

March 16, 2021 CPSC 531 F

- Today:

## Variational Methods:

① Rayleigh quotients to diagonalize

self-adjoint operators

② SVD (singular-value decomposition)

③ Calculus of variations and other  
variational methods

Not part of course, "oo-dimensional"  
vector spaces

Our context?

-  $\mathbb{R}^n$ ,  $(\vec{u}, \vec{v}) = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$

- More generally

this {  $(\vec{u}, \vec{v})_{\vec{w}} = u_1 v_1 w_1 + \dots + u_n v_n w_n$   
is mostly enough }  $\vec{w}$ -weighted dot product

More generally yet,

enough  $\rightarrow$  any inner product  $(,)$  on  $\mathbb{R}^n$

- More generally yet

any inner product  $(,)$  or

finite dim

vector space

- All this works in inner products  $\langle , \rangle$

over  $\mathbb{C}$ .

$\equiv$

Weighted inner product:

$$L : \mathbb{R}^3 \longrightarrow \mathbb{R}^3$$

$$\vec{v} \longmapsto A\vec{v}, \quad A \in M_3(\mathbb{R})$$

If  $\mathbb{R}^3$  = usual space in which we live,

$$\vec{v} = \begin{bmatrix} 3 \text{ cm} \\ 4 \text{ cm} \\ 2 \text{ cm} \end{bmatrix}, \quad \vec{v} = \begin{bmatrix} 3 \text{ ft} \\ 4 \text{ ft} \\ 5 \text{ ft} \end{bmatrix}$$

but imagine

$$\vec{v} = \begin{bmatrix} 3 \text{ cm} \\ 2 \text{ km} \\ 5 \text{ ft} \end{bmatrix} \dots \quad \text{:(}$$

for us, weighted inner products

come from  $( , )_{\pi} \quad \left. \right\} \pi \text{ is stationary dist}$   
 $( , )_{1/\pi} \quad \left. \right\} \text{of MC}$

=

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 6 \\ 3 & 6 & 9 \end{bmatrix},$$

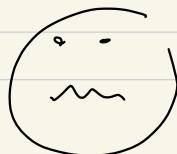
$$\mathcal{L} \begin{bmatrix} 3 \text{ cm} \\ 2 \text{ km} \\ 5 \text{ ft} \end{bmatrix} = \begin{bmatrix} ? \text{ cm} \\ ? \text{ light years} \\ ? \mu\text{m} \end{bmatrix}$$



$$A = \begin{pmatrix} 1 \text{ cm/cm} & 2 \text{ cm/cm} \\ - & - \end{pmatrix} \quad \dots$$

$$= \begin{pmatrix} 2 \text{ cm/cm} \end{pmatrix}$$

$$2 \frac{\text{cm}}{\text{cm}} = \frac{0.2}{1000} \frac{\text{cm}}{\text{km}}$$



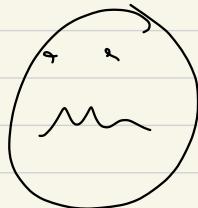
$$L \begin{pmatrix} 3 \text{ cm} \\ 2 \text{ km} \\ 5 \text{ ft} \end{pmatrix} = \begin{pmatrix} ? \text{ cm} \\ ? \text{ km} \\ ? \text{ ft} \end{pmatrix}$$



$$\begin{bmatrix} d_1 & \frac{\mu\text{m}}{\text{cm}} & 0 \\ 0 & d_2 & \frac{\mu\text{m}}{\text{km}} \\ 0 & 0 & d_3 & \frac{\mu\text{m}}{\text{ft}} \end{bmatrix} \begin{bmatrix} 3 \text{ cm} \\ 2 \text{ km} \\ 5 \text{ ft} \end{bmatrix}$$

then A

then ( ) invert



Simples : Inner Product !

$$\left( \begin{bmatrix} 3 \text{ cm} \\ 2 \text{ km} \\ 5 \text{ ft} \end{bmatrix}, \begin{bmatrix} -2 \text{ cm} \\ 4 \text{ km} \\ 19 \text{ ft} \end{bmatrix} \right)$$

