

CPSC 531 F, Jan 26, 2021

Homework + Supplement Notes - document,

supplemental notes

- Give extra examples
  - " material not in references
  - Outline " not central to CPSC 531
- order will not always correspond to order of topics in class
- some topics we won't cover this year.
- constantly revise throughout term

Yesterday's §4 → Appendix

Today's §4 → Examples from Graph Thry,  
SVD (singular value decomposition), Markov chains

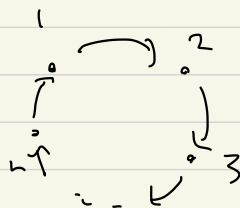
Emphasis on examples (homework).

Examples of matrices, graphs, Markov chains, ...

Last time!

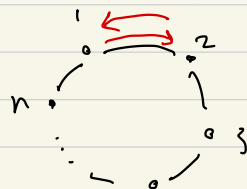
$$C_n = \begin{bmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & \dots & \dots & \dots & 0 & 1 \\ 1 & 0 & 0 & \dots & \dots & 0 \end{bmatrix}$$

(Directed)  
Cycle of length  $n$



Versus undirected cycle

$$A_{\text{undirected cycle}} = C_n + C_n^{-1}$$



$C_n$ : eigenpairs = eigenvalues/vectors

for any  $\zeta$  with  $\zeta^n = 1$

$$C_n \begin{bmatrix} 1 \\ \zeta \\ \zeta^2 \\ \vdots \\ \zeta^{n-1} \end{bmatrix} = \begin{bmatrix} \zeta \\ \zeta^2 \\ \vdots \\ \zeta^n \end{bmatrix} = \zeta \begin{bmatrix} 1 \\ \zeta \\ \zeta^2 \\ \vdots \end{bmatrix}$$

we have

"eigenpairs for  $C_n$ " :  $\zeta, \begin{bmatrix} 1 \\ \zeta \\ \vdots \\ \zeta^{n-1} \end{bmatrix}$

since  $\zeta = e^{2\pi i \frac{m}{n}}$ ,  $m = 0, 1, \dots, n-1$

this gives  $n$  distinct eigenvalues,

$\Rightarrow$  have an eigenvector for each

so we have "eigenbasis"

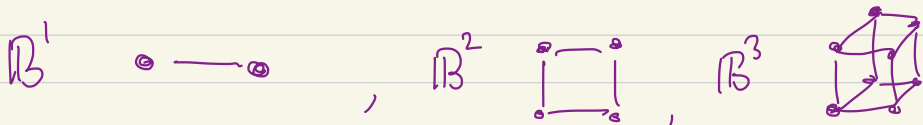
"a basis of eigenpairs"

$$A \in M_n(\mathbb{R}, \mathbb{C}), \quad A \vec{v}_i = \lambda_i \vec{v}_i$$

$\vec{v}_1, \dots, \vec{v}_n$  basis,  $\lambda_1, \dots, \lambda_n \in \mathbb{R}$   
for  $\mathbb{R}^n$  ( $\mathbb{C}^n$ ) (or  $\mathbb{C}$ )

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Today start:  $B^n$  - boolean hypercube of  
 $n$  dimensions



A boolean function on  $n$ -variables:

$$\text{function } \{0,1\}^n \rightarrow \{0,1\}$$

$$\{F, T\}^n \rightarrow \{F, T\} \quad \begin{array}{l} F = \text{false} \\ T = \text{true} \end{array}$$

Studying  $\mathbb{B}^n$  can help understand Boolean functions.

$$\mathbb{B}^1 \quad \begin{array}{c} 0 \\ \bullet \\ 0 \end{array} \rightarrow \begin{array}{c} 1 \\ \bullet \\ 0 \end{array} \quad A_{\mathbb{B}^1} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = C_2$$

$$C_2: \zeta^2 = 1, \quad \zeta = 1, -1$$



$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = -1 \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

notice  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$   $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$  are orthogonal!

