

# CPSC 213

## Introduction to Computer Systems

*Unit 1f*

***Dynamic Control Flow***

***Polymorphism and Switch Statements***

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## Readings for Next Two to Three Lectures

### ► Text

- Switch Statements, Understanding Pointers
  - 2nd ed: 3.6.7, 3.10
  - 1st ed: 3.6.6, 3.11

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# Polymorphism

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## Back to Procedure Calls

### ► Static Method Invocations and Procedure Calls

- target method/procedure address is known statically

### ► in Java

- *static* methods are class methods
  - invoked by naming the class, not an object

```
public class A {  
    static void ping () {}  
}  
  
public class Foo {  
    static void foo () {  
        A.ping ();  
    }  
}
```

### ► in C

- specify procedure name

```
void ping () {}  
  
void foo () {  
    ping ();  
}
```

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# Polymorphism

## ► Invoking a method on an object in Java

- variable that stores the object has a static type
- object reference is dynamic and so is its type
  - object's type must implement the type of the referring variable
  - but object's type may override methods of this base type

## ► Polymorphic Dispatch

- target method address depends on the type of the referenced object
- one call site can invoke different methods at different times

```
class A {  
    void ping () {}  
    void pong () {}  
}
```

```
class B extends A {  
    void ping () {}  
    void wiff () {}  
}
```

```
static void foo (A a) {  
    a.ping (); Which ping gets called?  
    a.pong ();  
}
```

```
static void bar () {  
    foo (new A());  
    foo (new B());  
}
```

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# Polymorphic Dispatch

## ► Method address is determined dynamically

- compiler can not hardcode target address in procedure call
- instead, compiler generates code to lookup procedure address at runtime
- address is stored in memory in the object's class *jump table*

## ► Class Jump table

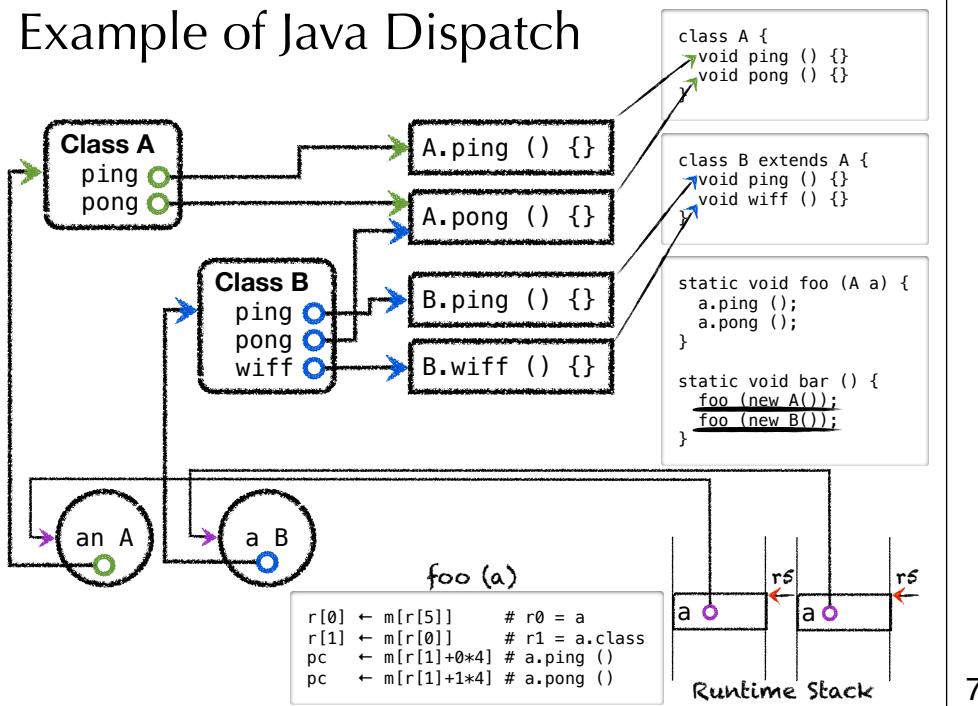
- every class is represented by class object
- the class object stores the class's jump table
- the jump table stores the address of every method implemented by the class
- objects store a pointer to their class object