= gives everything in same  
fixed units

→ weighted dot product

$$\begin{bmatrix} x_1 & \text{m} \\ x_2 & \text{km} \end{bmatrix} \cdot \begin{bmatrix} y_1 & \text{m} \\ y_2 & \text{km} \end{bmatrix} = \left( \underset{\uparrow}{x_1 y_1} + \underset{\rightarrow}{x_2 y_2} \cdot 10^6 \right) \text{m}$$

weights

⑥  $L : \mathbb{R}^n \rightarrow \mathbb{R}^n$ ,  $(\cdot, \cdot)$   
 inner product

Assume  $L$  is self-adjoint:

$$\forall \vec{x}, \vec{y} \in \mathbb{R}^n \quad (L\vec{x}, \vec{y}) = (\vec{x}, L\vec{y})$$

(intuition comes from special case:  
 $(\vec{x}, \vec{y}) = \vec{x} \cdot \vec{y}$ ,  $L(\vec{v}) \mapsto A\vec{v}$ )  
 with  $A = A^T$  symmetric

Thm: Assuming the above,  $L$  has  
 an orthonormal basis of eigenvectors

$\vec{v}_1, \dots, \vec{v}_n$ ,  $L(\vec{v}_i) = \lambda_i \vec{v}_i$ , and  
 $\lambda_i \in \mathbb{R}$ .

Proof!

$$R_L(\vec{v}) = \frac{(\vec{L}\vec{v}, \vec{v})}{(\vec{v}, \vec{v})}$$

- defined for  $\vec{v} \neq \vec{0}$

-  $R_L(\vec{v}) = R_L(\alpha\vec{v})$  for any

$\vec{v} \neq \vec{0}$  and  $\alpha \neq 0$ .

---

Claim:  $R_L(\vec{v})$  has its maximum

value somewhere. Idea: suffices to consider

$$S^1 = \left\{ \vec{v} \mid \|\vec{v}\|_2 = \sqrt{v_1^2 + \dots + v_n^2} = 1 \right\}$$

(the unit sphere). Then using (Math 320)

sequential compactness to prove this.

$\geq$  100-150 years ago, did this

without proof

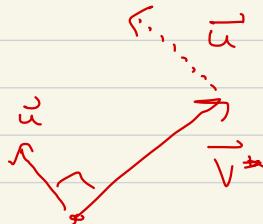
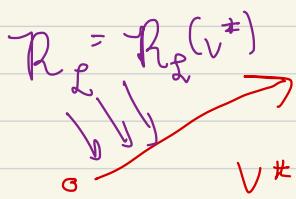
Assume this: we have  $\vec{v}^*$  s.t,

$$\max_{\vec{v} \neq 0} R_L(\vec{v}) = R_L(\vec{v}^*).$$

Claim!  $\vec{v}^*$  is an eigenvector

of  $L$ :  $L(\vec{v}^*) = \lambda \vec{v}^*$ .

—



Take any  $\vec{u} \perp \vec{v}^*$

}

perpendicular

$$(\vec{u}, \vec{v}^*) = 0$$

Look at

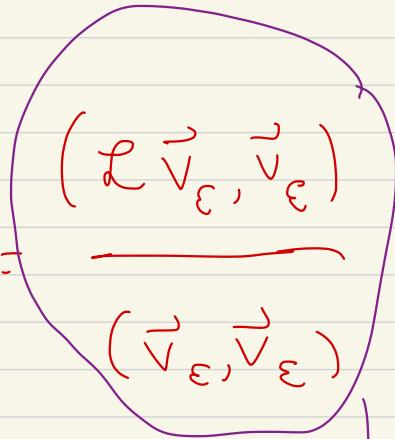
$$\vec{v}_\epsilon = \underbrace{\vec{v}^*}_{\text{—}} + \epsilon \underbrace{\vec{u}}_{\text{—}} \quad \left. \right\} \text{"variation"}$$

think of  $\epsilon$  near 0 :

$$R_L(\vec{v}^*) \geq R_L(\vec{v}_\epsilon) \quad \begin{matrix} \text{for} \\ \text{all} \\ \epsilon \end{matrix}$$

