

# **Marginal Independence and Conditional Independence**

**CPSC 322 Lecture 25**

# Lecture Overview

- **Recap with Example and Bayes' Rule**
- Marginal Independence
- Conditional Independence

# Recap Joint Distribution

- 3 binary random variables:  **$P(H, S, F)$** 
  - **H**  $\text{dom}(H) = \{h, \neg h\}$  has heart disease, does not have...
  - **S**  $\text{dom}(S) = \{s, \neg s\}$  smokes, does not smoke
  - **F**  $\text{dom}(F) = \{f, \neg f\}$  high fat diet, low fat diet

# Recap Joint Distribution (JPD)

• 3 binary random variables:  $\mathbf{P(H,S,F)}$

- **H**  $\text{dom}(\mathbf{H})=\{\mathbf{h}, \neg\mathbf{h}\}$  has heart disease, does not have...
- **S**  $\text{dom}(\mathbf{S})=\{\mathbf{s}, \neg\mathbf{s}\}$  smokes, does not smoke
- **F**  $\text{dom}(\mathbf{F})=\{\mathbf{f}, \neg\mathbf{f}\}$  high fat diet, low fat diet

		<b>f</b>		$\neg$ <b>f</b>	
		<b>s</b>	$\neg$ <b>s</b>	<b>s</b>	$\neg$ <b>s</b>
<b>h</b>	<b>h</b>	.015	.007	.005	.003
	$\neg$ <b>h</b>	.21	.51	.07	.18



# Recap Conditional Probability

P(H,S)	s	$\neg s$	P(H)
h	.02	.01	.03
$\neg h$	.28	.69	.97
P(S)	.30	.70	

$$P(S | H) = \frac{P(S, H)}{P(H)}$$

P(S|H)

h	.666	.333
$\neg h$	.29	.71

multiple  
probability  
distributions

do P(H|S) as  
an exercise

# Recap Conditional Probability (cont.)

$$P(S | H) = \frac{P(S, H)}{P(H)}$$

## Two key points

- We derived this equality from a “possible world” semantics of probability
- It is not a probability distribution but a **set of probability distributions**
  - One for each configuration of the conditioning variable(s)


# Recap Chain Rule

$$P(H, S, F) =$$

## Bayes Theorem

$$P(S | H) = \frac{P(S, H)}{P(H)}$$

$$P(H | S) = \frac{P(S, H)}{P(S)}$$


$$P(S | H) = \frac{P(H | S)P(S)}{P(H)}$$



# Learning Goals for today's class

- **You can:**
- Define and use **Marginal Independence**
- Define and use **Conditional Independence**

# Lecture Overview

- Recap with Example and Bayes Theorem
- **Marginal Independence**
- Conditional Independence

# Do you always need to revise your beliefs?

**NO**, not when your knowledge of **Y**'s value doesn't affect your belief in the value of **X**

**DEF.** A random variable **X** is **marginally independent** of random variable **Y** if, for all  $x_i \in \text{dom}(X)$  and all  $y_k \in \text{dom}(Y)$ ,

$$P(X = x_i \mid Y = y_k) = P(X = x_i)$$

# Marginal Independence: Example

- $X$  and  $Y$  are independent iff:

$$\mathbf{P}(X/Y) = \mathbf{P}(X) \quad \text{or} \quad \mathbf{P}(Y/X) = \mathbf{P}(Y) \quad \text{or} \quad \mathbf{P}(X, Y) = \mathbf{P}(X) \mathbf{P}(Y)$$

- That is, new evidence  $Y$  (or  $X$ ) does not affect current belief in  $X$  (or  $Y$ )
- Ex:  $\mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}, \textit{Weather})$   
 $= \mathbf{P}(\textit{Toothache}, \textit{Catch}, \textit{Cavity}) \mathbf{P}(\textit{Weather})$
- JPD requiring \_\_\_\_ entries is reduced to two smaller ones  
( \_\_\_\_ and \_\_\_\_ )