## ► Static and dynamic of method invocation

- address of jump table is determined dynamically
- method's offset into jump table is determined statically

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# Example of Java Dispatch



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# Dynamic Jumps in C

## Function pointer

- a variable that stores a pointer to a procedure
- declared
  - `<return-type> (*<variable-name>)(<formal-argument-list>);`
- used to make dynamic call
  - `<variable-name> (<actual-argument-list>);`

## Example

```
void ping () {}

void foo () {
    void (*aFunc) ();
    aFunc = ping;
    aFunc (); calls ping
}
```

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# Simplified Polymorphism in C

(SA-dynamic-call.c)

## ► Use a struct to store jump table

- drawing on previous example of A ...

### Declaration of A's jump table and code

```
struct A {  
    void (*ping)();  
    void (*pong)();  
};  
  
void A_ping () { printf ("A_ping\n"); }  
void A_pong () { printf ("A_pong\n"); }
```

### Create an instance of A's jump table

```
struct A* new_A () {  
    struct A* a = (struct A*) malloc (sizeof (struct A));  
    a->ping = A_ping;  
    a->pong = A_pong;  
    return a;  
}
```

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- and B ...

### Declaration of B's jump table and code

```
struct B {  
    void (*ping)();  
    void (*pong)();  
    void (*wiff)();  
};  
  
void B_ping () { printf ("B_ping\n"); }  
void B_wiff () { printf ("B_wiff\n"); }
```

### Create an instance of B's jump table

```
struct B* new_B () {  
    struct B* b = (struct B*) malloc (sizeof (struct B));  
    b->ping = B_ping;  
    b->pong = A_pong;  
    b->wiff = B_wiff;  
    return b;  
}
```

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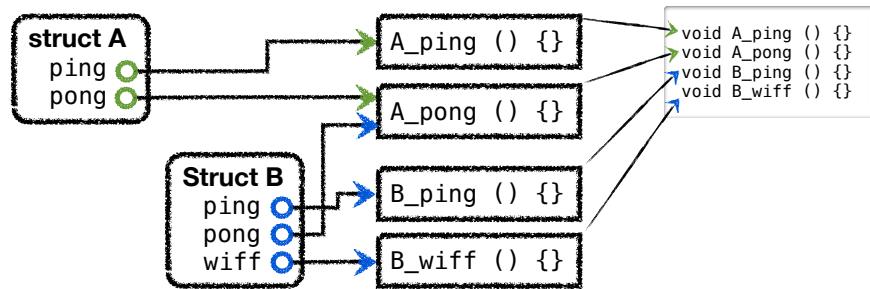
- invoking ping and pong on an A and a B ...

```
void foo (struct A* a) {
    a->ping ();
    a->pong ();
}

void bar () {
    foo (new_A ());
    foo ((struct A*) new_B ());
}
```