We consider :

$$g(\varepsilon) = \mathcal{R}_{\mathcal{L}}(\vec{v}_\varepsilon) = \frac{(\mathcal{L}\vec{v}_\varepsilon, \vec{v}_\varepsilon)}{(\vec{v}_\varepsilon, \vec{v}_\varepsilon)}$$



$$g(\varepsilon) \leq g(0) = \mathcal{R}_{\mathcal{L}}(\vec{v}^*) \text{ for all } \varepsilon.$$

hence

$$g'(0) = 0$$

now

$$\frac{d}{d\varepsilon} g(\varepsilon) = \frac{d}{d\varepsilon} \circlearrowleft$$

$$= \frac{(\vec{v}_\varepsilon, \vec{v}_\varepsilon) \left( \frac{d}{d\varepsilon} (\mathcal{L}\vec{v}_\varepsilon, \vec{v}_\varepsilon) \right) - \text{other way}}{(\vec{v}_\varepsilon, \vec{v}_\varepsilon)^2}$$

$$(\vec{V}_\epsilon, \vec{V}_\epsilon) =$$

$$(\vec{V}^* + \epsilon \vec{u}, \vec{V}^* + \epsilon \vec{u}) =$$

$$(\vec{V}^*, \vec{V}^*) + 2\epsilon (\vec{V}^*, \vec{u}) + \epsilon^2 (\vec{u}, \vec{u})$$

}

○

$$= \underbrace{(\vec{V}^*, \vec{V}^*)}_{\text{non-zero}} + \text{order } \epsilon^2 \text{ term}$$

$$\overbrace{(\vec{V}_\epsilon, \vec{V}_\epsilon)}^{\text{l}} = \overbrace{(\vec{V}^*, \vec{V}^*) + \text{order}(\epsilon^2)}^{\text{l}} + \underbrace{\gamma_0 + \gamma_1 \epsilon^2}_{\text{higher order terms}}$$

$$= \frac{1}{(\vec{V}^*, \vec{V}^*)} + \text{order } (\varepsilon^2)$$

really

$$\frac{1}{Y_0 + Y_1 \varepsilon^2} = \frac{1}{Y_0} \underbrace{\frac{1}{1 + (Y_1 \varepsilon^2 / Y_0)}}$$

$$= \frac{1}{Y_0} \left( 1 - \frac{Y_1}{Y_0} \varepsilon^2 + \left( \frac{Y_1}{Y_0} \varepsilon^2 \right)^2 \right)$$

$\varepsilon$  small,

bounded by  $(\varepsilon^2)$

$$(L \vec{V}_\varepsilon, \vec{V}_\varepsilon) =$$

$$(L(\vec{V}^* + \varepsilon \vec{u}), \vec{V}^* + \varepsilon \vec{u})$$

$$= (\mathcal{L} \vec{V}^*, \vec{V}^*) + 2\varepsilon (\mathcal{L} \vec{V}^*, \vec{U}^*)$$

$$+ O(\varepsilon^2)$$

something bounded  
by  $\text{Const} \cdot \varepsilon^2$

$\Rightarrow$

$$R_{\mathcal{L}}(\vec{V}_\varepsilon) = \frac{(\mathcal{L} \vec{V}_\varepsilon, \vec{V}_\varepsilon)}{(\vec{V}_\varepsilon, \vec{V}_\varepsilon)}$$

$$= \frac{1}{(\vec{V}_\varepsilon, \vec{V}_\varepsilon)} (\mathcal{L}(\vec{V}_\varepsilon), \vec{V}_\varepsilon)$$

$$= \left( \frac{1}{(\vec{v}^*, \vec{v}^*)} + O(\varepsilon^2) \right)$$

$$\left( (\mathcal{L} \vec{v}^*, \vec{v}^*) + 2\varepsilon (\mathcal{L} \vec{v}^*, \vec{u}^*) \right. \\ \left. + O(\varepsilon^2) \right)$$

$$= \frac{(\mathcal{L}(\vec{v}^*), \vec{v}^*)}{(\vec{v}^*, \vec{v}^*)} + 2\varepsilon \frac{(\mathcal{L} \vec{v}^*, \vec{u}^*)}{(\vec{v}^*, \vec{v}^*)} \\ + O(\varepsilon^2)$$

In terms of

$$g(\varepsilon) = \mathcal{R}_{\mathcal{L}}(\vec{v}_\varepsilon), \quad g'(0)$$

$$= \frac{2 (\mathcal{L}(\vec{v}^*), \vec{u})}{\text{Something positive}}$$

Hence, for any  $\vec{u} \perp \vec{v}^*$

$(\langle \vec{u}, \vec{v}^* \rangle = 0)$  we have

$$L(\vec{v}^*) \perp \vec{u}$$

$$(L(\vec{v}^*), \vec{u}) = 0.$$

Hence

$L(\vec{v}^*)$  is proportional to

$$\vec{v}^*$$

$$L(\vec{v}^*) = \text{Const. } \vec{v}^* = \lambda \vec{v}^*$$

Why? --

Next steps:

