

# Solutions to Final Practice 2, CPSC 303, 2024

(1) If  $p(x) = c_0 + c_1x + c_2x^2 + c_3x^3$ , we have

$$p(1) = c_0 + c_1 + c_2 + c_3$$

$$p'(1) = c_1 + 2c_2 + 3c_3$$

$$p(2) = c_0 + 2c_1 + 4c_2 + 8c_3$$

$$p'(2) = c_1 + 4c_2 + 12c_3$$

Hence given  $p(1), p'(1), p(2), p'(2)$ , we get a system of 4 equations with 4 unknowns.

This system has a unique solution iff the homogeneous system does. So it suffices to show that there is a unique polynomial  $p(x)$  as above with

$$p(1) = p'(1) = p(2) = p'(2) = 0,$$

namely  $p(x) = 0$ : Since  $p(1) = p(2) = 0$ ,

We have  $p'(\xi) = 0$  for some  $1 < \xi < 2$ .

Hence  $p'$  has  $\geq 3$  roots  $(1, \xi, 2)$ ;

by applying Rolle's theorem to  $p'$ , we

have that  $p''$  has at least 2 roots

(one between 1 and  $\xi$ , another between

$\xi$  and 2); similarly  $p'''$  has at

least one root. Since

$$p'''(x) = 6c_3 \quad \text{has } \geq 1 \text{ root,}$$

$$\text{we have } c_3 = 0;$$

then  $p(x) = c_0 + xc_1 + x^2c_2$ ; since

$$p''(x) = 2c_2 \quad \text{has } \geq 2 \text{ roots,}$$

$c_2 = 0$ . Then  $p(x) = c_0 + xc_1$ . Since

$p'(x) = c_1$  and has  $\geq 3$  roots,  $c_1 = 0$ .

Then  $p(x) = c_0$ ; since  $p(1) = p(2) = 0$ ,

$$c_0 = 0.$$

Hence the only polynomial  $p$  as above is  $p(x) = 0$ .

(2) We have

$$f(x+h) = f(x) + h f'(x) + \frac{h^2}{2} f''(x) + O(h^3)$$

$$f(x+2h) = f(x) + 2h f'(x) + \frac{(2h)^2}{2} f''(x) + O(h^3)$$

$$f(x+3h) = f(x) + 3h f'(x) + \frac{(3h)^2}{2} f''(x) + O(h^3)$$

Hence

$$= (c_0 + c_1 + c_2) f(x) + (c_0 + 2c_1 + 3c_2) h f'(x)$$

$$+ (c_0 + 4c_1 + 9c_2) \frac{h^2}{2} f''(x) + O(h^3)$$

$S_0$

$$\frac{c_0 f(x+h) + c_1 f(x+2h) + c_2 f(x+3h)}{h^2} = f''(x) + O(h)$$

iff

$$c_0 + c_1 + c_2 = 0$$

$$c_0 + 2c_1 + 3c_2 = 0$$

$$c_0 + 4c_1 + 9c_2 = 2.$$

Since

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 4 & 9 \end{bmatrix}$$

is the transpose of a Vandermonde matrix,  
the above  $3 \times 3$  system has a unique  
solution.

(3) We have

$$N_{\text{red}, n-1} \cup = N_{\text{red}, n-1} \begin{bmatrix} \sin(\pi/n) \\ \vdots \\ \sin(\pi(n-1)/n) \end{bmatrix}$$

$$= \begin{bmatrix} \sin(2\pi/n) \\ \sin(\pi/n) + \sin(3\pi/n) \\ \sin(2\pi/n) + \sin(4\pi/n) \\ \vdots \\ \sin(2\pi(n-3)/n) + \sin(2\pi(n-1)/n) \\ \sin(2\pi(n-2)/n) \end{bmatrix}$$

Since

$$\begin{aligned} \sin(\alpha + \beta) + \sin(\alpha - \beta) & \quad \left( \begin{array}{l} \text{see class} \\ \text{or 04-08} \end{array} \right) \\ = 2 \sin(\alpha) \cos(\beta) \end{aligned}$$

and  $\sin(0) = \sin(\pi) = 0$ , we have

$$N_{\text{rod}, n-1} \cup$$

$$= \begin{bmatrix} \sin(0) & \sin(2\pi/n) \\ \sin(\pi/n) + \sin(3\pi/n) \\ \sin(2\pi/n) + \sin(4\pi/n) \\ \vdots \\ \sin(\pi(n-3)/n) + \sin(\pi(n-1)/n) \\ \sin(\pi(n-2)/n) + \sin(\pi) \end{bmatrix}$$

$$= \begin{bmatrix} \sin(\pi/n) \\ \sin(2\pi/n) \\ \vdots \\ \sin((n-1)\pi/n) \end{bmatrix} 2 \cos(\pi/n)$$

$$= \cup 2 \cos(\pi/n)$$

Hence  $2 \cos(\pi/n)$  is the corresponding eigenvalue.

