

Uninformed Search Strategies

CPSC 322 - Search 2

January 14, 2011

Textbook §3.5

Discussion of feedback

- Printed lecture slides

30+, 2- (“waste of paper”)

- Example for decision theory:

- Utility = - (#sheets of paper used), want to maximize utility
- Action A = “I print lecture notes”
- Action B = “Student prints lecture notes at home”
- Variable D = “Student has double-sided printer at home”, $P(D) \approx 0.4$
- $U(A) = -3$
- $U(B) = -3 * P(D) + (-6) * P(\text{not } D) \approx -0.4 * (-3) + 0.6 * (-6) = -4.8$

- Conclusion: A is much better than B

- Only counting students who would o/w print themselves
- But most others would otherwise print when studying for midterm/exam
- ...

Discussion of feedback

- Examples: unanimous good
25+, 10- “more examples”, 3- “more real-world examples”
- Videos: unanimous good
Please send me any cool videos you find during the course
- Coloured cards: unanimous helpful
23+, 3- “even more, please”
2- “most of us have clickers”, 3+ “thanks for NOT using clickers”

Discussion of feedback

- Most negative point: definitions sometimes unclear (6-)
 - In the intro I was sometimes vague
 - Some concepts weren't too clear-cut
 - Trying to categorize AI research is not math
 - Starting with the search module, I hope definitions get more crisp
 - First crisp definitions, then examples ...
- Similarly: “missing math and algorithmic parts” (3-)
 - Those should be coming up
- Pace:
 - 5: “too slow”, 8: “good”, 0: “too fast”
 - I'll speed up a tiny bit (should naturally happen after intro is over)
- Speaking: 1 “too slow”, 1 “too fast”, I'll keep it as is

Discussion of feedback

- Which concepts are the important ones?
 - First 3 lectures only to frame & organize rest of course
 - Last lecture was important (all search algos depend on it)
 - Learning goals cover the most important parts
- Extra slide with answer to m/c question:
 - Sorry, defies the purpose a bit
- Expectations & hints how the midterm will look like
 - I put a sample midterm in WebCT (just to see the type of questions)
 - Again, see learning goals
- “Watch for hands more” (1-)
 - Help me out if I’m blind, I really encourage questions!
- Powerpoint slides incompatible “.pptx”: now .ppt

Today's Lecture

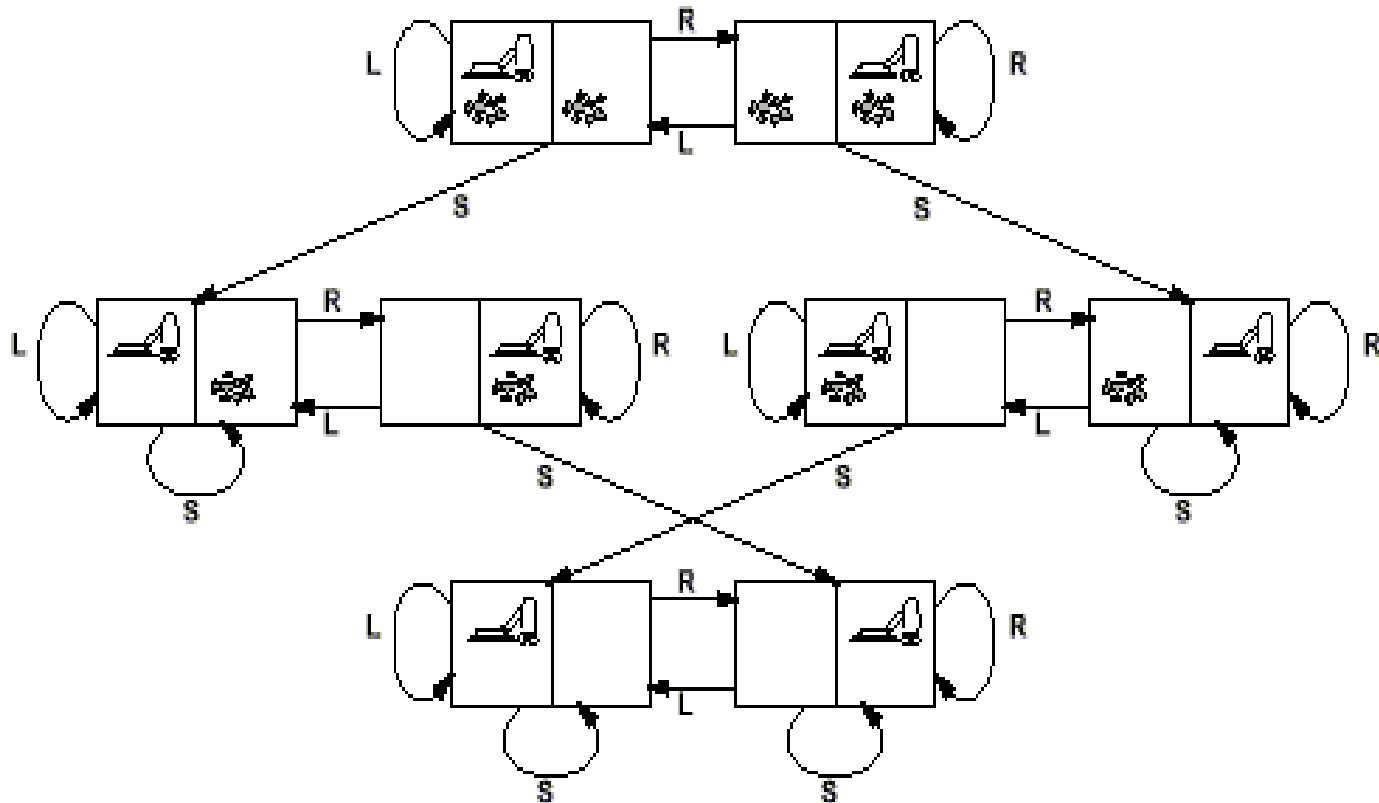
Lecture 4 Recap

- Uninformed search + criteria to compare search algorithms
 - Depth first
 - Breadth first