We can use the same idea to

- (1) get an entire orthonormal  
eigenbasis for  $L$

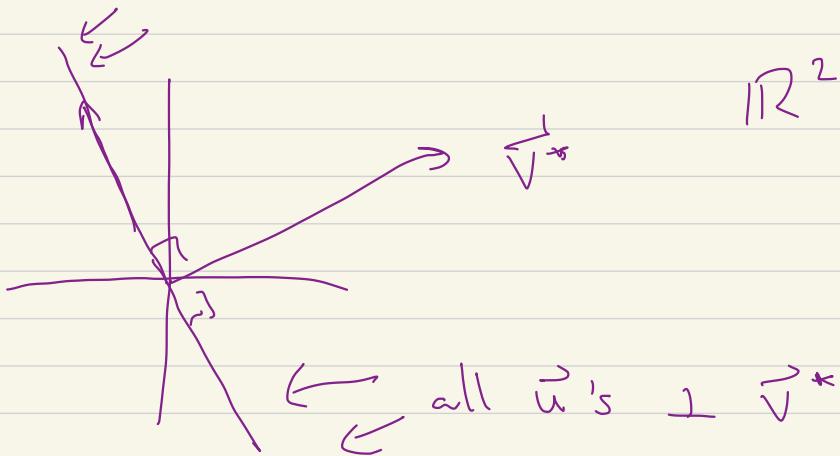
- (2) Same set of ideas

give SVD.

4 minute break

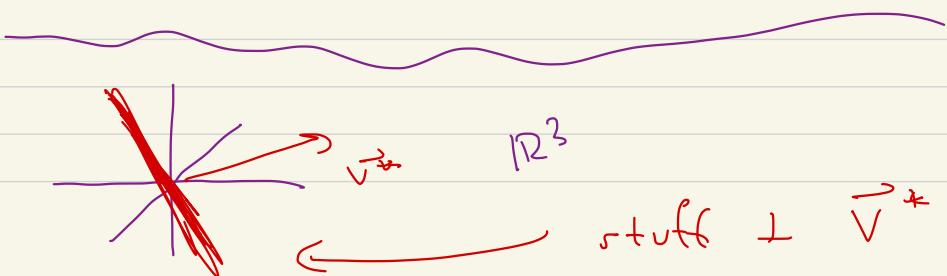
Exercise --

Intuition for dot products



if  $\vec{\omega} \perp (\text{all } \vec{u}'s \perp \text{to } \vec{v}^*)$

$$\Rightarrow \vec{\omega} = c \cdot \vec{v}^*$$



Everything with  $\cdot$  products goes through for  $(,)$  inner products.

Rem!

$$L(\vec{u}) = \mu \vec{u} \quad \left\{ \begin{array}{l} \vec{u} \neq \vec{0} \\ \vec{u} \in \mathbb{R}^n, \\ \mu \in \mathbb{R} \end{array} \right.$$

then

$$\rho_L(\vec{u}) = \frac{(L(\vec{u}), \vec{u})}{(\vec{u}, \vec{u})}$$

$$= \frac{(\mu \vec{u}, \vec{u})}{(\vec{u}, \vec{u})} = \mu$$

$$\mu \text{ eigenvalue} = \rho_L(\vec{u})$$

We know

$$R_L(\vec{v}^*) = \lambda \text{ with}$$

$$L(\vec{v}^*) = \lambda \vec{v}^*$$

and

$$R_\pi(\vec{v}^*) = \max_L R_L$$

$\lambda \leq$

at least as big

$\Rightarrow \lambda$  is the largest eigenvalue of  $L$  ( s.t  $L(\vec{u}) = \mu \vec{u}$  for some  $\vec{u} \neq 0$  )

