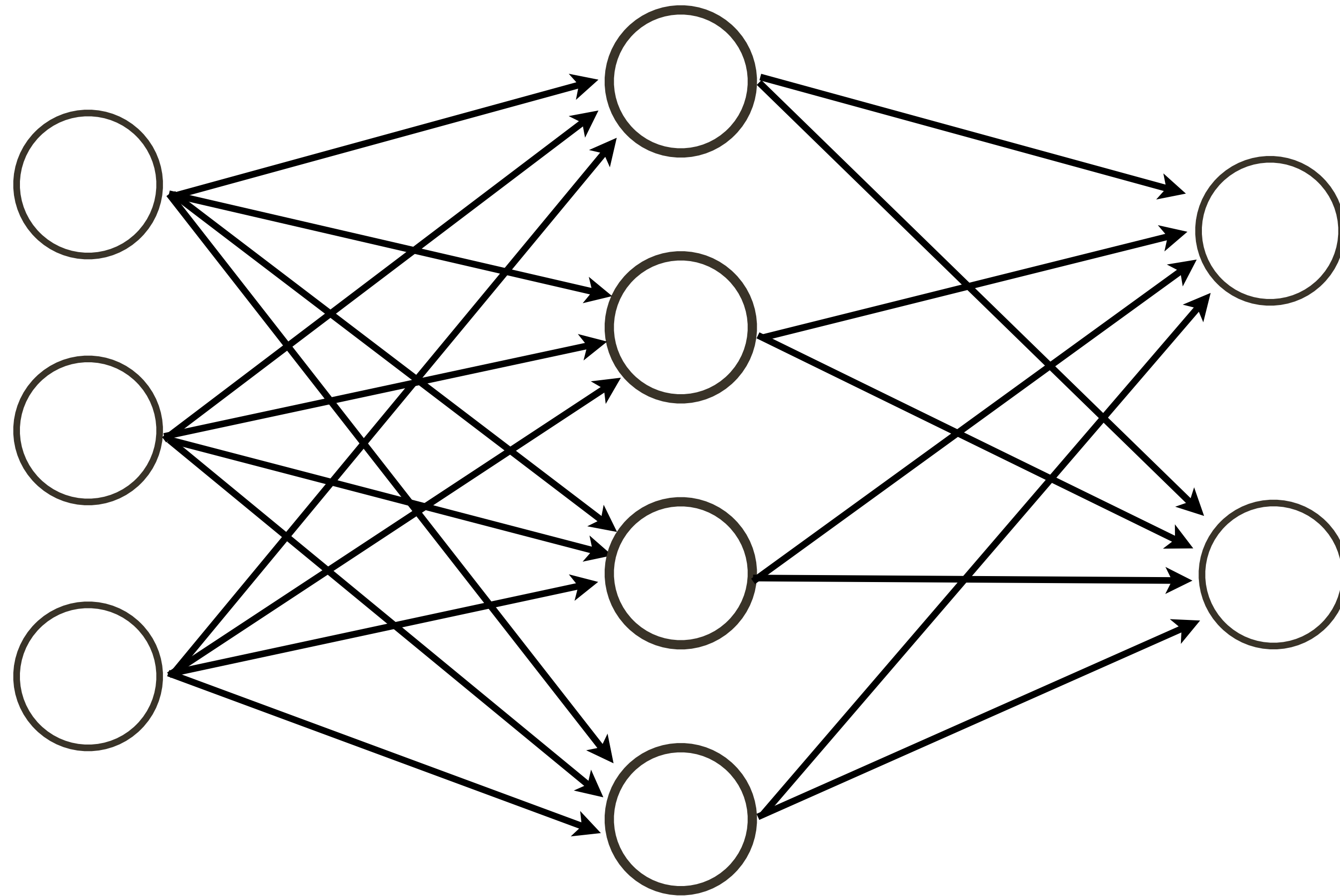
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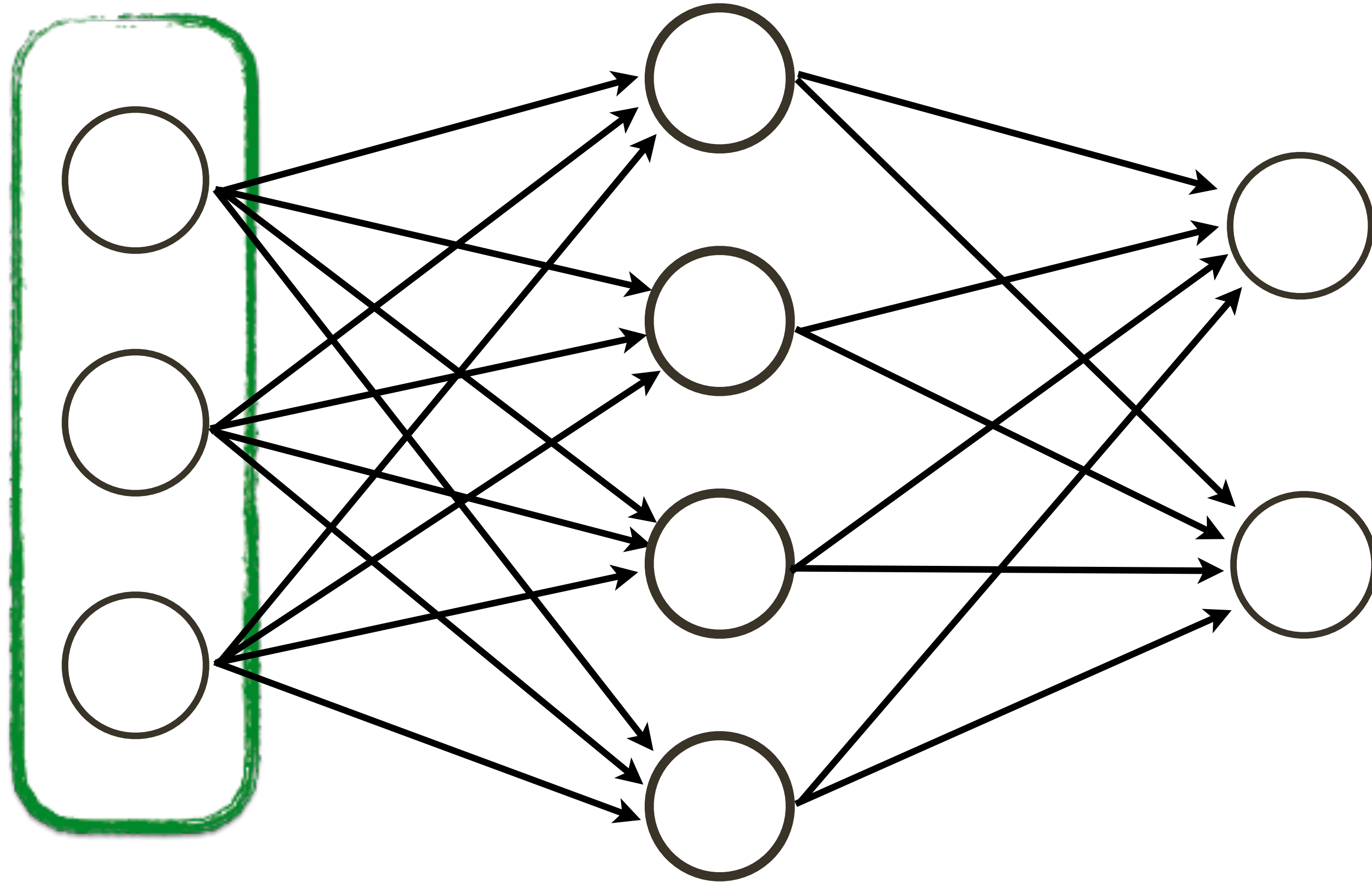
Neural Network

This network is also called a **Multi-layer Perceptron** (MLP)