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## Dispatch Diagram for C (data layout)



```
struct A {
    void (*ping) ();
    void (*pong) ();
};

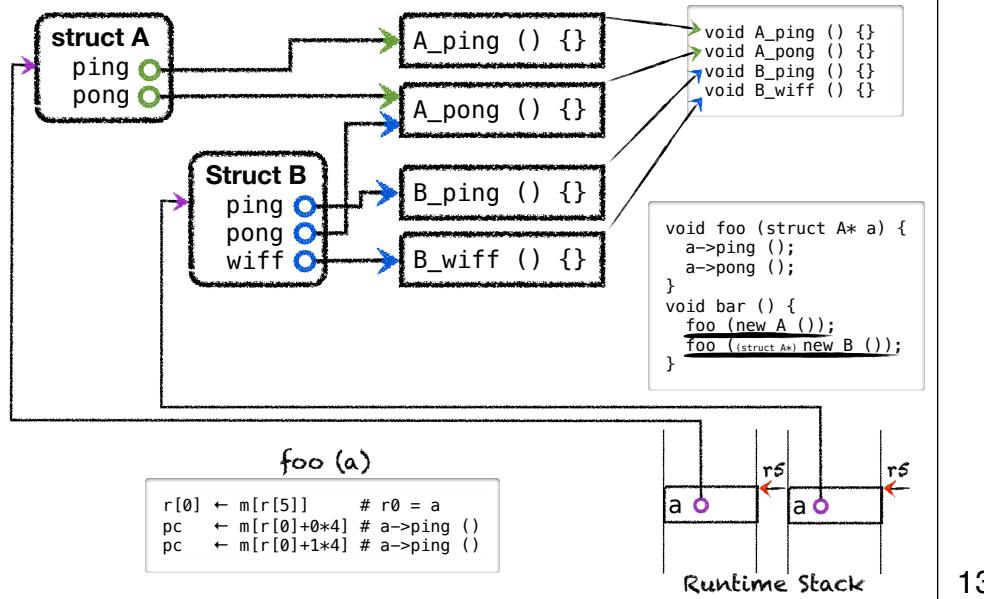
struct A* new_A () {
    struct A* a = (struct A*) malloc (sizeof (struct A));
    a->ping = A_ping;
    a->pong = A_pong;
    return a;
}
```

```
struct B {
    void (*ping)();
    void (*pong)();
    void (*wiff)();
};

struct B* new_B () {
    struct B* b = (struct B*) malloc (sizeof (struct B));
    b->ping = B_ping;
    b->pong = A_pong;
    b->wiff = B_wiff;
    return b;
}
```

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# Dispatch Diagram for C (the dispatch)



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# ISA for Polymorphic Dispatch

```

void foo (struct A* a) {
    a->ping ();
    a->pong ();
}
  
```

```

r[0] ← m[r[5]]      # r0 = a
pc   ← m[r[1]+0*4] # a->ping ()
pc   ← m[r[1]+1*4] # a->pong ()
  
```

► How do we compile

- a->ping () ?

► Pseudo code

- pc ← m[r[1]+0\*4]

► Current jumps supported by ISA

Name	Semantics	Assembly	Machine
jump absolute	pc ← a	j a	b--- aaaaaaaaa
indirect jump	pc ← r[t] + (o==pp*2)	j o(rt)	ctpp

► We will benefit from a new instruction in the is

- that jumps to an address that is stored in memory

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## ► Double-indirect jump instruction (b+o)

- jump to address stored in memory using base+offset addressing

Name	Semantics	Assembly	Machine
<i>jump absolute</i>	$pc \leftarrow a$	j a	b--- aaaaaaaaa
<i>indirect jump</i>	$pc \leftarrow r[t] + (o == pp * 2)$	j o(rt)	c <sub>tpp</sub>
<i>dbl-ind jump b+o</i>	$pc \leftarrow m[r[t] + (o == pp * 4)]$	j *o(rt)	d <sub>tpp</sub>

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## Question 1

### ► What is the difference between these two C snippets?

(1) 

```
void foo () {printf ("foon\n");}
void go(void (*proc)()) {
    proc();
}
go (foo);
```

(2) 

```
void foo () {printf ("foon\n");}
void go() {
    foo();
}
go();
```

- [A] (2) calls foo, but (1) does not
- [B] (1) is not valid C
- [C] (1) jumps to foo using a dynamic address and (2) a static address
- [D] They both call foo using dynamic addresses
- [E] They both call foo using static addresses

Now, implement proc() and foo() assembly code

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# Switch Statements

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## Switch Statement

```
int i;
int j;

void foo () {
    switch (i) {
        case 0: j=10; break;
        case 1: j=11; break;
        case 2: j=12; break;
        case 3: j=13; break;
        default: j=14; break;
    }
}
```

```
void bar () {
    if (i==0)
        j=10;
    else if (i==1)
        j = 11;
    else if (i==2)
        j = 12;
    else if (i==3)
        j = 13;
    else
        j = 14;
}
```

- ▶ Semantics the same as simplified nested if statements

- where condition of each *if* tests the same variable
- unless you leave the *break* the end of the case block

- ▶ So, why bother putting this in the language?