Recap

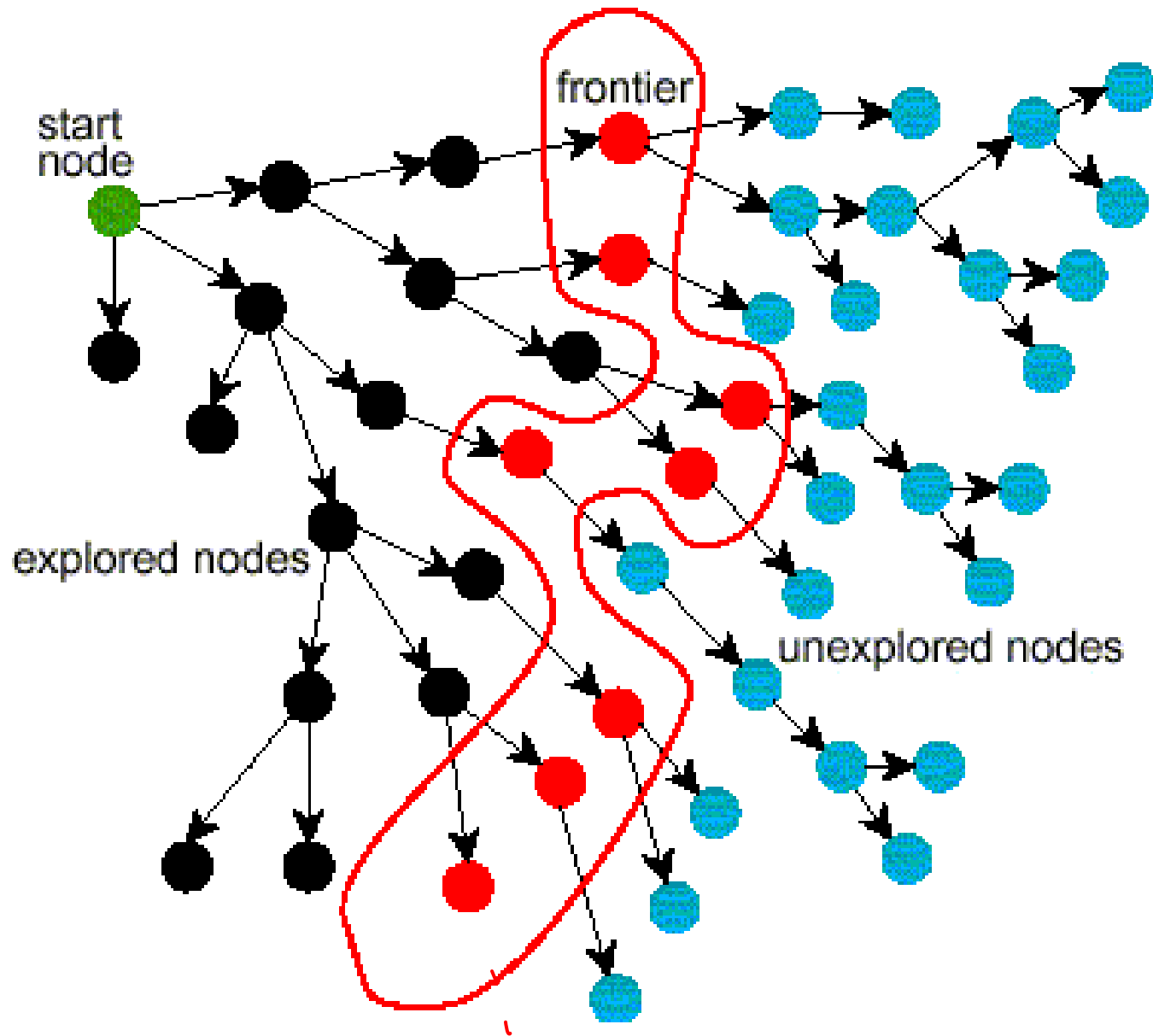
- Search is a key computational mechanism in many AI agents
- We will study the basic principles of search on the simple **deterministic goal-driven search agent model**
- Generic search approach:
 - Define a search space graph
 - Initialize the **frontier** with an empty path
 - incrementally expand frontier until goal state is reached
- Frontier:
 - The set of paths which could be explored next
- The way in which the frontier is expanded defines the search strategy

Search Space Graph: example



- **Operators** – *left, right, suck*
 - Successor states in the graph describe the effect of each action applied to a given state
- **Possible Goal** – no dirt

Problem Solving by Graph Searching



Bogus version of Generic Search Algorithm

Input: a graph

a set of start nodes

Boolean procedure $goal(n)$ that tests if n is a goal node

frontier:= [$\langle g \rangle$: g is a goal node];

While frontier is not empty:

select and **remove** path $\langle n_o, \dots, n_k \rangle$ from frontier;

If $goal(n_k)$

return $\langle n_o, \dots, n_k \rangle$;

Find a neighbor n of n_k

add $\langle n \rangle$ to frontier;

end

- There are a couple of bugs in this version here: help me find them!