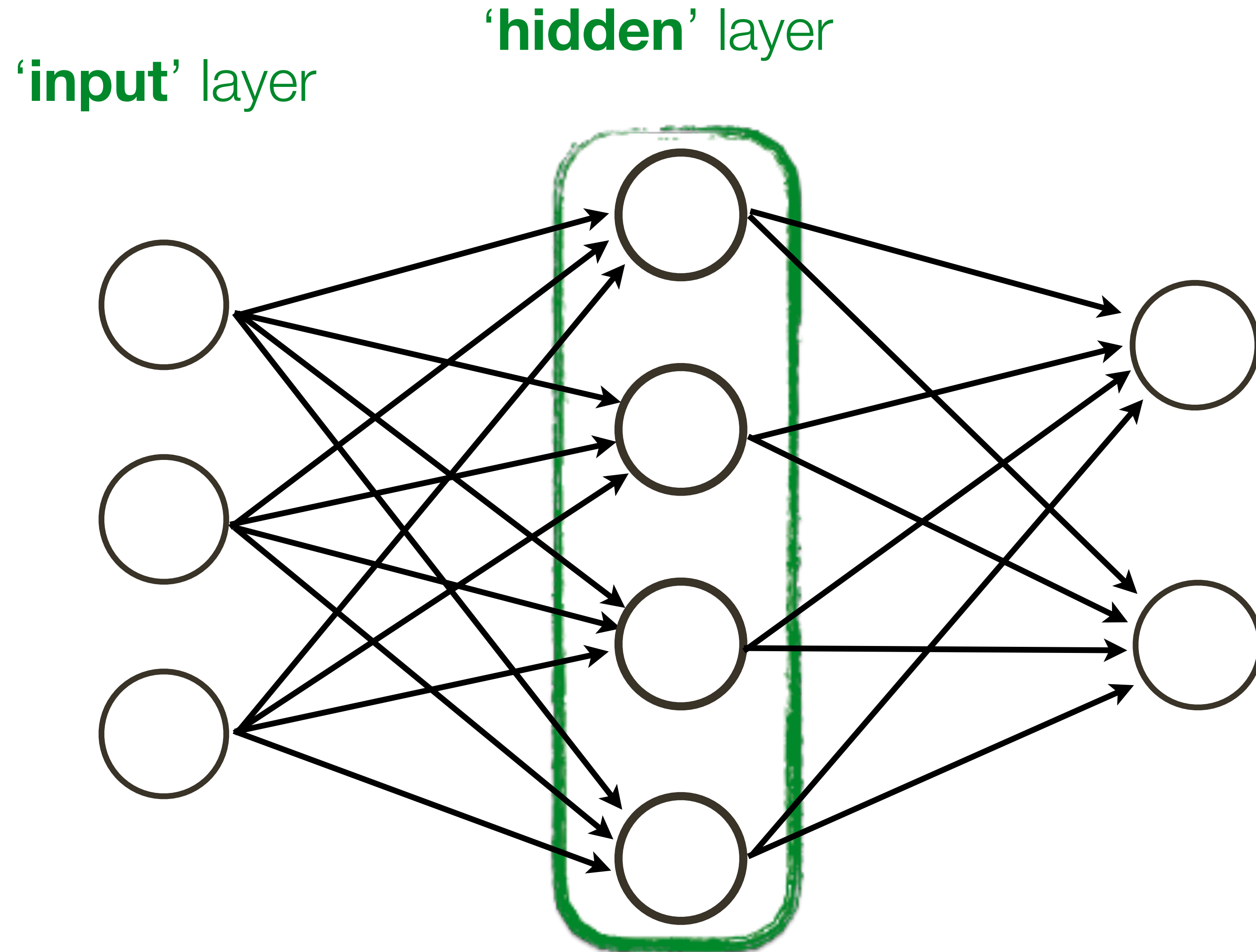


Neural Network: **Terminology**

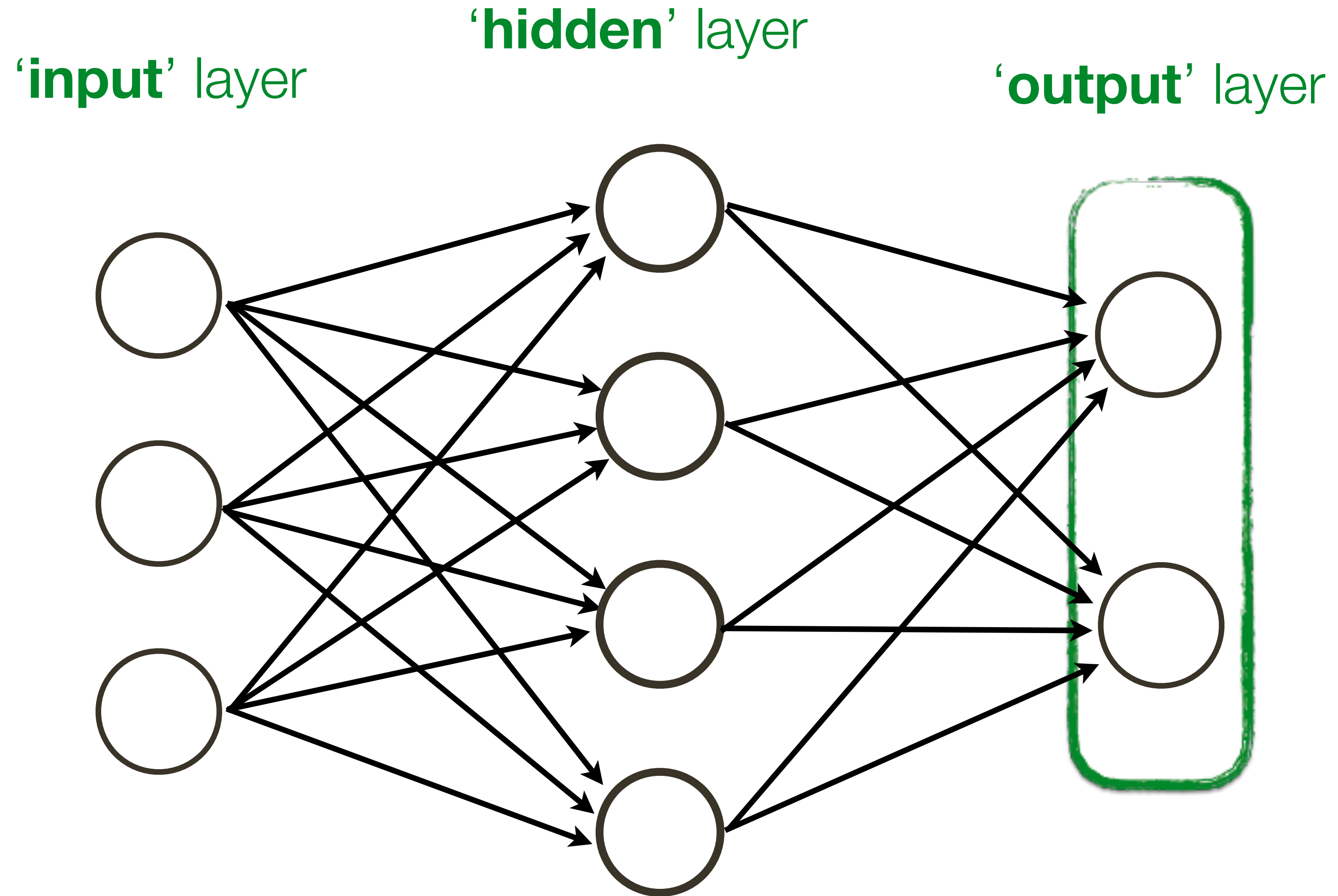
'input' layer



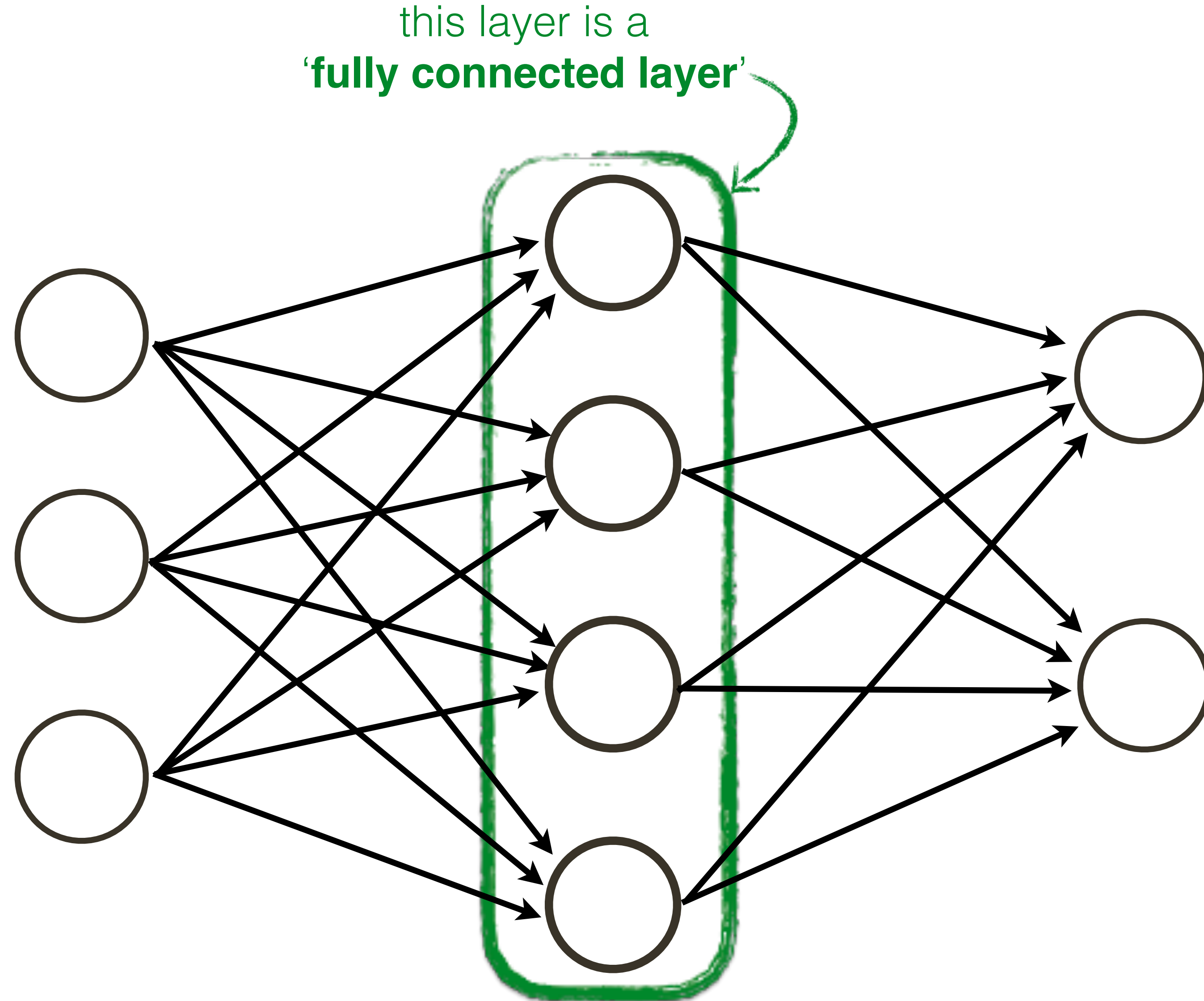
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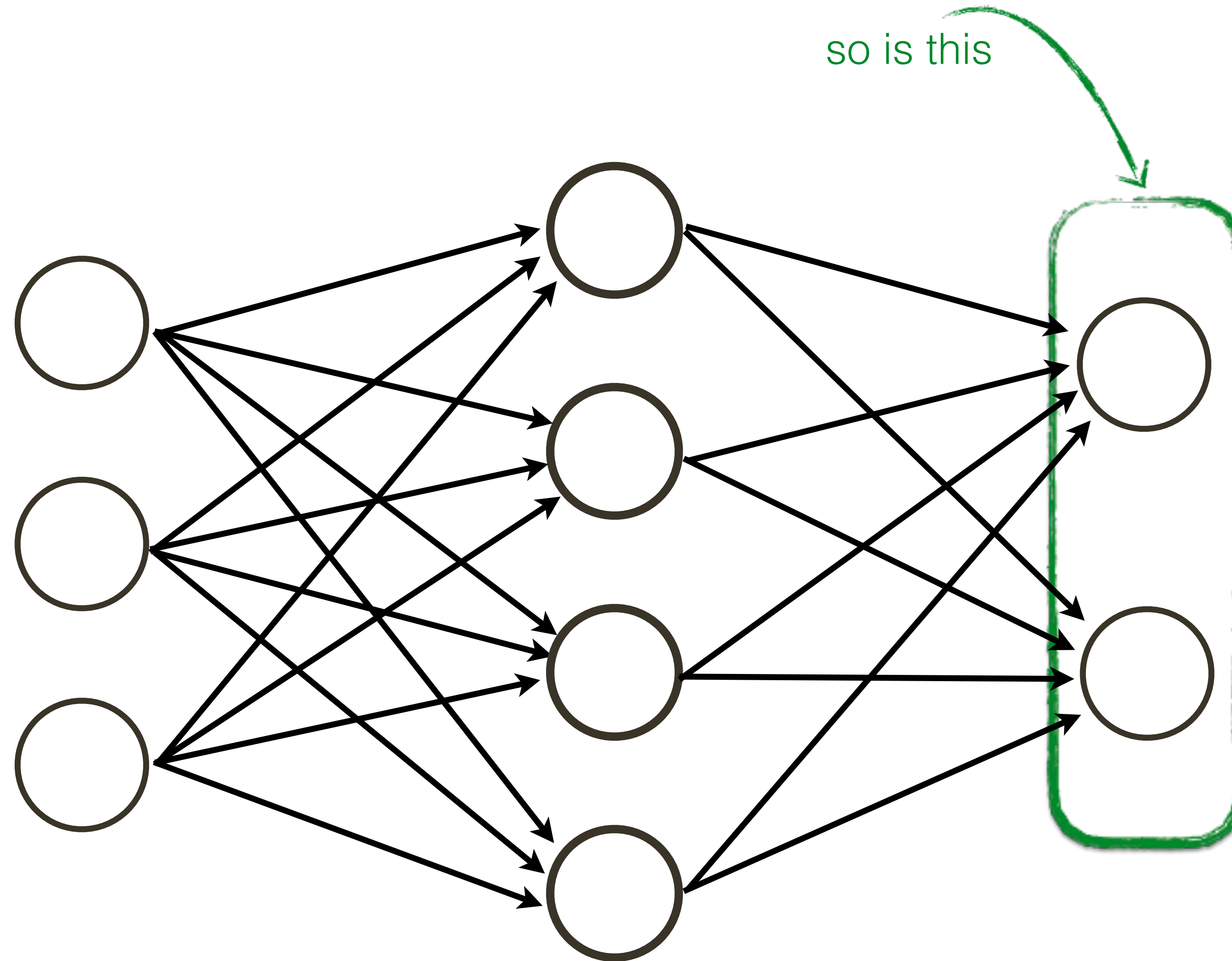
Neural Network: **Terminology**



