

Last time:

Ridge Regression:

$$A \in \mathbb{R}^{m \times n}, \vec{b} \in \mathbb{R}^m$$

$$\vec{u} \in \mathbb{R}^n, \text{ var } \vec{v} \in \mathbb{R}^n$$

$$\min_{\vec{u}} \left[ \underbrace{\|A\vec{u} - \vec{b}\|^2}_{f_1(\vec{u})} + \underbrace{C \|\vec{u}\|^2}_{f_2(\vec{u})} \right]$$

$f_1(\vec{u})$   
model

$f_2(\vec{u})$   
controls  
too many  
parameters

If  $n \geq 4$   
then



tend to fit  
to noise

Saw:

$$f_1(\vec{u} + \varepsilon \vec{v}) = f_1(\vec{u}) + \varepsilon \underbrace{\text{Term}_{1,f_1}} + O(\varepsilon^2)$$

$$2 \vec{v} \cdot A^T (A\vec{u} - \vec{b})$$

Hence:

$f_2(\vec{u} + \varepsilon \vec{v})$  similarly, with

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$$f_2(\vec{u} + \epsilon \vec{v}) = f_2(\vec{u}) + \epsilon \text{Term}_{1, f_2} + O(\epsilon^2)$$

$$\text{Term}_{1, f_2} = 2\vec{v} \cdot \vec{I}^T (\vec{I}\vec{u} - \vec{b})$$

(same as  $f_1$ ,  $A \rightarrow \vec{I}$ ,  $b \rightarrow \vec{b}$ )

Rem:

$$\min C_1 \|A_1 \vec{u} - \vec{b}_1\|^2 + C_2 \|A_2 \vec{u} - \vec{b}_2\|^2 + \dots$$
$$+ C_k \|A_k \vec{u} - \vec{b}_k\|^2$$

get similar

$$2\vec{v} \cdot \sum_{i=1}^k C_i A_i^T (A_i \vec{u} - \vec{b}_i)$$

Today: (1) Examine Ridge Regression

(2)  $\lambda$ 's of Symmetric Matrices

Admin:

I'll write a guide to what to

do from Exercises D, E, maybe F.

Now: I'm adding to  $\Delta$  for future uses.

E = current unit

F = anything else (infinite kernels,

Gaussian, etc.

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Ridge Regression:

$$f_1(u) = \|A\vec{u} - \vec{b}\|^2$$

$$f_2(u) = \|\vec{I} \vec{u} - \vec{0}\|^2 = \|\vec{u}\|^2$$

$$\min: \underbrace{f_1 + C f_2}_g \quad 0 \leq C < \infty$$

$$g(\vec{u} + \epsilon \vec{v}) = g(\vec{u}) +$$

$$\epsilon (2\vec{v}) \cdot A^T(A\vec{u} - \vec{b}) + \epsilon (2\vec{v}) \cdot (I^T(I\vec{u} - \vec{0})) + O(\epsilon^2)$$

$$\downarrow \epsilon (2\vec{v}) \cdot (A^T(A\vec{u} - \vec{b}) + C\vec{u})$$

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If  $g(\vec{u})$  has a min at  $\vec{u}^*$ ,

then

$$\forall \vec{v} \in \mathbb{R}^n$$

$$(2\vec{v}) \cdot \left( \begin{array}{c} \text{1st} \\ \text{variation} \\ \text{stuff} \end{array} \right) = 0$$

$$\Rightarrow \underbrace{\hspace{10em}}_{\text{must be } \vec{0}}$$

$$\Rightarrow (A^T(A\vec{u} - \vec{b}) + C\vec{u}) \stackrel{\text{must be } \vec{0}}{=} \vec{0}$$

$$A^T A \vec{u} + C \vec{u} = A^T \vec{b}$$

$\Rightarrow$

$$(A^T A + C I) \vec{w} = A^T \vec{b}$$

$$\vec{w} = (A^T A + C I)^{-1} A^T \vec{b}$$

$$C \approx 0$$

“normal equations”

$$A^T A \vec{w} = A^T \vec{b}$$

or if  $A^T A$  is “well-conditioned”