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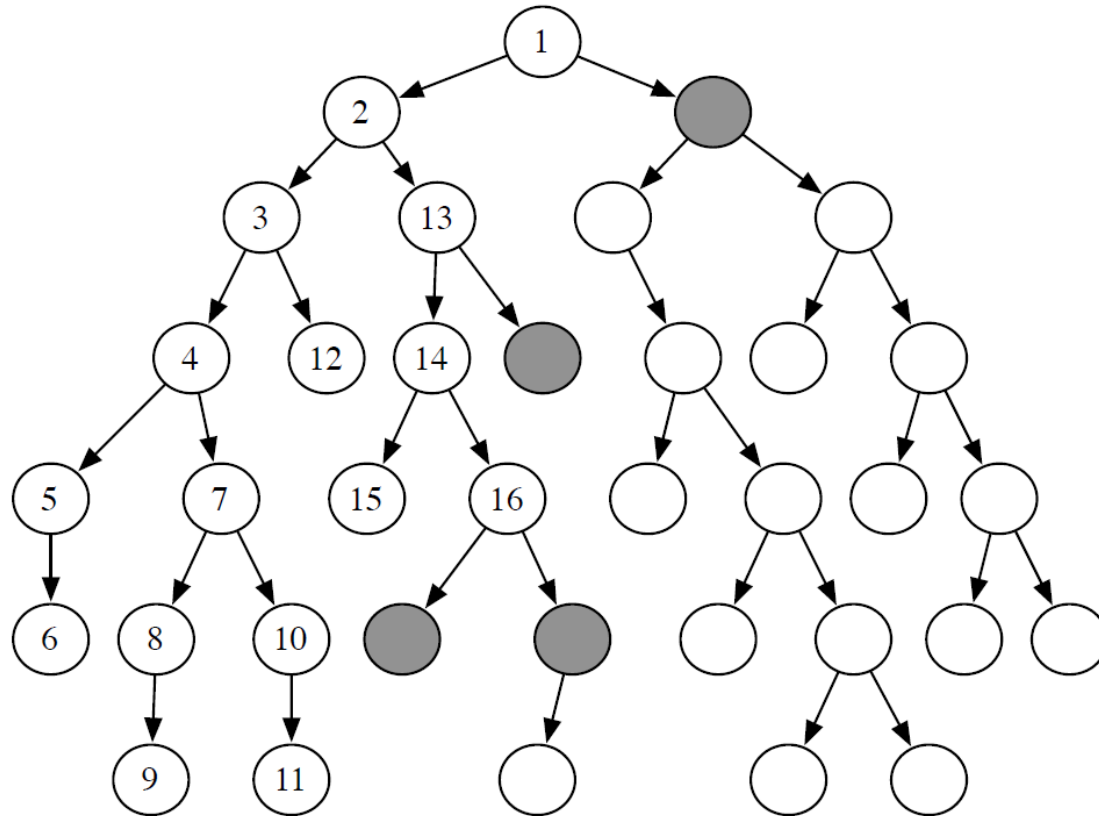
end

- Start at the **start** node(s)
- Add **all** neighbours of n_k to the frontier
- Add **path(s)** to frontier, NOT just the node(s)

Today's Lecture

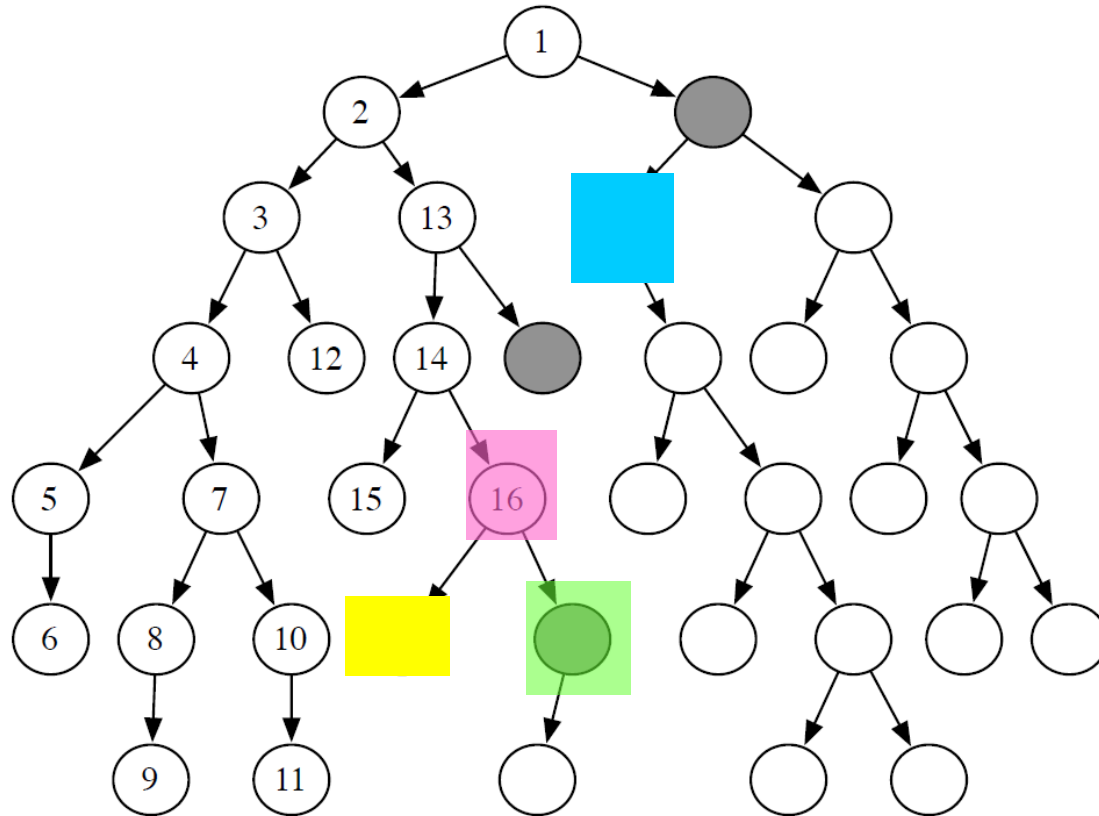
- Lecture 4 Recap
- ➔ Uninformed search + criteria to compare search algorithms
 - Depth first
 - Breadth first