- is it for humans, facilitate writing and reading of code?
- is it for compilers, permitting a more efficient implementation?

- ▶ Implementing switch statements

- we already know how to implement if statements; is there anything more to consider?

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# Human vs Compiler

## ► Benefits for humans

- the syntax models a common idiom: choosing one computation from a set

## ► But, switch statements have interesting restrictions

- case labels must be *static, cardinal* values

- a cardinal value is a *number* that specifies a *position* relative to the beginning of an ordered set
  - for example, integers are cardinal values, but strings are not

- case labels must be compared for equality to a single dynamic expression

- some languages permit the expression to be an inequality

## ► Do these restrictions benefit humans?

- have you ever wanted to do something like this?

```
switch (treeName) {  
    case "larch":  
    case "cedar":  
    case "hemlock":  
}
```

```
switch (i,j) {  
    case i>0:  
    case i==0 & j>a:  
    case i<0 & j==a:  
    default:  
}
```

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# Why Compilers like Switch Statements

## ► Notice what we have

- switch condition evaluates to a number
- each case arm has a distinct number

## ► And so, the implementation has a simplified form

- build a table with the address of every case arm, indexed by case value
- switch by indexing into this table and jumping to matching case arm

## ► For example

```
switch (i) {  
    case 0: j=10; break;  
    case 1: j=11; break;  
    case 2: j=12; break;  
    case 3: j=13; break;  
    default: j=14; break;  
}
```

```
label jumpTable[4] = { L0, L1, L2, L3 };  
if (i < 0 || i > 3) goto DEFAULT;  
goto jumpTable[i];  
L0: j = 10;  
goto CONT;  
L1: j = 11;  
goto CONT;  
L2: j = 12;  
goto CONT;  
L3: j = 13;  
goto CONT;  
DEFAULT:  
j = 14;  
goto CONT;  
CONT:
```

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# Happy Compilers mean Happy People

```
switch (i) {  
    case 0: j=10; break;  
    case 1: j=11; break;  
    case 2: j=12; break;  
    case 3: j=13; break;  
    default: j=14; break;  
}
```

```
label jumpTable[4] = { L0, L1, L2, L3 };  
if (i >3) goto DEFAULT;  
goto jumpTable[i];  
L0: j = 10;  
    goto CONT;  
L1: j = 11;  
    goto CONT;  
L2: j = 12;  
    goto CONT;  
L3: j = 13;  
    goto CONT;  
DEFAULT:  
    j = 14;  
    goto CONT;  
CONT:
```

- ▶ Computation can be much more efficient
  - compare the running time to if-based alternative
- ▶ But, could it all go horribly wrong?
  - construct a switch statement where this implementation technique is a really bad idea
- ▶ Guidelines for writing efficient switch statements

```
if (i==0)  
    j=10;  
else if (i==1)  
    j = 11;  
else if (i==2)  
    j = 12;  
else if (i==3)  
    j = 13;  
else  
    j = 14;
```

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## The basic implementation strategy

- ▶ General form of a switch statement

```
switch (<cond>) {  
    case <label_i>: <code_i>      repeated 0 or more times  
    default:        <code_default> optional  
}
```

- ▶ Naive implementation strategy

```
goto address of code_default if cond > max_label_value  
goto jumptable[label_i]  
  
statically: jumptable[label_i] = address of code_i forall label_i
```

- ▶ But there are two additional considerations

- case labels are not always contiguous
- the lowest case label is not always 0

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# Refining the implementation strategy

