

Nonlinear Preconditioning: How to use a Nonlinear Schwarz Method to Precondition Newton's method

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Outline

How to build a non-linear Schwarz method

Comparison of ASPIN and RASPEN

Two Level Variants of RASPEN and ASPIN

Numerical results

Classical vs. new approaches for non linear problems

Ideas for solving a non-linear problem $F(u) = 0$: use domain decomposition to solve the Jacobian equation in a Newton's method \Rightarrow Newton-Krylov-Schwarz methods (Cai 1994, 1998).

Alternatively we can

- ▶ use the fixed point iteration $u^{n+1} = \mathcal{G}(u^n)$; to accelerate convergence, we can solve instead $\mathcal{F}(u) := \mathcal{G}(u) - u = 0$ with Newton's method.
- ▶ use a non-linear preconditioner called ASPIN introduced by Cai and Keyes (2001, 2002).

A simple example

A one dimensional non-linear model problem

$$\begin{aligned}\mathcal{L}(u) &= f, & \text{in } \Omega &:= (0, L), \\ u(0) &= 0, \\ u(L) &= 0,\end{aligned}\tag{1}$$

where $\mathcal{L}(u) = -\partial_x((1 + u^2)\partial_x u)$. Two overlapping subdomains $\Omega_1 := (0, \beta)$ and $\Omega_2 := (\alpha, L)$, $\alpha < \beta$

$$\begin{aligned}\mathcal{L}(u_1^n) &= f, & \text{in } \Omega_1 &:= (0, \beta), \\ u_1^n(0) &= 0, \\ u_1^n(\beta) &= u_2^{n-1}(\beta), \\ \mathcal{L}(u_2^n) &= f, & \text{in } \Omega_2 &:= (\alpha, L), \\ u_2^n(\alpha) &= u_1^{n-1}(\alpha), \\ u_2^n(L) &= 0.\end{aligned}\tag{2}$$

Main idea for a simple problem

Global approximate solution, by glueing the approximate solutions together.

$$u^n(x) := \begin{cases} u_1^n(x) & \text{if } 0 \leq x < \frac{\alpha+\beta}{2}, \\ u_2^n(x) & \text{if } \frac{\alpha+\beta}{2} \leq x \leq L, \end{cases} \quad (3)$$

which induces two extension operators \tilde{P}_i

$$u^n = \tilde{P}_1 u_1^n + \tilde{P}_2 u_2^n$$

Acceleration by a Newton method

Let the local solutions in the subdomains be

$$u_1^n = G_1(u^{n-1}), \quad u_2^n = G_2(u^{n-1}), \quad (4)$$

\Rightarrow the classical parallel Schwarz method can be written in compact form

$$\boxed{u^n = \sum_{i=1}^l \tilde{P}_i G_i(u^{n-1}) =: \mathcal{G}_1(u^{n-1})} \quad (5)$$

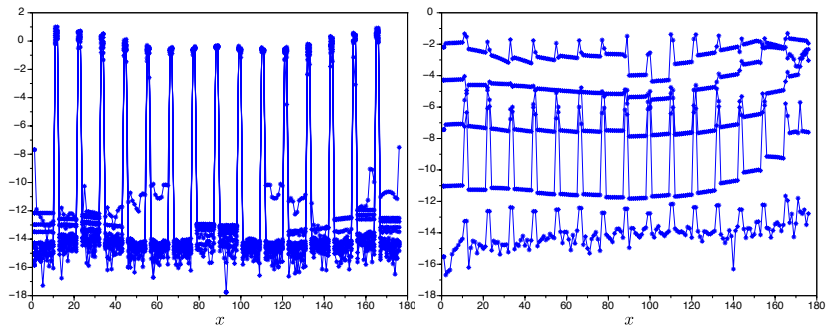
This fixed point iteration can be used as a preconditioner for Newton's method, which means to apply Newton's method to the non-linear equation

$$\tilde{\mathcal{F}}_1(u) := \mathcal{G}_1(u) - u = \sum_{i=1}^l \tilde{P}_i G_i(u) - u = 0, \quad (6)$$

We call this method **one level RASPEN** (Restricted Additive Schwarz Preconditioned Exact Newton).