Depth first search (DFS)



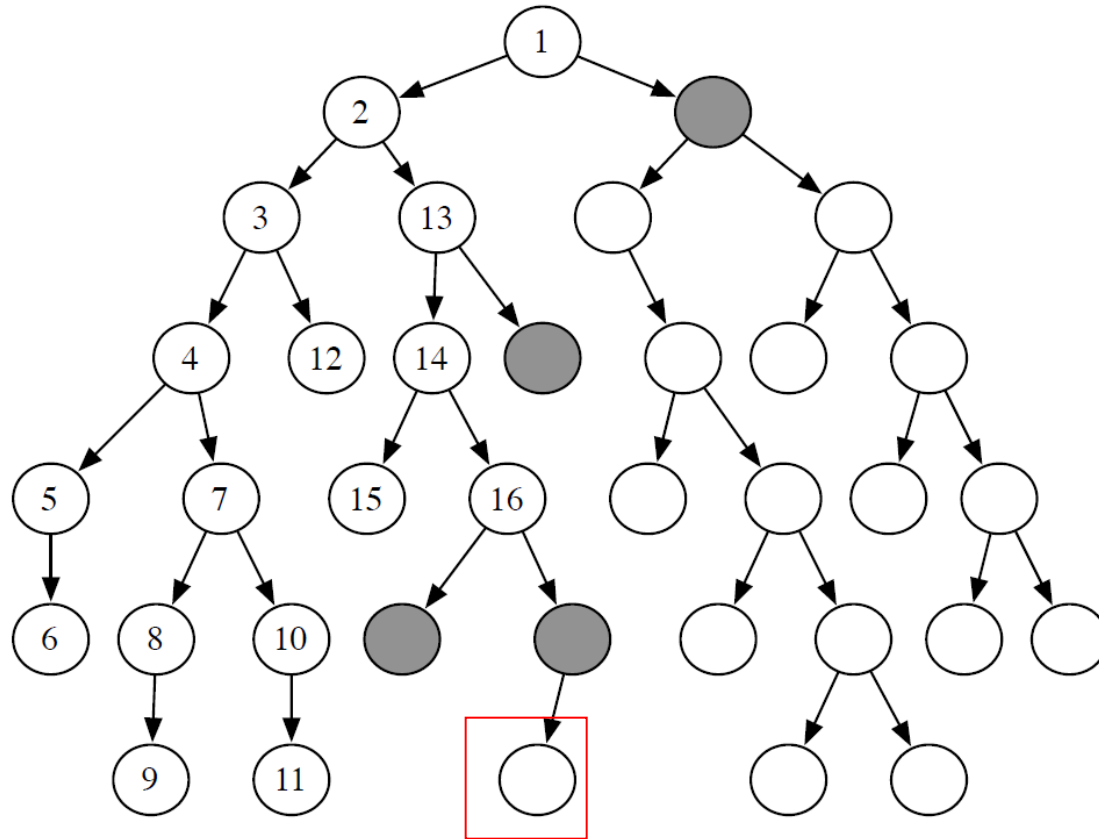
- Frontier: shaded nodes

Depth first search (DFS)



- Frontier: shaded nodes
- Which node will be expanded next?
(expand = “remove node from frontier & put its successors on”)

Depth first search (DFS)



- Say, node in red box is a goal
- How many more nodes will be expanded?

