

CPSC 531

- Giving some applications of "spectral" matrix theory, spectral = eigenvalues/vectors, to

- graph theory; directed graphs from info th: largest eigenvalue
graphs: symmetric matrices

Perron-Frobenius

Markov matrices: mixing, $p^k \xrightarrow{\text{ask}} \infty$?

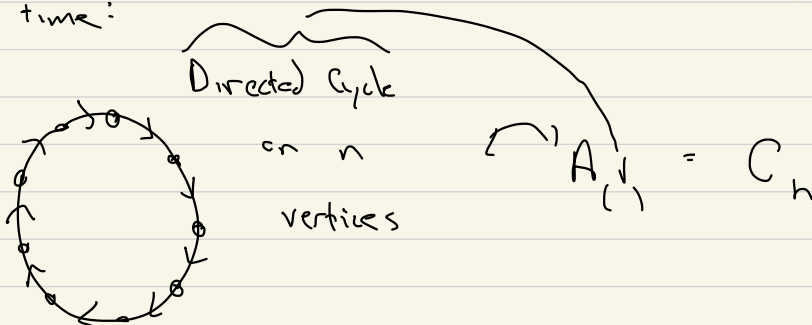
reversible Markov chains

simulated annealing

varying the stationary distribution

Familiarize ourselves with common matrices

Last time:



$$C_4 = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} = [a_{ij}] \text{ where } a_{ij} = \begin{cases} 1 & \text{if edge } i \rightarrow j \\ 0 & \text{otherwise} \end{cases}$$

$$\underbrace{[1 \ 0 \ 0 \ 0]}_{e_1^T} C_4 = \underbrace{[0 \ 1 \ 0 \ 0]}_{e_2^T}$$

vectors \vec{v} : col vect

row vector: \vec{v}^T

Goal! - Symmetric matrices have real eigenvalues with orthonormal eigenbasis

Markov chain, directed graph

- Any positive, square matrix (or non-negative, irreducible) has a largest eigenvalue λ_1 , in absolute,

- $\lambda_1 > 0$, real

- eigenvector can be taken to have all positive entries

undirected graph

reversible Markov chain

C_4 : Eigenvalue/vectors

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{pmatrix} \begin{bmatrix} \\ \\ \\ \end{bmatrix} = \text{scalar} \begin{bmatrix} \\ \\ \\ \end{bmatrix}$$

Also: left eigenvector

$$\begin{bmatrix} \\ \\ \\ \end{bmatrix} C_4 = \text{scalar} \begin{bmatrix} \\ \\ \\ \end{bmatrix}$$

C_4

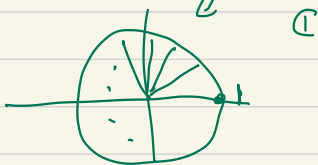
eigenvector

(right eigenvector)

Eigenvector: for C_n , any $n \in \mathbb{N} = \{1, 2, 3, \dots\}$

$$\zeta^n = 1$$

$$\zeta = e^{2\pi i \left(\frac{m}{n}\right)} \quad \text{"n-th roots of unity"}$$



$$C_n \begin{bmatrix} 1 \\ \zeta \\ \zeta^2 \\ \vdots \\ \zeta^{n-1} \end{bmatrix} = \begin{bmatrix} \zeta \\ \zeta^2 \\ \zeta^3 \\ \vdots \\ \zeta^n = 1 \end{bmatrix} = \zeta \begin{bmatrix} 1 \\ \zeta \\ \vdots \\ \zeta^{n-1} \end{bmatrix}$$

each ζ have an eigenvector, \uparrow eigenvalue is ζ .

Thm! If $A \in \mathcal{M}_n(\mathbb{C})$, and

① $p_A(t) = \det(tI - A)$ has n distinct roots
 $\lambda_1, \dots, \lambda_n$

② there are $\lambda_1, \dots, \lambda_n$ distinct st. $A\vec{v}_j = \lambda_j\vec{v}_j$
for some $\vec{v}_j \neq 0$, $j=1, \dots, n$

then $\vec{v}_1, \dots, \vec{v}_n$ are linearly independent

(lin ind: there are no nontrivial linear relations between the vectors; any n linearly independent vectors in \mathbb{R}^n or \mathbb{C}^n are a basis: each vector in \mathbb{R}^n (or \mathbb{C}^n) can be

written uniquely as $\alpha_1 \vec{v}_1 + \alpha_2 \vec{v}_2 + \dots + \alpha_n \vec{v}_n$
 $\alpha_1, \dots, \alpha_n$ are scalars (i.e. \mathbb{R}, \mathbb{C}).

$$C_4: \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

eigenvectors

$$\begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ i \\ -1 \\ -i \end{bmatrix} \quad \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \quad \begin{bmatrix} 1 \\ -i \\ -1 \\ i \end{bmatrix}$$