Neural Network: **Terminology**



Neural Network: **Terminology**



Neural Network

A neural network comprises neurons connected in an acyclic graph

The outputs of neurons can become inputs to other neurons

Neural networks typically contain multiple layers of neurons

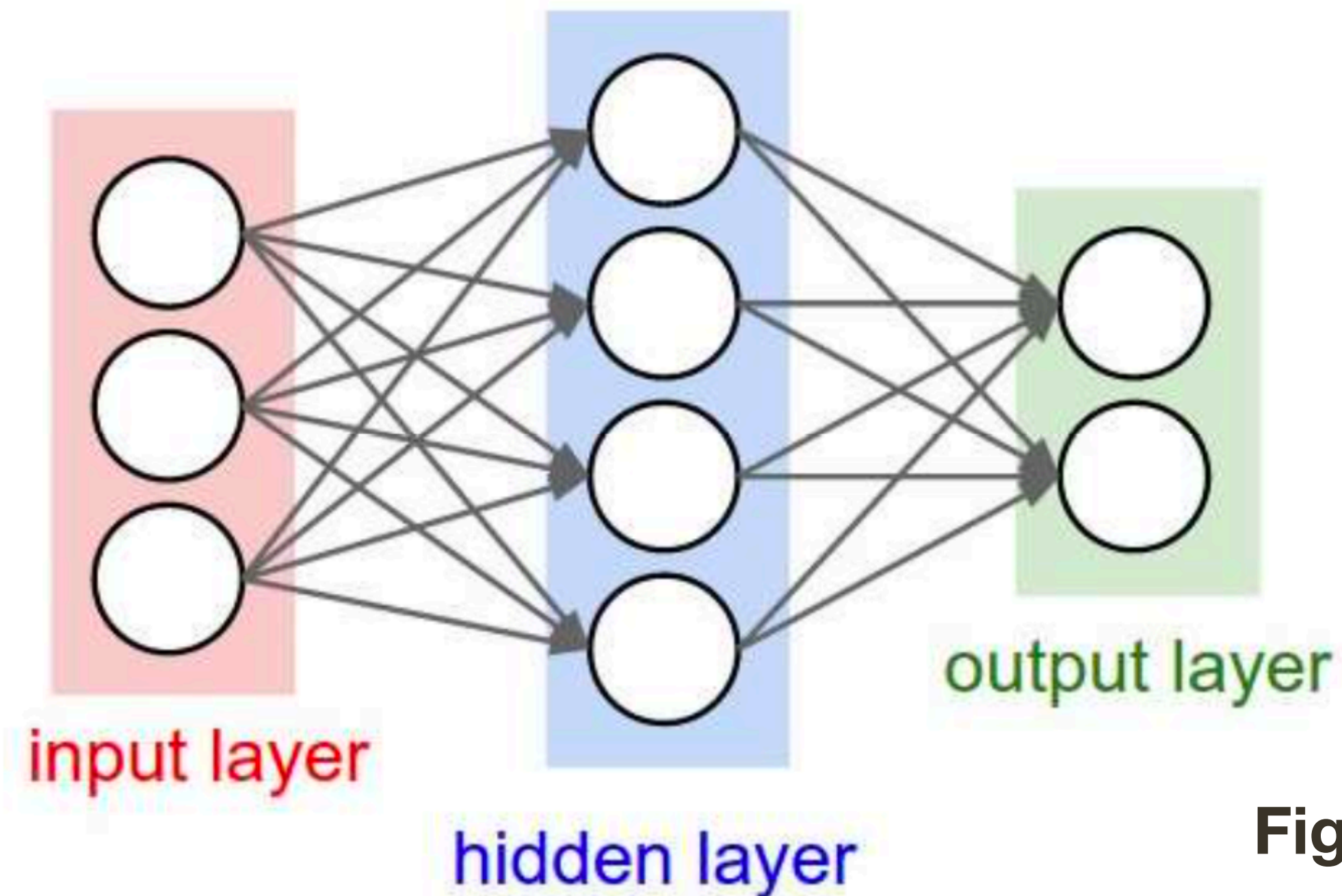


Figure credit: Fei-Fei and Karpathy

Example of a neural network with three inputs, a single hidden layer of four neurons, and an output layer of two neurons

Neural Network **Intuition**

Question: What is a Neural Network?

Answer: Complex mapping from an input (vector) to an output (vector)

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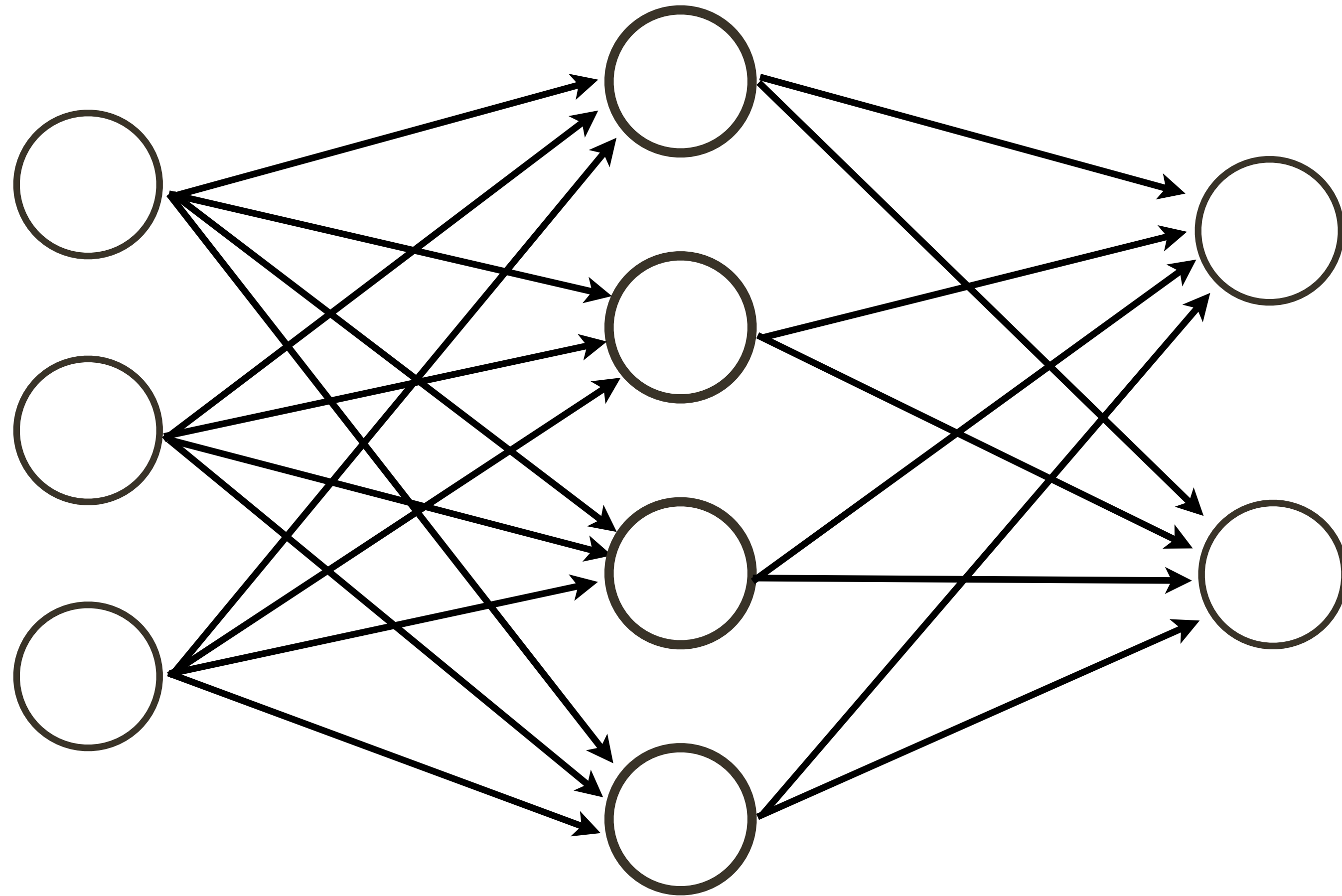
Answer: It can be thought of as classifier or a feature.

Question: Why have many layers?