Simple tests

Forchheimer equation with 8 subdomains.



FigRAS used as a nonlinear solver, or as a preconditioner for Newton's method

The nonlinear RAS method decreases the residual only slowly at interfaces but makes it zero within the subdomains.

Comparison of ASPIN and RASPEN

Consider $F : V \rightarrow V$, V - Hilbert vector space, and the non-linear problem

$$\text{find } u \in V \text{ such that } F(u) = 0. \quad (7)$$

Let V_i be Hilbert vector spaces. Let the linear restriction and prolongation operators

$$R_i : V \rightarrow V_i, \quad P_i : V_i \rightarrow V, \quad i = 1, \dots, l$$

as well as the “restricted” prolongation \tilde{P}_i

$$\tilde{P}_i : V_i \rightarrow V.$$

Assumption Assume R_i and P_i satisfy for $i = 1, \dots, l$

$$R_i P_i = I_{V_i}, \quad \text{the identity on } V_i$$

and that R_i and \tilde{P}_i satisfy

$$\boxed{\sum_{i=1}^l \tilde{P}_i R_i = I_V}$$

Formulation of ASPIN and RASPEN

Define the local inverse $G_i : V \rightarrow V_i$ to be solutions of

$$R_i F(P_i G_i(u) + (I - P_i R_i)u) = 0, \quad (8)$$

Then, **one level RASPEN** solves the non-linear equation

$$\boxed{\tilde{\mathcal{F}}_1(u) = \sum_{i=1}^I \tilde{P}_i G_i(u) - u} \quad (9)$$

using Newton's method. The preconditioned nonlinear function (9) corresponds to the fixed point iteration

$$\boxed{u^n = \sum_{i=1}^I \tilde{P}_i G_i(u^{n-1})} \quad (10)$$

Formulation of ASPIN and RASPEN

For $u \in V$ define the corrections $C_i(u) \in V_i$ such that

$$R_i F(u + P_i C_i(u)) = 0, \quad i = 1, \dots, l. \quad (11)$$

where

$$G_i(u) = R_i u + C_i(u).$$

Then, the one level ASPIN is

$$\mathcal{F}_1(u) = \sum_{i=1}^l P_i C_i(u) = \sum_{i=1}^l P_i G_i(u) - \sum_{i=1}^l P_i R_i u \quad (12)$$

This corresponds to the non-linear fixed point iteration

$$u^n = u^{n-1} - \sum_{i=1}^l P_i R_i u^{n-1} + \sum_{i=1}^l P_i G_i(u^{n-1}) \quad (13)$$

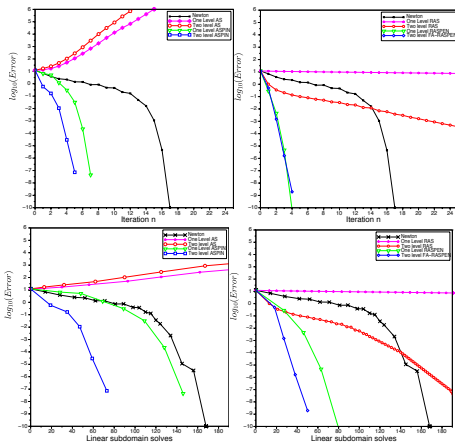
ASPIN vs. RASPEN

Remarks:

- ▶ The iterative version of ASPIN is not convergent in the overlap, and needs a relaxation parameter to yield convergence for the non-linear case.
- ▶ The use of restricted extension makes the RASPEN iterative method convergent.
- ▶ The only interest in the additive correction in the overlap is that in the linear case for a symmetric problem, the preconditioner remains symmetric.

Numerical comparison

Forchheimer equation on a domain of unit size, 8 subdomains, $h = 1/100$.