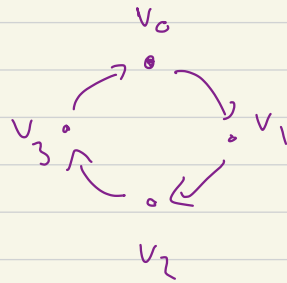
C_4 is an example of

a circulant matrix

$$\lambda=1 \quad \lambda=i \quad \lambda=-1 \quad \lambda=-i$$

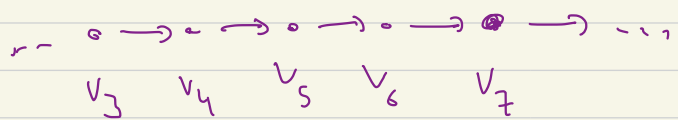
$$(1) \quad b_0 I + b_1 C_4 + b_2 C_4^2 + b_3 C_4^3$$

$$(2) \quad \begin{bmatrix} b_0 & b_1 & b_2 & b_3 \\ b_3 & b_0 & b_1 & b_2 \\ b_2 & b_3 & b_0 & b_1 \\ b_1 & b_2 & b_3 & b_0 \end{bmatrix}$$



$$f(v_6) \quad f(v_7)$$

Moving average



moving last 3 $\left\{ \begin{array}{l} \text{days} \\ \text{hours} \\ \text{seconds} \end{array} \right\} := \text{at } v_7: \frac{f(v_5) + f(v_6) + f(v_7)}{3}$

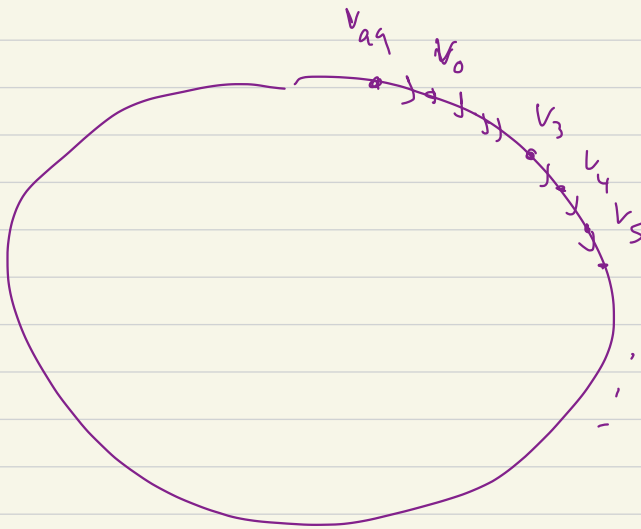
moving avg on n large

C_n has eigenvalues

$$\zeta, \zeta^n = 1$$

eigenvectors

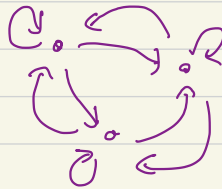
$$\begin{bmatrix} 1 \\ \zeta \\ \zeta^2 \\ \vdots \\ \zeta^{n-1} \end{bmatrix}$$



$$\begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & 1 & 1 & \dots & 1 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & 1 & \dots & 1 \end{bmatrix} = E_n$$

"complete directed graph adjacency matrix"

$$\begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = n \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$



turns out :

n eigenvalue multiplicity 1
 0 " multiplicity $n-1$

Multiplicity of eig λ of A !

"Algebraic multiplicity"

mult. of λ as a root of $p_A(t)$

polynomial

$$p_A(t) = \det(tI - A)$$

$$A \in M_n(\mathbb{R})$$

$$= t^n + r_1(A)t^{n-1} + r_2(A)t^{n-2} + \dots$$

$$\begin{bmatrix} t & & & \\ & t & & \\ & & t & \\ & & & \ddots \end{bmatrix} - \begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & \ddots & \ddots \\ \vdots & \ddots & \ddots \\ \vdots & & \ddots \end{bmatrix}$$

$$\det \begin{bmatrix} (t-a_{11}) & -a_{12} & -a_{13} & \dots \\ -a_{21} & (t-a_{22}) & -a_{23} & \dots \\ -a_{31} & -a_{32} & (t-a_{33}) & \dots \\ \vdots & \vdots & \vdots & \ddots \end{bmatrix}$$

$$\det(B) = \sum_{\sigma \in \text{Perm}(n)} b_{1\sigma(1)} b_{2\sigma(2)} \dots b_{n\sigma(n)} \\ (t - \lambda) \times$$

$$\det \begin{bmatrix} (t-a_{11}) & -a_{12} & -a_{13} \\ -a_{21} & (t-a_{22}) & -a_{23} \\ -a_{31} & -a_{32} & (t-a_{33}) \end{bmatrix} \quad \text{sign}(\sigma)$$

