

15.1

$$e = \left| \overset{\text{patch}}{\underline{I}_1(x+\Delta u)} - \overset{\text{patch}}{\underline{I}_0(x)} \right|^2$$

for a small flow Δu

$$\underline{I}_1(x+\Delta u) \approx \underline{I}_1(x) + \frac{\partial \underline{I}^T}{\partial x} \Delta u = \underline{I}_1(x) + \begin{pmatrix} I_{1x} \\ I_{1y} \end{pmatrix} \cdot \begin{pmatrix} \Delta u_x \\ \Delta u_y \end{pmatrix}$$

$$e = \left| \underset{\substack{\uparrow \\ \text{patches}}}{\underline{I}_1(x)} - \underline{I}_0(x) + \frac{\partial \underline{I}^T}{\partial x} \Delta u \right|^2$$

↓
unknown
gradients

least squares.

of form $|\underline{J}\Delta u - r|^2 \rightarrow \underline{\Delta u} = \underline{(\underline{J}^T \underline{J})^{-1} \underline{J}^T r}$

15.2

let $e = 0$ for a single pixel

$$\underline{I}_t(x) - \underline{I}_{t+\Delta t}(x) = \frac{\partial \underline{I}^T}{\partial x} \Delta x$$

$\div \Delta t$

$$-\frac{\partial \underline{I}}{\partial t} = \frac{\partial \underline{I}^T}{\partial x} \frac{\Delta x}{\Delta t} \leftarrow \text{velocity}$$

temporal difference

$$\underline{I}_t + \frac{\partial \underline{I}^T}{\partial x} \frac{\partial x}{\partial t} = 0$$

$$\underline{I}_t + \begin{pmatrix} I_x \\ I_y \end{pmatrix} \cdot \begin{pmatrix} v_x \\ v_y \end{pmatrix} = 0$$

$$\underline{I}_t + I_x v_x + I_y v_y = 0$$

optical flow constraint eqn (single patch)

15.3

$$I_t + \begin{pmatrix} I_x \\ I_y \end{pmatrix} \cdot \begin{pmatrix} v_x \\ v_y \end{pmatrix} = 0$$

$$I_t + \nabla I \cdot \underline{v} = 0$$

Optical flow in 1D

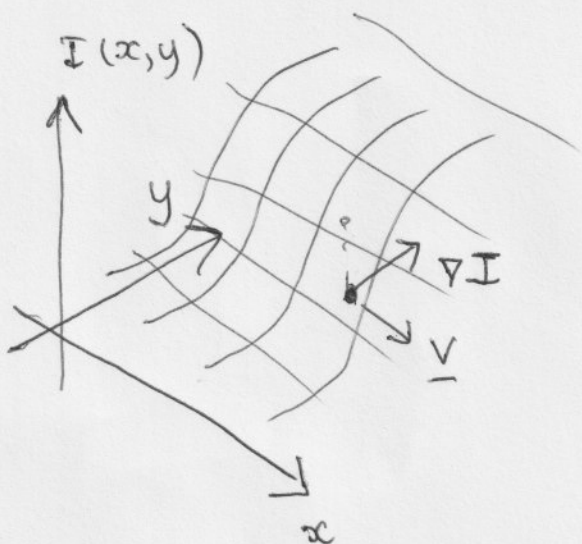


$$I(x, t + \Delta t) = I(x, t) - \Delta x \frac{\partial I}{\partial x}$$

Δt

$$\frac{\partial I}{\partial t} = -v \frac{\partial I}{\partial x}$$

Optical flow in 2D



If \underline{v} is $\uparrow\uparrow$ to ∇I

$$I_t = -v |\nabla I|$$

If \underline{v} is perpendicular to ∇I ?

$$I_t = 0$$