## ► Naive strategy

```
goto address of code_default if cond > max_label_value  
goto jumptable[label_i]  
  
statically: jumptable[label_i] = address of code_i forall label_i
```

## ► Non-contiguous case labels

- what is the problem
- what is the solution

```
switch (i) {  
    case 0: j=10; break;  
    case 3: j=13; break;  
    default: j=14; break;  
}
```

## ► Case labels not starting at 0

- what is the problem
- what is the solution

```
switch (i) {  
    case 1000: j=10; break;  
    case 1001: j=11; break;  
    case 1002: j=12; break;  
    case 1003: j=13; break;  
    default: j=14; break;  
}
```

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# Implementing Switch Statements

## ► Choose strategy

- use jump-table unless case labels are sparse or there are very few of them
- use nested-if-statements otherwise

## ► Jump-table strategy

- statically
  - build jump table for all label values between lowest and highest
- generate code to
  - goto default if condition is less than minimum case label or greater than maximum
  - normalize condition to lowest case label
  - use jumptable to go directly to code selected case arm

```
goto address of code_default if cond < min_label_value  
goto address of code_default if cond > max_label_value  
goto jumptable[cond-min_label_value]  
  
statically: jumptable[i-min_label_value] = address of code_i  
forall i: min_label_value <= i <= max_label_value
```

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## Snippet B: In template form

```
switch (i) {  
    case 20: j=10; break;  
    case 21: j=11; break;  
    case 22: j=12; break;  
    case 23: j=13; break;  
    default: j=14; break;  
}  
  
label jumpTable[4] = { L20, L21, L22, L23 };  
if (i < 20) goto DEFAULT;  
if (i > 23) goto DEFAULT;  
goto jumpTable[i-20];  
L20:  
    j = 10;  
    goto CONT;  
L21:  
    j = 11;  
    goto CONT;  
L22:  
    j = 12;  
    goto CONT;  
L23:  
    j = 13;  
    goto CONT;  
DEFAULT:  
    j = 14;  
    goto CONT;  
CONT:
```

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## Snippet B: In Assembly Code

```
foo:    ld    $i, r0      # r0 = &i  
        ld    $0x0(r0), r0    # r0 = i  
        ld    $0xffffffffed, r1 # r1 = -19  
        add   r0, r1          # r0 = i-19  
        bgt   r1, l0          # goto l0 if i>19  
        br    default         # goto default if i<20  
l0:    ld    $0xffffffe9, r1 # r1 = -23  
        add   r0, r1          # r1 = i-23  
        bgt   r1, default     # goto default if i>23  
        ld    $0xfffffec, r1  # r1 = -20  
        add   r1, r0          # r0 = i-20  
        ld    $jmpTable, r1    # r1 = &jmpTable  
        j     *(r1, r0, 4)    # goto jmpTable[i-20]
```

```
case20: ld    $0xa, r1      # r1 = 10  
        br    done            # goto done  
...  
default: ld    $0xe, r1      # r1 = 14  
        br    done            # goto done  
done:   ld    $j, r0          # r0 = &j  
        st    r1, 0x0(r0)      # j = r1  
        br    cont            # goto cont
```

```
jmpTable: .long 0x00000140    # & (case 20)  
          .long 0x00000148    # & (case 21)  
          .long 0x00000150    # & (case 22)  
          .long 0x00000158    # & (case 23)
```

Simulator ...