Jacobian matrices ASPIN/RASPEN

Denote by

$$u^{(i)} := P_i G_i(u) + (I - P_i R_i)u \quad \text{and} \quad J(v) := \frac{dF}{du}(v) \quad (14)$$

By differentiating the subdomain solves we get

$$\frac{dG_i}{du}(u) = -(R_i J(u^{(i)}) P_i)^{-1} R_i J(u^{(i)}) + R_i.$$

Jacobian of RASPEN

$$\boxed{\frac{d\tilde{\mathcal{F}}_1}{du}(u) = \sum_{i=1}^l \tilde{P}_i \frac{dG_i}{du}(u) - I = - \sum_{i=1}^l \tilde{P}_i (R_i J(u^{(i)}) P_i)^{-1} R_i J(u^{(i)})} \quad (15)$$

Similarly, for ASPEN we get

$$\boxed{\frac{d\mathcal{F}_1}{du}(u) = \sum_{i=1}^l P_i \frac{dG_i}{du}(u) - \sum_{i=1}^l P_i R_i = - \sum_{i=1}^l P_i (R_i J(u^{(i)}) P_i)^{-1} R_i J(u^{(i)})} \quad (16)$$

In ASPIN, this exact Jacobian is replaced by the inexact Jacobian

$$\frac{d\mathcal{F}_1^{inexact}}{du}(u) = - \left(\sum_{i=1}^I P_i (R_i J(u) P_i)^{-1} R_i \right) J(u).$$

Remarks:

- ▶ The inexact Jacobian corresponds to the Jacobian $J(u)$ of $F(u)$ preconditioned by the restricted additive Schwarz preconditioner, up to the minus sign.
- ▶ The exact Jacobian is however also easily accessible, since the non linear Newton solver for the non linear subdomain system $R_i F(P_i G_i(u) + (I - P_i R_i)u) = 0$ already computes the Jacobian matrix $R_i J(u^{(i)}) P_i$.
- ▶ It suffices to compute instead the matrix $R_i J(u^{(i)})$ for each non linear subdomain system to easily obtain the exact Jacobian of \mathcal{F}_1 .

Coarse spaces for RASPEN and ASPIN

Let V_0 and the linear restriction and prolongation operators

$$R_0 : V \rightarrow V_0 \quad \text{and} \quad P_0 : V_0 \rightarrow V. \quad (17)$$

We introduce a projection operator in the residual space

$$\tilde{R}_0 : V' \rightarrow V'_0. \quad (18)$$

Let $F_0 : V_0 \rightarrow V_0$ be the coarse non-linear function,

$$F_0(u_0) = \tilde{R}_0 F(P_0(u_0)). \quad (19)$$

Let the coarse solution for two level ASPIN be $u_0^* \in V_0$, i.e. $F_0(u_0^*) = 0$.

Coarse correction in two-level ASPIN

The coarse correction $C_0^A : V \rightarrow V_0$ is defined by

$$F_0(C_0^A(u) + u_0^*) = -\tilde{R}_0 F(u), \quad (20)$$

and the associated two level ASPIN function uses the coarse correction in an additive fashion, i.e. Newton's method is used to solve

$$\mathcal{F}_2(u) = P_0 C_0^A(u) + \sum_{i=1}^I P_i C_i(u) = 0. \quad (21)$$

This corresponds to the non-linear two level fixed point iteration

$$u^{n+1} = u^n + P_0 C_0^A(u^n) + \sum_{i=1}^I P_i C_i(u^n)$$

which is not convergent without relaxation parameter and also slows down the Newton solver.

Coarse correction in two-level FAS-RASPEN

Use the well established non-linear coarse correction $C_0(u)$ from the full approximation scheme

$$F_0(C_0(u) + R_0 u) = F_0(R_0 u) - \tilde{R}_0 F(u). \quad (22)$$

This gives a different coarse correction from ASPIN and this coarse correction is used in a multiplicative fashion in RASPEN, i.e. we solve with Newton the preconditioned non-linear system

$$\tilde{\mathcal{F}}_2(u) = P_0 C_0(u) + \sum_{i=1}^n \tilde{P}_i C_i(u + P_0 C_0(u)) = 0. \quad (23)$$

This corresponds to the non-linear two level fixed point iteration

$$u^{n+1} = u^n + P_0 C_0(u^n) + \sum_{i=1}^n \tilde{P}_i C_i(u^n + P_0 C_0(u^n))$$

This iteration is convergent.