Note: This is a good way to conceptualize why in class on

04\_08 we have that the heat equation approximation is

$$u(x, sH) \approx \left(1 - 2\rho + 2\rho \cos(\pi h)\right)^2 u(x, 0)$$

when

$$u(x, 0) = \sin(\pi x).$$

(4)<sup>(a)</sup> We have  $m \ddot{x}(t) = -u(\|x\|) x / \|x\|$

where  $-u(\|x\|) x / \|x\| = -4x$ ,

So  $u(\|x\|) = 4\|x\|$  so  $u(r) = 4r$

So  $U' = u$  for  $U = 2r^2$ . Hence the energy is

$$\frac{1}{2} m (\dot{x})^2 + m(2x^2).$$

(e.g. Homework 5, Problem 2).

[An alternate approach is to multiply

$$m\ddot{x} + 4mx = 0$$

by  $\dot{x}$  and integrate:

$$m\ddot{x}\dot{x} + 4m x\dot{x} = 0$$

So

$$\frac{1}{2} m (\dot{x})^2 + m(2x^2) = \text{constant},$$

and the left-hand-side is the energy.]



Note: if  $U(r) = 2r^2 + C$  where

$C$  is any constant, then still  $U'(r) = 4r$ .

Hence one can equally well say that the energy is

$$\frac{1}{2} m (\dot{x})^2 + m(2x^2) + C$$

for any constant,  $C$ .

(It is simplest to take  $C=0$ , which we do above, and which we do for part (b))

(4b) With

$$\text{Energy} = \frac{1}{2} m (\dot{x})^2 + m(2x^2),$$

since  $x(1) = 1$  and  $\dot{x}(1) = 4$ ,

we have

$$\text{Energy} = m \left( \left(\frac{1}{2}\right)16 + 2(1^2) \right) = 10m.$$

(4c) Hence for all  $t$  we have

$$10m = \text{Energy} \geq m(2x^2)$$

$$\text{so } 2(x(t))^2 \leq 10 \text{ so } x(t) \leq \sqrt{5}$$

5 (a) Similar to solution of Homework 4, Problem (2a).

(b) Since

$$y(h) = e^{ah} y_0 = \left( 1 + ah + \frac{(ah)^2}{2} + \mathcal{O}(h^3) \right) y_0$$

$$= \left( 1 + ah + \frac{(ah)^2}{2} \right) y_0 + \mathcal{O}(h^3),$$

any second order method must

have

$y_1$  = an approximation to  $y(h)$   
valid up to  $O(h^3)$

( $O(h^3)$  for a second order method),

so

$y_1$  must equal  $y(h) + O(h^3)$

$$= \left( \left( 1 + ah + \frac{(ah)^2}{2} \right) y_0 + O(h^3) \right) + O(h^3)$$

$$= \left( 1 + ah + \frac{(ah)^2}{2} \right) y_0 + O(h^3)$$

(6)<sup>(a)</sup> Hence

$$y_1' = -300 y_1, \quad y_1(0) = 2$$

$$y_1' = y_2, \quad y_2(0) = 3$$

$$\text{So } y_1(t) = e^{-3cc t} 2$$

$$y_2(t) = e^t 3$$

$$\text{(or } \vec{y}(t) = (e^{-3cc t} 2, e^t 3)).$$

$$(6b) \quad \vec{y}_{i+1} = (\mathbf{I} + hA) \vec{y}_i$$

$$= \left( \mathbf{I} + \frac{1}{10c} \begin{bmatrix} -3cc & 0 \\ 0 & 1 \end{bmatrix} \right) \vec{y}_i$$

$$= \begin{bmatrix} 1 - 3 & 0 \\ 0 & 1 + \frac{1}{10c} \end{bmatrix} \vec{y}_i$$

$$= \begin{bmatrix} -2 & 0 \\ 0 & 1 + \frac{1}{10c} \end{bmatrix} \vec{y}_i$$

$S_c$

$$\vec{y}_i = \begin{bmatrix} -2 & 0 \\ 0 & 1 + \frac{1}{100} \end{bmatrix}^i \vec{y}_0 = \begin{bmatrix} (-2)^i & 2 \\ (1 + \frac{1}{100})^i & 3 \end{bmatrix}$$

(c) The first component is  $(-2)^i 2$ ,  
which does not decrease.

(d) For  $\vec{y}_{i+1} = \vec{y}_i + h f(\vec{y}_{i+1})$

we have

$$\vec{y}_{i+1} = \vec{y}_i + h \begin{bmatrix} -300 & 0 \\ 0 & 1 \end{bmatrix} \vec{y}_{i+1}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \vec{y}_{i+1} = \vec{y}_i + \begin{bmatrix} -3 & 0 \\ 0 & 1/100 \end{bmatrix} \vec{y}_{i+1}$$

$S_c$

$$\begin{bmatrix} 4 & 0 \\ 0 & 1 - 1/100 \end{bmatrix} \vec{y}_{i+1} = \vec{y}_i$$

$$\text{So } \vec{y}_{i+1} = \begin{bmatrix} 1/4 & 0 \\ 0 & 100/99 \end{bmatrix} \vec{y}_i$$

$$\text{So } \vec{y}_i = \begin{bmatrix} 1/4 & 0 \\ 0 & 100/99 \end{bmatrix}^i \vec{y}_0$$

$$= \begin{bmatrix} (1/4)^i 2 \\ (100/99)^i 3 \end{bmatrix}.$$

So for Backward Euler's method, the first component is  $(1/4)^i 2$ , which does decrease in  $i$ .

[Note! The above is an example of a "stiff ODE", where backward

Euler does better than forward Euler. ]