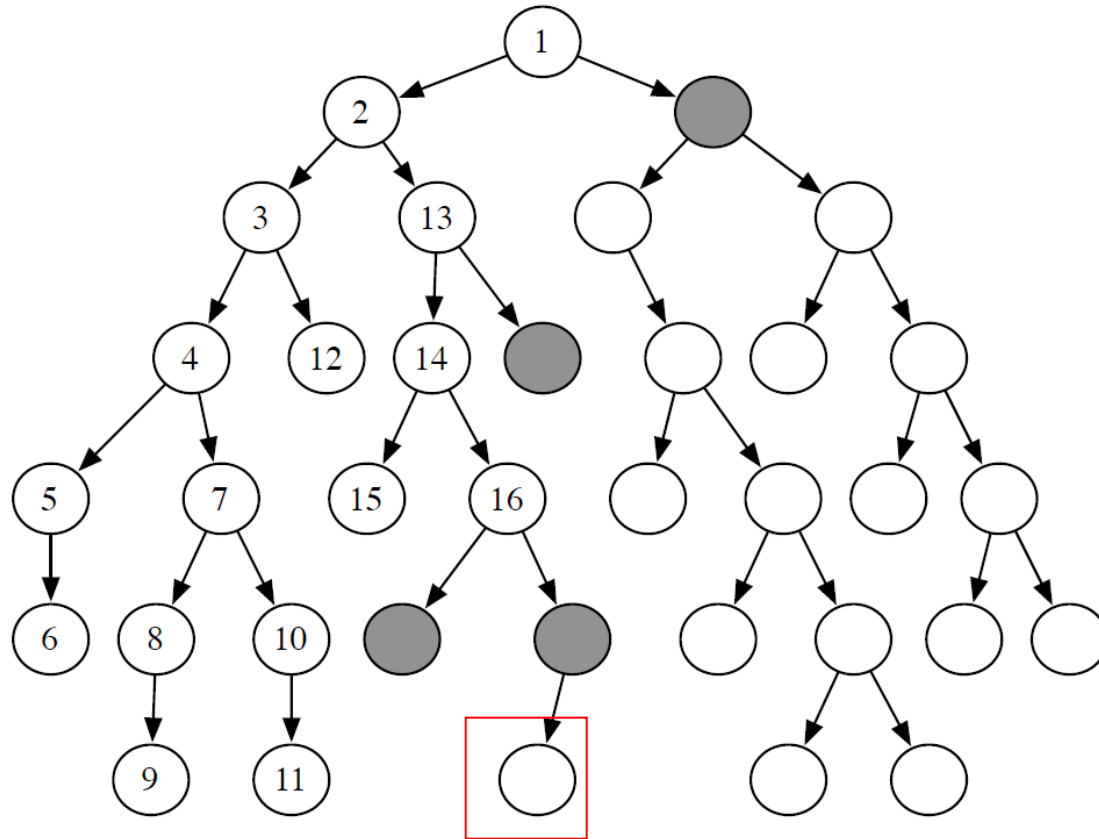
1

2

3

4

Depth first search (DFS)



- Say, node in red box is a goal
- How many more nodes will be expanded?
 - 3: you only return once the goal is being expanded!
 - Not once a goal is put onto the frontier!

DFS as an instantiation of the Generic Search Algorithm

Input: a graph

a set of start nodes

Boolean procedure $goal(n)$

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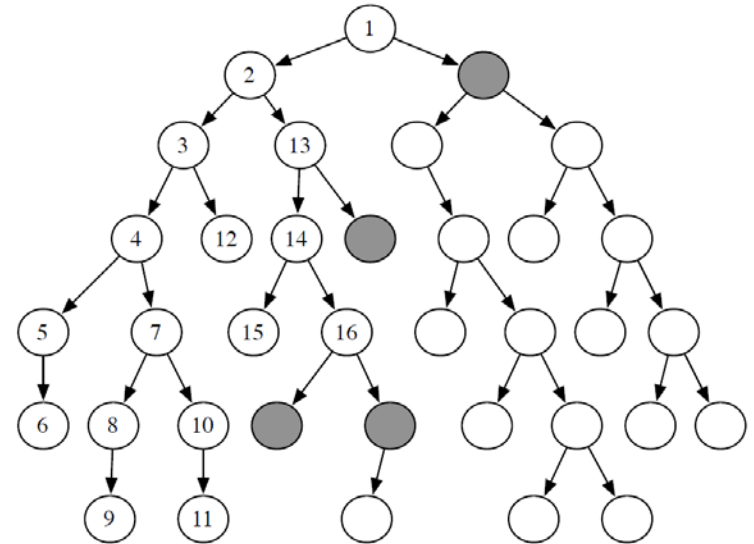
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Else

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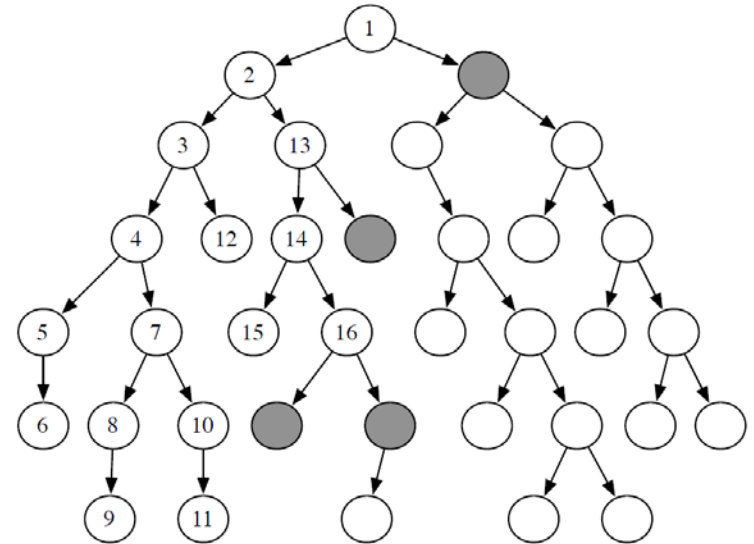
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In DFS, the frontier is a
last-in-first-out stack