Now set

$$\vec{v}_1 = \vec{v}^*, \quad \lambda_1 = \lambda$$

$$= R_L(\vec{v}^*)$$

Consider

$$\max R_L(\vec{v})$$

$$\left\{ \begin{array}{l} \vec{v} + \vec{o} \text{ and} \\ \vec{v} \perp \vec{v}_1 \end{array} \right\}$$

clever  
trick

If this max is attained at

$$\vec{v}^* = \vec{v}_2, \text{ i.e.}$$

$\vec{v}_2 \perp \vec{v}_1, \vec{v}_2 \neq 0$ , and

$$R_L(\vec{v}_2) \geq R_L(\vec{v}) \text{ for}$$

any  $\vec{v} \perp \vec{v}_1$ ,

Some variational argument shows  
that if  $\vec{u} \perp$  both  $\vec{v}_1, \vec{v}_2$ , then

$$\vec{u} \perp L(\vec{v}_2)$$

$$\Rightarrow \mathcal{L}(\vec{v}_2) = c_1 \vec{v}_1 + c_2 \vec{v}_2$$

$$\vec{v}_2 + \vec{v}_1 = c_2 \vec{v}_2$$

we write

$$\vec{v}_1 = \lambda_1 \vec{v}_2$$

So

$$\mathcal{L}(\vec{v}_1) = \lambda_1 \vec{v}_1$$

$$\mathcal{L}(\vec{v}_2) = \lambda_2 \vec{v}_2$$

$\vec{v}_2 \perp \vec{v}_1$ . Now let  $\vec{v}_3$  be

the vector  $\perp \vec{v}_1, \vec{v}_2$  where

$\max \quad R_2(\vec{v})$

$\vec{v} \neq 0$

$\vec{v} + \vec{u}_1, \vec{u}_2$

is attached ...



Claim!

SVD comes from almost

the same argument



Class ends

Idea!

