

# Thin-Plate Spline Interpolation: Convergence Analysis and H-Matrix Solution Techniques

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Radial basis functions provide a versatile tool for scattered data interpolation. One of the basic questions is the interpolation problem: Given  $N$  data points  $x_i$  with corresponding values  $f_i$ , find the function  $If$  of the form  $If(x) = \sum_{i=1}^N c_i \phi(|x - x_i|) + \pi(x)$  that interpolates the given data  $f_i$  in the points  $x_i$ . One possible choice of the function  $\phi$  is that of polyharmonic splines, i.e.,  $\phi$  is the fundamental solution of the iterated Laplacian  $\Delta^m$ . In the case  $d = 2 = m$ , the function  $\phi$  is the fundamental solution of the biharmonic equation and called thin-plate spline.

Existence, uniqueness, and optimal rates of convergence for quasi-uniformly distributed data points  $x_i$  were established in fundamental papers by Duchon and Meinguet. Convergence here means that the interpolation data  $f_i = f(x_i)$  originate from a function  $f \in H^m(\Omega)$  and the error  $f - If$  is considered. We extend this classical theory to functions  $f \in H^k(\Omega)$  with  $k > m$ . Specifically, we show that optimal convergence rates can be obtained for  $f \in H^k(\Omega)$  in the range  $k \in [m, m + 1/2)$ . Boundary effects limit the achievable convergence in the regime  $k > m + 1/2$ ; however, we show how further improvements in the convergence rate can be obtained by condensing data points  $x_i$  near the boundary. The linear system of equations that describes the interpolation problem is a dense system due to the non-locality of  $\phi$ , which calls for data-sparse techniques. We propose to employ H-matrix techniques, which were introduced by W. Hackbusch in 1999. This data-sparse format allows for compressing the linear system to log-linear storage requirement. More importantly, the H-matrix format comes with an (approximate) arithmetic including factorizations in this format in log-linear complexity, thus opening the door to solving very large interpolation problems.

Numerical examples corroborate the theoretical assertions.

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