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# Static and Dynamic Control Flow

## ▶ Jump instructions

- specify a *target address* and a *jump-taken condition*
- target address can be static or dynamic
- jump-target condition can be static (unconditional) or dynamic (conditional)

## ▶ Static jumps

- jump target address is static
- compiler hard-codes this address into instruction

Name	Semantics	Assembly	Machine
branch	$pc \leftarrow (a == pc + 00*2)$	br a	8-oo
branch if equal	$pc \leftarrow (a == pc + 00*2) \text{ if } r[c] == 0$	beg a	9coo
branch if greater	$pc \leftarrow (a == pc + 00*2) \text{ if } r[c] > 0$	bgt a	acoo
jump	$pc \leftarrow a$	j a	b--- aaaaaaaaa

## ▶ Dynamic jumps

- jump target address is dynamic

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# Dynamic Jumps

## ▶ Indirect Jump

- Jump target address stored in a register
- We already introduced this instruction, but used it for **static** procedure calls

Name	Semantics	Assembly	Machine
indirect jump	$pc \leftarrow r[t] + (o == pp*2)$	j o(rt)	ctpp

## ▶ Double indirect jumps

- Jump target address stored in memory
- Base-plus-displacement and indexed modes for memory access

Name	Semantics	Assembly	Machine
dbl-ind jump b+o	$pc \leftarrow m[r[t] + (o == pp*2)]$	j *o(rt)	dtpp
dbl-ind jump indexed	$pc \leftarrow m[r[t] + r[i]*4]$	j *(rt,ri,4)	eti-

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## Question 2

- What happens when this code is compiled and run?

```
void foo (int i) {printf ("foo %d\n", i);}
void bar (int i) {printf ("bar %d\n", i);}
void bat (int i) {printf ("bat %d\n", i);}

void (*proc[3])() = {foo, bar, bat};

int main (int argc, char** argv) {
    int input;
    if (argc==2) {
        input = atoi (argv[1]);
        proc[input] (input+1);
    }
}
```

- [A] It does not compile
- [B] For any value of input it generates an error
- [C] If input is 1 it prints “bat 1” and it does other things for other values
- [D] If input is 1 it prints “bar 2” and it does other things for other values

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## Question 3

- What happens when this code is compiled and run?

```
void foo (int i) {printf ("foo %d\n", i);}
void bar (int i) {printf ("bar %d\n", i);}
void bat (int i) {printf ("bat %d\n", i);}

void (*proc[3])(int) = {foo, bar, bat};

int main (int argc, char** argv) {
    int input;
    if (argc==2) {
        input = atoi (argv[1]);
        proc[input] (input+1);
    }
}
```

- [A] It does not compile
- [B] For any value of input it generates an error
- [C] If input is 1 it prints “bat 1” and it does other things for other values
- [D] If input is 1 it prints “bar 2” and it does other things for other values

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## Question 4

- Which implements `proc[input] (input+1);`

• [A]

```
ld    (r5), r0
ld    $proc, r1
deca r5
mov  r0, r2
inc  r2
st   r2, (r5)
gpc $2, r6
j    *(r1, r0, 4)
```

```
void foo (int i) {printf ("foo %d\n", i);}
void bar (int i) {printf ("bar %d\n", i);}
void bat (int i) {printf ("bat %d\n", i);}

void (*proc[3])(int) = {foo, bar, bat};
```

• [B]

```
ld    (r5), r0
ld    $proc, r1
deca r5
mov  r0, r2
inc  r2
st   r2, (r5)
gpc $6, r6
j    bar
```

```
int main (int argc, char** argv) {
    int input;
    if (argc==2) {
        input = atoi (argc[1]);
        proc[input] (input+1);
    }
}
```

- [C] I think I understand this, but I can't really read the assembly code.
- [D] Are you serious? I have no idea.

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## Summary

- Static vs Dynamic flow control

- static if jump target is known by compiler
- dynamic for polymorphic dispatch, function pointers, and switch statements

- Polymorphic Dispatch in Java

- invoking a method on an object in java
- method address depends on object's type, which is not known statically
- object has pointer to class object; class object contains method jump table
- procedure call is this a double-indirect jump – i.e., target address in memory

- Function Pointers in C

- a variable that stores the address of a procedure
- used to implement dynamic procedure call, similar to polymorphic dispatch

- Switch Statements

- syntax restricted so that they can be implemented with jump table
- jump-table implementation running time is independent of the number of case labels
- but, only works if case label values are reasonably dense

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