

FINAL PRACTICE, CPSC 303, SPRING 2024

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The following problems are sample final exam problems, largely based on the homework. There are a lot on material after the midterm, i.e., starting with divided differences, but some cover earlier material.

- (1) Answer true or false:
 - (a) In the central force problem, $m\ddot{\mathbf{x}} = -u(\|\mathbf{x}\|)\mathbf{x}/\|\mathbf{x}\|$, the momentum $m\mathbf{v} = m\dot{\mathbf{x}}$ is conserved.
 - (b) In the central force problem, $m\ddot{\mathbf{x}} = -u(\|\mathbf{x}\|)\mathbf{x}/\|\mathbf{x}\|$, the energy $(1/2)m\|\mathbf{v}\|^2 + U(\|\mathbf{x}\|)$ is conserved, where $\mathbf{v} = \dot{\mathbf{x}}$ and U satisfies $U' = u$.
 - (c) The central force problem, $m\ddot{\mathbf{x}} = -u(\|\mathbf{x}\|)\mathbf{x}/\|\mathbf{x}\|$ is reversible in time, i.e., if $\mathbf{x}(t)$ is a solution, then $\mathbf{x}(T - t)$ is also a solution.
 - (d) If A is a 2×2 matrix, then there exists an \mathbf{x} each of whose components are all either 1, -1 , such that $\|A\mathbf{x}\|_\infty = \|A\|_\infty\|\mathbf{x}\|_\infty$.
 - (e) If A is a 2×2 matrix, and $\mathbf{x} \neq \mathbf{0}$ satisfies $\|A\mathbf{x}\|_\infty = \|A\|_\infty\|\mathbf{x}\|_\infty$, then all components of \mathbf{x} are either 1, -1 .
 - (f) We have an algorithm for monomial interpolation on n points that takes order n^2 floating point operations **to form the polynomial and evaluate it at one point.**
 - (g) We have an algorithm for Lagrange interpolation on n points that takes order n^2 floating point operations **to form the polynomial and evaluate it at one point.**
 - (h) We have an algorithm for **Newton's form of interpolation (i.e., via divided differences)** on n points that takes order n^2 floating point operations **to form the polynomial and evaluate it at one point.**
 - (i) There exist functions $f: \mathbb{R} \rightarrow \mathbb{R}$ such that $f[0, 1, 2] \neq f[0, 2, 1]$.
 - (j) MORE EXERCISES MAY APPEAR

Note: for a cubic spline $v(x)$ with abscissae $A = x_0 < \dots < x_n = B$ that approximates $f(x)$, the following formulas are useful regarding the piecewise cubic spline $s_i(x) = a_i + b_i(x - x_i) + c_i(x - x_i)^2 + d_i(x - x_i)^3$ satisfies (this piece is for v on $[x_i, x_{i+1}]$):

$$a_i = f(x_i), \quad b_i = f[x_i, x_{i+1}] - \frac{h_i}{3}(2c_i + c_{i+1}), \quad d_i = \frac{c_{i+1} - c_i}{3h_i}$$

and that for each $i = 1, \dots, n - 1$ we have

$$\frac{h_i}{h_i + h_{i+1}}c_{i-1} + 2c_i + \frac{h_{i+1}}{h_i + h_{i+1}}c_{i+1} = 3f([x_{i-1}, x_i, x_{i+1}]).$$

where $h_i = x_{i+1} - x_i$, and where $c_0 = v''(A)$ and $c_n = v''(B)$ (c_n is not really defined since $s_n(x)$ isn't defined, but it is convenient to define it so that the above formulas hold).

- (2) Say that $x_0 < x_1 < \dots < x_n$ are reals, and $v(x)$ is a cubic spline with abscissae x_0, \dots, x_n (i.e., $v(x)$ is a piecewise cubic polynomial in the intervals (x_i, x_{i+1}) for $i = 0, \dots, n - 1$). How many parameters describe $v(x)$? If we insist that $v(x_0), \dots, v(x_n)$ take on $n + 1$ given values, how many equations do we get on the parameters describing v ? If we insist that v is twice continuously differentiable at x_1, \dots, x_{n-1} , show many equations do we get?
- (3) Say that $A = x_0 < x_1 < \dots < x_n = B$, and $v(x)$ is a cubic spline approximating $f(x)$, with abscissae x_0, \dots, x_n . Say that instead of the natural spline (i.e., $v''(A) = v''(B) = 0$), we fix $v'(A) = f'(A)$ (which we presume is known), but we keep the condition $v''(B) = 0$. **As usual, say that $h_1 = h_2 = \dots = h_{n-1}$.**
- (a) What does $v'(A) = f'(A)$ tell you about the coefficients of the cubic polynomial $s_0(x) = a_0 + b_0(x - x_0) + c_0(x - x_0)^2 + d_0(x - x_0)^3$ that agrees with $v(x)$ in $[x_0, x_1]$?
- (b) Show that the above information allows you to determine $2c_0 + c_1$.
- (c) If we now write a system of equations for $\mathbf{c} = (c_0, c_1, \dots, c_{n-1})$, do we still get a system of equations where $(2I + M)\mathbf{c}$ is determined for some matrix with $\|M\|_\infty \leq 1$?