$$f(x_1, x_2) = x_1^2 + x_2^2, \quad x_1, x_2 \in \mathbb{R}$$

where is the min

$$\nabla f = (2x_1, 2x_2)$$

$$\nabla f = \vec{0} \Rightarrow x_1 = x_2 = 0$$

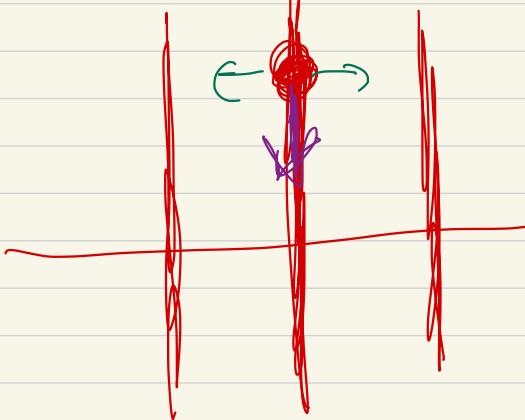


$$f(x_1, x_2) = x_1^2$$

$$\nabla f = (2x_1, 0)$$

$$\nabla f = \vec{0} \Rightarrow x_1 = 0, \quad x_2 \text{ anything}$$

$$f=1 \quad f=0 \quad f=1$$



$$f(x_1, x_2) = x_1^2$$

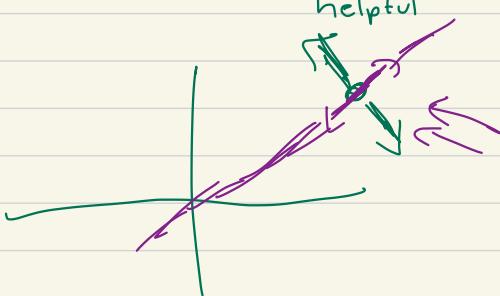
↓ not helpful

$\leftrightarrow$  helpful

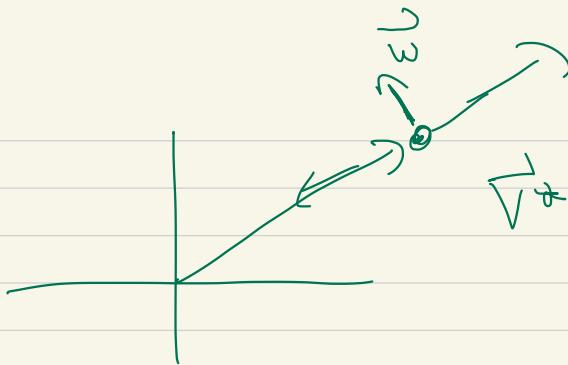


$$R_{[2,1]}(x_1, x_2) = \frac{2x_1^2 + x_2^2}{x_1^2 + x_2^2}$$

helpful



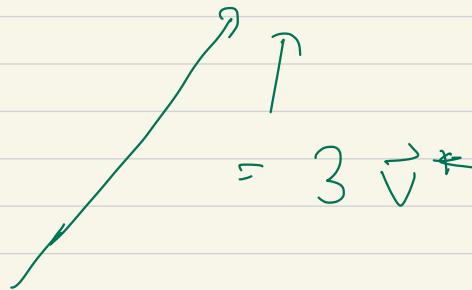
$R = \text{constant}$



$$R_e(\vec{v}^*)$$

$$= R_L(\sqrt{3} \vec{v}^*)$$

$$\vec{v}_c = \vec{v}^* + \epsilon \vec{\omega}$$



$$3 \vec{v}^* + \vec{\omega}$$

$$\vec{\omega} \perp \vec{v}^*$$

$$(\vec{v}_\varepsilon, \vec{v}_\varepsilon)$$

$$= (\vec{v}^*, \vec{v}^*) + 2\varepsilon (\vec{v}^*, \vec{u}) + (\vec{u}, \vec{u}) \underbrace{\varepsilon^2}_{\text{brace}}$$

if  $\vec{u} = 3\vec{v}^* + \vec{\omega}$

$$\vec{\omega} \perp \vec{v}^*$$

$$(\vec{v}^*, \vec{u}) = (\vec{v}^*, 3\vec{v}^* + \vec{\omega})$$

$$= 3(\vec{v}^*, \vec{v}^*) + 0$$

$\neq 0$

# EXERCISE



Solve Heat Eq

$$\frac{\partial}{\partial t} u + \boxed{\Delta u} = 0$$

Wave Eq

$$(\frac{\partial}{\partial t})^2 u + \boxed{\Delta u}$$

Laplace Eq

$$\boxed{\Delta u} = 0, \text{ no time}$$

To solve

$$\vec{u}: \mathbb{R} \rightarrow \mathbb{R}^n, \vec{u} = \vec{u}(t)$$

$$\frac{d}{dt} \vec{u} = A \vec{u} \Rightarrow$$

want to

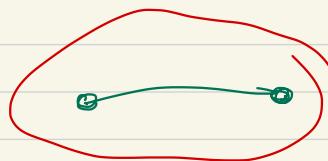
$$\vec{u}(t) = e^{At} \vec{u}(0)$$

find eigenpairs of  $A$

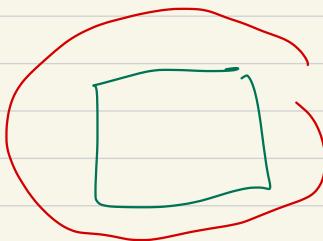
Want to eigenpairs of  $\Delta u$

Wave  
Heat

1-dim



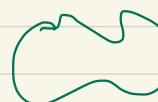
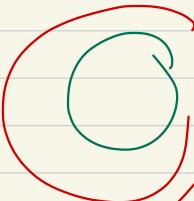
2-dim



Can

explicitly

find eigenpairs



Something  
worse



can't

generally

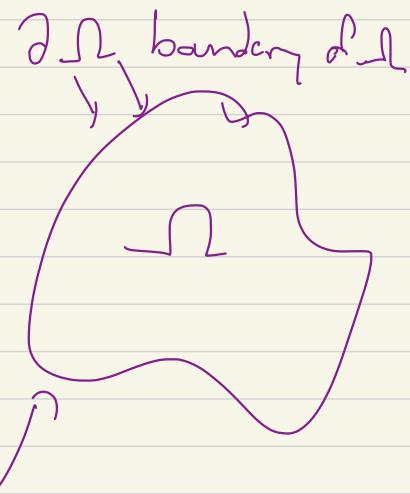
but eigenpairs of  $\Delta$  {  $R = \frac{-(\Delta f, f)}{(f, f)}$   
can be found by  $-D = \frac{-(\Delta f, f)}{(f, f)}$

$$\leq \frac{(\nabla f, \nabla f)}{(f, f)}$$

minimize

$$\frac{(\nabla f, \nabla f)}{(f, f)}$$

over



$$f \text{ s.t. } f|_{\partial\Omega} = 0$$

gives lowest

eigenfunction } of  $-\Delta$   
eigenvalue }

wave equation  $\Rightarrow$  becoming all the eigenvalues of  $-\Delta$