

## CPSC 421/501 Note Sheet for Final Exam, Fall 2014

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A set,  $S$ , is *countable* if we can write

$$S = \{s_1, s_2, \dots\},$$

and otherwise *uncountable*, i.e., meaning that any sequence of its elements does not contain all of the set.

The power set of a set,  $S$ , denoted  $\mathcal{P}ower(S)$  or  $2^S$  is the set of all subsets of  $S$ . We know that there is no function  $f: S \rightarrow \mathcal{P}ower(S)$  whose image is all of  $\mathcal{P}ower(S)$ .

The set of all strings over a countable set is countable. The set of subsets of a countably infinite set is uncountable. In many contexts, the set of “programs” or “algorithms” is countable, while the set of languages is uncountable; in this case, there are many languages which cannot be “recognized” or “solved” by a program or algorithm.

Axiom 1: There exists a Result function, from  $\mathcal{P} \times \mathcal{I}$  to  $\{\text{yes}, \text{no}, \text{NoHalt}\}$ . Axiom 2: There exists a universal program. Axiom 3: One can modify the **yes** and **no** results of a program. Axiom 4: One can modify a program so that inputs of the form  $\langle p \rangle$  on the modified program run the original program on the input  $\langle p, \langle p \rangle \rangle$ . Axiom 5: One can combine two programs and wait for one of them to say **yes**.

A program,  $p \in \mathcal{P}$  recognizes the language

$$L = L_p = \{i \in \mathcal{I} \mid P[i] = \text{yes}\}.$$

A program is a *decider* if on any input its result is either **yes** or **no**. A language is *recognizable* if it is recognized by some program, and *decidable* if it is recognized by a some program that is a decider.

If a language is recognizable but not decidable, then its complement is unrecognizable (i.e., not recognized by any element of  $\mathcal{P}$ ).

“421Simple” is an example of a simple programming language that produces algorithms in a similar way to Turing machines. It has the keywords:

INPUT, WORKTAPE, OUTPUT, RESET, AUG, DEC, LET, EOF, =, IF, THEN, GOTO, END, COMMENT.

A Turing machine is a tuple:

$$(Q, \Sigma, \Gamma, \delta, q_0, q_{\text{accept}}, q_{\text{reject}})$$

and an understood “blank” symbol that is in  $\Gamma$  but not in  $\Sigma$ ;  $Q$  is the set of states,  $\Sigma$  is the input alphabet,  $\Gamma$  is the worktape alphabet,

$$\delta: Q \times \Gamma \rightarrow Q \times \Gamma \times \{\text{L}, \text{R}\}.$$

Savitch’s Theorem:  $\text{NSPACE}(f(n)) \subset \text{SPACE}((f(n))^2)$  provided that  $f(n)$  is computable in  $\text{SPACE}((f(n))^2)$ . Hence  $\text{NSPACE}$  equals  $\text{PSPACE}$ .

Our half of the Baker-Gill-Soloway Theorem:  $P^A = NP^A$  where  $A$  is any language complete for PSPACE.

There are “easy” examples of NP-complete and PSPACE-complete languages:

$$L_{NP \text{ easy}} = \{ \langle M, i, 1^t \rangle \mid M \text{ is a non-det TM that accepts } i \text{ in time } t \}$$

(the term  $1^t$  is the string of 1's of length  $t$ , i.e.,  $t$  written out in unary); and

$$L_{PSPACE \text{ easy}} = \{ \langle M, i, 1^s \rangle \mid M \text{ is a TM that accepts } i \text{ in space } s \}.$$

UTM's (universal Turing machines) are used to prove the Time Hierarchy Theorem. If you simulate  $s$  steps of a Turing machine by a UTM in time  $O(s^2)$ , then you can conclude that  $\text{TIME}(n^a)$  is a proper subset of  $\text{TIME}(n^b)$  for  $b > 2a$ . If you simulate  $s$  steps of a Turing machine by a UTM in time  $O(s \log s)$ , then you can conclude that  $\text{TIME}(n^a)$  is a proper subset of  $\text{TIME}(n^b)$  for  $b > a$ .

A DFA is a tuple  $(Q, \Sigma, \delta, q_0, F)$  where  $Q$  and  $\Sigma$  are finite sets,  $\delta: Q \times \Sigma \rightarrow Q$ ,  $q_0 \in Q$ , and  $F \subset Q$  ( $F$  is the set of final or accepting states).

Myhill-Nerode Theorem: For a language  $L \subset \Sigma^*$  and  $w \in \Sigma^*$ , we define

$$\text{Future}(L, w) = \{u \in \Sigma^* \mid wu \in L\}.$$

Then the number of different futures of a language is the minimum number of states in a DFA recognizing  $L$ .