Answer: 1) More layers = more complex functional mapping
2) More efficient due to distributed representation

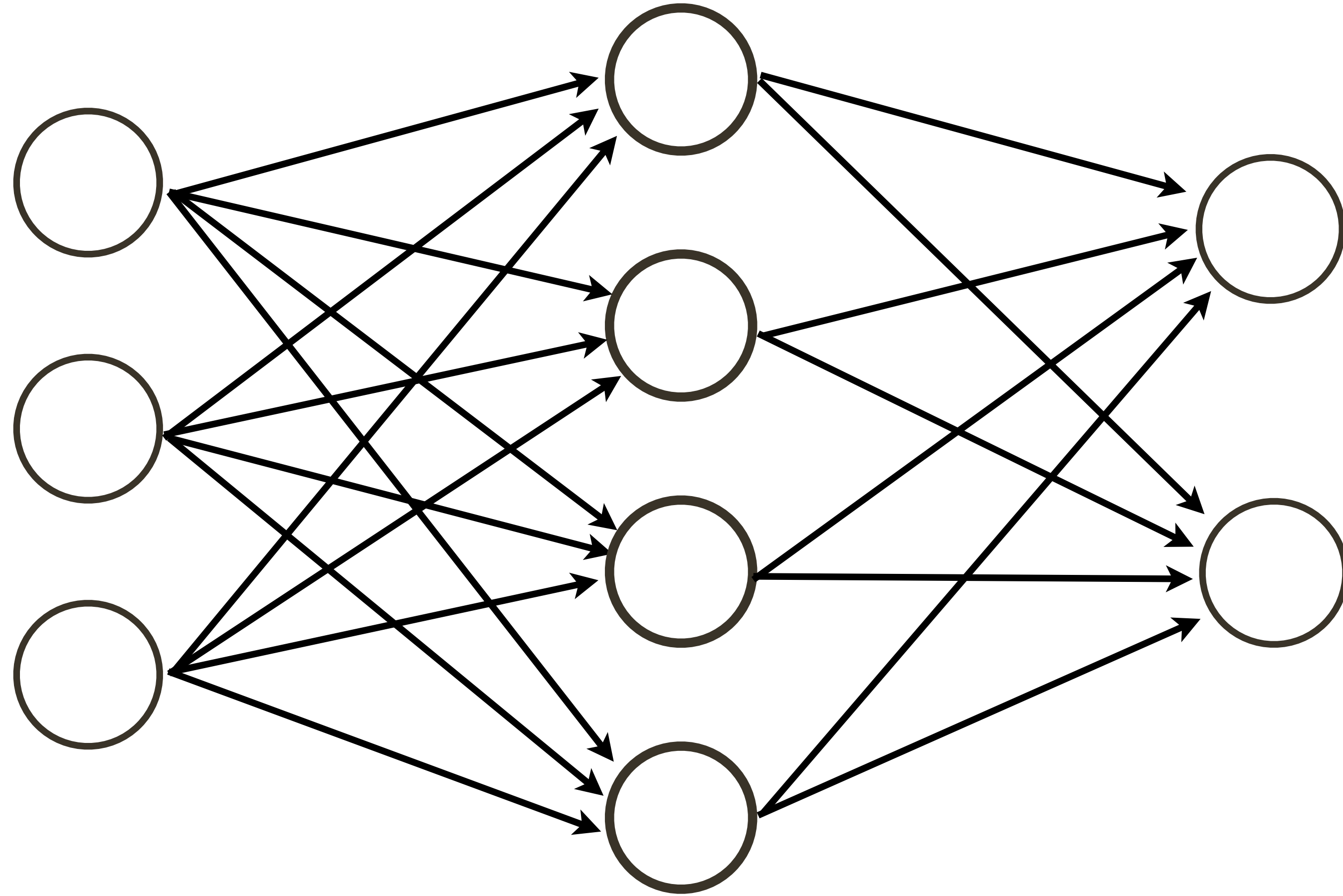
Activation Function

Why can't we have **linear** activation functions? Why have non-linear activations?



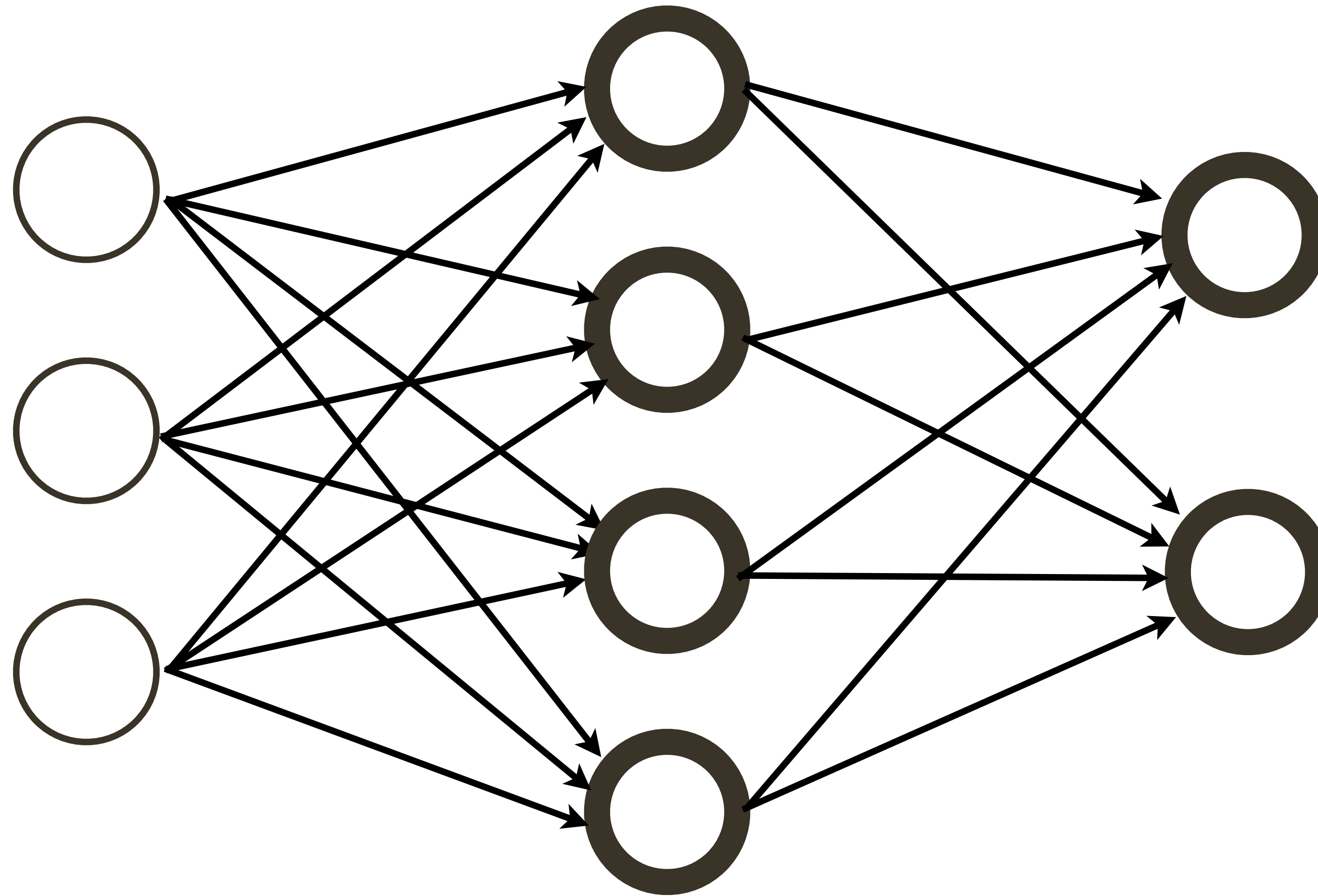
Neural Network

How many neurons?



Neural Network

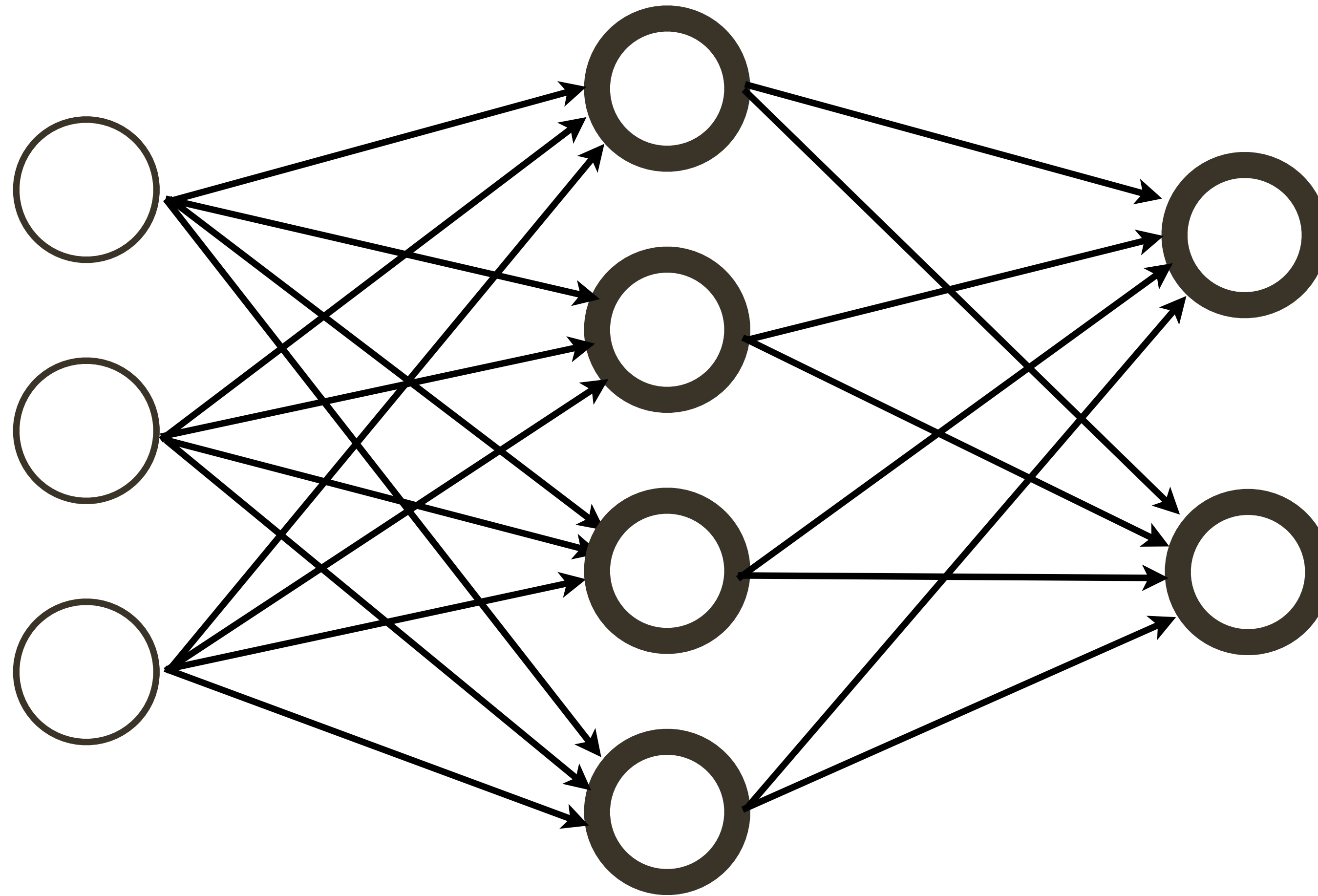
How many neurons? $4+2 = 6$



Neural Network

How many neurons? $4+2 = 6$

How many weights?