Forchheimer model

Let the Forchheimer parameter $\beta > 0$, the permeability $\lambda \in L^\infty(\Omega)$ such that $0 < \lambda_{\min} \leq \lambda(x) \leq \lambda_{\max}$ for all $x \in \Omega$, and the function

$q(g) = \operatorname{sgn}(g) \frac{-1 + \sqrt{1 + 4\beta|g|}}{2\beta}$. The Forchheimer model on the interval $\Omega = (0, L)$ is defined by the equation

$$\begin{cases} (q(-\lambda(x)u(x)'))' = f(x) & \text{in } \Omega, \\ u(0) = u_0^D, \\ u(L) = u_L^D. \end{cases} \quad (24)$$

Note that at the limit when $\beta \rightarrow 0^+$, we recover the linear Darcy equation.

Notations

Each Newton iteration requires two major steps:

1. Evaluation of the fixed point function \mathcal{F} \rightarrow solving a non-linear problem in each subdomain \rightarrow maximum number of inner iterations needed by the subdomains at the outer iteration j : ls_j^{in} .
2. The Jacobian matrix needs to be inverted (GMRES) \rightarrow a linear subdomain solve per subdomain per GMRES iteration \rightarrow the number of linear solves needed by GMRES at the outer Newton iteration step j : ls_j^G .

The total number of linear subdomain solves after n outer Newton iterations

$$LS_n := \sum_{j=1}^n (ls_j^{in} + ls_j^G)$$

- ▶ PIN \rightarrow outer Newton iterations for ASPIN
- ▶ PEN \rightarrow outer Newton iterations for RASPEN.

Test case: a smooth vs a non smooth example

- ▶ $\Omega = (0, 1)$, boundary conditions $u(0) = 0$ and $u(1) = 1$, $\beta = 1$.
- ▶ Linear stopping criterion for GMRES: 10^{-8} , non linear stopping criteria for the inner and outer Newton iterations: 10^{-8} .
- ▶ Smooth example: $\lambda(x) = \cos x$, $f(x) = \cos x$.

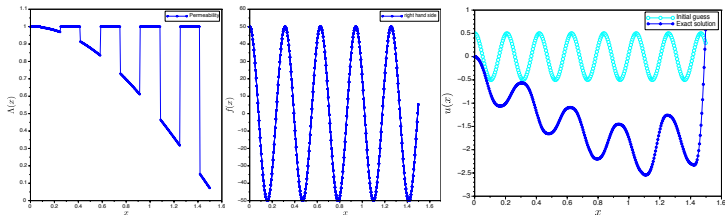


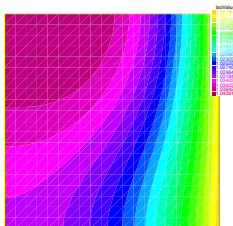
Fig Non smooth example: $\lambda(x)$ (left), $f(x)$ (middle), initial guess/solution (right).

ASPIN						
No of domains	10		20		40	
Iter type						
Overlap	PIN	LS_n	PIN	LS_n	PIN	LS_n
h	5	118	5	228	6	520
3h	5	118	5	227	6	516
5h	5	117	5	222	6	480
RASPEN						
No of domains	10		20		40	
Iter type						
Overlap	PEN	LS_n	PEN	LS_n	PEN	LS_n
h	4	92	4	172	4	340
3h	4	87	4	172	4	331
5h	4	88	4	168	4	313
Two level ASPIN						
No of domains	10		20		40	
Iter type						
Overlap	PIN	LS_n	PIN	LS_n	PIN	LS_n
h	5	140	5	240	5	280
3h	5	130	6	170	6	200
5h	5	115	7	149	6	147
Two level FAS RASPEN						
No of domains	10		20		40	
Iter type						
Overlap	PEN	LS_n	PEN	LS_n	PEN	LS_n
h	4	77	3	87	4	131
3h	3	60	3	67	4	90
5h	3	55	3	57	3	57