# In our example are Smoking and Heart Disease marginally Independent ?



## What are our probabilities telling us....?

X and Y are independent iff:

$$P(X|Y) = P(X) \quad \text{or} \quad P(Y|X) = P(Y) \quad \text{or} \quad P(X, Y) = P(X) P(Y)$$

P(S,H)	s	¬ s	P(H)
h	.02	.01	.03
¬ h	.28	.69	.97
P(S)	.30	.70	

P(S H)	s	¬ s
h	.666	.334
¬ h	.29	.71

- A. Yes    B. No    C. It depends    D. 42    E. Please make it stop

# Lecture Overview

- Recap with Example
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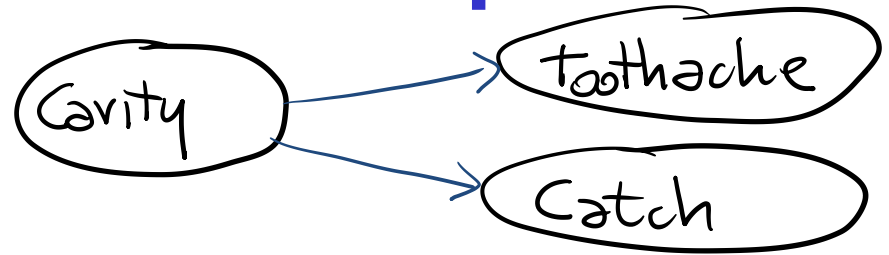
# Conditional Independence

- With marginal independence, for  $n$  independent random vars,  $O(d^n) \rightarrow O(n*d)$  space complexity

$$P(x_1, \dots, x_n) = P(x_1) * \dots * P(x_n)$$

- Absolute independence is powerful **but** when you model a **particular domain**, it is **rare**
- Dentistry is a large field with hundreds of variables, few of which are independent (e.g., *Cavity*, *Heart-disease*).
- What to do?

# Look for weaker form of independence



- $P(\text{Toothache}, \text{Cavity}, \text{Catch})$
- Are *Toothache* and *Catch* marginally independent?  
 $P(\text{Toothache} \mid \text{Catch}) = P(\text{Toothache})$  ? **NO**
- BUT **If I have a cavity**, does the probability that the probe catches depend on whether I have a toothache? **NO**  
(1)  $P(\text{catch} \mid \text{toothache}, \text{cavity}) = P(\text{catch} \mid \text{cavity})$
- What if I haven't got a cavity?  
(2)  $P(\text{catch} \mid \text{toothache}, \neg \text{cavity}) = P(\text{catch} \mid \neg \text{cavity})$

*Each is directly caused by the cavity, but neither has a direct effect on the other*



# Conditional independence

- In general, *Catch* is **conditionally independent** of *Toothache* given *Cavity*:

①  $\mathbf{P}(\textit{Catch} \mid \textit{Toothache}, \textit{Cavity}) = \mathbf{P}(\textit{Catch} \mid \textit{Cavity})$

- Equivalent statements:

②  $\mathbf{P}(\textit{Toothache} \mid \textit{Catch}, \textit{Cavity}) = \mathbf{P}(\textit{Toothache} \mid \textit{Cavity})$

③  $\mathbf{P}(\textit{Toothache}, \textit{Catch} \mid \textit{Cavity}) =$   
 $\mathbf{P}(\textit{Toothache} \mid \textit{Cavity}) \mathbf{P}(\textit{Catch} \mid \textit{Cavity})$

# Proof of equivalent statements

①  
if  $P(X|Y,z) = P(X|z) \Rightarrow$

$\Rightarrow$  (A)  $\frac{P(X,Y,z)}{P(Y,z)} = \frac{P(X,z)}{P(z)} \Rightarrow$  (2)

$\Rightarrow \frac{P(X,Y,z)}{P(X,z)} = \frac{P(Y,z)}{P(z)} \Rightarrow P(Y|X,z) = P(Y|z)$