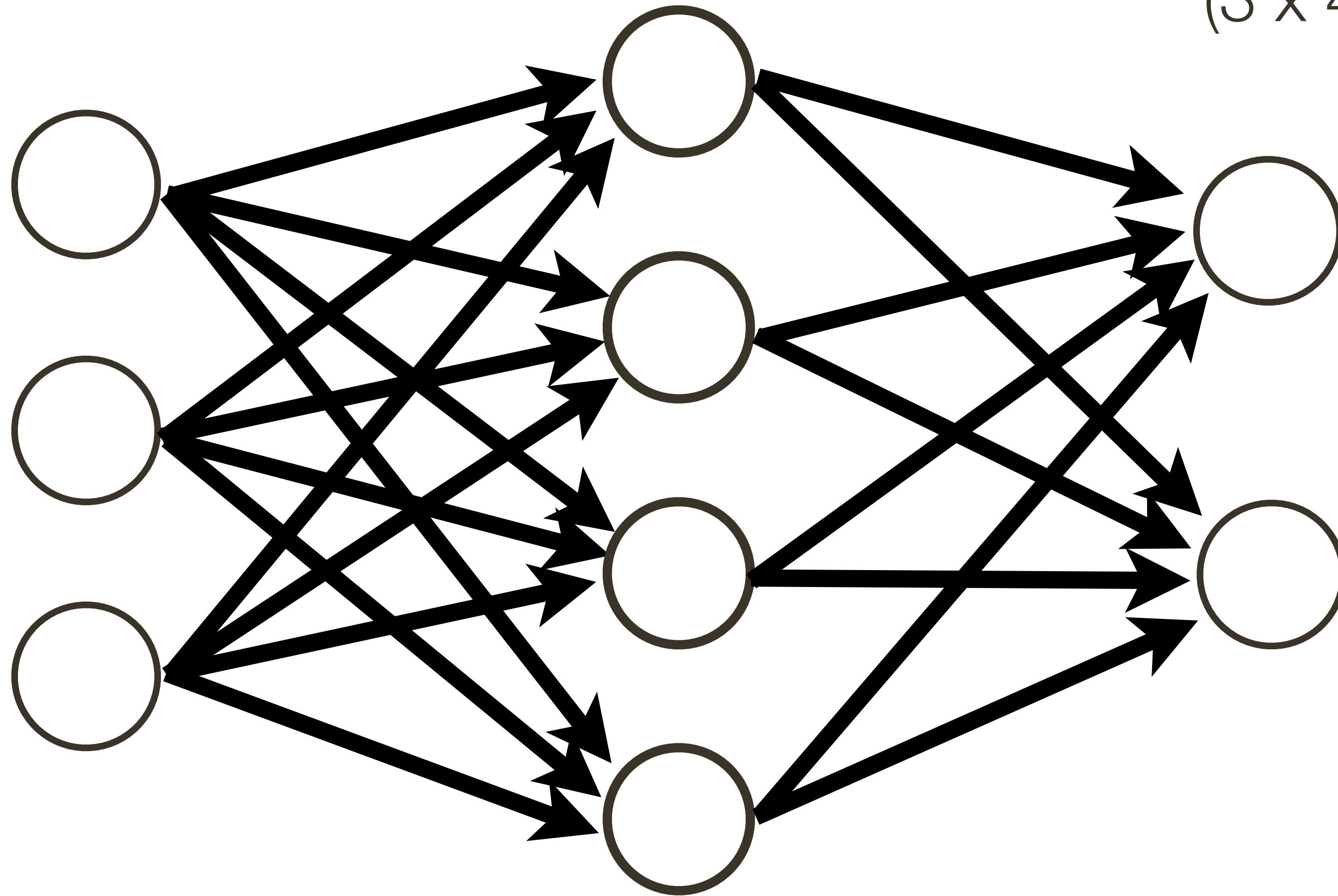


Neural Network

How many neurons? $4+2 = 6$

How many weights?

$$(3 \times 4) + (4 \times 2) = 20$$

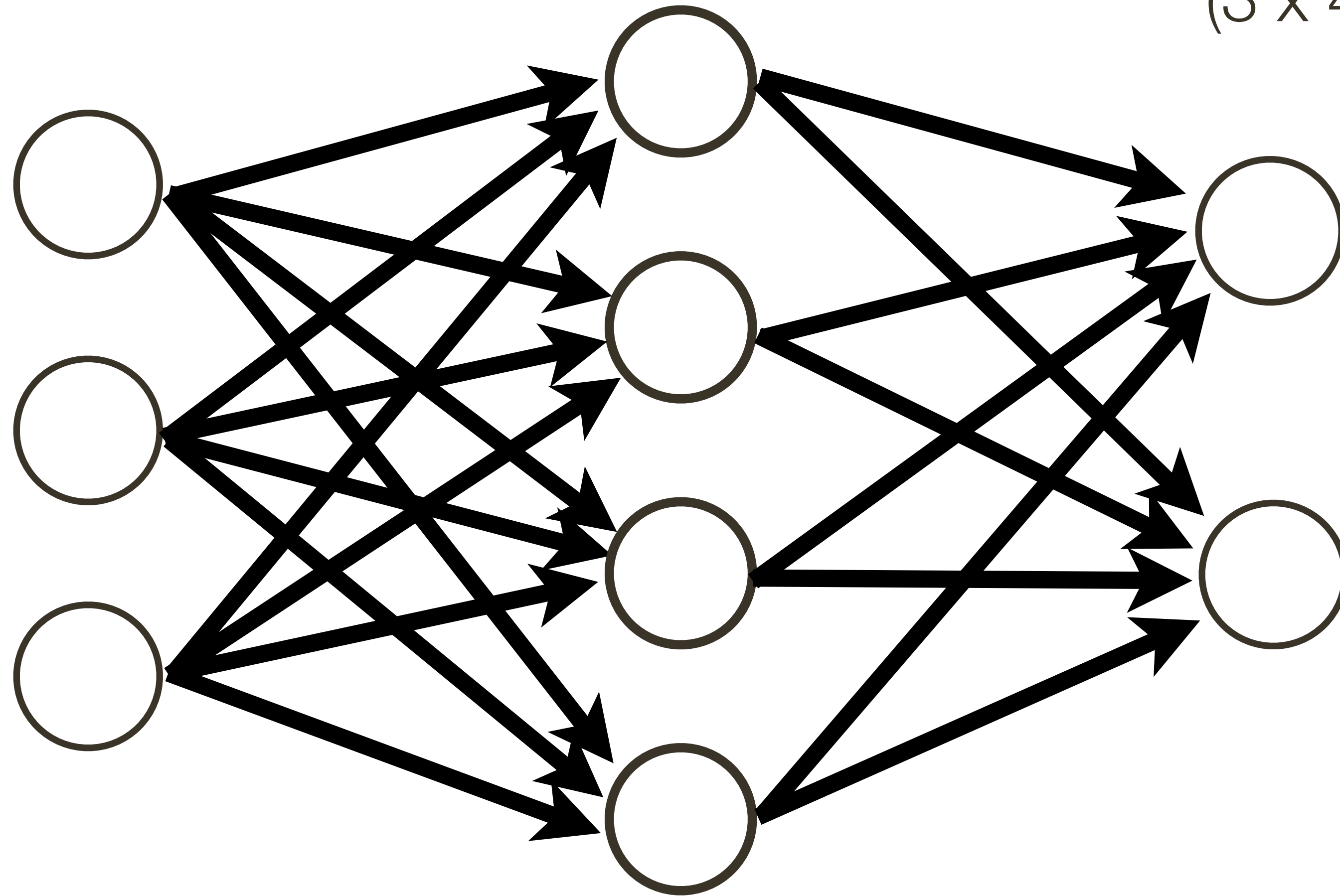


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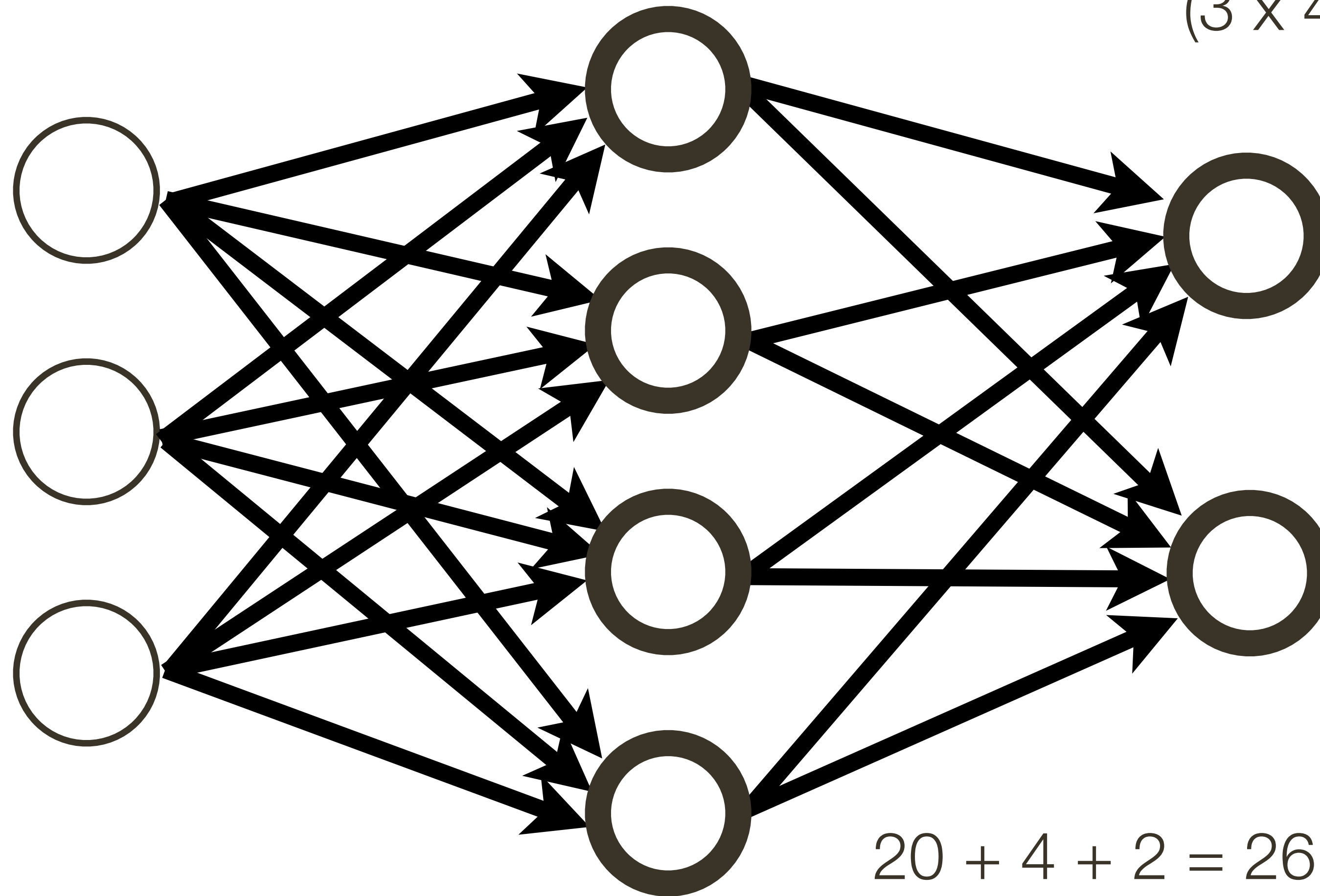
How many learnable parameters?