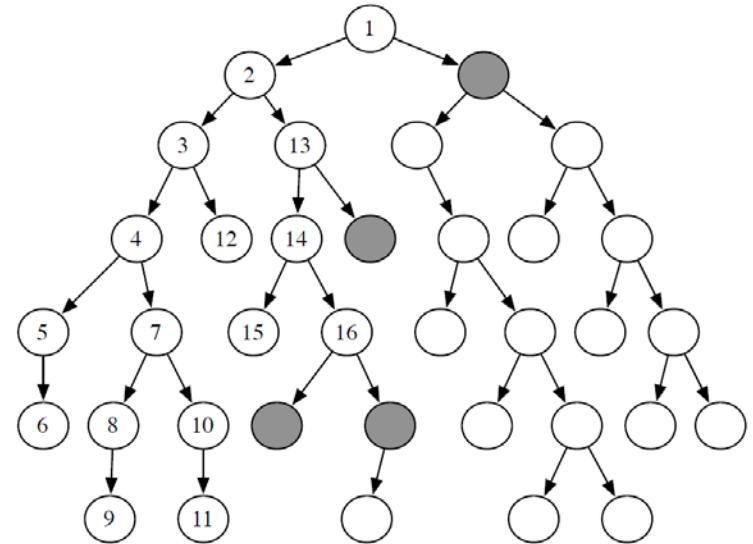
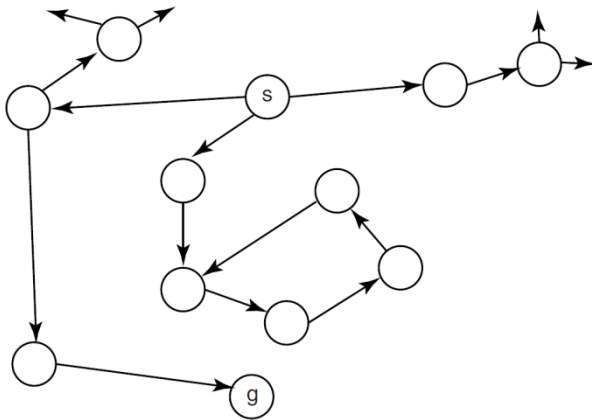
Analysis of DFS

Def. : A search algorithm is **complete** if whenever there is at least one solution, the algorithm **is guaranteed to find it** within a finite amount of time.

Is DFS **complete**?

Yes

No



Analysis of DFS

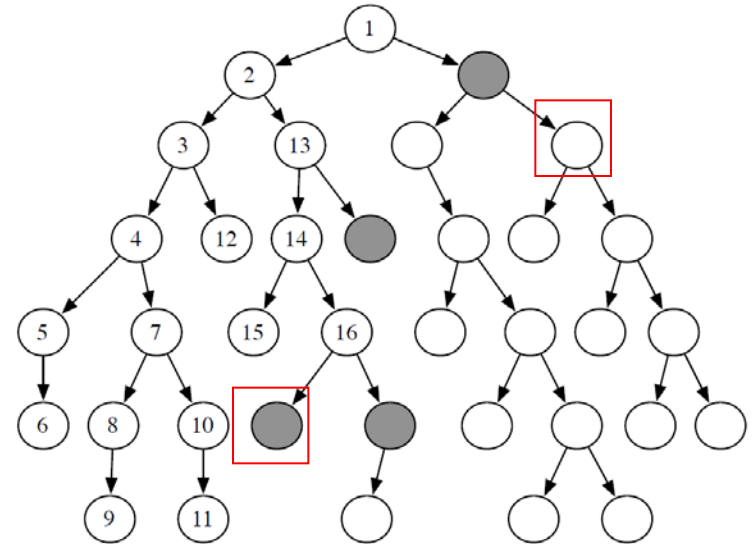
Def.: A search algorithm is **optimal** if
when it finds a solution, it is **the best one**

Is DFS **optimal**?

Yes

No

- E.g., goal nodes: red boxes



Analysis of DFS

Def.: The **time complexity** of a search algorithm is the **worst-case** amount of time it will take to run, expressed in terms of

- maximum path length m
- maximum forward branching factor b .

- What is DFS's **time complexity**, in terms of m and b ?

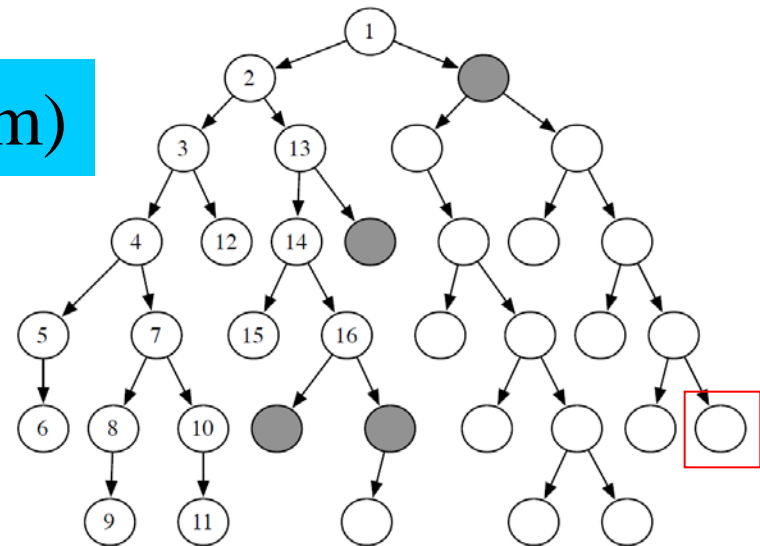
$O(b^m)$

$O(m^b)$

$O(bm)$

$O(b+m)$

- E.g., single goal node: red box



Analysis of DFS

Def.: The **space complexity** of a search algorithm is the **worst-case** amount of memory that the algorithm will use (i.e., the maximal number of nodes on the frontier), expressed in terms of