③  $P(X,Y|z) = \frac{P(X,Y,z)}{P(z)} \xrightarrow{\text{from A}} \frac{P(Y,z) P(X,z)}{P(z)} \cdot \frac{1}{P(z)}$   
 $= \frac{P(Y,z)}{P(z)} \cdot \frac{P(X,z)}{P(z)} = P(Y|z) \cdot P(X|z)$

# Conditional Independence: Formal Def.

Sometimes, two variables might not be marginally independent. However, they *become* independent after we observe some third variable

**DEF.** Random variable **X** is **conditionally independent** of random variable **Y** given random variable **Z** if, for all  $x_i \in \text{dom}(X)$ ,  $y_k \in \text{dom}(Y)$ ,  $z_m \in \text{dom}(Z)$

$$P(X = x_i \mid Y = y_k, Z = z_m) = P(X = x_i \mid Z = z_m)$$

That is, knowledge of **Y**'s value doesn't affect your belief in the value of **X**, given a value of **Z**

# Side note: storing distributions

Joint Probability Distribution (JPD): has  $O(d^n)$  values

- but they have to **sum to 1**, so do we need to store all of them?
- how many do we need to store?

Conditional Probability Table (CPT): has  $O(d^n)$  values

- but **each row** has to sum to 1, so do we need to store all of them?
- how many do we need to store?

# Conditional independence: Use

- Write out full joint distribution using chain rule:

$$\mathbf{P}(\textit{Cavity}, \textit{Catch}, \textit{Toothache})$$

$$= \mathbf{P}(\textit{Toothache} \mid \textit{Catch}, \textit{Cavity}) \mathbf{P}(\textit{Catch} \mid \textit{Cavity}) \mathbf{P}(\textit{Cavity})$$

$$= \mathbf{P}(\textit{Toothache} \mid \textit{Cavity}) \mathbf{P}(\textit{Catch} \mid \textit{Cavity}) \mathbf{P}(\textit{Cavity})$$

how many probabilities?

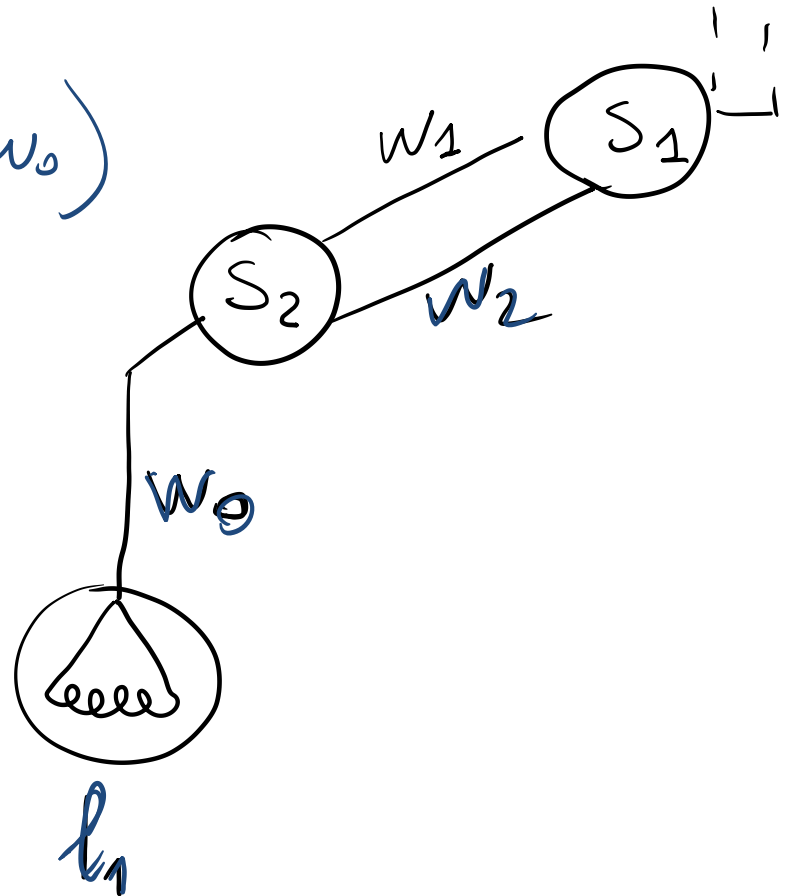
- The use of conditional independence often reduces the size of the representation of the joint distribution from exponential in  $n$  to linear in  $n$ , where  $n$  is the # of variables
- **Conditional independence** is our **most basic** and **robust** form of **knowledge** about **uncertain environments**.

