## C19 : Unsupervised Machine Learning

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Unsupervised Machine Learning

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## Introduction

- Supervised machine learning (covered by AZ)
  - $\bullet\ = {\sf regression}/{\sf classification} = {\sf conditional\ density}/{\sf distrib.\ estimation}$
  - Requires training pairs; input/output
  - Sometimes "easier"
    - Lower dimensional parameter space (needn't model inputs)
- Unsupervised Machine Learning
  - = dimensionality reduction = joint density estimation
  - Requires data + model
  - Often harder
    - Must model inputs
    - Richer models
  - Many supervised models arrive from conditioning unsupervised models on observed data
    - Conditioning on observed data = fixing values of some variables in joint
  - Inference techniques for unsupervised models automatically work for supervised models

- Understand connection between graphical models and joint distributions
- Be able to "invent" graphical models for problems of interest
- Understand sampling techniques
  - Basic sampling techniques
  - Markov chain Monte Carlo (MCMC)
    - Metropolis Hasting (MH)
    - Gibbs
- Understand how to derive and implement MCMC samplers for arbitrary graphical models
- Understand Monte Carlo integration
- Understand how to formulate inference questions in terms of integrals

• Lecture Notes and Problem Sheet :

http://www.robots.ox.ac.uk/~fwood/teaching/C19\_hilary\_2013\_2014/

- Books :
  - Pattern Recognition and Machine Learning [Bishop, 2007]
  - Bayesian data analysis [Gelman et al., 1995]
  - Machine Learning : a probabilistic perspective [Murphy, 2012]
  - Sequence Monte Carlo Methods in Practice [Doucet et al., 2001]
  - (free online) Information Theory, Inference, and Learning Algorithms [MacKay, 2003]
- Tutorials :
  - Probabilistic Inference using MCMC methods [Neal, 1993]
  - A Tutorial on particle Filters for Online Nonlinear/Non-Gaussian Bayesian Tracking [Arulampalam et al., 2002]

- M Sanjeev Arulampalam, Simon Maskell, Neil Gordon, and Tim Clapp. A Tutorial on Particle Filters for Online Nonlinear / Non-Gaussian Bayesian Tracking. *IEEE Transactions on Signal Processing*, 50(2): 174-188, 2002. ISSN 1053587X. doi: 10.1109/78.978374. URL http://ieeexplore.ieee.org/lpdocs/epic03/wrapper.htm? arnumber=978374.
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