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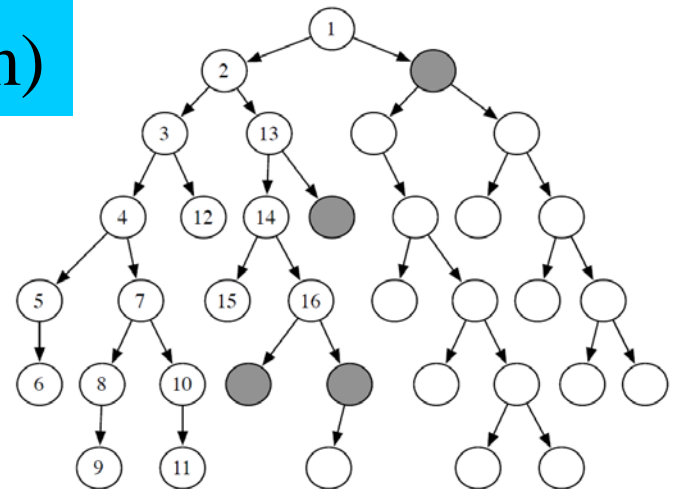
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- $O(bm)$
- The longest possible path is m , and for every node in that path must maintain a fringe of size b



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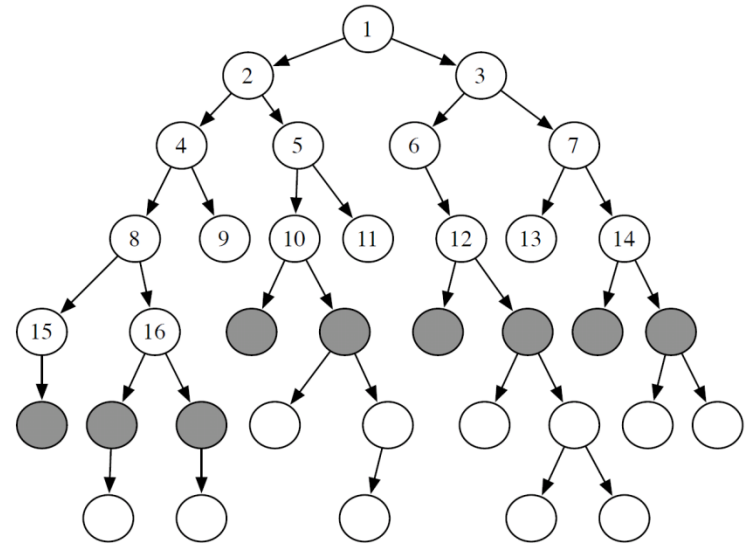
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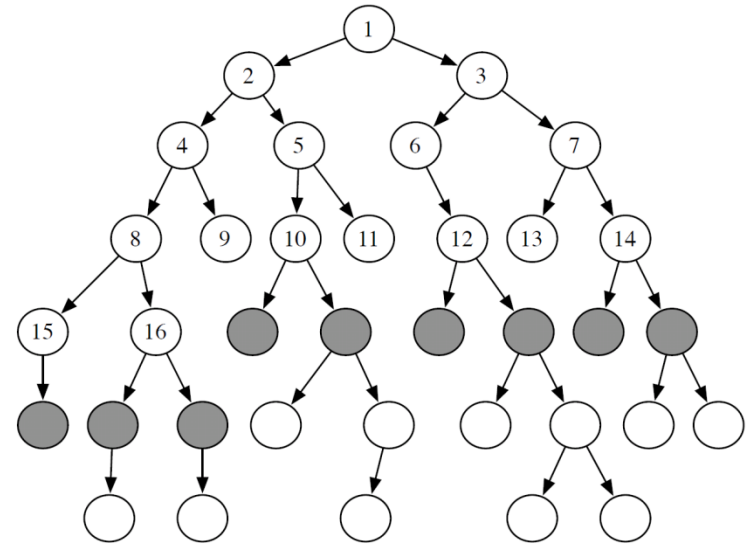
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In BFS, the frontier is a
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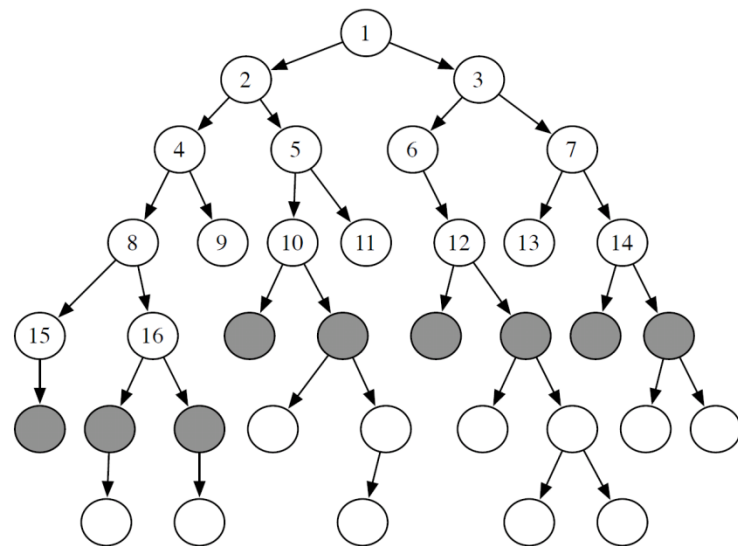
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- Proof sketch?