Neural Network

How many neurons? $4 + 2 = 6$

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How many learnable parameters?

$$20 + 4 + 2 = 26$$

bias terms

Neural Networks

Modern **convolutional neural networks** contain 10-20 layers and on the order of 100 million parameters

Training a neural network requires estimating a large number of parameters

Backpropagation

When training a neural network, the final output will be some loss (error) function

— e.g. cross-entropy loss:
$$L_i = -\log \left(\frac{e^{f_{y_i}}}{\sum_j e^{f_{y_j}}} \right)$$

which defines loss for i -th training example with true class index y_i ; and f_j is the j -th element of the vector of class scores coming from neural net.

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f

$$c_1 = -2.85$$

$$c_2 = 0.86$$

$$c_3 = 0.28$$

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Consider neural net which takes input vector \mathbf{x}_i and predicts scores for 3 classes, with true class being class 3:

$$\begin{array}{ccc} & f & \\ c_1 = -2.85 & \xrightarrow{\text{exp}} & 0.058 \\ c_2 = 0.86 & & 2.36 \\ c_3 = 0.28 & & 1.32 \end{array}$$

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Consider neural net which takes input vector \mathbf{x}_i and predicts scores for 3 classes, with true class being class 3:

c	f			
$c_1 = -2.85$			Normalize to	0.016
$c_2 = 0.86$		0.058	sum to 1	0.631
$c_3 = 0.28$		2.36		0.353
		1.32		

Note: The diagram shows a flow from left to right. The first column contains the class scores c_1, c_2, c_3 . An arrow labeled 'exp' points to the second column, which contains the values 0.058, 2.36, and 1.32. A second arrow labeled 'Normalize to sum to 1' points to the third column, which contains the values 0.016, 0.631, and 0.353.

Backpropagation

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$c_2 = 0.86$		2.36		0.631
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Backpropagation

When training a neural network, the final output will be some loss (error) function

— e.g. cross-entropy loss: $L_i = -\log \left(\frac{e^{f_{y_i}}}{\sum_j e^{f_{y_j}}} \right)$ **softmax** function multi-class classifier

which defines loss for i-th training example with true class index y_i ; and f_j is the j-th element of the vector of class scores coming from neural net.

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$c_2 = 0.86$		2.36		0.631
$c_3 = 0.28$		1.32		0.353

$L_i = -\log(0.353) = 1.04$

Backpropagation

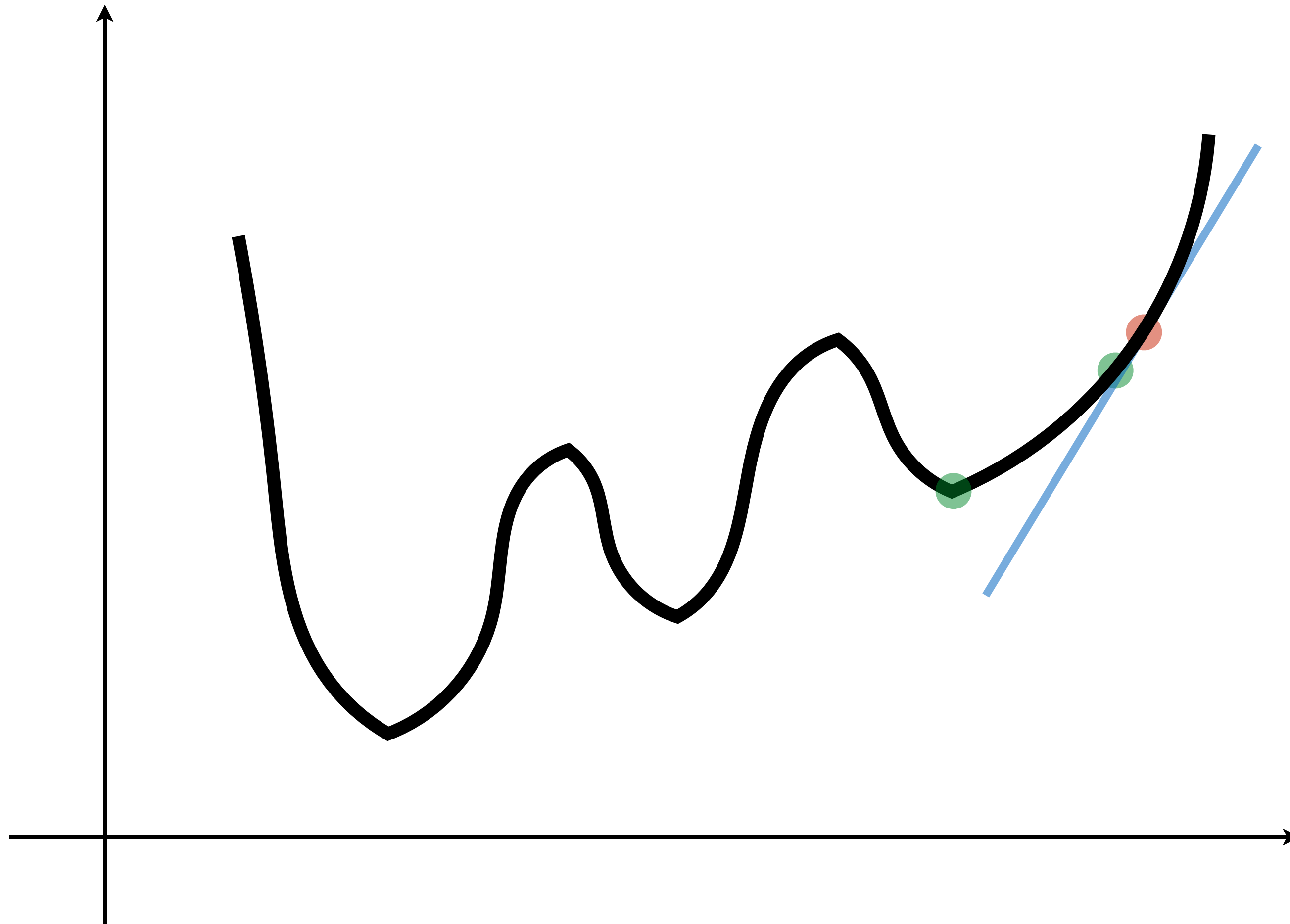
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We want to compute the **gradient** of the loss with respect to the network parameters so that we can incrementally adjust the network parameters

Gradient Descent



λ - is the learning rate

1. Start from random value of $\mathbf{W}_0, \mathbf{b}_0$

For $k = 0$ to max number of iterations

2. Compute gradient of the loss with respect to previous (initial) parameters:

$$\nabla \mathcal{L}(\mathbf{W}, \mathbf{b}) \Big|_{\mathbf{W}=\mathbf{W}_k, \mathbf{b}=\mathbf{b}_k}$$

3. Re-estimate the parameters

$$\mathbf{W}_{k+1} = \mathbf{W}_k - \underline{\lambda} \frac{\partial \mathcal{L}(\mathbf{W}, \mathbf{b})}{\partial \mathbf{W}} \Big|_{\mathbf{W}=\mathbf{W}_k, \mathbf{b}=\mathbf{b}_k}$$

$$\mathbf{b}_{k+1} = \mathbf{b}_k - \underline{\lambda} \frac{\partial \mathcal{L}(\mathbf{W}, \mathbf{b})}{\partial \mathbf{b}} \Big|_{\mathbf{W}=\mathbf{W}_k, \mathbf{b}=\mathbf{b}_k}$$

*slide adopted from V. Ordonex

Backpropagation

The parameters of a neural network are learned using **backpropagation**, which computes gradients via recursive application of the **chain rule** from calculus

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Suppose $f(x, y) = xy$. What is the partial derivative of f with respect to x ? What is the partial derivative of f with respect to y ?

Backpropagation

The parameters of a neural network are learned using **backpropagation**, which computes gradients via recursive application of the **chain rule** from calculus

Suppose $f(x, y) = xy$. What is the partial derivative of f with respect to x ? What is the partial derivative of f with respect to y ?

$$\frac{\partial f}{\partial x} = y$$

$$\frac{\partial f}{\partial y} = x$$

Backpropagation

Suppose $f(x, y) = x + y$. What is the partial derivative of f with respect to x ?
What is the partial derivative of f with respect to y ?

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$$\frac{\partial f}{\partial x} = 1$$

$$\frac{\partial f}{\partial y} = 1$$

Backpropagation

A trickier example: $f(x, y) = \max(x, y)$

Backpropagation

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$$\frac{\partial f}{\partial x} = \mathbf{1}(x \geq y)$$

$$\frac{\partial f}{\partial y} = \mathbf{1}(y \geq x)$$

That is, the (sub)gradient is 1 on the input that is larger, and 0 on the other input

— For example, say $x = 4$, $y = 2$. Increasing y by a tiny amount does not change the value of f (f will still be 4), hence the gradient on y is zero.

Backpropagation

We can compose more complicated functions and compute their gradients by applying the **chain rule** from calculus

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Suppose $f(x, y, z) = (x + y)z$. What are the partial derivatives of f with respect to x ? y ? z ?

