

Nov 29,

$P^{\text{SAT}}$ ,  $NP^{\text{SAT}}$

vs

$SAT \in$  non-deterministic  
poly time

$P^B$ ,  $NP^B$

$B = \text{PSPACE-SNEAKY}$

deterministic

(1)  $P^{\text{SAT}} \stackrel{?}{=} NP^{\text{SAT}}$ ,

but having a SAT oracle

$SAT \in NP$ , non-det poly time

$\in \text{PSPACE}$  (deterministic)

deterministic  $\Leftrightarrow$  have a  
subroutine for it

=

$NP \subset P^{\text{SAT}}$ ,

$\text{co}NP \subset P^{\text{SAT}}$

=

Long story:



buttons  
A  
" B  
" C  
:

Flush toilet

Simulate A

per each call  
(1) you have to go outside  $\leftarrow$  time resources  
 $\leftarrow$  patience ..

(2) " " " another toilet

(3) take toilet apart, look main gasket, replace, test  
 $\leftarrow$  resource cost  
might need to replace bolts

knew this  
(4) replace gasket & bolts & test

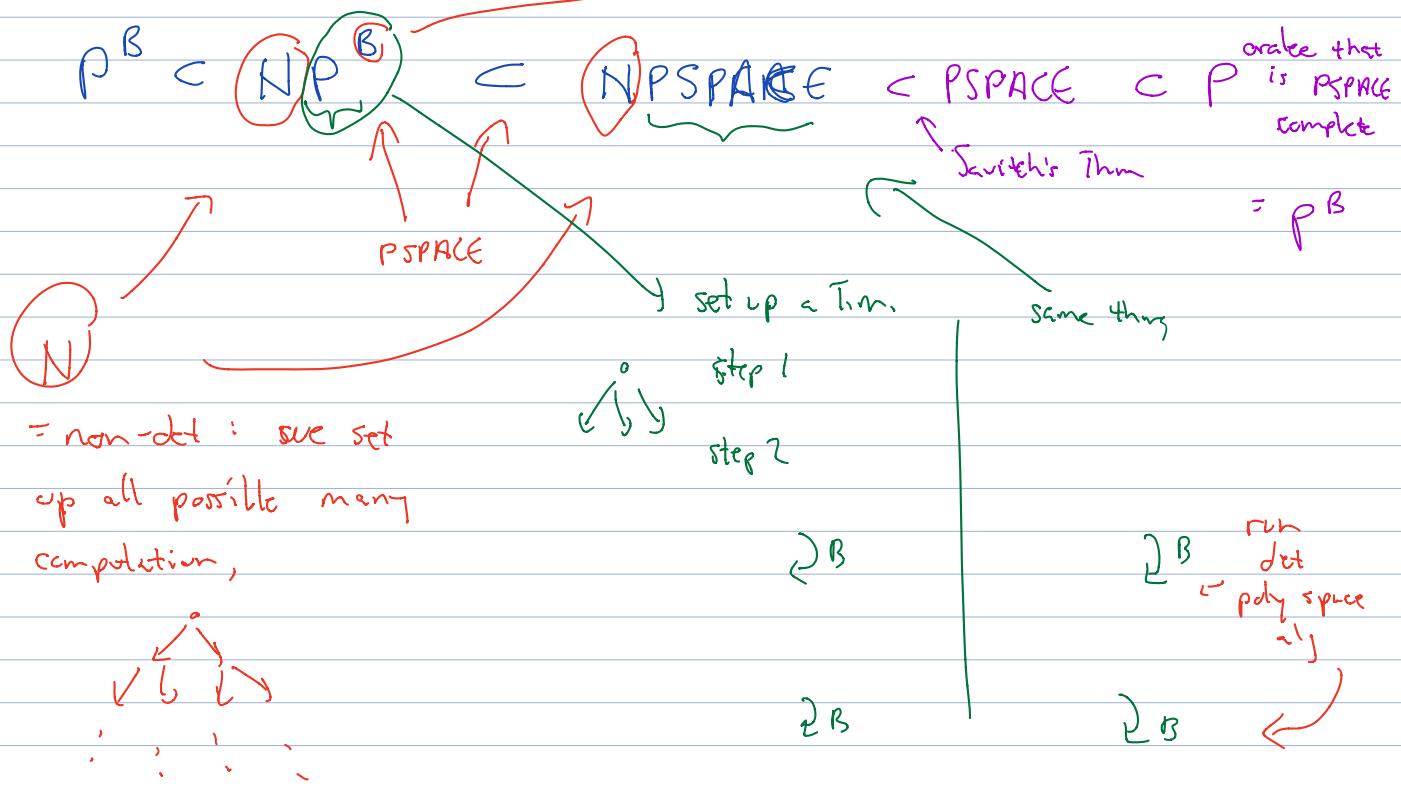
(3')

But ~~if~~ I don't non-det do (1), (2), (3), (4), (5)

Difference: deterministic substitute for oracle call

non-  
=

$\text{B} = \text{PSPACE-SNEAKY}$  ← deterministic poly space



$q_{\text{acc}}$   $q_{\text{ rej}}$   $q_{\text{acc}}$

=

HALT is undecidable (by T.m)

?  $\hookrightarrow$   $\text{HALT}^A$  is undecidable (by  $\text{T.m}^A$ ) for  $A = \text{oracle}$  ? any given

↗  
yes, this theorem relativizes

$$\text{TIME}^B(n^3) \subset \text{TIME}^B(n^{3.001})$$

$L_1 \cap L_2$  regular  
decidable  
poly time decider  
" space "

$L_1^*$  (dynamic programming)  
(DFA  $\rightarrow$  NFA)

deterministic

$L_1 \cap L_2$

$L_1 \cup L_2$   
:

$L_1^{\text{comp}}$

$L_1 \in NP$

is  $L_1^{\text{comp}}$  in NP? Don't know

$L_1 \in NPSPACE$

is  $L_1^{\text{comp}}$  in NPSPACE?

PSPACE  
deterministic