For divided differences the following formulas are useful: $f[x_0, \dots, x_n] = f^{(n)}(\xi)/n!$ for some ξ contained in any interval containing x_0, \dots, x_n (we called this the “generalized mean-value” theorem). If $p(x)$ interpolates $f(x)$ at x_0, \dots, x_n , then the “error in polynomial interpolation” theorem states that $f(x) - p(x) = f^{(n+1)}(\xi)/(n + 1)!$ for some ξ contained in any interval containing x_0, \dots, x_n and x . You should realize that this second statement follows from the first. You should realize that fixing x_0 and taking x_1, \dots, x_n tending to x_0 you essentially get Taylor’s theorem.

- (4) Let x_0, x_1, x_2, x_3 be given by $x_i = i/3$, and $f(x) = \sin(x)$. Give a bound on $|f[x_0, x_1, x_2, x_3]|$ using the generalized mean-value theorem.
- (5) Let x_0, x_1, x_2, x_3 be given by $x_i = i/3$, and $f(x) = \sin(x)$. Say that you find the polynomial $p(x)$ of degree at most 3 such that $p(x_i) = f(x_i)$ $i = 0, \dots, 3$. Estimate the error in $p(1/2)$ and $f(1/2)$ using the error in Newton divided differences formula.

- (6) Let $n \in \mathbb{N}$, and let x_0, x_1, x_2, x_3 be given by $x_i = 10^{-n}i/3$. Say that you find the polynomial $p(x)$ of degree at most 3 such that $p(x_i) = \sin(i)$, and that you compute $p(10^{-n}(3/2))$.
- For $n = 6$, is it more numerically accurate to compute $p(x)$ using monomial interpolation or using Lagrange interpolation? Explain roughly why this holds.
 - Does the value (with exact computation) of $p(10^{-n}(3/2))$ depend on n ? Explain.
- (7) Say that $n \in \mathbb{N}$, and that you have computed the monomial form of $p(x) = c_0 + c_1x + \dots + c_{n-1}x^{n-1}$ such that $p(i) = 1/i$ for $i = 1, 2, \dots, n$. Say that $q(x)$ is the unique polynomial of degree at most n such that $q(i) = 1/i$ for $i = 1, 2, \dots, n+1$. Imagine that you want to compute q at ℓ values y_1, \dots, y_ℓ .
- Explain how to do this in a way that takes you $O(\ell n + n^2)$ flops (floating-point operations).¹
 - If you used Lagrange interpolation (from scratch, ignoring the fact that you already know p), explain why this would take $O(\ell n + n^2)$ flops as well (with slightly different constants).
- (8) Consider the implicit trapezoidal method (see [A&G], bottom page 493) to solve $\mathbf{y} = \mathbf{f}(\mathbf{y})$, subject to $\mathbf{y}(0) = \mathbf{y}_0$: choose a step size, $h > 0$, and define $\mathbf{y}_1, \mathbf{y}_2, \dots$ via
- $$(1) \quad \mathbf{y}_{i+1} = \mathbf{y}_i + h \frac{\mathbf{f}(\mathbf{y}_i) + \mathbf{f}(\mathbf{y}_{i+1})}{2};$$
- taking \mathbf{y}_i as an approximation to $\mathbf{y}(ih)$.
- Consider the single variable ODE $y' = ay$, where $a \in \mathbb{R}$ is constant. Show that the above method gives the recurrence
- $$y_{i+1} = y_i \frac{1 + ah/2}{1 - ah/2}.$$
- Show that if $a < 0$ and $y_0 = 1$, we have $0 < |y_{i+1}| < |y_i|$ for all m . [Hint: show that $(1 + ah)/(1 - ah)$ is both < 1 and > -1 ; since $1 - ah$ is positive, you can multiply both sides by $1 - ah$.]
 - Show that if $0 \leq ah < 2$ and $y_0 = 1$, we have $y_{i+1} > y_i$ for all i . [Hint: use the idea for part (b); if $0 \leq ah < 2$, is it still the case that $1 - ah$ is positive?]
 - What happens when $ah > 2$? Why is the behaviour of y_1, y_2, \dots qualitatively different than the true solution $y(t) = e^{at}$?
- (9) Let $y = y(t)$ be infinitely differentiable (for simplicity), and consider the approximation

$$\frac{y(t+h) - y(t)}{h} \approx \frac{y'(t+h) + y'(t)}{2}$$

for a fixed t and small $h > 0$.

¹Note: there are ways to do this in $O(\ell n + n) = O(\ell n)$ flops; see the solutions.

- (a) By a Taylor expansion, show that both sides equal $y'(t) + (h/2)y''(t) + O(h^2)$. [Hint: You'll want to apply Taylor's theorem to y' , namely $y'(t+h) = y'(t) + hy''(t) + O(h^2)$.]
- (b) Show that if $y'(t) = f(y(t))$ for some function, f , then

$$y(t+h) = y(t) + h \frac{f(y(t+h)) + f(y(t))}{2} + O(h^3).$$

- (c) Conclude that the scheme (1) is a second order scheme, i.e., each iteration holds to within $O(h^3)$.

(10) NO MORE EXERCISES FOR THIS YEAR.

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