ASPIN						
No. of domains	10		20		40	
Overlap \ Iter type	PIN	LS_n	PIN	LS_n	PIN	LS_n
	h	8	184	15	663	-
3h	7	156	14	631	11	883
5h	6	130	11	479	10	744
RASPEN						
No of domains	10		20		40	
Overlap \ Iter type	PEN	LS_n	PEN	LS_n	PEN	LS_n
	h	7	150	9	369	9
3h	7	145	8	324	9	691
5h	6	126	7	274	9	659
Two-level ASPIN						
No of domains	10		20		40	
Overlap \ Iter type	PIN	LS_n	PIN	LS_n	PIN	LS_n
	h	7	184	9	316	8
3h	6	141	9	246	7	183
5h	6	135	8	199	7	164
Two-level FAS-RASPEN						
No of domains	10		20		40	
Overlap \ Iter type	PEN	LS_n	PEN	LS_n	PEN	LS_n
	h	7	134	9	272	8
3h	7	133	8	220	6	136
5h	6	112	8	211	6	116

Two-dimensional examples

A non-linear diffusion problem discretised by P1 finite elements on a uniform triangular mesh (computations using FreeFEM++)



$$\left\{ \begin{array}{l} -\nabla \cdot ((1 + u^2)\nabla u) = f, \quad \Omega = [0, 1]^2, \\ u = 1, \quad x = 1, \\ \frac{\partial u}{\partial \mathbf{n}} = 0, \quad \text{otherwise.} \end{array} \right. \quad (25)$$

Detailed convergence RASPEN vs. ASPIN

- ▶ decomposition into $N \times N$ subdomains with an overlap of one mesh size h
- ▶ number of degrees of freedom per subdomain fixed

$N \times N$	n	1-Level				2-Level			
		l_s^G	l_s^{in}	l_s^{min}	LS_n	l_s^G	l_s^{in}	l_s^{min}	LS_n
2×2	1	15(20)	4(4)	3(3)		13(23)	4(4)	3(3)	
	2	17(23)	3(3)	3(3)	59(78)	15(26)	3(3)	3(3)	54(86)
	3	18(26)	2(2)	2(2)		17(28)	2(2)	2(2)	
4×4	1	32(37)	3(3)	3(3)		18(33)	3(3)	3(3)	
	2	35(41)	3(3)	2(2)	113(132)	22(39)	3(3)	2(2)	74(126)
	3	38(46)	2(2)	2(2)		26(46)	2(2)	2(2)	
8×8	1	62(71)	3(3)	2(2)		18(35)	3(3)	3(2)	
	2	67(77)	3(3)	2(2)	211(240)	23(44)	3(3)	2(2)	77(139)
	3	74(84)	2(2)	1(2)		28(53)	2(2)	2(1)	
16×16	1	125(141)	3(3)	2(2)		18(35)	3(3)	3(2)	
	2	136(155)	2(2)	2(2)	418(471)	23(44)	2(2)	2(2)	75(140)
	3	150(167)	2(2)	1(1)		27(54)	2(2)	2(1)	

⇒ RASPEN clearly outperforms ASPIN (which not convergent as a basic fixed point iteration).

Conclusions

- ▶ accelerate fixed point iterations for non-linear problems using Newton's method → guiding principle for constructing non-linear preconditioners.
- ▶ explore the parallel properties of the RASPEN method on more realistic models and configurations.
- ▶ design of other nonlinear preconditioners (ongoing work) based on non-overlapping decompositions using Neumann-Neumann or Robin-Robin iterations. (application to the Richards equation).

References and acknowledgements

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