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If columns A are features, and

if

$$A = \begin{pmatrix} 5m & 500cm \\ 2m & 200cm \\ 30m & 3000cm \\ -1m & -100cm \end{pmatrix}$$

$\uparrow \qquad \uparrow$

then these 2 columns are  
linearly dependent features,



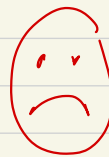
If same but with noise

$$A = \begin{bmatrix} 5m & 500cm + \epsilon_1 \\ 2m & 200cm + \epsilon_2 \\ 30m & 3000cm + \epsilon_3 \\ -1m & -100cm + \epsilon_4 \\ & \vdots \end{bmatrix}$$

$\uparrow$   
 $\epsilon_i = \text{noise}$

Fitting to

$$\begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \end{bmatrix}$$



(exercise  
?)



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Key!

$$\vec{u} = (A^T A + C \mathbf{I})^{-1} A^T \vec{b}$$

maybe  $C$  big enough s.t.

$$A^T A + C \mathbf{I} = C \left( \frac{A^T A}{C} + \mathbf{I} \right)$$

is invertible, so inverse is

$$\frac{1}{C} \left( \mathbf{I} + \frac{A^T A}{C} \right)^{-1}$$

$$= \frac{1}{C} \left( \mathbf{I} - \left( \frac{A^T A}{C} \right) + \left( \frac{A^T A}{C} \right)^2 - \dots \right)$$

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PageRank damping factor is  
analogous ...

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$A$  symmetric,  $A \in \mathbb{R}^{n \times n}$ ,

looking at

$$R_A(\vec{u}) = \frac{(A\vec{u}) \cdot (\vec{u})}{\vec{u} \cdot \vec{u}}$$

want to minimize, maximize

Basic idea: we believe that  
eigenvalues of  $A$  all real,

$$\lambda_n(A) \leq \dots \leq \lambda_2(A) \leq \lambda_1(A).$$

Find  $\lambda_1(A)$  largest:

$$\max_{\vec{u} \neq \vec{0}} R_A(\vec{u}) = \lambda_1(A)$$

and wherever max occurs, say

$\vec{u}^*$ , we'll have

$$A \vec{u}^* = \lambda_1 \vec{u}^*.$$

We said, now simplifying,

say  $\vec{u}^*$  is maximum

$$\vec{u}^* \rightsquigarrow \frac{\vec{u}^*}{\|\vec{u}^*\|_{L^2}} = \text{unit vector.}$$

So!

$$\max \left\{ (A\vec{u}) \cdot \vec{u} \mid \begin{array}{l} \|\vec{u}\|_{L^2} = 1 \\ \vec{u} \cdot \vec{u} = 1 \end{array} \right\}$$

maximum is attained at

$$\vec{u}^*.$$

Rem: If  $\vec{v} \perp \vec{u}^*$ , then  $\|\vec{u}^* + \epsilon \vec{v}\| \leq 1$

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 Class Ends  $\|m\| < 1$

$$(I - M)^{-1}$$

$$= I + M + M^2 + M^3 + \dots$$

$$\|m\| = \alpha$$

$$I + M + M^2 + \dots + M^k$$

$$+ \underbrace{(M^{k+1} + \dots)}_{\text{bounded by } \alpha^{k+1} \cdot \frac{1}{1-\alpha}}$$

$$\| \vec{u}^* + \varepsilon \vec{v} \|^2 \quad \left( \begin{array}{c} \uparrow \\ \downarrow \end{array} \right)$$

$$(\vec{u}^* + \varepsilon \vec{v}) \cdot (\vec{u}^* + \varepsilon \vec{v})$$

$$= \vec{u}^* \cdot \vec{u}^* + 2\varepsilon \underbrace{\vec{u}^* \cdot \vec{v}}_{\text{if } \vec{u}^* \cdot \vec{v} = 0} + \varepsilon^2 \vec{v} \cdot \vec{v}$$

$$= 1 + 2\varepsilon \cdot 0 + \varepsilon^2 C$$

$$\frac{1}{1 + \varepsilon^2 C} = 1 - \varepsilon^2 C + O(\varepsilon^4)$$