$$= (t-a_{11})(t-a_{22})(t-a_{33}) \pm \text{other prod of entries}$$

$$= t^3 + t^2(-a_{11}-a_{22}-a_{33}) +$$

+ terms of deg 1 or 0

$$t^n + t^{n-1}(-a_{11}-a_{22}-\dots-a_{nn}) + \dots + t^1(\dots)$$

$$\underbrace{\hspace{10em}}_{- \text{Trace}(A)}$$

$$+ t^0(\dots)$$

$$\det \begin{bmatrix} -a_{11} & -a_{12} & -a_{13} \\ -a_{21} & \ddots & \ddots \\ \vdots & \ddots & \ddots \end{bmatrix}$$

$$= (-1)^n \det(A)$$

Break 10:30 — 10:34

Matrices that aren't diagonalizable:

$$A = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$$

$$P_A(t) = (t-2)^2$$

$$\text{eigs } \lambda = 2$$

$$\begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 2a \\ 2b \end{bmatrix}$$

$$2a = 2a + b \Rightarrow$$

$$\begin{bmatrix} 2a + b \\ 2b \end{bmatrix}$$

$$b = 0,$$

$$\text{eigenspace } \lambda=2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\left(\begin{array}{c} \text{eigenspace of } \lambda \\ \text{w.r.t } A \end{array} \right) := \left\{ \vec{v} : A\vec{v} = \lambda\vec{v} \right\}$$

$$= \ker(A - \lambda I)$$

$$\left(\begin{array}{c} \text{generalized} \\ \text{eigenspace of } \lambda \\ \text{w.r.t } A \end{array} \right) := \bigcup_{m=1,2,\dots} \ker((A - \lambda I)^m)$$

$$\text{or } \int \left[\begin{array}{ccc} & & \\ & 3 & \\ & -3 & \\ & & 3 \\ & & & 7 \\ & & & & 7 \\ & & & & & 8 \\ & & & & & & 8 \\ & & & & & & & 8 \end{array} \right] 5^{-1}$$

blank spaces = 0's

$$\bar{J}_1(\lambda) = [\lambda] \quad \leftarrow \text{eigenvector}$$

$$\bar{J}_2(\lambda) = \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix} \leftarrow$$

$$\bar{J}_3(\lambda) = \begin{bmatrix} \lambda & 1 & 0 \\ 0 & \lambda & 1 \\ 0 & 0 & \lambda \end{bmatrix} \leftarrow$$

only one eigenvector per block

$$\bar{J}_3(0) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{matrix} \circ & \rightarrow & \circ & \rightarrow & \circ & \left(\begin{matrix} \circ \\ \circ \\ \circ \end{matrix} \right) \\ v_1 & & v_2 & & v_3 \end{matrix}$$

$$(\bar{J}_3(0))^2 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$(\bar{J}_3(0))^3 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

They come up for a reason ---

$$x_n - 2x_{n-1} + x_{n-2} = 0$$

$$x_n = 2x_{n-1} - x_{n-2}$$

$$\rightarrow \begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_{n-1} \\ x_{n-2} \end{bmatrix} = \begin{bmatrix} x_n \\ x_{n-1} \end{bmatrix}$$

"defective matrices"

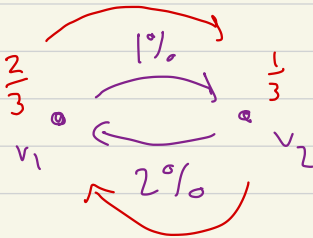
"geometric mult = dim space eigenvectors"

$$= \dim \ker(A - \lambda I)$$

Class ends

Marka metre

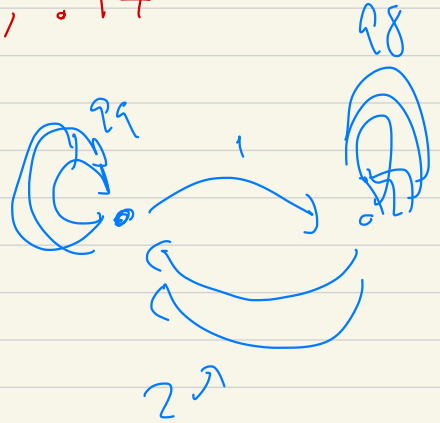
$$\begin{bmatrix} .99 & .01 \\ .02 & .98 \end{bmatrix} \xrightarrow{\text{large}} \begin{bmatrix} 2/3 & 1/3 \\ 2/3 & 1/3 \end{bmatrix}$$



balance

$$\lambda = 1, .97$$

$$\begin{bmatrix} 99 & 1 \\ 2 & 98 \end{bmatrix}$$



$$\begin{bmatrix} 99 & 1 \\ 2 & 98 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 100 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 2/3 & 1/3 \\ 2/3 & 1/3 \end{bmatrix} \begin{bmatrix} 99 & 1 \\ 2 & 98 \end{bmatrix} = \begin{bmatrix} 2/3 & 1/3 \\ 2/3 & 1/3 \end{bmatrix} \cdot 100$$