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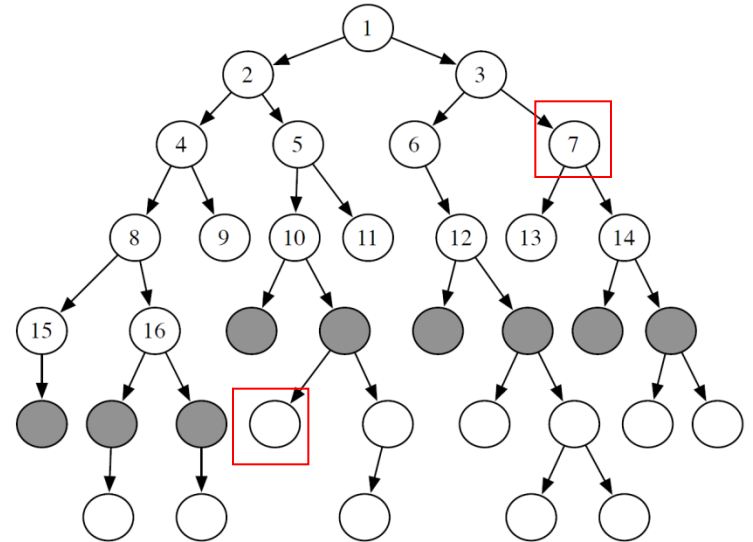
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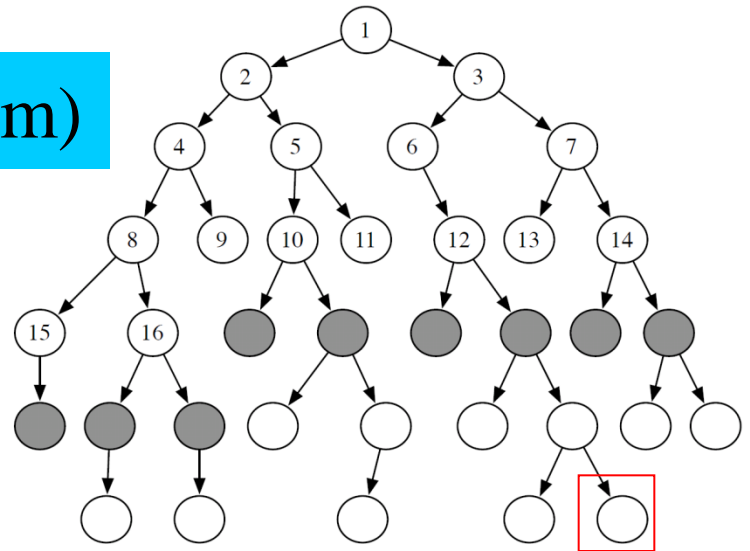
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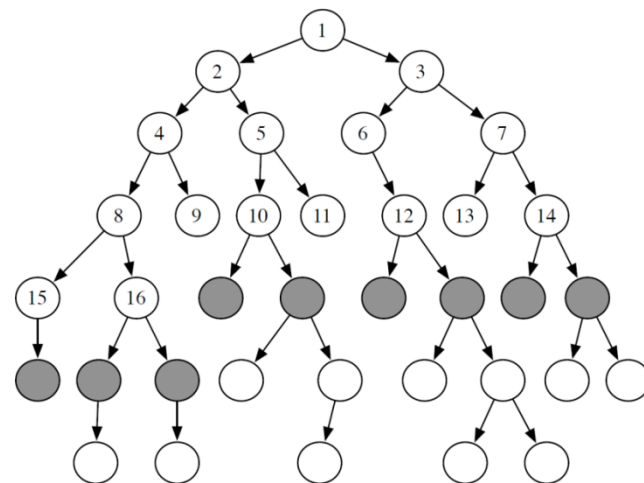
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- How many nodes at depth m ?



When to use BFS vs. DFS?

- The search graph has cycles or is infinite

BFS

DFS

- We need the shortest path to a solution

BFS

DFS

- There are only solutions at great depth

BFS

DFS

- There are some solutions at shallow depth: the other one

- No way the search graph will fit into memory

BFS

DFS

Real Example: Solving Sudoku

Sudoku Puzzle

	9	3	6	2	8	1	4	
	6						5	
	3			1			9	
	5		8		2		7	
	4			7			6	
	8						3	
	1	7	5	9	3	4	2	

- E.g. start state on the left
- Operators:
fill in an allowed number
- Solution: all numbers filled in,
with constraints satisfied
- Which method would you
rather use?

BFS

DFS

Real Example: Eight Puzzle. DFS or BFS?

5	4	
6	1	8
7	3	2

1	2	3
8		4
7	6	5

- Which method would you rather use?

BFS

DFS

Learning Goals for today's class

- Apply basic properties of search algorithms:
 - completeness
 - optimality
 - time and space complexity of search algorithms
- Select the most appropriate search algorithms for specific problems.
 - Depth-First Search vs. Breadth-First Search

Coming up ...

- I am away all next week
 - AI conference in Rome: Learning and Intelligent Optimization
 - I will check email regularly
- All classes will happen. TAs will teach:
 - Monday: Mike (including **demo of AIspace** search applet)
 - Wednesday: Vasanth (including lots more **Infinite Mario**)
 - Friday: Mike (including a proof of the optimal search algorithm)
- First practice exercise online - see **assessments** from WebCT Vista
 - Covers paths, frontier, BFS and DFS
 - Tracing algorithms as in there is the first question in assignment 1
- Read section 3.6