$$\text{for } \vec{u}, \vec{v} \in \mathbb{R}^n \quad \vec{u} \cdot \vec{v} = \sum_{i=1}^n u_i v_i = \begin{pmatrix} \vec{v}^T \\ \vec{u} \end{pmatrix} = \begin{pmatrix} \vec{u}^T \\ \vec{v} \end{pmatrix}$$

really  
 $|x|$  matrices

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ -1 \end{bmatrix} = (1)(1) + (1)(-1) = 0$$

$$\text{"="} \quad \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix}$$

Orthogonal basis:

$$\vec{v}_1, \dots, \vec{v}_n \in \mathbb{R}^n$$

$$\text{s.t.} \quad \vec{v}_i \cdot \vec{v}_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Rem: } \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \xrightarrow{\text{ON}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} / \sqrt{2}$$

$$\begin{bmatrix} 1 \\ -1 \end{bmatrix} / \sqrt{2}$$

become orthonormal

Orthogonal basis  $\vec{v}_1, \dots, \vec{v}_n$  s.t.

$$\vec{v}_i \cdot \vec{v}_j = \begin{cases} \text{non-zero} & i=j \\ 0 & i \neq j \end{cases}$$

If  $\vec{v}_1, \dots, \vec{v}_n$  are orthonormal,  
then  $\vec{u} \in \mathbb{R}^n$ ,

$$(*) \quad \vec{u} = (\vec{u} \cdot \vec{v}_1) \vec{v}_1 + \dots + (\vec{u} \cdot \vec{v}_n) \vec{v}_n$$

An orthogonal matrix is a matrix,  
 $Q \in \mathcal{M}_n(\mathbb{R})$  s.t. any of the following  
hold:

(1)  $Q^{-1}$  exists and equals  $Q^T$

(2)  $Q Q^T = I$       (3)  $Q^T Q = I$

(4) the columns of  $Q$  are orthonormal

(5) " rows " " " " "

(6) (\*) holds for all  $\vec{v} \in \mathbb{R}^n$

e.g.,  $C_2 = A_{B'} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$

OK eigenbasis:  $1, \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$

$-1, \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}$

$$A_{B'} \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} = 1 \cdot \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$A_{B'} \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix} = (-1) \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix}$$

$$A_{B'} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Q

Q

$$\underbrace{Q^{-1}}_{Q^T} A Q = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Fundamental Way to Write a Symmetric Matrix!

- If  $A \vec{v}_i = \lambda_i \vec{v}_i$ ,  $\vec{v}_1, \dots, \vec{v}_n$  ON  
 $\lambda_1, \dots, \lambda_n$  real

then

$$A = \sum_{i=1}^n \lambda_i \vec{v}_i \vec{v}_i^T \quad \text{EXERCISE}$$

claim! here

"spectral thm"

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = (1) \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & 1/\sqrt{2} \end{bmatrix}$$

$$+ (-1) \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix} \begin{bmatrix} 1/\sqrt{2} & -1/\sqrt{2} \end{bmatrix}$$



$$(\text{check}) \Rightarrow \begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix} + \begin{bmatrix} 1/2 & -1/2 \\ -1/2 & 1/2 \end{bmatrix} (-1)$$

$$= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$A_{\mathbb{B}^2} = \begin{array}{c} \circ \text{---} \circ \\ | \quad | \\ \circ \text{---} \circ \end{array} \quad ! \quad \left. \begin{array}{l} \text{Cartesian} \\ \text{product} \end{array} \right\}$$

$$= A_{\mathbb{B}^1} \times A_{\mathbb{B}^1}$$

$$A_{\mathbb{B}^n} = A_{\mathbb{B}^1} \times \dots \times A_{\mathbb{B}^1}$$

More generally, let's define

digraphs / graphs "cartesian product"

