

Local Search

CPSC 322 Lecture 12

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Textbook §3.8

Lecture Overview

- 1 Recap
- 2 Local Search
- 3 Hill Climbing

Arc Consistency

Definition

An arc $\langle X, r(X, \bar{Y}) \rangle$ is **arc consistent** if for each value of X in \mathbf{D}_X there is some value \bar{Y} in $\mathbf{D}_{\bar{Y}}$ such that $r(X, \bar{Y})$ is satisfied.

- In symbols, $\forall X \in \mathbf{D}_X, \exists \bar{Y} \in \mathbf{D}_{\bar{Y}}$ such that $r(X, \bar{Y})$ is satisfied.
- A network is arc consistent if all its arcs are arc consistent.
- If an arc $\langle X, \bar{Y} \rangle$ is *not* arc consistent, all values of X in \mathbf{D}_X for which there is no corresponding value in $\mathbf{D}_{\bar{Y}}$ **may be deleted** from \mathbf{D}_X to make the arc $\langle X, \bar{Y} \rangle$ consistent.
 - This removal **can never rule out any models**

Arc Consistency Algorithm

- Consider the arcs in turn making each arc consistent.
 - An arc $\langle X, r(X, \bar{Y}) \rangle$ needs to be revisited if the domain of X is reduced.
- Regardless of the order in which arcs are considered, we will terminate with the same result: an arc consistent network.

Revisiting Edges

- When we change the domain of a variable X in the course of making an arc $\langle X, r \rangle$ arc consistent, we add every arc $\langle Z, r' \rangle$ where r' involves X and:
 - $r \neq r'$
 - $Z \neq X$
- Thus we don't add back the same arc:
 - This makes sense—it's definitely arc consistent.

Revisiting Edges

- When we change the domain of a variable X in the course of making an arc $\langle X, r \rangle$ arc consistent, we add every arc $\langle Z, r' \rangle$ where r' involves X and:
 - $r \neq r'$
 - $Z \neq X$
- We don't add back other arcs involving the **same variable** X
 - We've just *reduced* the domain of X
 - If an arc $\langle X, r \rangle$ was arc consistent before, it will still be arc consistent
 - in the "for all" we'll just check fewer values

Revisiting Edges

- When we change the domain of a variable X in the course of making an arc $\langle X, r \rangle$ arc consistent, we add every arc $\langle Z, r' \rangle$ where r' involves X and:
 - $r \neq r'$
 - $Z \neq X$
- We don't add back other arcs involving the **same constraint** and a **different variable**:
 - Imagine that such an arc—involving variable Y —had been arc consistent before, but was no longer arc consistent after X 's domain was reduced.
 - This means that some value in Y 's domain could satisfy r only when X took one of the dropped values
 - But we dropped these values precisely because there were no values of Y that allowed r to be satisfied when X takes these values—contradiction!

Arc Consistency Outcomes

- Three possible outcomes (when all arcs are arc consistent):
 - One domain is empty \Rightarrow no solution
 - Each domain has a single value \Rightarrow unique solution
 - Some domains have more than one value \Rightarrow may or may not be a solution
 - in this case, arc consistency isn't enough to solve the problem: we need to perform search

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Local Search

- Many search spaces are too big for systematic search.
- A useful method in practice for some consistency and optimization problems is **local search**
 - **idea**: consider the space of complete assignments of values to variables
 - **neighbours** of a current node are similar variable assignments
 - move from one node to another according to a function that scores how good each assignment is

Local Search

Definition

A local search problem consists of a:

- **Set of Variables.** A node in the search space will be a complete assignment to all of the variables.
- **Neighbour relation.** An edge in the search space will exist when the neighbour relation holds between a pair of nodes.
- **Scoring function.** This can be used to incorporate information about how many constraints are violated. It can also incorporate information about the cost of the solution in an optimization context.

Selecting Neighbours

How do we choose the **neighbour relation**?

- Usually this is simple: some small incremental change to the variable assignment
 - assignments that differ in one variable's value
 - assignments that differ in one variable's value, by a value difference of one
 - assignments that differ in two variables' values, etc.
- There's a **trade-off**: bigger neighbourhoods allow more nodes to be compared before a step is taken
 - the best step is more likely to be taken
 - each step takes more time: in the same amount of time, multiple steps in a smaller neighbourhood could have been taken
- Usually we prefer pretty small neighbourhoods

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Hill Climbing

Hill climbing means selecting the neighbour which best improves the scoring function.

- For example, if the goal is to find the highest point on a surface, the scoring function might be the height at the current point.

Gradient Ascent

What can we do if the variable(s) are **continuous**?

- With a constant step size we could overshoot the maximum.
- Here we can use the scoring function h to determine the neighbourhood dynamically:
 - **Gradient ascent**: change each variable proportional to the gradient of the heuristic function in that direction.
 - The value of variable X_i goes from v_i to $v_i + \eta \frac{\partial h}{\partial X_i}$.
 - η is the constant of proportionality that determines how big steps will be
 - **Gradient descent**: go downhill; v_i becomes $v_i - \eta \frac{\partial h}{\partial X_i}$.
 - these partial derivatives may be estimated using finite differences

Problems with Hill Climbing

Foothills local maxima that are not global maxima

Plateaus heuristic values are uninformative

Ridge foothill where a larger neighbour relation would help

Ignorance of the peak no way of detecting a global maximum