Backpropagation

We can compose more complicated functions and compute their gradients by applying the **chain rule** from calculus

Suppose $f(x, y, z) = (x + y)z$. What are the partial derivatives of f with respect to x ? y ? z ?

For illustration we break this expression into $q = x + y$ and $f = qz$. This is a sum and a product, and we have just seen how to compute partial derivatives for these.

Backpropagation

We can compose more complicated functions and compute their gradients by applying the **chain rule** from calculus

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By the chain rule

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x} = z \cdot 1 = z$$

Backpropagation

We can compose more complicated functions and compute their gradients by applying the **chain rule** from calculus

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By the chain rule

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x} = z \cdot 1 = z$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial y} = z \cdot 1 = z$$

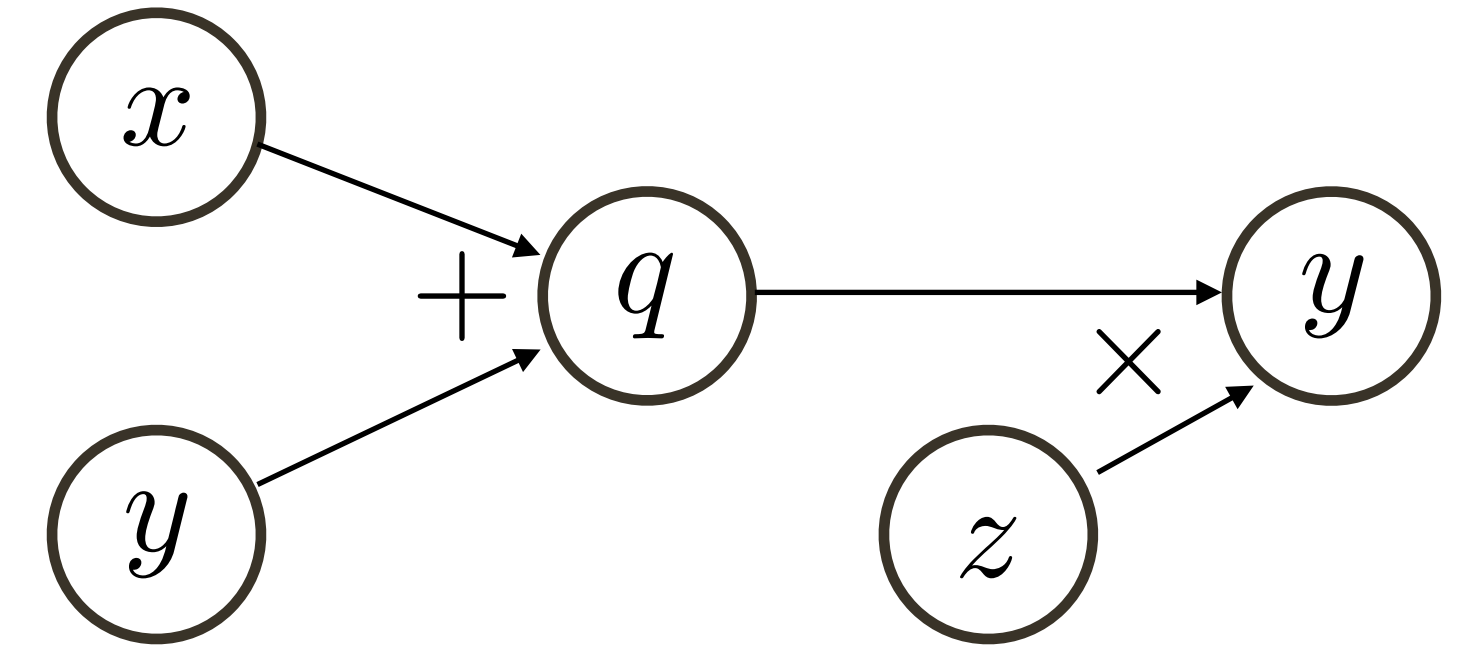
$$\frac{\partial f}{\partial z} = q$$

Backpropagation

$$f(x, y, z) = (x + y)z$$

Backpropagation

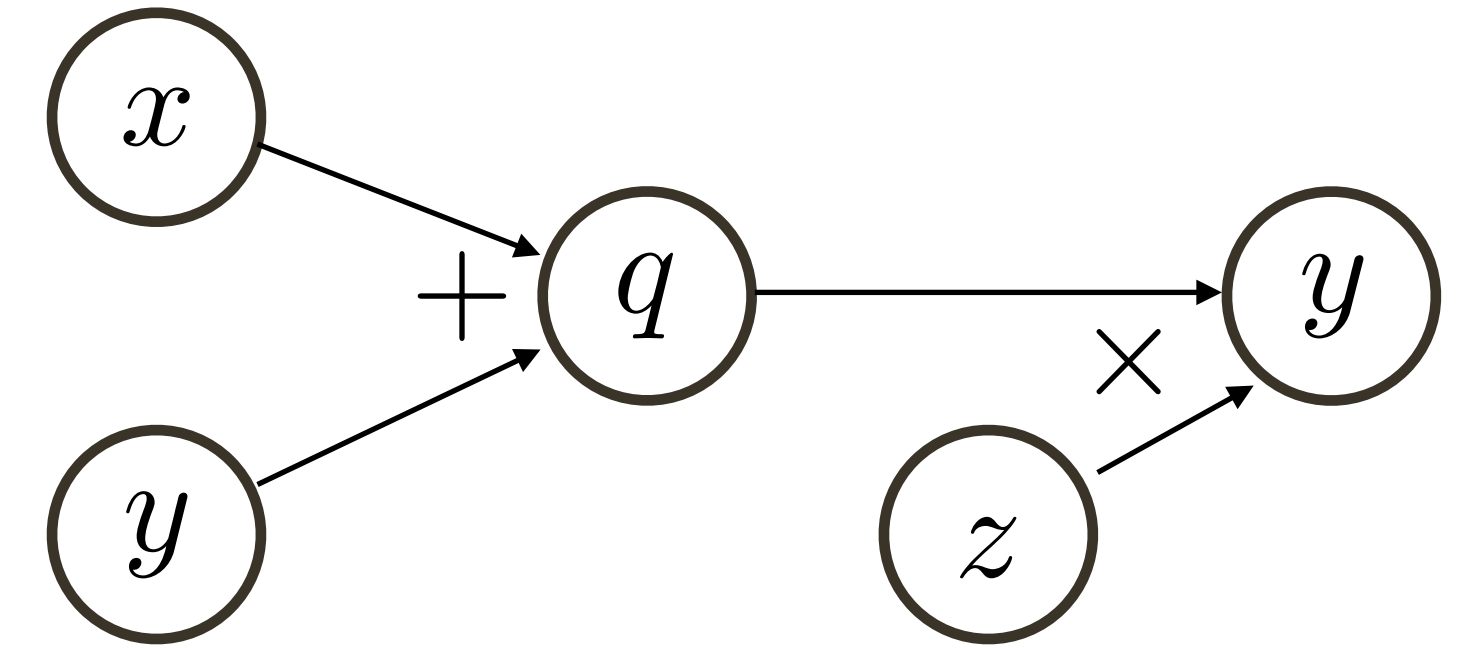
$$f(x, y, z) = (x + y)z$$



Computational graph (a DAG) with variable ordering from topological sort, where each **node** is an input, intermediate, or output variable

Backpropagation

$$f(x, y, z) = (x + y)z$$



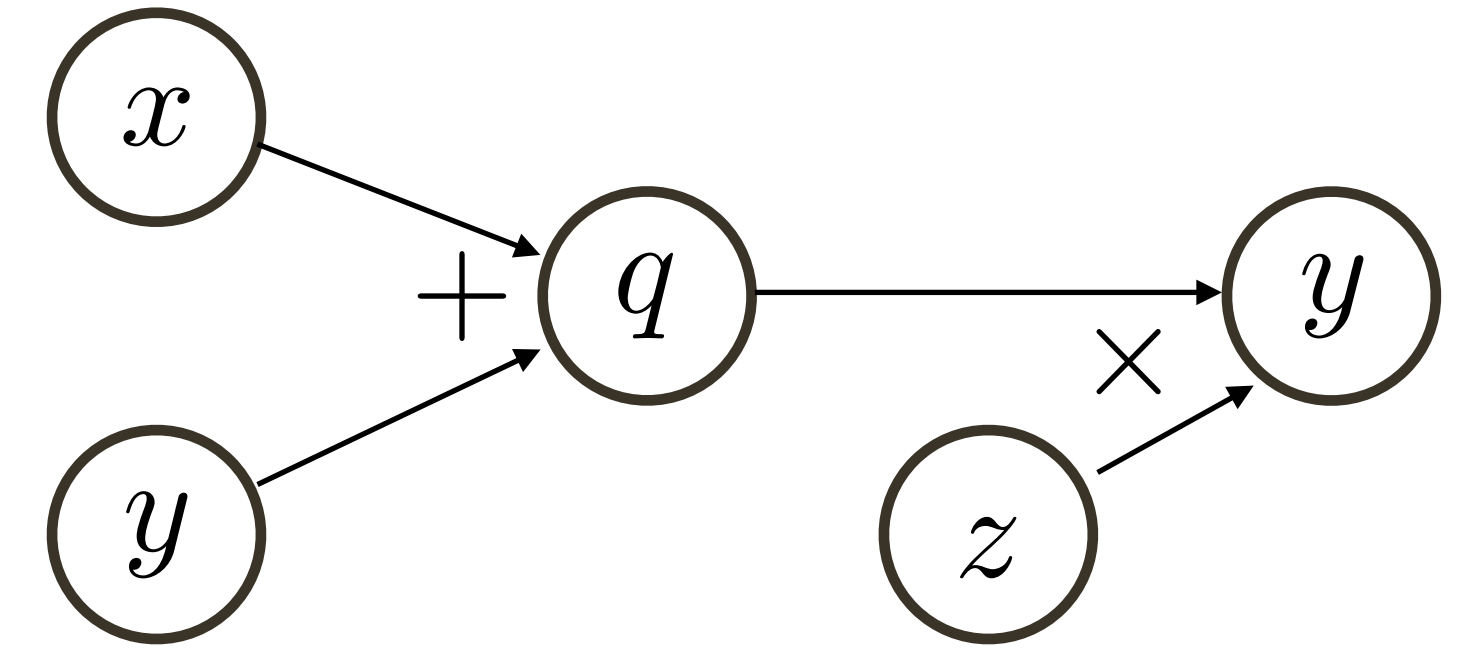
Computational graph (a DAG) with variable ordering from topological sort, where each **node** is an input, intermediate, or output variable