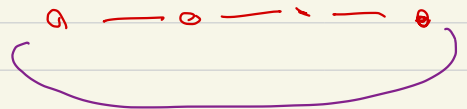
note

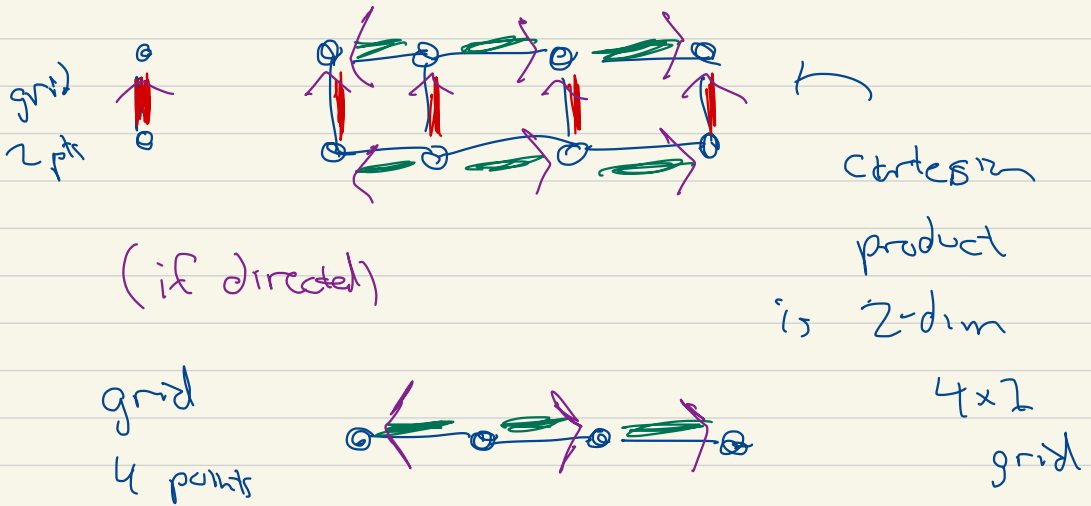


cycle length 4



1-dim grid 4 points





Definition: Let  $G, H$  be two directed graphs

$$G = (V_G, E_G, t_G, h_G), H = (V_H, E_H, t_H, h_H)$$

Cartesian product  $G \times H$ :

$$\textcircled{1} V_{G \times H} = V_G \times V_H = \left\{ (v_1, v_2) \mid \begin{array}{l} v_1 \in V_G \\ v_2 \in V_H \end{array} \right\}$$

Recall!  $S, T$  sets  $S \sqcup T$  disjoint union

$$\textcircled{2} \quad E_{G \times H} = ( \quad ) \perp\!\!\!\perp ( \quad )$$

each edge in  
 $G$ , each vertex of  
 $H$

$$(E_G \times V_H) \perp\!\!\!\perp (V_G \times E_H)$$

$$t \begin{matrix} \uparrow & \uparrow \\ (e, v) = (t(e), v) \end{matrix}$$

$$h \begin{matrix} \uparrow & \uparrow \\ (e, v) = (h(e), v) \end{matrix}$$

$$t(v, e) = (v, t(e))$$

$$h(v, e) = (v, h(e))$$

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Recall:  $S, T$  sets,  $S \times T = \{(s, t) \mid s \in S, t \in T\}$

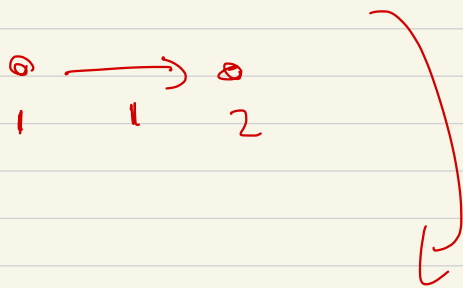
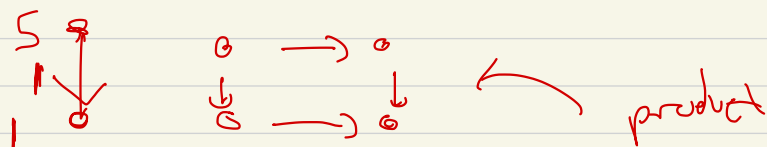
Also  $S \sqcup T =$  union of  $S$  and  $T$  regarded  
as different sets