# Conditional Independence Example 2

- Given whether there is/isn't power in wire  $w_0$ , is whether light  $l_1$  is lit or not, independent of the position of switch  $s_2$ ?

$$P(l_1 | s_2, w_0) \stackrel{?}{=} P(l_1 | w_0)$$

yes!



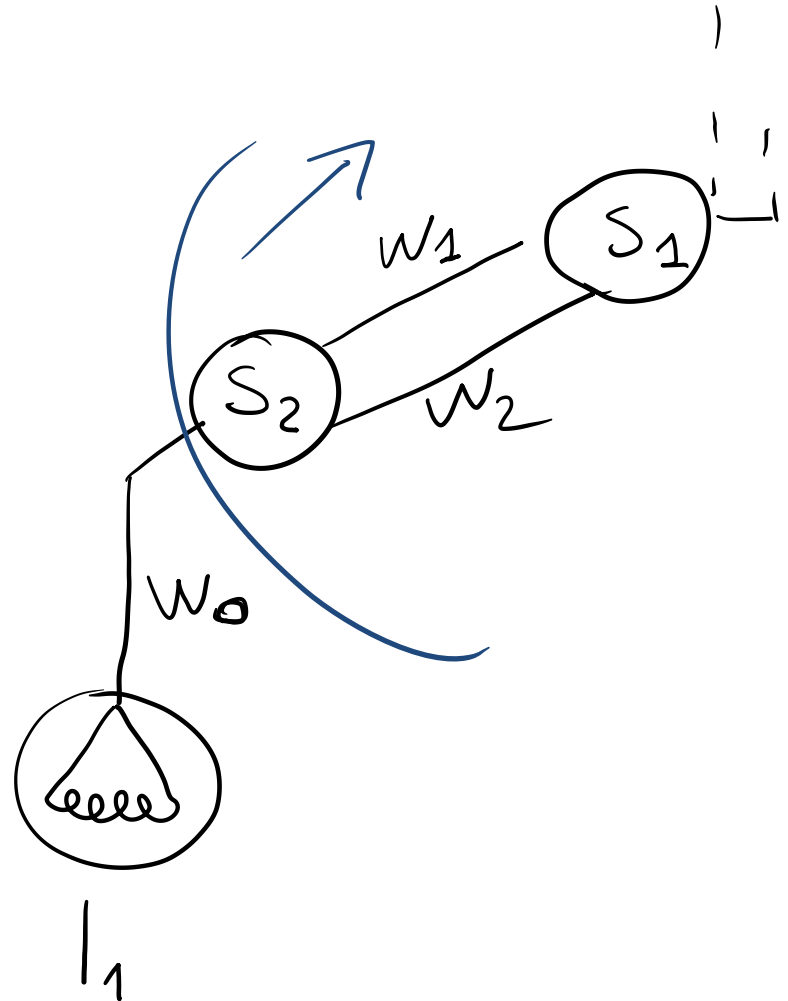
# Conditional Independence Example 3

- Is every other variable in the system independent of whether light **l1** is lit, given whether there is power in wire **w0**?

$$P(s_1 | l_1, w_0) = P(s_1 | w_0)$$

$w_1$   
 $w_2$   
⋮

yes!



# Where are we? (Summary)

- Probability is a rigorous formalism for uncertain knowledge
- **Joint probability distribution** specifies probability of every **possible world**
- Queries can be answered by summing over possible worlds
- For nontrivial domains, we must find a way to reduce the joint distribution size
- **Independence** (*rare*) and **conditional independence** (*frequent*) provide the tools



# Next Class

- Bayesian Networks (Textbook 8.3)