Suppose the network input is: $(x, y, z) = (-2, 5, -4)$

Then: $q = x + y = 3$ $f = qz = -12$ (**forward** pass)

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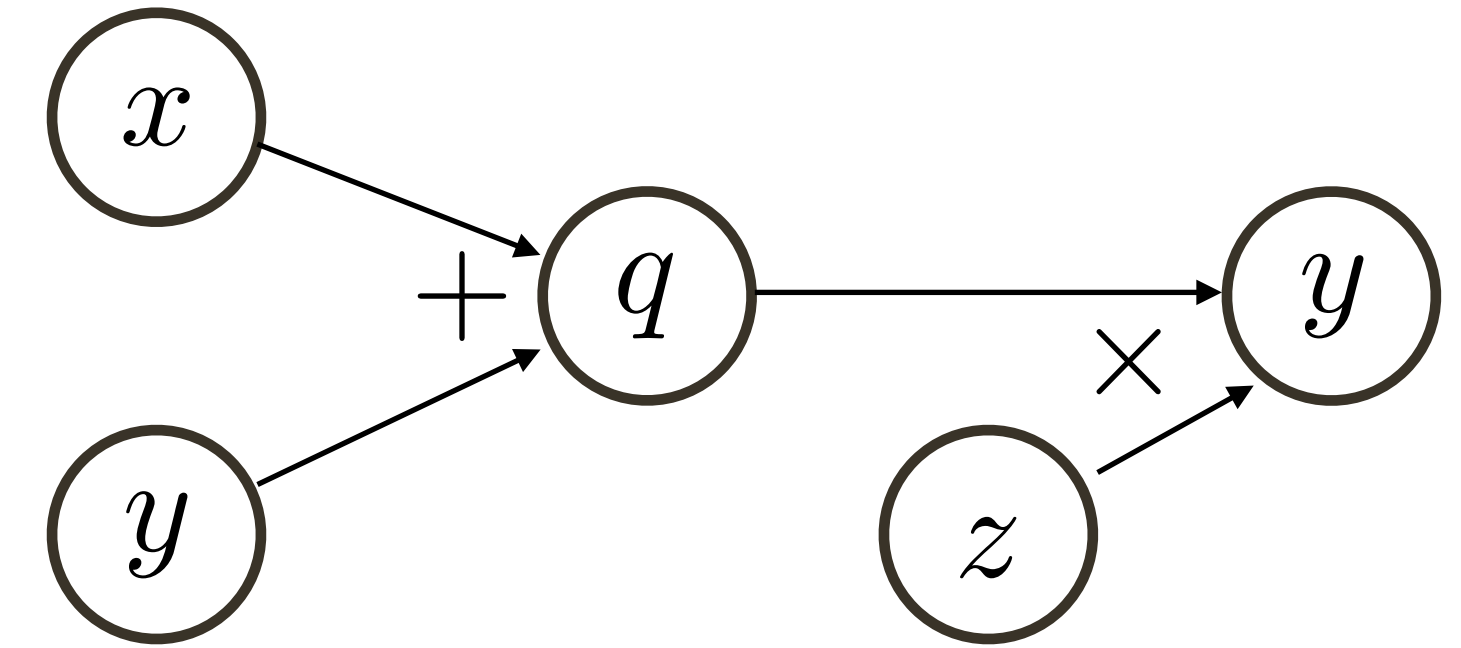
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$$\frac{\partial f}{\partial q} = z = -4$$

(**backward** pass)

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$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x} = \frac{\partial f}{\partial q} \cdot 1$$

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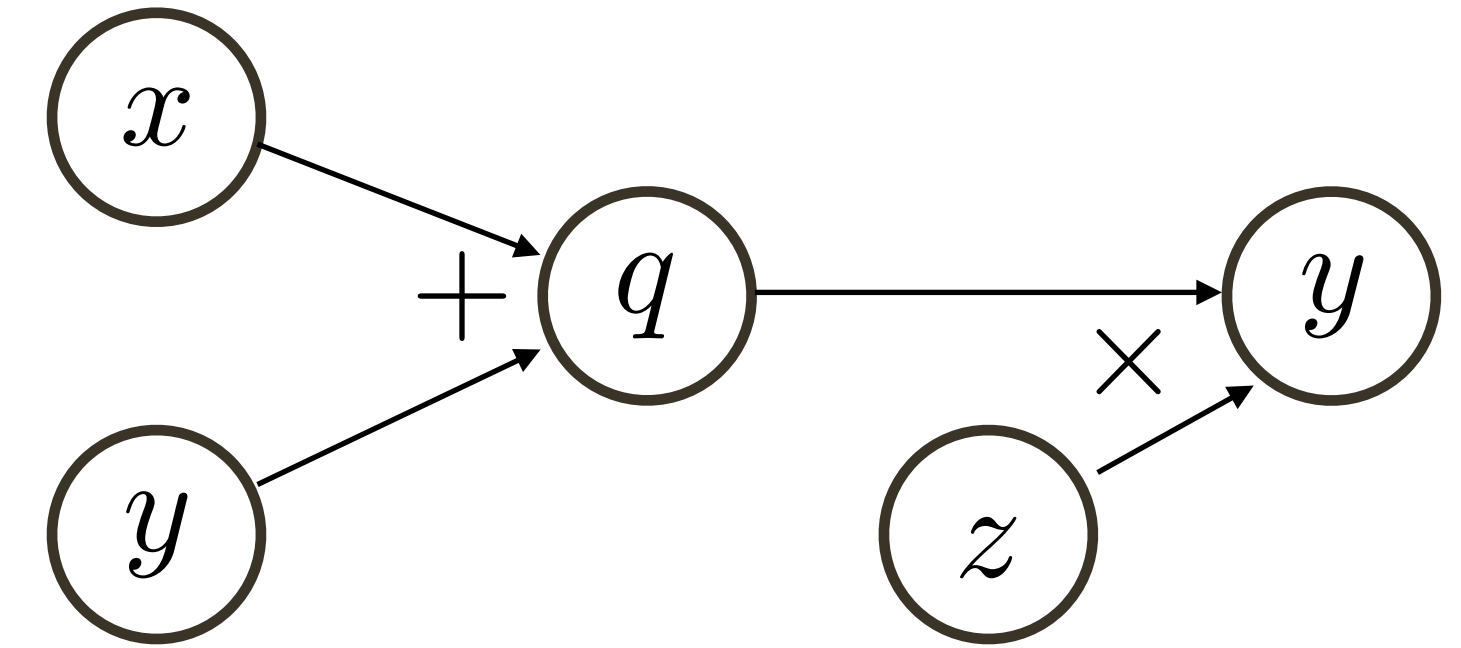
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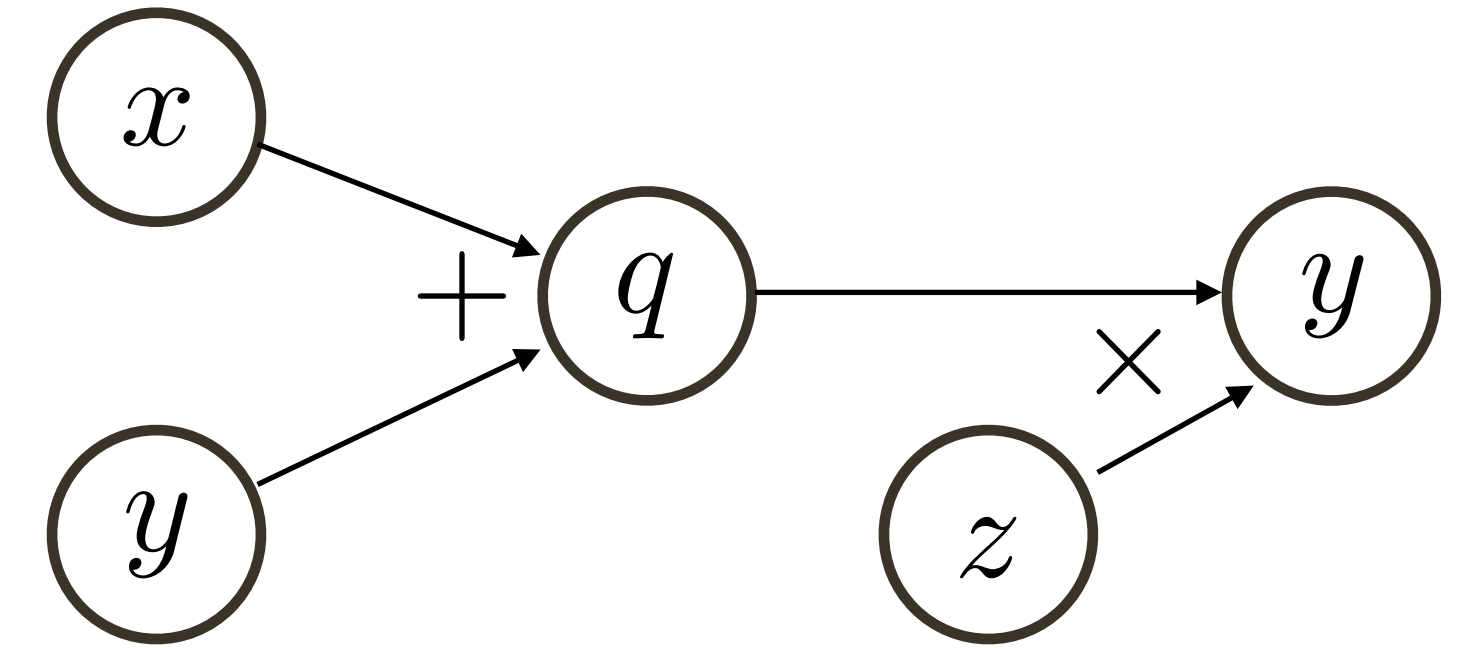
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$$\frac{\partial f}{\partial q} = z = -4$$
$$\frac{\partial f}{\partial x} = -4$$

(**backward** pass)

Backpropagation

$$f(x, y, z) = (x + y)z$$



$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial x} = \frac{\partial f}{\partial q} \cdot 1$$

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial q} \frac{\partial q}{\partial y} = \frac{\partial f}{\partial q} \cdot 1$$

$$\frac{\partial f}{\partial z} = q$$

Suppose the network input is: $(x, y, z) = (-2, 5, -4)$

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$$\frac{\partial f}{\partial q} = z = -4$$

$$\frac{\partial f}{\partial x} = -4$$

$$\frac{\partial f}{\partial y} = -4$$

$$\frac{\partial f}{\partial z} = 3$$

(**backward** pass)