of the  $S \times \{0\} \cup T \times \{1\}$

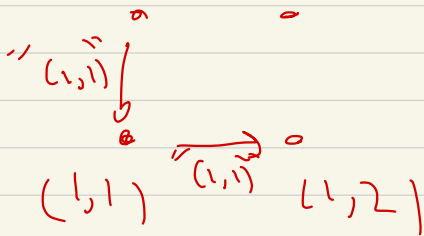
$$(1, 2) \sqcup (3, 4) = (1, 2, 3', 4')$$

$$(1, 2) \sqcup (2, 3) = (1, 2, 2', 3')$$

Aside on disjoint union



$$(S, 1) \quad (S, 2)$$

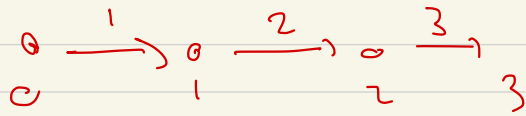


the two

$(1, 1)$  edges

are different

# Grid graphs



Upshot:

Let  $G, H$  be (di)graphs, with

eigenbases

$$A_G \vec{v}_1 = \lambda_1 \vec{v}_1, \dots, A_G \vec{v}_n = \lambda_n \vec{v}_n$$

$$n = |V_G|,$$

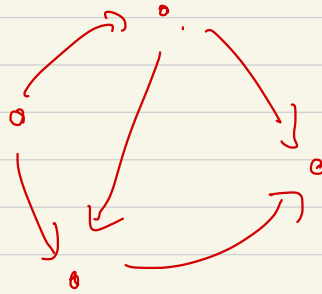
$$A_H \vec{u}_1 = \gamma_1 \vec{u}_1, \dots, A_H \vec{u}_m = \gamma_m \vec{u}_m$$

then an eigenbasis for  $A_{G \times H}$

is  $\bullet \bullet \bullet$  [NEXT TIME]

In general!

$G$  directed



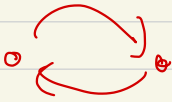
undirected version

has

$$A_{\text{undirected version of } G} = A_G + A_G^T$$

$$A \left( \begin{array}{c} \text{graph} \end{array} \right) = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

we have  $\mathbb{R}^3$  eigenbasis



$$C_2: \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, 1$$

perpendicular  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}, -1$

not unit vectors

$$\begin{bmatrix} 1\sqrt{2} \\ 1\sqrt{2} \end{bmatrix}, \begin{bmatrix} 1\sqrt{2} \\ -1\sqrt{2} \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1\sqrt{2} & 1\sqrt{2} \\ 1\sqrt{2} & -1\sqrt{2} \end{bmatrix} \begin{bmatrix} 1\sqrt{2} & 1\sqrt{2} \\ 1\sqrt{2} & -1\sqrt{2} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

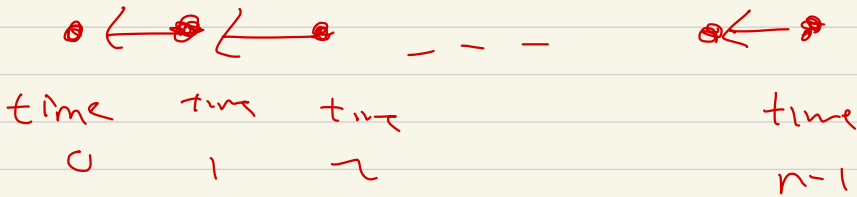


# Max Average

grid graph  $n$  vertices

directed graph

grid  
(di)graph



$$f: V \rightarrow \mathbb{R}$$

(Max Avg) (time  $t$ )

$$= \frac{f(t) + f(t-1) + \dots + f(t-b)}{7}$$

nicer!

